

The ABC of Mixed Reality Interactions



Hrvoje Benko
Facebook Reality Labs



Waiting for command

Aug 29



2.45 km

Center of city

**Command Line
Interfaces**
(text based)

1960s

**Graphical User
Interfaces**
(mouse + keyboard)

1980s

Natural User Interfaces
(touch/gestures, tablets,
smartphones)

2000s

Mixed Reality Interfaces

2020s



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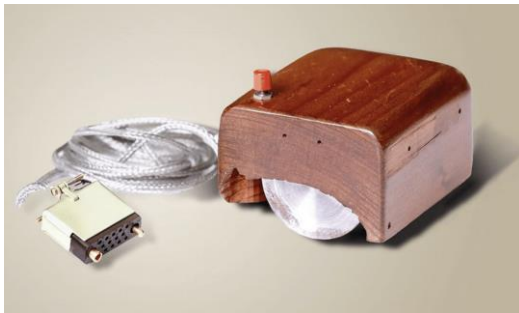
Mixed Reality Interfaces

2020s



1968
Engelbart & English
MOAD

1983
Microsoft Mouse / Apple Mouse



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(text based)

1960s

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(mouse + keyboard)

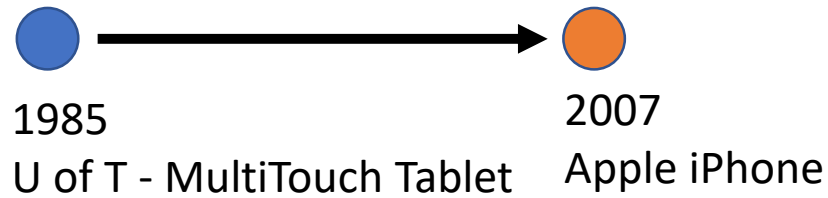
1980s

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(touch/gestures, tablets, smartphones)

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Mixed Reality Interfaces

2020s



SK Lee, W. Buxton, and K. C. Smith. A multi-touch three dimensional touch-sensitive tablet. In Proc. of the CHI '85.

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Mixed Reality Interfaces

2020s



???



New York 2001



Bell B., Feiner, S., and Hollerer, T. *Columbia Touring Machine - ACM ISAR 2001*



Bell B., Feiner, S., and Hollerer, T. *Columbia Touring Machine - ACM ISAR 2001*



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Bell B., Feiner, S., and Hollerer, T. *Columbia Touring Machine - ACM ISAR 2001*

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2001

MARS - Columbia Touring
Machine @ ISAR 2001

Michael Abrash

“Imagine AR glasses that are socially acceptable and all-day wearable, that give you useful virtual objects like your phone, your TV and virtual work spaces, that give you perceptual super powers, a context-aware personal assistant, and above all the ability to connect, share and collaborate with others anywhere, any time. If those glasses existed today, we’d all be wearing them right now.”

Might be “obvious” ...

... why not available today?

2001 vs. 2018 - Same Challenges

Display

Optics

Battery

Tracking/localization

Compute power

Spatial understanding

Spatial audio

Input/Interactions



2001 vs. 2018 - Same Challenges

Display

Optics

Battery

Tracking/localization

Compute power

Spatial understanding

Spatial audio

Input/Interactions



What kind of interactions will define the MR era?

Compelling MR interactions will be
adaptive,
believable, and
computational.



Compelling MR interactions will be
adaptive,
believable, and
computational.



Magic of MR interactions happens when they are tightly coupled to the user's environment.

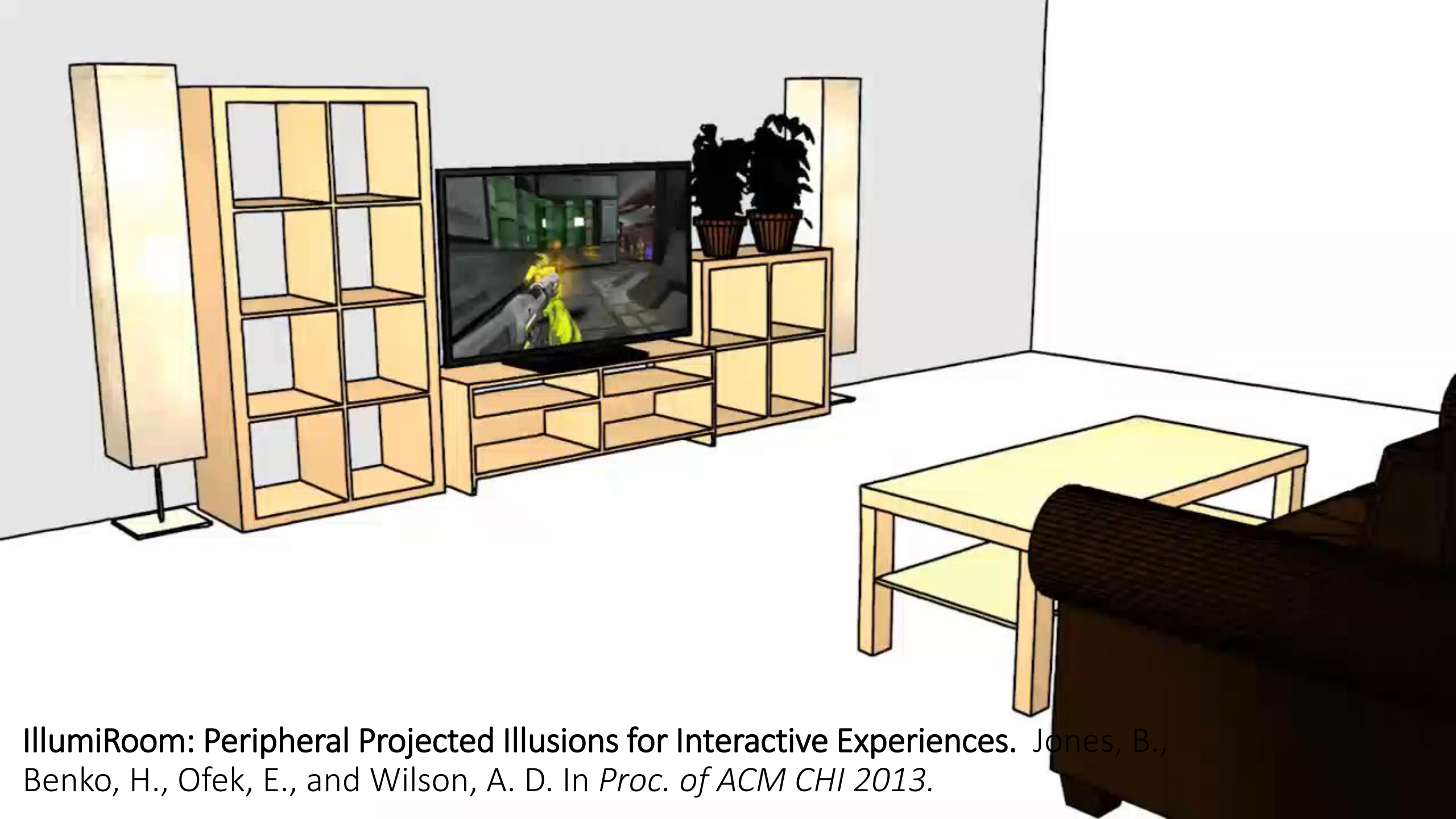
Projection AR



Projector



Depth Camera
(Kinect)



IllumiRoom: Peripheral Projected Illusions for Interactive Experiences. Jones, B., Benko, H., Ofek, E., and Wilson, A. D. In *Proc. of ACM CHI 2013*.



Context Full

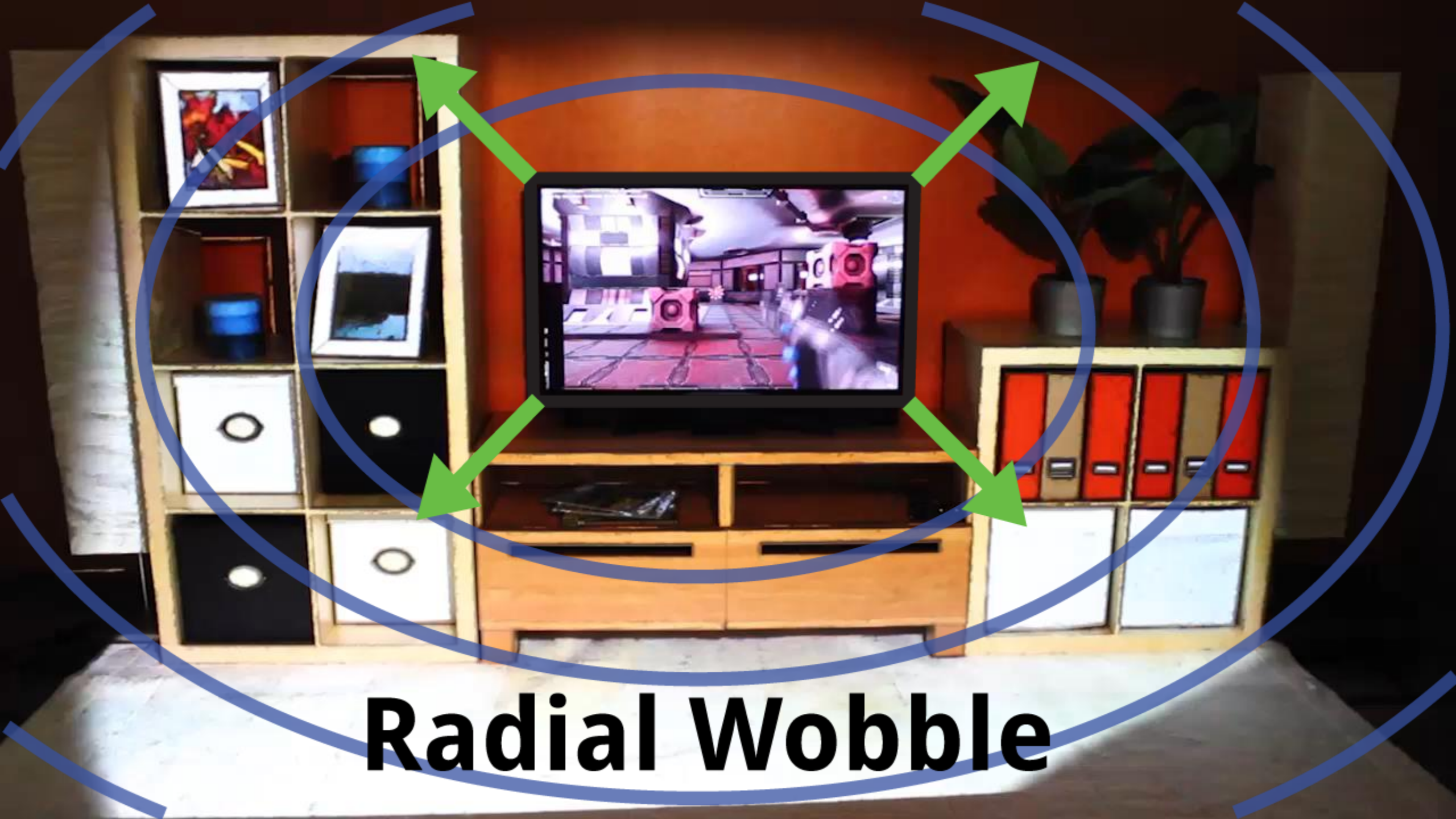
Segmented



FOCUS



Appearance



Radial Wobble

Lighting



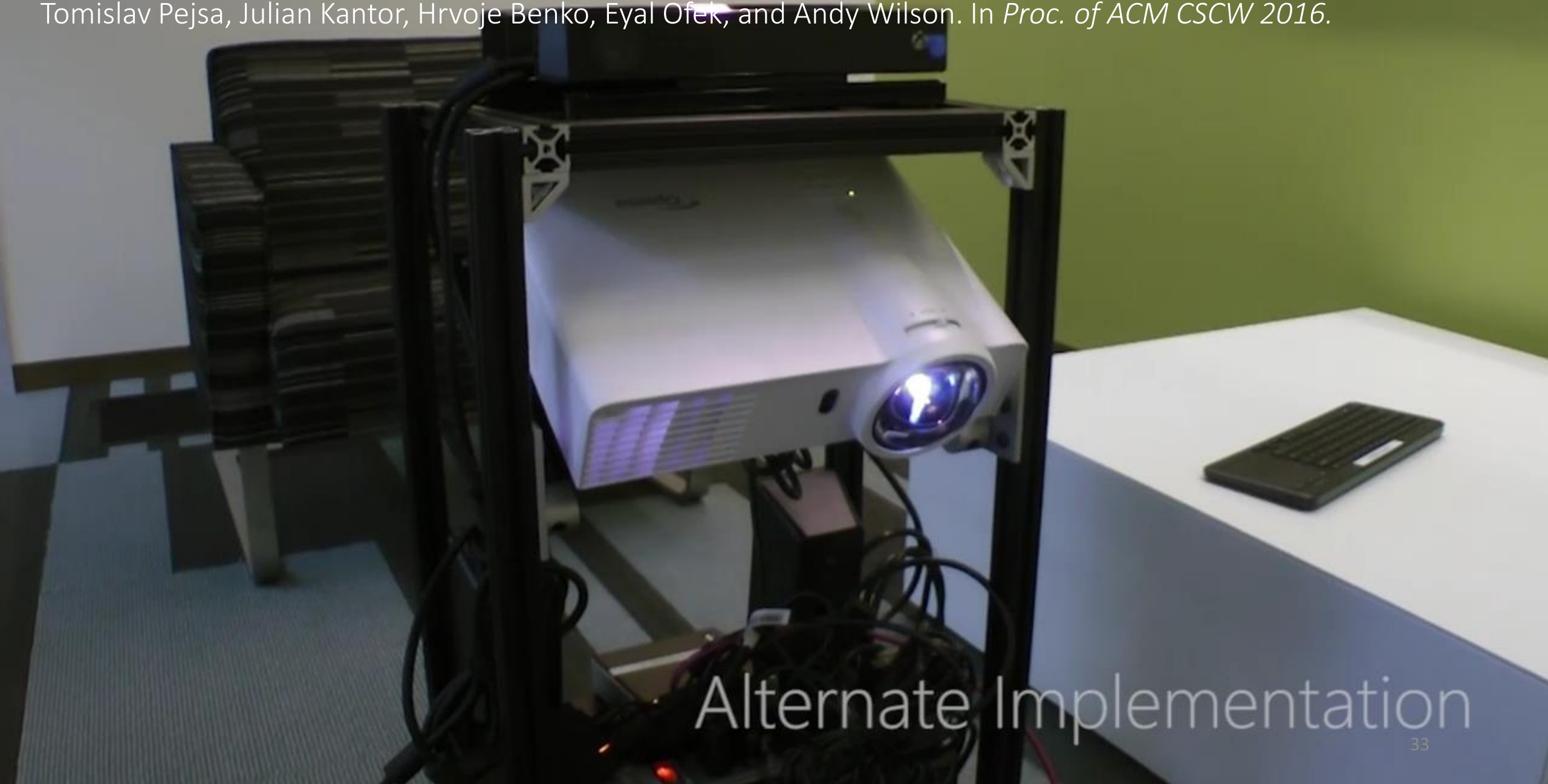
Steerable Augmented Reality with the Beamatron

**Andy Wilson, Hrvoje Benko, Shahram Izadi and Otmar Hilliges
Microsoft Research**

ACM UIST 2012



Room2Room: Enabling Life-Size Telepresence in a Projected Augmented Reality Environment.
Tomislav Pejša, Julian Kantor, Hrvoje Benko, Eyal Ofek, and Andy Wilson. In *Proc. of ACM CSCW 2016*.



Alternate Implementation

Magic of MR interactions happens
when they are tightly coupled to the
user's ~~environment~~.
context

Context

environment

(e.g., space geometry, object semantics, people around)

user actions

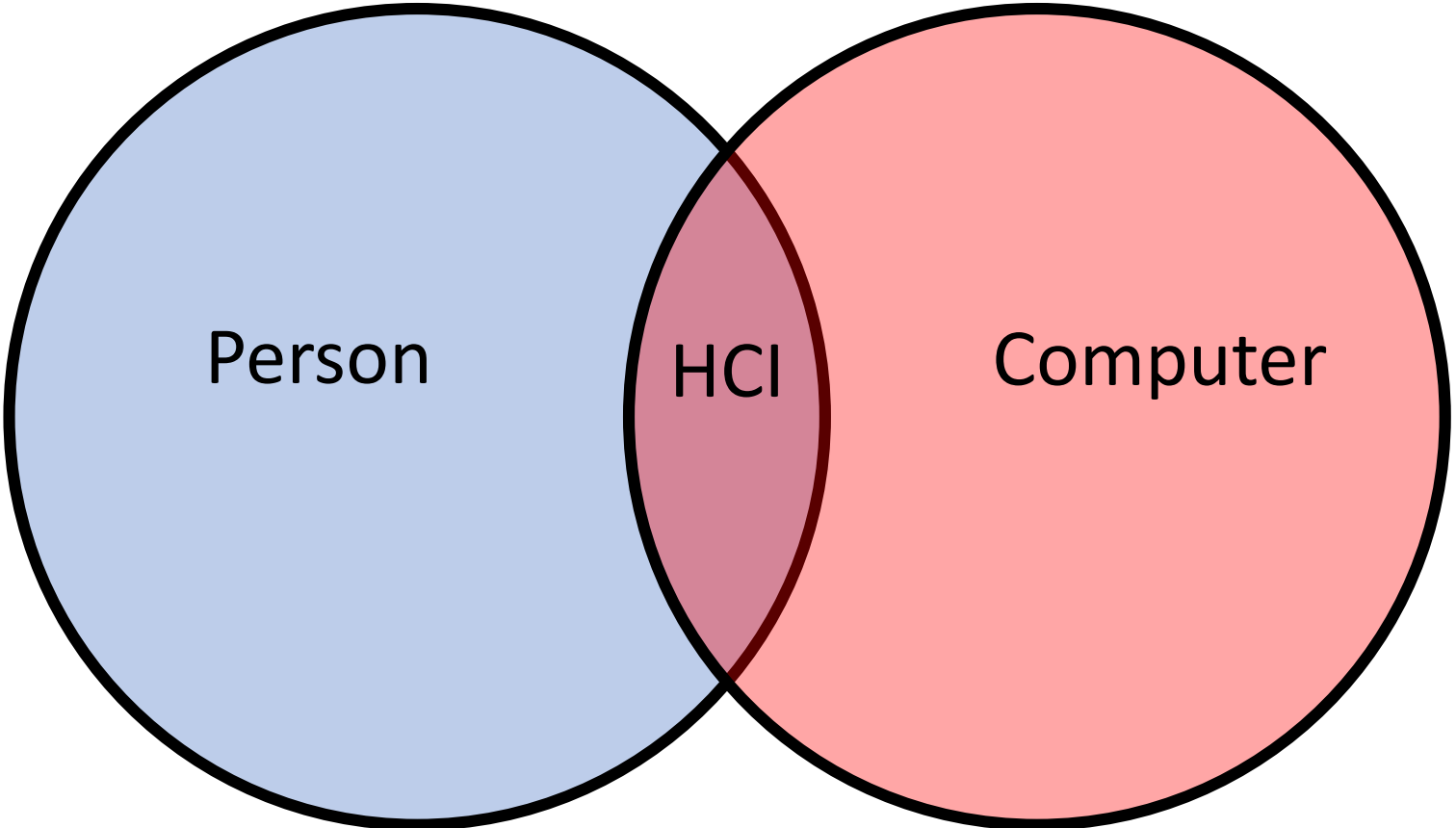
(e.g., gestures, body pose, bio-signals)

user's mental state

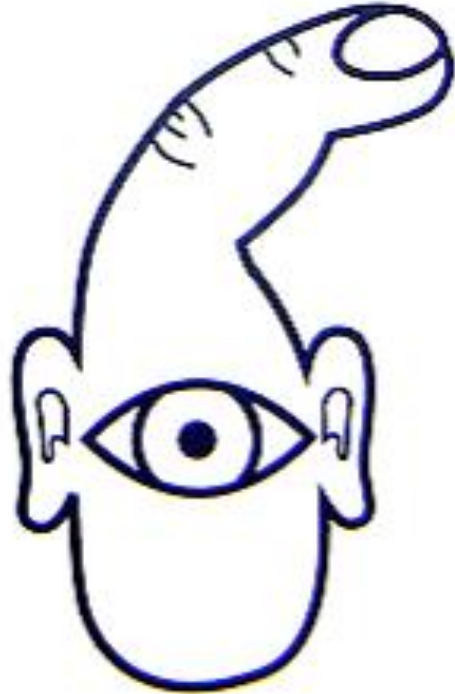
(e.g., emotional, mental load, cognitive, focus)

task

(e.g., communication, navigation, calendar)

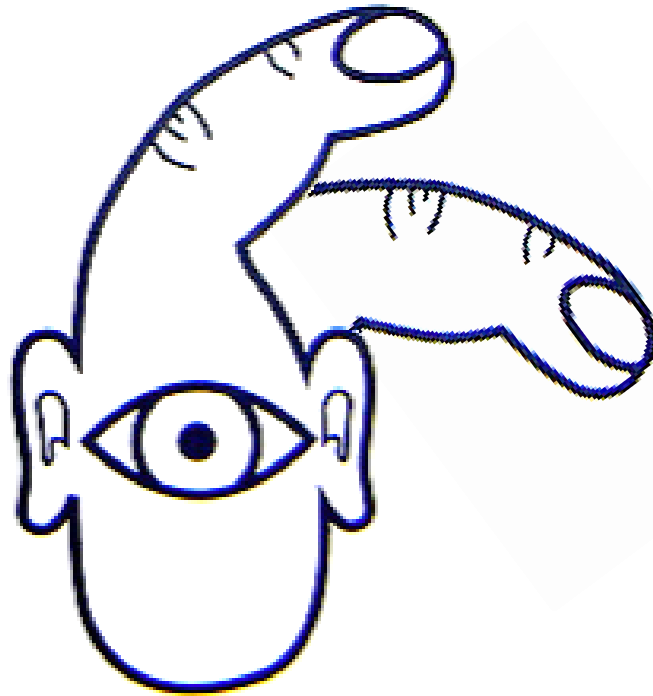


How the computer sees us!

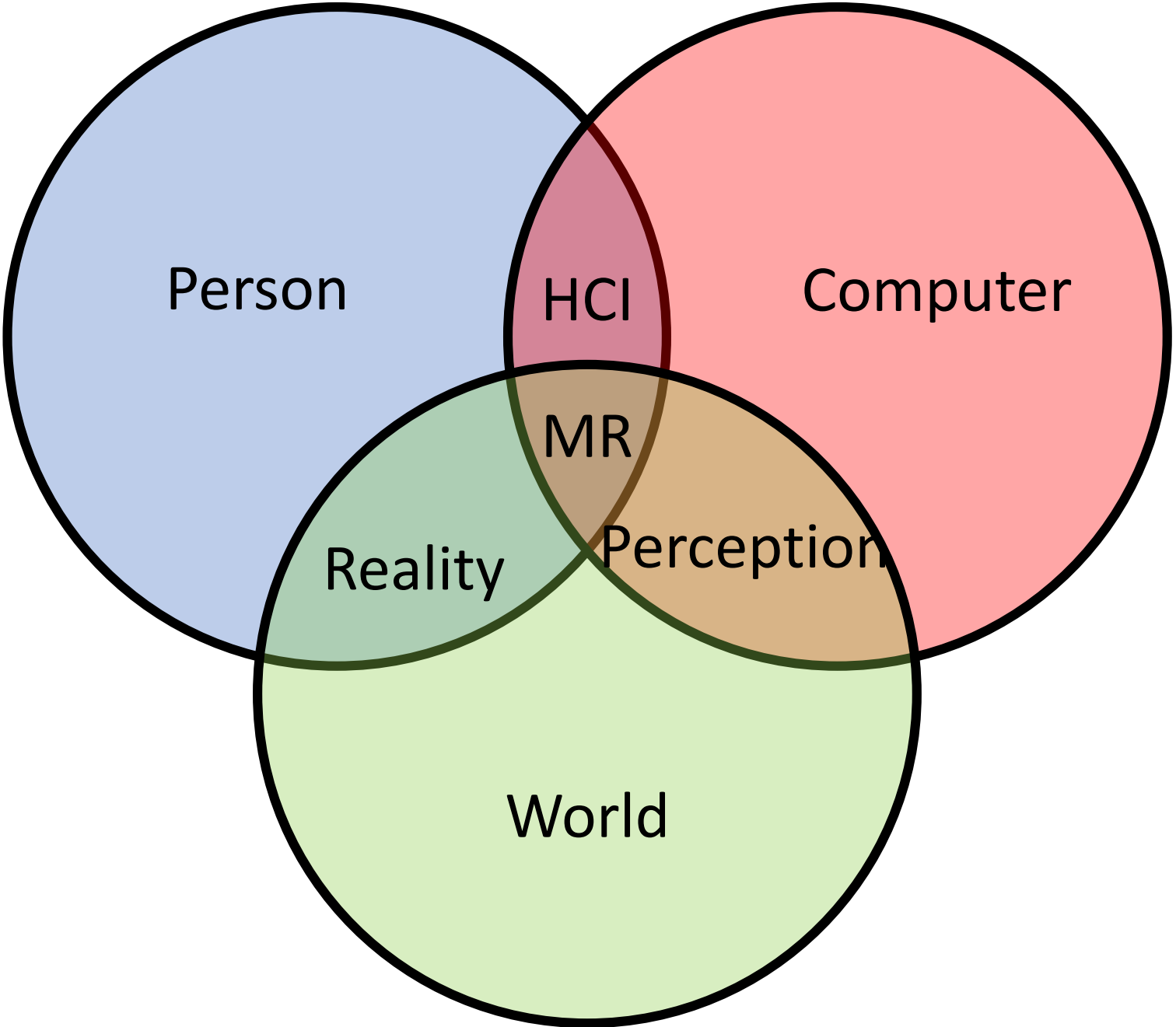


Tom Igoe and Dan O'Sullivan - *Physical Computing*. 2004.

How the phone sees us!



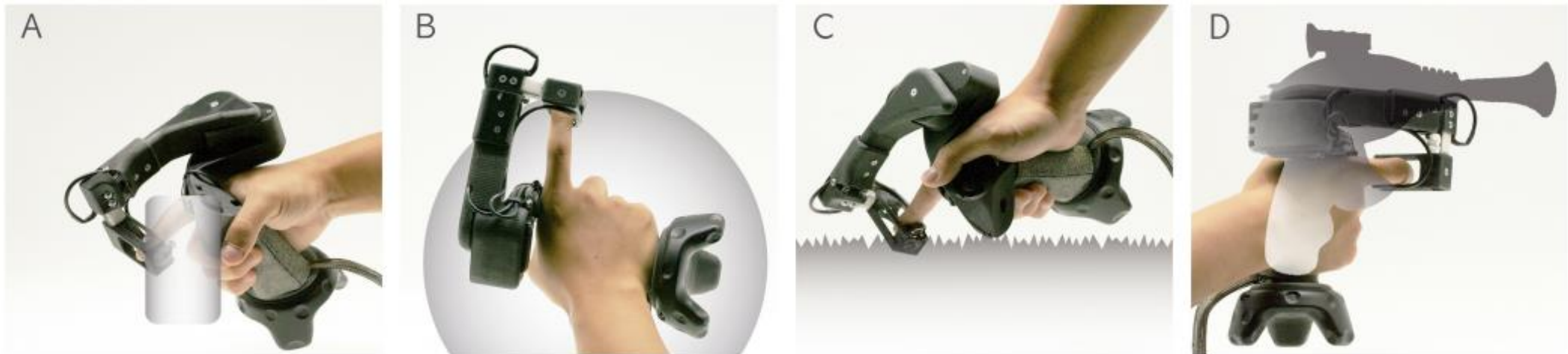
Modified Tom Igoe and Dan O'Sullivan - *Physical Computing*. 2004.



Example: Context-aware Tools

CLAW:

Multi-purpose controller that *adapts* to the user's context of use.





CLAW

Choi, I., Ofek, E., Benko, H., Sinclair, M. and Holz, C. CLAW: A Multifunctional Handheld Haptic Controller for Grasping, Touching, and Triggering in Virtual Reality. In *Proc. of ACM CHI '18*.



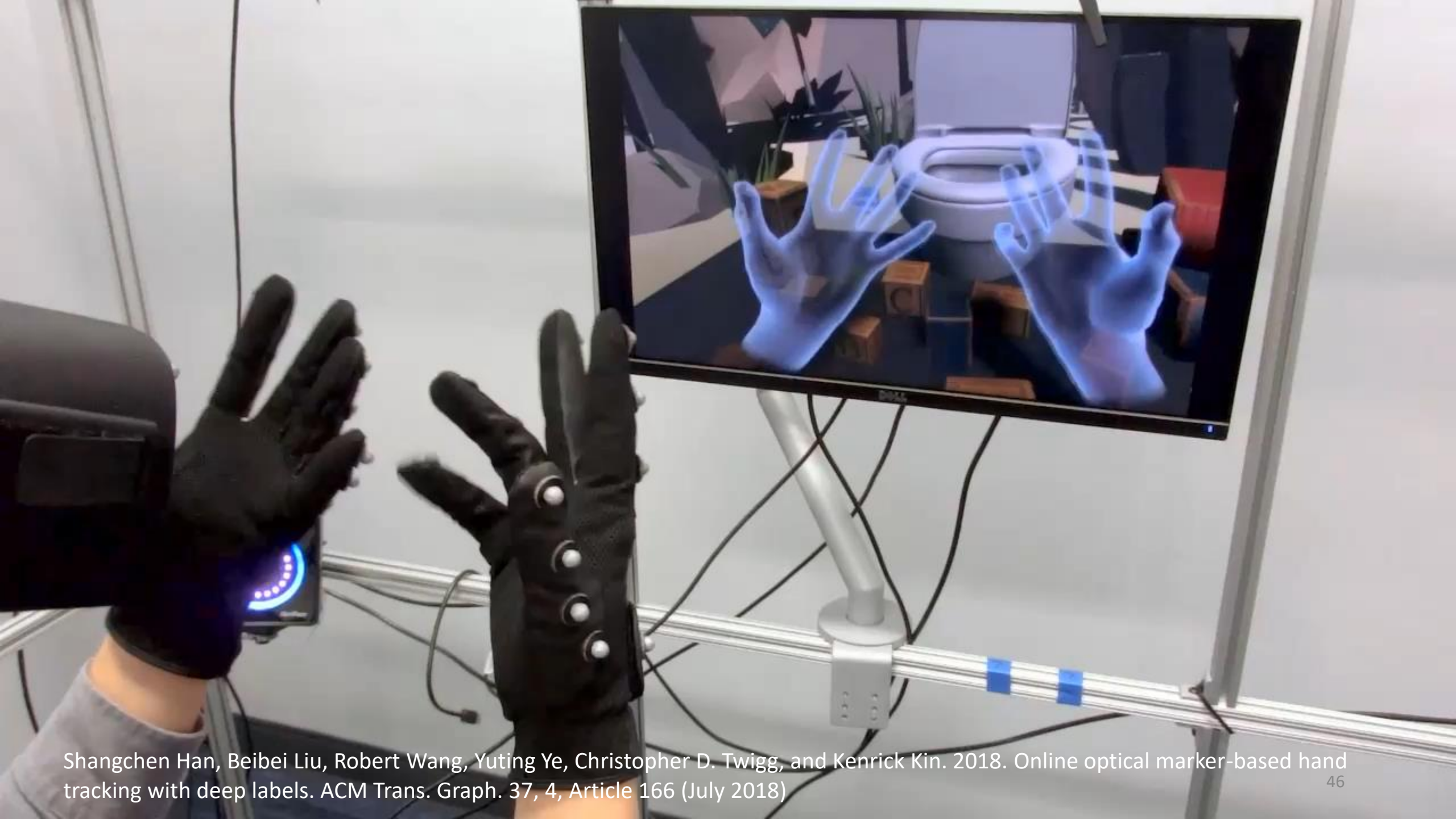
Force Sensor



Servo Motor

Voice Coil

Example: Hand interactions
adapted to the environment



Accurate, Robust, and Flexible Real-time Hand Tracking

Toby Sharp[†] Cem Keskin[†] Duncan Robertson[†] Jonathan Taylor[†] Jamie Shotton[†]
David Kim Christoph Rhemann Ido Leichter Alon Vinnikov Yichen Wei
Daniel Freedman Pushmeet Kohli Eyal Krupka Andrew Fitzgibbon* Shahram Izadi*

Microsoft Research



Figure 1: We present a new system for tracking the detailed motion of a user’s hand using only a commodity depth camera. Our system can accurately reconstruct the complex articulated pose of the hand, whilst being robust to tracking failure, and supporting flexible setups such as tracking at large distances and over-the-shoulder camera placement.

ABSTRACT

We present a new real-time hand tracking system based on a single depth camera. The system can *accurately* reconstruct complex hand poses across a variety of subjects. It also allows for *robust* tracking, rapidly recovering from any temporary failures. Most uniquely, our tracker is highly *flexible*, dramatically improving upon previous approaches which have

the user’s hand with gloves or markers can be cumbersome and inaccurate. Much recent effort, including this work, has thus focused on camera-based systems. However, cameras, even modern consumer depth cameras, pose further difficulties: the fingers can be hard to disambiguate visually and are often occluded by other parts of the hand. Even state of the art academic and commercial systems are thus sometimes in

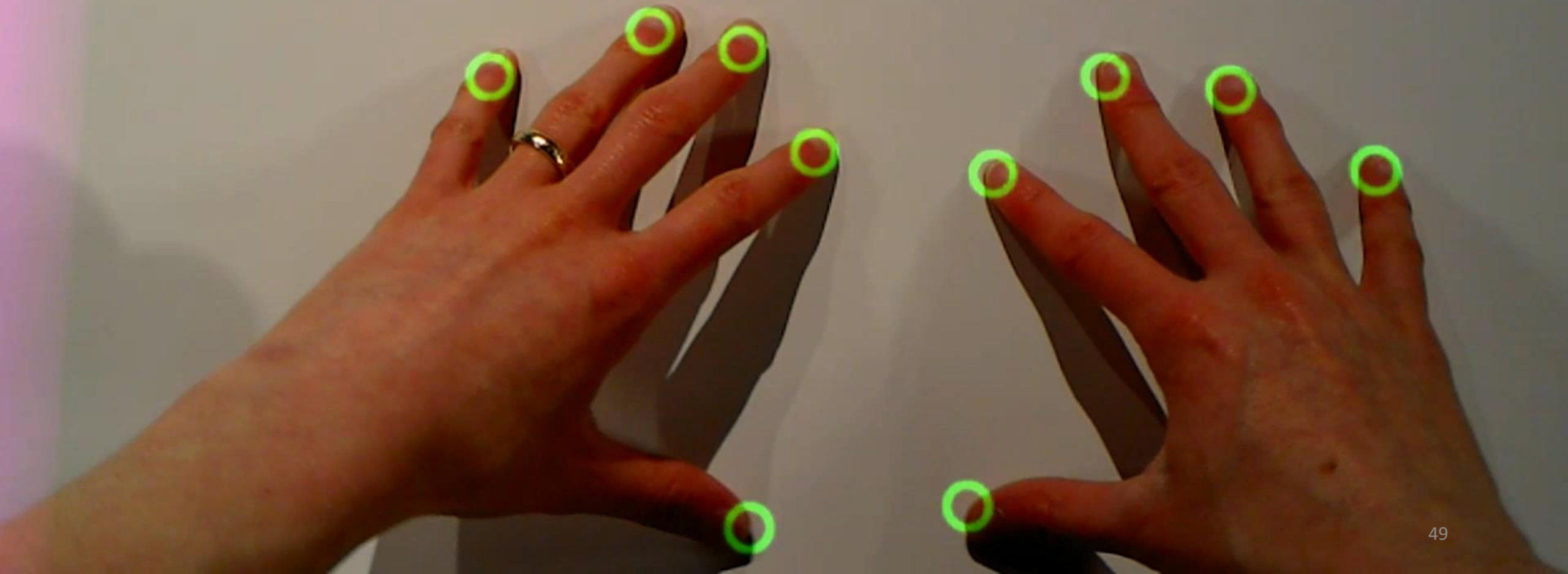
One small problem...

People don't generally interact in mid air!

People interact with objects and on surfaces!



Hand interaction context = any available surface



Depth



Reflectivity



MRTouch: Adding Touch to Head Mounted Mixed Reality.

Robert Xiao, Julia Schwarz, Nick Throm, Andrew D. Wilson, Hrvoje Benko. IEEE TVCG 2018 (Vol 24, No 4, April 2018)

Sample Interactions

(Continuous shot, first and only take)

FYI....

Hololens Research Mode API

Depth and reflectivity data now part of the public Research Mode API (developer mode only)

- <https://github.com/Microsoft/HoloLensForCV>
- Possible now to implement MRTouch using only public APIs

Compelling MR interactions will be
adaptive,
believable, and
computational.



In MR, we are obsessed with creating a
rich sense of *reality*!

Deep Appearance Models for Facial Rendering

**STEPHEN LOMBARDI, JASON SARAGIH,
TOMAS SIMON, YASER SHEIKH**
Facebook Reality Labs



For interactions,
realistic is not always better

Believable \neq Realistic

Believable =
consistent with user's
expectations + non surprising

In AR/VR we want to induce the suspension of disbelief, whereby users suspend their critical faculties (i.e., sacrifice logic and realism) to believe the unbelievable.

Haptic Revolver

Touch, Shear, Texture, and Shape Rendering
on a Reconfigurable VR Controller

Eric Whitmire¹, Hrvoje Benko², Christian Holz²,
Eyal Ofek², Mike Sinclair²



¹Paul G. Allen School, University of Washington

²Microsoft Research, Redmond

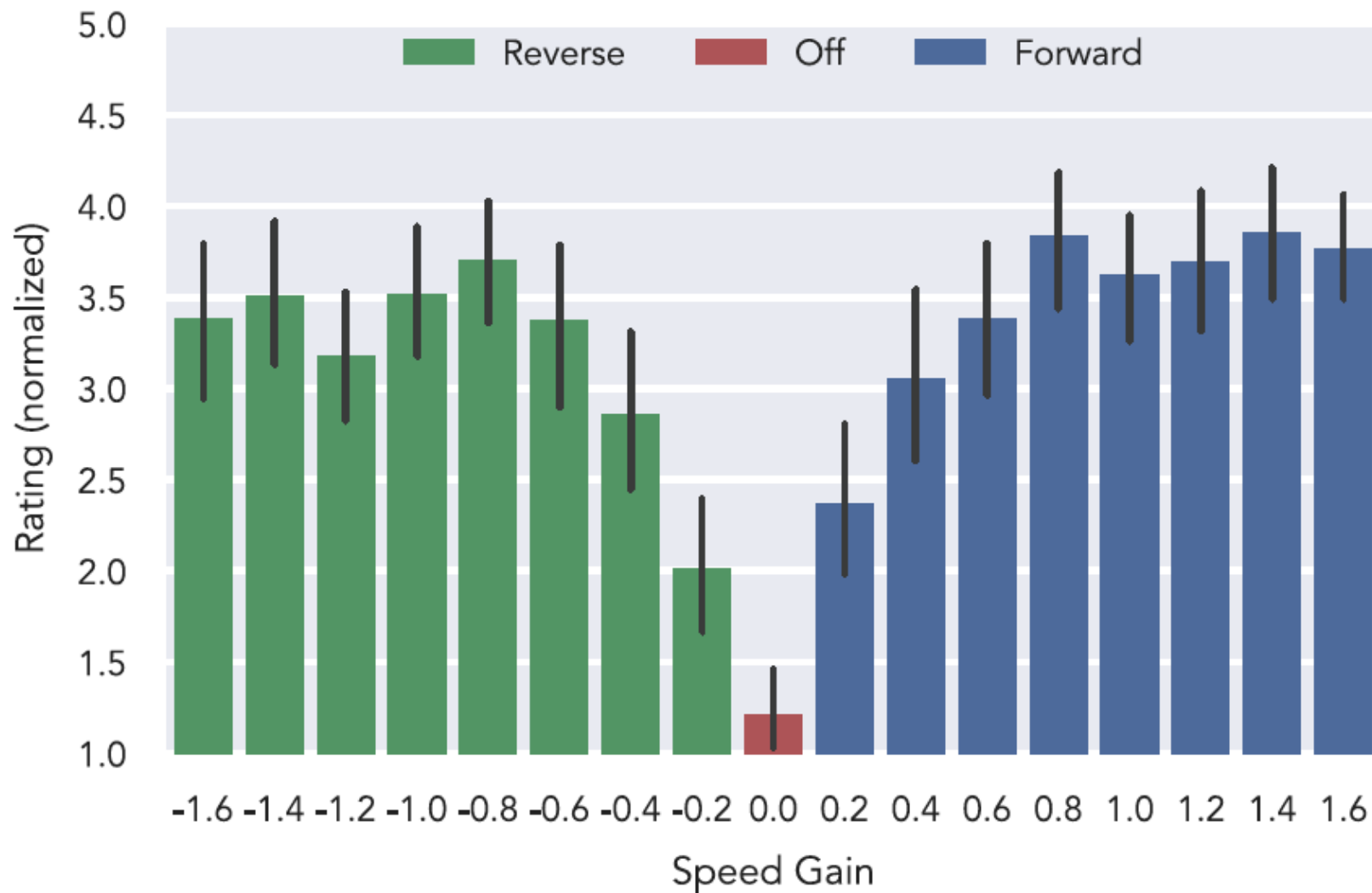
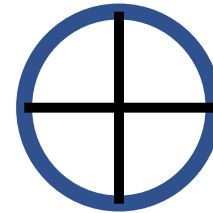


Figure 10. Results of the first user study showing mean realism ratings across participants as a function of the wheel speed gain. The error bars show a 95% confidence interval. A negative gain indicates the wheel was spun in the opposite direction.

Hand Movement



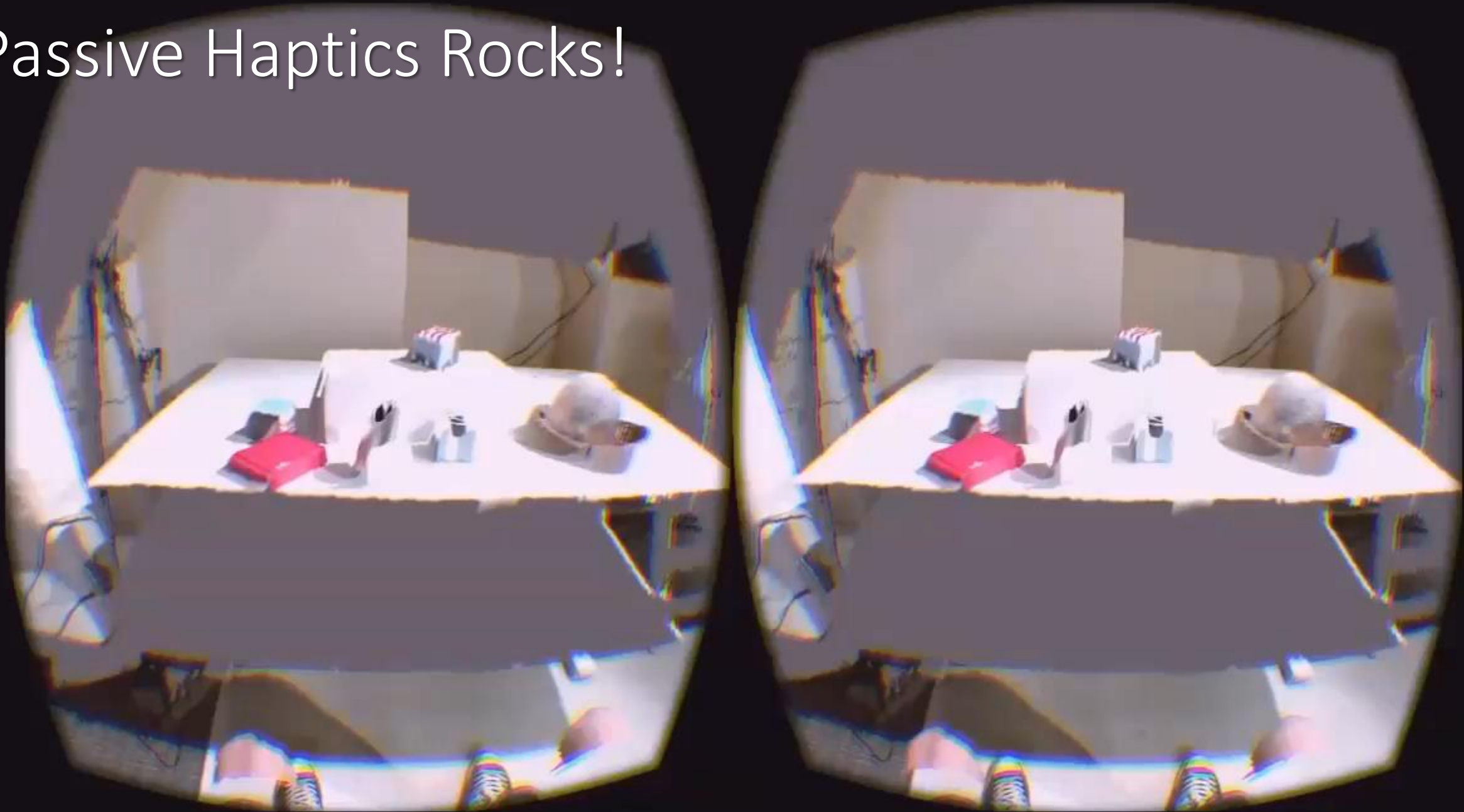
Wheel Movement



Haptic Retargeting

Azmandian, M., Hancock, M., Benko, H., Ofek, E., and Wilson, A. *Haptic Retargeting: Dynamic Repurposing of Passive Haptics for Enhanced Virtual Reality Experiences*. In *Proc. of ACM CHI 2016*.

Passive Haptics Rocks!





Putting it all together...

Focusing on “as real as possible”
designs can lead to sub-optimal
MR experience.

Design for BELIEVABILITY, not REALISM.

Compelling MR interactions will be
adaptive,
believable, and
computational.



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(text based)

Graphical User Interfaces
(mouse + keyboard)

Natural User Interfaces
(touch/gestures, tablets, smartphones)

Mixed Reality Interfaces

1960s

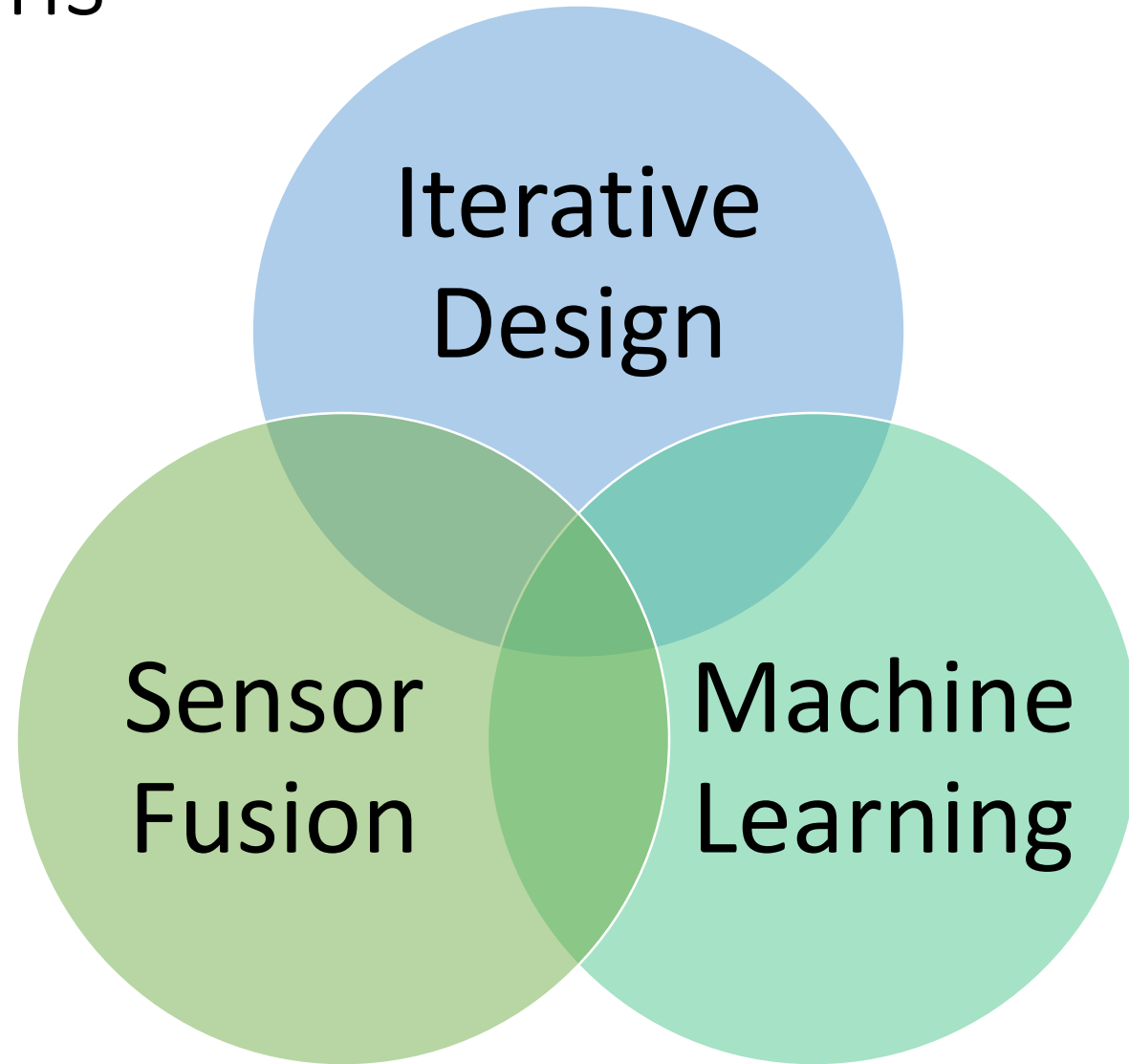
1980s

2000s

2020s



AR Interactions



Can you type on a phone touch keyboard?



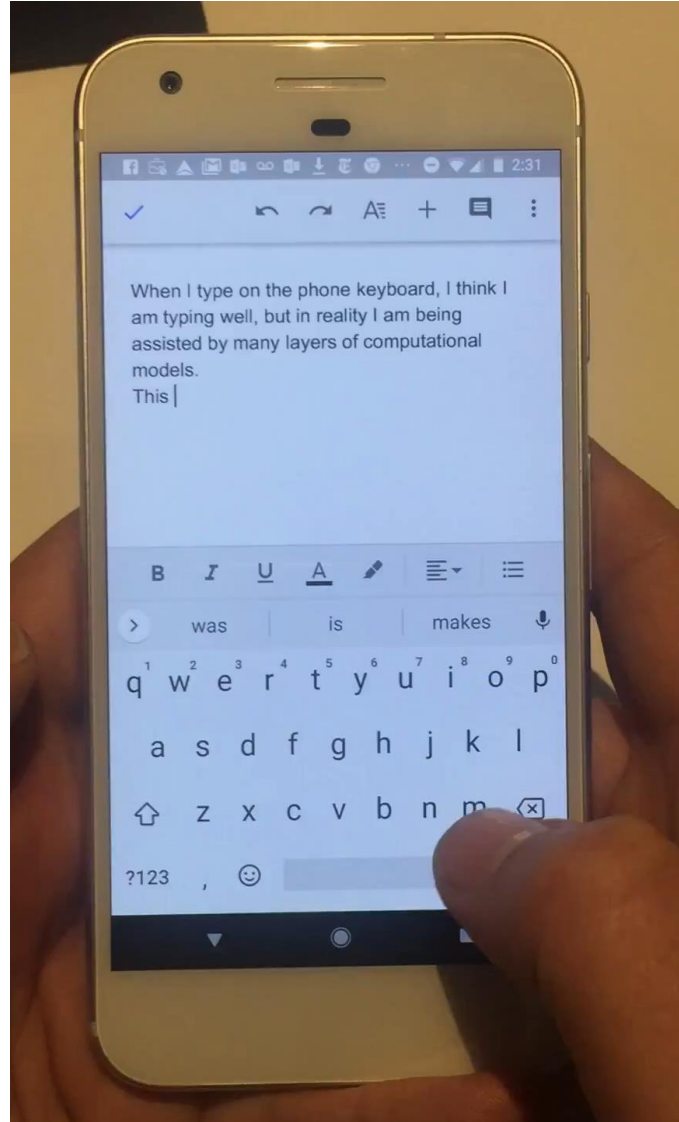
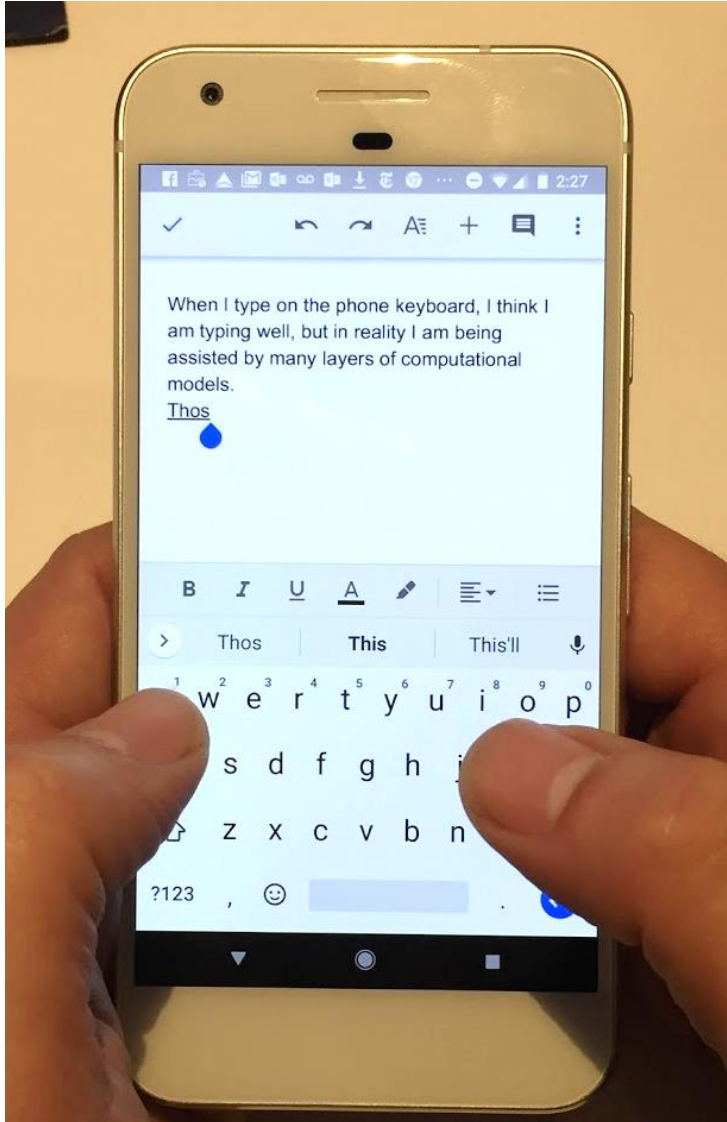
Modern Android touch keyboard (two thumbs)

No correction – 27.5 WPM, error rate 6.5%

With correction – 31 WPM, error rate 1.1%

Reyal, S., Zhai, S. and Kristensson, P.O. Performance and user experience of touchscreen and gesture keyboards in a lab setting and in the wild. In Proc. ACM CHI 2015. 679-688.

Probabilistic phone touch keyboard



Layers of probabilistic models:

- Touch precision model
- Dictionary model
- Language model

+ N-best list UI for error correction

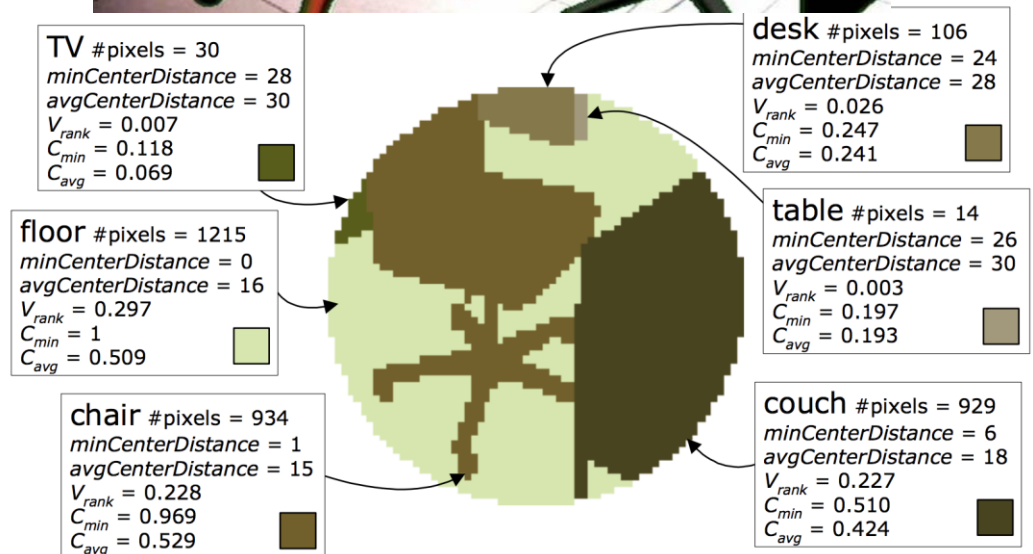
+ Gesture model

Similar optimizations needed in MR

- Text entry

Similar optimizations needed in MR

- Text entry
- Object selection



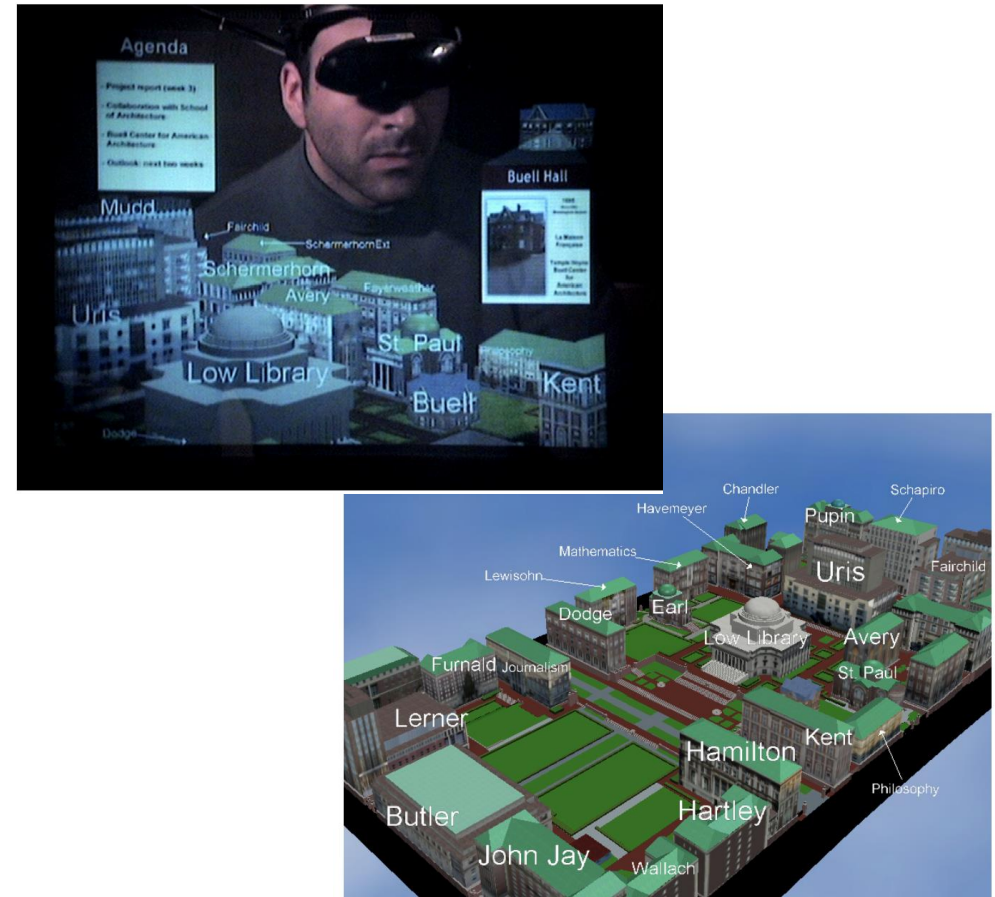
Olwal, A., Benko, H., Feiner, S. SenseShapes: Using Statistical Geometry for Object Selection in a Multimodal Augmented Reality System. *In Proc. ISMAR '03*. 300-301.

Similar optimizations needed in MR

- Text entry
- Object selection
- (Multimodal) input fusion

Similar optimizations needed in MR

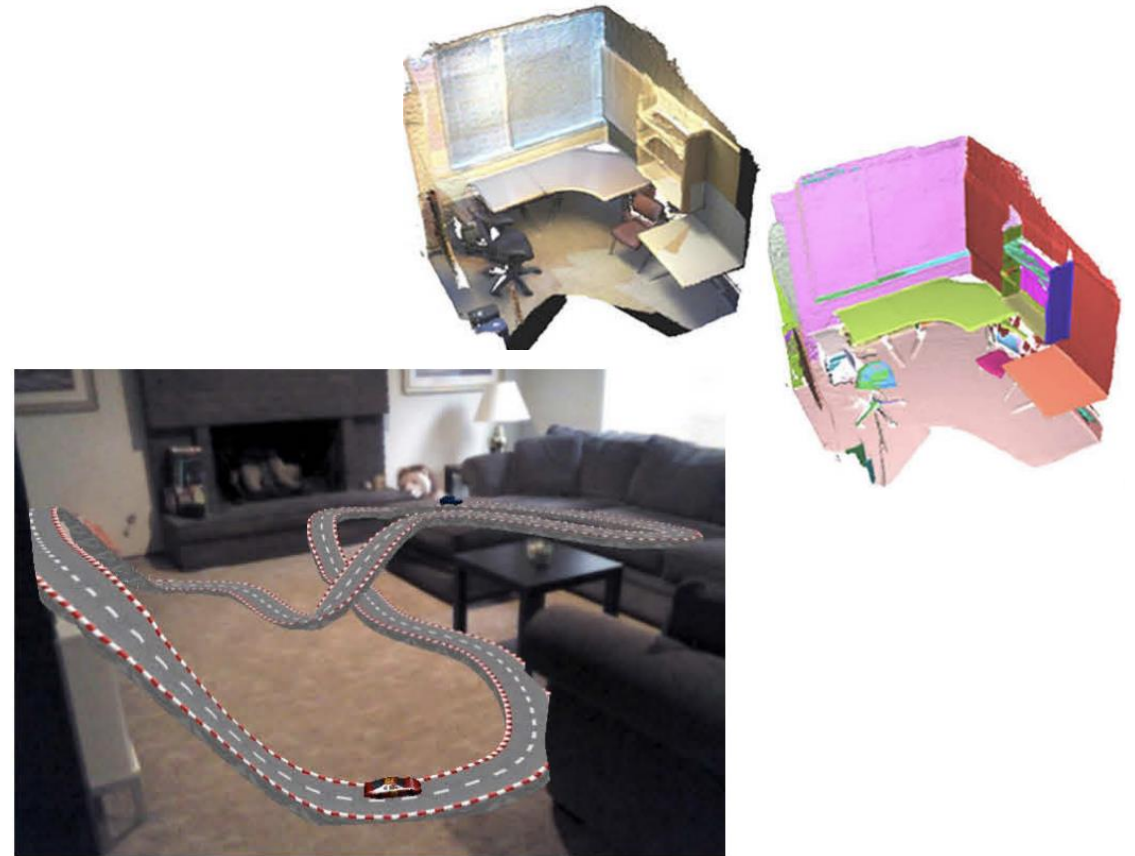
- Text entry
- Object selection
- Multimodal input fusion
- Output optimizations



Bell B., Feiner, S., and Hollerer, T. View Management for Virtual and Augmented Reality. In Proc. ACM UIST 2001.

Similar optimizations needed in MR

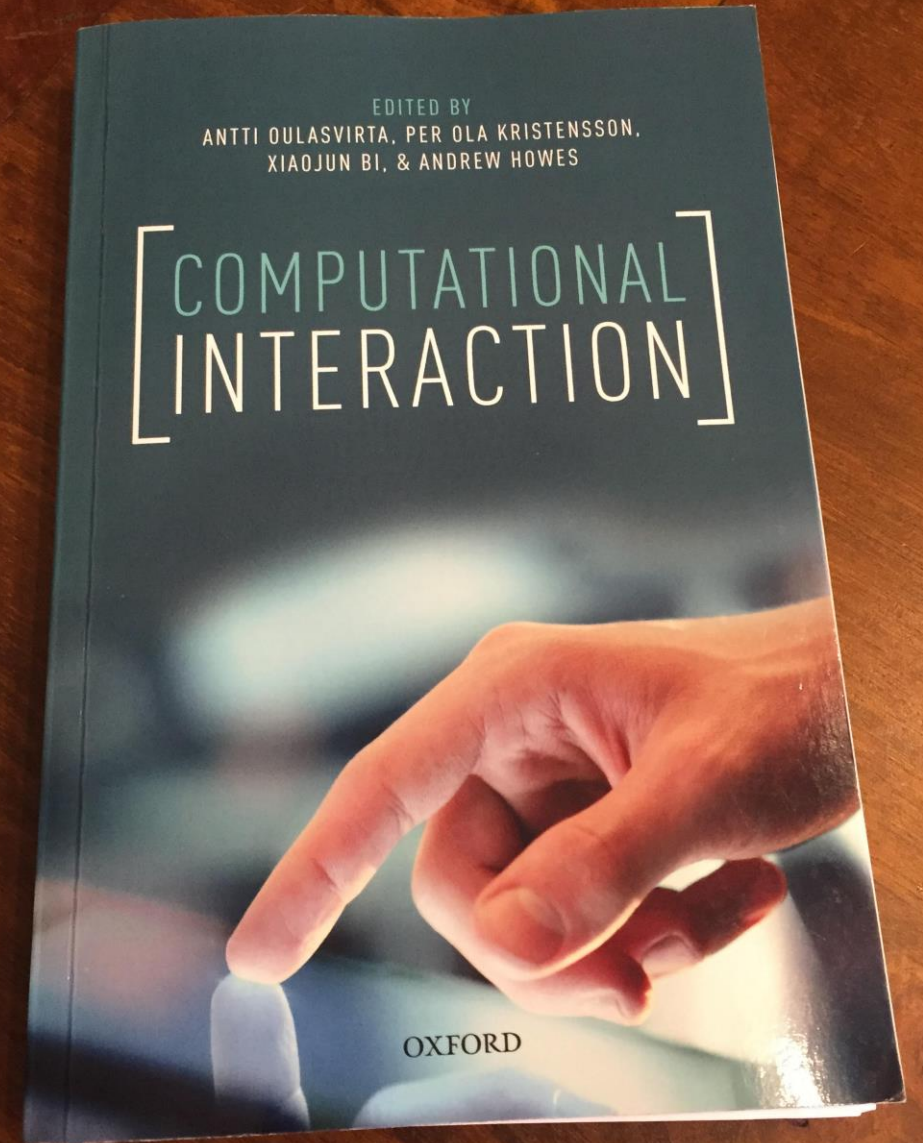
- Text entry
- Probabilistic object selection
- Multimodal input fusion
- Output optimizations



Gal R., Shapira, L., Ofek, E., Kohli, P. FLARE: Fast Layout for Augmented Reality Applications. In Proc. IEEE ISMAR 2014.

formulate the UI challenges as
computational problems
(inferring, sensor fusing,
predicting, tolerating noise)

that adapt the interface
depending on the user and world
context



Compelling MR interactions will be
adaptive,
believable, and
computational.



Maybe it should have been the CAB of MR Interactions?



Design interactions that adapt to the user's actions, the world around them, and the context of use.

Focus on believability. Reality is overrated!

Harness the computational methods to overcome uncertainty, scale, noise, and enable adaptivity.

A man with short grey hair, wearing a red button-down shirt, is smiling and looking upwards. He is standing behind a VR headset that is positioned in the foreground, partially obscuring his lower body. The background is a plain wall with two framed abstract paintings and a door handle on the right side.

Hrvoje Benko

benko@fb.com

Facebook Reality Labs

Thanks to all my
collaborators!

Extra Slides

Sparse Haptic Proxy: Touch Feedback in Virtual Environments Using a General Passive Prop

Lung-Pan Cheng^{2,1}, Eyal Ofek¹, Christian Holz¹, Hrvoje Benko¹, Andrew D. Wilson¹

¹Microsoft Research

Redmond, WA, USA

{eyalofek, cholz, benko, awilson}@microsoft.com

²Hasso Plattner Institute

Potsdam, Germany

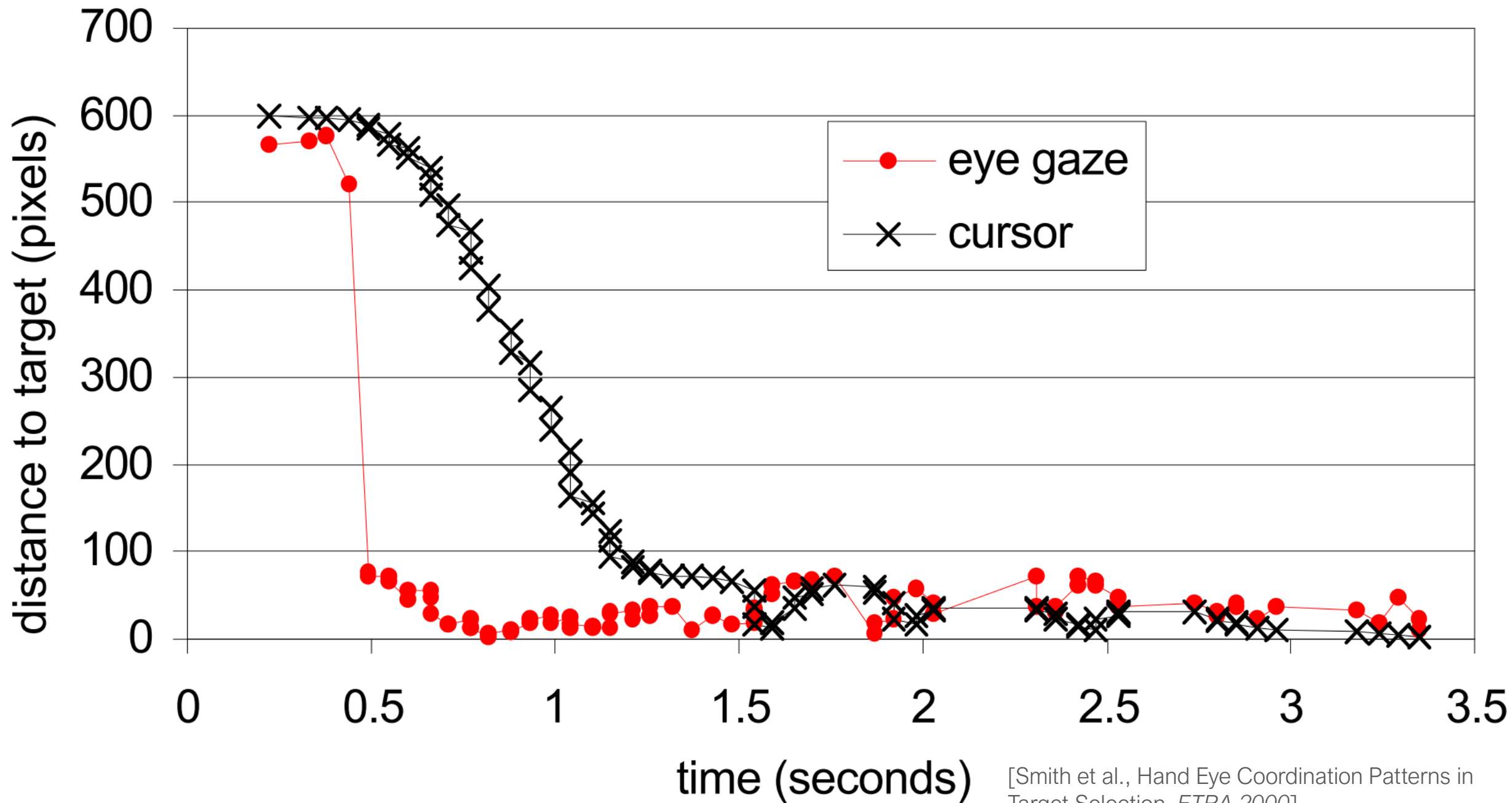
lung-pan.cheng@hpi.de



Figure 1. (a) Our hemispherical prop is an example of a *Sparse Haptic Proxy*. It simulates both, (b) a room and (c) a cockpit scene to provide physical touch feedback during interaction. (White lines on the prop added for visibility on the black background).

ABSTRACT

over better-matching surfaces of our Sparse Haptic Proxy

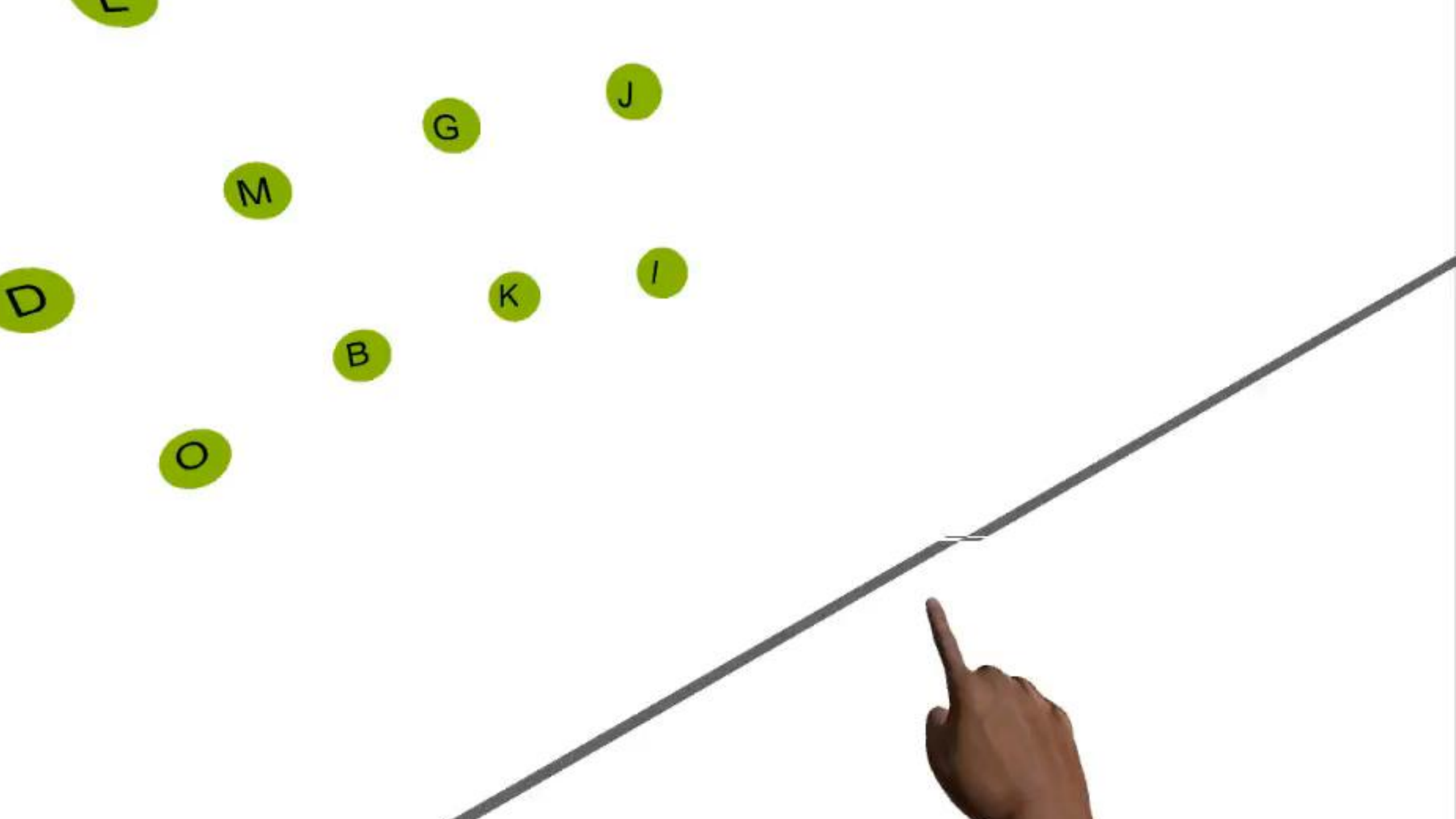


[Smith et al., Hand Eye Coordination Patterns in Target Selection, *ETRA 2000*]

SMI eye-tracking module

250 hz eye-tracker
on Oculus DK2

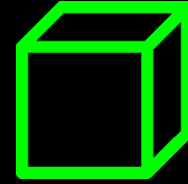
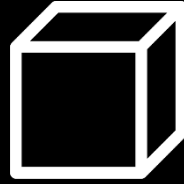




We can predict with 97.5% accuracy
what is the user's intended target
2 seconds before reaching the target!

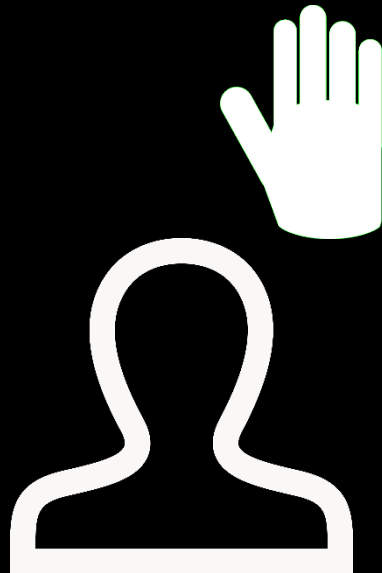
Body Warping

physical
cube



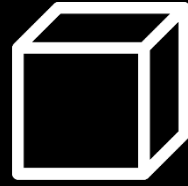
virtual
cube

*The Rendered Body
Shifts to The Right*

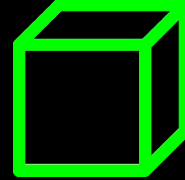


World Warping

physical
cube



30°



virtual
cube

*The World Also Rotates
(At Different Rate)*



IllumiRoom

Peripheral Projected Illusions for Interactive Experiences.

Jones, B., Benko, H., Ofek, E., and Wilson, A. D. In *Proc. of ACM CHI 2013*.



Focus

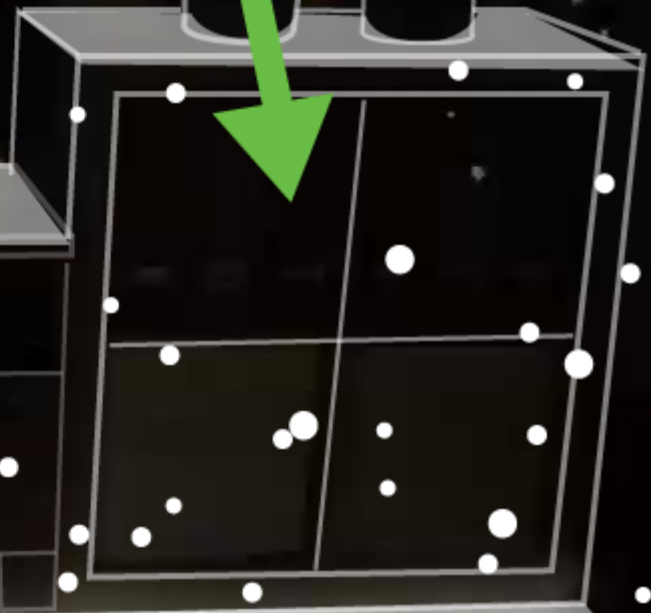
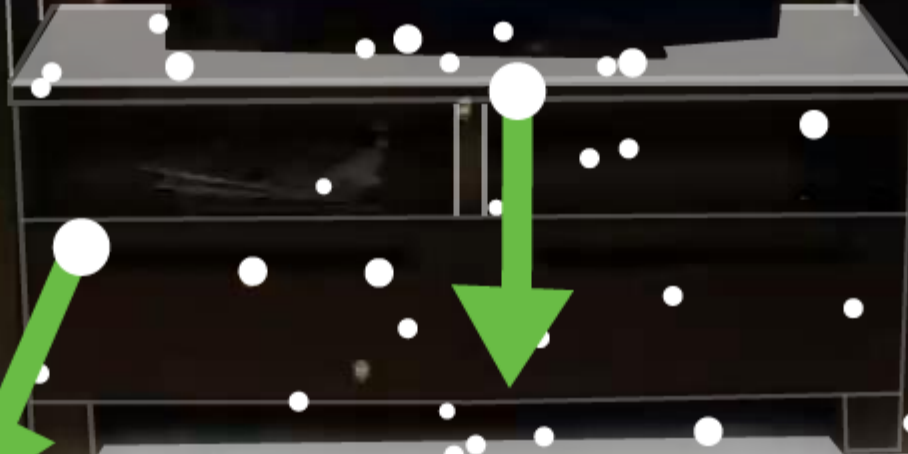
Context Edges

A living room scene with a television set on a stand. The TV screen displays the word "Focus" in large, bold, black letters over a blurred background of a modern interior. To the left is a tall, dark shelving unit with a white grid pattern. To the right is a smaller, dark cabinet with a white grid pattern, topped with two potted plants. The entire scene is overlaid with a white wireframe grid. In the bottom left corner, there is a blue graphic consisting of several parallel diagonal lines, with the word "Selective" written in white, bold, sans-serif font across them.

Focus

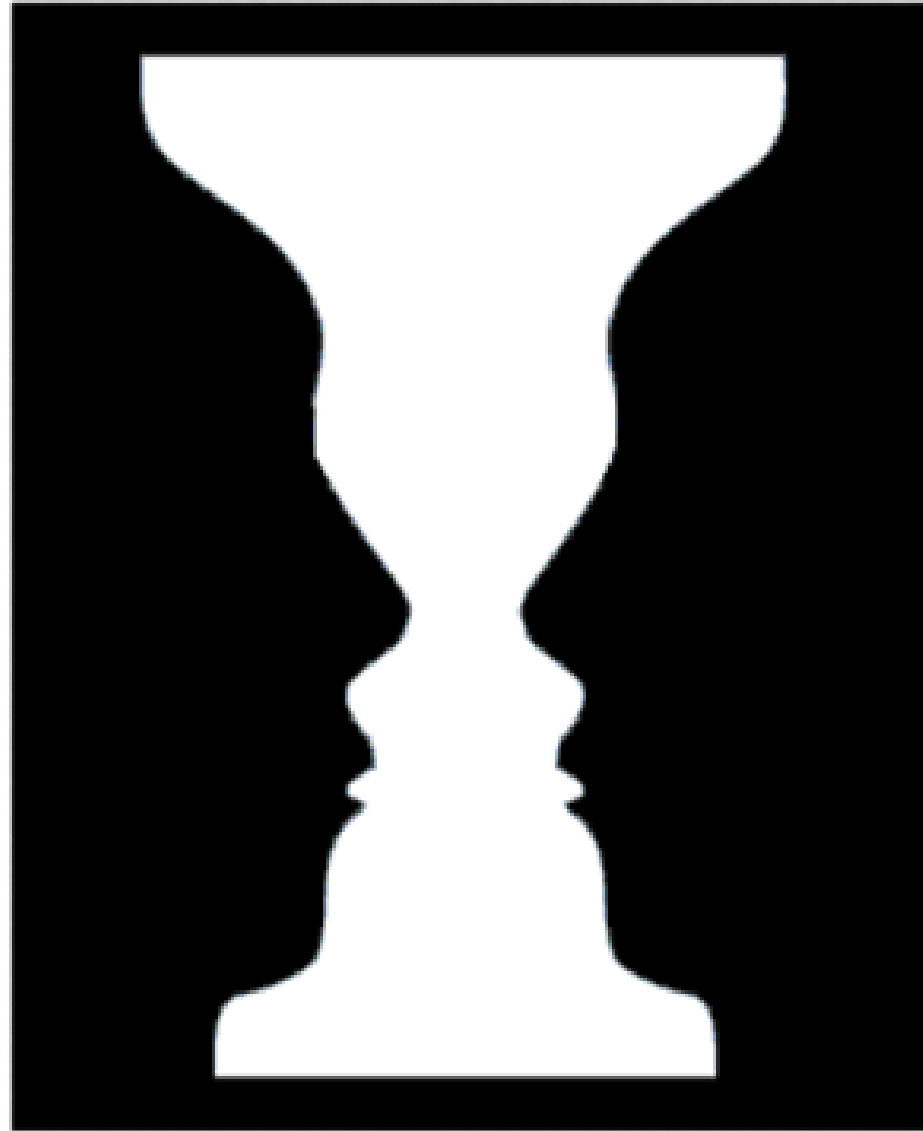
Selective

Snow

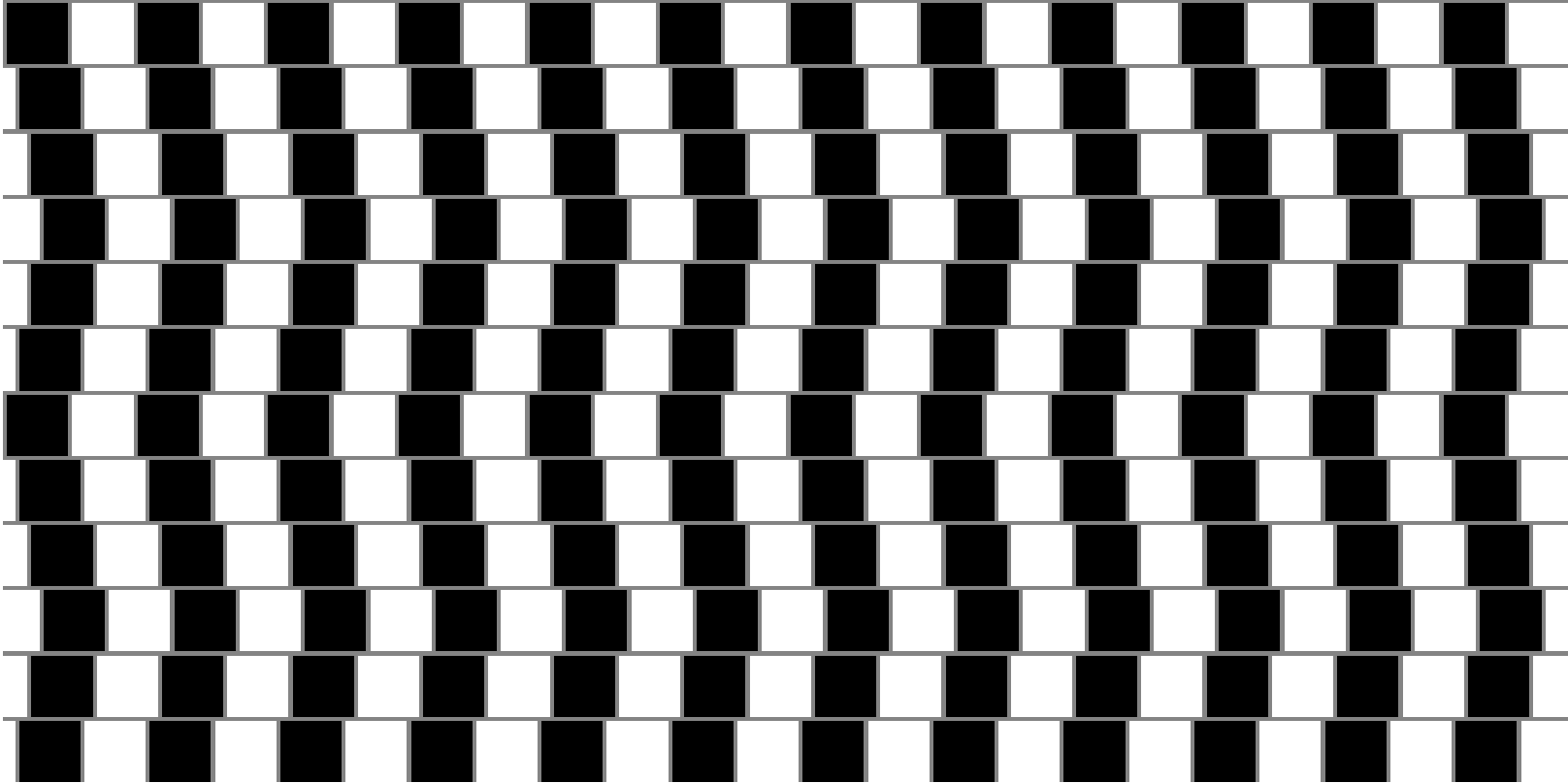


What is “real” vs. what we
“perceive as real” is not
necessarily the same!

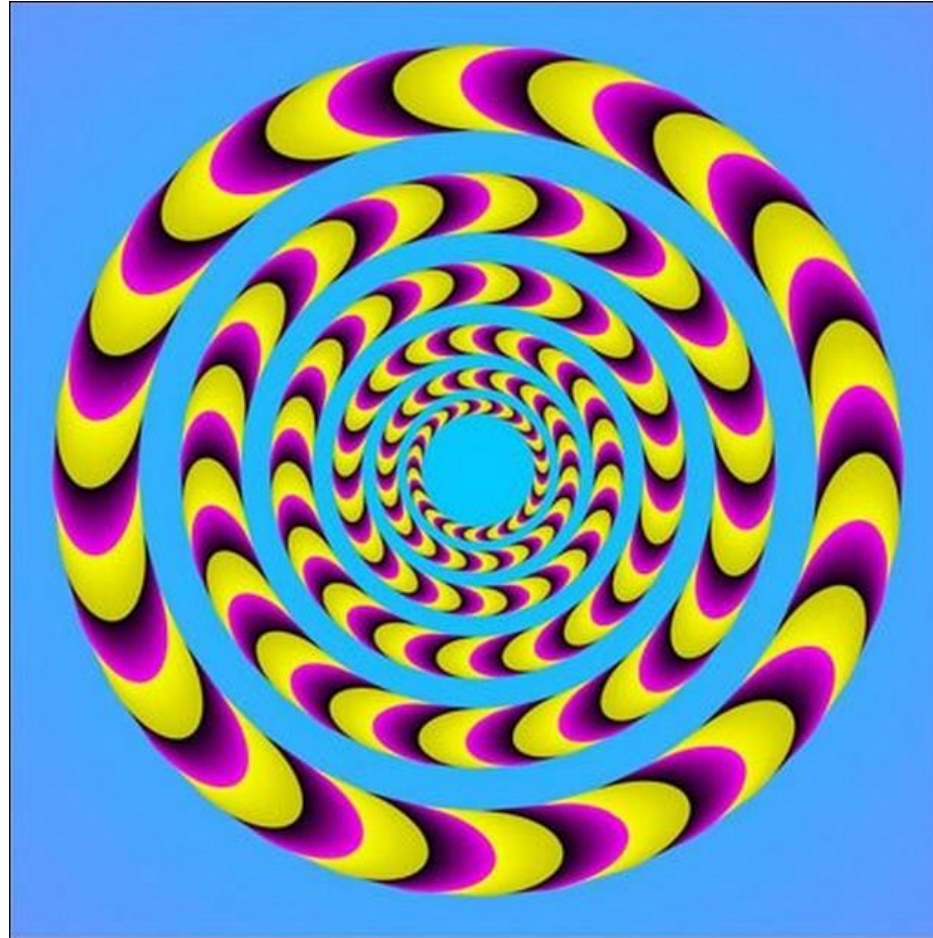
Faces or vase?



Straight or crooked?



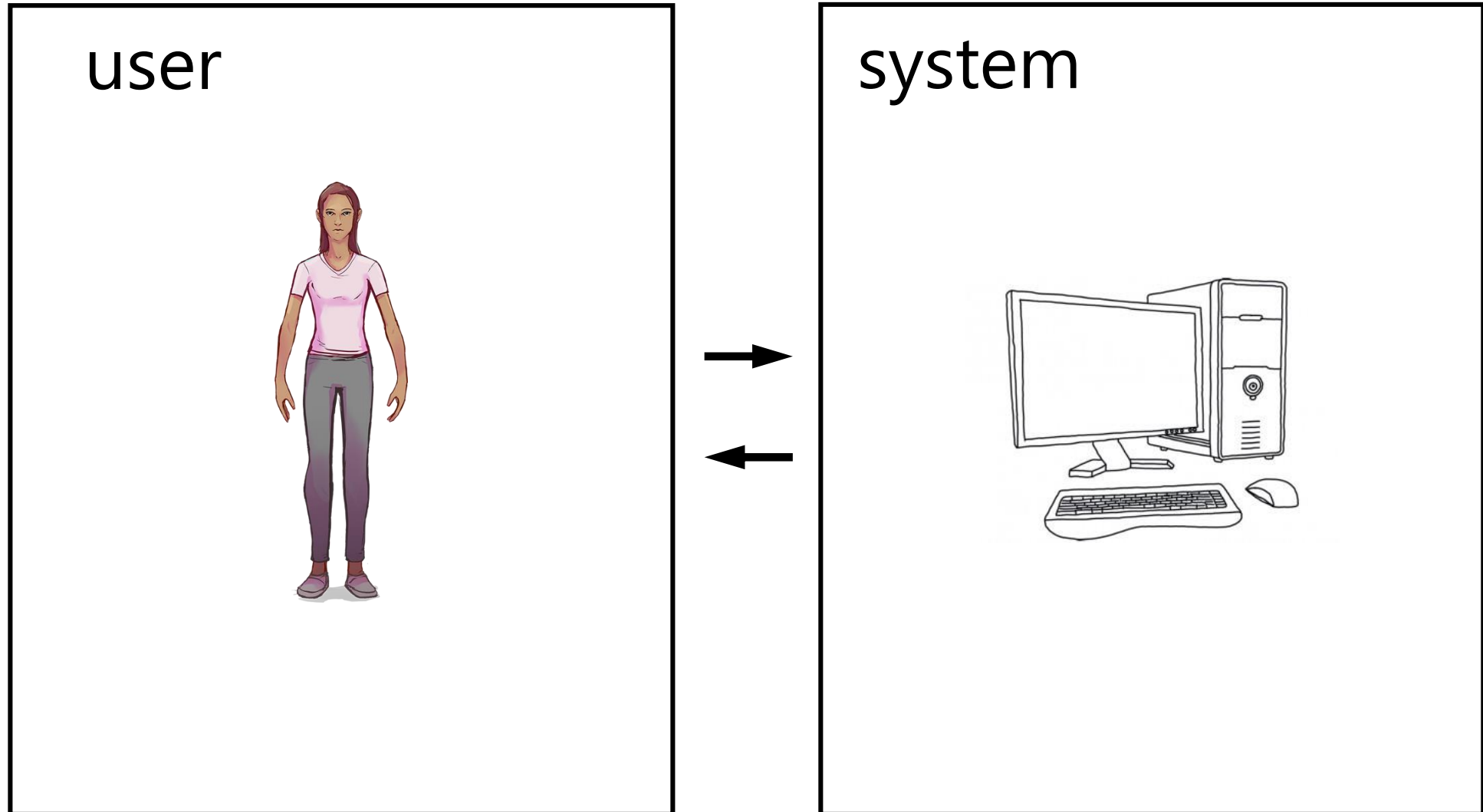
Moving or static?



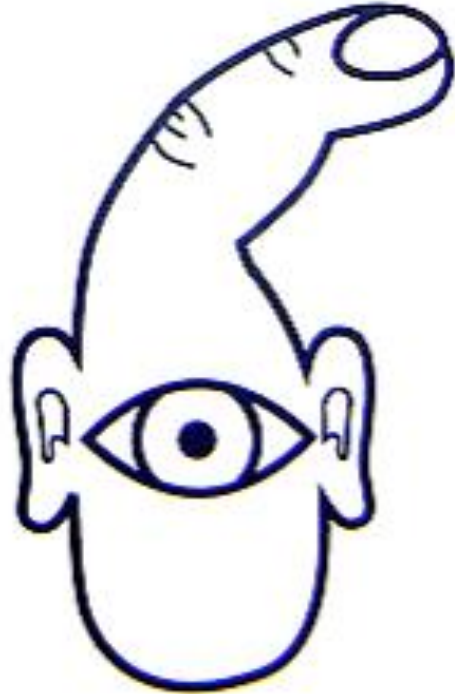
Insisting on “**as real as possible**” designs can lead to **sub-optimal** MR experience.

Think about MR interfaces as **perceptual illusions** that give the user a **believable** experience!

Typical HCI model

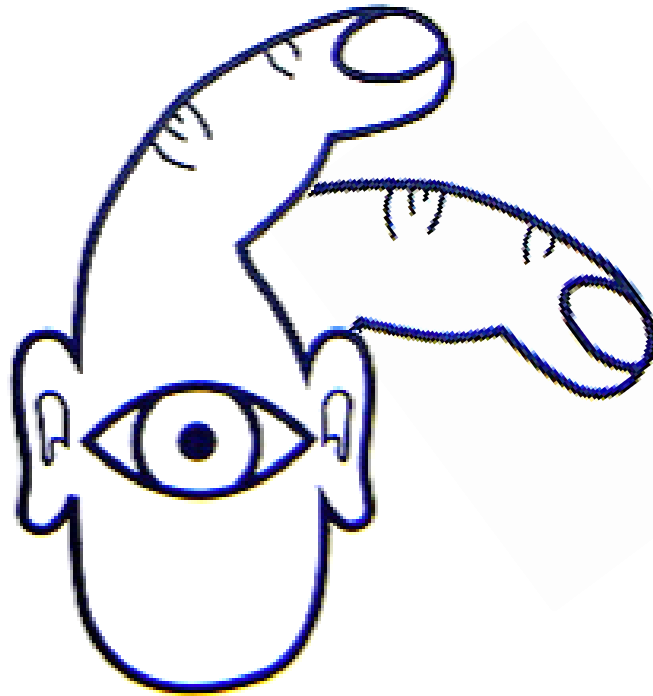


How the computer sees us!



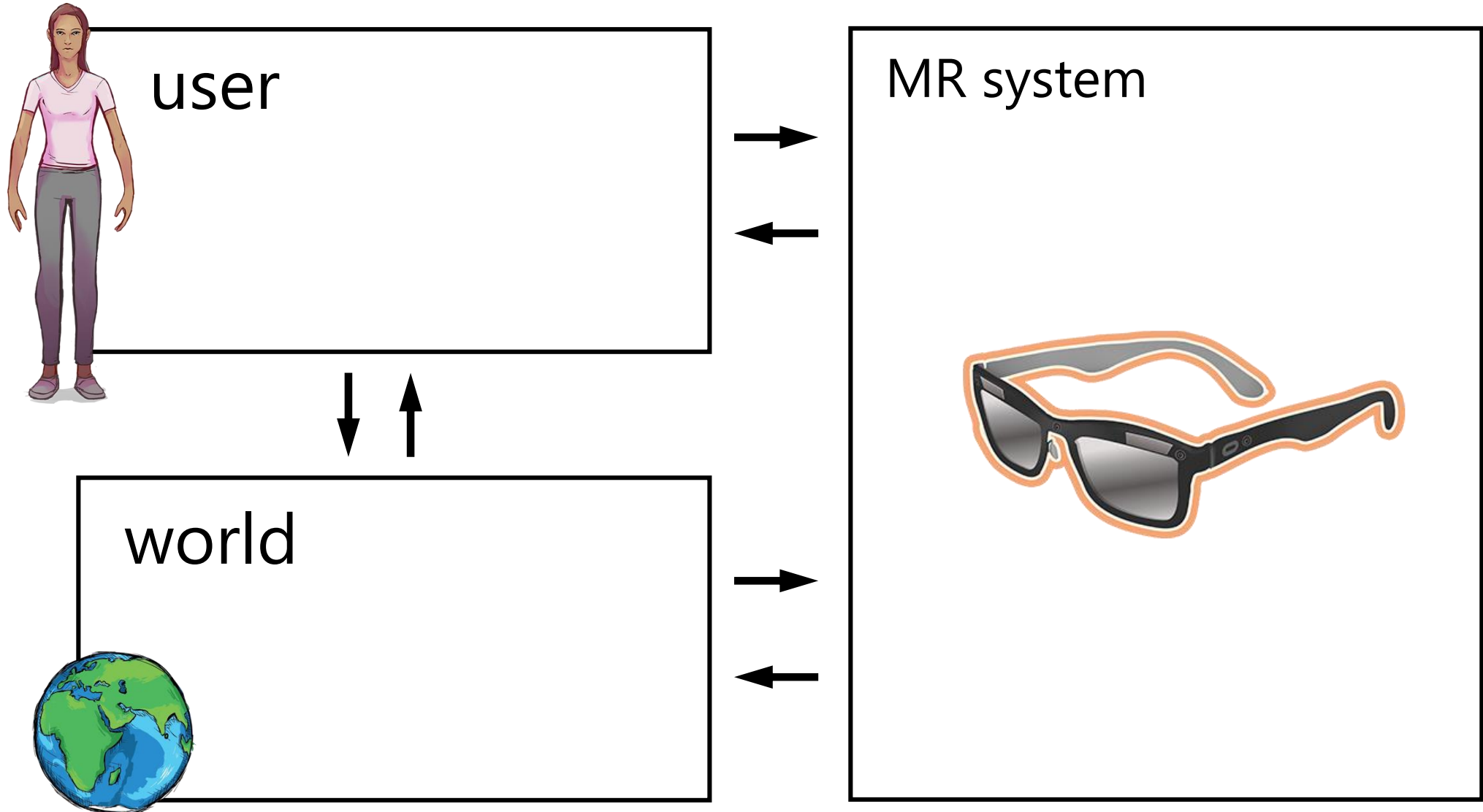
Tom Igoe and Dan O'Sullivan - *Physical Computing*. 2004.

How the phone sees us!



Modified Tom Igoe and Dan O'Sullivan - *Physical Computing*. 2004.

MR interaction model



MR interaction model

