

VR Haptic Controllers

Multi-Purpose Handheld Haptics Beyond Vibro-Tactors

Hrvoje Benko

Currently @



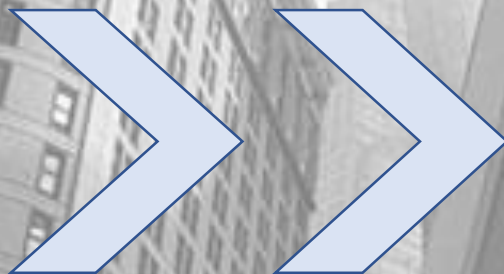
Work conducted @



Visuals Audio



Visuals
Audio



Haptics



VR Controllers – vibrotactile only



Oculus Touch



HTC Vive



Sony PSVR



Two Realities of Haptics in VR Today

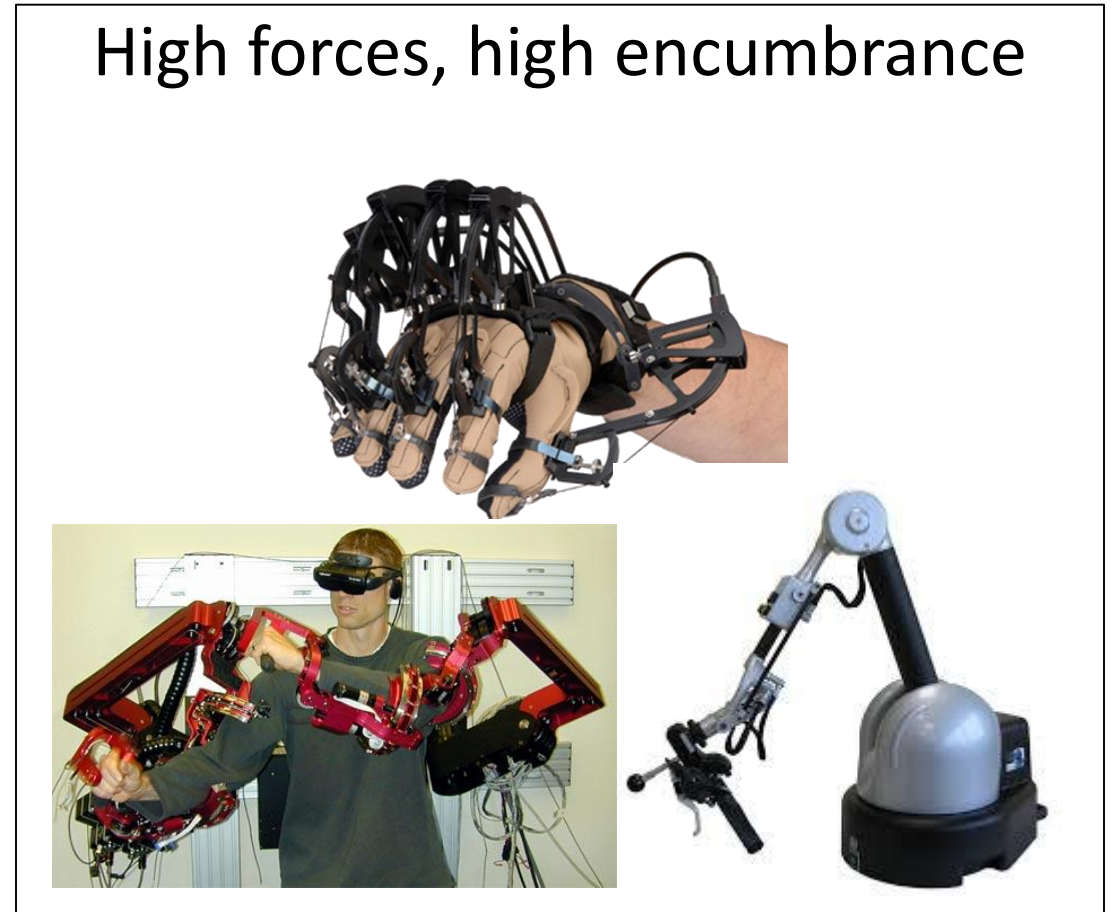
Mainstream Use

Vibrotactile only, low
encumbrance



Research Use

High forces, high encumbrance



Actuated Gloves – individual feedback to each finger/low comfort/low resolution



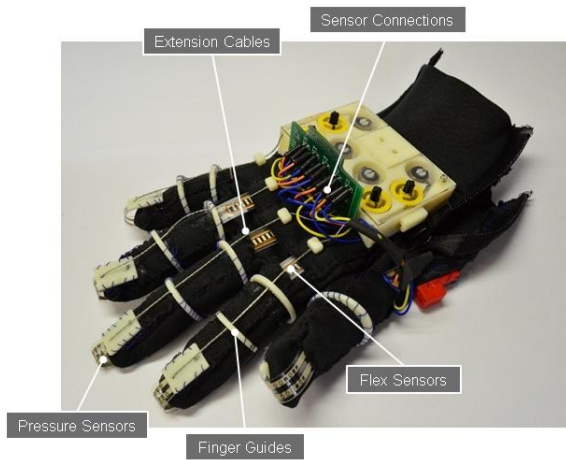
CyberTouch



CyberGrasp - 1997



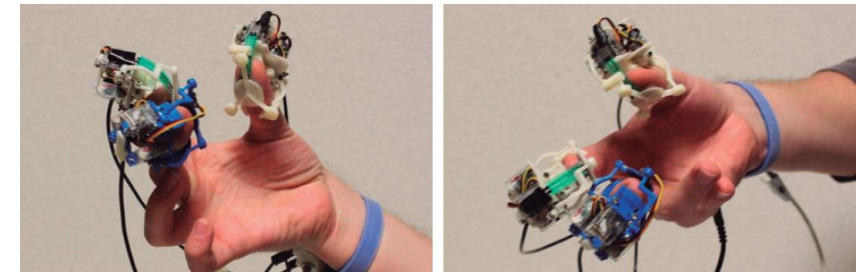
Rutgers Master II-ND - 2002



Delph et al. Soft Exo-Skeletal Arm - 2013



Dexmo Robotics - 2016



Perez et al. Haptics Symposium 2016

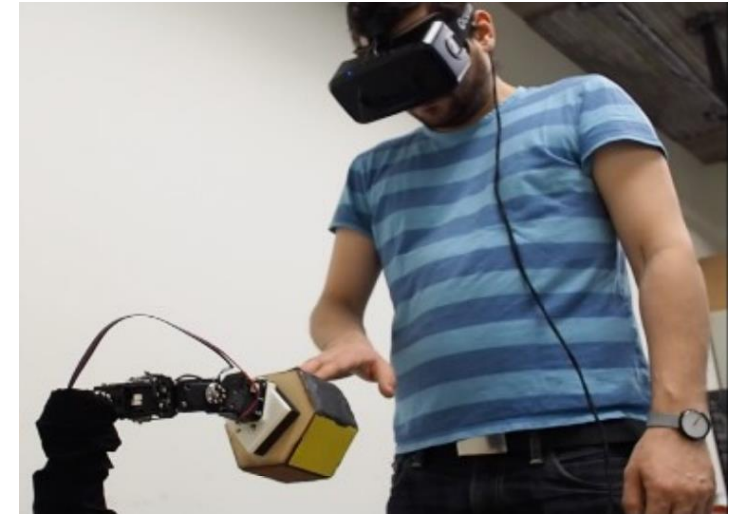
Haptic Robotic Arms – high force/restricted mobility/low resolution



Sensable Phantom Omni



Van der Linde et al. HapticMaster 2002



Araujo et al. SnakeCharmer TEI 2016



Novint Falcon

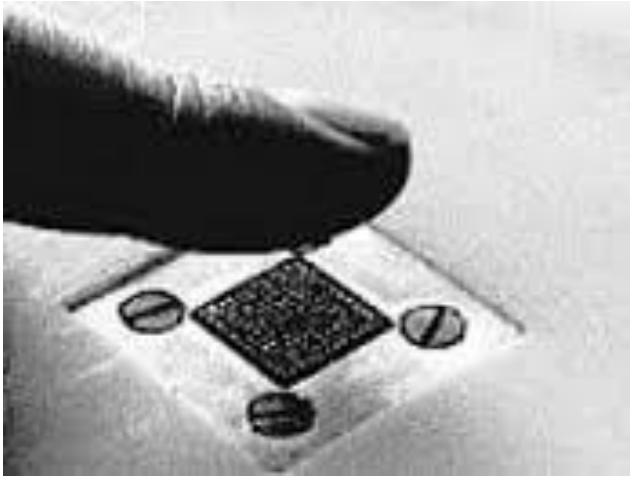


Haption Virtuose 6D

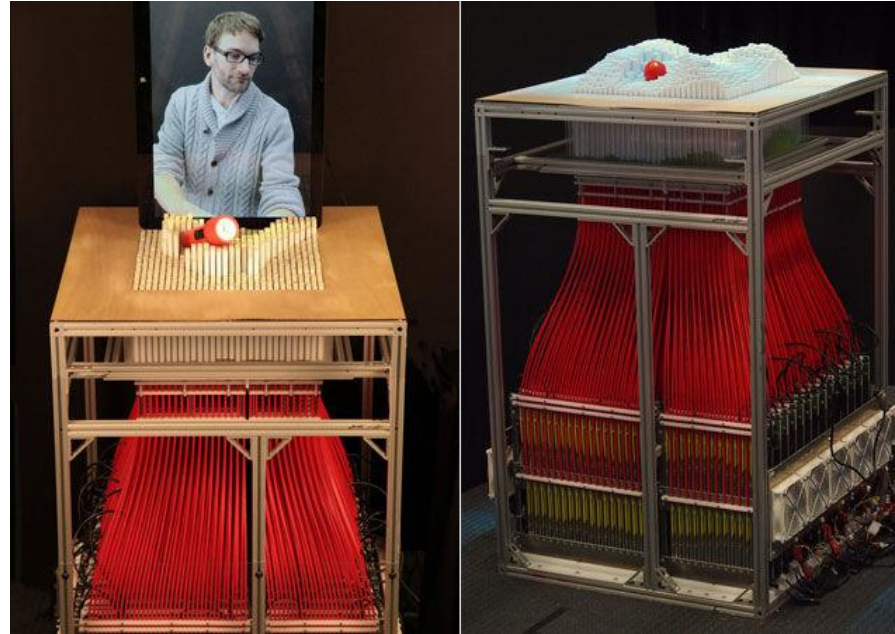


UCLA Bionics Lab

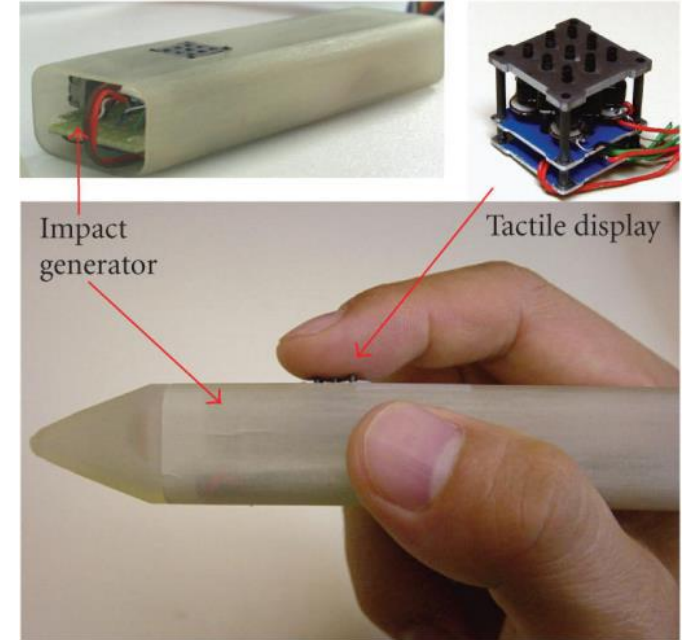
Tactile Arrays – higher resolution/stationary/2.5D at best



Summers et al. Exeter
Touch Array. EuroHaptics
2001



Follmer et al. InFORM. UIST 2013



Kyung et al. Ubi-Pen IEEE CG&A 2009



Poupyrev et al. Lumen Siggraph Etech 2004

Why such discrepancy between haptic research and product?

None of the research prototypes have demonstrated significant utility without a significant drawback.

VR Controllers are:

- Easy to hold for a variety of people with different hand sizes.
- Easily acquired, dropped, and tracked.
- A platform for additional buttons and joysticks.
- In a tool form factor.



Tools:

Familiar objects

Amplify our abilities

Become extensions of our body

[Tool-use induces morphological updating of the body schema](#)

L Cardinali, F Frassinetti, C Brozzoli, C Urquizar, et. al. - Current Biology, 2009

An opportunity: VR Haptic Controllers

Extend the tool form factor of VR handheld controllers with higher fidelity haptics.

What kinds of VR Haptic Controllers do we need?



5 Ideas for VR Haptic Controllers Toolbox



#1



Ungrounded haptic devices
with *force feedback* rendering.

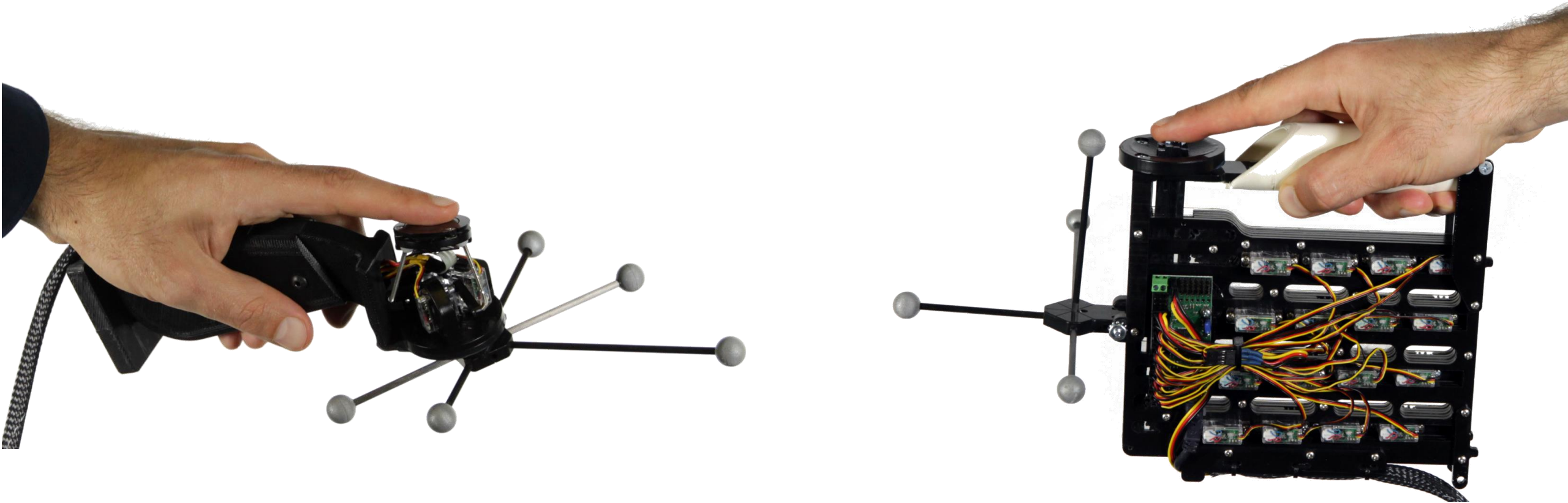
Reactive Grip by Tactical Haptics



W.R. Provancher, "Creating Greater VR Immersion by Emulating Force Feedback with Ungrounded Tactile Feedback," *IQT Quarterly* 6(2), 2014, pp. 18-21.

NormalTouch and TextureTouch

3D shape output on the handheld controller form factor



Hrvoje Benko, Christian Holz, Mike Sinclair, and Eyal Ofek. (2016). NormalTouch and TextureTouch: High-fidelity 3D Haptic Shape Rendering on Handheld Virtual Reality Controllers. In *Proc. of ACM UIST 2016*.

NormalTouch and TextureTouch

High-fidelity 3D Haptic Shape
Rendering on Handheld Virtual
Reality Controllers

Hrvoje Benko, Christian Holz, Mike Sinclair, Eyal Ofek
Microsoft Research
2016

#2

Multi-purpose haptic devices that *adapt* to the user's context of use.



Goal

One VR Haptic Controller device that integrates multiple haptic rendering capabilities and adaptively selects which one to use based on the user's grip and the environmental context.

CLAW

CLAW:
A Multifunctional Handheld Haptic Controller
for Grasping, Touching, and Triggering in Virtual Reality

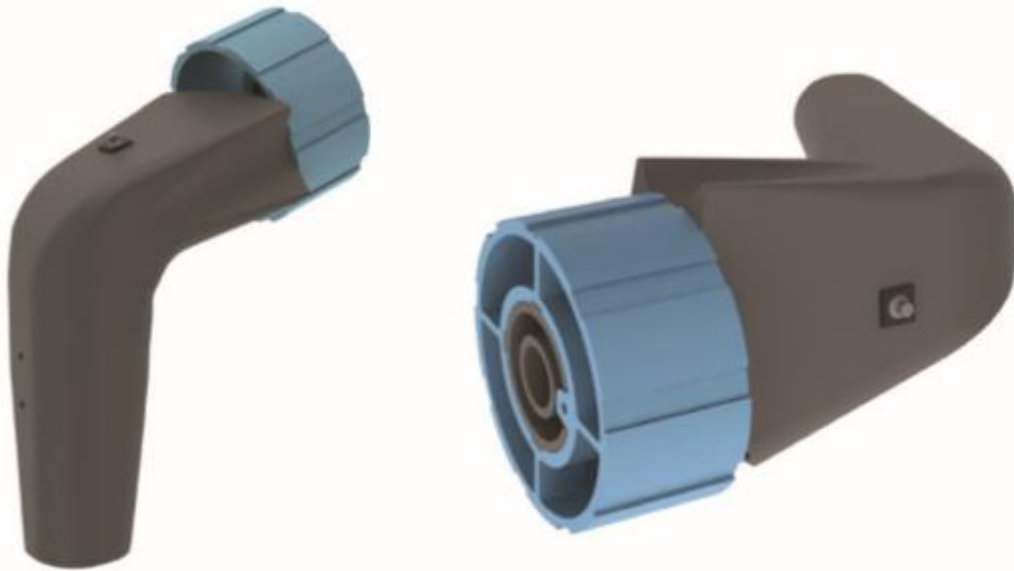
Choi, I., Ofek, E., Benko, H., Sinclair, M. and Holz, C. CLAW: A Multifunctional Handheld Haptic Controller for Grasping, Touching, and Triggering in Virtual Reality. To appear in *Proc. of ACM CHI '18*.

#3

User-customizable
haptic devices.

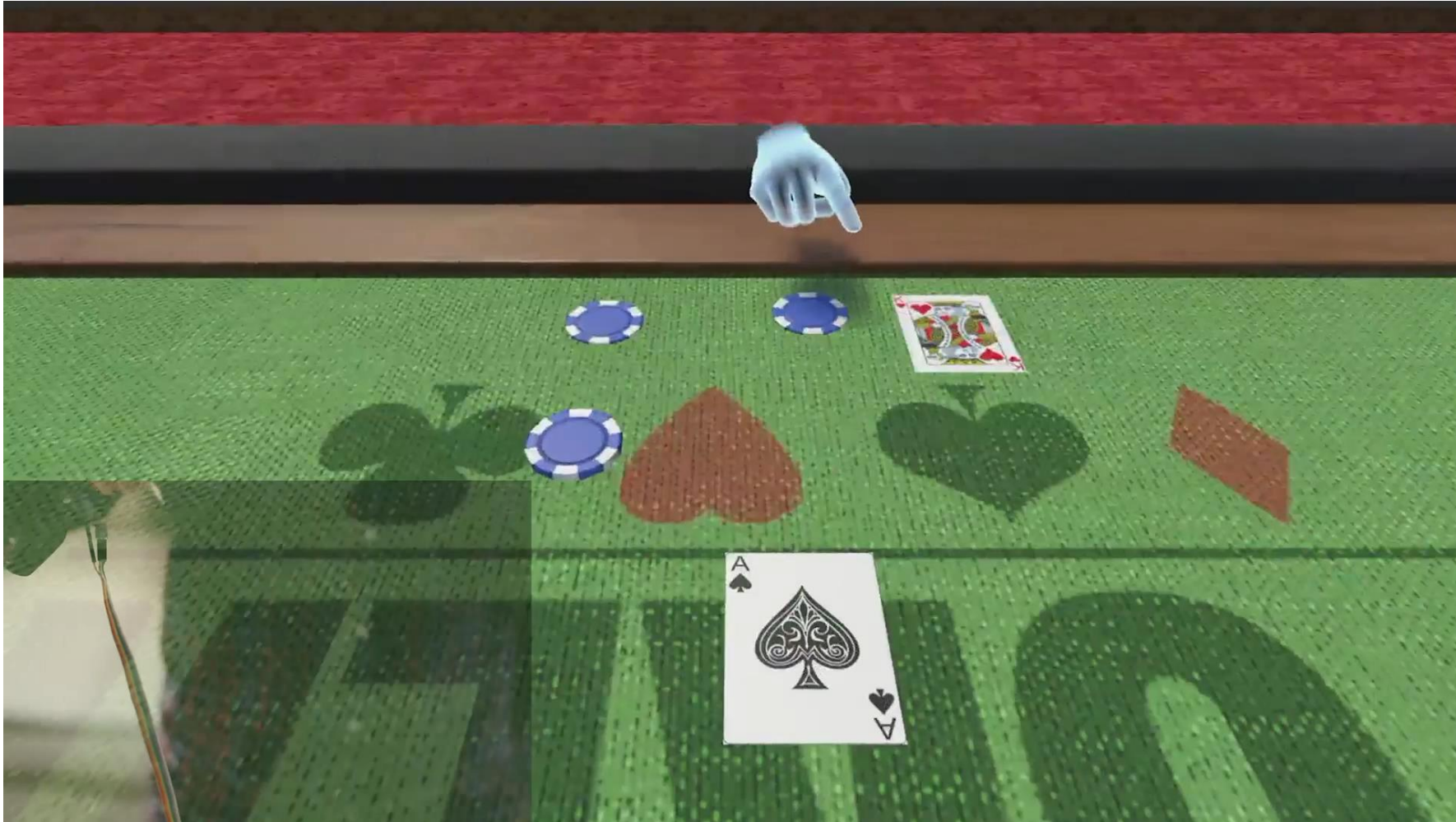


Haptic Revolver



Whitmire, E., Benko, H., Holz, C., Ofek, E. and Sinclair, M. Haptic Revolver: Touch, Shear, Texture, and Shape Rendering on a Reconfigurable Virtual Reality Controller. To appear in *Proc. of ACM CHI '18*. Honorable mention.

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#4

Haptic rendering
between devices.



Haptic Links

Haptic Links: Bimanual Haptics for Virtual Reality Using Variable Stiffness Actuation

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Christian Holz ·-----
Eyal Ofek ·-----
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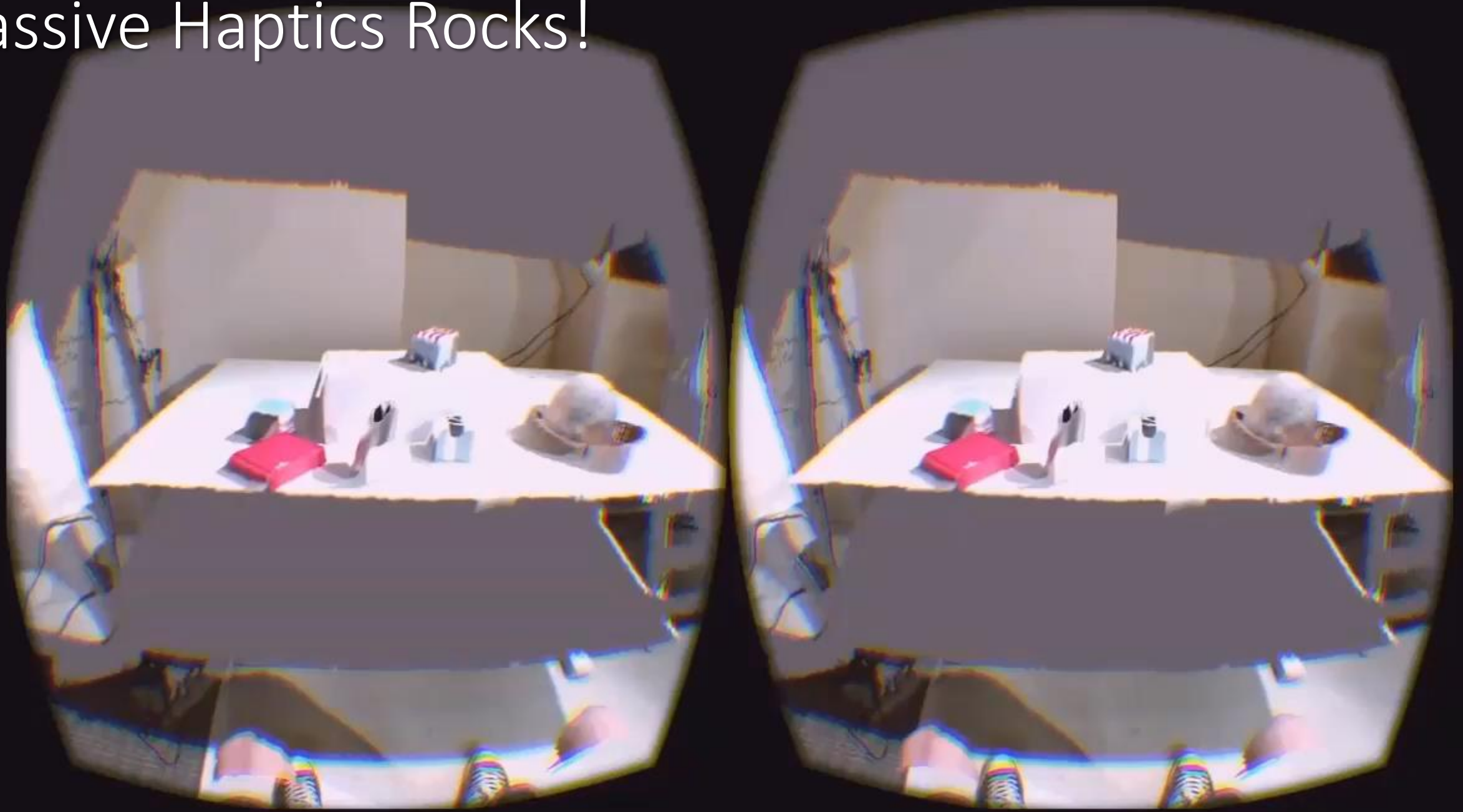
Strasnick, E., Holz, C., Ofek, E., Sinclair, M. and Benko, H. Haptic Links: Bimanual Haptics for Virtual Reality Using Variable Stiffness Actuation. To appear in *Proc. of ACM CHI '18*.

#5

Reuse existing
objects as haptic
tools.



Passive Haptics Rocks!



But, passive haptics approach doesn't scale!

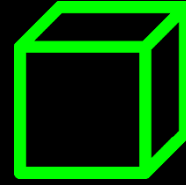
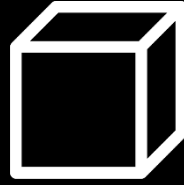
Haptic Retargeting

Azmandian, M., Hancock, M., Benko, H., Ofek, E., and Wilson, A. *Haptic Retargeting: Dynamic Repurposing of Passive Haptics for Enhanced Virtual Reality Experiences*. In *Proc. of ACM CHI 2016*.



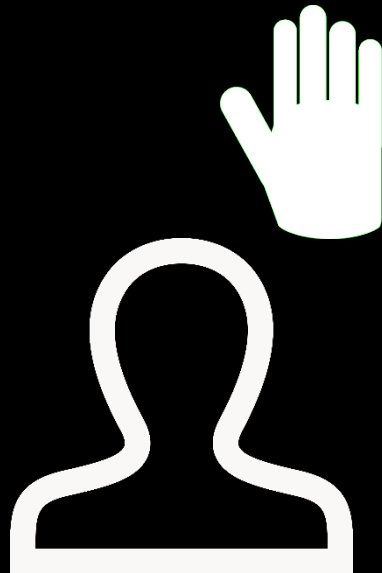
Body Warping

physical
cube



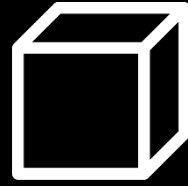
virtual
cube

*The Rendered Body
Shifts to The Right*

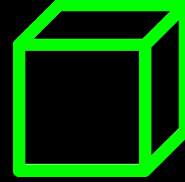


World Warping

physical
cube



30°

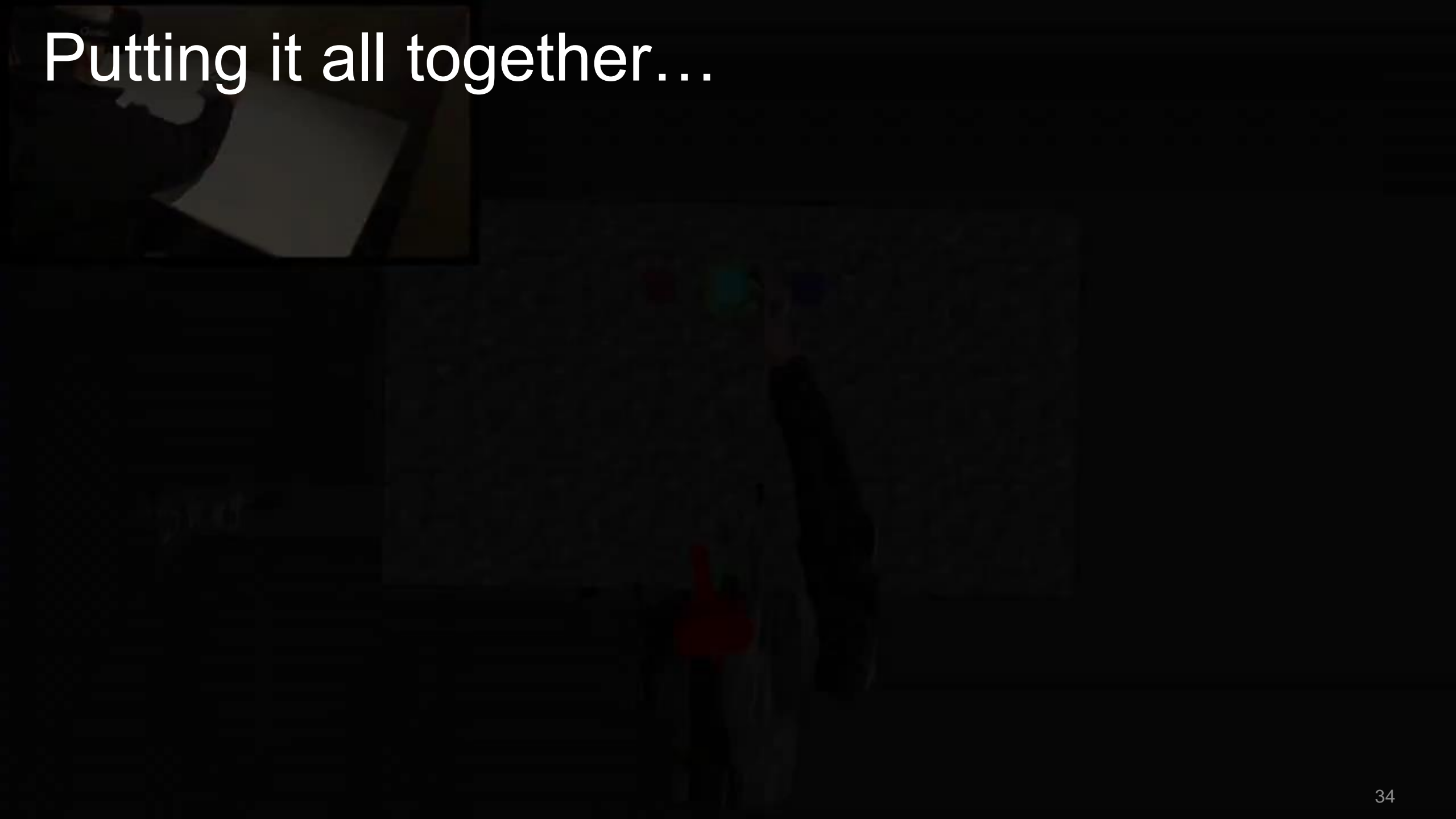


virtual
cube

*The World Also Rotates
(At Different Rate)*



Putting it all together...



Haptic retargeting allows physical props to be reused for haptics by **leveraging the dominance of vision** to retarget people's hand motions.

A single prop can be repurposed to allow **movement** and **stacking** of a virtual space with a multitude of virtual objects.

5 Ideas for VR Haptic Controller Toolbox

1. Provide *force feedback* rendering on *ungrounded* devices.
2. Design *multi-purpose* haptic devices that *adapt* to the context of use.
3. Design *user-customizable* haptic controllers.
4. Don't ignore haptics *between* devices.
5. Enable *reuse* of existing objects as haptic tools.



Thanks to my collaborators

Andy Wilson (MSR)

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Evan Strasnick (Stanford)

Inrak Choi (Stanford)

Mark Hancock (U. Waterloo)

A man with short grey hair, wearing a red button-down shirt, is looking towards the camera with a slight smile. In the foreground, a VR headset is visible, showing a virtual scene of a green landscape with a white object. The background is a plain wall with two framed pictures and a door handle on the right.

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