# How to Hold a Convex Body?

#### T. ZAMFIRESCU\*

Mathematical Institute, University of Dortmund, 44221 Dortmund, Germany e-mail: zamfi@steinitz.mathematik.uni-dortmund.de

(Received: 24 November 1993)

Abstract. Convex bodies are often used for mathematical tests. They occasionally try to escape. Can the testing mathematician hold them still by using a circle? Rarely not.

Mathematics Subject Classification (1991): 52A15.

### The Problem and the Answer

There have been various ways in which people tried to carry a convex body. For a trip by train a stiff bag is probably appropriate. This means a polytope and, to get an economical one, its facets must touch the convex body. Such approximating polytopes have been often considered in the literature (see, for example, P. Gruber's survey [5]). If, instead, the total length of the edges should be minimal then, in the case of the unit ball, the polytope must be a cube, as Besicovitch and Eggleston showed [1].

For a walk in fresh air a cage might be the right holding instrument. Coxeter [4] asked about its minimal total length in the case of the unit ball and the question was investigated by Besicovitch [3] and Valette [6].

For a visit on a market the use of a net might be appropriate. The minimal length in the case of the unit ball was determined by Besicovitch [2].

Can a very simple instrument such as a (rigid) circle be used to hold a convex body? Certainly not in the case of a ball. More generally, it cannot be used to hold any ellipsoids, (bounded) circular cylinders, or other usual convex bodies. F. Caragiu asked: 'Do there exist any convex bodies which can be held using a circle?'

We shall see here not only that these convex bodies exist, but also that they appear to form a large majority!

Let  $\mathcal{B}$  be the space of all convex bodies and  $\mathcal{C}$  the space of all circles in  $\mathbb{R}^3$ , both endowed with the usual Pompeiu–Hausdorff metric  $\delta$ .

Mathematically, for a convex body B to be held by the circle C means that  $C \cap \text{int } B = \emptyset$  and, for some number  $m \in \mathbb{N}$ , there is no continuous mapping  $f : [0, 1] \to C$  such that f(0) = C,  $\delta(f(0), f(1)) > m$  and, for all  $t \in [0, 1]$ , f(t) is congruent with C and  $f(t) \cap \text{int } B = \emptyset$ .

<sup>\*</sup> The final part of the work for this paper was done during the COST mobility action CIPA-CT-93-1547 and supported by the European Community.

THEOREM. The convex bodies which cannot be held by a circle form a nowhere dense subset of  $\mathcal{B}$ .

## Prerequisites

Before giving a proof to our theorem we formulate and prove a lemma.

Let  $C_0$  be a circle and  $a_1, b_1, c_1 \in C_0$  be the vertices of an acute triangle. Now let  $a_i, b_i, c_i \in C_0$  (i = 2, 3) be other six points such that the triangles  $a_i b_i c_i$  be similar to  $a_1 b_1 c_1$  and

$$||a_i - a_{i+1}|| = ||b_i - b_{i+1}|| = ||c_i - c_{i+1}|| = \varepsilon > 0 \quad (i = 1, 2).$$

The number  $\varepsilon < 1$  is chosen so small that the triangle  $a_i b_j c_k$  be acute for any indices i, j, k. A small rotation leaving  $C_0$  invariant plus a small translation in a direction perpendicular to the plane of  $C_0$  can be chosen such that, for the new positions  $a'_i, b'_i, c'_i$  of  $a_i, b_i, c_i$ , the triangles  $a'_i a_i a_{i+1}, b'_i b_i b_{i+1}, c'_i c_i c_{i+1}$  be equilateral (i = 1, 2).

Consider the polytope

$$Q = \operatorname{conv}\{a_1, a_1', a_2, a_2', a_3, b_1, b_1', b_2, b_2', b_3, c_1, c_1', c_2, c_2', c_3\}$$

and the circle  $\Gamma$  circumscribed to the intersection of Q with the plane P situated at mid-distance between the plane of  $C_0$  and that through  $a'_i$ ,  $b'_i$ ,  $c'_i$  (i = 1, 2).

**LEMMA**. The polytope Q can be held by a circle coplanar and concentric with  $\Gamma$ , disjoint from Q.

*Proof.* First, we claim that each circle  $\Gamma^{\dagger}$  congruent with  $\Gamma$  and satisfying

$$0<\delta(\Gamma,\,\Gamma^\dagger)\leq \frac{\varepsilon}{4}$$

meets int Q. To prove this, let k be a congruence mapping  $\Gamma$  into  $\Gamma^{\dagger}$  and remark that each edge in the set

$$\mathcal{E} = \bigcup_{i=1}^{2} \{ a_i a'_i, \, a'_i a_{i+1}, \, b_i b'_i, \, b'_i b_{i+1}, \, c_i c'_i, \, c'_i c_{i+1} \}$$

meets the plane k(P) inside of conv  $\Gamma^{\dagger}$  if  $\Gamma^{\dagger} \cap \operatorname{int} Q = \emptyset$ .

The orthogonal projection  $\Gamma'$  of  $\Gamma^{\dagger}$  onto P is an ellipse whose long axis equals the diameter of  $\Gamma$ . The orthogonal projection of  $\cup \mathcal{E}$  on P consists of three (congruent) broken lines circumscribed to  $\Gamma$ . Any halfcircle of  $\Gamma$  meets at most two of these broken lines (remember the initial choice of the points  $a_i$ ,  $b_i$ ,  $c_i$ ,  $a'_i$ ,  $b'_i$ ,  $c'_i$ ).

Now, either

(i)  $\Gamma = \Gamma'$ 

or

(ii)  $\Gamma \cap \operatorname{conv} \Gamma'$  is contained in a half of  $\Gamma$ .

In case (i), k(P) is parallel to, but different from, P. But  $k(P) \cap Q$  has a circumscribed circle larger than, and concentric with,  $\Gamma^{\dagger}$ . This implies  $\Gamma^{\dagger} \cap \operatorname{int} Q \neq \emptyset$ .

In case (ii),  $\operatorname{conv} \Gamma'$  does not meet one of the three broken lines mentioned above, which implies that  $\operatorname{conv} \Gamma^{\dagger}$  does not meet each edge in  $\mathcal{E}$  and, therefore,  $\Gamma^{\dagger} \cap \operatorname{int} Q \neq \emptyset$ .

Hence our claim is verified. Now, suppose there exists a sequence  $\{\Gamma_n\}_{n=1}^{\infty}$ of circles converging to  $\Gamma$ , all coplanar and concentric with  $\Gamma$  such that, for no n, the polytope Q can be held by  $\Gamma_n$ . Choose m = 1. There is, for each n, a path  $f_n : [0, 1] \to C$  with the required properties. Since  $\delta(\Gamma_n, f_n(1)) > 1$ , there is some number  $t_n$  such that  $\delta(\Gamma_n, f_n(t_n)) = \varepsilon/4$ . Some subsequence of  $\{f_n(t_n)\}_{n=1}^{\infty}$  must converge and let  $\Gamma^*$  be its limit. Clearly, the circle  $\Gamma^*$  is congruent to  $\Gamma$ ,  $\Gamma^* \cap \operatorname{int} Q = \emptyset$  and  $\delta(\Gamma, \Gamma^*) = \varepsilon/4$ . Here we use the assertion claimed above with  $\Gamma^{\dagger} = \Gamma^*$ , and a contradiction is obtained. Hence Q can be held by all circles in a whole neighbourhood of  $\Gamma$  in  $\{C \in \mathcal{C} : C \text{ is coplanar and concentric with } \Gamma$ and  $C \cap \operatorname{int} Q = \emptyset$ . Just select one of these circles different from  $\Gamma$  and the lemma is proved.

### The proof

*Proof of Theorem.* Let  $\mathcal{O}$  be an open set in  $\mathcal{B}$ . Choose a convex body  $B \in \mathcal{O}$ . Select a section S of B such that the circle C circumscribed to S be maximal. Then the cylinder U with C as orthogonal section encloses int B and  $B \cap U \subset S$ . Indeed, together with any point in  $B \setminus (S \cup \text{int conv } U)$  we would find another one or two in  $S \cap C$  determining a larger circumcircle.

If  $a \in C \cap B$ , then either (i) the diametrically opposite point  $a^* \in C$  belongs to B or (ii) there is an acute triangle *abc* with  $b, c \in C \cap B$ .

Now consider a polytope  $L \in \mathcal{O}$  approximating B such that

(\*) in case (i)  $L \cap C$  consists of  $a^*$  plus two vertices  $a^+$  and  $a^-$ , symmetrical with respect to the line through a,  $a^*$  and close to a,

(\*\*) in case (ii)  $L \cap C = \{a, b, c\},\$ 

(\*\*\*) all vertices of L except for  $a^+$  and  $a^-$  (in case (i)) lie in B.

Now remember the circle  $C_0$  considered prior to the lemma, put  $C_0 = C$  and take the points  $a_1$ ,  $b_1$ ,  $c_1$  from there to be  $a^+$ ,  $a^-$ ,  $a^*$  in case (i), or a, b, c in case (ii). The polytope Q constructed there will now be used in the following way. We keep the circle  $C_0$  circumscribed to one facet of Q identified with our circle C and take the convex hull K of  $L \cup Q$ . If the number  $\varepsilon$  used to construct Q is small enough then  $K \in \mathcal{O}$ , because  $\lim_{\varepsilon \to 0} Q \subset L$  and, consequently,  $\lim_{\varepsilon \to 0} K = L$ .

The lemma provides a circle C' disjoint from Q, with which Q can be held. Let  $\gamma$  be the angle between any triangular facet of Q and aff C. Since  $U \cap L \subset C$ , L lies in a circular cone V over C with the apex on the same side of aff C as Q. This and  $\lim_{\varepsilon \to 0} \gamma = \pi/2$  imply  $C' \cap V = \emptyset$  and therefore  $C' \cap K = \emptyset$ , for  $\varepsilon$  sufficiently

small. Now take a parallel body  $K_{\nu}$  of K at distance  $\nu$ . If  $\nu$  is small enough,  $C' \cap K_{\nu} = \emptyset$  too. Consider a neighbourhood  $\mathcal{N}$  of  $K_{\nu}$  such that  $C' \cap D = \emptyset$  and  $K \subset D$  for every  $D \in \mathcal{N}$ . Then, obviously, each  $D \in \mathcal{N}$  includes Q and therefore can be held by C'.

This ends the proof.

## References

- 1. Besicovitch, A. S. and Eggleston, H. G.: The total length of the edges of a polyhedron, *Quart. J. Math. Oxford Ser.* (2) 8 (1957), 172–190.
- 2. Besicovitch, A. S.: A net to hold a sphere, Math. Gaz. 41 (1957), 106-107.
- 3. Besicovitch, A. S.: A cage to hold a unit-sphere, *Proc. Sympos. Pure Math.* Vol. VII, Amer. Math. Soc., Providence, RI, 1963, pp. 19–20.
- 4. Coxeter, H. S. M.: Review 1950, Math. Reviews 20 (1959), 322.
- 5. Gruber, P. M.: Aspects of approximation of convex bodies, in P. Gruber and J. Wills (eds), Handbook of Convex Geometry, Elsevier Science Publishers, 1993.
- 6. Valette, G.: A propos des cages circonscrites à une sphère, Bull. Soc. Math. Belg. 21 (1969), 124-125.