

## Supplementary Material

Tables 1 and 2 describe parameter settings used in the experimentation for SARSA and DQN, respectively.

Table 1: Parameter settings for the tabular expected SARSA algorithm.

| PARAMETER  | DESCRIPTION                       | GRID-WORLD          | CART-POLE                                    | SUPPLY-CHAIN        |
|------------|-----------------------------------|---------------------|--|---------------------|
| $\eta_t$   | Table initialization              | uniform on [0, 0.1] | zeros  | uniform on [0, 0.1] |
| $T$        | Learning rate ( $t$ episode #)    | 0.7                 | $\max\left\{\frac{1}{2}0.99^t, 0.01\right\}$ | 0.6                 |
|            | Max. episode length               | 200                 | 200  | 200                 |
| $\mu_0$    | Prior parameter in (8)            | 0                   | 0  | 0                   |
| $\tau_0$   | Prior parameter in (8)            | 1                   | 1  | 1                   |
| $a_0$      | Prior parameter in (8)            | 500                 | 500  | 500                 |
| $b_0$      | Prior parameter in (8)            | 500                 | 500  | 500                 |
| $\alpha_0$ | Prior parameter for $\varepsilon$ | 1                   | 10   | 1000                |
| $\beta_0$  | Prior parameter for $\varepsilon$ | 1 + 0.01            | 10 + 0.01                                    | 1000 + 0.01         |

Table 2: Parameter settings for the deep Q-learning algorithm.

| PARAMETER  | DESCRIPTION                       | GRID-WORLD     | CART-POLE      | SUPPLY-CHAIN    |
|------------|-----------------------------------|----------------|----------------|-----------------|
| $f$        | Network initialization            | Glorot uniform | Glorot uniform | Glorot uniform  |
|            | Network topology                  | 16-25-25-4     | 4-12-12-2      | 102-100-100-100 |
|            | Hidden activation                 | ReLU           | ReLU           | ReLU            |
|            | Regularization                    | none           | $L2(10^{-6})$  | none            |
| $\phi$     | State encoding                    | one-hot        | none           | one-hot         |
| $\eta_t$   | Learning rate                     | 0.001          | 0.0005         | 0.001           |
| $N$        | Replay buffer size                | 2000           | 2000           | 3000            |
| $B$        | Batch size                        | 24             | 32             | 64              |
|            | Training epochs per batch         | 5              | 3              | 2               |
| $T$        | Max. episode length               | 200            | 200            | 200             |
| $\mu_0$    | Prior parameter in (8)            | 0              | 0              | 0               |
| $\tau_0$   | Prior parameter in (8)            | 1              | 1              | 1               |
| $a_0$      | Prior parameter in (8)            | 500            | 500            | 500             |
| $b_0$      | Prior parameter in (8)            | 500            | 500            | 500             |
| $\alpha_0$ | Prior parameter for $\varepsilon$ | 1              | 5              | 25              |
| $\beta_0$  | Prior parameter for $\varepsilon$ | 1 + 0.01       | 5 + 0.01       | 25 + 0.01       |