

RIOS: Runtime Integrated Query Optimizer for Spark

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Cloud Computing Programs

Open Source Data-Intensive Scalable Computing (DISC) Platforms: Hadoop MapReduce and Spark

- functional API
- map and reduce User-Defined Functions
- RDD transformations (filter, flatMap, zipPartitions, etc.)

Several years later, introduction of high-level SQL-like declarative query languages (and systems)

- Conciseness
- Pick a physical execution plan from a number of alternatives

Query Optimization

Two steps process

- Logical optimizations (e.g., filter pushdown)
- Physical optimizations (e.g., join orders and implementation)

Physical optimizer in RDMBS:

• Cost-based

• Data statistics (e.g., predicate selectivities, cost of data access, etc.)

The role of the cost-based optimizer is to

- (1) enumerate some set of equivalent plans
- (2) estimate the cost of each
- (3) select a sufficiently good plan

Query Optimization: Why Important?



Query Optimization: Why Important?



Challenges for Cost-based Optimizer in DISC

Lack of **upfront statistics**:

data sits in HDFS and unstructured

Even if input statistics are available:

- Correlations between predicates
- Exponential error propagation in joins
- Arbitrary UDFs

Pre-existing statistics

Bad statistics

No upfront statistics

Pre-existing statistics

• Spark CBO[1]

- Collect and store statistics
- No runtime plan revision

Bad statistics

No upfront statistics

Pre-existing statistics

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- Collect and store statistics
- No runtime plan revision

Bad statistics

Adaptive Query planning[2]

Assumption is that some initial statistics exist

No upfront statistics

Pre-existing statistics

• Spark CBO[1]

Bad statistics

Adaptive Query planning[2]

No upfront statistics

Pilot runs (samples)[3]

Collect and store statisticsNo runtime plan revision

Assumption is that some initial statistics exist

- Samples are expensiveOnly foreign-key joins
- No runtime plan revision

Traditional Query Planning VS RIOS



Traditional Query Planning VS RIOS



Runtime Integrated Optimizer for Spark

Key idea: Execute-Gather-Aggregate-Plan strategy (EGAP)

- Query plans are lazily executed
- Statistics are gathered at runtime
- Aggregate statistics after gathering
- Joins are greedily planned for execution
- Plan can be dynamically changed if a bad decision was made

Neither upfront statistics nor pilot runs are required

• Raw dataset size is required for initial guess

Support for not foreign-key joins

Runtime Optimizer: an Example

 $A \bowtie B \bowtie C$







Runtime Optimizer: Execute Step

AXBXC

Assumption: A < C



A





Runtime Optimizer: Gather step



Runtime Optimizer: Aggregate step



Runtime Optimizer: Plan step



Runtime Optimizer: Execute step



Runtime Optimizer: Gather step



Runtime Optimizer: Plan step



Runtime Optimizer: Execute step



$\sigma(A) \boxtimes B \boxtimes \sigma(C)$ Assumption: A < C $\sigma(A) > \sigma(C)$





















Runtime Integrated Optimizer for Spark

Spark batch execution model allows late binding of joins

Set of Statistics:

- Join estimations (based on sampling or sketches)
- Number of records
- Average size of each record

Statistics are aggregated using a Spark job or accumulators

Join implementations are picked based on thresholds

Challenges and Optimizations

Execute - Block and revise execution plans without wasting computation

Aggregate - Efficient accumulation of statistics

Plan - Try to schedule as many broadcast joins as possible

Experiments

Q1: What are the performance of RIOS compared to regular Spark, pilot runs and Spark-CBO?

Q2: How expensive are wrong guesses?

Minibenchmark with 3 Fact Tables



Minibenchmark with 3 Fact Tables



Q1: RIOS is always faster than Spark and pilot run

Minibenchmark with 3 Fact Tables



Q2: Not much, around 15% in the worst case

TPCDS and TPCH Queries



TPCDS and TPCH Queries



Q1: RIOS is always the faster approach

Conclusions

RIOS: cost-based query optimizer for Spark

Statistics are gathered at runtime (no need for initial statistics or pilot runs)

Late bind of joins

Up to 2x faster than the best plan generated by pilot run, and > 100X than previous approaches for fact table joins.



Experiment Configuration

- Datasets:
 - <u>TPCDS</u>
 - <u>TPCH</u>
- Configuration:
 - 16 machines, 4 cores (2 hyper threads per core) machines, 32GB of RAM, 1TB disk
 - Spark 2.2.1
 - Scale factor from 1 to 1000 (~1TB)

Reference

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Thank you