## **Appendix**

**Proof of Equation (3):** Note that

$$\begin{split} F(x+e) \neq F(x) \\ \Leftrightarrow \langle x+e,z\rangle\langle x,z\rangle < 0 \\ \Leftrightarrow \langle e,z\rangle > |\langle x,z\rangle|. \end{split}$$

The left-hand side is clearly maximized for  $e = ||e|| \frac{z}{||z||}$ , leading to

$$||e|||z|| > |\langle x, z \rangle|.$$

This proves the claim by taking the infimum over ||e||.

**Lemma 1.** Let F be a classifier with locally affine score function  $\Psi$ . Assume  $l(x) \ge \rho(x)$ . Then

$$\rho(x) = \min_{j \neq i^*} \frac{\Psi^{i^*}(x) - \Psi^j(x)}{\|\nabla \Psi^{i^*}(x) - \nabla \Psi^j(x)\|},$$
 (8)

for  $i^* := F(x)$  the predicted class at x.

*Proof.* As  $l(x) \ge \rho(x)$ , we can take the infimum in (1) over all perturbations in the local affine component, i.e. e with  $\|e\| \le l(x)$  only. This allows us to reformulate

$$F(x+e) \neq F(x)$$

$$\Leftrightarrow \exists j \neq i^* : \Psi^j(x+e) > \Psi^{i^*}(x+e)$$

$$\Leftrightarrow \exists j \neq i^* : \langle \nabla \Psi^j(x) - \nabla \Psi^{i^*}(x), e \rangle > \Psi^{i^*}(x) - \Psi^j(x).$$

The infimum over ||e|| is achieved by choosing e as a multiple of  $\nabla \Psi^j(x) - \nabla \Psi^{i^*}(x)$ . A direct computation then finishes the proof.

## **Proofs of Homogenization results**

**Lemma 3** (Euler's Homogeneous Function Theorem). Let  $f: \mathbb{R}^m \to \mathbb{R}$  be a positive one-homogeneous function that is continuously differentiable on  $\mathbb{R}^m \setminus \{0\}$ . Then

$$f(x) = \langle \nabla f(x), x \rangle$$

Proof. First note that

$$\partial_i f(ax) = \lim_{t \to 0} \frac{f(ax + te_i) - f(ax)}{t}$$
$$= \lim_{t \to 0} \frac{f(ax + ate_i) - f(ax)}{at} = \partial_i f(x).$$

Hence

$$f(x) = \int_0^1 \langle \nabla f(tx), x \rangle dt = \langle \nabla f(x), x \rangle$$

**Lemma 2** (Linearized Robustness of Homogeneous Classifiers). *Consider a classifier F with positive one-homogeneous score functions. Then* 

$$\tilde{\rho}(x) = \alpha^{\dagger}(x). \tag{12}$$

*Proof.* Direct consequence of 3.  $\square$ 

**Definition 5** (Neural Networks). Define the class of neural networks  $\mathcal{N}$  to be any network built on learnable affine transforms (convolutional layers, dense layers) with linear weights  $\Theta$  and biases b and ReLU or leaky ReLU activations. The network can include arbitrary skip-connections, batchnormalization layers and max or average pooling layers of arbitrary window size. This in particular includes many state-of-the-art classification networks.

**Lemma 4** (Homogeneous Networks). For fixed x, consider the logit  $\Psi^i_{\Theta,b}(x)$  of a network  $\Psi_{\Theta,b} \in \mathcal{N}$ , where  $\Theta$  denotes the linear weights and b the bias vector of the network. Then the function

$$f: y \mapsto \Psi^i_{\Theta, b \frac{\|y\|}{\|x\|}}(y),$$

f is positive one-homogeneous and  $f(x) = \Psi_{\Theta,b}^i(x)$ .

*Proof.* Consider first a network consisting of a single layer with linear transform A and bias b with ReLU nonlinearity. The associated network function is hence given by  $\Psi_{A,b}(x)=(Ax+b)_+$ . For this network, we compute for x fixed and any y and a>0 as

$$f(ay) = \left(A(ay) + b\frac{\|ay\|}{\|x\|}\right)_{+}$$
$$= \left(a \cdot Ay + a \cdot b\frac{\|y\|}{\|x\|}\right)_{+} = af(y).$$

A single layer is hence positive one-homogeneous. A function consisting of compositions of positive one-homogeneous functions is positive one-homogeneous itself as well, the function f associated to a network consisting of affine transforms and ReLU activations is positive one-homogeneous. All of the operations skip-connections, batch-normalization layers and max or average pooling are positive one-homogeneous as well, thus proving the claim.  $\Box$ 

**Theorem 1** (Homogeneous Decomposition of Neural Networks). Let  $\Psi^i_{\Theta,b}$  be any logit of a neural network with ReLU activations (of class N in the appendix). Denote by  $\Theta$  the linear filters and by b the bias terms of the network. Then

$$\Psi_{\Theta,b}^{i}(x) = \langle x, \nabla_{x} \Psi_{\Theta,b}^{i}(x) \rangle + \langle b, \nabla_{b} \Psi_{\Theta,b}^{i}(x) \rangle 
= \langle x, \nabla_{x} \Psi_{\Theta,b}^{i}(x) \rangle + \sum_{k} b_{k} \partial_{b_{k}} \Psi_{\Theta,b}^{i}(x).$$
(13)

*Proof.* Let f be the functions associated with the network  $\Psi^i_{\Theta,b}$  as in Lemma 4. Then by Lemma 3 we can compute the value of f at the point x via

$$f(x) = \langle x, \nabla_y f(y)|_{y=x} \rangle.$$

Note that by construction  $f(x) = \Psi_{\Theta,b}^i(x)$ . We compute the gradient of f at the point x explicitly as

$$\nabla_y f(y)|_{y=x} = \nabla_x \Psi_{\Theta,b}^i(x) + \frac{x}{\|x\|^2} \langle b, \nabla_b \Psi_{\Theta,b}^i(x) \rangle.$$

Combining these results shows

$$f(x) = \langle x, \nabla_x \Psi_{\Theta,b}^i(x) + \frac{x}{\|x\|^2} \langle b, \nabla_b \Psi_{\Theta,b}^i(x) \rangle \rangle$$
$$= \langle x, \nabla_x \Psi_{\Theta,b}^i(x) \rangle + \langle b, \nabla_b \Psi_{\Theta,b}^i(x) \rangle.$$

Recall the notation  $i^* = F(x)$  and  $j^*$  for the minimizer in j in (9).

**Theorem 2.** Let  $g:=\nabla \Psi^{i^*}(x)$ . Furthermore, let  $g^{\dagger}:=\nabla (\Psi^{i^*}-\Psi^{j^*})(x)$  and  $\beta^{\dagger}:=\beta^{i^*}(x)-\beta^{j^*}(x)$ . Then

$$\tilde{\rho}(x) \le \alpha^{\dagger}(x) + \frac{|\beta^{\dagger}|}{\|q^{\dagger}\|} \tag{14}$$

$$\leq \alpha(x) + \|x\| \cdot \|\overline{g}^{\dagger} - \overline{g}\| + \frac{|\beta^{\dagger}|}{\|g^{\dagger}\|}. \tag{15}$$

Proof. We have

$$\begin{split} \tilde{\rho}(x) &= \frac{\Psi^{i^*}(x) - \Psi^{j^*}(x)}{\|\nabla \Psi^{i^*}(x) - \nabla \Psi^{j^*}(x)\|} \\ &= \frac{\langle x, \nabla \Psi^{i^*}(x) - \nabla \Psi^{j^*}(x) \rangle + \beta^{i^*}(x) - \beta^{j^*}(x)}{\|\nabla \Psi^{i^*}(x) - \nabla \Psi^{j^*}(x)\|} \\ &= \left| \langle x, \overline{g}^\dagger \rangle + \frac{\beta^\dagger}{\|g^\dagger\|} \right| \leq \alpha^\dagger(x) + \frac{|b^\dagger|}{\|g^\dagger\|}, \end{split}$$

using the decomposition theorem and the triangle inequality. Further,

$$\alpha^{\dagger}(x) + \frac{|b^{\dagger}|}{\|g^{\dagger}\|}$$

$$= \left| \langle x, \overline{g}^{\dagger} \rangle \right| + \frac{|b^{\dagger}|}{\|g^{\dagger}\|}$$

$$= \left| \langle x, \overline{g}^{\dagger} - \overline{g} + \overline{g} \rangle \right| + \frac{|b^{\dagger}|}{\|g^{\dagger}\|}$$

$$\leq \left| \langle x, \overline{g} \rangle \right| + \left| \langle x, \overline{g}^{\dagger} - \overline{g} \rangle \right| + \frac{|b^{\dagger}|}{\|g^{\dagger}\|}$$

$$\leq \alpha(x) + \|x\| \cdot \|\overline{g}^{\dagger} - \overline{g}\| + \frac{|b^{\dagger}|}{\|g^{\dagger}\|},$$

using the Cauchy-Schwarz inequality.

**Theorem 3.** Let  $\xi := x + \frac{\beta^{\dagger}}{\|g^{\dagger}\|} \frac{g^{\dagger}}{\|g^{\dagger}\|}$  and  $\gamma := \nabla \Psi^{i^*}(\xi)$ , with  $g^{\dagger}$  and  $\beta^{\dagger}$  defined as in the previous theorem. Then

$$\tilde{\rho}(x) \le \frac{|\langle \xi, \gamma \rangle|}{\|\gamma\|} + \|\xi\| \cdot \|\overline{g}^{\dagger} - \overline{\gamma}\|, \tag{16}$$

and if additionally  $F(x) = F(\xi)$ , then

$$\tilde{\rho}(x) \le \alpha(\xi) + \|\xi\| \cdot \|\overline{g}^{\dagger} - \overline{\gamma}\|.$$

Proof. We have

$$\begin{split} \tilde{\rho}(x) &= \frac{\langle x, g^{\dagger} \rangle + \beta^{\dagger} \langle \frac{g^{\dagger}}{\|g^{\dagger}\|^{2}}, g^{\dagger} \rangle}{\|g^{\dagger}\|} \\ &= \frac{\langle x + \frac{\beta^{\dagger}}{\|g^{\dagger}\|} \frac{g^{\dagger}}{\|g^{\dagger}\|}, g^{\dagger} \rangle}{\|g^{\dagger}\|} \\ &= \langle \xi, \overline{g}^{\dagger} \rangle = \langle \xi, \overline{g}^{\dagger} - \overline{g} + \overline{g} \rangle \\ &\leq |\langle \xi, \overline{\gamma} \rangle| + \|\xi\| \cdot \|\overline{g}^{\dagger} - \overline{\gamma}\|, \end{split}$$

using the Cauchy-Schwarz inequality in the same way as in the last theorem.  $\hfill\Box$ 

## **MNIST Model Architecture**

Here we describe the architecture that was used for the MNIST models.

Conv2D ( $3 \times 3$ , 'same'), 32 feature maps, ReLU
Max Pooling (factor 2)
Conv2D ( $3 \times 3$ , 'same'), 64 feature maps, ReLU
Max Pooling (factor 2)
Conv2D ( $3 \times 3$ , 'same'), 128 feature maps, ReLU
Max Pooling (factor 2)
Dense Layer (128 neurons), ReLU
Dropout (0.5)
Softmax