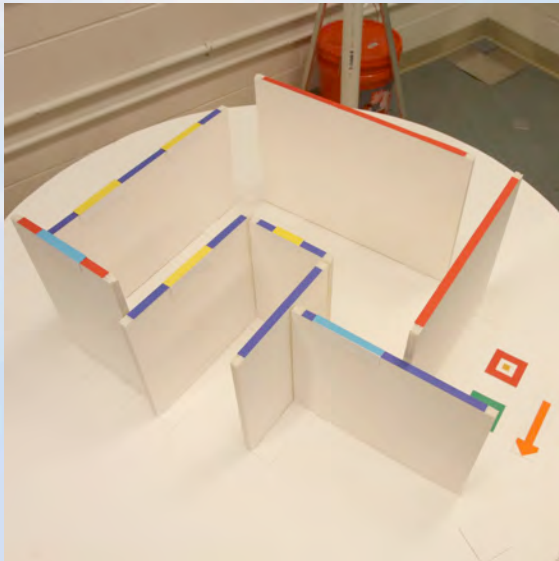


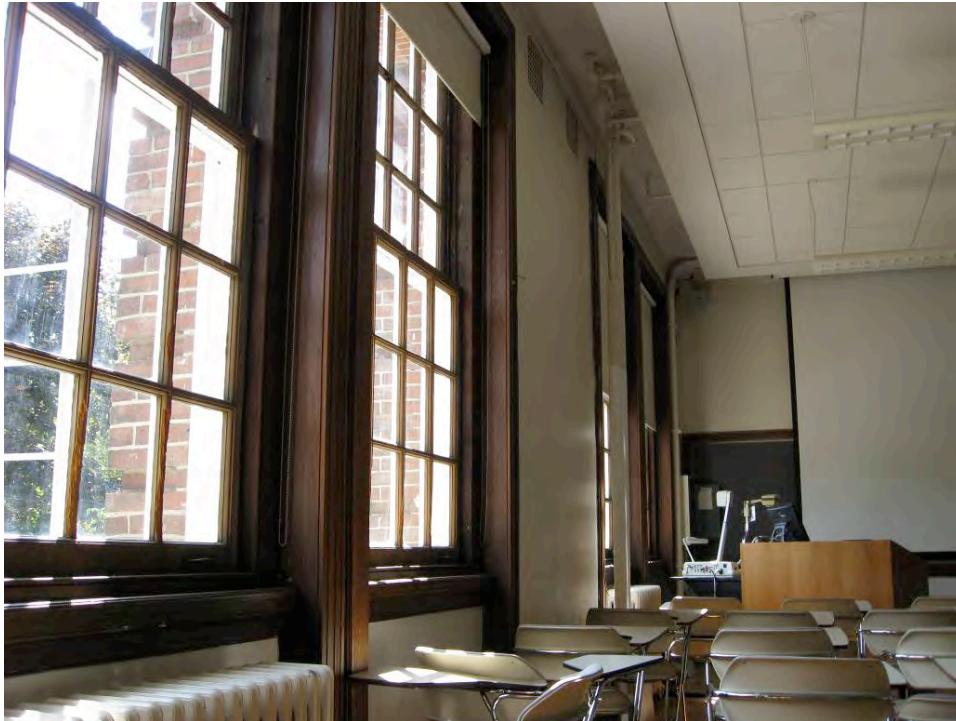
# Virtual Heliodon: Spatially Augmented Reality for Architectural Daylighting Design



Yu Sheng, Theodore C. Yap,  
Christopher Young, Barbara Cutler

Department of Computer Science  
Rensselaer Polytechnic Institute

# Natural Light vs. Electric Light



*Lighting accounts for 22% of  
US electricity consumption*





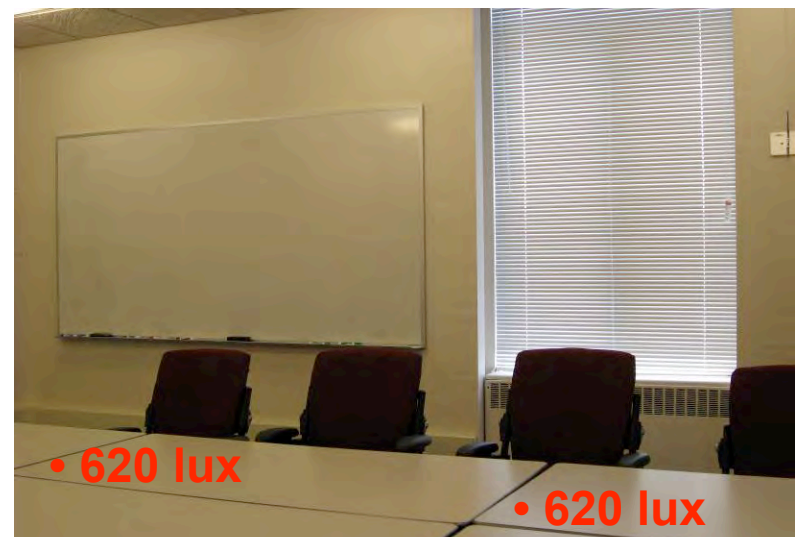
Lights off, no blinds



Lights off, blinds open



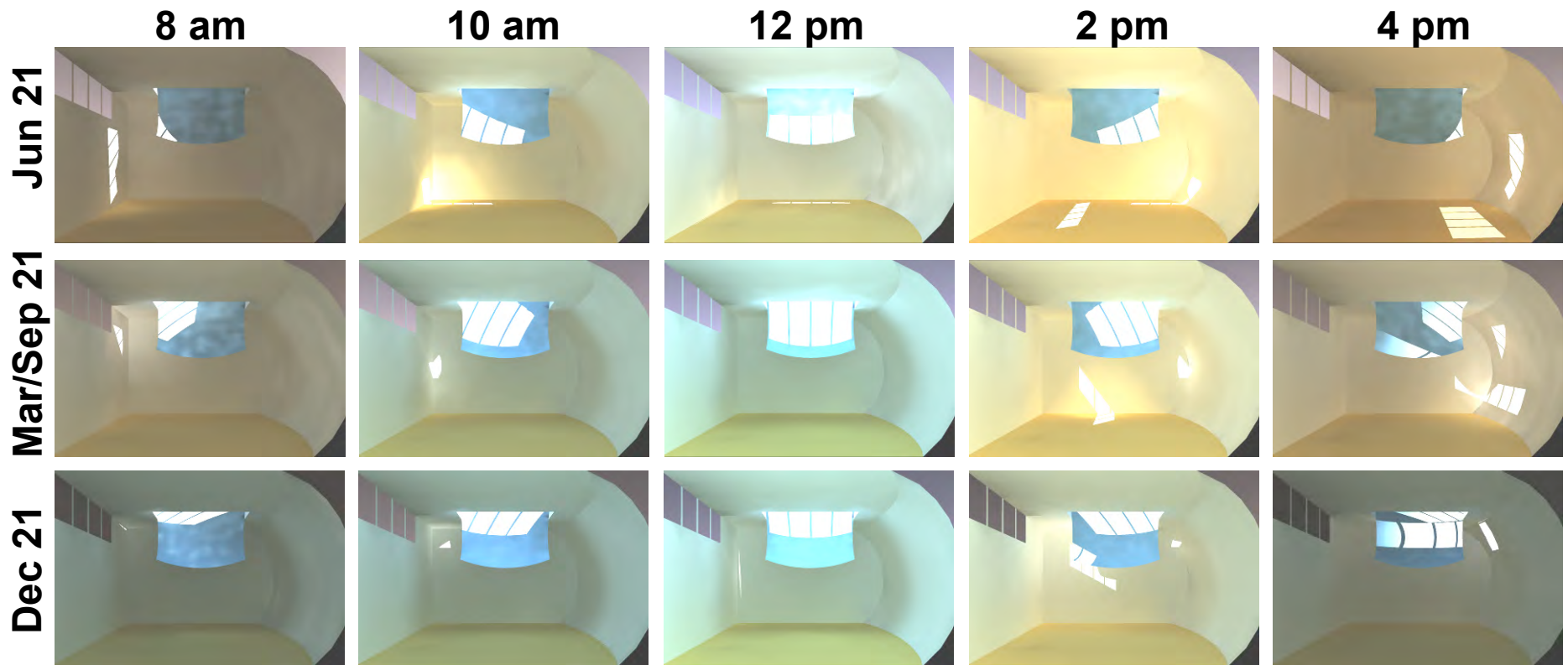
Lights off, blinds closed



Lights on, blinds closed

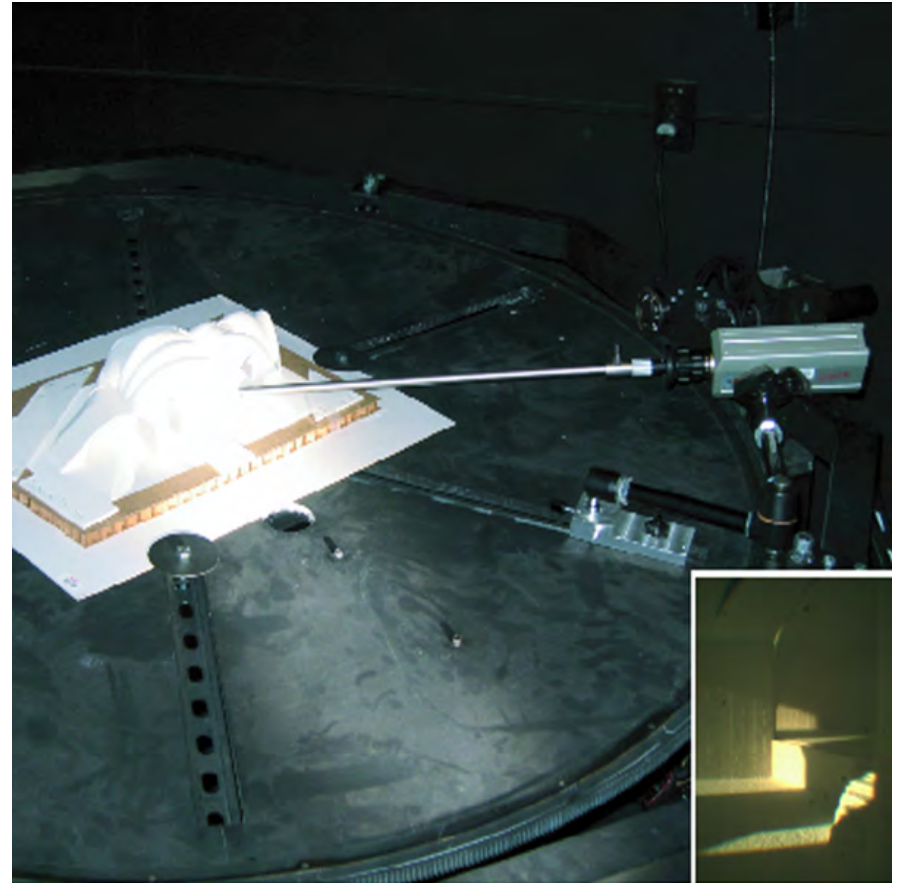
*500-1000 lux recommended for reading  
direct sunlight  $\approx$  100,000 lux*

Architectural Daylighting Design: The use of windows and reflective surfaces to allow natural light from the sun and sky to provide effective and interesting internal illumination.



*Residential design proposal by Mark Cabrinha*

# Analysis with Traditional Heliodon

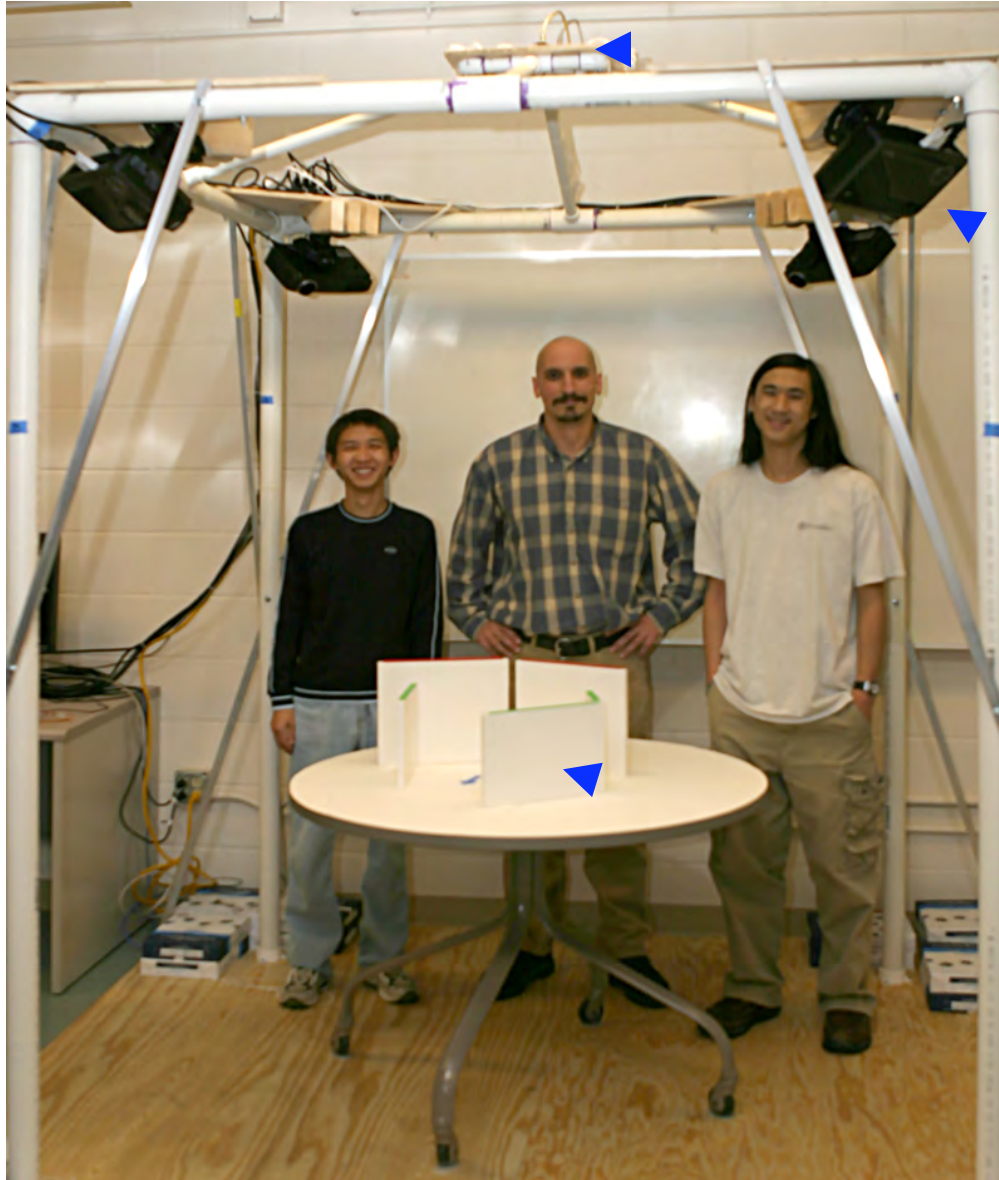


*Shadows and light penetration can be observed on small scale physical model*

# Related Work:

- Daylighting Design
  - Radiance, Greg Ward Larson
- Virtual / Augmented Reality
  - CAVE (Cruz-Neira et al., 1992)
  - Interior Architectural design (Mackie et al., 2004, Dunston et.al, 2007)
- Spatially Augmented Reality
  - Office of the future (Raskar et al., 1998)
  - Everywhere Display (Underkoffler et al., 1999)
  - Shader Lamps (Raskar et al., 2001)
  - Automatically-calibrated cameras and projectors (Raskar et al., 2001)
  - Multi-planar display (Ashdown et al., 2004)
  - Shadows and occlusions (Audet & Cooperstock, 2007)

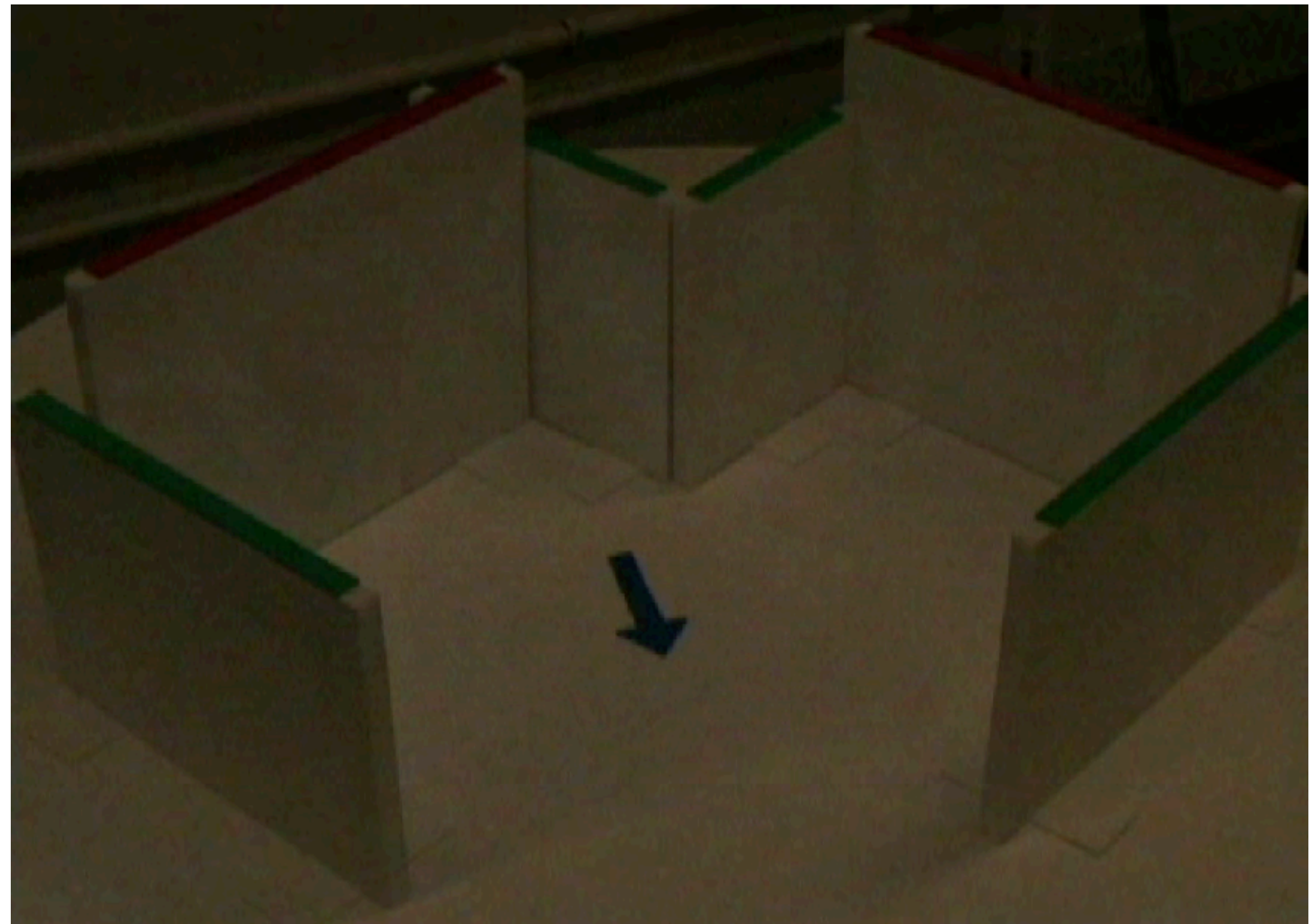
# Table-top Daylighting Design



*camera to  
detect geometry*

*4 projectors to  
display solution*

*design sketched with  
foam-core walls*





# Algorithms and Implementation

- Hybrid Rendering Algorithm
- Model Construction
- Camera & Projector Calibration
- Primitive Detection
- Multi-Projector Display

# Algorithms and Implementation

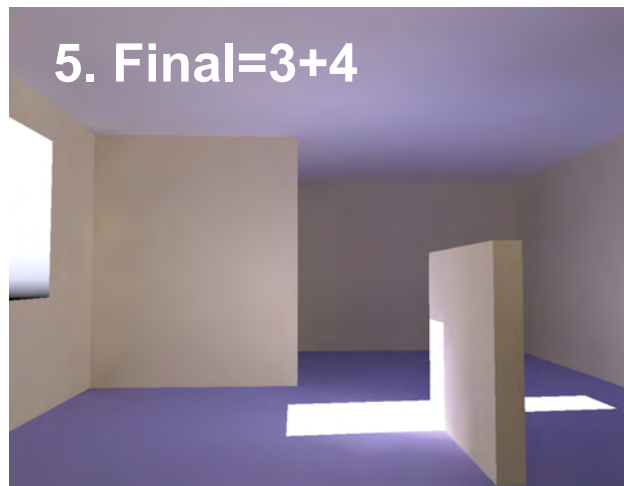
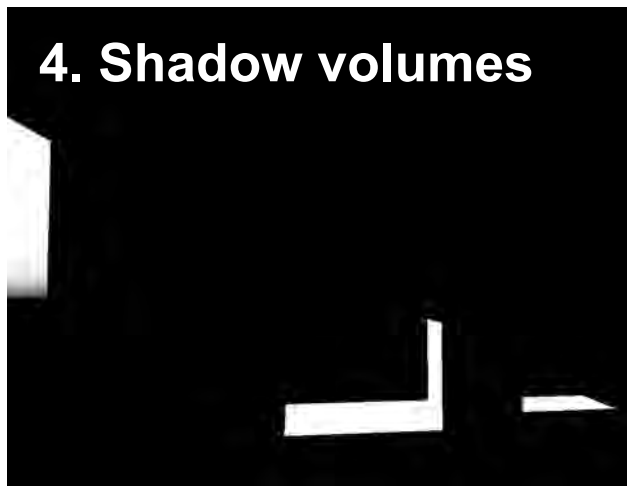
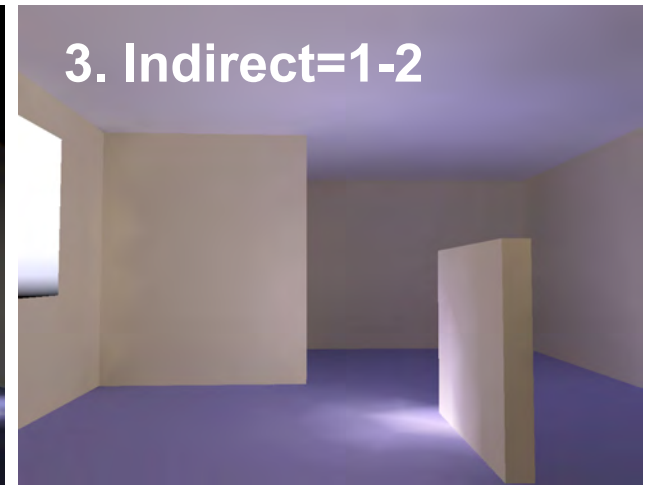
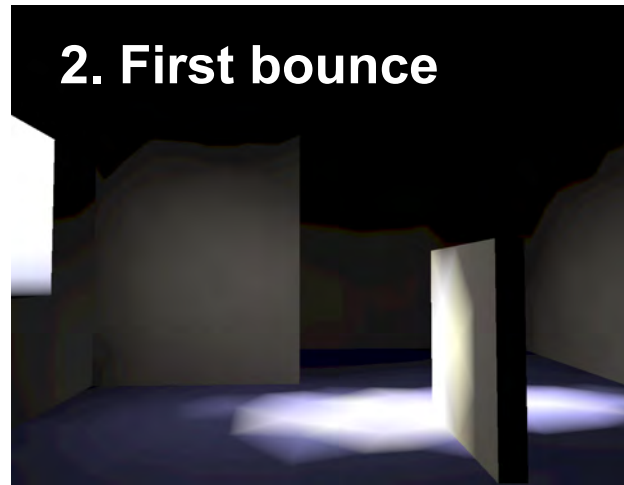
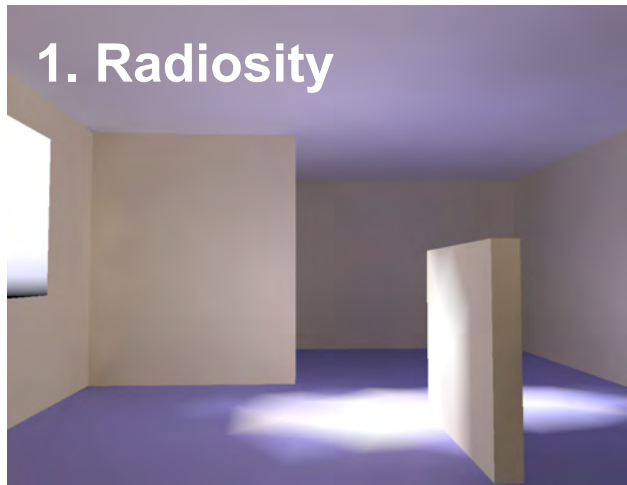
- Hybrid Rendering Algorithm
- Model Construction
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# Radiosity

- Global illumination algorithm
  - Diffuse surfaces
- Why not radiosity alone?
  - Low resolution mesh → inaccurate shadows
- Why do we need “hard shadows”?
  - More realistic
  - More intuition about scene geometry & lighting



# Interactive Global Illumination: Hybrid Radiosity/Shadow Volumes



*Exploit smoothness  
in indirect  
illumination*

*Efficiently compute  
direct illumination*

# Algorithms and Implementation

- Hybrid Rendering Algorithm
- **Model Construction**
- Camera & Projector Calibration
- Primitive Detection
- Multi-Projector Display

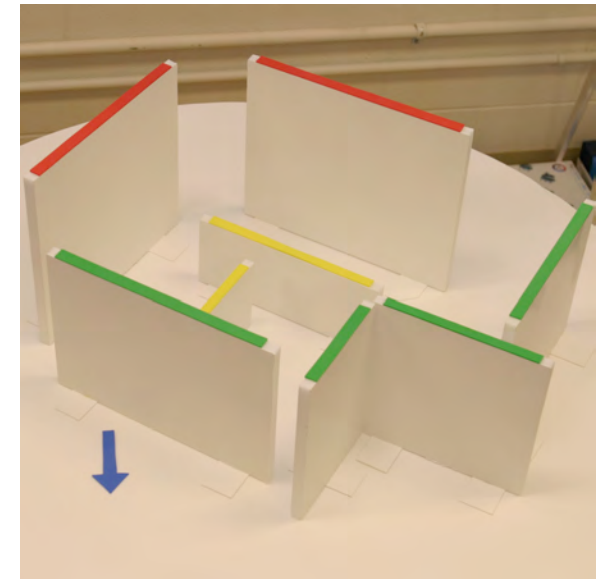
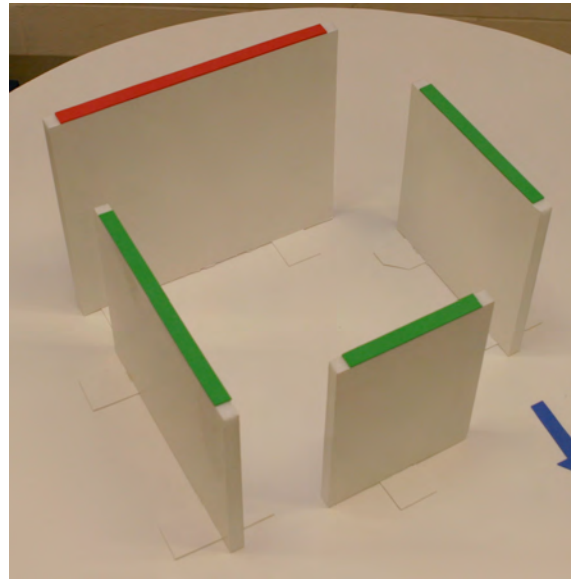
# Sketch Interpretation

*red: exterior wall  
w/ window*

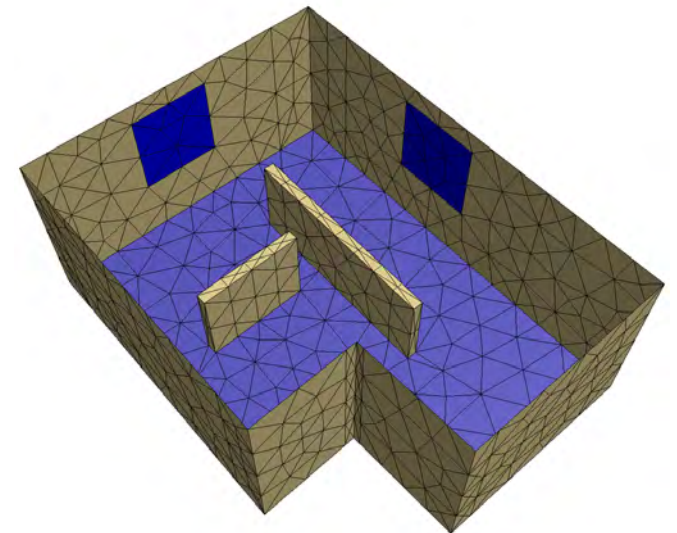
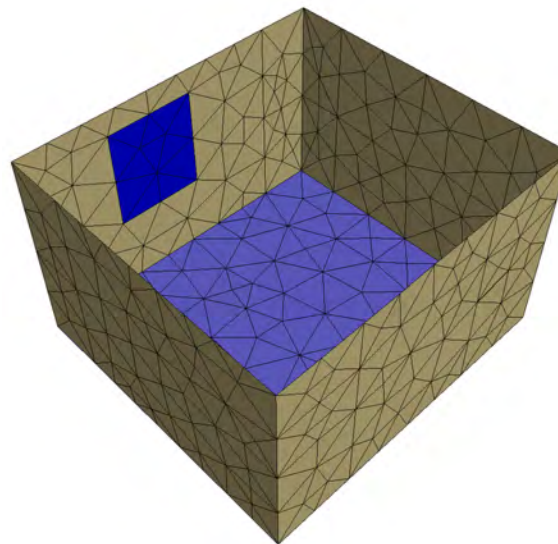
*green: exterior wall*

*yellow: interior wall*

*blue north arrow*



*software  
automatically  
constructs closed  
polygonal model  
for simulation*

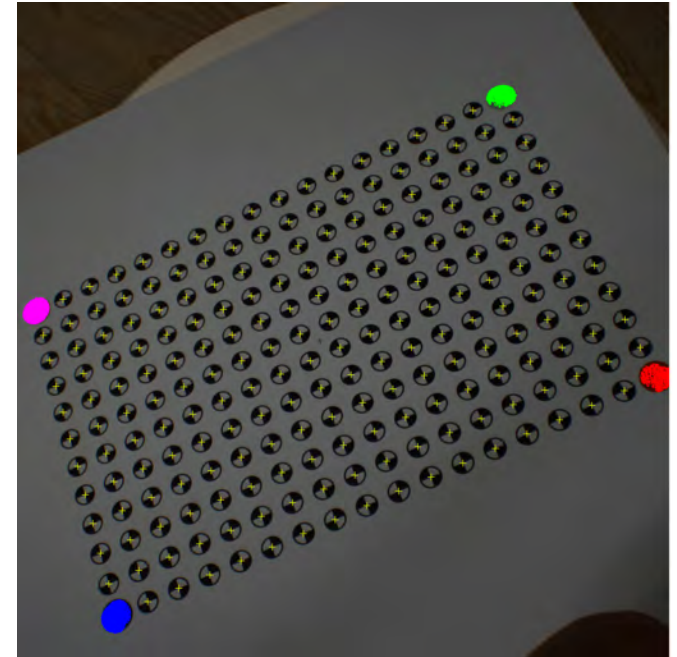


# Algorithms and Implementation

- Hybrid Rendering Algorithm
- Model Construction
- **Camera & Projector Calibration**
- Primitive Detection
- Multi-Projector Display

# Camera Calibration

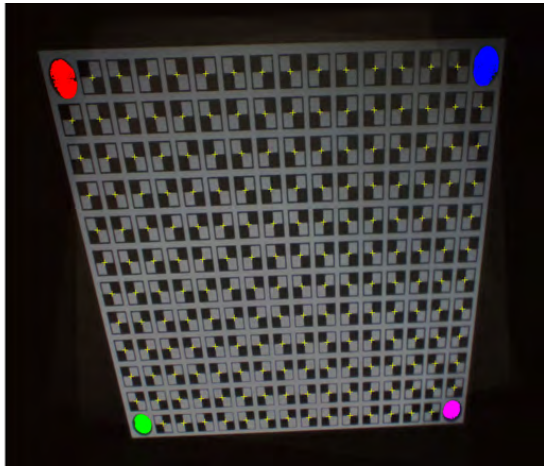
- Using Zhang's algorithm [Zhang 1999] to estimate the intrinsic parameters of camera
  - Calibration target consisting of 212 black and white corner marks on a white background
  - 40 pictures taken at different orientations



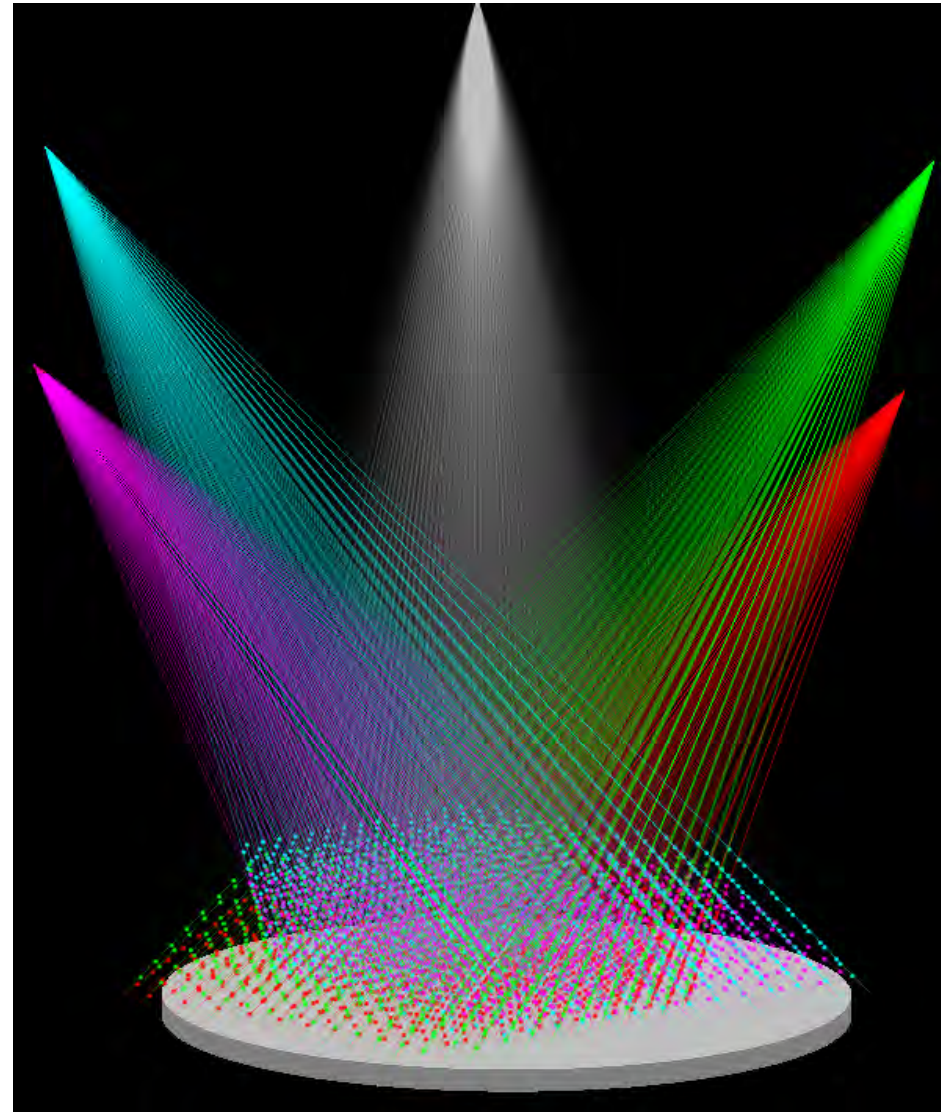


# Projector Calibration

- Tsai's algorithm [Tsai 1987]
  - Uniformly spaced horizontal planes



*Projector calibration*



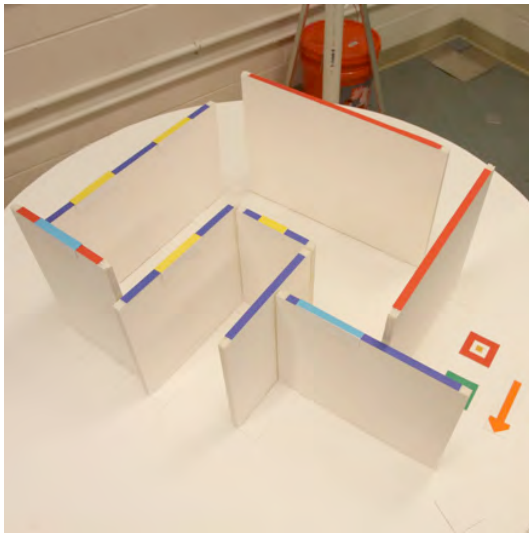
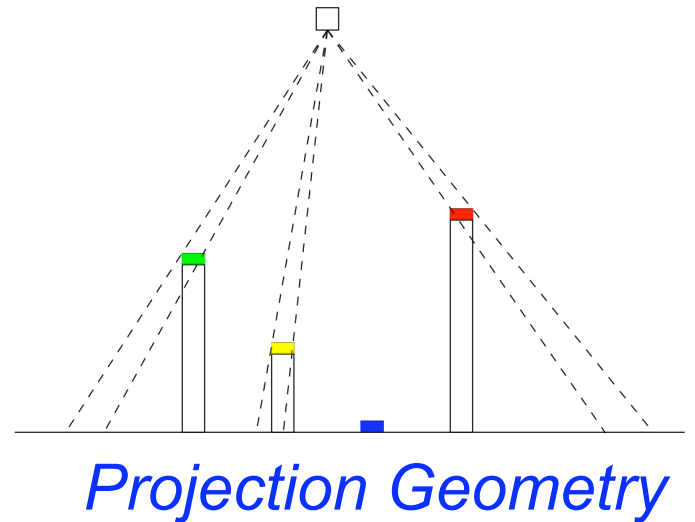
*Common coordinate system*

# Algorithms and Implementation

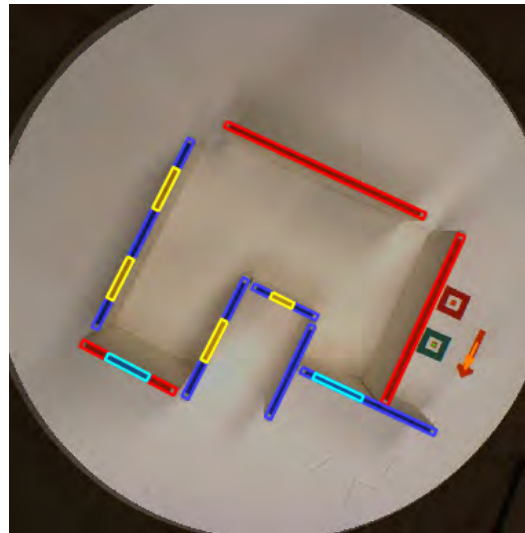
- Hybrid Rendering Algorithm
- Model Construction
- Camera & Projector Calibration
- **Primitive Detection**
- Multi-Projector Display

# Primitive Detection

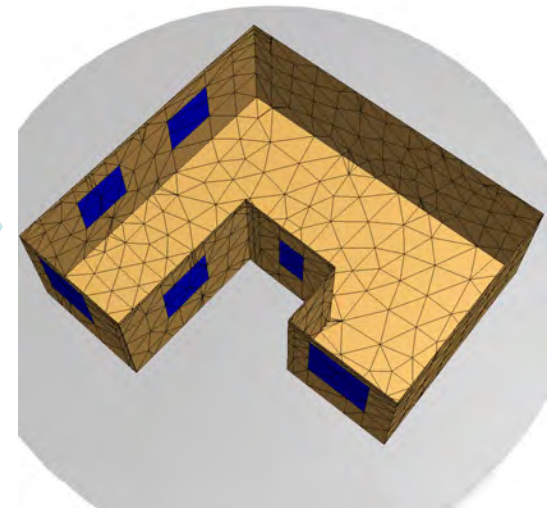
- Color classification
- RANSAC: fit line to edges
- 2D  $\rightarrow$  3D, projection matrix



*Physical Sketch*

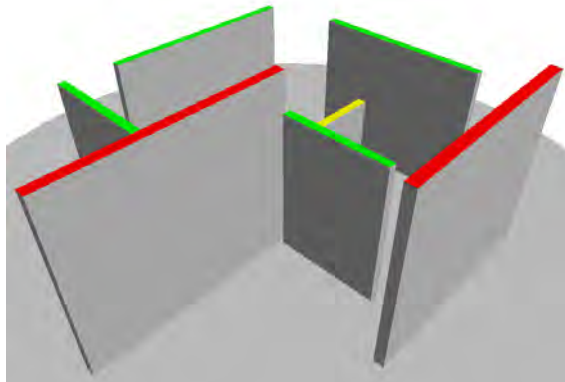


*Edge Detection*

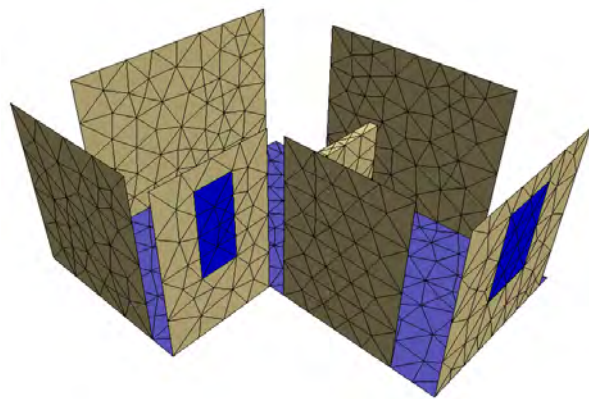
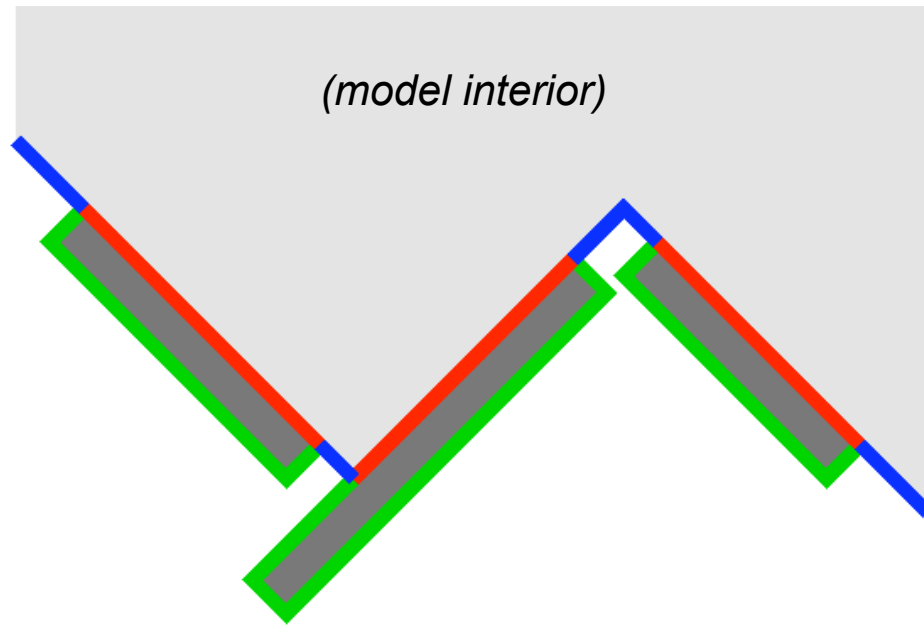


*Reconstructed Scene*

# Watertight Mesh for Simulation



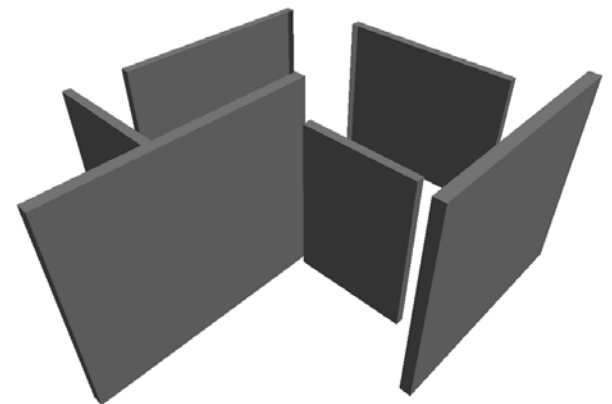
*Detected geometry*



*Projection surfaces*



*"Fill-in" geometry*



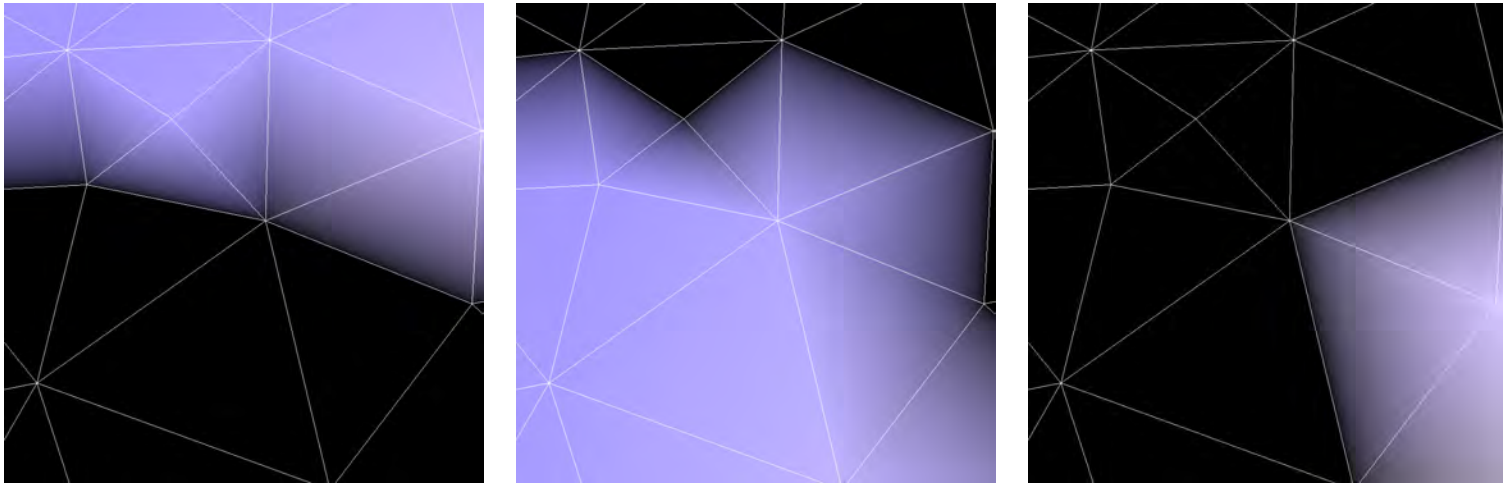
*"Extra" physical geometry*

# Algorithms and Implementation

- Hybrid Rendering Algorithm
- Model Construction
- Camera & Projector Calibration
- Primitive Detection
- **Multi-Projector Display**

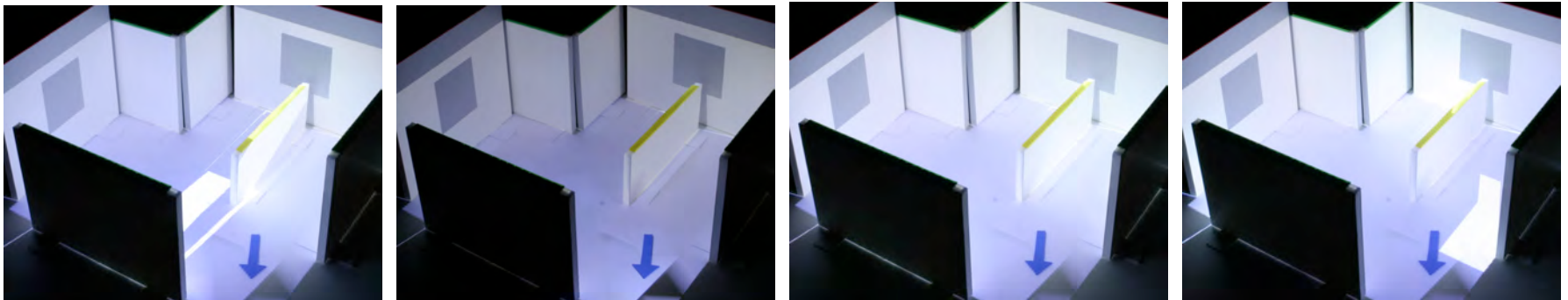
# Multi-Projector Display

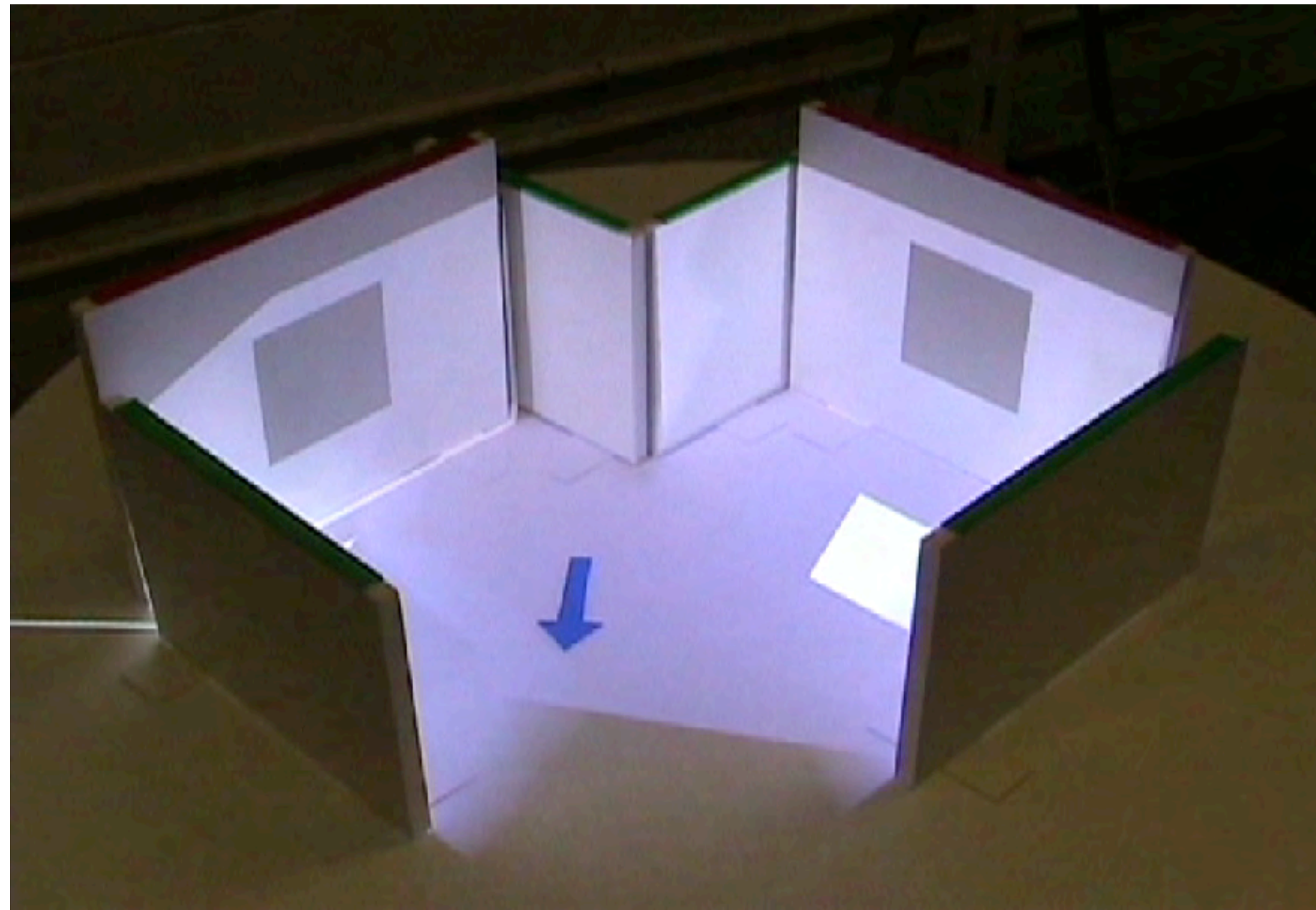
- Radiance adjustment  $I = E \frac{r^2}{\rho \cos \theta}$
- Intensity blending
  - Smooths transitions between projectors
  - Each vertex in the mesh has a “best projector” for display



# Results

- For a geometry with 1500 triangles
  - 0.6 seconds to relight for changing time / day, north orientation, etc.
  - 6-7 seconds to generate the projection images for a new geometry
    - Image processing: 0.05 seconds
    - Remeshing: 2.5 seconds
    - Form factor computation: 3 seconds







## Traditional Heliodon

- Must peer in the windows, but avoid blocking the “sun”
- Close approximations of all materials must be used in model construction
- Model construction is tedious

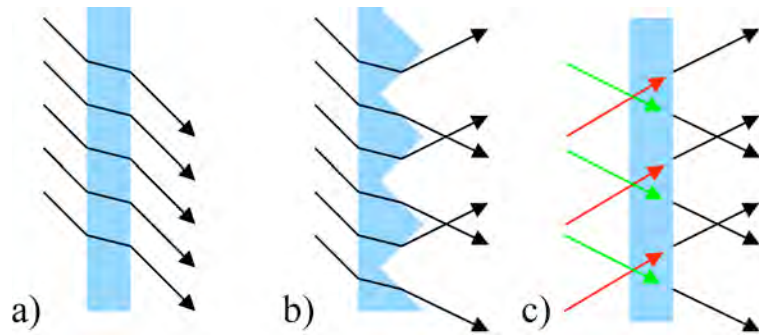
## Virtual Heliodon

- Ceiling has been removed allowing easy viewing
- Less precision is needed in joining walls
- Materials are specified digitally and do not require a physical sample of the material
- Initial construction and edits are fast and easy

# Ongoing and Future Work

- Formal user studies
- Robust image processing, e.g., ignore users' hands
- Table surfaces, curved walls, sloped ceilings
- Consider dynamic range of projectors
- Complex fenestration (window) materials
- Compensate for secondary scattering of projected imagery

# Light-Redirecting Materials



*Prismatic panels available in late 1800's, but lost popularity when electric lighting was introduced*

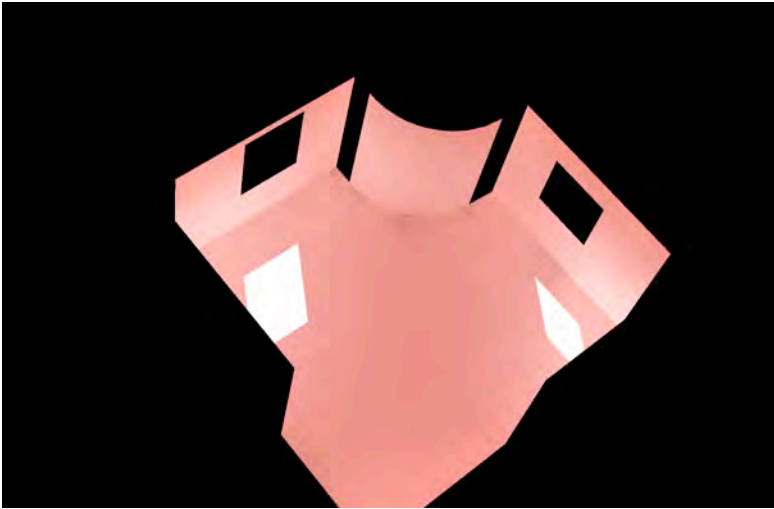
plain glass



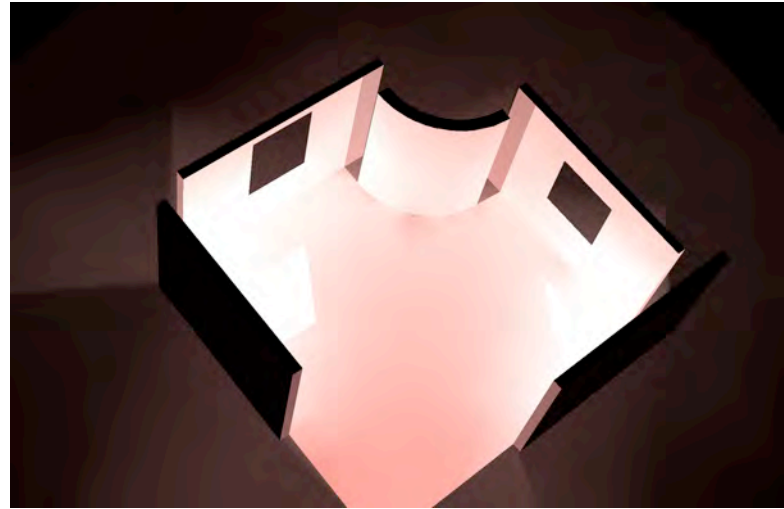
prismatic



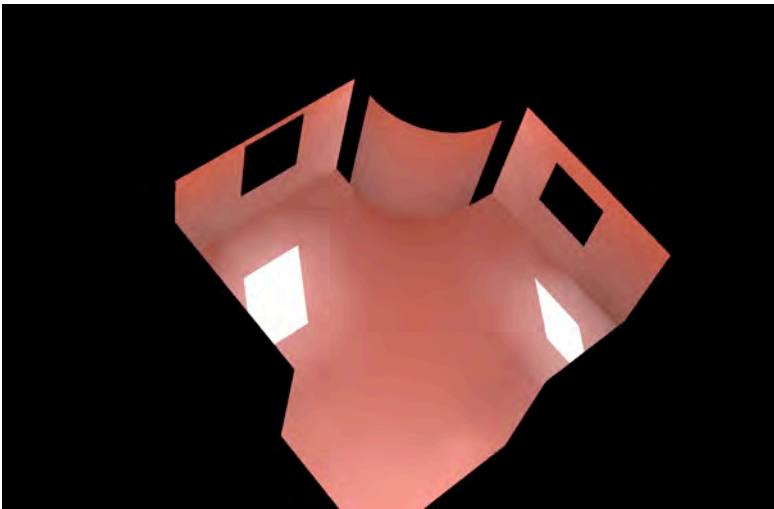
# Secondary Scattering Compensation



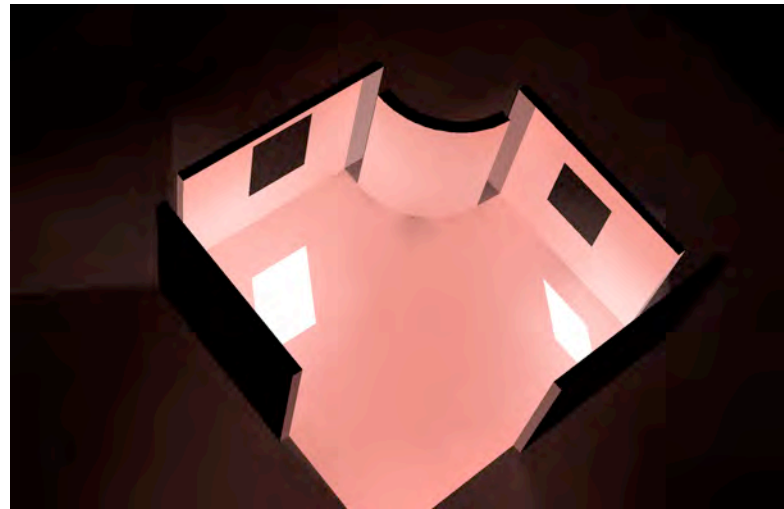
*Desired illumination*



*Naïve projection*



*Compensated*



*Compensated projection*

# Thanks!

- *Collaborators:*  
*Marilyne Andersen*  
*Mark Cabrinha*  
*Melissa Schroyer*
- *RPI Computer Vision Research Group*
- *IBM & NSF*

