

*Newbauer.*



NATIONAL AERONAUTICS AND SPACE ADMINISTRATION

**LUNAR MODULE  
SYSTEMS HANDBOOK,  
VEHICLE LM-1,  
AS-204/LM-1,  
REV C**

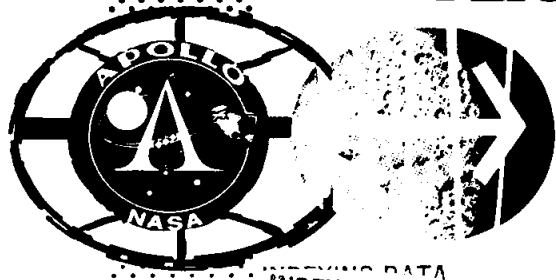
**JULY 7, 1967**

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DO NOT DISCARD REVISION A, DATED MARCH 16, 1967. REVISION A REFLECTS THE MANNED LM CONFIGURATION AND SHOULD BE RETAINED FOR REFERENCE PURPOSES UNTIL THE LM-2 SYSTEMS HANDBOOK IS PUBLISHED.

**PREPARED BY**

**FLIGHT CONTROL DIVISION**



**MANNED SPACECRAFT CENTER  
HOUSTON, TEXAS**

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LUNAR MODULE SYSTEMS HANDBOOK  
VEHICLE LM-1  
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PREFACE

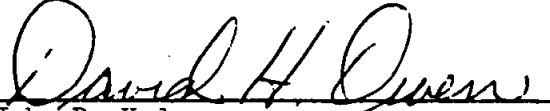
This Rev C has been prepared by the Flight Control Division, Manned Spacecraft Center, Houston, Texas, with technical support by Grumman Aircraft Engineering Corporation (GAEC). This document is not a complete revision, but a page change update. Information contained within this document represents the LM-1 configuration as of July 7, 1967.

This document is intended for specialized use by Flight Controllers in real-time and near-real-time operations. Comments concerning the contents should be directed to Mr. James E. Hannigan, Lunar Module Systems Branch, Building 45, Room 438, Phone HU3-4626.

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APOLLO

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LUNAR MODULE SYSTEMS HANDBOOK

VEHICLE LM-1  
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REVISION INSTRUCTION SHEET

Update this document in accordance with the following instructions:

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TABLE 2-1 CAPABILITIES AND LIMITATIONS

NO.	FUNCTION	COMPONENTS	SYSTEM A INITIATORS	SYSTEM B INITIATORS	
1	STAGING				
	EXPLOSIVE NUTS	FOUR NUTS	0	4	ONE INITIATOR PER NUT OR BOLT
	EXPLOSIVE BOLTS	FOUR BOLTS	4	0	
	ELECTRICAL CIRCUIT INTERRUPTERS	THREE INTERRUPTERS	3	3	
CABLE CUTTER	ONE CUTTER	1	1		
2	RCS HE. PRESSURIZE	TWO VALVES IN PARALLEL	1	1	TWO OPPOSING BLADES, ONE POWERED BY SYSTEM A AND ONE POWERED BY SYSTEM B. TWO TUBES INTERCONNECT THE CHARGES BEHIND EACH BLADE SUCH THAT ONE INITIATOR CAN FIRE THE CHARGE BEHIND BOTH BLADES, ONE BLADE CAN SEVER THE INTERSTAGE UMBILICAL
	RCS SYSTEM B	TWO VALVES IN PARALLEL	1	1	
3	DESCENT ENGINE PRESSURIZE				VALVES ARE THE SINGLE INITIATOR TYPE PLACED IN PARALLEL. ONE VALVE WILL PRESSURIZE THE SYSTEM
	HE. PRESS.	ONE VALVE	1	1	
	OX ISOLATION VALVE	ONE VALVE	1	1	
	FUEL ISOLATION VALVE	ONE VALVE	1	1	
4	ASCENT ENGINE PRESSURIZE				VALVE IS DUAL INITIATOR TYPE, ONE POWERED FROM SYSTEM A AND ONE FROM SYSTEM B. ONE INITIATOR WILL OPERATE THE VALVE
	HE. PRESS. TANK 1	ONE VALVE	1	1	
	HE. PRESS. TANK 2	ONE VALVE	1	1	
	OX ISOLATION VALVES	TWO VALVES IN PARALLEL	1	1	
	FUEL ISOLATION VALVES	TWO VALVES IN PARALLEL	1	1	VALVES ARE DUAL INITIATOR TYPE WITH .NE PORT PLUGGED. WITH THE VALVES IN PARALLEL ONE IS POWERED FROM SYSTEM A AND THE OTHER IS POWERED FROM SYSTEM B. ONE VALVE WILL PRESSURIZE THE SYSTEM

2.2 CAPABILITIES AND LIMITATIONS

A. THE PYRO SYSTEM HAS TWO 30 VOLT BATTERIES RATED AT 9.75 AMP-HOURS, ONE FOR SYSTEM A AND ONE FOR SYSTEM B. BOTH PYRO BATTERIES ARE LOCATED IN THE DESCENT STAGE

TABLE 2-2 PRELAUNCH STATUS OF SWITCH/CIRCUIT BREAKER POSITION

NAME	NUMBER	POSITION
LANDING GEAR DEPLOY STAGE	2510 PHL VIII	SAFE
RCS PRESSURIZE	255 PHL VIII	SAFE
ASCENT HE PRESSURIZE	252 PHL VIII	SAFE
ASCENT HE SELECT	253 PHL VIII	BOTH
ABORT STAGE	254 PHL VIII	SAFE
MASTER ARM	257 PHL VIII	OFF
ABORT STAGE	4C8 2	CLOSED
ABORT STAGE	4C8 3	CLOSED
LOGIC POWER B	4C875	CLOSED
LOGIC POWER A	4C876	CLOSED

2.3 SYSTEM OPERATION

- AT LEAST ONE PYRO BUS MUST BE ARMED FOR ANY PYRO FUNCTION TO OCCUR
- THE PROPULSION SYSTEMS (DPS, APS, J) WILL OPERATE PROPERLY FOR A SHORT TIME IN A PREPRESSURIZED BLOWDOWN MODE IF BOTH PYRO BUSES FAIL TO ARM. THE APPROXIMATE TIMES ARE:  
DPS - 17 SEC  
APS - 6 SEC  
THE RCS SYSTEM WILL NOT OPERATE IN A PREPRESSURIZED BLOWDOWN MODE

TABLE 2-3 DESCENT STAGE FUNCTIONS LOST AT STAGING

ELECTRICAL CIRCUIT INTERRUPTER #1 (P174)			
1.	BAT 3 & 4 POWER		
2.	ECA 1 & 2 POWER		
3.	DESCENT ENGINE CONTROL ASSY (DECA)		
4.	GIMBAL DRIVE ACTUATORS (PITCH & ROLL)		
5.	DESCENT ENGINE FUNCTIONS		
6.	OPERATIONAL TELEMETRY		
	GC0201V	BAT 1 VOLT	GH1301X DPS ON
	GC0202V	BAT 2 VOLT	GH1311V MAN THRUST CMD
	GC0203V	BAT 3 VOLT	GH1313V PITCH GDA POS
	GC0204V	BAT 4 VOLT	GH1314V ROLL GDA POS
	GC1201C	BAT 1 CUR	GH1323V P TRN FAIL
	GC1202C	BAT 2 CUR	GH1330X R TRN FAIL
	GC1203C	BAT 3 CUR	GH1331V AUTO THRUST CMD
	GC1204C	BAT 4 CUR	GH1340X DPS ARM
	GC4361X	BAT 1 HI TAP	GL4026X CES AC PWR FAIL
	GC4362X	BAT 1 LO TAP	GL4027X CES DC PWR FAIL
	GC4363X	BAT 2 HI TAP	Q23018P DPS HE REC PRESS
	GC4364X	BAT 2 LO TAP	Q23455P DPS HE PRESS
	GC4365X	BAT 3 HI TAP	Q23603Q DPS FUEL 1 QTY
	GC4366X	BAT 3 LO TAP	Q23604Q DPS FUEL 2 QTY
	GC4367X	BAT 4 HI TAP	Q23611P DPS FUEL PRESS
	GC4368X	BAT 4 LO TAP	Q24103Q DPS OX 1 QTY
	GC9963U	BAT 1 MAL	Q24104Q DPS OX 2 QTY
	GC9962U	BAT 2 MAL	Q24111P DPS OX PRESS
	GC9963U	BAT 3 MAL	Q24455Q DPS PROP LO
	GC9964U	BAT 4 MAL	QV0112X ED ARM A ON
			QV0112X ED ARM B ON
			QV0121X STG RLY A FIRE
			QV0122X STG RLY B FIRE

ELECTRICAL CIRCUIT INTERRUPTER #2 (P173)

- BAT 1 & 2 POWER
- ECA 1 & 2 POWER
- LUNAR DRILL POWER
- DESCENT ENGINE FUNCTIONS
- DPI TELEMETRY
- OPERATIONAL TELEMETRY
- Q23309X DPS HE. 1 CLSD
- Q23310X DPS HE. 2 OPW
- Q23718T DPS FUEL 1 TEMP
- Q23719T DPS FUEL 2 TEMP
- Q24218T DPS OX 1 TEMP
- Q24219T DPS OX 2 TEMP
- Q26510P DPS TGP
- Q26804H VAR INJ ACT POS
- Q27498U DPS PROP VLVS & POS
- Q27499U

ELECTRICAL CIRCUIT INTERRUPTER #3 (L72)

- DPI TELEMETRY
- OPERATIONAL TELEMETRY
- GL4222X LM/SLSEP

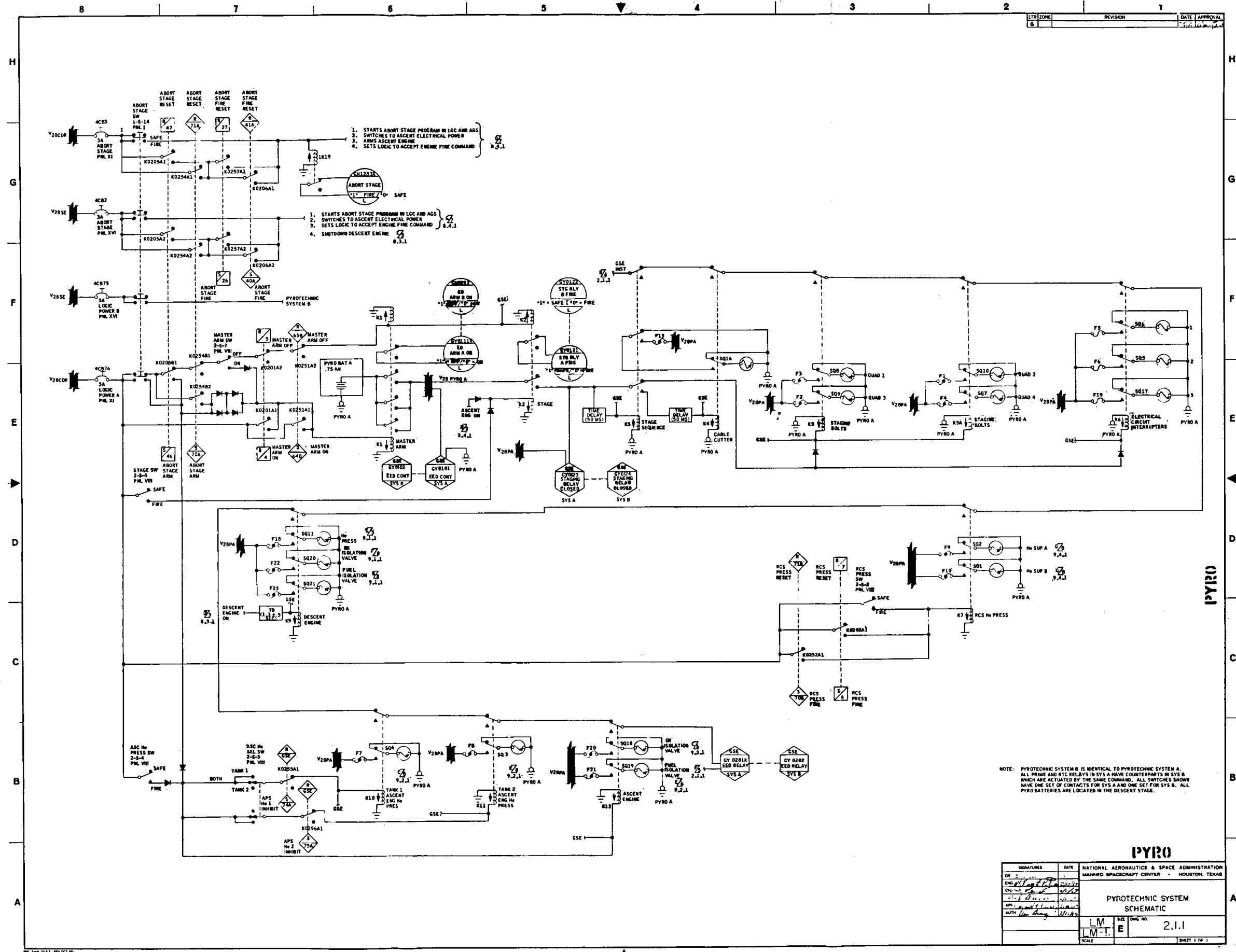
\* POWER IS IN PARALLEL TO BOTH DESCENT ECAMS THROUGH ECPS 1 AND 2

2.4 COMPARISON OF AS-206 PGNC'S AND PRA CONTROLLED ABORT STAGE SEQUENCES

THE SEQUENCE OF EVENTS ASSOCIATED WITH THE NOMINAL LM ABORT STAGE MANEUVER WILL BE FOLLOWED IN THE LM-1 (AS-206) MISSION UNDER PGNC'S CONTROL. LM MISSION PROGRAMMER (LMP) IMPLEMENTATION REQUIRES THAT THE TIMING OF THIS SEQUENCE BE MODIFIED SLIGHTLY FOR THE ABORT STAGE MANEUVER ACCOMPLISHED UNDER PROGRAM READER ASSEMBLY (PRA) CONTROL. THE TWO AS-206 CONTROL MODE SEQUENCES FOR ABORT STAGE ARE COMPARED IN TABLE 2-4. THE TIMING OF THE ASSOCIATED EVENTS IS BASED UPON THE ACTIVATION OF THE ABORT STAGE COMMAND FOR EACH CASE; HOWEVER, FOR THE PRA CONTROL MODE, THE TAPE FRAME INCREMENTS ARE ALSO INDICATED FOR THOSE FUNCTIONS DISCRETELY COMMANDED BY THE PRA. IT SHOULD BE NOTED THAT THE ONLY VARIATIONS WHICH EXIST BETWEEN THE TWO MODES ARE THE ABSENCE OF LGC ASSOCIATED FUNCTIONS AND A 26 MS LAG IN ARMING THE ASCENT ENGINE AND A.E. THRUST BUILD-UP TO 90 PER CENT IN THE PRA MODE. IN ALL OTHER RESPECTS, THE TWO SEQUENCES ARE IDENTICAL.

TABLE 2-4 COMPARISON OF AS-206 PGNC'S AND PRA CONTROLLED ABORT STAGE SEQUENCES

EVENT	PGNC'S SEQ TIME	PRA SEQ TIME
ABORT STAGE INITIATED	-1	-1
ASCENT ENGINE PRESSURIZATION INITIATED		
ASCENT HELIUM PRESSURIZATION TANK VALVES AND ISOLATION VALVES OPENED	-.97	-.97
ABORT STAGE FIRE INITIATED		
ASCENT ENGINE START DELAY TIMER INITIATED	0 SEC	0 SEC
LGC RECEIVES 'ABORT STAGE' DISCRETE AND STARTS ABORT ASCENT PROGRAM	.009	NA
LGC CONTINUED 'ENGINE OFF' COMMAND THRU STAGING		
DESCENT ENGINE SHUTDOWN INITIATED BY DECA	.025	.025
DESCENT BATTERIES OFF LINE	.070	.070
LGC RECOGNIZES ABORT STAGE DISCRETE	.140	NA
LGC STARTS LM ATTITUDE HOLD		
LGC STARTS COMPUTATION OF NEW AMPOUNT FOR THRUST VECTOR ASCENT STAGE CONTROL AND STARTS NEW GUIDANCE LAW		
PRA INITIATED DESCENT ARM OFF	NA	.250
DESCENT ENGINE THRUST DECAYED 90% (MAXIMUM TIME)	.275	.275
ASCENT ENGINE ARMED	.412	NA
ASCENT ENGINE START INITIATED		
ASCENT/DESCENT STAGING INITIATED		
(ASCENT ENGINE ARMED)	NA	.438
(ASCENT ENGINE START INITIATED)	NA	
ASCENT/DESCENT STAGE INTERSTAGE BOLTS PYROTECHNICALLY EXPLODED	.448	.448
ASCENT/DESCENT STAGE CONNECTING UMBILICAL DEARMED ON ASCENT STAGE		
ASCENT/DESCENT STAGE UMBILICAL SEVERED BY GUNFLOYING	.502	.502
LGC RECEIVES STAGE VERIFIED DISCRETE	NA	NA
ASCENT ENGINE THRUST BUILD UP TO 90% (MINIMUM TIME)	.687	.713
LGC INITIATED DESCENT ENGINE ARM OFF	1.140	NA
LGC TERMINATES LM ATTITUDE HOLD	4.140	NA
LGC COMMENCES ASCENT STAGE THRUST VECTOR CONTROL	NA	NA



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SECTION 3  
ELECTRICAL POWER

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3.1 SYSTEM DESCRIPTION

3.1.1 LM DC Electrical System

- A. The LM dc electrical system consists of six silver zinc primary batteries, four Electrical Control Assemblies (ECA), and two dc buses (commander's and system engineer's).
- B. Four of the primary batteries and two ECA's are located in the descent stage. A low voltage tap is provided at the 17 cell point of each 20 cell descent battery, but is disconnected. The high voltage battery tap is wired to the low voltage terminal on each ECA such that the LV contactors are used to connect the batteries to the buses. To avoid over voltage conditions due to using all 20 cells, the descent batteries will be installed pre-discharged from the nominal 400 amp-hr rating to 350 amp-hrs. Battery No. 1 is tied to the SE bus and Batteries 2, 3, and 4 are tied to the CDR bus. R-C
- C. Two of the LM primary batteries and two ECA's are located in the ascent stage. To avoid overvoltage conditions and to suppress transients, the ascent batteries may be installed pre-discharged from the nominal 300 amp-hr rating to 250 amp-hrs. R-C

3.1.2 LM AC Electrical System

The LM ac electrical system consists of two single phase ac inverters and one ac bus, and is located in the ascent stage. Only one of the ac inverters will supply power to the ac bus at any given time.

\*

TABLE 3-1 LM-1 LOAD ANALYSIS

<u>SYSTEM</u>	<u>WATTS</u>	<u>DC AMPS AT 30 VDC</u>	<u>ON AT ALL TIMES</u>
<b>ELECTRICAL</b>			
ELECTRICAL CONTROL ASSEMBLY (DESCENT)	20.0	0.67	NO
ELECTRICAL CONTROL ASSEMBLY (ASCENT)	10.0	0.33	YES
METERS & FLAGS (DESCENT AND ASCENT)	4.5	0.15	NO
METERS & FLAGS (ASCENT)	3.5	0.11	NO
INVERTER LOSSES (EFF = 65%) (BURN)	45	1.5	NO
(COAST)	40	1.33	NO
<b>ENVIRONMENTAL</b>			
GLYCOL PUMPS (2)	61.0	2.02	YES
<b>COMMUNICATIONS</b>			
S-BAND XMTR/RCVR	36	1.20	NO
S-BAND PWR AMP	72	2.4	NO
SIG PROC ASSY	15.5	0.52	
<b>INSTRUMENTATION</b>			
PCMTE	11	0.37	YES
C&WEA	13.6	0.45	YES
SIG COND UNITS	30.7	1.02	YES
SENSORS (DESCENT AND ASCENT)	14.5	0.48	NO
SENSORS (ASCENT)	10.5	0.35	YES
C-BAND BEACON (2)	56.0	1.87	YES
VHF XMTRS (5)	280	9.3	YES
DFI (EXCEPT XMTRS)	311	10.4	YES
DUAL FEED COUPLER	1.5	0.05	YES
<b>PROGRAMMER</b>			
PRA	23	.71	NO
DCA	15.0	0.50	YES
PCA	14	0.47	NO
<b>GUIDANCE</b>			
IMU	300.0	10.0	YES
LGC	110.0	3.67	YES

R-C

\*

TABLE 3-1 LM-1 LOAD ANALYSIS (CONCLUDED)

<u>SYSTEM</u>	<u>WATTS</u>	<u>DC AMPS AT 30 VDC</u>	<u>ON AT ALL TIMES</u>
<b>CONTROL</b>			
DECA	10.5	0.35	YES
DECA (AC)	6.3	0.11	YES
GIMBAL DRIVE ACTUATORS (AC)	80	2.67	NO
ATCA	42	1.4	YES
S&C CONT ASSY	5.2	0.17	YES
<b>PROPULSION</b>			
ASCENT ENG PROP VALVE	200.0	6.67	NO
ASCENT ENG ISOL REG SOL VALVE	56.0	1.87	NO
ASCENT ENG GAGING	1.0	0.03	NO
DESCENT ENG ISOL REG SOL VALVE	56.0	1.87	NO
DESCENT ENG GAGING	12.7	0.42	NO
THROTTLE ACT AMP	90	3.0	NO
DESCENT ENG S/O VALVE	60	2.0	NO
DESCENT ENG PRE-VALVE	85	2.8	NO
<b>RCS</b>			
THRUST CHAMBER ASSY	112 PER TCA	3.74 PER TCA	NO
ASCENT INTERCONNECT VALVE	70 PER VLV	2.33 PER VLV	NO
MAIN PROP SOV	70 PER VLV	2.33 PER VLV	NO
CLUSTER SOL VALVE	70 PER VLV	2.33 PER VLV	NO
CROSSFEED VALVE	70 PER VLV	2.33 PER VLV	NO
THRUSTER PRESS. TRANSDUCER	4.5	0.15	NO
PROP QTY GAGING	1.0	0.03	YES
THRUSTER HEATERS (MAX)	764	25.5	NO
(AVG)	190	6.3	NO
<b>TYPICAL POWER LOADS</b>			
COAST	55.1 AMPS		
DPS BURN	70.1 AMPS		
APS BURN	61.8 AMPS		

R-C



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TABLE 3-2 COMMANDER'S BUS CIRCUIT BREAKER TABULATIONS (PANEL XI)

<u>SYSTEM</u>	<u>CIRCUIT BREAKER</u>	<u>RATING</u>	<u>NOMENCLATURE</u>	
PYROTECHNICS	4CB76	3A	LOGIC PWR A	
	4CB149	3A	LDG GEAR FLAG	
ELECTRICAL	4CB129	3A	DOCK WINDOW (HEATER)	
	4CB6	3A	ASC ECA CONT	
	4CB8	3A	DES ECA CONT	
	4CB10	3A	DES ECA	
	4CB15	3A	ASC ECA	
	4CB12	25A	INV 1	
	4CB4	50A	X LUNAR BUS TIE	R-B
	4CB184	25A	BAL LOAD CROSS TIE	
	4CB20	100A	BUS CROSS TIE	
	4CB18	100A	BAT FEED TIE	R-B
	4CB26	100A	BAT FEED TIE	
ENVIRONMENTAL	4CB107	5A	CABIN FAN 1	
	4CB138	20A	SUIT FAN 1	
	4CB117	3A	GLYCOL PUMP 1	
	4CB141	3A	GLYCOL PUMP 2	
COMMUNICATIONS	4CB137	5A	SEC S-BND XMTR/RCVR	R-B
	4CB136	5A	SEC S-BND PWR AMPL	
	4CB86	3A	CDR AUDIO	
	4CB87	3A	VHF A RCVR	
	4CB162	3A	VHF B XMTR	
INSTRUMENTATION	4CB131	3A	SIG CONDR 1	
	4CB22	3A	DC BUS VOLT	
	4CB181	50A	R/D INST	
PROGRAMER	4CB179	50A	LMP FEED	R-B
GUIDANCE (PRIMARY)	4CB122	7.5A	LGC/DSKY	
	4CB105	10A	LDG RDR	
	4CB157	3A	LDG RDR (HEATER)	
	4CB124	20A	IMU OPR	
	4CB155	5A	RDR OPR (HEATER)	R-B
	4CB156	5A	RNDZ STBY (HEATER)	
	4CB29	15A	RNDZ RDR	
	4CB213	3A	AOT (HEATER)	
4CB154	3A	SIG STR DISP		
	4CB161	3A	IMU STBY	

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TABLE 3-3 SYSTEMS ENGINEERS BUS CIRCUIT BREAKER TABULATIONS (PANEL SVI)  
(Concluded)

R-B

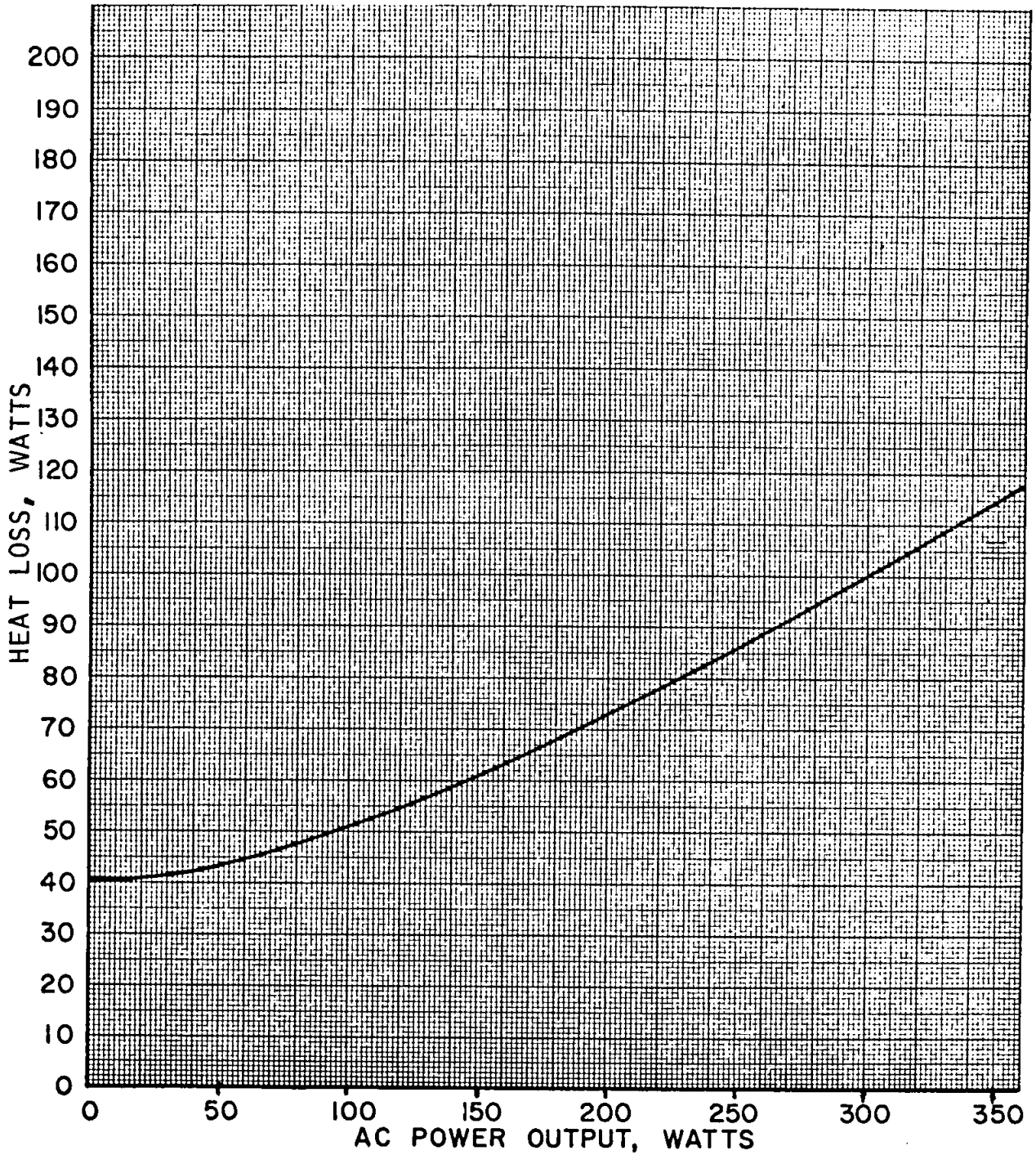
<u>SYSTEM</u>	<u>CIRCUIT BREAKER</u>	<u>RATING</u>	<u>NOMENCLATURE</u>		
CONTROL	4CB37	3A	ENGINE ARM	R-B	
	4CB41	7.5A	AELD		
	4CB82	7.5A	ATCA		
	4CB2	3A	ABORT STAGE		
PROPULSION	4CB50	3A	TEMP/PRESS/DISP FLAGS	R-B	
	4CB49	5A	ISOL VLV-B		
	4CB45	15A	QUAD 1 TCA-B		
	4CB44	15A	QUAD 2 TCA-B		
	4CB43	15A	QUAD 3 TCA-B		
	4CB42	15A	QUAD 4 TCA-B		
	4CB54	5A	CROSSFEED		
	4CB73	5A	MAIN SOV-B		
	4CB52	5A	ASC FEED		
	4CB121	3A	PQGS (RCS)		R-C
	4CB68	3A	DISPLAY (HEATER)		R-B
	4CB53	5A	ASC HE. REG		R-B
	4CB103	3A	TEMP/PRESS. DISPLAY		R-C
	4CB32	3A	PQGS (DES)		R-C
(HEATERS)	4CB222	7.5A	QUAD 1 RCS SYS A/B-2	R-B	
	4CB223	7.5A	QUAD 2 RCS SYS A/B-2		
	4CB224	7.5A	QUAD 3 RCS SYS A/B-2		
	4CB225	7.5A	QUAD 4 RCS SYS A/B-2		
MISC (FLIGHT DISPLAYS)	4CB126	3A	FDAI	R-B	
	4CB134	3A	X-POINTER		
LIGHTING	4CB128	5A	FLOOD	R-B	
	4CB147	5A	MASTER ALARM		
	4CB160	15A	TRACK		
	4CB148	3A	ANUN/DOCK/COMPNT		
CREW PROVISIONS	4CB33	3A	CAMERA SEQUENCE	R-C	

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TABLE 3-4 AC BUS CIRCUIT BREAKER TABULATIONS (PANEL XI)

R-B

<u>SYSTEM</u>	<u>CIRCUIT BREAKER</u>	<u>RATING</u>	<u>NOMENCLATURE</u>	
ELECTRICAL	4CB144	3A	CDR WINDOW (HEATER)	R-B
	4CB152	3A	S.E. WINDOW (HEATER)	
	4CB23	5A	AC BUS FEED TIE	
	4CB24	5A	AC BUS FEED TIE	
COMMUNICATIONS	4CB34	1A	S-BAND ANT	
INSTRUMENTATION	4CB202	3A	TAPE RCDR	
	4CB27	1A	AC BUS VOLT	
GUIDANCE	4CB203	3A	AGS	
	4CB212	3A	AOT LAMP	
	4CB206	3A	RNDZ RDR	
CONTROL	4CB207	3A	DECA GIMBAL	
PROPULSION	4CB169	3A	HE/PQGS DISP	R-C
MISC (FLIGHT DISPLAY'S)	4CB201	3A	GASTA	
	4CB209	1A	CDR FDAI	
	4CB204	3A	RNG/RNG RT	
	4CB210	1A	ALT/ALT RT SE FDAI	
LIGHTING	4CB211	3A	INTGL	
	4CB200	3A	NUM	



$$\text{DC POWER INPUT} = \text{AC POWER OUTPUT} + \text{HEAT LOSS}$$

Figure 3-2 Inverter Heat Loss



TABLE 3-9- LM-1 SWITCH TABULATION

SYSTEM	SWITCH/ CONTROL	SW/CONT NOMENCLATURE	PANEL													PRELARMING CONDITION	POSITIONS	
			I	II	III	IV	V	VI	VIII	X	XII	XIV	ECS CONT	TYPE & POS. TITLES	TYPE OF CLOSURE			
ENGINE THRUST CONTROL	1-5-1	ENGINE ARM	X													OFF	3-POS. TOGGLE ASC/OFF/DES	LOCK/LOCK/LOCK
	1-5-2	ENGINE START					X									OUT	PUSH BUTTON IN: START	MAIN
	1-5-3	ENGINE STOP (CLR)					X									OUT	PUSH BUTTON IN: STOP	MAIN
	1-5-4	ENGINE STOP (SE)						X								OUT	PUSH BUTTON IN: STOP	MAIN
	1-5-5	DESCENT RATE					X									CTRLR	3-POS. TOGGLE	MOM/MAIN/MOM
	1-5-6	X-TRANSLATION	X													4 JET	2-POS. TOGGLE 4/2 JET	MAIN/MAIN
	1-5-8	ENGINE GIMBAL			X											ENABLE	2-POS. TOGGLE ENABLE/OFF	LOCK/LOCK
	1-5-9	UNBALANCED COUPLES	X													ON	2-POS. TOGGLE ON/OFF	LOCK/LOCK
	1-5-10	MANUAL THROTTLE	X													SE	2-POS. TOGGLE CDR/SE	LOCK/LOCK
	1-5-11	THRUST CONTROL	X													AUTO	2-POS. TOGGLE AUTO MAN	LOCK/LOCK
	1-5-12	+X TRANSLATION					X									OFF	PUSH BUTTON IN: TRANSL	MOM
	1-5-13	ALORT	X													OFF	PUSH BUTTON IN: ABORT	MAIN
	1-5-14	ALORT STAGE	X													OFF	PUSH BUTTON IN: ABORT STAGE	MAIN
EXPLOSIVE DEVICES	2-5-1	DESC. PRESS.							X							SAFE	2-POS. TOGGLE FIRE/SAFE	MOM/LOCK
	2-5-2	PCS PRESS.							X							SAFE	2-POS. TOGGLE FIRE/SAFE	MOM/LOCK
	2-5-3	ASC. HE. SELECT							X							BOTH	3-POS. TOGGLE TARA 1/30TH/TARA 2	LOCK/LOCK/LOCK
	2-5-4	ASC. HC. PRESS.							X							SAFE	2-POS. TOGGLE FIRE/SAFE	MOM/LOCK
	2-5-5	STAGE							X							SAFE	2-POS. TOGGLE FIRE/SAFE	LOCK/LOCK
	2-5-7	MASTER ARM								X						OFF	2-POS. TOGGLE ON/OFF	LOCK/LOCK
	2-5-10	LEG GEAR DEPLOY								X						OFF	2-POS. TOGGLE ON/OFF	MOM/LOCK
IMU	3-5-1	IMU GAGE			X											OFF	2-POS. TOGGLE ON/OFF	MOM/MAIN
ELECTRICAL POWER SYSTEM	4-5-1	HI VOLT BAT 1												X		* OFF/RST	3-POS. TOGGLE ON/CENTER/OFF RST	MOM/MAIN/MOM
	4-5-2	HI VOLT BAT 2												X		* OFF/RST	3-POS. TOGGLE ON/CENTER/OFF PST	MOM/MAIN/MOM
	4-5-3	HI VOLT BAT 3												X		* OFF/RST	3-POS. TOGGLE ON/CENTER/OFF RST	MOM/MAIN/MOM
	4-5-4	HI VOLT BAT 4												X		* OFF/RST	3-POS. TOGGLE ON/CENTER/OFF RST	MOM/MAIN/MOM
	4-5-5	LO VOLT BAT 1												X		* OFF/RST	3-POS. TOGGLE ON/CENTER/OFF RST	MOM/MAIN/MOM
	4-5-6	LO VOLT BAT 2												X		* OFF/RST	3-POS. TOGGLE ON/CENTER/OFF RST	MOM/MAIN/MOM
	4-5-7	LO VOLT BAT 3												X		* OFF/RST	3-POS. TOGGLE ON/CENTER/OFF RST	MOM/MAIN/MOM
	4-5-8	LO VOLT BAT 4												X		* OFF/RST	3-POS. TOGGLE ON/CENTER/OFF RST	MOM/MAIN/MOM
	4-5-9	DESC BATS												X		* CONNECT	3-POS. TOGGLE CONNECT/CTR/DLA/FACE	MOM/LOCK/MOM
	4-5-10	NORM FEED BAT 5												X		* OFF/RST	3-POS. TOGGLE ON/CENTER/OFF RST	MOM/MAIN/MOM
	4-5-11	NORM FEED BAT 6												X		* OFF/RST	3-POS. TOGGLE ON/CENTER/OFF PST	MOM/MAIN/MOM
	4-5-12	LO FEED BAT 5												X		* OFF/RST	3-POS. TOGGLE ON/CENTER/OFF RST	MOM/MAIN/MOM
	4-5-13	LO FEED BAT 6												X		* OFF/RST	3-POS. TOGGLE ON/CENTER/OFF RST	MOM/MAIN/MOM
	4-5-14	AC PWR/P												X		OFF	3-POS. TOGGLE INV 1/OFF/INV 2	LOCK/LOCK/LOCK
	4-5-15	P.P/TEMP MON												X		OFF	10-POS. ROTARY OFF/1 THRU 6/CDR/SE/AC	
	4-5-16	AUTO TRANSFER												X		ENABLE	2-POS. LOCK TOGGLE ENABLE/INHIBIT	LOCK/LOCK
C&W	6-5-2	MASTER ALARM	X													OFF	PUSH BUTTON IN: RST ALARM	MOM
	6-5-3	MASTER ALARM		X												OFF	PUSH BUTTON IN: RST ALARM	MOM
ENVIRONMENTAL CONTROL SYSTEM	7-H-6	CDR SUIT FLOW												X		N/A	3-POS. COLLAR CONT. TORSO/SUIT DISCONNECT/HELMET	
	7-H-7	SE SUIT FLOW												X		N/A	3-POS. COLLAR CONT. TORSO/SUIT DISCONNECT/HELMET	
	7-H-8	SUIT GAS DIVERTER												X		N/A	2-POS. "H" HANDLE PUSH-CABIN/PULL-EGRESS	

TABLE 3 3 LM-1 SWITCH TABULATION

SYSTEM	SWITCH/ CONTROL	SW./CONT. NOMENCLATURE	PANEL													PRELAUNCH CONDITION	POSITIONS	
			I	II	III	IV	V	VI	VIII	X	XII	XIV	ECS CONT.	TYPE & POSITION TITLES	TYPE OF CLOSURE			
ENVIRONMENTAL CONTROL SYSTEM (CONTINUED)	7-H-9	SUIT CKT RELIEF													X	N/A	3 POS. FAUCET OPEN/AUTO/CLOSE	
	7-H-10	WATER SEPARATOR RELIEF													X	N/A	2 POS. "H" HANDLE PUSH-SEP 1/PULL SEP-2	
	7-H-11	CABIN RELIEF & DUMP VLV (FWD)													X	AUTO	3 POS. BAR LEVER CLOSE/AUTO/DUMP	
	7-H-12	CABIN TEMP CONT.													X	MAX COOL	MODULATING FAUCET MAX HEAT/NORM/MAX COOL	
	7-H-13	PLSS DRINK													X	CLOSE	2-POS. FAUCET OPEN/CLOSE	
	7-H-14	WATER TANK SELECT													X	ASC.	3-POS. FOLLOUT HAND CRANK DESC/ASC./EMER	
	7-H-17	CABIN GAS RETURN VLV													X	N/A	3-POS. FAUCET OPEN/AUTO/EGRESS	
	7-H-18	SEC GLYCOL													X	CLOSED	2-POS. MOD MODULATING FAUCET OPEN/CLOSE	
	7-H-19	CO <sub>2</sub> CANISTER SEL.													X	N/A	2-POS. BAR LEVER PRIMARY/SECONDARY	
	7-H-20	CABIN RELIEF & DUMP VLV (U/H)													X	AUTO	3-POS. BAR LEVER CLOSE/AUTO/DUMP	
	7-H-22	SUIT TEMP													X	COLD	MODULATING FAUCET HOT/INCP/DECR/COLD	
	7-H-23	PRIM CANISTER VENT													X	N/A	MEM. PUSH BUTTON VENT PUSH	
	7-H-24	SEC CANISTER VENT													X	N/A	MEM. PUSH BUTTON VENT PUSH	
	7-S-1	SUIT FAN		X												1	2-POS. ROTARY 1/2	
	7-S-2	O <sub>2</sub> /H <sub>2</sub> O QTY MON		X												ASC 1	4-POS. ROTARY CEN RST/DES/ASC1/ASC2	
7-S-3	GLYCOL PUMP		X												1	3-POS. ROTARY EMER/1/2		
7-S-4	PRIM EVAP FLOW													X	CENTER OFF	3-POS. TOGGLE OPEN/CENTER/CLOSE	MOM/LOCK/MOM	
REACTION CONTROL	8-S-7	MAIN SOV (SYS A)		X											*CLOSE/	3-POS. TOGGLE OPEN/CENTER/CLOSE	MOM/LOCK/MOM	
	8-S-8	ASC FEED (SYS A)		X											*CLOSE/	3-POS. TOGGLE OPEN/CENTER/CLOSE	MOM/LOCK/MOM	
	8-S-9	MAIN SOV (SYS B)		X											*CLOSE/	3-POS. TOGGLE OPEN/CENTER/CLOSE	MOM/LOCK/MOM	
	8-S-10	ASC FEED (SYS B)		X											*CLOSE/	3-POS. TOGGLE OPEN/CENTER/CLOSE	MOM/LOCK/MOM	
	8-S-11	QUAD 1 (SYS A)		X											*OPEN/	3-POS. TOGGLE OPEN/CENTER/CLOSE	MOM/MAIN/MOM	
	8-S-12	QUAD 2 (SYS A)		X											*OPEN/	3-POS. TOGGLE OPEN/CENTER/CLOSE	MOM/MAIN/MOM	
	8-S-13	QUAD 1 (SYS B)		X											*OPEN/	3-POS. TOGGLE OPEN/CENTER/CLOSE	MOM/MAIN/MOM	
	8-S-14	QUAD 2 (SYS B)		X											*OPEN/	3-POS. TOGGLE OPEN/CENTER/CLOSE	MOM/MAIN/MOM	
	8-S-15	QUAD 3 (SYS A)		X											*OPEN/	3-POS. TOGGLE OPEN/CENTER/CLOSE	MOM/MAIN/MOM	
	8-S-16	QUAD 4 (SYS A)		X											*OPEN/	3-POS. TOGGLE OPEN/CENTER/CLOSE	MOM/MAIN/MOM	
	8-S-17	QUAD 3 (SYS B)		X											*OPEN/	3-POS. TOGGLE OPEN/CENTER/CLOSE	MOM/MAIN/MOM	
	8-S-18	QUAD 4 (SYS B)		X											*OPEN/	3-POS. TOGGLE OPEN/CENTER/CLOSE	MOM/MAIN/MOM	
	8-S-19	TEMP/PRESS MON.		X											HE.	4-POS. ROTARY HE/PRPLNT/FUEL MAN/F/OXID MAN/F		
8-S-20	CROSS FEED		X											*CLOSE/	3-POS. TOGGLE OPEN/CENTER/CLOSE	MOM/LOCK/MOM		
FLIGHT CONTROLS	9-S-2	RATE/ERP MON (CDR)	X												LDG RDR/CMPT	2-POS. TOGGLE RNDZ RADAR/LDG RDR-CMPT	MAIN/MAIN	
	9-S-3	ATTITUDE MON (CDR)	X												PGNS	2-POS. TOGGLE PGNS/AGS	MAIN/MAIN	
	9-S-4	RNG/ALT MON	X												RNG/RNG RT	2-POS. TOGGLE RNG-RNG RT/ALT-AL+RT	MAIN/MAIN	
	9-S-6	GUID CONT	X												PGNC	2-POS. TOGGLE PGNS/AGS	LOCK/LOCK	
	9-S-7	RATE ERROR MON (SE)		X											LDG RDR/CMPT	2-POS. TOGGLE RNDZ RADAR/LDG RDR-CMPT	MAIN/MAIN	
	9-S-8	SHFT/TRUP ANGLE	X												+/-50°	2-POS. TOGGLE ±50°/±5°	MAIN/MAIN	
	9-S-9	MODE SELECT	X												PGNS	3-POS. TOGGLE LDG RADAR/PGNS/AGS	MAIN/MAIN/MAIN	
	9-S-10	ATTITUDE MON (SE)		X											PGNS	2-POS. TOGGLE PGNS/AGS	MAIN/MAIN	
	9-S-11	RESET/COUNT						X							UP	3-POS. TOGGLE RST/UP/DOWN	MOM/MAIN/MAIN	
	9-S-12	TIMER COUNT						X							CENTER	3-POS. TOGGLE START/CENTER/STOP	MOM/MAIN/MOM	
	9-S-13	MIN SLEW CONT.						X							CENTER	3-POS. TOGGLE TENS/CENTER/UNITS	MOM/MAIN/MOM	
	9-S-14	SEC SLEW CONT.						X							CENTER	3-POS. TOGGLE TENS/CENTER/UNITS	MOM/MAIN/MOM	

TABLE 3-9 LM-1 SWITCH TABULATION

SYSTEM	SWITCH/ CONTROL	SW./CONT NOMENCLATURE	PANEL												PRELATCH CONDITION	POSITIONS			
			I	II	III	IV	V	VI	VII	X	XII	XIV	ECS CONT	TYPE & POS. TITLES		TYPE OF CLOSURE			
FLIGHT CONTROLS	9-S-17	X-POINTER SCALE (CDR)			X											HI MULT	2 POS TOGGLE HI MULT/LO MULT	MAIN/MAIN	
	9-S-18	X-POINTER SCALE (SE)			X											HI MULT	2 POS TOGGLE HI MULT/LO MULT	MAIN/MAIN	
MAIN PROP (CONTINUED)	10-S-1	PROPELLANT TEMP/PRESS MON	X													DES 1	3 POS TOGGLE ASC/DES 1/DES 2	MAIN/MAIN/MAIN	
	10-S-3	ASC HE. REG 1	X													* OPEN/	3 POS TOGGLE OPEN/CENTER/CLOSE	MOH/MAIN/MOH	
	10-S-4	ASC HE. REG 2	X													* OPEN/	3 POS TOGGLE OPEN/CENTER/CLOSE	MOH/MAIN/MOH	
	10-S-5	DES HE. REG 1	X													* OPEN/	3 POS TOGGLE OPEN/CENTER/CLOSE	MOH/MAIN/MOH	
	10-S-6	HELIUM MON	X													OFF	DESC: SUPCRIT PRESS ASC: TEMP 1/TEMP 2/PRESS 1/PRESS 2		
	10-S-7	DES HE. REG 2	X													* CLOSE/	3 POS TOGGLE OPEN/CENTER/CLOSE	MOH/MAIN/MOH	
	10-S-8	PRPLNT QTY MON	X													OFF	3 POS TOGGLE DES 1/DES 2/OFF	MAIN/MAIN/MAIN	
STABILIZATION AND CONTROL	11-S-1	GYRO TEST			X											OFF	3 POS TOGGLE POSRT/OFF/NEGRT	MOH/LOCK/MOH	
	11-S-2	DEADBAND			X											MIN	2 POS TOGGLE MAX/MIN	MAIN/MAIN	
	11-S-3	PITCH ATT. CONT.			X											MODE CONT.	3 POS TOGGLE DIR/PULSE/MODE CONT	MAIN/MAIN/MAIN	
	11-S-4	ROLL ATT. CONT.			X											MODE CONT.	3 POS TOGGLE DIR/PULSE/MODE CONT	MAIN/MAIN/MAIN	
	11-S-5	YAW ATT. CONT			X											MODE CONT.	3 POS TOGGLE DIR/PULSE/MODE CONT	MAIN/MAIN/MAIN	
	11-S-6	MODE CONTROL			X											AUTO	3 POS TOGGLE OFF/ATT HOLD/AUTO	MAIN/MAIN/MAIN	
	11-S-7	GYRO TEST			X											PITCH	3 POS TOGGLE ROLL/PITCH/YAW	MAIN/MAIN/MAIN	
AGS	12-S-17	AGS STATUS					X									OFF	3 POS TOGGLE OPERATE/STANDBY/OFF	LOCK/LOCK/LOCK	
COMM	13-R-10	SQUELCH: VHF A														X	FULL DECR	THUMBWHEEL	
	13-R-15	SQUELCH: VHF B														X	FULL DECR	THUMBWHEEL	
	13-S-1	RANGE/TV														X	OFF	3 POS TOGGLE RANGE/OFF/TV	MAIN/MAIN/MAIN
	13-S-2	PWR AMPL														X	OFF	3 POS TOGGLE PRIM/OFF/SEC	MAIN/MAIN/MAIN
	13-S-3	BTOMED														X	OFF	3 POS TOGGLE LEFT/OFF/RT	MAIN/MAIN/MAIN
	13-S-4	PCM/KEY														X	PCM	3 POS TOGGLE PCM/OFF/KEY	MAIN/MAIN/MAIN
	13-S-5	MODULATE														X	PM	2 POS TOGGLE PM/PM	MAIN/MAIN
	13-S-6	VOICE/VOICE BU														X	OFF	3 POS TOGGLE VOICE/OFF/VOICE BU	MAIN/MAIN/MAIN
	13-S-7	VHF A: XMTR														X	OFF	2 POS TOGGLE ON/OFF	MAIN/MAIN
	13-S-8	XMTR/RCVR														X	OFF	3 POS TOGGLE PRIM/OFF/SEC	MAIN/MAIN/MAIN
	13-S-10	VHF A: RCVR														X	OFF	2 POS TOGGLE ON/OFF	MAIN/MAIN
	13-S-11	RECORDER														X	OFF	2 POS TOGGLE ON/OFF	MAIN/MAIN
	13-S-12	VHF B: XMTR														X	OFF	3 POS TOGGLE VOICE/OFF/DATA	MAIN/MAIN/MAIN
	13-S-13	PCM														X	HI	3 POS TOGGLE HI/LO	MAIN/MAIN
13-S-15	VHF B: RCVR														X	OFF	2 POS TOGGLE ON/OFF	MAIN/MAIN	
COMM A/T.	14-B-1	PITCH														X	+255°	ROTARY -75° TO +255°	
	14-B-2	YAW														X	-30 DEG	ROTARY -75° TO +75°	
	14-S-3	TRACK MODE														X	OFF	3 POS TOGGLE AUTO/OFF/SLEW	MAIN/MAIN/MAIN
	14-S-5	S-BAND														X	2	4 POS TOGGLE 1/2/SLEW/LUNAR STAY	
	14-S-6	VHF														X	1	4 POS TOGGLE PLSS TEST/1/2/EVA	
COMM (AUDIO CONT)	15A-R-7	ICS PCV VOL														X	FULL DECR	THUMBWHEEL	
	15A-R-8	VOX SENS														X	FULL DECR	THUMBWHEEL	
	15A-R-12	VHF B VOL														X	FULL DECR	THUMBWHEEL	
	15A-R-13	VHF A VOL														X	FULL DECR	THUMBWHEEL	
	15A-R-14	S-BAND RCV VOL														X	FULL DECR	THUMBWHEEL	
	15A-R-15	MASTER VOL														X	FULL DECR	THUMBWHEEL	



TABLE 3-8 LM-1 SWITCH TABULATION

SYSTEM	SWITCH/ CONTROL	SW./CONT. NOMENCLATURE	PANEL												PRELAUNCH CONDITION	POSITIONS		
			I	II	III	IV	V	VI	VII	X	XI	XIV	ECS CONT	TYPE & POS TITLES		TYPE OF CLOSURE		
COMM (AUDIO CONT.) CONTINUED	15A-S-1	S-BAND T/R/RCV								X						OFF	3 POS TOGGLE S-BAND TR/OFF/S-BAND RCV	MAIN/MAIN/MAIN
	15A-S-2	VHF A								X						OFF	3 POS TOGGLE TR/OFF/RCV	MAIN/MAIN/MAIN
	15A-S-3	ICS T/R/RCV								X						OFF	3 POS TOGGLE ICS TR/OFF/ICS RCV	MAIN/MAIN/MAIN
	15A-S-4	RELAY								X						RELAY OFF	2 POS TOGGLE RELAY ON/RELAY OFF	LOCK/LOCK
	15A-S-5	AUDIO CONT								X						NORM	2 POS TOGGLE NORM/BU	MAIN/MAIN
	15A-S-6	VOX								X						PTT	3 POS TOGGLE ICS XMTR/ICS/PTT	MAIN/MAIN/MAIN
	15A-S-9	VHF B								X						OFF	3 POS TOGGLE TR/OFF/RCV	MAIN/MAIN/MAIN
	15B-R-7	ICS VOL										X				FULL DECR	THUMBWHEEL	
	15B-R-8	VOX SENS										X				FULL DECR	THUMBWHEEL	
	15B-R-12	VHF A VOL										X				FULL DECR	THUMBWHEEL	
	15B-R-13	VHF B VOL										X				FULL DECR	THUMBWHEEL	
	15B-R-14	S-BAND VOL										X				FULL DECR	THUMBWHEEL	
	15B-R-15	MASTER VOL										X				FULL DECR	THUMBWHEEL	
	15B-S-1	S-BAND T/R/RCV										X				OFF	3 POS TOGGLE S-BAND TR/OFF/S-BAND RCV	MAIN/MAIN/MAIN
	15B-S-2	VHF A										X				OFF	3 POS TOGGLE TR/OFF/RCV	MAIN/MAIN/MAIN
	15B-S-3	ICS T/R/RCV										X				OFF	3 POS TOGGLE ICS TR/OFF/ICS RCV	MAIN/MAIN/MAIN
	15B-S-4	RELAY										X				RELAY OFF	2 POS TOGGLE RELAY ON/RELAY OFF	LOCK/LOCK
	15B-S-5	AUDIO CONTROL										X				NORM	2 POS TOGGLE NORM/BU	LOCK/LOCK
15B-S-6	VOX										X				PTT	3 POS TOGGLE ICS XMTR/ICS/PTT	MAIN/MAIN/MAIN	
15B-S-9	VHF B										X				OFF	3 POS TOGGLE TR/OFF/RCV	MAIN/MAIN/MAIN	
LIGHTING	16-R-2	ANUN/NUM					X									FULL DECR	CONTINUOUS ROTARY DIM→BRT	
	16-R-3	INTEGRAL					X									FULL DECR	CONTINUOUS ROTARY DIM→BRT	
	16-S-1	SIDE PANELS					X									OFF	2 POSITION TOGGLE ON/OFF	MAIN/MAIN
	16-S-2	EXTERIOR LTG			X											OFF	5 POS. ROTARY DOCK/OFF/DIM/OFF/BRIGHT	
	16-S-3	INTEGRAL					X									OFF	2 POS TOGGLE ON/OFF	MAIN/MAIN
	16-S-4	ANUN					X									OFF	2 POS TOGGLE ON/OFF	MAIN/MAIN
	16-S-5	NUM					X									OFF	2 POS TOGGLE ON/OFF	MAIN/MAIN
	16-S-6	FLOOD			X											OFF	3 POS TOGGLE ON/OFF/PARTIAL	MAIN/MAIN/MAIN
	16-S-9	LIGHTING SIDE PANELS			X											OFF	2 POS TOGGLE ON/OFF	MAIN/MAIN
	16-S-10	LAMP/TONE TEST			X											OFF	8 POS ROTARY:OFF/ALARM TONE/CW 8/ ENG PB-CW 2/CW 3/CW 4/COMPNT/OFF	
RADAR	17-S-1	SLEW			X											CENTER	SPRING LOADED 4-WAY CENTER OFF TOGGLE:UP/RIGHT/DOWN/LEFT	
	17-S-2	SLEW RATE			X											LO	2 POS TOGGLE HI/LO	MAIN/MAIN
	17-S-3	RNDZ RDR MODE			X											SLEW	3 POS ROTARY AUTO TRACK/SLEW/LGC	
	17-S-5	LDG ANT			X											DES	3 POS TOGGLE AUTO/DES/HOVER	LOCK/LOCK/LOCK
	17-S-6	RADAR TEST			X											OFF	3 POS TOGGLE RNDZ/OFF/LDG	MAIN/LOCK/MAIN
	17-S-8	TEST MONITOR			X											AGC	6 POS ROTARY:ALT XMTR/VEL XMTR/AGC XMTR PWR/SHFT ERR/TRUN ERR	
HEAT. CONT	18-S-10	HEATER CONT TEMP MON			X											RADAR:RNDZ	7 POS ROTARY:RNDZ/LDG/QUAD 1/ QUAD 2/QUAD 3/QUAD 4/S-BAND	
DFI	19-S-1	C-BAND PWR									X					ON	2 POS TOGGLE OFF/ON	MAIN/MAIN
	19-S-2	R/D TM CAL									X					OFF	2 POS TOGGLE OFF/ON	MAIN/MAIN
	19-S-3	LMP-TCA-ISOL			X											ENABLE	2 POS TOGGLE ENABLE/OFF	MAIN/MAIN

\*THE PRELAUNCH CONDITION COLUMN FOR THESE SWITCHES IS THE LAST PRELAUNCH MOMENTARY ACTUATION OF THIS SWITCH.

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REV C

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3.2 SYSTEM DATA

3.2.1 PREDISCHARGED DESCENT BATTERY  
CAPACITY 350 AMP-HRS  
TERMINAL VOLTAGE 28.0 TO 32.5VDC

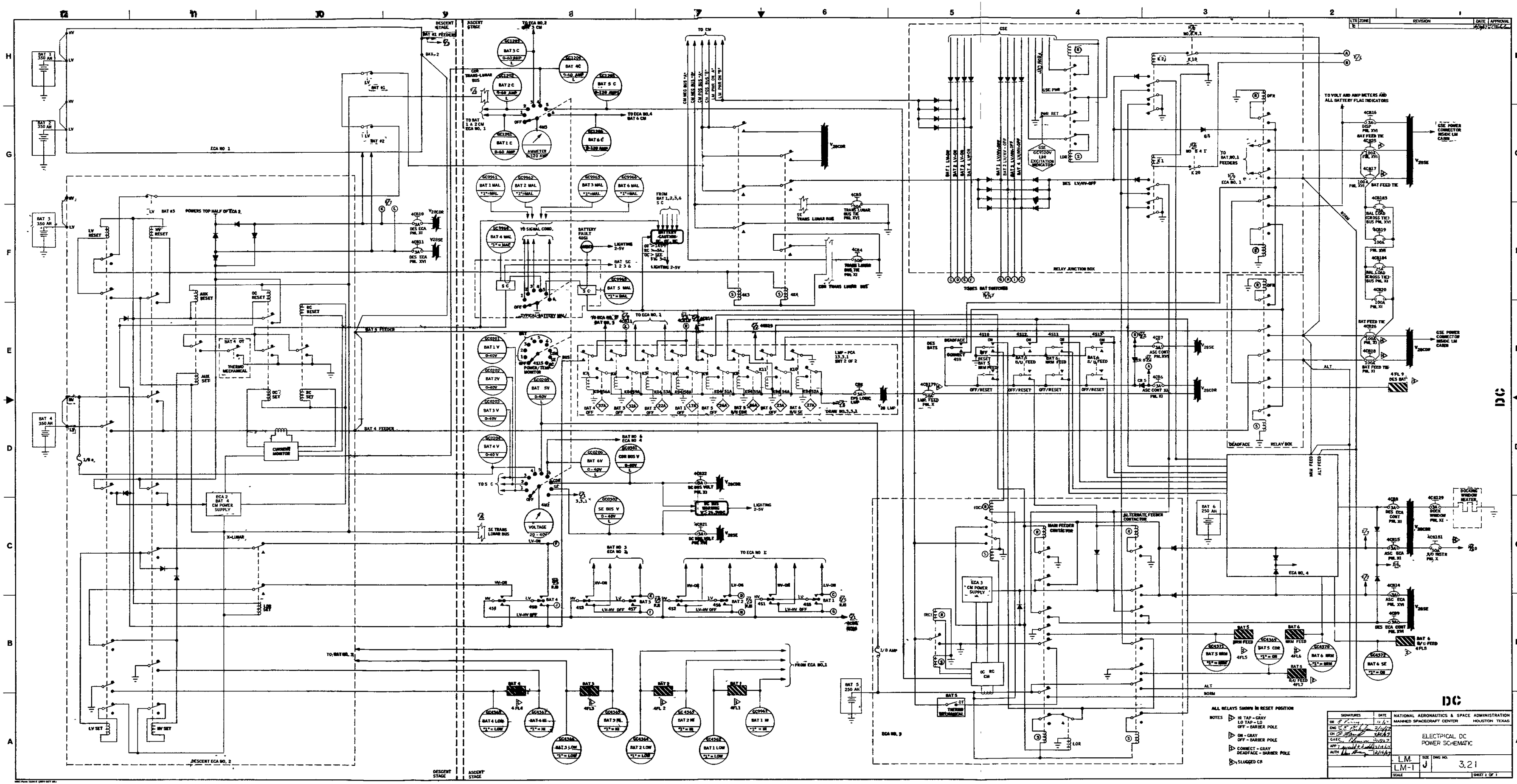
3.2.2 ASCENT BATTERY  
CAPACITY 250 AMP-HRS  
TERMINAL VOLTAGE 28.0 TO 32.5VDC

3.2.3 AC BUS  
VOLTAGE  $115 \pm 2.5$ VAC  
FREQUENCY  $400 \pm 10$ CPS

3.2.4 MALFUNCTION INDICATION

- A. THE LIMITS FOR A MALFUNCTION INDICATION ARE:
- |                  |   |
|------------------|---|
| OVER-TEMPERATURE | $>145 \pm 5^\circ\text{F}$ (RESETS AT $125^\circ \pm 5^\circ\text{F}$ ) |
| OVER-CURRENT     | SEE FIGURE 3-1  |
| REVERSE CURRENT  | $-6 \pm -10$ AMPS (INDICATION WILL BE RESET AT $-4$ AMPS)               |
- B. THERE WILL BE NO CAPABILITY FOR A DESCENT BATTERY MALFUNCTION INDICATION CAUSED BY A BATTERY OVER-TEMPERATURE IF THE BATTERY IS OFF
- C. THERE WILL BE NO CAPABILITY FOR THE RESPECTIVE ASCENT BATTERY MALFUNCTION INDICATION CAUSED BY A BATTERY OVER-TEMPERATURE IF BAT. 5 IS NOT CONNECTED TO THE S.E.'s OR BAT. 6 IS NOT CONNECTED TO THE CDR's BUS. ALSO, THE BACKUP FEED PATHS, DO NOT HAVE AUTOMATIC OVERCURRENT PROTECTION.

DWG NO. 3.2.1  
DETAIL SHEET NO.1



ALL RELAYS SHOWN IN RESET POSITION  
 NOTES:  
 ▽ IN TAP - GRAY  
 ▽ LO TAP - LO  
 ▽ OFF - BARRIER POLE  
 ▽ ON - GRAY  
 ▽ OFF - BARRIER POLE  
 ▽ CONNECT - GRAY  
 ▽ DEADFACE - BARRIER POLE  
 ▽ SLUGGED CP

REVISION	DATE	BY	CHKD	APP'D
1	10/1/62	...	...	...
2	10/1/62	...	...	...
3	10/1/62	...	...	...
4	10/1/62	...	...	...
5	10/1/62	...	...	...
6	10/1/62	...	...	...
7	10/1/62	...	...	...
8	10/1/62	...	...	...
9	10/1/62	...	...	...
10	10/1/62	...	...	...
11	10/1/62	...	...	...
12	10/1/62	...	...	...

NATIONAL AERONAUTICS & SPACE ADMINISTRATION  
 MANNED SPACECRAFT CENTER  
 HOUSTON, TEXAS  
 ELECTRICAL DC  
 POWER SCHEMATIC  
 LM-1 J 3.21  
 SHEET 1 OF 1

\*

SECTION 4

LM-1  
REV C

ENVIRONMENTAL CONTROL SUBSYSTEM

4.1 SUBSYSTEM DESCRIPTION

4.1.1 Oxygen Supply Section

A. Configuration

1. The descent oxygen tank will not be installed.
2. Each ascent oxygen tank will be evacuated to 4.35 psia.
3. The Oxygen Control Module, (reduces tank oxygen pressure to breathing pressure) will not be installed.

B. Function

1. Ascent oxygen will be supplied directly to the sensing ports of both the primary and secondary water regulators. Ascent tank Number 2 will provide reference pressure to the primary regulators while ascent tank Number 1 will provide an independent source of pressure to the secondary regulator.
2. The LM-1 cabin gas will not be replenished, consequently a 0.69 pound per hour N<sub>2</sub> leak rate may be anticipated during the mission.

4.1.2 Suit Loop

A. Configuration

1. Installed but functionally disabled by opening appropriate circuit breakers.

B. Function

1. None

4.1.3 Water Supply Section

A. Configuration

1. Descent water tank will be installed, however, there is no requirement to load water based on the present mission plan.

R-B

R-C

R-B

R-C

R-B

- 2. Ascent tanks will supply water to the primary water boiler during the entire mission. R-C
- 3. The water feed line to the smaller water boiler (item Number 224) will be capped since the reduced heat load precludes using this unit.

B. Function

- 1. To supply water to the water boiler such that proper thermal control may be accomplished.

C. Operation

- 1. Primary Water Feed - The water tank select valve, preset to ASCENT, allows water to flow through the primary feed path up to the primary water feed valve. At 3 minutes after liftoff, the LMP (LGC mode) will command the valve OPEN, allowing water to flow to the primary water boiler. RTC 24A, PRI H2O FEED and RTC 25A, PRI H2O RESET, are available to backup this onboard command. R-B
- 2. Primary Water Feed Verification - Prior to opening the feed valve, water pressure downstream of the regulators will be between 15.45 psia, (water was loaded using an ambient reference pressure) and ASC H2O Tank Pressure (48 psia). Subsequent to this loading, the oxygen tanks will be evacuated to 4.35 psia resulting in a  $\Delta P$  of between 11.1 (15.45 - 4.35) and 43.65 (48.0 - 4.35) psid. This will be reflected by PRI H2O REG  $\Delta P$  (GF4101P) having an off-scale high reading of 2.0 psid. Upon opening the feed valve at T + 3 minutes, H2O  $\Delta P$  will decay in order to become compatible with the ascent oxygen reference pressure. The drop in  $\Delta P$  can be verified by GF4101P decreasing to the nominal value of 0.75 psid. R-C  
R-B  
R-C
- 3. Secondary Water Feed - In the event that the primary water feed valve does not open on command, the secondary feed path may be used by sending RTC 60B, SEC H2O FEED ENABLE and R-C

\*

- RTC 44B, SEC H<sub>2</sub>O FEED followed by RTC 61B, SEC H<sub>2</sub>O FEED  
ENABLE RESET and RTC 45B, SEC H<sub>2</sub>O RESET. Upon receipt of  
this command the feed valve, in the independently regulated  
secondary path, will open. Water will flow through this  
parallel path to a point downstream of the primary feed  
valve where the paths are manifolded and provide a common  
feed to the water boiler. R-C
4. Secondary Water Feed Verification - Verification of the  
secondary valve opening cannot be ascertained in a manner  
analogous to the primary path since there is no regulator  
ΔP measurement. However, a continued rise in GLY TEMP  
GF9998U (GF2681T) is indicative of the valve not opening. R-B  
R-C
5. Water Regulation - Nominal regulated water pressure varies  
from 0.5 to 1.0 psid above oxygen tank pressure. The  
pressure of the water supplied to the water boiler should  
not exceed 6.5 psia in order to maintain optimum performance.
6. Water Boiler Operation - A porous plate sublimator rejects  
heat to the vacuum of space by the sublimation of ice. R-B  
The heat rejection capability of the water boiler is greatly  
reduced if the heat load is either below the "freeze-up"  
point or above the "breakthrough" point of the unit. These  
limits are defined as follows:
- a. Breakthrough - This refers to a water boiler condition  
where the heat load is sufficient to cause the vapor  
pressure at the outlet face of the plate to exceed the R-C  
triple point pressure. If, at this point, the pore  
size is too large to support the water feed pressure, R-B  
breakthrough will occur. This condition may also  
exist in the event that the water feed pressures be-  
come exceedingly high. Both primary water regulators  
must fail before the regulated pressure would reach R-C  
this limit.

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REV C

When the aforementioned condition is present, heat rejection capability is reduced and water usage is high since the water may pass into the plate and escape to ambient. For anticipated temperature and Btu profiles, see Figures 4-1 (TBD) and 4-2 (TBD).

R-B

- b. Freezeup - If the heat load dissipated by the water boiler drops below a lower limit, the ice layer will grow so as to fill the water passages. The expanding ice layer will rupture the sublimator, rendering it and the primary loop useless.

R-C

#### 4.1.4 Glycol Loops

##### A. Configuration

1. Both glycol pumps will be on.
2. The primary glycol loop is installed and operable.
3. The secondary glycol loop is installed but it will be left dry and disabled since it cannot be used on this flight.
4. As a result of the LM-1 simplification program the following pieces of equipment will not require cooling since they are no longer on the vehicle.
  - a. VHF Transceivers
  - b. Rendezvous Radar Electronics Assembly (RRE)
  - c. Abort Sensor Assembly (ASA)
  - d. Tracking Lights (TLE).

R-B

##### B. Function

1. To provide, by forced convection, thermal control of spacecraft electronic equipment.

##### C. Operation

1. Prelaunch Cooling - AS-206 is a launch of a powered up LM, and spacecraft cooling must be provided up to lift-off. Since the LM ECS water sublimator must be exposed to a vacuum environment to operate properly, two freon

R-C



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REV C  
NEW PAGE

boilers are installed in the primary glycol loop. The 221 freon boiler is located upstream of the batteries and the 224 freon boiler is located downstream of the batteries. There are three phases during which the glycol loop is in operation. The first phase begins when glycol is circulated through the vehicle via a ground based trim control unit. This unit pumps glycol through the onboard loop and out to a refrigeration unit to reject the heat. During this time, the coolant is supplied to the vehicle at 40°F with a flow rate of 390 lb/hr. At T-14 hours to liftoff, the second phase begins when, (with the trim control unit still operating) both freon boilers are activated. A total of 160 lb/hr of freon is supplied to both boilers at -20.8°F via the LUT. This concurrent operation of the freon boilers and the trim control unit lasts for 2 hours. At T-12 hours, the trim control unit is disconnected from the LM glycol loop. Glycol is then circulated through the vehicle by two onboard pumps. From T-12 hours to T-0 hours, a total freon flow of 160 lb/hr is to be maintained as long as temperature measurement GF9998U (GF2681T) is above 35°F. The total freon flow will be adjusted to maintain GF9998U at 35°F if necessary. Flyaway umbilicals terminate the freon supply at liftoff.

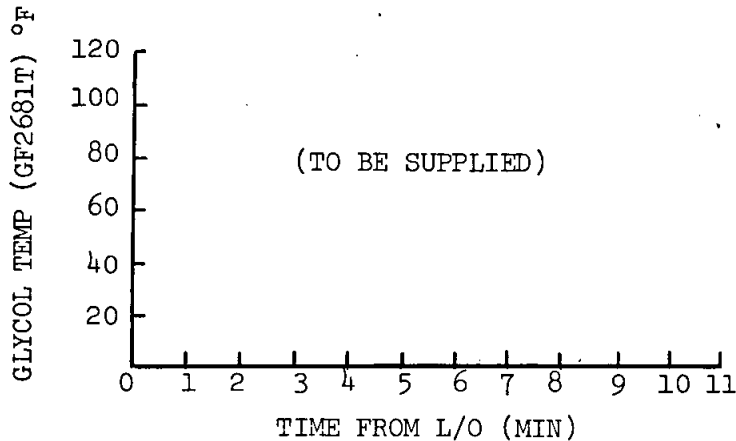
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R-C

2. Pump Switchover - The automatic switchover circuitry is such that should a transient cause the switchover from Pump 1 to Pump 2, it is impossible to return to Pump 1 on an unmanned mission. To avoid the possibility of losing a good pump both glycol pumps will be placed on the line prior to launch. The automatic switchover circuitry has been deactivated and the capability of executing RTC 50B, (Pump 2 SEL), and RTC 51B, (Pump 1 SEL), has been deleted.
3. Glycol Temperature Behavior During Launch - Since there will be no active cooling during the first three minutes of powered flight, GLY GF9998U (GF2681T) will behave as follows:

R-B

R-C



R-B

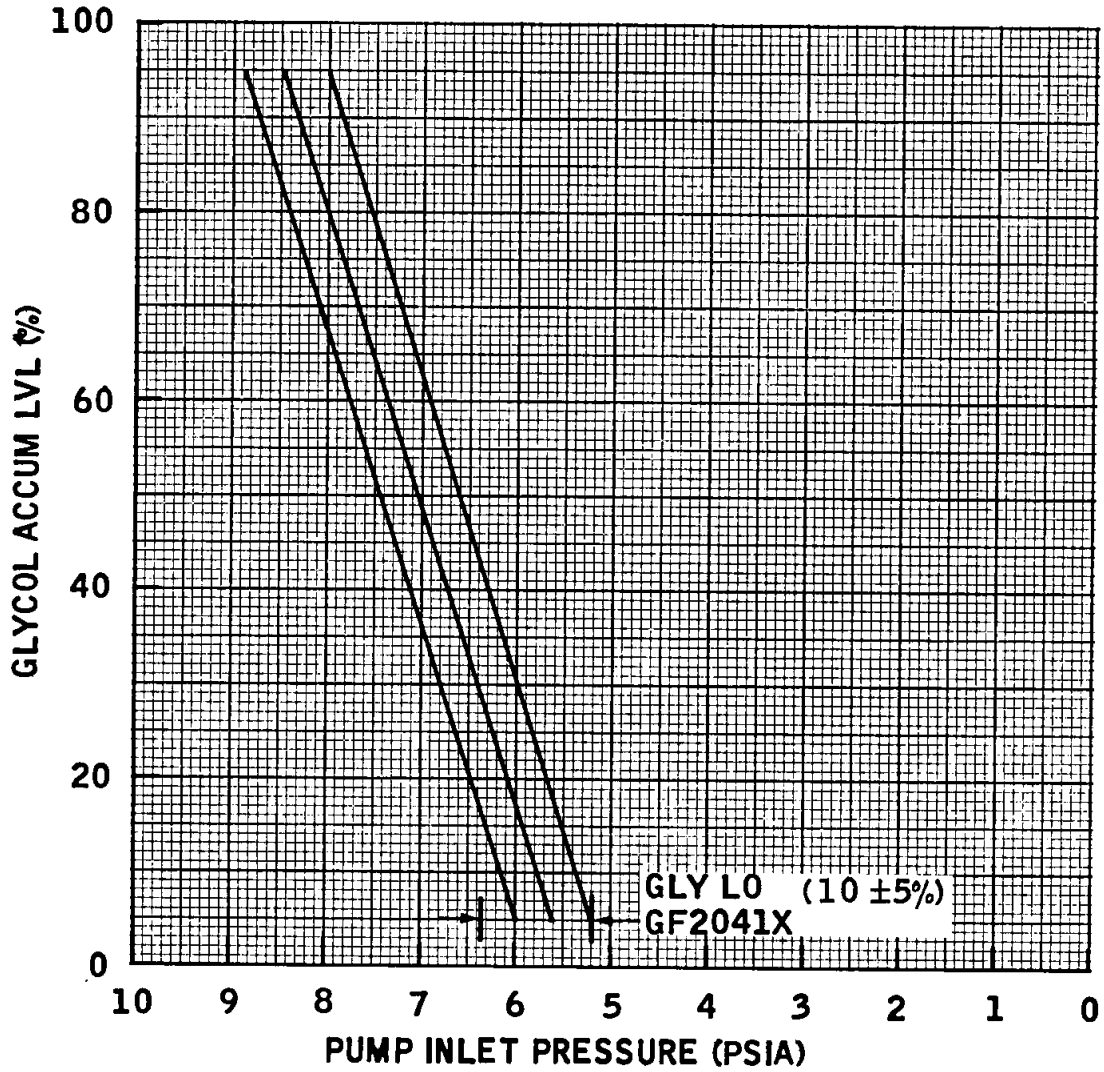


Figure 4-3 Glycol Accumulator Quantity

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TABLE 4-1 PRELAUNCH STATUS OF VALVES AND SWITCHES

<u>Switch/Valve Name</u>	<u>Position</u>	<u>Notes</u>	
<u>Oxygen Supply Section</u>			
Desc O <sub>2</sub> (7-H-15)	}	The O <sub>2</sub> control module, on which these valves are located, will not be installed.	
Asc O <sub>2</sub> No. 1 (7-H-21)			
Asc O <sub>2</sub> No. 2 (7-H-5)			
PLSS Fill (7-H-4)			
Cabin Repress (7-H-3)			
Demand Reg A (7-H-1)			
Demand Reg B (7-H-2)			
Cabin Relief & Dump Valve (7-H-11)	AUTO	Valves are present to this position in order to permit cabin "bleed" during launch.	R-B
Cabin Relief & Dump Valve (7-H-20)	AUTO		
Cabin Repress (4CB113)	}	These circuit breakers will be opened since the associated hardware is not required on an unmanned mission.	
Cabin Fan 1 (4CB107)			
Cabin Fan 2 (4CB108)			
Cabin Fan Control (4CB109)			
O <sub>2</sub> /H <sub>2</sub> O Qty Mon Sw (7-S-2)	ASC #1	Switch position irrelevant for LM-1.	R-C
<u>Suit Loop</u>			
CDR Suit Flow (7-H-6)	}	The Suit Circuit Assembly, on which these valves are located, will be electrically disabled by pulling circuit breakers and capping electrical connectors.	R-B
S E Suit Flow (7-H-7)			
Suit Circuit Relief (7-H-9)			
Suit Gas Diverter (7-H-8)			
Cabin Gas Return (7-H-17)			
CO <sub>2</sub> Cannister Select (7-H-19)			
CO <sub>2</sub> Primary Cannister Vent (7-H-23)			
CO <sub>2</sub> Secondary Cannister Vent (7-H-24)			
Water Sep Sel (7-H-10)			
Suit Fan (7-S-1)	Fan #1	Fan circuit breakers are open. Therefore, switch position is irrelevant for LM-1.	
Divert VLV (4CB112)	}	These circuit breakers will be opened since the associated hardware is not required for an unmanned mission.	R-C
CO <sub>2</sub> Sensor (4CB84)			
Suit Fan 1 (4CB138)			
Suit Fan 2 (4CB119)			
Suit Fan P (4CB120)			
Displays (4CB140)			
<u>Water Supply Section</u>			
Water Tank Select (7-H-14)	ASCENT	This setting will permit ascent H <sub>2</sub> O flow to the water boiler via the primary feed path, when the primary feed valve is opened by the LMP.	R-B

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REV C

TABLE 4-1 PRELAUNCH STATUS OF VALVES AND SWITCHES (Concluded)

<u>Switch/Valve Name</u>	<u>Position</u>	<u>Notes</u>	
<u>Water Supply Section (Concluded)</u>			R-B
PRIMARY FEED (7-S-4)	CENTER	Momentary toggle spring loaded to Center (OFF). Switch is not required to initiate H <sub>2</sub> O flow via the LMP.	R-C
PRIM H <sub>2</sub> O Feed (4CB98)	OPEN	Power is supplied to solenoid by the LMP.	
SEC Glycol Evap Flow (7-H-18)	CLOSE	The secondary glycol loop is dry for this mission.	
SEC Suit Evap Flow (7-H-16)	OPEN	Valve is required open to allow H <sub>2</sub> O to the water boiler via the secondary feed path. R&D solenoid (secondary H <sub>2</sub> O feed valve) is located downstream from this valve.	R-B
PLSS/Drink (7-H-13)	CLOSE	Not required on unmanned mission.	
O <sub>2</sub> Press. H <sub>2</sub> O Qty Mon	ASC #1	Switch position irrelevant for LM-1.	
<u>Glycol Loop</u>			
Glycol Pump Select (7-S-3)	No. 1	Required for Pump 1 operation.	
Glycol Pump 1 (4CB117)	CLOSE	Pumps will be running simultaneously for LM-1.	R-C
Glycol Pump 2 (4CB141)	CLOSE		
Glycol Pump Sec (4CB96)	OPEN	The secondary glycol loop is dry for this mission.	
Suit Temp (7-H-22)	COLD	Suit loop temp control is not required due to the unmanned configuration.	R-B
Cabin Temp (7-H-12)	COLD	Assures minimum temperature of glycol to aft equipment bay.	
Signal Sensor (4CB132)	CLOSE	Supplies 28V to certain ECS transducers (ref. Instrumentation/Environmental Interface Diagram Drawing No. 6.3.3.)	R-C

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REV C

#### 4.2 ECS CONSTRAINTS

##### 4.2.1 Water Supply Section

- A. Failure of the PRIM FEED valve to open will result in equipment malfunction in \_\_\_\_\_ minutes, if SEC FEED valve is not opened.
- B. A failed close regulator will result in an increase of GLY TEMP (GF9998U) in \_\_\_\_\_ minutes. (Corresponds to \_\_\_\_\_ Btu/hours into water boiler.

R-B

##### 4.2.2 Primary Glycol Loop

Loss coolant recirculation (pumps fail) will result in water boiler freezeup in 2 minutes and equipment overheating in \_\_\_\_\_ minutes.

R-C

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LM-1  
REV C

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ECS SYSTEMS DATA

EQUIPMENT

DATA

WATER SUPPLY SECTION

1. H2O REGULATORS

A. MAX. FLOW RATE = .85 LB/MIN

GLYCOL LOOP

1. COOLANT

A. 35% ETHYLENE GLYCOL AND 65% H2O  
 B. QUANTITY PRIMARY LOOP = 44 LBS  
 C. NOMINAL FLOW RATE = 420 LBS/HR  
 D. SPECIFIC HEAT = 0.870 BTU/LB-F° AT 75°F

2. PUMPS)

A. 7.0 LBS/MIN AT 40°F AND AP = 33.0 PSIA  
 B. PAD DISCHARGE PRESSURE = 55.0 PSIA  
 C. NOMINAL PUMP AP = 33.0 PSIA  
 D. NOMINAL PUMP DISCHARGE PRESSURE = 40.0 PSIA

3. PUMP RELIEF VALVES

A. CRACK = 33 PSID, FULL OPEN = MAX 36.0 PSID, RESEAT = 32 PSID

4. WATER BOILER

A. MAXIMUM CAPACITY = 8,500 BTU/HR  
 B. MINIMUM LOAD (TO PREVENT FREEZEUP) = 400 BTU/HR  
 C. THE POSSIBILITY OF FREEZEUP EXISTS BELOW HEAT LOAD OF 800 BTU/HR  
 D. MAX H2O PRESS. APPROX 8.5 PSIA  
 MINIMUM ALLOWABLE H2O PRESS. 1.5 PSIA

5. GLYCOL TEMPERATURE

A. ESTIMATED NOMINAL TEMP BAND FOR GF9998U GF2681T  
 HIGH = 47°F LOW = 36°F  
 B. NORMAL MAXIMUM INLET TEMP OF LOW TEMP ELECTRONICS = 50°F  
 C. GF9998U READING 47°F IS INDICATION THAT INLET TEMP OF THE LOW TEMP ELECTRONICS IS APPROACHING UPPER LIMIT.

6. GLYCOL ACCUMULATOR (SEE FIG. 4-3)

A. 95% FULL ACCUMULATOR = 8.49 ± .42 PSIA PUMP INLET PRESSURE.  
 B. 50% LEVEL = 5.16 ± .28 PSIA PUMP INLET PRESSURE.  
 C. GLYCOL LEVEL AT 10 ± 5% WILL TRANSMIT A DISCRETE SIGNAL (GLY LOW GF2041X).

ECS CONSUMABLES

TANK	VOLUME FY3	CAPACITY			ACTUAL LOADING			RESIDUAL	
		QUANTITY LBS %	PRESSURE PSIA	TEMPERATURE °F	QUANTITY LBS %	PRESSURE PSIA	TEMPERATURE °F	QUANTITY LBS %	
A/1 H2O	0.910 <sup>2</sup>	42.3 100 <sup>2</sup>	48.0	80				1.00 2.35	
A/2 H2O	0.910 <sup>2</sup>	42.3 100 <sup>2</sup>	48.0	80				1.00 2.35	

**HEAT CONVERSION**

1. 1KWH = 3413 BTU
2. 1LB OF H2O REJECTS = 1040 BTU
3. ESTIMATED BTU LOAD IS SHOWN ON FIG. 4-2. (TBD)

**WATER USAGE**

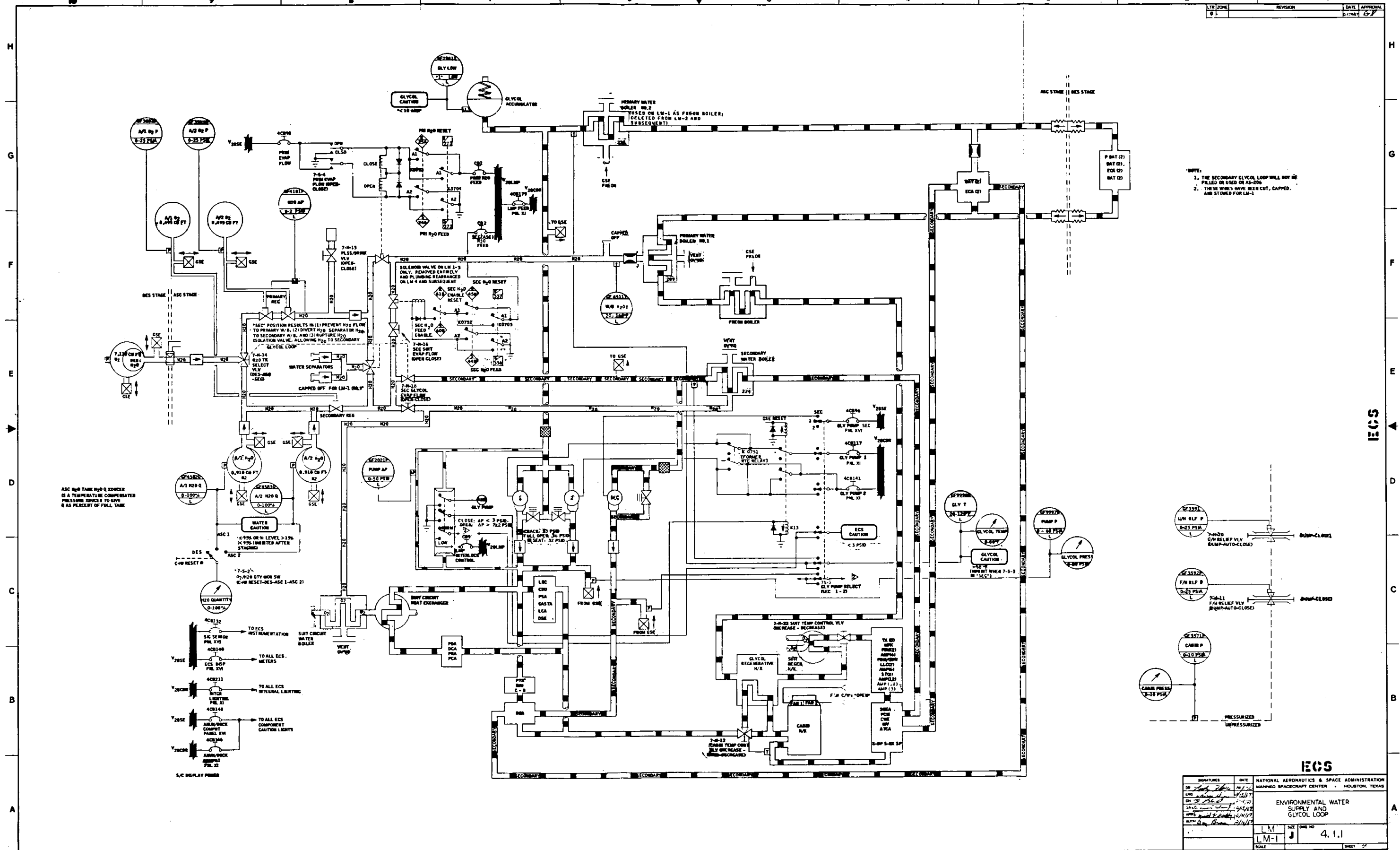
1. AVERAGE USAGE FOR HEAT REJECTION = 5.0 TO 6.0 LB/HR
2. ESTIMATED WATER USAGE PROFILE IS SHOWN ON FIG. 4-1. (TBD)

1. THIS INCLUDES H2 + WATER VOLUME
2. ANY WATER QUANTITY UP TO THIS FIGURE MAY BE LOADED AND THE MEASURING DEVICE ADJUSTED TO INDICATED 100%.

ECS SWITCH AND VALVE POSITION AT LIFTOFF

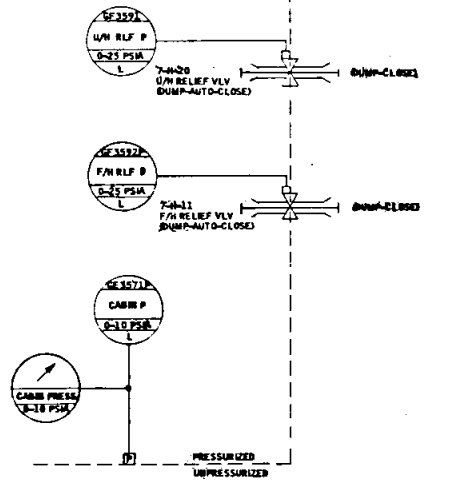
SWITCH NO.	NAME	POSITION
7-S-1	SUIT FAN SELECT	FAN #1
7-S-2	O2/H2O QTY MON SW	ASC #1
7-S-3	GLY PUMP SELECT	NO. 1
7-S-4	PRIM FEED	CENTER/OFF
7-H-13	PLSS/DRINK VLV	CLOSE
7-H-14	H2O TK SELECT VLV	ASCENT
7-H-16	SEC SUIT EVAP FLOW	OPEN
7-H-18	SEC GLY EVAP FLOW	CLOSE
7-H-12	CABIN TEMP CONT VLV	COLD
7-H-22	SUIT TEMP CONT VLV	COLD
7-H-11	F/H RELIEF VLV	AUTO
7-H-20	U/H RELIEF VLV	AUTO
4CB96	GLY PUMP SEC	OPEN
4CB98	PRIM EVAP FLOW	OPEN
CB1	PRIM H2O FEED	CLOSE
CB2	SEC H2O FEED	CLOSE
4CB179	LMP FEED	CLOSE
4CB140	ECS DISP	OPEN
4CB211	INTGR LIGHTING	OPEN
4CB148	ANUM/DOCK COMPNT	OPEN
4CB146	ANUM/DOCK COMPNT	OPEN
4CB117	GLY PUMP.1	CLOSE
4CB141	GLY PUMP.2	CLOSE
4CB132	SIG SENSOR	CLOSE





NOTE:  
 1. THE SECONDARY GLYCOL LOOP WILL NOT BE FILLED OR USED ON AS-206  
 2. THESE WIRES HAVE BEEN CUT, CAPPED, AND STORED FOR LM-1

ASC H<sub>2</sub>O TANK H<sub>2</sub>O Q. SENSER IS A TEMPERATURE COMPENSATED PRESSURE SENSER TO GIVE Q AS PERCENT OF FULL TANK



- 4C8132 TO ECS INSTRUMENTATION
- 4C8148 TO ALL ECS METERS
- 4C8211 TO ALL ECS INTEGRAL LIGHTING
- 4C8148 TO ALL ECS COMPONENT CAUTION LIGHTS
- 4C8346
- 4C8346
- S/C DISPLAY POWER

SIGNATURES		DATE	NATIONAL AERONAUTICS & SPACE ADMINISTRATION	
DR		10/1/67	MANNED SPACECRAFT CENTER - HOUSTON, TEXAS	
ENR		2/24/67		
DR		2/24/67		
SAC		2/24/67		
APPS		2/24/67		
AUTH		2/24/67		
ENVIRONMENTAL WATER SUPPLY AND GLYCOL LOOP				
LM	REV	QWG NO		
LM-1	J	4.1.1		
SCALE			SHEET 02	

ECS

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LM-1  
REV C

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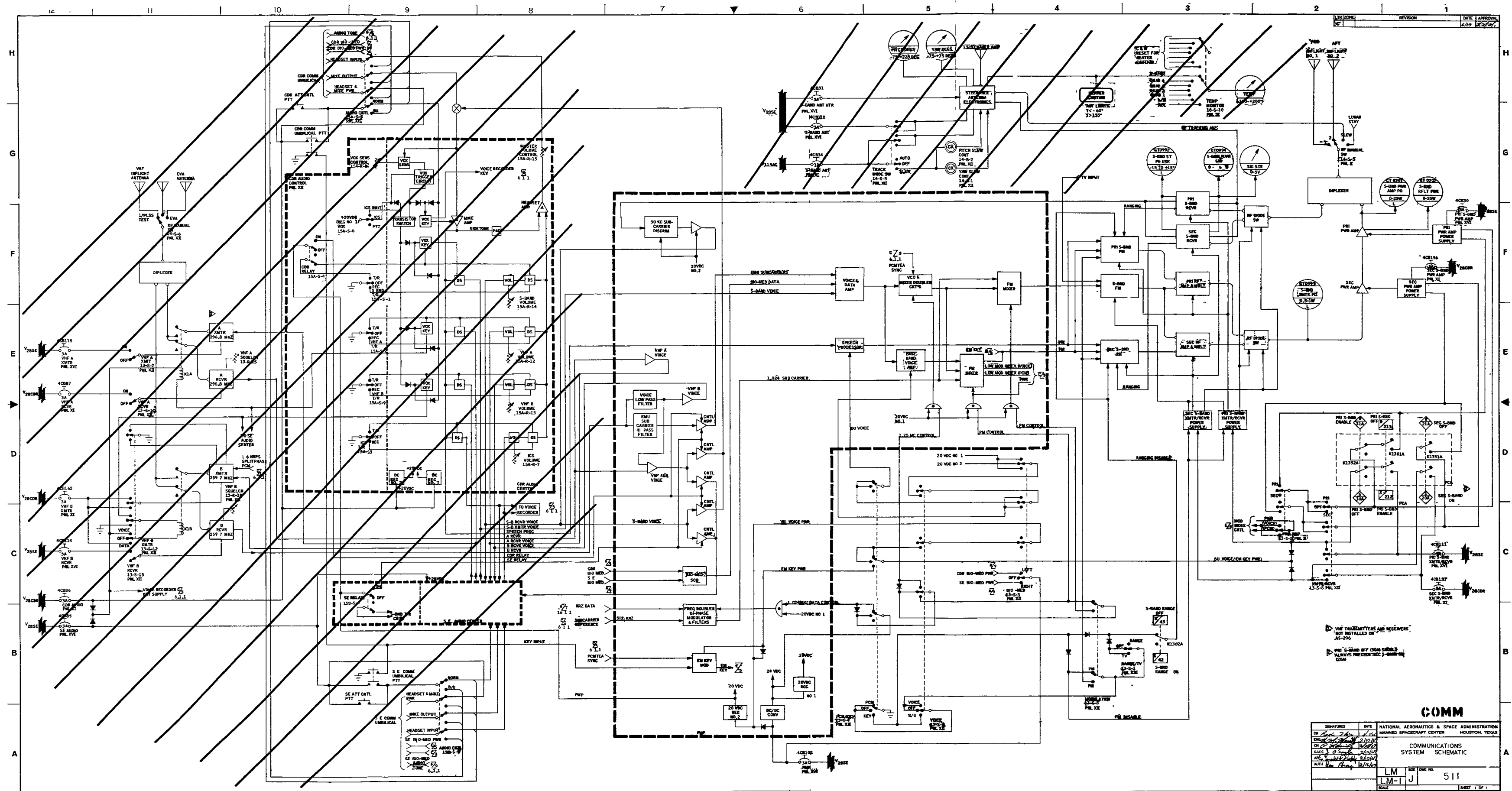
5.2 SYSTEM DATA

5.2.1 S-BAND

- A. TRANSCIVER POWER REQUIREMENTS 36 WATTS
- B. RECEIVER CHARACTERISTICS
1. PHASE LOCK RECEIVER
  2. FREQUENCY 2101.8 MHZ
  3. SENSITIVITY -127 dbm
- C. TRANSMITTER CHARACTERISTICS
1. MODULATION PM OR FM
  2. FREQUENCY FM 2282.5 MHZ  
PM 240  
221 F<sub>R</sub> MHZ
  3. RF POWER OUTPUT 0.75 TO 1.5 WATTS
- D. POWER AMPLIFIER CHARACTERISTICS
1. TYPE AMPLITRON (QKS 1300)
  2. RF DRIVE LEVEL 0.72 WATTS (MIN)
  3. RF POWER OUTPUT (PRD) 20 WATTS
  4. POWER INPUT 68.6 WATTS
- E. THE APPLICATION OF DC POWER TO THE PRIMARY OR SECONDARY POWER AMPLIFIER POWER SUPPLY WILL START AN AUTOMATIC 20 SECOND WARMUP SEQUENCE. AFTER THE WARMUP PERIOD, -1500 VDC IS APPLIED TO THE AMPLITRON ENABLING THE TUBE TO LOCK ON THE INPUT RF SIGNAL. IF THE AMPLITRON FAILS TO LOCK, THE POWER SUPPLY WILL AUTOMATICALLY REVERT TO THE WARMUP MODE AND THE CYCLE WILL BE REPEATED. THE MAXIMUM WARMUP TIME FOR A POWER AMPLIFIER IS 60 SECONDS.

TABLE 5-1 PRELAUNCH STATUS OF SWITCH/CIRCUIT BREAKER POSITIONS

SWITCH NAME	NUMBER	POSITION
AUDIO CONT	15A-S-5 AND 15B-S-5	NORM
S-BAND T/R	15A-S-1 AND 15B-S-1	OFF
ICS T/R	15A-S-3 AND 15B-S-3	OFF
RELAY	15A-S-4 AND 15B-S-4	OFF
S-BND RCVR VOL	15A-R-14 AND 15B-R-14	CCW
ICS RCVR VOL	15A-R-7 AND 15B-R-7	CCW
VOX ICS/XMTR	15A-S-6 AND 15B-S-6	PIT
VHF A T/R	15A-S-2 AND 15B-S-2	OFF
VHF B T/R	15A-S-9 AND 15B-S-9	OFF
VOX SENS	15A-R-8 AND 15B-R-8	CCW
VHF A VOL	15A-R-12 AND 15B-R-12	CCW
VHF B VOL	15A-R-13 AND 15B-R-13	CCW
MASTER VOL	15A-R-15 AND 15B-R-15	CCW
MODULATOR	13-S-5	PM
S-BND XMTR/RCVR	13-S-8	OFF
PWR AMP	13-S-2	OFF
VOICE/BU VOICE	13-S-6	OFF
PCM/KEY	13-S-4	PCM
RANGE/TV	13-S-1	OFF
VHF A XMTR	13-S-7	OFF
VHF A RCVR	13-S-10	OFF
VHF B XMTR	13-S-12	OFF
VHF B RCVR	13-S-15	OFF
BIOMED	13-S-3	OFF
SQUELCH VHF A	13-R-10	CCW
SQUELCH VHF B	13-R-15	CCW
VHF RF SW	14-S-6	1
S-BND RF SW	14-S-5	2
RECORDER	13-S-11	OFF
TRACK MODE	14-S-3	OFF
<u>CIRCUIT BREAKER NAME</u>		
S-BAND ANT HTR	4CB31	OPEN
S-BAND ANT	4CB34	OPEN
SEC S-BND XMTR/RCVR	4CB137	CLOSED
SEC S-BND PWR AMP	4CB136	CLOSED
VHF A RCVR	4CB87	OPEN
VHF B XMTR	4CB162	OPEN
CDR AUDIO	4CB86	OPEN
SE AUDIO	4CB85	OPEN
VHF A XMTR	4CB715	OPEN
VHF B RCVR	4CB114	OPEN
PRI S-BND PWR AMP	4CB30	CLOSED
PRI S-BND XMTR/RCVR	4CB111	CLOSED
S-BND ANT	4CB110	OPEN
PMF	4CB102	CLOSED
TV	4CB104	OPEN
DISP	4CB153	OPEN



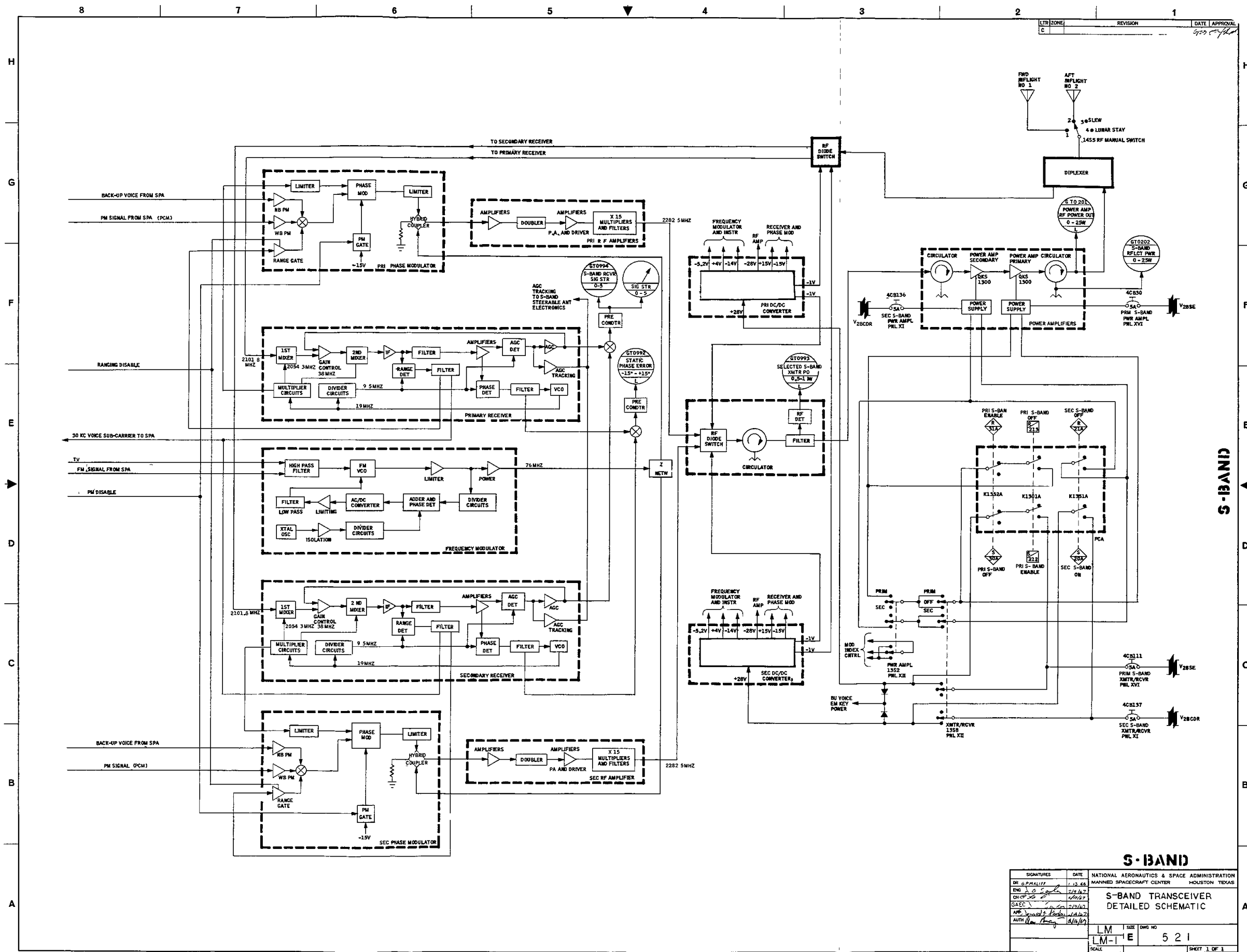
VHF TRANSMITTER AND RECEIVERS  
 NOT INSTALLED ON  
 AS-200  
 SEC 5-BAND OFF CHAN SIGNALS  
 ALWAYS PRECEDER SEC 5-BAND ON  
 CHAN

**COMM**

DATE	REVISION	DATE	APPROVAL
12/10/68	1	12/10/68	[Signature]
12/10/68	2	12/10/68	[Signature]
12/10/68	3	12/10/68	[Signature]
12/10/68	4	12/10/68	[Signature]
12/10/68	5	12/10/68	[Signature]

COMMUNICATIONS SYSTEM SCHEMATIC	
LM-1	511
SCALE	SHEET 1 OF 1



**S-BAND**

SIGNATURES		DATE	NATIONAL AERONAUTICS & SPACE ADMINISTRATION
DR. G. PHILLIPS		1-13-66	MANNED SPACECRAFT CENTER HOUSTON TEXAS
ENG. J. O. COOPER		2/2/67	
CH. J. S. ...		2/2/67	
SHEC ...		2/2/67	
APR. ...		2/2/67	
AUTO. ...		2/2/67	
SCALE		LM E	521
			SHEET 1 OF 1

\*

visual caution\*, warning\*, flag and/or indicator closures.

The C&WEA is capable of handling data in the form of analog signals, discrete voltage levels and switch closures. The C&WEA can evaluate this data and determine if the input signals are within the prescribed limits, and provide caution, warning, flag, advisory, and telemetry relay closures as required; there are three types of analog signal evaluation:

1. High limit - voltage above a specified value
2. Low limit - voltage below a specified value
3. Bandpass - voltage above or below a specified value

The C&WEA is also capable of processing inhibits which allow the C&WEA logic to ignore out-of-tolerance conditions when it is desirable to do so.

#### 6.1.4 Pulse Code Modulation and Timing Electronics Assembly (PCMTEA)

A. The PCMTEA consists of the following components:

1. Analog multiplexer drivers
2. High-level analog multiplexer
3. Calibrator
4. Analog-to-digital converter (coder)
5. Programmer
6. Digital multiplexer
7. Output register
8. Power supply
9. Timing equipment

B. Input signals for the PCM equipment are of three types: high-level analog, parallel digital, and serial digital.

Some parallel digital and high-level analog inputs are supplied directly to the PCMTEA from subsystem sensors; all other signals are first processed through the SCEA.

\* Definitions:

Caution - Malfunctions not requiring immediate attention but which would affect crew safety if action is not taken. Malfunctions in subsystems which time share displays. Malfunctions in subsystems whose displays are not readily visible to the astronaut.

Warning - Malfunctions that affect crew safety and require immediate attention.

\*

- C. The PCM equipment accepts the high-level analog signals through the multiplexer. The multiplexer forms pulse-amplitude-modulated (PAM) outputs representative of the analog inputs. The high-level PAM outputs of the multiplexer are supplied to high-speed gates (see Table 6-5) for application to the analog-to-digital converter on command from the programmer.
- D. The calibrator supplies two precision voltage outputs (4.25 and 0.75 volts dc) to the multiplexer to insure that overall accuracy of data is maintained through the PCMTEA. R-B
- E. The analog-to-digital converter converts the high-level PAM outputs of the high-speed gates into eight-bit binary words. For a zero-volt input, the converter generates the binary equivalent of a decimal 1 (MSB00000001 LSB). Each additional 19.7 millivolts of input signal increases the binary output by one; therefore, with a 5.00 volt dc input, the binary output will be 254 (MSB11111110 LSB). For an input exceeding 5 volts dc, the binary output will be all ones (MSB11111111 LSB) for an input less than 0 Vdc, the binary output will be all zeros (MSB00000000 LSB). R-C  
R-B  
R-C  
R-B  
R-C
- F. The programmer generates the necessary commands for analog and digital data sampling and operations, and supplies the basic timing for data transfer and subcarrier frequencies required in the PCMTEA as well as other subsystems. The programmer selects the high-bit rate or low-bit rate data-sampling formats by actuating Switch 13S13.
- G. The output of the analog-to-digital converter is supplied to the digital multiplexer. This multiplexer gates the analog-to-digital converter outputs, along with the frame synch and format identification words from the programmer and the serial digital and parallel digital data from the SCEA or from the subsystem sensors, to the output register. When these data exceed eight bits per word, the most significant eight bits R-B

are gated to the output first and then followed by the next most significant eight bits. The register converts these eight-bit words (parallel by bit) to serial outputs and routes them to the Communications Subsystem. These data are sampled and routed to the Communications Subsystem in non-returned-to-zero (NRZ) format at 51,200 bits per second (high bit rate) or 1,600 bits per second (low-bit rate), and split phase (RZ) format at 1,600 bits per second. Data generated by the LM Guidance Computer (LGC) in the Primary Guidance, Navigation, and Control (PGN&C) Subsystem are supplied to the output register in a 40-bit serial word format. Data generated by the Abort Guidance Computer (AGS) are supplied to the output register in a 24-bit serial word format.

R-B

- H. The timing equipment consists of an oscillator component, timing generator, time accumulator, and an output buffer. The oscillator component accepts a 1024 kc signal from the LGC, frequency doubles it, and routes it to the timing generator. The frequency doubled 1024 kc LGC signal also controls the output of an internal 2048 kc crystal oscillator. Therefore, if the LGC signal fails, the oscillator component can instantaneously switch to the crystal oscillator signal without any interruption of the signal to the timing generator. The timing generator supplies sync pulses to the Electrical Power Subsystem, the Guidance, Navigation, and Control Subsystem, and the Communications Subsystem via the timing data output buffer. It also supplies the time accumulator with a 1 cps signal that is converted to mission-elapsed-time data. The time accumulator recycles to zero at 40 days or upon interruption of PCMTEA power. These data are routed to the DSEA (when used) for simultaneous recording with voice.

R-C

R-B



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LM  
AS-206  
REV B

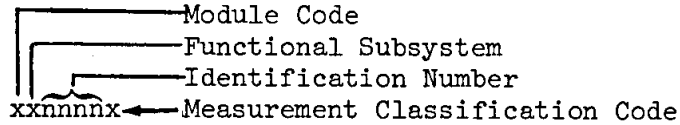
The timing generator supplies all the timing signals required in the programmer for generating frame sync, frame identification, and format identification data.

- I. Internally Redundant Measurement Sampling (See Figure 6-1) - Some data words are wired redundantly within their respective multiplexer (analog or digital). This does not, in effect, double the sampling rate for such parameters because the redundant data word loading is spaced unevenly timewise. (Were the time correlation evenly spaced, then sampling would be essentially doubled or supercommutated). Refer to Figure 6-1 for a depiction of the time correlation. An example of this type of parameter would be the battery currents GC1201-1206C. Redundant transducers, which supply duplicate data concerning a particular parameter, are wired to the PCMTE external connector and may be treated as two separate data points. An example of this type of parameter would be GQ3018P and GQ3025P (LM-2 and sub) DPS HE REG PRESS.

R-B

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1. MEAS ID - Measurement identification number as delineated below:



Module Code: A = Adapter - NAA  
G = LM GAEC

Functional Subsystem Codes: A = Adapter  
C = Electrical Power  
D = Command  
F = Environmental Control  
G = Navigation and Guidance  
H = Stab and Control - CES  
I = Stab and Control - AGS  
L = Instrumentation  
M = Mechanical Design  
N = Radars  
P = Propulsion - Ascent Engine  
Q = Propulsion - Descent Engine  
R = Reaction Control  
T = Communications  
W = Programmer  
Y = Pyrotechnics

R-B

Measurement Classification Codes:

B = Phase  
C = Current  
E = Power  
F = Frequency  
H = Position  
J = Biomedical  
L = Velocity  
P = Pressure  
Q = Quantity  
R = Rate  
T = Temperature  
U = Combined meas.  
V = Voltage  
W = Time  
X = Discrete Event

2. MEAS DESCRIPTION - A brief "field title" given to each measurement.

\*

LM-1  
REV C

TABLE 6-3 SPACECRAFT INSTRUMENTATION (Cont'd)

3. PAM LOCATION - The PCMTE high-speed PAM gate and sequences assigned to each indicated measurement.
4. SCERA LOCATION - The signal conditioning electronic replaceable assembly (SCERA) member and location within the assembly for the indicated measurement.
5. TM DATA RANGE - Actual telemetered range of the data to be received by the ground stations.
  1. Discretes - "0" or "1" with applicable indication
  2. Analog - Lowest and highest telemetered data range for each analog measurement.ACC PCT - Spacecraft telemetered data range Root Sum Square (RSS) accuracy in percent of full scale.
6. ONBOARD DISPLAY RANGE - Indicated range of the spacecraft onboard display.  
ACC PCT - Onboard display Root Sum Square accuracy in percent of full scale.
7. C&W LIMITS - The low and high value of the accuating parameter inputs to the onboard caution and warning instrumentation.
8. ADV - The spacecraft onboard advisory indication; light or flag designation number listed.
9. ESTIMATED NORMAL OPERATING LIMITS - Best engineering estimate of the low, normal, and high limits of the respective analog parameters. Discrete parameters are designated as such.
10. CRITICAL LIMITS - The high and/or low limits of each measurement that will cause permanent loss of equipment and/or life, or mission.
11. S/C SAMPLING - Spacecraft PCMTE data sampling rate using the following code:

R-C

R-B

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LM  
AS-206  
REV B

TABLE 6-3 SPACECRAFT INSTRUMENTATION (Concluded)

EXAMPLE: 50/1DPER

High-bit rate samples per second  
Low-bit rate samples per second  
Digital  
Parallel  
Event  
Internally wired redundant on high  
and low bit rate within the PCMTE  
Event

NOTE

Where the redundant "R" is shown as  
1R/1..... the internal redundancy is  
wired for high-bit rate only.

R-B

Alphabetic characters utilized to describe the types of input channels to PCM:

AH = Analog, High-Level  
D = Digital  
P = Parallel  
S = Serial  
E = Event

11. NOTES - May contain any other pertinent notation concerning each respective parameter.

TABLE 6-3.1 SPACECRAFT INSTRUMENTATION FOR SLA (S-IVB/IU)

MEAS ID	MEAS DESCRIPTION	PAM LOCATION TABLE V PAM NO. - SEQ NO.	SCERA LOCATION TABLE IV SCERA/LOC	TM DATA RANGE			RSS ACC PCT	ONBOARD DISPLAY RANGE		RSS ACC PCT	CSW LIMITS			ESTIMATED NORMAL OPERATING LIMITS		CRITICAL LIMITS		S/C SAMPLING	NOTES	
				LOW	HIGH	UNITS		LOW	HIGH		LOW	HIGH	ADV	LOW	HIGH	LOW	HIGH			
K141-900	CAP/SLA PHYS 1			0 = SEP	-															
K142-900	CAP/SLA PHYS 2			0 = SEP	-															
K143-900	MOSECAP RLY A			1 = RLY CLSD	-													120 S/S	IU TM	
K144-900	MOSECAP RLY B			1 = RLY CLSD	-													120 S/S	IU TM	
K145-900	LM/SLA SEP CMD A			1 = RLY CLSD	-													120 S/S	IU TM	
K146-900	LM/SLA SEP CMD B			1 = RLY CLSD	-													12 S/S	IU TM	
K147-900	SLA DEPLOY CMD A			1 = RLY CLSD	-													12 S/S	IU TM	
K148-900	SLA DEPLOY CMD B			1 = RLY CLSD	-													12 S/S	IU TM	
K149-900	SLA PANEL DEPLOY			1 = DEPLOY	-													12 S/S	IU TM	

MEAS ID	MEAS DESCRIPTION	PAM LOCATION TABLE V PAM NO. - SEQ NO.	SCERA LOCATION TABLE IV SCERA/LOC		TM DATA RANGE LOW HIGH UNITS			RSS ACC PCT	ONBOARD DISPLAY RANGE		RSS ACC PCT	C&W LIMITS			ESTIMATED NORMAL OPERATING LIMITS			CRITICAL LIMITS		S/C SAMPLING	NOTES
									LOW	HIGH		LOW	HIGH	ADV	LOW	NORM	HIGH	LOW	HIGH		
GC0071V	AC BUS VOLT	3-10	1/17	1/18	0	125	VRMS	1.27	GREEN BAND	4.63	112			115.8	117	118.2	110	120	1/1 AH	GL4046 4M2 NO AC LOAD	
GC0155F	AC BUS FREQ	3-14	1/16	1/18	380	420	CP5	1.27			398		402	399	400	401	390	410	1 AH	GL4046	
GC0201V	BAT. 1 VOLT	1-8	2/16		0	40	VDC	1.12	20	40	4.47			28.5	29-30	32.5	31.0		1 AH	4M2 UNDER LOAD OPEN CKT	
GC0202V	BAT. 2 VOLT	1-7	2/16		0	40	VDC	1.12	20	40	4.47			28	29-30	32.5	31.0		1 AH	4M2 UNDER LOAD OPEN CKT	
GC0203V	BAT. 3 VOLT	1-9	2/16		0	40	VDC	1.12	20	40	4.47			28	29-30	32.5	31.0		1 AH	4M2 UNDER LOAD OPEN CKT	
GC0204V	BAT. 4 VOLT	1-7	2/16		0	40	VDC	1.12	20	40	4.47			28	29-30	32.5	31.0		1 AH	4M2 UNDER LOAD OPEN CKT	
GC0205V	BAT. 5 VOLT	2-5	2/17		0	40	VDC	1.12	20	40	4.47			27.5	29	30	32.0		1/1 AH	4M2 UNDER LOAD OPEN CKT	
GC0206V	BAT. 6 VOLT	2-6	2/18		0	40	VDC	1.12	20	40	4.47			27.5	29	30	32.0		1/1 AH	4M2 UNDER LOAD OPEN CKT	
GC0301V	CDR BUS VOLT	3-12/3-14	1/15	1/18	0	40	VDC	1.27	20	40	4.6	26.5		27		32.5	32.0		1/1 AH	4M2 GL4034	
GC0302V	SE BUS VOLT	1-11	2/8	2/15	0	40	VDC	1.50	20	40	4.9	26.5		27		32.5	26.5		1/1 AH	4M2 GL4034	
GC1201C	BAT. 1 CUR	1-9/3-11			0	60	AMPS	1.58	0	120	2.5			0	25	25			1/1 AHR	4M3	
GC1202C	BAT. 2 CUR	3-12/1-13			0	60	AMPS	1.58	0	120	2.5			0	25	25			1/1 AHR	4M3	
GC1203C	BAT. 3 CUR	1-9/3-9			0	60	AMPS	1.58	0	120	2.5			0	25	25			1/1 AHR	4M3	
GC1204C	BAT. 4 CUR	3-9/3-10			0	60	AMPS	1.58	0	120	2.5			0	25	25			1/1 AHR	4M3	
GC1205C	BAT. 5 CUR	1-8/3-11			0	120	AMPS	1.58	0	120	2.5			0	45	45			1/1 AHR	4M3	
GC1206C	BAT. 6 CUR	1-9/3-9			0	120	AMPS	1.58	0	120	2.5			0	45	45			1/1 AHR	4M3	
GC4361X	BAT. 1 HI TAP		2/4		ALWAYS ZERO									HFL1		DISCRETE			1 DPE	BAT HI TAPS WIRED TO LO TAP DISCRETES LM-1 ONLY	
GC4362X	BAT. 1 LO TAP		2/4		1 = LO									HFL1		DISCRETE			1 DPE		
GC4363X	BAT. 2 HI TAP		2/4		ALWAYS ZERO									HFL2		DISCRETE			1 DPE		
GC4364X	BAT. 2 LO TAP		2/4		1 = LO									HFL2		DISCRETE			1 DPE		
GC4365X	BAT. 3 HI TAP		2/4		ALWAYS ZERO									HFL3		DISCRETE			1 DPE		
GC4366X	BAT. 3 LO TAP		2/4		1 = LO									HFL3		DISCRETE			1 DPE		
GC4367X	BAT. 4 HI TAP		2/4		ALWAYS ZERO									HFL4		DISCRETE			1 DPE		
GC4368X	BAT. 4 LO TAP		2/4		1 = LO									HFL4		DISCRETE			1 DPE		
GC4369X	BAT. 5 B/U CDR		2/4		1 = ON									HFL7		DISCRETE			1 DPE		
GC4370X	BAT. 6 NORM CDR		2/4		1 = ON									HFL6		DISCRETE			1 DPE		
GC4371X	BAT. 5 NORM SE		2/4		1 = ON									HFL5		DISCRETE			1 DPE		
GC4372X	BAT. 6 B/U SE		2/4		1 = ON									HFL8		DISCRETE			1 DPE		
GC9961U	BAT. 1 MAL		2/12	2/13	1 = MAL							OC/OT/RC		HDS1		DISCRETE			1 DPE	GL9001	
GC9962U	BAT. 2 MAL		2/12	2/13	1 = MAL							OC/OT/RC		HDS1		DISCRETE			1 DPE	GL4047	
GC9963U	BAT. 3 MAL		2/12	2/13	1 = MAL							OC/OT/RC		HDS1		DISCRETE			1 DPE	GL9001	
GC9964U	BAT. 4 MAL		2/12	2/13	1 = MAL							OC/OT/RC		HDS1		DISCRETE			1 DPE	GL4047	
GC9965U	BAT. 5 MAL		2/12	2/13	1 = MAL							OC/OT/RC		HDS1		DISCRETE			1 DPE	GL9001	
GC9966U	BAT. 6 MAL		2/12	2/13	1 = MAL							OC/OT/RC		HDS1		DISCRETE			1 DPE	GL4047	
GL0300	FRAME SYNC AND ID																			50/1 DP	
GL0302	LBR																			1/1 DP	
GL0401V	CAL 85 PCT	3-5/1-4			0	5.00	VDC	0.50							4.23	4.25	4.27	4.23	4.27	1 OR/1 AH	
GL0402V	CAL 15 PCT	3-5/4-5			0	5.00	VDC	0.50							0.73	0.75	0.77	0.73	0.77	1 OR/1 AH	
GL0501W	MET				-	40	DAYS													10/1 DP	
GL4054X	C&W PWR FAIL				1 = FAIL								POWER FAIL							1/1 DP	
GL4221X	DFTI CAL ON				1 = ON															1/1 DP	
GL4222X	LM/SLA SEP				0 = SEP															1 DPE	
GT0201E	S-BND PWR AMP PO	1-14			0	25	W													1/1 AH	
GT0202E	S-BND RELT PWR	1-13			0	25	W													1 AH	
GT0441X	DCA STATUS																			50 DP	
GT0619V	UMF SIG STR	2-5			-114	-59	DBM													1 AH	
GT0992B	S-BND ST PH ERR	2-14/2-3			-15	+15	DEG													10 AH	
GT0993E	S-BND XMTR PO	1-14			0.3	1.5	W													1/1AH	
GT0994V	S-BND SIG STR	3-3			0	4.2	VDC		0	5					3.4		4.25	1.1	4.25	10 AH	THIS MEASUREMENT NO LONGER INDICATES THE S-BAND TRANSMITTER POWER OUTPUT. FOR READOUTS GREATER THAN 0.5 VDC TRANSCIEVER IS ON. MAINTAIN LOCK ACQ LOCK WITH PRI AMP
GY1111X	ED ARM A ON			1/14	1 = OFF															1/1 DP	
GY1112X	ED ARM B ON			1/14	1 = OFF															1/1 DP	
GY1121X	STG RLY A FIRE			1/14	1 = SAFE															1/1 DP	
GY1122X	STG RLY B FIRE			1/14	1 = SAFE															1/1 DP	

R-C

R-C

R-C

R-C

TABLE 6-3.3 SPACECRAFT INSTRUMENTATION FOR ECS

MEAS ID	MEAS DESCRIPTION	PAM LOCATION TABLE V PAM NO. - SEQ NO.	SCERA LOCATION TABLE IV SCERA/LOC	TM DATA RANGE			RSS ACC PCT	ONBOARD DISPLAY RANGE		RSS ACC PCT	C/W LIMITS		ADV	ESTIMATED NORMAL OPERATING LIMITS			CRITICAL LIMITS		S/C SAMPLING	NOTES
				LOW	HIGH	UNITS		LOW	HIGH		LOW	HIGH		LOW	NORM	HIGH	LOW	HIGH		
GF2021P	PRI GLY PUMP	1-10/3-9	---	0	50	PSID	1.87	---	---	---	---	---	35	35.3	35.7	13	36.8	1/1 A/R	GL4058	
GF2041X	GLY LEVEL LOW	---	2/3	1 = LOW				---	CC					DISCRETE			1/1 DPER			
GF2936X	SEL GLY PUMP FAIL	---	---						CC			7053						---		
GF3571P	CABIN PRESS.	1-9/3-11	---	0	10	PSIA	2.55	0	10	3.20			1.0		6.1		7.7	1/1 A/R	NOT TM 7M2A DURING FLIGHT	
GF3582P	ASC 1 O <sub>2</sub> PRESS	1-14	1/7	0	25	PSIA	2.62	0	100%				3.5	4.35	5.0	B	D	1 AH		
GF3583P	ASC 2 O <sub>2</sub> PRESS	2-13	1/7	0	25	PSIA	2.62	0	100%				3.5	4.35	5.0	B	D	1 AH		
GF3591P	U/H RLF PRESS.	3-15	---	0	25	PSIA	2.55		---				1		6.1			1/1 AH	A + B > 2.5 C + D < 6.5	
GF3592P	F/H RLF PRESS.	1-14	---	0	25	PSIA	2.55		---				1		6.1			1/1 AH		
GF4101P	PRI H <sub>2</sub> O REG ΔP	2-12/4-14	1/18	0	2	PSID	3.04		---				0.5	.75	1.0	A	C	1/1 A/R		
GF4511T	PRI W/B H <sub>2</sub> O TEMP	4-15	2/6	20	160	°F			---				57	70	83	33	120	1/1 AH	GL4059 7M4B GL4059 7M4B	
GF4582Q	ASC 1 H <sub>2</sub> O QTY	2-6/4-8	1/8	0	100	PCT	2.91	0	100	3.49	95		67		100	34		1/1 A/R		
GF4583Q	ASC 2 H <sub>2</sub> O QTY	2-6/4-8	1/8	0	100	PCT	2.91	0	100	3.49	95		67		100	34		1/1 A/R		
GF9997U	GLY PUMP PRESS	3-6	---	0	60	PSIA	2.06	0	80	2.50			41.0	42.8	44.7	19	46	1/1 AH	7M5A 7M5B GL4058	
GF9998U	GLY TEMP	3-11	1/10	20	120	°F	2.77	0	80	3.95	47.6		38	42	45	32	50	1/1 AH		

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TABLE 3-3.- SPACECRAFT INSTRUMENTATION FOR GNC

FORM 1  
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MEAS ID	MEAS DESCRIPTION	PAM LOCATION TABLE V PAM NO. - SEQ NO.	SCERA LOCATION TABLE IV SCERA/LOC	TM DATA RANGE			RSS ACC PCT	ONBOARD DISPLAY RANGE		RSS ACC PCT	CGW LIMITS			ESTIMATED NORMAL OPERATING LIMITS		CRITICAL LIMITS		S/C SAMPLING	NOTES
				LOW	HIGH	UNITS		LOW	HIGH		LOW	HIGH	ADV	LOW	NORM HIGH	LOW	HIGH		
GG0001X GG0117H	PG'S CONTR WGRS PCS ALT (LGC)																	50 DS	---
GG0118L	VEL ALT RATE (LGC)																		NOT TM 9M9A
GG0119L	VEL FWD (LGC)																		NOT TM 9M9B
GG0120L	VEL LAT (LGC)																		NOT TM 9M2/3
GG1340V	FLS TGRS REF	1-7/3-6																	NOT TM 9M2/3
GG1110V	2-3 VDC TM BJA	2-7/4-7																	
GG1201V	TM 28 VAC 600	2-11																	
GG1331V	JRIG SUSP 3.2																		
GG1513X	KC	2-5																	
GG1523X	IMU STBY																		
GG2001V	LGC OPR																		
GG2021V	X PIPA OUT	2-1/1-2																	
GG2041V	Y PIPA OUT																		
GG2041V	IN 4	1-1																	
GG2107V	Z PIPA OUT																		
GG2107V	IN 4	3-1/2-2																	
GG2110C	IG TORQ MTR																		
GG2112V	CLR	3-2																	
GG2113V	IG RSVR OUT																		
GG2113V	SIN	3-3																	
GG2121V	IG RSVR OUT																		
GG2122V	CLR	3-4																	
GG2122V	CCS	2-2																	
GG2123V	IG RSVR OUT																		
GG2123V	SIN																		
GG2137V	IG RSVR OUT																		
GG2137V	CLR	3-1/2-1																	
GG2140C	MG TORQ MTR																		
GG2142V	CLR	3-2																	
GG2143V	MG RSVR OUT																		
GG2143V	SIN	4-3/2-3																	
GG2151V	MG RSVR OUT																		
GG2152V	CLR	1-4/1-5																	
GG2153V	MG RSVR OUT																		
GG2153V	SIN	2-1																	
GG2167V	MG RSVR OUT																		
GG2167V	CLR																		
GG2170C	CG RSVP SIN																		
GG2172V	(EXP)	2-2																	
GG2172V	CG RSVR OUT																		
GG2173V	CLR																		
GG2181V	CG RSVR OUT																		
GG2182V	SIN	1-2/2-2																	
GG2183V	CG RSVR OUT																		
GG2183V	CLR																		
GG2217V	CG RSVR OUT																		
GG2219V	SIN																		
GG2247V	PITCH ATT ERR (PG-S)																		
GG2249V	PITCH ATT ERR (PG-S)																		
GG2277V	ROLL ATT ERR (PG-S)																		
GG2279V	ROLL ATT ERR (PG-S)																		
GG2300T	PIPA TEMP	1-11/3-14																	
GG2301T	JRIG TEMP	3-12																	
GG6320T	PIPA CAL TEMP	1-15																	
GG9301X	LGC WARNING																		
GG9302X	ISE WARNING																		
GG9303X	PG'S CAUTION																		
GG1204X	C-T DET																		
GG1214X	AUTO ON																		

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MEAS ID	MEAS DESCRIPTION	PAM LOCATION TABLE V PAM NO. - SEQ NO.	SCERA LOCATION TABLE IV SCERA/LOC	TM DATA RANGE		RSS ACC PCT	ONBOARD DISPLAY RANGE		RSS ACC PCT	CDW LIMITS		ADV	ESTIMATED NORMAL OPERATING LIMITS			CRITICAL LIMITS		S/C SAMPLING	NOTES
				LOW	HIGH		UNITS	LOW		HIGH	LOW		HIGH	LOW	NORM	HIGH	LOW		
GH1237X	AUTO OFF	---	2/14	1 = OFF															
GH1230X	APS ARM	---	1/3	1 = ARM															
GH1240V	X-TRANS CMD	1-3	2/17	-10 +10	VDC														
GH1247V	YAW ERR CMD	1-12/4-4	2/18	-13 +13	VDC	1.12													
GH1248V	PITCH ERR CMD	1-12/2-4	2/18	-13 +13	VDC	1.12													
GH1249V	ROLL ERR CMD	1-13/2-4	2/18	-13 +13	VDC	1.12													
GH1260X	APS ON	---	2/2	1 = ON															
GH1283X	ABORT STAGE	---	2/14	1 = STAGE															
GH1286X	EIG FIRE OVER- RIDE	---	2/14	1 = ON															
GH1301X	EPS ON	---	2/3	1 = ON															
GH1311V	NOZ THRUST CMD	4-12	1/15	0 14.6	VDC	5.12	0	100%	4.94										
GH1313V	PITCH GDA POS	1-6/3-3	2/9	-15 +15	VRMS	1.50													
GH1314V	ROLL GDA POS	1-5/4-3	2/9	-15 +15	VRMS	1.50													
GH1323X	P TRM FAIL	---	2/3	1 = FAIL															
GH1330X	R TRM FAIL	---	2/3	1 = FAIL															
GH1331V	AUTO THRUST CMD	3-15/4-3	1/15	0 12	VDC	5.81	0	100%	5.50										
GH1346X	DPS ARM	---	1/3	1 = ARM	VDC														
GH1401V	RGA SP MTR A-B	---	2/7																
GH1402V	RGA SP MTR B-C	---	2/7																
GH1433V	RGA SP MTR C-A	---	2/7																
GH1405V	RGA PICKOFF	---	1/17																
GH1406V	+15 VDC SUP	---	2/19																
GH1407V	+15 VDC SUP	---	2/19																
GH1408V	+4.3 VDC SUP	---	2/8																
GH1418V	JD 4U OUTPUT	---	1/4	1 = ON															
GH1419V	JD 4D OUTPUT	---	1/4	1 = ON															
GH1420V	JD 4F OUTPUT	---	1/4	1 = ON															
GH1421V	JD 4S OUTPUT	---	1/4	1 = ON															
GH1422V	JD 3U OUTPUT	---	1/4	1 = ON															
GH1423V	JD 3D OUTPUT	---	1/4	1 = ON															
GH1424V	JD 3F OUTPUT	---	1/4	1 = ON															
GH1425V	JD 3S OUTPUT	---	1/4	1 = ON															
GH1426V	JD 2U OUTPUT	---	1/2	1 = ON															
GH1427V	JD 2D OUTPUT	---	1/2	1 = ON															
GH1428V	JD 2F OUTPUT	---	1/2	1 = ON															
GH1429V	JD 2S OUTPUT	---	1/2	1 = ON															
GH1430V	JD 1U OUTPUT	---	1/2	1 = ON															
GH1431V	JD 1D OUTPUT	---	1/2	1 = ON															
GH1432V	JD 1F OUTPUT	---	1/2	1 = ON															
GH1433V	JD 1S OUTPUT	---	1/2	1 = ON															
GH1451V	RGA YAW RATE	2-3/3-4	2/10	-3.5 +3.5	VRMS	2.74													
GH1452V	RGA PITCH RATE	2-3/3-5	2/10	-3.5 +3.5	VRMS	2.74													
GH1453V	RGA ROLL RATE	2-3/3-4	2/10	-3.5 +3.5	VRMS	2.74													
GH1458V	PRT -4.7 VDC	---	2/15																
GH1459V	SEC -4.7 VDC	---	2/15																
GH1473V	+6 VDC SUP	---	2/10																
GH1484V	+6 VDC SUP	---	2/19																
GH1487V	YAW RGA SIG	---			VRMS		-2.8	+2.8	6.00										
GH1488V	PITCH RGA SIG	---			VRMS		-2.8	+2.8	6.00										
GH1495V	ROLL RGA SIG	---			VRMS		-2.8	+2.8	6.00										
GH1503X	MIN D-24 (INVS LOGIC)	---	1/3	1 = 0 VDC	(WIDE)														
GH1508X	AUTO VEE	---	2/14	1 = ON															
GH1509X	ATT HOLD	---	2/14	1 = HOLD	(ON)														
GH1511X	AGS SEL	---	2/3	1 = AGS SEL															
GH1296X	REAL CPLS	---	2/14	1 = ON	(YES)														
GL4026X	LES AC PAR FAIL	---		1 = FAIL															
GL4027X	LES DC PAR FAIL	---		1 = FAIL															
GW5151V	PRA COMPARE	---		1 = COMPARE															
GW5153V	PRA CLOCK ON	---		1 = ON															
GY0056X	SECRET CMD	---	1/2	1 = CMD	(ON)														

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TABLE 6-3.5 SPACECRAFT INSTRUMENTATION FOR PROPULSION

MEAS ID	MEAS DESCRIPTION	PAM LOCATION TABLE V PAM NO. - SEQ NO.	SCERA LOCATION TABLE IV SCERA/LOC	TM DATA RANGE				R55 ACC PCT	ONBOARD DISPLAY RANGE			R55 ACC PCT	CDW LIMITS			ESTIMATED NORMAL OPERATING LIMITS			CRITICAL LIMITS		S/C SAMPLING	NOTES	
				LOW	HIGH	UNITS	ACC		LOW	HIGH	LOW		HIGH	ADV	LOW	NORM	HIGH	LOW	HIGH				
GP0001P	APS HE 1 PRESS	1-14/2-12	1/3	0	4000	PSIA	1.96	0	4000	1.94	2993.6				2700	3500	1000	3500	1/1 AHR	PREPRESS. POSTPRESS. ENG. BURN GL4022 10M1	R-C		
GP0002P	APS HE 2 PRESS	2-9/4-11	1/9	0	4000	PSIA	1.96	0	4000	1.94	2993.6				400	3500	1000	3500	1/1 AHR	GL4022 10M1	-		
GP0025P	APS HE REG PRESS.	3-7	1/8	0	300	PSIA	1.96						220.2						1/1 AHR	PREPRESS. POSTPRESS. ENG. BURN GL4041	R-C		
GP0201T	APS HE 1 TEMP	1-11/3-14	2/21	-200	+200	°F	1.78	-200	+200	1.78					30	70	140	140	1/1 AHR	10M1 PREPRESS. POSTPRESS. ENG. BURN POST BURN	R-C		
GP0202T	APS HE 2 TEMP	2-5/4-7	2/21	-200	+200	°F	1.78	-200	+200	1.78					30	70	140	140	1/1 AHR	10M1 PREPRESS. POSTPRESS. ENG. BURN POST BURN	R-C		
GP0318X	APS HE 1 CLSD		1/12	1 = CLSD										10FL1									
GP0320X	APS HE 2 CLSD		1/12	1 = CLSD										10FL2									
GP0718T	APS FUEL TEMP	2-13/4-12	1/8	20	120	°F	2.78	40	100	4.97					50	70	90	100	1/1 AHR	10MAA GL4042			
GP0908X	APS FUEL LO		2/2	1 = LO																			
GP1218T	APS OX TEMP	2-11/4-13	1/8	20	120	°F	2.78	40	100	4.97					50	70	90	100	1/1 AHR	10M4B GL4042			
GP1408X	APS OX LO		2/2	1 = LO																			
GP1501P	APS FUEL PRESS	2-8/4-10	1/19	0	250	PSIA	2.15	0	300	2.65	119.75								1/1 AHR	GL4022 10M3A			
GP1503P	APS OX PRESS.	2-10/4-9	1/19	0	250	PSIA	2.15	0	300	2.65	119.75				100	190	100	190	1/1 AHR	PREPRESS. POSTPRESS. ENG. BURN POST BURN GL4022 10M3B	R-C		
GP2010P	APS TOP	2-13/3-15	-	0	150	PSIA	2.06								100	190	100	190					
GP2997U	APS PROP VLVS POS		2/14	1 = MISMATCH											155	165	175	115	225	1/1 AHR	POST BURN ENG. BURN	R-C	
GP2998U	APS HE REG PRESS.	4-8	1/19	0	300	PSIA	1.96				220	260			178	203	170	203	1/1 AHR	GL4023 PREPRESS. BETWEEN BURNS FULL THR. BURNS	R-C		
GQ3309X	DPS HE 1 CLSD		-	1 = CLSD											50	243	248	0	308				
GQ3310X	DPS HE 2 OPN		-	1 = OPN											243		248	242	253	1 DPE			
GQ3435P	DPS HE PRESS.	1-5/3-6	-	0	2000	PSIA	1.21	0	2000	1.35							245	248	220	260	1 DPE		
GQ3603Q	DPS FUEL 1 QTY	2-9/4-11	-	0	95	PCT	*		SELECTED						500	1380	350	1560	1/1 AHR	10M1 PREPRESS. FULL THR. BURN BETWEEN BURNS	R-C		
GQ3604Q	DPS FUEL 2 QTY	2-10/4-9	-	0	95	PCT	#	0	SELECTED	**					350	1550	300	1710	1R/1 AH	10M5B 10M5B 10M5B			
GQ3605Q	DPS FUEL QTY SEL		-	0	95	PCT	#	0	SELECTED	**					300	1550		1710	1R/1 AH				
GQ3611P	DPS FUEL PRESS	1-10/3-10	-	0	300	PSIA	1.87	0	300	2.69									1/1 AHR	10M3A PREPRESS. FULL THR. BURN 10% THR. BURN BETWEEN BURNS	R-C		
GQ3718T	DPS FUEL 1 TEMP	2-7/4-6	1/9	20	120	°F	40	40	100						190	220	230	160	230	1 AHR	10M4A 10M4A		
GQ3719T	DPS FUEL 2 TEMP	1/4-13	1/9	20	120	°F	40	40	100						214	220	224	190	240	1 AHR	10M4A 10M4A		
GQ4103Q	DPS OX 1 QTY	2-13/4-12	-	0	95	PCT	*		SELECTED						229	235	239	220	260	1R/1 AH	10M5A 10M5A		
GQ4104Q	DPS OX 2 QTY	2-11/4-15	-	0	95	PCT	#		SELECTED						242	253	242	253	5.6	5.6	1R/1 AH	10M5A 10M5A	
GQ4105Q	DPS OX QTY SEL		-	0	95	PCT	#	0	SELECTED	**					50	70	90	40	100	1R/1 AH	10M5A 10M5A		
GQ4111P	DPS OX PRESS.	1-5/3-7	-	0	300	PSIA	1.87	0	300	2.69									1/1 AHR	10M5B PREPRESS. FULL THR. BURN 10% THR. BURN BETWEEN BURNS	R-C		
GQ4218T	DPS OX 1 TEMP	1-5/3-8	1-10	20	120	°F	2.78	40	100	4.97					242	253	242	253	1 AHR	10M4B 10M4B			
GQ4219T	DPS OX 2 TEMP	1-6/3-8	1-10	20	120	°F	2.78	40	100	4.97					50	70	90	40	100	1 AHR	10M4B 10M4B		
GQ4455X	DPS PROP LO		2/2	1 = LO											50				100	1 DPE	GL4024		

\*ACC  
0 TO 8 PCT  
8 TO 25 PCT  
25 TO 95 PCT

\*\*ACC  
0 TO 8% QTY  
8 TO 25% QTY  
25 TO 95% QTY

1.0%  
0.5%  
1.0%

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TABLE 6-3.5 SPACECRAFT INSTRUMENTATION FOR PROVISION (CONCLUDED)

MEAS ID	MEAS DESCRIPTION	PAY LOCATION TABLE V PAM NO. - SEQ NO.	SCERA LOCATION TABLE IV SCERA/LOC	TM DATA RANGE			RSS ACC PCT	ONBOARD DISPLAY RANGE		RSS ACC PCT	CDW LIMITS		ADV	ESTIMATED NORMAL OPERATING LIMITS			CRITICAL LIMITS		S/C SAMPLING	NOTES
				LOW	HIGH	UNITS		LOW	HIGH		LOW	HIGH		LOW	NORM	HIGH	LOW	HIGH		
GQ610P	RCS TOP	1-13/3-10	-	0	200	PSIA	1.87	0	100%	3.50	-	-	-	100	104	100	55	110	1/1 AHR	SM2A FULL THRO. BURN
GQ610H	VAR 1 IS ACT POS	2-14/4-1/4-2	-	0	1	INCH	1.12	0	-	-	-	-	-	0	-	100	7	14	(50 AH) 1/1 AH	IS THRO. BURN
GQ7-98U	RCS PREP VALS 2PCS	-	2/14	1 = Δ POSITION MISMATCH			-	-	-	-	-	-	-	-	-	-	-	-	(100 DPE) 1 DPE	
GQ7-99U	RCS PREP A DT	1-12/3-14	-	0	100	PCT	-	-	-	-	-	-	-	0	-	100	-	-	1R/1 AH	
GR105Q	RCS A HE TEMP	1-12/3-12	2/20	20	120	°F	-	-	-	-	-	-	-	40	-	100	-	120	1/1 AHR	
GR105R	RCS B HE TEMP	1-11/3-13	-	0	100	PCT	-	-	-	-	-	-	-	0	-	100	-	-	1R/1 AHR	
GR105T	RCS A HE PRESS	1-13/3-13	2/20	20	120	°F	-	-	-	-	-	-	-	40	-	100	-	120	1/1 AHR	
GR110P	RCS B HE PRESS	2-12/4-14	1/6	0	3500	PSIA	1.96	0	4000	2.60	1696	-	-	1240	-	3000	500	3500	1/1 AHR	GL-052 8M1A
GR120P	RCS B HE PRESS	2-12/4-12	1/6	0	3500	PSIA	1.96	0	4000	2.60	1696	-	-	1240	-	3000	500	3500	1/1 AHR	GL-052 8M1A
GR120P	RCS A REG PRESS.	3-11/4-11	1/6	0	350	PSIA	1.96	0	400	2.60	170	200	-	-	-	-	-	-	1/1 AH	NOT VALID ON LM-1
GR120P	RCS B REG PRESS.	4-13/3-13	1/6	0	350	PSIA	1.96	0	400	2.60	170	200	-	178	179	188	150	213	1/1 AH	GL-032 8M1A
GR210T	RCS A FUEL TEMP	2-8	2/20	20	120	°F	2.78	20	120	3.38	-	-	-	50	90	100	40	100	1/1 AH	8M2A
GR210T	RCS B FUEL TEMP	2-8	2/20	20	120	°F	2.78	20	120	3.38	-	-	-	50	90	100	40	100	1/1 AH	8M2B
GR220P	A FUEL MFLD PRESS.	1-1/1-7/3-6/4-1	-	0	350	PSIA	1.87	0	400	2.55	-	-	-	165	-	165	140	210	200 AHR	8M1A
GR220P	B FUEL MFLD PRESS.	1-5/3-1/3-8	-	0	350	PSIA	1.87	0	400	2.55	-	-	-	165	-	165	140	210	1R/1 AH	8M1B
GR320P	A OX MFLD PRESS.	1-7/2-2/3-7	-	0	350	PSIA	1.87	0	400	2.55	-	-	-	165	-	165	140	210	200 AHR	8M1A
GR320P	B OX MFLD PRESS.	1-2/1-6/2-1/3-8	-	0	350	PSIA	1.87	0	400	2.55	-	-	-	165	-	165	140	210	1R/1 AH	8M1B
GR5031P	TCP 4G	-	-	-	-	-	-	-	-	-	CC	-	-	-	-	-	-	-	-	GL4031
GR5032P	TCP 4E	-	-	-	-	-	-	-	-	-	CC	-	-	-	-	-	-	-	-	GL4031
GR5033P	TCP 4F	-	-	-	-	-	-	-	-	-	CC	-	-	-	-	-	-	-	-	GL4031
GR5034P	TCP 4E	-	-	-	-	-	-	-	-	-	CC	-	-	-	-	-	-	-	-	GL4031
GR5035P	TCP 3U	-	-	-	-	-	-	-	-	-	CC	-	-	-	-	-	-	-	-	GL4031
GR5036P	TCP 3D	-	-	-	-	-	-	-	-	-	CC	-	-	-	-	-	-	-	-	GL4031
GR5037P	TCP 3F	-	-	-	-	-	-	-	-	-	CC	-	-	-	-	-	-	-	-	GL4031
GR5038P	TCP 3S	-	-	-	-	-	-	-	-	-	CC	-	-	-	-	-	-	-	-	GL4031
GR5039P	TCP 2U	-	-	-	-	-	-	-	-	-	CC	-	-	-	-	-	-	-	-	GL4031
GR5040P	TCP 2D	-	-	-	-	-	-	-	-	-	CC	-	-	-	-	-	-	-	-	GL4031
GR5041P	TCP 2F	-	-	-	-	-	-	-	-	-	CC	-	-	-	-	-	-	-	-	GL4031
GR5042P	TCP 2S	-	-	-	-	-	-	-	-	-	CC	-	-	-	-	-	-	-	-	GL4031
GR5043P	TCP 1U	-	-	-	-	-	-	-	-	-	CC	-	-	-	-	-	-	-	-	GL4031
GR5044P	TCP 1D	-	-	-	-	-	-	-	-	-	CC	-	-	-	-	-	-	-	-	GL4031
GR5045P	TCP 1F	-	-	-	-	-	-	-	-	-	CC	-	-	-	-	-	-	-	-	GL4031
GR5046P	TCP 1S	-	-	-	-	-	-	-	-	-	CC	-	-	-	-	-	-	-	-	GL4031
GR6001T	QUAD 4 TEMP	4-6	1/20	20	200	°F	2.17	-100	200	2.37	36.4	186.7	-	122	126	130	120	190	1/1 AH	GL4053 18M1
GR6002T	QUAD 3 TEMP	4-7	1/20	20	200	°F	2.17	-100	200	2.37	36.4	186.7	-	122	126	130	120	190	1/1 AH	GL4053 18M1
GR6003T	QUAD 2 TEMP	4-10	1/20	20	200	°F	2.17	-100	200	2.37	36.4	186.7	-	122	126	130	120	190	1/1 AH	GL4053 18M1
GR6004T	QUAD 1 TEMP	4-12	1/20	20	200	°F	2.17	-100	200	2.37	36.4	186.7	-	122	126	130	120	190	1/1 AH	GL4053 18M1
GR9609U	RCS MAIN A CLSD	-	1/12	1 = CLSD	-	-	-	-	-	-	8FL5	-	-	-	-	-	-	-	-	1/1 DPER
GR9610U	RCS MAIN B CLSD	-	1/12	1 = CLSD	-	-	-	-	-	-	8FL7	-	-	-	-	-	-	-	-	1/1 DPER
GR9611U	ASC FEED A CPM	-	1/13	1 = OPEN	-	-	-	-	-	-	8FL6	-	-	-	-	-	-	-	-	1/1 DPER
GR9612U	ASC FEED B CPM	-	1/13	1 = OPEN	-	-	-	-	-	-	8FL8	-	-	-	-	-	-	-	-	1/1 DPER
GR9613U	A/B X-FEED CPM	-	1/13	1 = OPEN	-	-	-	-	-	-	8FL17	-	-	-	-	-	-	-	-	1/1 DPER
GR9614U	4A 150 CLSD	-	1/13 1/14	1 = CLSD	-	-	-	-	-	-	8FL14	-	-	-	-	-	-	-	-	1 DPE
GR9615U	4B 150 CLSD	-	1/13 1/14	1 = CLSD	-	-	-	-	-	-	8FL16	-	-	-	-	-	-	-	-	1 DPE
GR9616U	3A 150 CLSD	-	1/13 1/14	1 = CLSD	-	-	-	-	-	-	8FL13	-	-	-	-	-	-	-	-	1 DPE
GR9617U	3B 150 CLSD	-	1/13 1/14	1 = CLSD	-	-	-	-	-	-	8FL15	-	-	-	-	-	-	-	-	1 DPE
GR9618U	2A 150 CLSD	-	1/13 1/14	1 = CLSD	-	-	-	-	-	-	8FL10	-	-	-	-	-	-	-	-	1 DPE
GR9619U	2B 150 CLSD	-	1/13 1/14	1 = CLSD	-	-	-	-	-	-	8FL12	-	-	-	-	-	-	-	-	1 DPE
GR9620U	1A 150 CLSD	-	1/13 1/14	1 = CLSD	-	-	-	-	-	-	8FL9	-	-	-	-	-	-	-	-	1 DPE
GR9621U	1B 150 CLSD	-	1/13 1/14	1 = CLSD	-	-	-	-	-	-	8FL11	-	-	-	-	-	-	-	-	1 DPE

R-C

R-C

TABLE 6-4 SIGNAL CONDITIONING MEASUREMENT ASSIGNMENT

SCERA 1										SCERA 2																				
SCERA LOCATION AND TYPE	ELEC/COMM	ECS	GNC	PROP	MEASUREMENT FIELD TITLES	CEV	PCM	DISP		SCERA LOCATION AND TYPE	ELEC/COMM	ECS	GNC	PROP	MEASUREMENT FIELD TITLES	CEV	PCM	DISP		SCERA LOCATION AND TYPE	ELEC/COMM	ECS	GNC	PROP	MEASUREMENT FIELD TITLES	CEV	PCM	DISP		
LOC-1 GSE CHECKOUT					LOC-12 SIGNAL ISOLATING DISCRETE BUFFER 504-4					LOC-1 GSE CHECKOUT					LOC-12 SIGNAL ISOLATING DISCRETE BUFFER 504-4						LOC-1 GSE CHECKOUT					LOC-12 SIGNAL ISOLATING DISCRETE BUFFER 504-4				
					GR9609U GR9610U GR9618X GR9620X GR9609U GR9610U										GR9661U GR9662U GR9663U GR9664U GR9665U GR9666U GR9667U GR9668U GR9611U GR9612U GR9613U															
					LOC-13 SIGNAL ISOLATING DISCRETE BUFFER 504-4					LOC-2 SIGNAL ISOLATING DISCRETE BUFFER 504-3					LOC-13 SIGNAL ISOLATING DISCRETE BUFFER 504-5						LOC-2 SIGNAL ISOLATING DISCRETE BUFFER 504-3					LOC-13 SIGNAL ISOLATING DISCRETE BUFFER 504-5				
					GH1426V GH1427V GH1428V GH1429V GH1430V GH1431V GH1432V GH1433V GY0050X										GH1260X GQ4455X											GC9961U GC9962U GC9963U GC9964U GC9965U GC9966U				
					LOC-14 SIGNAL ISOLATING DISCRETE BUFFER 504-5					LOC-3 SIGNAL ISOLATING DISCRETE BUFFER 504-3					LOC-14 SIGNAL ISOLATING DISCRETE BUFFER 504-5						LOC-3 SIGNAL ISOLATING DISCRETE BUFFER 504-3					LOC-14 SIGNAL ISOLATING DISCRETE BUFFER 504-5				
					GH1603X GH1230X GH1348X										GH1283X GH1286X GH1508X GH1509X GH1204X GH1214X GH1217X GH1856X										GH1283X GH1286X GH1508X GH1509X GH1204X GH1214X GH1217X GH1856X					
					LOC-15 ATTENUATOR 502-2					LOC-4 SIGNAL ISOLATING DISCRETE BUFFER 504-4					LOC-15 ATTENUATOR 502-2						LOC-4 SIGNAL ISOLATING DISCRETE BUFFER 504-4					LOC-15 ATTENUATOR 502-2				
					GH1418V GH1420V GH1419V GH1421V GH1422V GH1423V GH1424V GH1425V										GH1488V GH1489V											GH1488V GH1489V				
					LOC-16 FREQ TO DC CONVERTER 505-1					LOC-5 SIGNAL ISOLATING DISCRETE BUFFER 504-5					LOC-16 ATTENUATOR 502-2						LOC-5 SIGNAL ISOLATING DISCRETE BUFFER 504-5					LOC-16 ATTENUATOR 502-2				
					GC0155F										GC0201V GC0202V GC0203V GC0204V											GC0201V GC0202V GC0203V GC0204V				
					LOC-17 AC TO DC CONVERTER 503-2					LOC-6 RESISTANCE TO DC CONVERTER 506-2					LOC-17 ATTENUATOR 502-2						LOC-6 RESISTANCE TO DC CONVERTER 506-2					LOC-17 ATTENUATOR 502-2				
					GC0071V										GC0205V										GC0205V					
					LOC-18 SIGNAL ISOLATING ANALOG BUFFER 504-1					LOC-7 AC TO DC CONVERTER 503-2					LOC-18 ATTENUATOR 502-2						LOC-7 AC TO DC CONVERTER 503-2					LOC-18 ATTENUATOR 502-2				
					GR1101P GR1102P GR1201P GR1202P										GH1240V										GH1240V					
					LOC-19 SIGNAL ISOLATING ANALOG BUFFER 504-1					LOC-8 DC AMPLIFIER 501-1					LOC-19 ATTENUATOR 502-2						LOC-8 DC AMPLIFIER 501-1					LOC-19 ATTENUATOR 502-2				
					GF4582Q GF4583Q										GH1406V GH1407V GH1455V GH1494V										GH1406V GH1407V GH1455V GH1494V					
					ASC 1 H <sub>2</sub> O QTY ASC 2 H <sub>2</sub> O QTY APS HE REG PRESS APS HE 1 PRESS																									
					LOC-20 RESISTANCE TO DC CONVERTER 506-2					LOC-9 PHASE SENSITIVE DEMODULATOR 507-1					LOC-20 RESISTANCE TO DC CONVERTER 506-2						LOC-9 PHASE SENSITIVE DEMODULATOR 507-1					LOC-20 RESISTANCE TO DC CONVERTER 506-2				
					GQ3718T GQ3719T GP0718T GP1218T										GR1089T GR2121T GR2122T GR1099T										GR1089T GR2121T GR2122T GR1099T					
					LOC-21 RESISTANCE TO DC CONVERTER 506-2					LOC-10 PHASE SENSITIVE DEMODULATOR 507-1					LOC-21 RESISTANCE TO DC CONVERTER 506-2						LOC-10 PHASE SENSITIVE DEMODULATOR 507-1					LOC-21 RESISTANCE TO DC CONVERTER 506-2				
					GF9998U										GH1461V GH1462V GH1463V										GH1461V GH1462V GH1463V					
					GLY TEMP DPS OX 1 TEMP DPS OX 2 TEMP																									
					LOC-22 CAPPED					LOC-11 CAPPED					LOC-22 CAPPED						LOC-11 CAPPED					LOC-22 CAPPED				
					OPEN OPEN OPEN OPEN																									

TABLE 6-5 TELEMETRY VERSUS PAM GATES

PAM 1						PAM 2						PAM 3						PAM 4						
SEQ	CHANNEL(S)	ELEC/COMM	ECS	GNC	PROP	SEQ	CHANNEL(S)	ELEC/COMM	ECS	GNC	PROP	SEQ	CHANNEL(S)	ELEC/COMM	ECS	GNC	PROP	SEQ	CHANNEL(S)	ELEC/COMM	ECS	GNC	PROP	
1	200AH1 (200AH4) 100AH1 (100AH9) 100AH8 100AH15 50AH1	--	--	GG2107 GG2107 GG2021	GR2201	1	200AH2 (200AH5) 100AH2 100AH9 (100AH1) 100AH16 (100AH3) 50AH2 (50AH5)	--	--	GG2151 GG2107 GG2137 GG2001	GR3202	1	200AH3 100AH3 (100AH16) 100AH10 (100AH18) 100AH17 50AH3 (50AH6)	--	--	GG2137 GG2137 GG2041	GR2202	1	200AH4 (200AH1) 100AH4 (100AH12) 100AH11 100AH18 (100AH10) 50AH4	--	--	--	--	GR2201 -- -- -- GQ6806
2	200AH5 (200AH2) 100AH5 100AH12 (100AH6) 100AH19 (100AH13) 50AH5 (50AH2)	--	--	GG2167 GG2167 GG2001	GR3202	2	200AH6 100AH6 100AH13 (100AH19) 100AH20 50AH6 (50AH3)	--	--	GQ2121 GG2167 GG2181 GG2041	GR3201	2	200AH7 100AH7 100AH14 100AH21 50AH7	--	--	GG2170 GG2140 GG2110	--	2	100AH22 50AH8	--	--	--	--	-- GQ6806
3	10AH1 10AH8 10AH18 10AH28 10AH37 (10AH13)	--	--	GH1240 -- GG2173 --	--	3	10AH2 10AH9 (10AH40) + 10AH19 (10AH43) 10AH29 (10AH45) 10AH38 (10AH39)	GT0992	--	GG2142 GH1461 GH1462 GH1463	--	3	10AH3 10AH10 10AH20 10AH30 10AH39 (10AH15)	GT0994	--	--	GH1313	--	3	10AH6 10AH11 10AH21 10AH31 10AH40 (10AH9) -	--	--	--	-- -- GH1331 GH1314 GG2142
4	10AH12 10AH22 10AH32 10AH41 (10AH26) -	--	--	GG2143 -- -- GL0401	--	4	10AH5 10AH13 (10AH37) 10AH23 10AH33 10AH42 (10AH7)	--	--	GH1249 GG2279 GH1248	--	4	10AH6 (10AH44) 10AH14 10AH24 10AH34 (10AH38) 10AH43 (10AH19)	--	--	GG2113 GG2172 GH1463 GH1461	--	4	10AH7 (10AH42) 10AH15 (10AH39) 10AH25 10AH35 10AH44 (10AH6)	--	--	--	-- -- GH1247 GG2219	
5	1AH3 (1AH48) 1AH7 1AH11 1AH15 (1AH44) - 1AH19 (1AH29)	--	--	GG2143 GH1314 GR2202 GQ4111	GQ4218	5	1AH1 1AH5 1AH9 1AH13 (1AH27) 1AH17 (1AH46)	GT0619	--	GG1331	GP0202	5	10AH16 10AH26 (10AH41) - 10AH36 (10AH27) - 10AH45 (10AH29)	GL0401 GL0402	--	--	GG2112 GH1462	--	5	10AH17 10AH27 (10AH36) -	GL0402	--	GG2249	--
6	1AH22 1AH26 1AH30 (1AH6) 1AH34 (1AH56) 1AH38 (1AH52) -	--	--	GH1313 -- GQ3435 GQ4219 GR3202	--	6	1AH20 (1AH54) 1AH24 (1AH50) 1AH28 (1AH12) 1AH32 1AH36	--	--	GF4582 GF4583	--	6	1AH2 (1AH49) 1AH6 (1AH30) 1AH10 1AH14 (1AH45) * 1AH18	--	--	GG1040 GF9997	GQ3435 GR2201	6	1AH4 (1AH47) 1AH8 1AH12 (1AH28) 1AH16 (1AH43)	--	--	--	-- -- -- -- R-C	
7	1AH41 1AH45 (1AH14) * 1AH49 (1AH2) 1AH53 (1AH21) - 1AH57	GC0202	--	GG1040	GR2201 GR3201	7	1AH39 1AH43 (1AH16) - 1AH47 (1AH4) 1AH51 (1AH23) - 1AH55 (1AH31)	--	--	GG1110	GQ3718	7	1AH21 (1AH55) - 1AH25 1AH29 (1AH19) 1AH33 1AH37	--	--	GR3201 -- GQ4111 -- GP0025	--	7	1AH23 (1AH51) 1AH27 (1AH13) 1AH31 (1AH55) 1AH35	--	--	GG1110	GP0202 GR6002	
8	1AH60 1AH64 1AH68 (1AH102) 1AH72 1AH76 (1AH86)	--	--	GC1205 GC0201	GG2173 GQ6510	8	1AH58 (1AH88) 1AH62 (1AH92) 1AH66 1AH70 1AH74	--	--	--	GP1501 GR2121 GR2122	8	1AH40 1AH44 (1AH15) * 1AH48 (1AH3) 1AH52 (1AH38) 1AH56 (1AH34)	--	--	GR2202 GR2121 GR3202 GQ4219	--	8	1AH2 (1AH105) 1AH6 (1AH17) 1AH50 (1AH24) 1AH54 (1AH20)	--	--	GF4583 GF4582	GP1503 GQ3604	
9	1AH79 1AH83 (1AH98) 1AH87 (1AH75) 1AH91 (1AH106) 1AH95 (1AH63)	GC0203	--	GC1206 GC1201 GC1203	GF3571	9	1AH77 (1AH104) - 1AH81 (1AH96) * 1AH85 1AH89 (1AH65) 1AH93 (1AH100)	--	--	--	GP0002	9	1AH59 (1AH99) 1AH63 (1AH95) 1AH67 (1AH94) 1AH71 1AH75 (1AH87)	GC1203 GC1204	GF2021	--	--	9	1AH61 (1AH105) 1AH65 (1AH89) 1AH69 (1AH101) - 1AH73 (1AH97)	--	--	--	GP1503 GQ3604	
10	1AH99 (1AH59) 1AH103 (1AH90) 1AH107 1AH111 1AH115	--	--	GR2021	GQ3611	10	1AH97 (1AH73) 1AH101 (1AH69) - 1AH105 (1AH61) 1AH109 1AH113	--	--	--	GP3604 GP1503	10	1AH78 1AH82 1AH86 (1AH76) 1AH90 (1AH103) 1AH94 (1AH67)	GC0071 GC1204	--	--	GQ6510 GQ3611	10	1AH80 1AH84 1AH88 (1AH58) 1AH92 (1AH62)	--	--	--	GR6003 GR6004 GP1501	
11	1AH119 (1AH146) - 1AH123 (1AH166) 1AH127 1AH131 (1AH142) 1AH135 (1AH170)	GC0302	--	GG2300	GR1095	11	1AH117 (1AH148) 1AH121 1AH125 (1AH160) 1AH129 (1AH144) 1AH133 (1AH176) -	--	--	GG1201	GQ3719	11	1AH98 (1AH83) 1AH102 (1AH68) 1AH106 (1AH91) 1AH110 1AH114	GC1205 GC1201	GF3571	GR1201	11	1AH96 (1AH81) - 1AH100 (1AH93) 1AH104 (1AH77) - 1AH108 1AH112	--	--	--	GP0002 GQ3603 GR1201		
12	1AH139 1AH143 (1AH134) 1AH147 (1AH130) 1AH151 (1AH162) 1AH155	--	--	GH1247	GR1089	12	1AH137 1AH141 (1AH168) 1AH145 (1AH124) 1AH149 (1AH164) - 1AH153 (1AH179)	--	--	GF4101	GR1102	12	1AH118 1AH122 (1AH167) 1AH126 1AH130 (1AH147) 1AH134 (1AH145)	GC1202 GC0301	GG2301	--	--	12	1AH116 (1AH165) - 1AH120 (1AH169) 1AH124 (1AH145) 1AH128 1AH132	--	--	GH1311	GQ4103 GP0718 GR1102	
13	1AH159 1AH163 (1AH154) 1AH167 (1AH122) 1AH171 1AH175	GT0202	--	GC1202	GR1099	13	1AH157 1AH161 (1AH152) 1AH165 (1AH116) - 1AH169 (1AH120) 1AH173 (1AH178)	--	--	GF3583	GQ4103 GP0718 GP2010	13	1AH138 1AH142 (1AH131) 1AH146 (1AH119) - 1AH150 1AH154 (1AH165)	--	--	GR1202 GR1095 GR1099	--	13	1AH136 1AH140 1AH144 (1AH129) 1AH148 (1AH117) 1AH152 (1AH161)	--	--	--	GR1202 GF1218 GQ3719	
14	1AH179 (1AH153) 1AH183 1AH187 1AH191 1AH195	GT0201	GF3582	GT0993	GP0001	14	1AH177 (1AH172) 1AH181 1AH185 1AH189 1AH193	GT0992	--	--	--	14	1AH158 1AH162 (1AH151) - 1AH166 (1AH123) 1AH170 (1AH135) 1AH174	GC0155	GG2300	GP0201	14	1AH156 1AH160 (1AH125) 1AH164 (1AH149) - 1AH168 (1AH141) 1AH172 (1AH177)	--	--	GF4101	GR1101		
15						15	1AH178 (1AH173) 1AH182 1AH186 1AH190 1AH194	--	--	--	GP2010 F511	15	1AH178 (1AH173) 1AH182 1AH186 1AH190 1AH194	--	--	GH1331 GF3591	--	15	1AH176 (1AH133) - 1AH180 1AH184 1AH188 1AH192	--	--	GF4511	GQ4104 R-C	

\*LBR ( ) REDUNDANT CHANNEL  
\*\*REDUNDANT HBR ONLY  
\*\*\*TRANSDUCER MALFUNCTIONED

\*

LM-1  
REV C

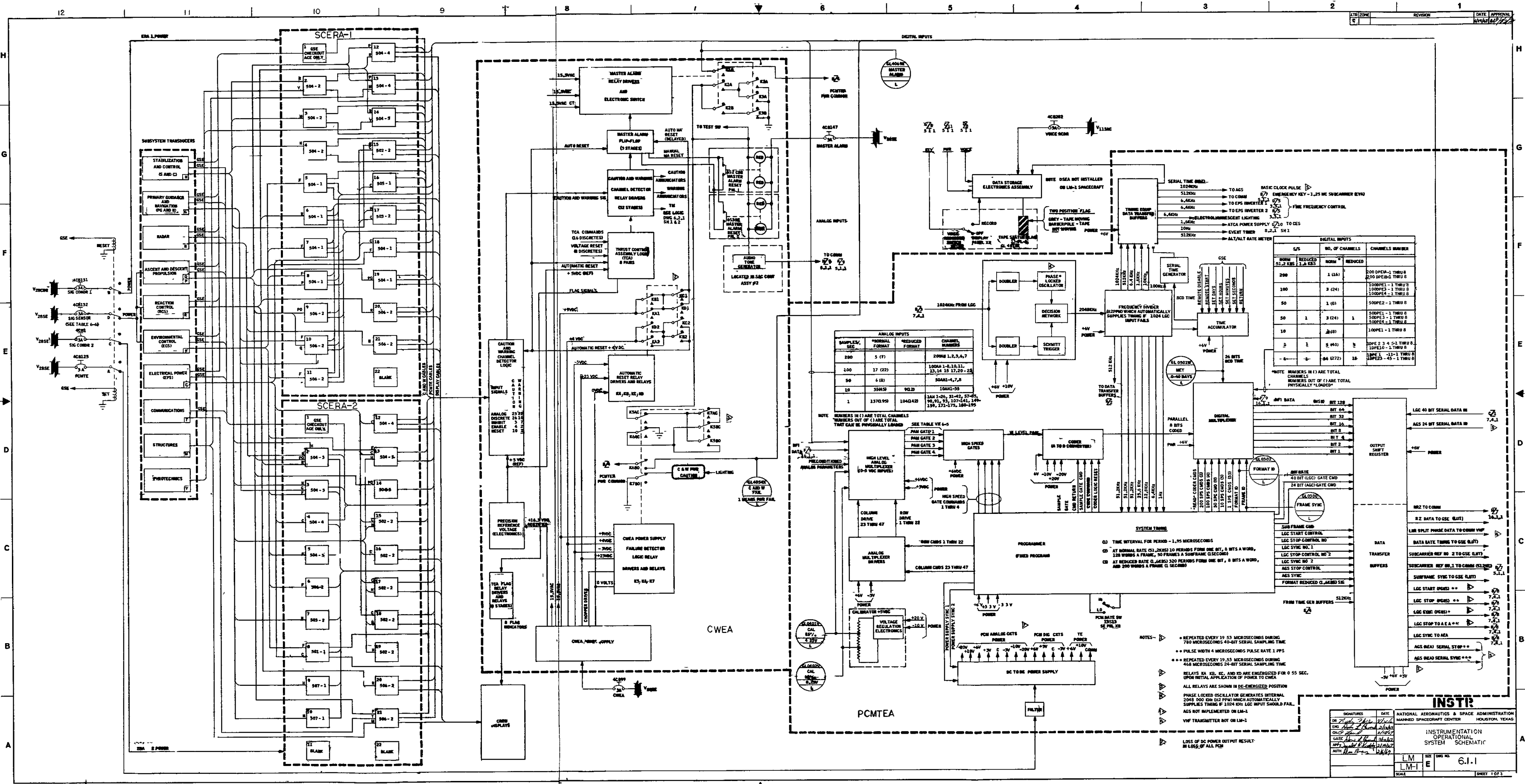
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TABLE 6-7 PCMTEA SINGLE POINT FAILURES

FAILURE OF:	DATA LOST:
ANALOG MULTIPLEXER SEQUENCER	UP TO 20 ANALOG CHANNELS
ANALOG MULTIPLEXER ROW DRIVER	UP TO 20 ANALOG CHANNELS (4 SEQUENCE GATES)
ANALOG MULTIPLEXER COLUMN DRIVER	UP TO 14 ANALOG CHANNELS
HIGH-SPEED PAM GATE	UP TO 75 ANALOG CHANNELS
PROGRAMER	
a. ROW CMDS	a. UP TO 20 ANALOG CHANNELS
b. COLUMN CMDS	b. UP TO 14 ANALOG CHANNELS
c. HIGH-SPEED GATE CMDS	c. UP TO 75 ANALOG CHANNELS
CODER	ALL ANALOG DATA
CALIBRATOR	LOSS OF ACCURACY CHECKS ON CODER
DIGITAL MULTIPLEXER	a. LOSS OF ALL ANALOG DATA, OR b. LOSS OF ALL DATA IN SAME BIT POSITION, OR c. LOSS OF ALL DATA
OUTPUT REGISTER	a. LOSS OF ALL SERIAL DIGITAL DATA (AGS OR PGNS), OR b. LOSS OF ALL DATA
FAILURE OF:	DATA LOST:
DATA TRANSFER BUFFERS	LOSS OF ALL DATA
POWER SUPPLY	LOSS OF ALL DATA AND TIMING OUTPUTS

TABLE 6-8 PRELAUNCH STATUS OF SWITCH AND CIRCUIT BREAKER POSITIONS

NAME	NUMBER	POSITION
SWITCHES		
MASTER ALARM; CDR	6S2	EXTINGUISHED
MASTER ALARM, SE	6S3	EXTINGUISHED
PCM	13S13	HI
TAPE RECORDER	13S11	OFF
CKT BREAKERS		
TAPE RECORDER	4CB202	OPEN
SIG CONDR 1	4CB131	CLOSED
MASTER ALARM	4CB147	OPEN
PCMTEA	4CB125	CLOSED
C&WEA	4CB99	CLOSED
SIG SENSOR	4CB132	CLOSED
SIG CONDR	4CB1	CLOSED



SAMPLES/SEC	NORMAL FORMAT	REDUCED FORMAT	CHANNEL NUMBERS
200	5 (7)	200M 1, 2, 3, 4, 7	
100	17 (22)	100M 1-6, 10, 11, 13, 14, 15, 17, 20-25	
50	6 (8)	50M 1-4, 7, 8	
10	35 (45)	10M 1-35	
1	137 (155)	104 (42)	1A 1-26, 31-42, 37-45, 40, 41, 43, 107-141, 144-154, 157-175, 180-197

MODE	NO. OF CHANNELS	CHANNELS NUMBER
200	1 (16)	500 DP 1-1 THRU 8
100	3 (24)	500 DP 1-1 THRU 8 100 DP 1-1 THRU 8 100 DP 4-1 THRU 8
50	1 (8)	500 P 2-1 THRU 8
50	1 (24)	500 P 1-1 THRU 8 500 P 3-1 THRU 8 500 P 4-1 THRU 8
10	8 (8)	100 P 1-1 THRU 8
2	1 (40)	100 P 2 3 4 5 6 THRU 8 100 P 3 1 THRU 8
-	8 (472)	100 P 1-1 THRU 8 100 P 3-45-1 THRU 8

**SYSTEM TIMING**

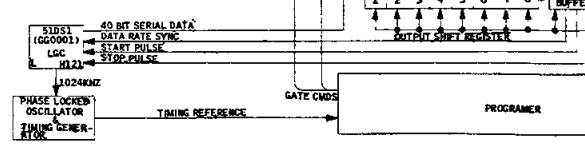
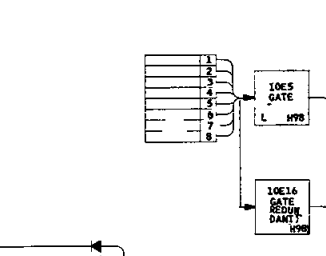
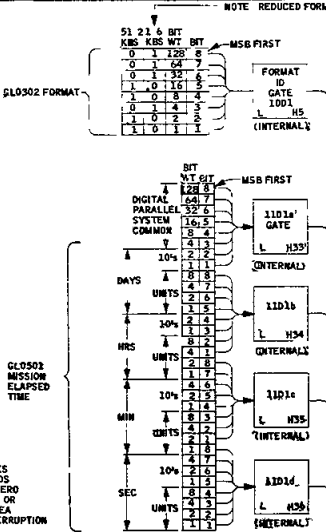
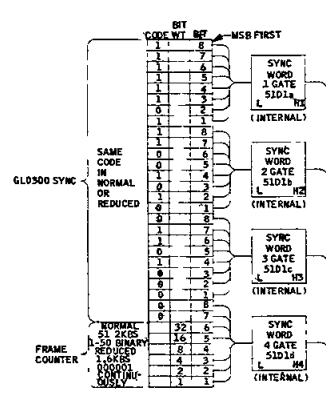
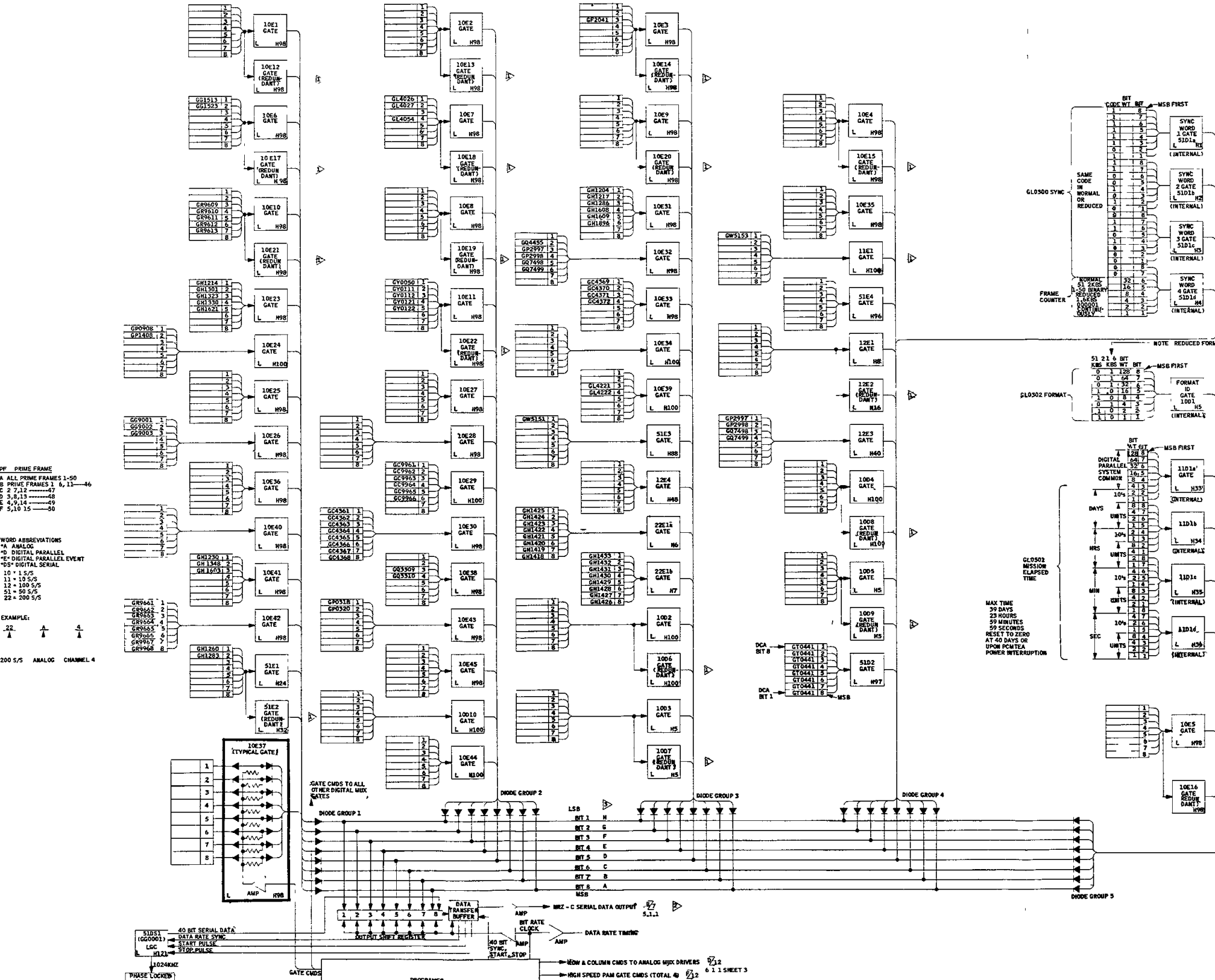
- (1) TIME INTERVAL FOR PERIOD - 1.95 MICROSECONDS
- (2) AT NORMAL RATE (50 SAMPLES PER WORD), 5 BITS A WORD, 128 WORDS A FRAME, 50 FRAMES A SUBFRAME (1.5 SECS)
- (3) AT REDUCED RATE (10 SAMPLES PER WORD), 8 BITS A WORD, 100 WORDS A FRAME (1.5 SECS)

- NOTES:**
- REPEATED EVERY 19.53 MICROSECONDS DURING 780 MICROSECONDS 40-BIT SERIAL SAMPLING TIME
  - PULSE WIDTH 4 MICROSECONDS PULSE RATE 1 PPS
  - REPEATED EVERY 19.53 MICROSECONDS DURING 468 MICROSECONDS 24-BIT SERIAL SAMPLING TIME
  - RELAYS RA, RB, RC, AND RD ARE ENERGIZED FOR 0.55 SEC. UPON INITIAL APPLICATION OF POWER TO CWEA
  - ALL RELAYS ARE SHOWN IN DE-ENERGIZED POSITION
  - PHASE LOCKED OSCILLATOR GENERATES INTERNAL 2048 000 KHZ (12.2 PPM) WHICH AUTOMATICALLY SUPPLIES TIMING IF 100K OHM LOG INPUT SHOULD FAIL
  - ACS NOT IMPLEMENTED ON LM-1
  - VHF TRANSMITTER NOT ON LM-1
  - LOSS OF DC POWER OUTPUT RESULT IN LOSS OF ALL PCM

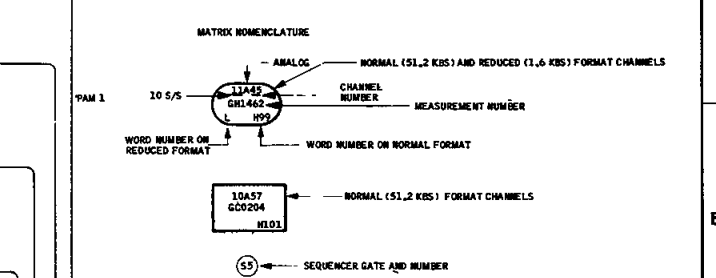
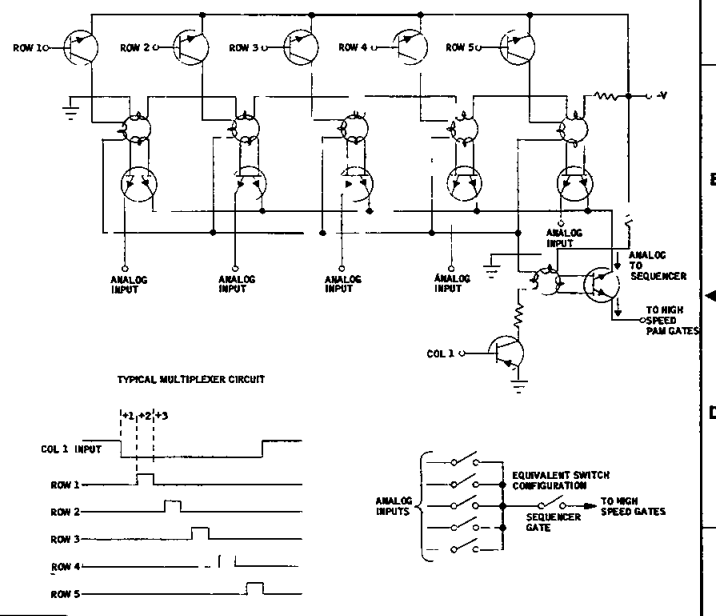
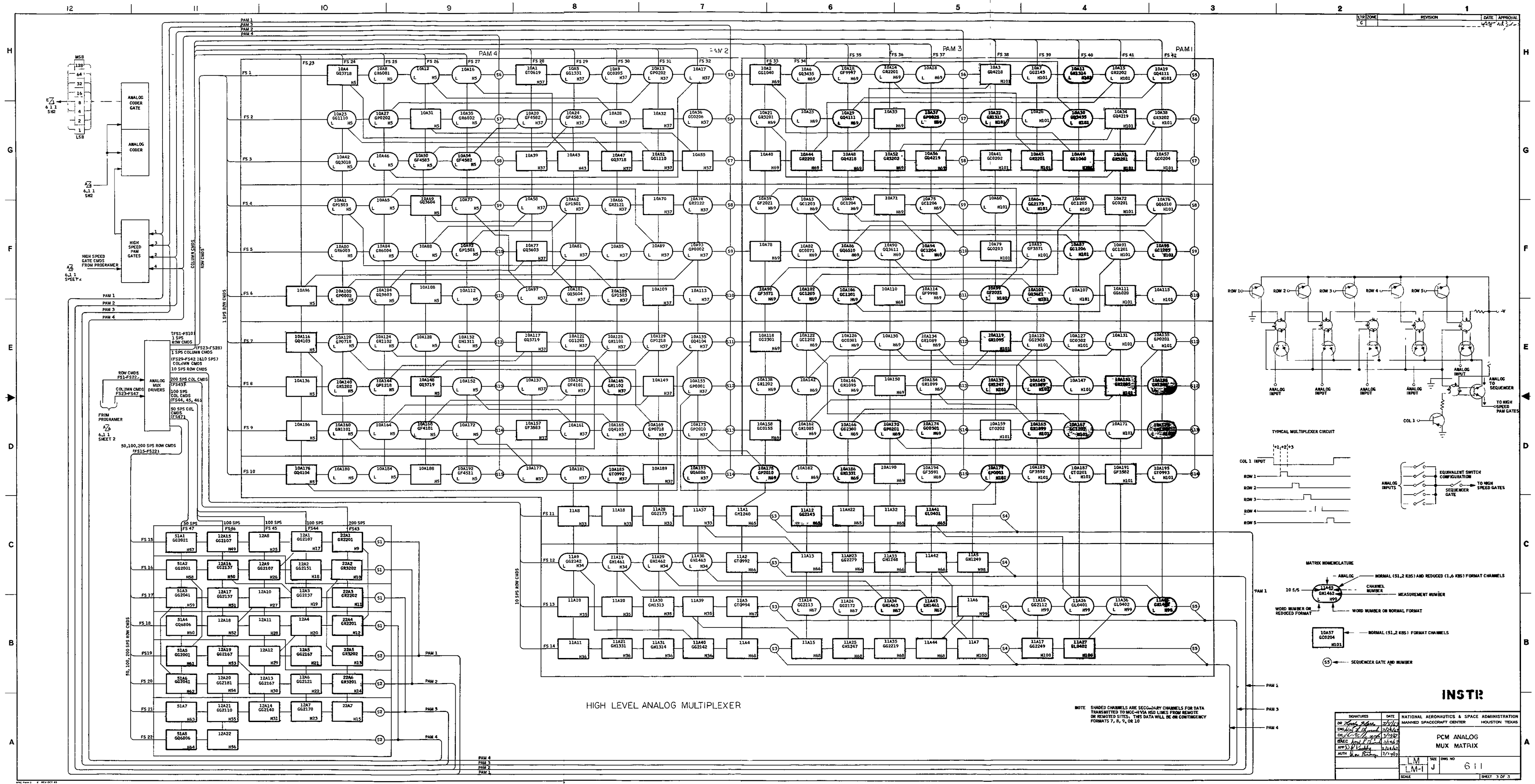


Table with columns: FRAME, WD 5, WD 37, WD 69, WD 98, WD 100, WD 101. Rows 1-50. HBR FORMAT

Table with columns: SYNC, 11A, 11B, 11C, 11D, 11E, 11F, 11G, 11H, 11I, 11J, 11K, 11L, 11M, 11N, 11O, 11P, 11Q, 11R, 11S, 11T, 11U, 11V, 11W, 11X, 11Y, 11Z. Rows 1-50. WORD ABBREVIATIONS



Signature table with columns: SIGNATURES, DATE, NATIONAL AERONAUTICS & SPACE ADMINISTRATION, MANNED SPACECRAFT CENTER, HOUSTON TEXAS. Includes project title: LM-1 DIGITAL MULTIPLEXING FOR DISCRETE TELEMETRY.

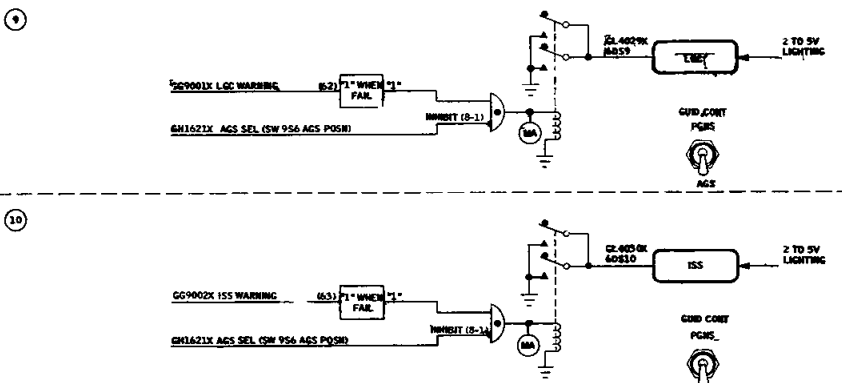
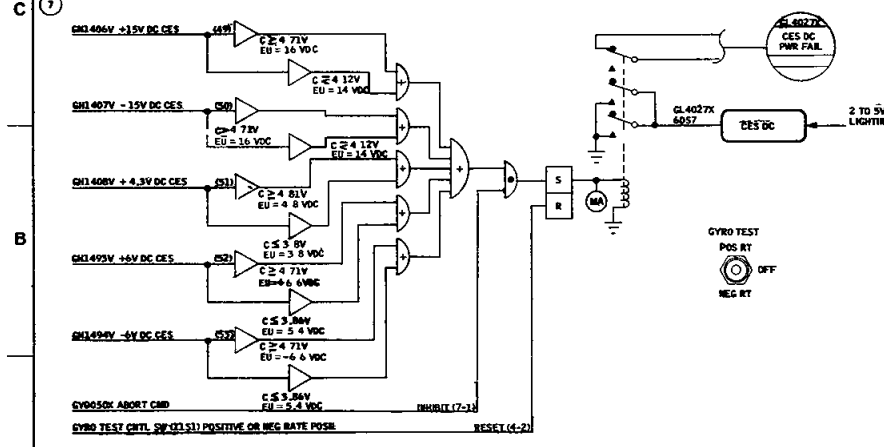
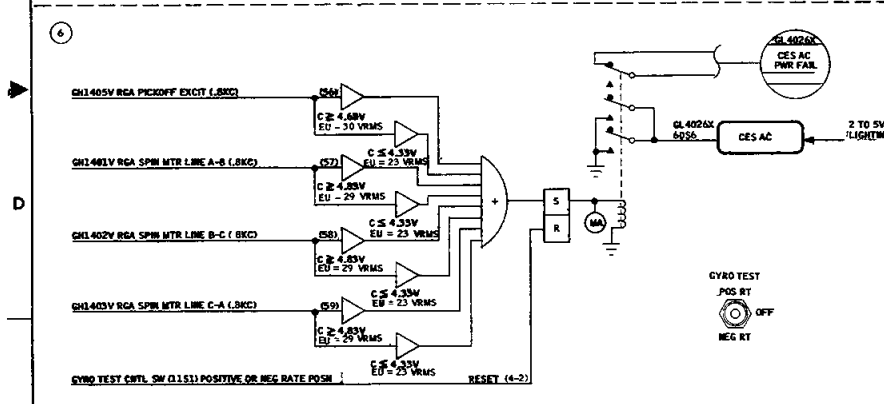
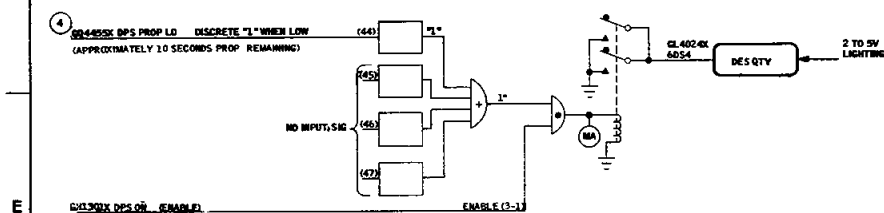
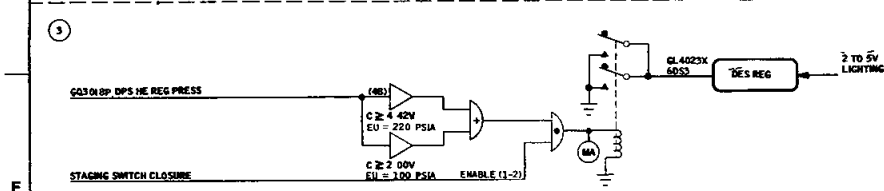
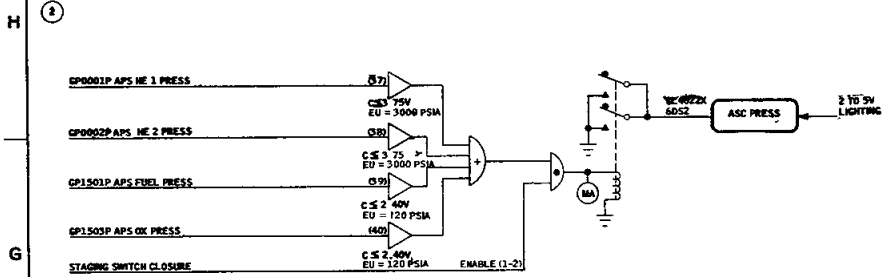
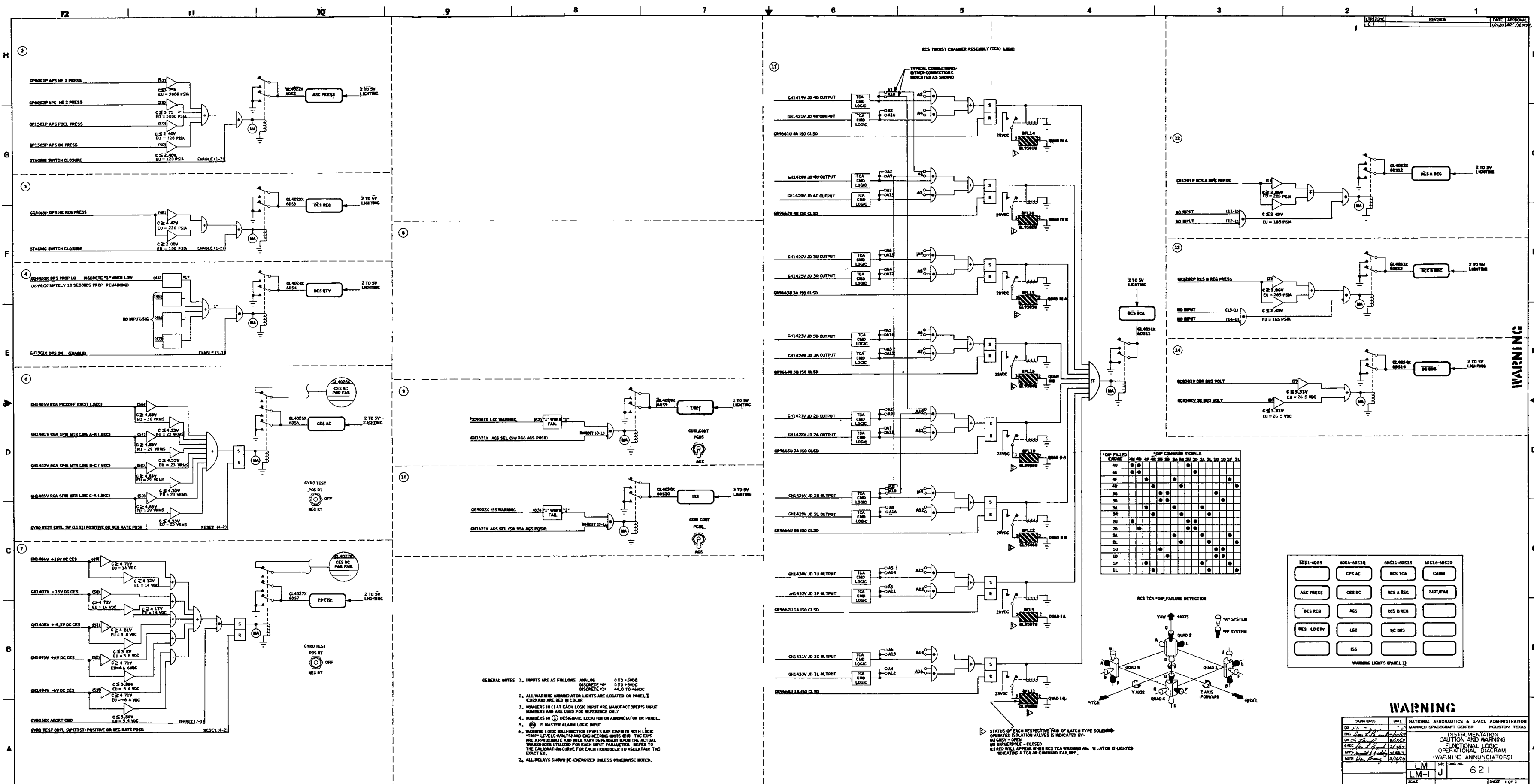


DATE	12/1/68	DATE	12/1/68
BY	J. B. ...	DATE	12/1/68
CHKD	J. B. ...	DATE	12/1/68
APP'D	J. B. ...	DATE	12/1/68
AUTH	J. B. ...	DATE	12/1/68

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HOUSTON, TEXAS

PCM ANALOG  
MUX MATRIX

SCALE: LM-1 J 611  
SHEET 3 OF 3



GENERAL NOTES 1. INPUTS ARE AS FOLLOWS: ANALOG 0 TO +5VDC, DISCRETE "0" 0 TO +5VDC, DISCRETE "1" +4.0 TO +4VDC.

2. ALL WARNING ANNUNCIATOR OR LIGHTS ARE LOCATED ON PANEL 1 (CROSS AND ARE RED IN COLOR).

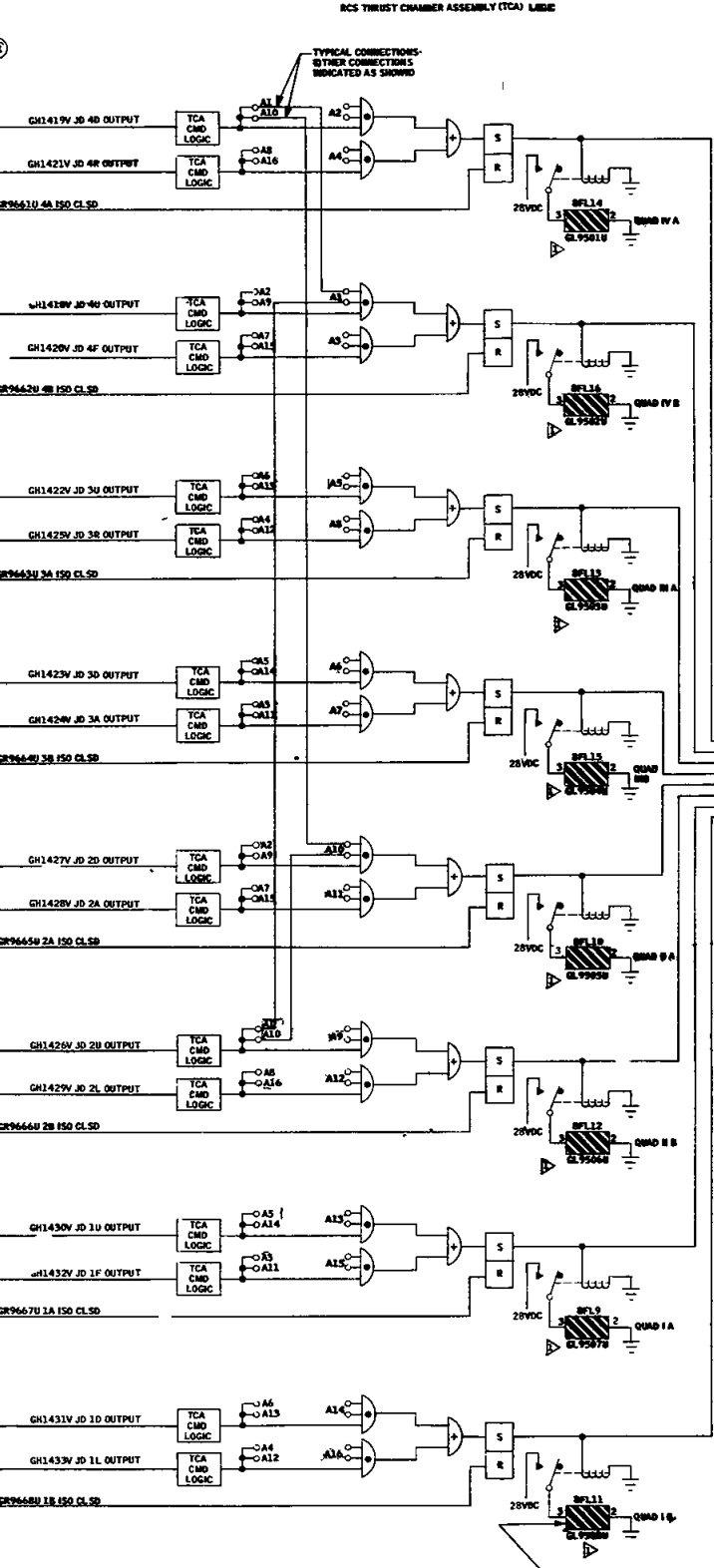
3. NUMBERS IN ( ) AT EACH LOGIC INPUT ARE MANUFACTURER'S INPUT NUMBERS AND ARE USED FOR REFERENCE ONLY.

4. NUMBERS IN ( ) DESIGNATE LOCATION ON ANNUNCIATOR OR PANEL.

5. (A) IS MASTER ALARM LOGIC INPUT.

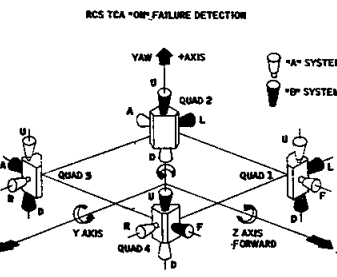
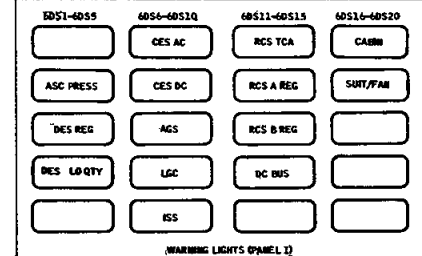
6. WARNING LOGIC MALFUNCTION LEVELS ARE GIVEN IN BOTH LOGIC "TRIP" LEVELS (VOLTS) AND ENGINEERING UNITS (EU). THE EU'S ARE APPROXIMATE AND WILL VARY DEPENDANT UPON THE ACTUAL TRANSDUCER UTILIZED FOR EACH INPUT PARAMETER. REFER TO THE CALIBRATION CURVE FOR EACH TRANSDUCER TO ASCERTAIN THE EXACT EU.

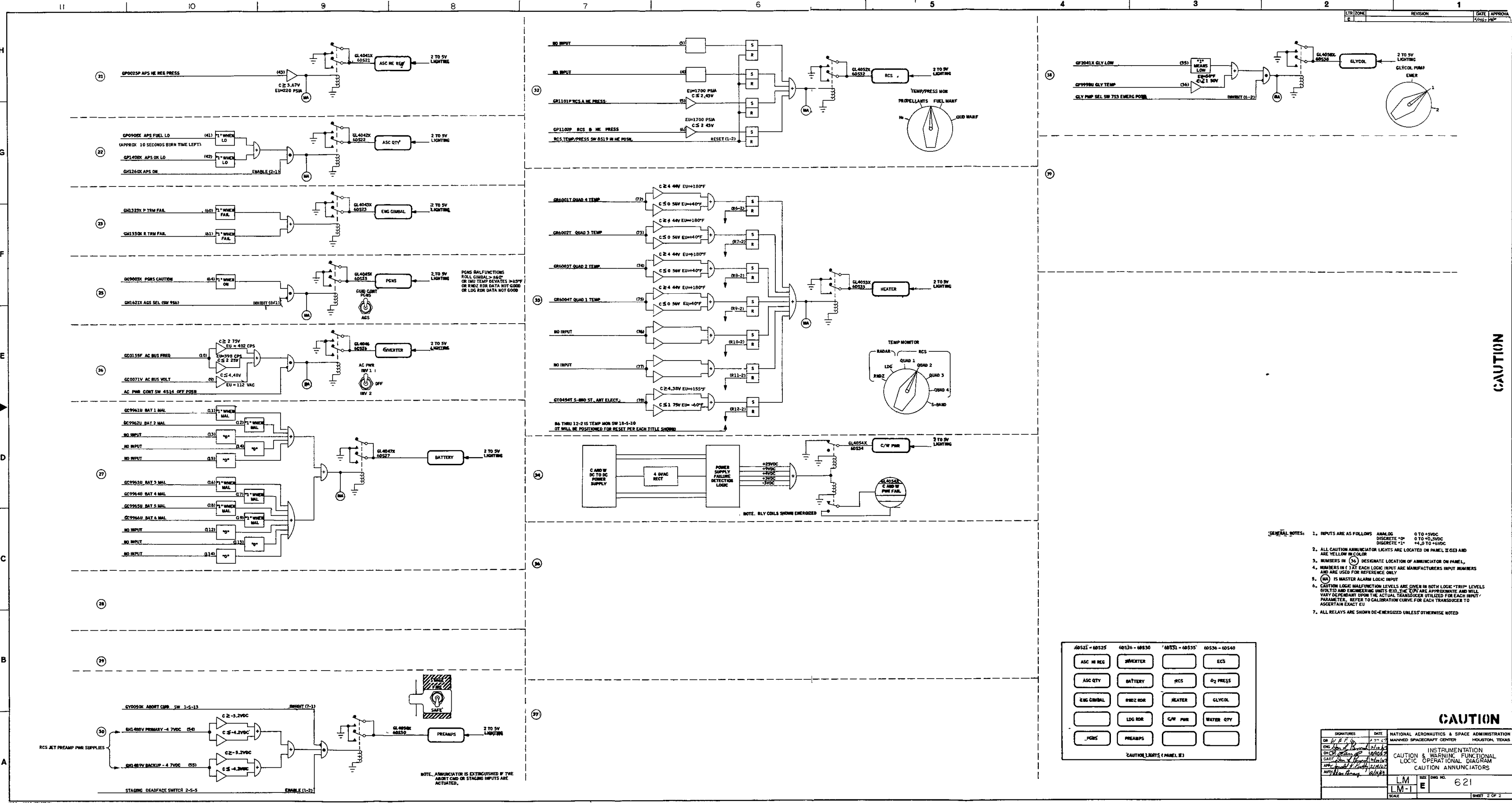
7. ALL RELAYS SHOWN DE-ENERGIZED UNLESS OTHERWISE NOTED.



WARNING LIGHTS PANEL 1

4U	4D	4F	4R	3D	3R	3U	3L	2D	2A	2U	2L	1U	1D	1F	1L
●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●





- GENERAL NOTES:
1. INPUTS ARE AS FOLLOWS: ANALOG 0 TO +5VDC, DISCRETE +0V 0 TO +0.5VDC, DISCRETE +1V +4.5 TO +6VDC
  2. ALL CAUTION ANNUNCIATOR LIGHTS ARE LOCATED ON PANEL 12533 AND ARE YELLOW IN COLOR
  3. NUMBERS IN (S) DESIGNATE LOCATION OF ANNUNCIATOR ON PANEL
  4. NUMBERS IN (T) EACH LOGIC INPUT ARE MANUFACTURER'S INPUT NUMBERS AND ARE USED FOR REFERENCE ONLY
  5. (MA) IS MASTER ALARM LOGIC INPUT
  6. CAUTION LOGIC MALFUNCTION LEVELS ARE GIVEN IN BOTH LOGIC TRIP LEVELS (VOLTS) AND ENGINEERING INPUTS (EUI). THE EUI ARE APPROXIMATE AND WILL VARY DEPENDANT UPON THE ACTUAL TRANSDUCER UTILIZED FOR EACH INPUT. PARAMETERS. REFER TO CALIBRATION CURVE FOR EACH TRANSDUCER TO ASCERTAIN EXACT EUI
  7. ALL RELAYS ARE SHOWN DE-ENERGIZED UNLESS OTHERWISE NOTED

60521 - 60525	60530 - 60535	60531 - 60535	60536 - 60540
ASC IN RES	INVERTER		ECS
ASC QTY	BATTERY	RCS	O <sub>2</sub> PRESS
ENG CRIBAL	RNDZ HOR	HEATER	GLYCOL
	LOG RDR	C/W PWR	WATER QTY
	PREAMPS		

CAUTION LIGHTS (PANEL 12)

4

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LTR	ZONE	REVISION	DATE	APPROVAL
C			6/22/67	1838

D

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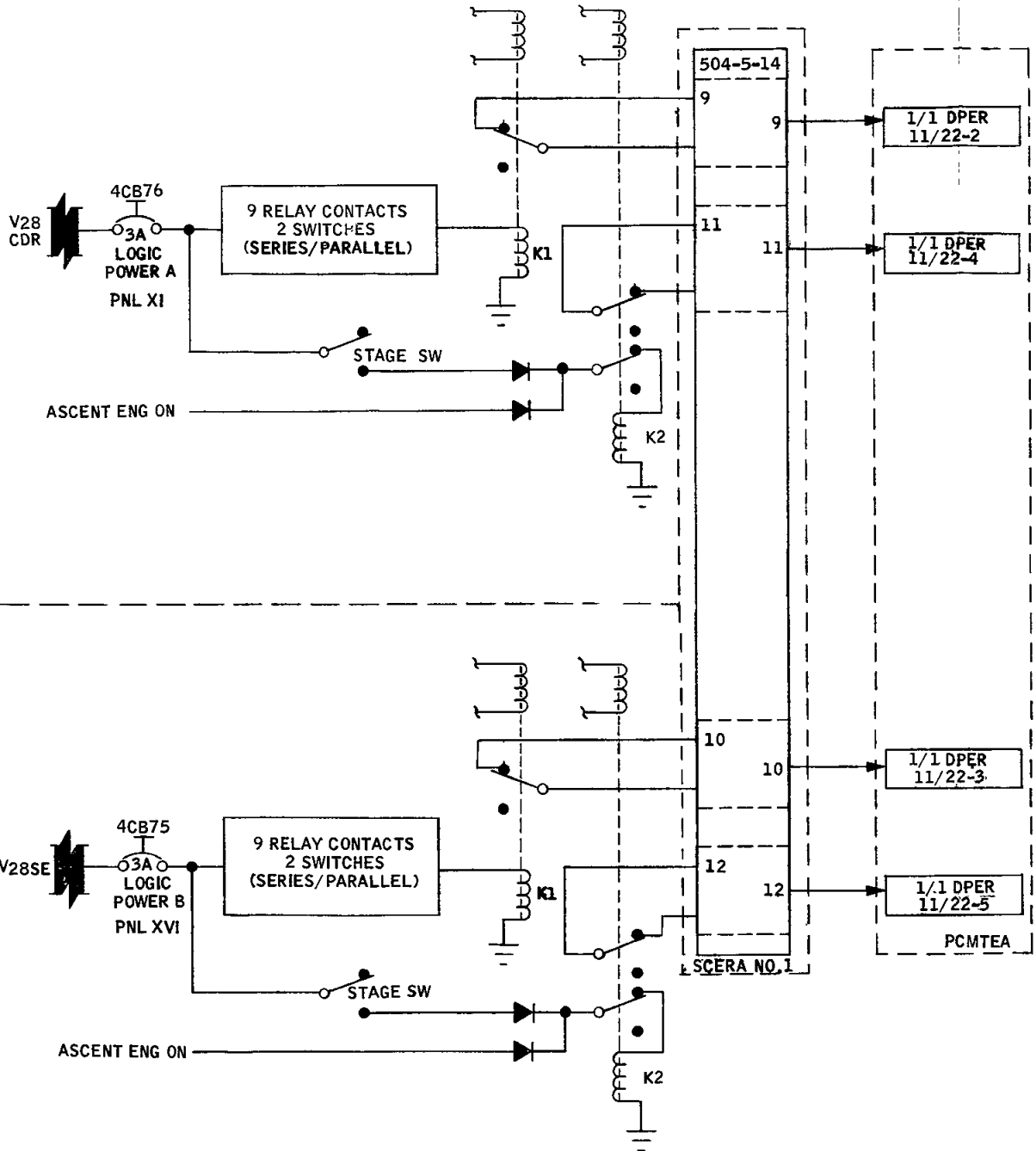
A

GY0111  
ED ARM A ON

GY0121  
STG RLY A FIRE

GY0112  
ED ARM B ON

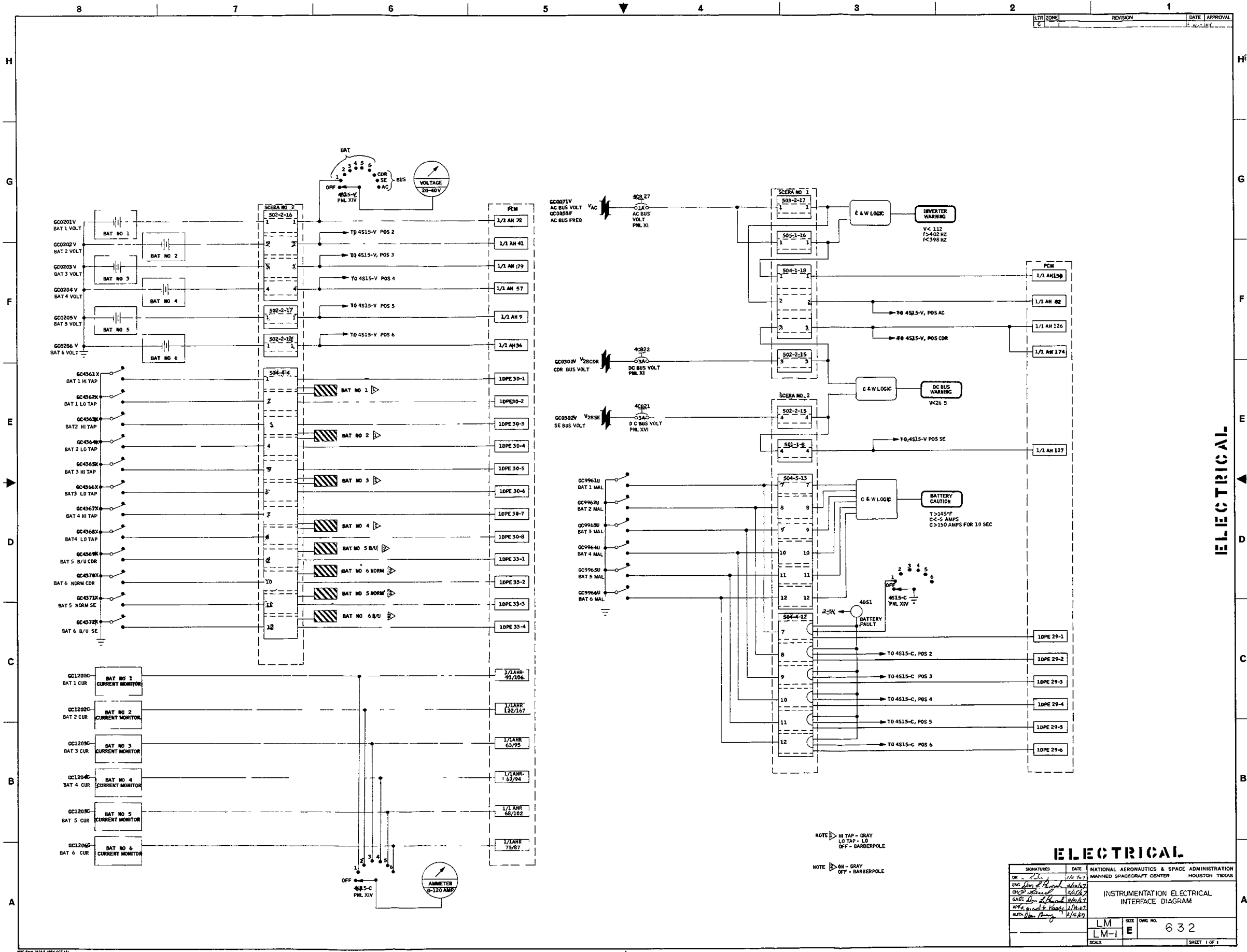
GY0122  
STG RLY B FIRE



PYRO

PYRO

SIGNATURES		DATE	NATIONAL AERONAUTICS & SPACE ADMINISTRATION MANNED SPACECRAFT CENTER • HOUSTON, TEXAS	
DR	<i>Donald Boyd</i>	2/23/67	INSTRUMENTATION PYROTECHNIC INTERFACE DIAGRAM	
ENG	<i>Don L. Parry</i>	2/19/67		
CH	<i>P. Haniel</i>	2/15/67		
GAEC	<i>Don L. Parry</i>	2/22/67		
APP	<i>Donald P. Parry</i>	2/14/67		
AUTH	<i>Don Bray</i>	2/16/67	LM LM-1	
SCALE		SIZE	DWG NO	
		C	6.3.1	
			SHEET	1 OF 1



LTR ZONE	REVISION	DATE	APPROVAL
C			

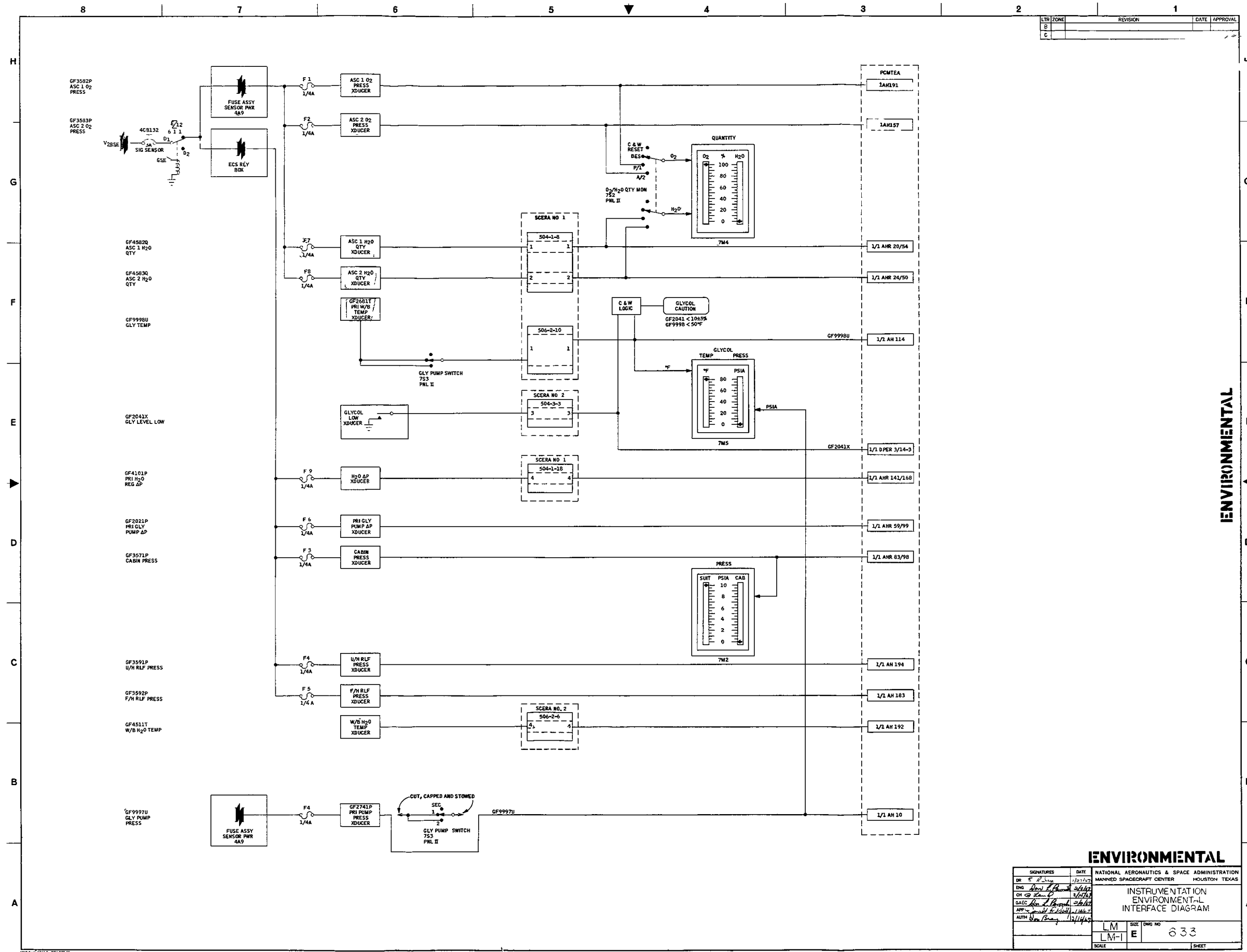
ELECTRICAL

NOTE: HI TAP - GRAY  
LO TAP - LO  
OFF - BARBERPOLE

NOTE: ON - GRAY  
OFF - BARBERPOLE

**ELECTRICAL**

SIGNATURES DR: [Signature] ENG: [Signature] GAC: [Signature] APPR: [Signature] AUTH: [Signature]	DATE 1/16/87	NATIONAL AERONAUTICS & SPACE ADMINISTRATION MANNED SPACECRAFT CENTER HOUSTON, TEXAS
INSTRUMENTATION ELECTRICAL INTERFACE DIAGRAM		
LM	SIZE	DWG NO.
LM-1	E	632
SCALE		SHEET 1 OF 1



LTR	ZONE	REVISION	DATE	APPROVAL
B				
C				

ENVIRONMENTAL

**ENVIRONMENTAL**

SIGNATURES		DATE	NATIONAL AERONAUTICS & SPACE ADMINISTRATION MANNED SPACECRAFT CENTER HOUSTON TEXAS	
DR	<i>[Signature]</i>	12/1/73		
ENG	<i>[Signature]</i>	1/16/74		
QA	<i>[Signature]</i>	1/16/74		
SAEC	<i>[Signature]</i>	1/16/74		
APP	<i>[Signature]</i>	1/16/74		
AUTH	<i>[Signature]</i>	1/16/74		
LM		SIZE	DWG NO	
LM-1		E	633	
SCALE		SHEET		

GLY PUMP 753 PNL II REV OCT 63

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LTR	ZONE	REVISION	DATE	APPROVAL
C			6/30/67	DFP

D

C

B

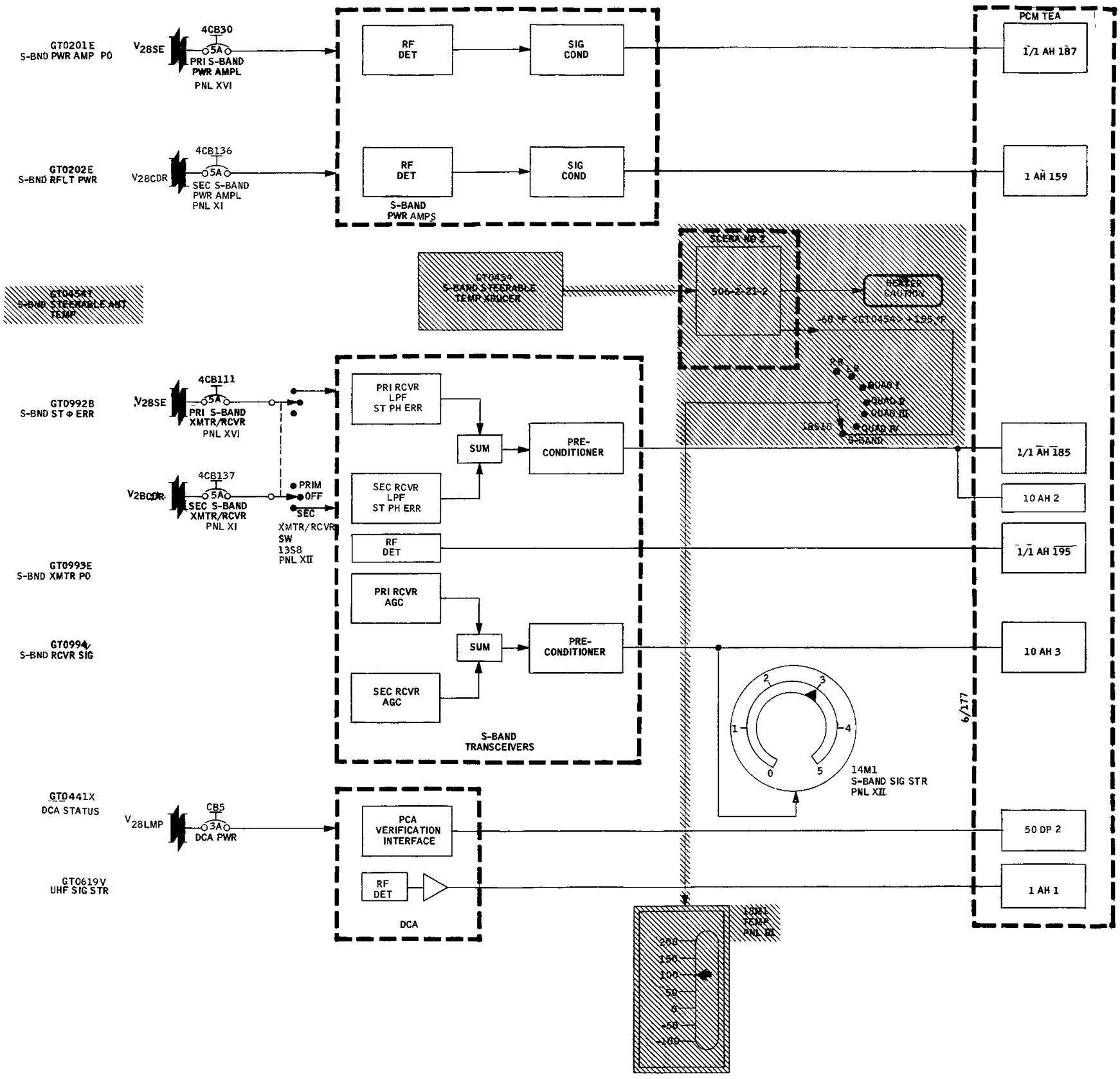
A

D

C

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A

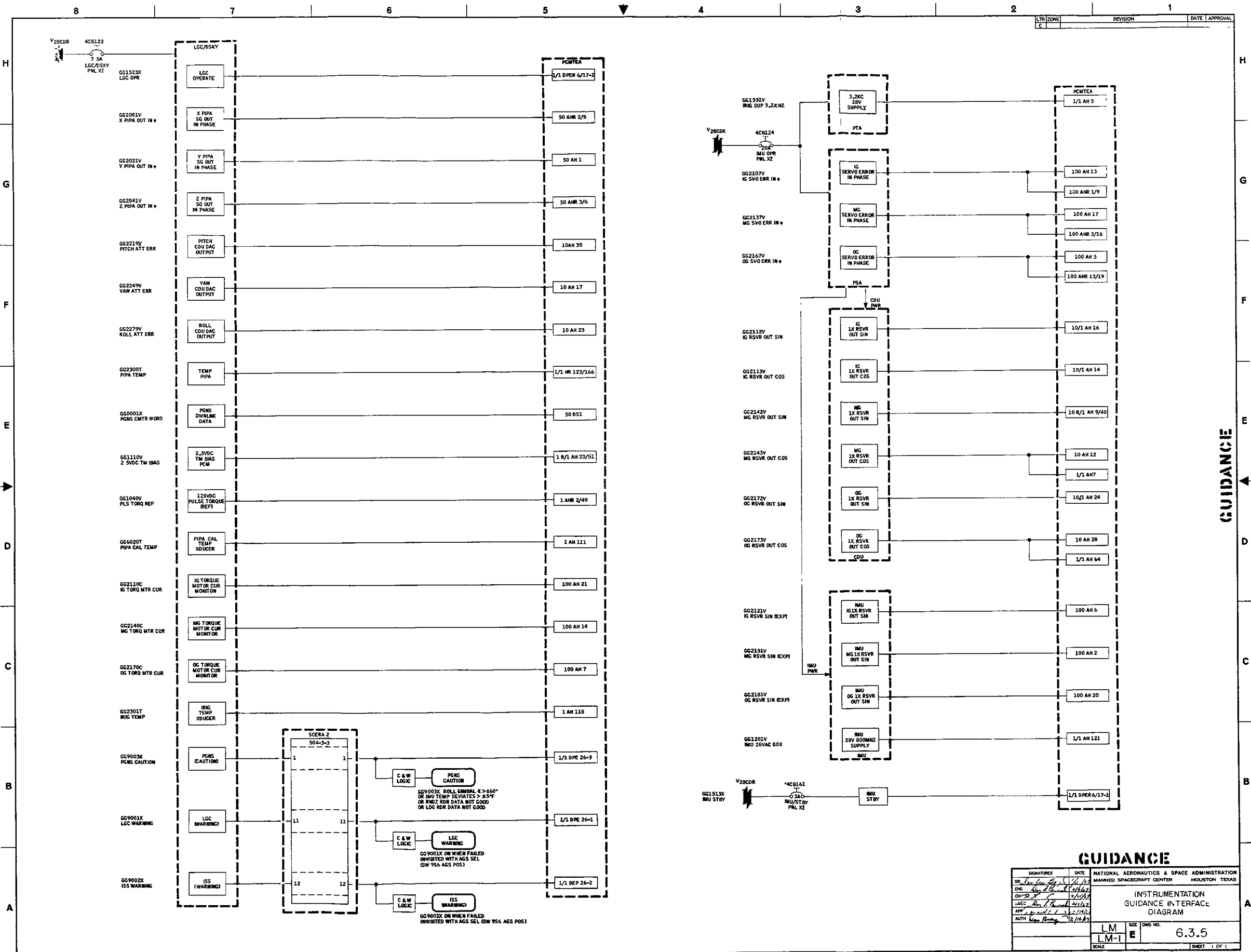


COMM

COMM

SIGNATURES		DATE	NATIONAL AERONAUTICS & SPACE ADMINISTRATION MANNED SPACECRAFT CENTER - HOUSTON TEXAS	
DR	<i>[Signature]</i>	1 1 67	INSTRUMENTATION COMMUNICATIONS INTERFACE DIAGRAM	
ENG	<i>[Signature]</i>	2/10/67		
CH	<i>[Signature]</i>	2/15/67		
GAEC	<i>[Signature]</i>	2/10/67		
APR	<i>[Signature]</i>	2/18/67		
AUTH	<i>[Signature]</i>	2/14/67	LM LM-1	
SCALE		SIZE	DWG NO	6.34
				SHEET 1 OF 1



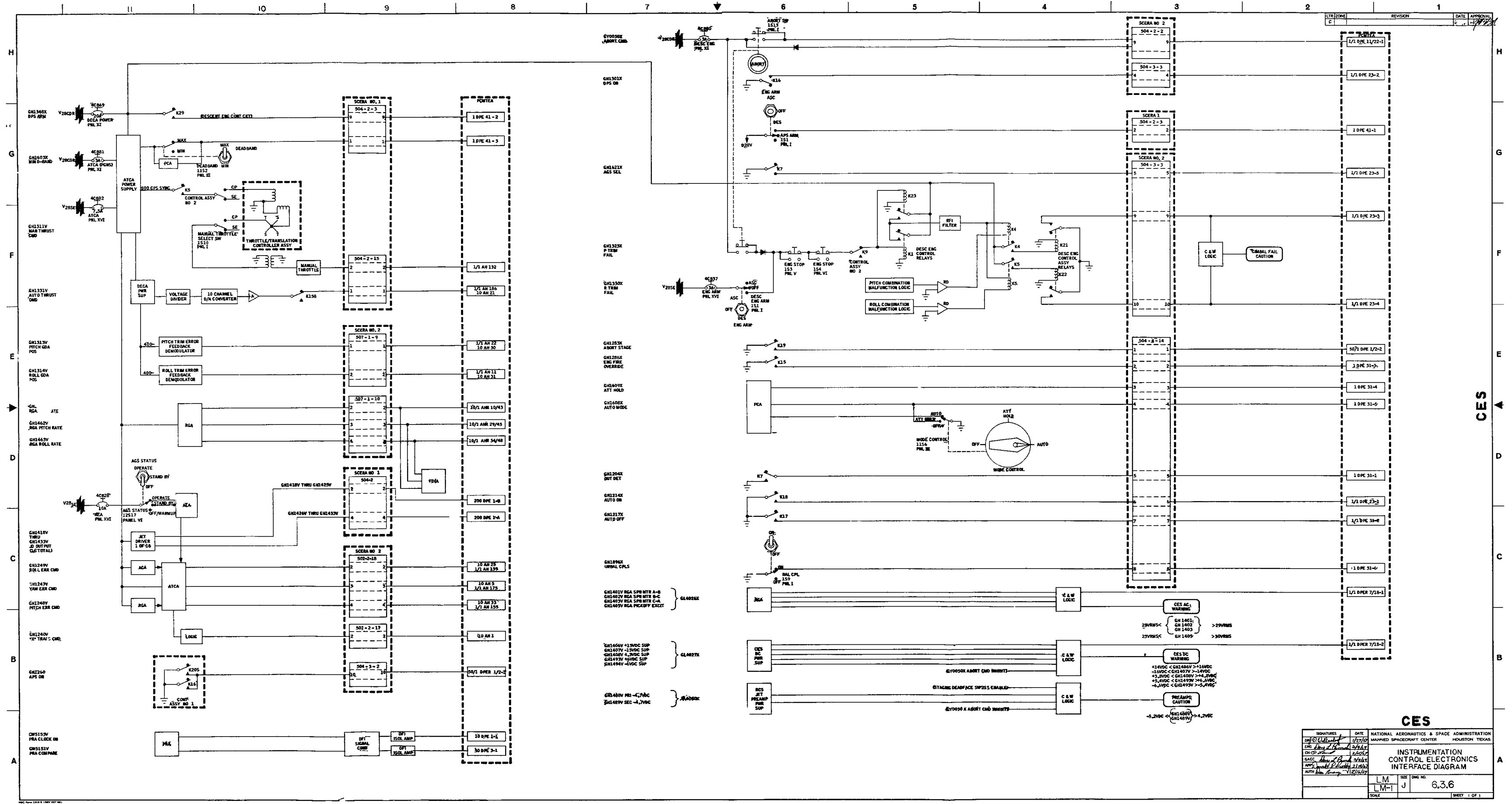


SIGNATURES		DATE	NATIONAL AERONAUTICS & SPACE ADMINISTRATION	
OR			MANNED SPACECRAFT CENTER HOUSTON TEXAS	
DR	<i>[Signature]</i>	1/1/77		
ENC	<i>[Signature]</i>	2/1/77		
CHK	<i>[Signature]</i>	2/1/77		
APP	<i>[Signature]</i>	2/1/77		
AUTH	<i>[Signature]</i>	2/1/77		
			LM	SIZE: 6.3.5
			LM-1	E
			SCALE	SHEET 1 OF 1

GUIDANCE

**GUIDANCE**

INSTRUMENTATION  
GUIDANCE INTERFACE  
DIAGRAM



DATE	REVISION	APPROVAL
1/10/72	1	[Signature]
1/10/72	2	[Signature]
1/10/72	3	[Signature]
1/10/72	4	[Signature]
1/10/72	5	[Signature]
1/10/72	6	[Signature]
1/10/72	7	[Signature]
1/10/72	8	[Signature]
1/10/72	9	[Signature]
1/10/72	10	[Signature]
1/10/72	11	[Signature]

DESCRIPTION	QUANTITY	REVISION
1 DPE 41-2	1	
1 DPE 41-3	1	
1 DPE 41-4	1	
1 DPE 41-5	1	
1/2 AH 132	1	
1/2 AH 136	1	
1/2 AH 22	1	
1/2 AH 11	1	
1/2 AH 10/43	1	
10/1 AH 29/43	1	
10/1 AH 34/48	1	
200 DPE 1-8	2	
200 DPE 3-4	2	
10 AH 25	1	
10 AH 35	1	
10 AH 33	1	
1/2 AH 155	1	
10 AH 1	1	
50/2 DPE 1/2-2	1	
10 DPE 1-1	1	
30 DPE 3-1	1	
50/2 DPE 1/2-2	1	
1 DPE 23-2	1	
1 DPE 43-1	1	
1/2 DPE 23-5	1	
1/2 DPE 23-3	1	
1/2 DPE 23-4	1	
1/2 DPE 23-6	1	
1 DPE 31-1	1	
1/2 DPE 31-2	1	
1/2 DPE 31-3	1	
1 DPE 31-4	1	
1 DPE 31-5	1	
1 DPE 31-6	1	
1/2 DPE 7/19-1	1	
1/2 DPE 7/19-2	1	

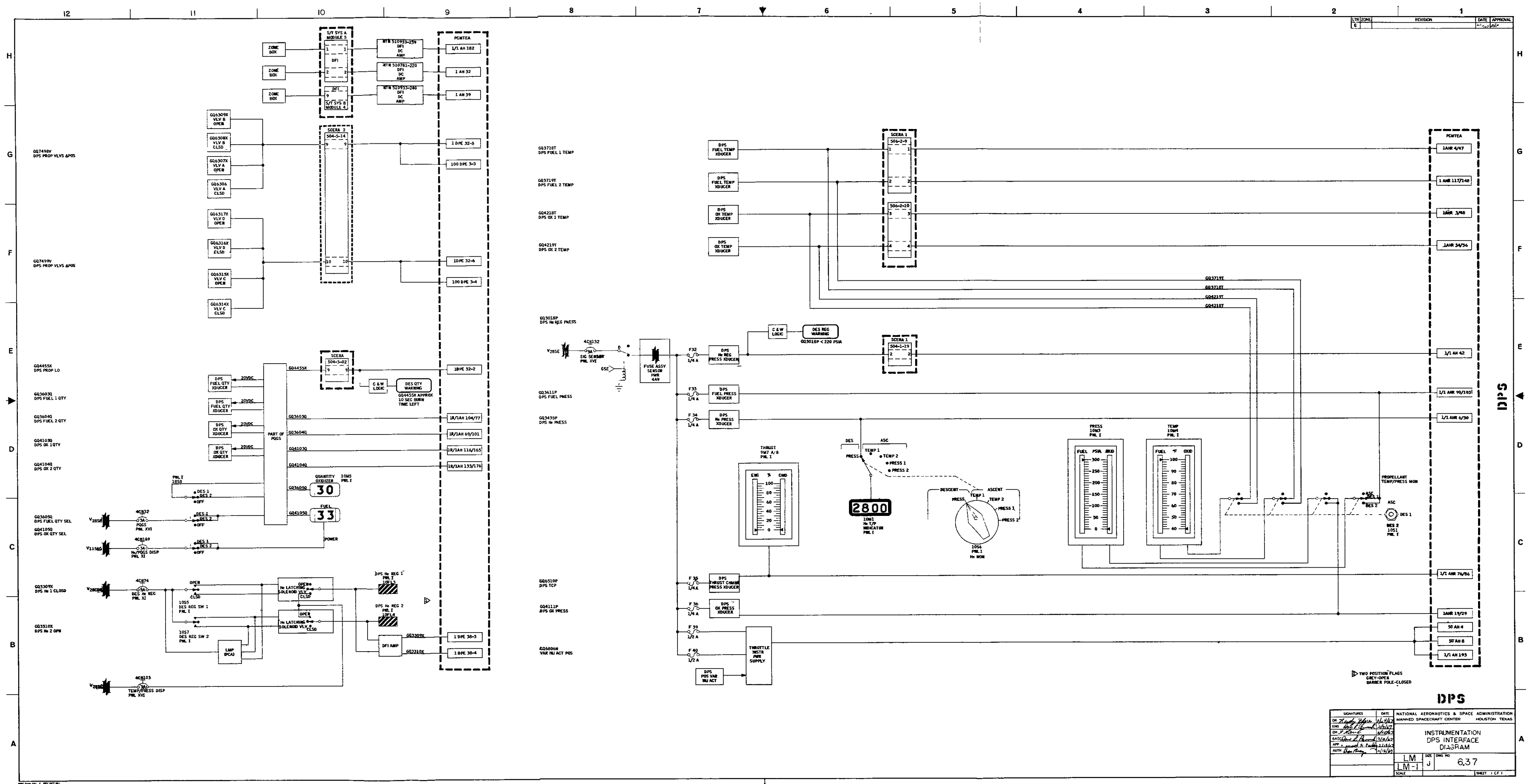
DESCRIPTION	QUANTITY
CES AC1 WARNING	1
CES AC2 WARNING	1
CES AC3 WARNING	1
CES AC4 WARNING	1
CES AC5 WARNING	1
CES AC6 WARNING	1
CES AC7 WARNING	1
CES AC8 WARNING	1
CES AC9 WARNING	1
CES AC10 WARNING	1
CES AC11 WARNING	1
CES AC12 WARNING	1
CES AC13 WARNING	1
CES AC14 WARNING	1
CES AC15 WARNING	1
CES AC16 WARNING	1
CES AC17 WARNING	1
CES AC18 WARNING	1
CES AC19 WARNING	1
CES AC20 WARNING	1
CES AC21 WARNING	1
CES AC22 WARNING	1
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CES AC24 WARNING	1
CES AC25 WARNING	1
CES AC26 WARNING	1
CES AC27 WARNING	1
CES AC28 WARNING	1
CES AC29 WARNING	1
CES AC30 WARNING	1
CES AC31 WARNING	1
CES AC32 WARNING	1
CES AC33 WARNING	1
CES AC34 WARNING	1
CES AC35 WARNING	1
CES AC36 WARNING	1
CES AC37 WARNING	1
CES AC38 WARNING	1
CES AC39 WARNING	1
CES AC40 WARNING	1
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CES AC43 WARNING	1
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CES AC45 WARNING	1
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CES AC47 WARNING	1
CES AC48 WARNING	1
CES AC49 WARNING	1
CES AC50 WARNING	1

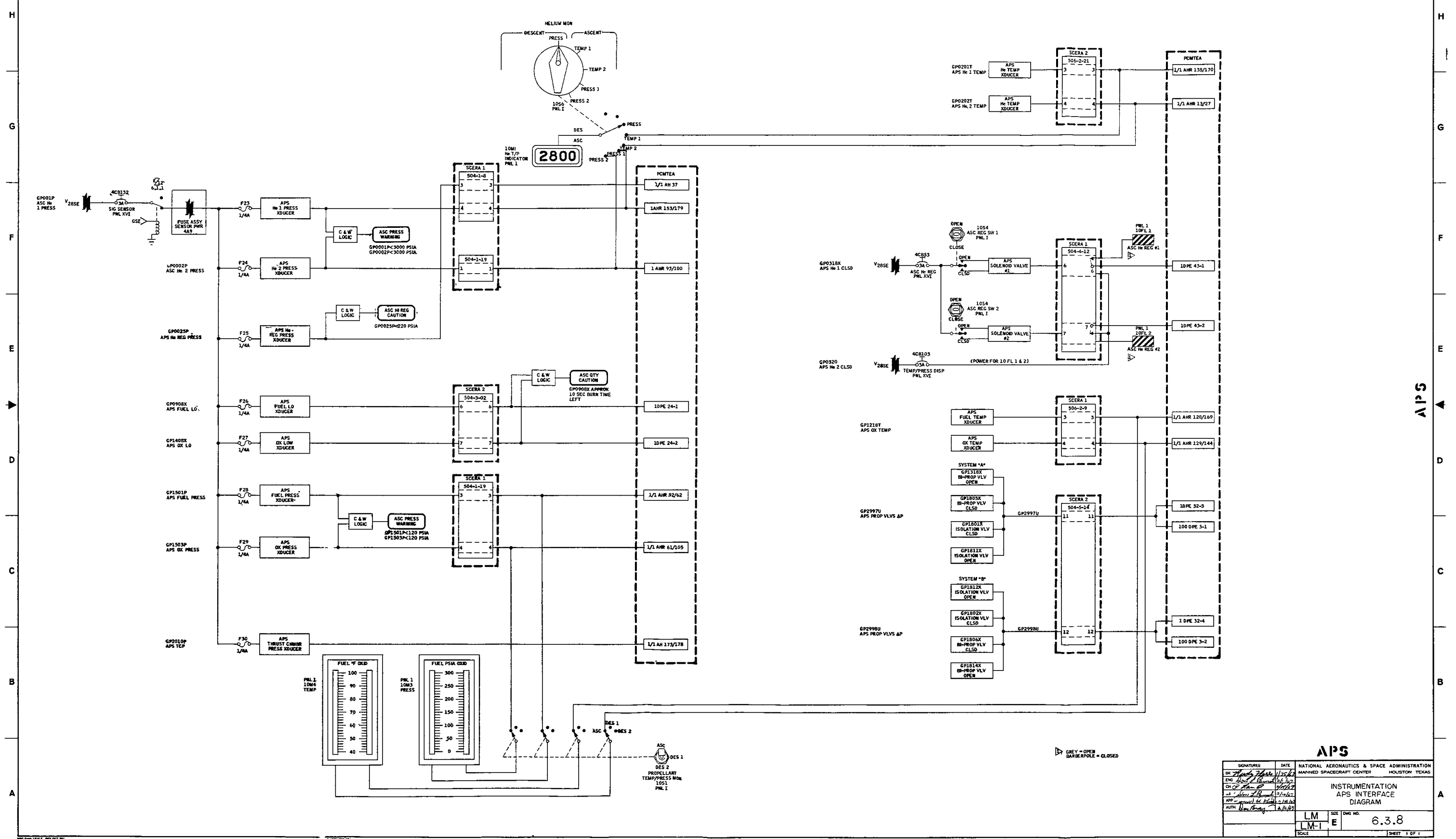
**CES**

NATIONAL AERONAUTICS & SPACE ADMINISTRATION  
 MARSH SPACECRAFT CENTER HOUSTON TEXAS

**INSTRUMENTATION CONTROL ELECTRONICS INTERFACE DIAGRAM**

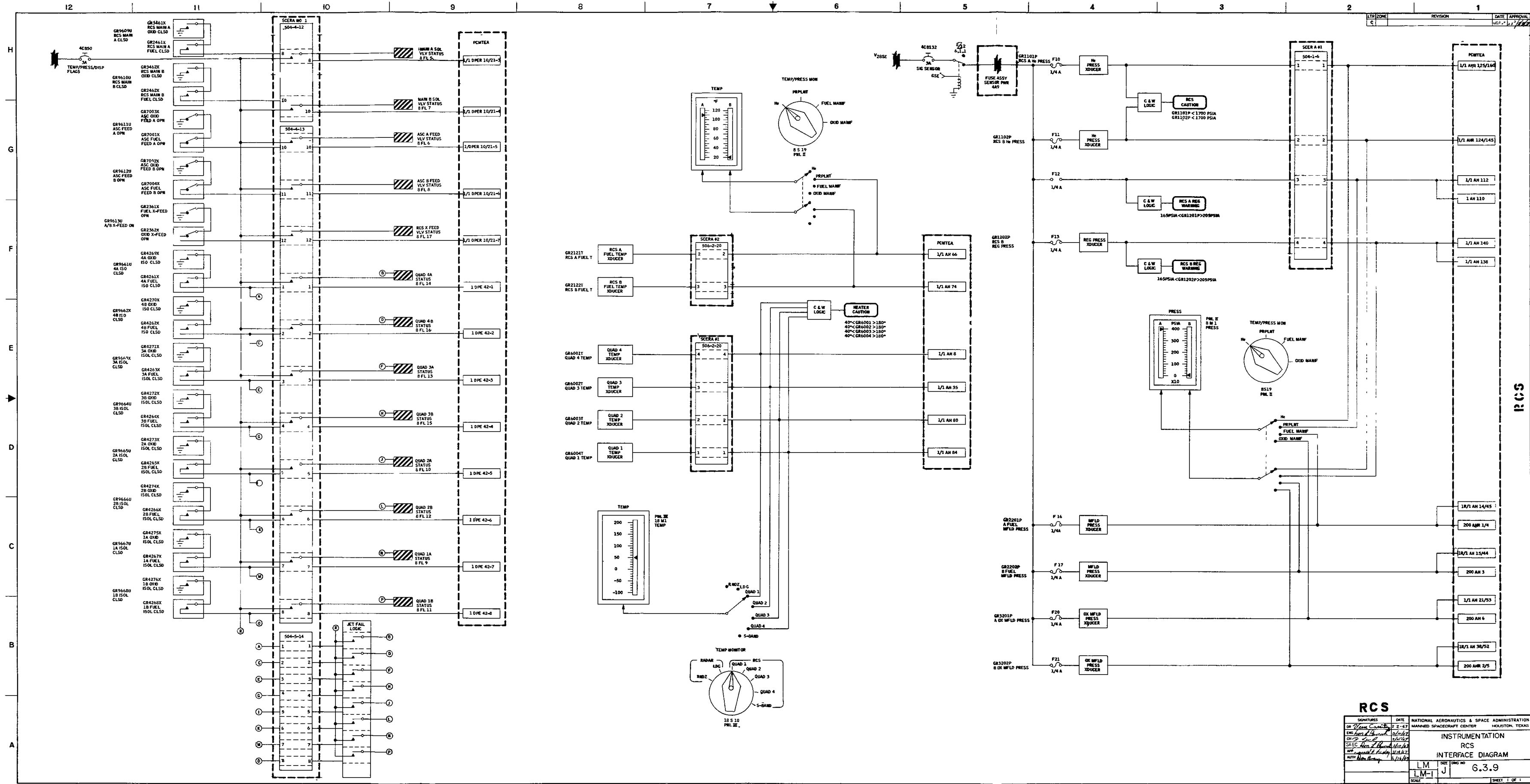
LM-1 J 6.3.6  
 SCALE 1 OF 1





### APS

SIGNATURES		DATE	NATIONAL AERONAUTICS & SPACE ADMINISTRATION MANNED SPACECRAFT CENTER HOUSTON TEXAS	
LM	LM	11/26/64	INSTRUMENTATION APS INTERFACE DIAGRAM	
LM-1	E	12/15/64	LM	6.3.8
SCALE		SHEET 1 OF 1		



SIGNATURES		DATE	NATIONAL AERONAUTICS & SPACE ADMINISTRATION MANNED SPACECRAFT CENTER HOUSTON, TEXAS	
DR	W. J. ...	2-2-47	INSTRUMENTATION RCS INTERFACE DIAGRAM	
ENG	...	...		
CRS	...	...		
AUT	...	...		
LM		LM-1	J	6.3.9
SCALE		SHEET 1 OF 1		

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SECTION 7

LM-1  
REV C

PGNS

7.1 GENERAL

7.1.1 General Information

The PGNS is the primary means of accomplishing guidance, navigation and control for the Lunar Module (LM). The system is designed to perform these functions in a self-contained mode, requiring no data from sources external to the LM after system initialization. On Mission AS-206 the primary mode of operation shall also be self-contained. However, provision is made for insertion of navigation, target and mode control data from the ground via the LGC (LM Guidance Computer) is desired. On AS-206, a secondary method of guidance and control is provided by the Program Reader Assembly (PRA) which replaces the LM Guidance Computer function. The Abort Guidance system which ordinarily has this backup function has been deleted on AS-206. With respect to the LM, the terms guidance and navigation are defined as:

- A. Guidance - The orientation of a thrust vector with respect to inertial space and the regulation of the level of thrust where possible so that specific and conditions on a desired trajectory are met.
- B. Navigation - The determination of vehicle position and velocity with respect to a known coordinate frame.

7.1.2 PGNS Hardware Configuration

The Primary Guidance, Navigation and Control System for Mission AS-206 is comprised of the following assemblies:

- A. Inertial Subsystem (ISS)
  - 1. Inertial Measurement Unit (IMU)
  - 2. Electronic Coupling Data Unit (ECDU)
  - 3. Power Servo Assembly (PSA)
  - 4. Pulse Torquing Assembly (PTA)
  - 5. Signal Conditioning Assembly (SCA).
- B. Computer Subsystem (CSS)
  - 1. LM Guidance Computer (LGC)
  - 2. Display and Keyboard (DSKY).

R-B

R-C

R-B

R-C

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C. Optics Subsystem

R-C

1. Alignment Optical Telescope (AOT)

R-B

2. Computer Control and Reticle Dimmer Assembly (CCRD).

R-C

D. Radar Subsystem (Electronic Assembly deleted on AS-206)

7.1.3 Inertial Measurement Unit (IMU)

The Inertial Measurement Unit (IMU) is the primary inertial sensing device of the LM. Three rate Integrating Gyroscopes (IRIG's) and three Pulse Integrating Pendulous Accelerometers (PIPA's) are mounted on the stable member (inner gimbal) of a three gimbal system. The stable member is held nonrotating with respect to inertial space by three gimbal servos, which derive their input error signals from three gyroscopes. The stable member is aligned at prelaunch to a known reference coordinate which is held fixed with respect to earth via gyrocompassing until Gyro Reference Release (GRR). At or near liftoff GRR is initiated by sensing 1.12 acceleration, however, GRR may be backed up by RF uplink if necessary. Once the system is released to become inertial, it will remain unchanged through the flight. There is no realignment of the inertial reference after liftoff, and the system will be in the inertial reference mode continuously. Velocity changes along three orthogonal axes are sensed by accelerometers, which produce signals that represent incremental changes in velocity. Attitude of the LM is generated by the inner, middle, and outer gimbal resolvers. These attitude signals are inputs to the CDU's. IMU temperature control is completely automatic and remains in operation once power is applied to the system.

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7.1.4 Electronic Coupling Data Unit (ECDU)

The Coupling Data Units (CDU's) perform two basic functions: An analog-to-digital conversion (A/D) and a digital-to-analog conversion (D/A) of information. In the (A/D) conversion, the CDU's convert and transfer angular information between the IMU and LGC. For each of the three inertial system CDU's, each IMU gimbal angle resolver provides the respective CDU with analog gimbal angle signals that represent the attitude of the LM with respect to the navigation base. The CDU converts

R-B

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these signals to digital form and transforms them serially to the LGC in angle increments. The CDU's also have the capability of providing via the D/A portion drive signals to the IMU gimbals to coarse align the stable member to a known orientation with respect to the navigation base. On AS-206, this function will be performed prelaunch only, during initial alignment.

R-C

#### 7.1.5 Power Servo Assembly (PSA)

The purpose of the power and servo assembly (PSA) is to provide a central mounting point for the majority of the PGNS power supplies, amplifiers and other modular electronic components. The PSA is mounted on a coldplate through which water-glycol coolant flows to dissipate operating heat.

#### 7.1.6 Pulse Torque Assembly (PTA)

The Pulse Torque Assembly (PTA) consists of a group of modular electronic assemblies used in the pulsing circuits of the gyros and accelerometers. Heat Dissipation is accomplished in the same manner as with the PSA.

R-B

#### 7.1.7 LM Guidance Computer (LGC)

The LM Guidance Computer (LGC) is the central data processing device of the PGNS system. The LGC inputs include: gimbal angle increments from the CDU's, incremental changes in velocity via the PIPA's and vehicle status inputs from the Control Electronics System (CES).

For the AS-206A Mission, the LGC will function as a completely automatic programmer that will control all onboard functions for the unmanned vehicle. The PGNS will automatically accomplish all guidance, navigation, and control of the LM. An uplink command capability exists for the LM to provide a limited amount of program change, in real time, by ground control. A major failure with either the LGC or IMU will



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LM  
AS-206  
REV B

## 7.2 PGNS OPERATION

### 7.2.1 PGNS Interfaces

The following list tabulates the electrical and functional interfaces between the PGNS and the remainder of the LM spacecraft. For reference consult MIT Document NEI6015000 PGNS and Control System for LM (Classified).

- A. Mode and Status
  - 1. PGNS in control of Spacecraft
  - 2. Attitude Hold Mode
  - 3. Auto Stabilization Mode
  - 4. Auto Throttle Mode
  - 5. Stage Verify
  - 6. Engine Armed
  - 7. Abort
  - 8. Abort Stage
  - 9. Thruster Fail Discrettes
  - 10. GDA Fail Discrettes
- B. Engine and Jet Control
  - 1. RCS Jet Commands
  - 2. Roll/Pitch Gimbal Trim Commands
  - 3. Increase/Decrease Throttle Rate
  - 4. Engine ON/OFF Commands
- C. Angle Data Signals
  - 1. Attitude Errors
  - 2. Gimbal Angles
- D. Maneuver Command Signals
  - 1. Translation Commands
  - 2. Out of Detent
  - 3. Attitude Rate Commands
  - 4. Rotation Commands
- E. Timing Signals and Telemetry

R-B

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- F. Caution and Warning Signals
- G. Power, Reference and Lighting
- H. DSKY and PCA (LMP) Commands

7.2.2 Guidance and Navigation Functions

- A. PGNS performs the guidance function in the following manner:

The LGC senses incremental velocity changes using the PIPA information in a known inertial orientation (angular increments from ICDU's). From this information the steering signals are derived to orient the thrust vector to a near optimum position in inertial space. Engine ON commands are issued by the LGC when certain initial conditions are satisfied. For AS-206 these conditions may be an absolute time interval from some preceding event (e.g. APS - 2) or the satisfaction of trajectory conditions arrived at by some navigation function. Engine OFF commands are generated by the LGC when desired end conditions for the burn are met.

R-B

- B. The PGNS navigation function is handled internal to the LGC. This function is performed both during thrust phase and during coast. It is performed on a 2 second basis during thrusting and on a 585 second basis during coast. During thrusting, external inputs, gimbal angle increments and PIPA data are required from the ISS and CDU, while during coasting phases, no external system input is required.

R-C

R-B

LM  
AS-206  
REV B

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7.3 INERTIAL MEASUREMENT UNIT SCHEMATIC NOTES (Drawing 7.2.1)

A. Notes

All latching relays are shown in the reset position and all unlatching relays are shown in the de-energized position.

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7.4 COUPLING DATA UNIT SCHEMATIC NOTES (Drawing 7.3.1)

A. The following abbreviations are applicable to the CDU schematic:

1.  $\Theta_{ig}$  = Inner gimbal angle (actual)
2.  $\Theta_{mg}$  = Middle gimbal angle (actual)
3.  $\Theta_{og}$  = Outer gimbal angle (actual)
4.  $\Delta\Theta_{ic}$  = Increment of command angle (inner gimbal)
5.  $\Delta\Theta_{mc}$  = Increment of command angle (middle gimbal)
6.  $\Delta\Theta_{oc}$  = Increment of command angle (outer gimbal)
7. AGS = Abort Guidance System
8. CDU = Coupling Data Unit
9. CS = Crew Systems
10. EX = Attitude Error signal about X-axis
11. EY = Attitude Error signal about Y-axis
12. EZ = Attitude Error signal about Z-axis
13. IMU = Inertial Measurement Unit
14. ISS = Inertial Subsystem
15. LGC = LM Guidance Computer
16. PC = Percent
17. RR = Rendezvous Radar

R-C

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LM  
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7.5 COMPUTER SCHEMATIC NOTES (Drawing 7.4.1)  
(To be supplied at a later date)

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TABLE 7-1 AS-206 DOWNLINK FORMAT

LM-1  
REV C

WORD NUMBER	FIRST REGISTER	SECOND REGISTER	WORD ORDER CODE
1	DOWNLIST I D	*SYNC BITS (00437-OCTAL)	0
2	LATEST CAL STATE VEC X POS MSB	*LATEST CAL STATE VEC X POS LSB	1
3	LATEST CAL STATE VEC Y POS MSB	*LATEST CAL STATE VEC Y POS LSB	1
4	LATEST CAL STATE VEC Z POS MSB	*LATEST CAL STATE VEC Z POS LSB	1
5	LATEST CAL STATE VEC X VEL MSB	*LATEST CAL STATE VEC X VEL LSB	1
6	LATEST CAL STATE VEC Y VEL MSB	*LATEST CAL STATE VEC Y VEL LSB	1
7	LATEST CAL STATE VEC Z VEL MSB	*LATEST CAL STATE VEC Z VEL LSB	1
8	STATE VECTOR TIME MSB	*STATE VECTOR TIME LSB	1
9	1d PIPADT	*DESIRED CDU X	1
10	DESIRED CDU Y	*DESIRED CDU Z	1
11	DELV X MSB	*DELV X LSB	1
12	DELV Y MSB	*DELV Y LSB	1
13	DELV Z MSB	*DELV Z LSB	1
14	OUTPUT TO LMP	*OUTPUT TO LMP	1
15	OUTPUT TO LMP	*OUTPUT TO LMP	1
16	OUTPUT TO LMP	*OUTPUT TO LMP	1
17	OUTPUT TO LMP	*OUTPUT TO LMP	1
18	LMPIN	LMPOUT	1
19	ALPHAR	EDOTP	1
20	UPVERB	*COMPNUMB	1
21	STATE COUNT	*UPOLOMOD	1
22	ST BUFF +0	*ST BUFF +1	1
23	ST BUFF +2	*ST BUFF +3	1
24	ST BUFF +4	*ST BUFF +5	1
25	ST BUFF +6	*ST BUFF +7	1
26	ST BUFF +8D	*ST BUFF +9D	1
27	ST BUFF +10D	*ST BUFF +11D	1
28	ST BUFF +12D	*ST BUFF +13D	1
29	I MODE 30	*I MODE 33	1
30	TIME OF EVENT MSB	*TIME OF EVENT LSB	1
31	GUIDANCE THRUST CMD MSB	*GUIDANCE THRUST CMD LSB	1
32	MOMENT OFFSET (Q)	*MOMENT OFFSET (R)	1
33	PREDICTED ENGINE ON TIME MSB	*PREDICTED ENGINE ON TIME LSB	1
34	REDO COUNTER	SFAIL	1
35	TIME 6	ACTUAL CDU X	1
36	ACTUAL CDU Y	*ACTUAL CDU Z	1
37	DERIVED RATE (P)	*DERIVED RATE (Q)	1
38	ALPHA Q	DERIVED RATE (R)	1
39	FLAGWORD 0	*FLAGWORD 1	1
40	FLAGWORD 2	*DAP BOOLS	1
41	CHANNEL 11	*CHANNEL 12	1
42	CHANNEL 13	*CHANNEL 14	1
43	CHANNEL 30	*CHANNEL 31	1
44	CHANNEL 32	*CHANNEL 33	1
45	DSPTAB +0	*DSPTAB +1	1
46	DSPTAB +2	*DSPTAB +3	1
47	DSPTAB +4	*DSPTAB +5	1
48	DSPTAB +6	*DSPTAB +7	1
49	DSPTAB +8D	*DSPTAB +9D	1
50	DSPTAB +10D	*DSPTAB +11D	1

\* TABLE 7-1 AS-206 DOWNLINK FORMAT (Concluded)

LM-1  
REV C

WORD NUMBER	FIRST REGISTER	SECOND REGISTER	WORD ORDER	CODE
51	TIME 2	*TIME 1	1	
52	COMPTORK + 0	COMPTORK + 1	1	
53	COMPTORK + 2	COMPTORK + 3	1	
54	COMPTORK + 4	COMPTORK + 5	1	
55	FAILREQ + 0	FAILREQ + 1	1	
56	FAILREQ + 2	ALMCADR	1	
57	ALMCADR + 1	ERCOUNT	1	
58	PIPA X	PIPA Y	1	R-C
59	PIPA Z	RHCP	1	
60	FLAGWORD 4	LMPJFAIL	1	
61	MASS (MSB)	MASS (LSB)	1	
62	CDU Y	CDU Z	1	
63	CDU Y	CDU Z	1	
64	OUTPUT TO LMP	*OUTPUT TO LMP	1	
65	OUTPUT TO LMP	*OUTPUT TO LMP	1	
66	OUTPUT TO LMP	*OUTPUT TO LMP	1	
67	OUTPUT TO LMP	*OUTPUT TO LMP	1	
68	LMPIN	LMPOUT	1	R-C
69	DELAREA (MSB)	DELAREA (LSB)	1	
70	MISSION PHASE REGISTER 4	*MISSION PHASE REGISTER 3	1	
71	MISSION PHASE REGISTER 2	*MISSION PHASE REGISTER 1	1	R-B
72	MISSION TIME REGISTER 4	*MISSION TIME REGISTER 3	1	
73	MISSION TIME REGISTER 2	*MISSION TIME REGISTER 1	1	
74	PRESENT MISSION PHASE	IDPIPADT	1	R-C
75	TIME TO GO MSB	*TIME TO GO LSB	1	
76	BURN DATA	*BURN DATA	1	
77	BURN DATA	*BURN DATA	1	
78	BURN DATA	*BURN DATA	1	
79	BURN DATA	*BURN DATA	1	
80	BURN DATA	*BURN DATA	1	
81	BURN DATA	*BURN DATA	1	
82	BURN DATA	*BURN DATA	1	
83	BURN DATA	*BURN DATA	1	
84	BURN DATA	*BURN DATA	1	
85	TIME 6	ACTUAL CDU X	1	R-C
86	ACTUAL CDU Y	*ACTUAL CDU Z	1	
87	DERIVED RATE (P)	*DERIVED RATE (Q)	1	
88	ALPHAQ	DERIVED RATE (R)	1	R-C
89	FLAGWORD 0	*FLAGWORD 1	1	
90	FLAGWORD 2	*DAP BOOLS	1	
91	CHANNEL 11	*CHANNEL 12	1	
92	CHANNEL 13	*CHANNEL 14	1	
93	CHANNEL 30	*CHANNEL 31	1	
94	CHANNEL 32	*CHANNEL 33	1	
95	DSPTAB +0	*DSPTAB +1	1	
96	DSPTAB +2	*DSPTAB +3	1	
97	DSPTAB +4	*DSPTAB +5	1	
98	DSPTAB +6	*DSPTAB +7	1	
99	DSPTAB +8D	*DSPTAB +9D	1	
100	DSPTAB +10D	*DSPTAB +11D	1	

TABLE 7-2 MISSION AS-206 - MISSION PHASES

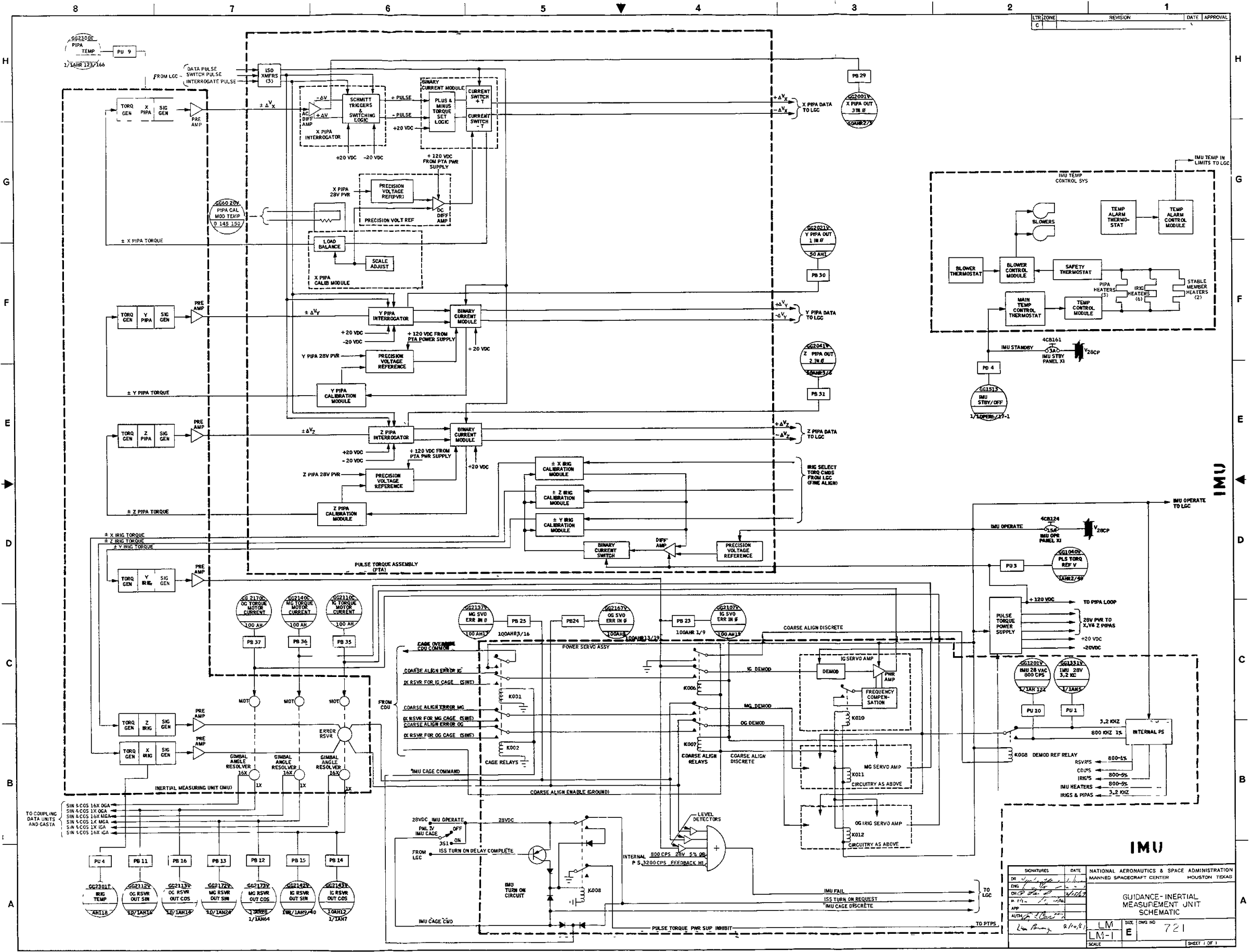
LM-1  
REV C

\*

<u>Phase No.</u>	<u>Phase</u>	<u>Programs Executed</u>	
1	Prelaunch Alignment	01, 02, 04, 05	R-C
2	Guidance Reference Release	07, 11, 12	
3	Suborbital Abort	71	
4	Contingency Orbit Insertion	72	
5	*	*	
6	Coast - S-IVB Attached	13	
7	S-IVB/LM Separate	14	
8	DPS Cold Soak	15	
9	DPS 1	31, 41	R-B
10	*	*	
11	DPS 2/FITH/APS 1	32, 42, 43, 44, 72	
12	*	*	
13	APS 2	34, 46	
14	*	*	
15	*	*	
16	*	*	
17	*	*	
18	*	*	
19	*	*	

\*Not used for Mission AS-206

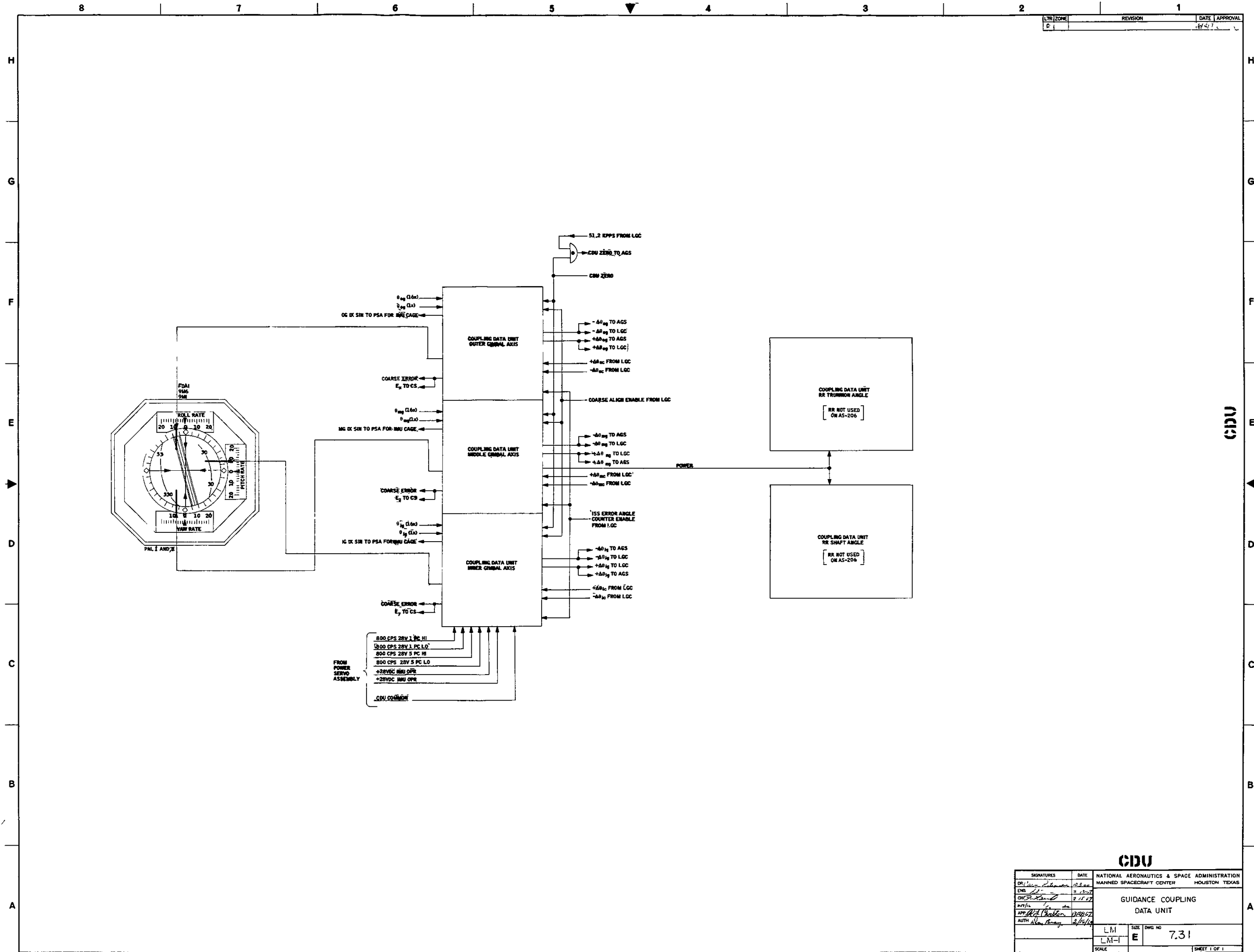




REV	DATE	APPROVAL
1		
2		
3		
4		
5		
6		
7		
8		

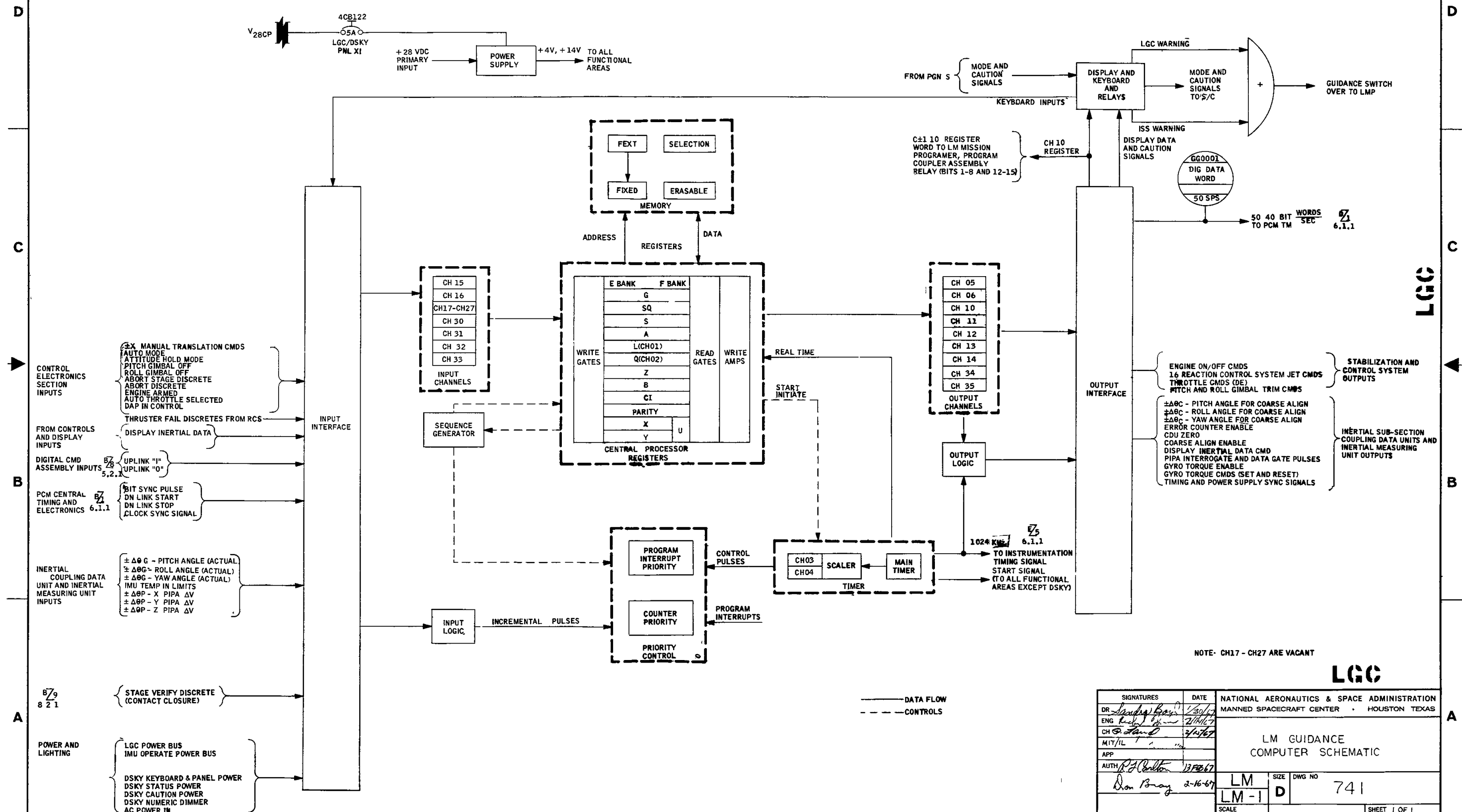
REV	DATE	APPROVAL
1		
2		
3		
4		
5		
6		
7		
8		

NATIONAL AERONAUTICS & SPACE ADMINISTRATION  
 MANNED SPACECRAFT CENTER HOUSTON TEXAS  
 GUIDANCE-INERTIAL MEASUREMENT UNIT SCHEMATIC  
 LM-1 E 721  
 SCALE SHEET 1 OF 1



LTN/ZONE	REVISION	DATE	APPROVAL
C		12/27	

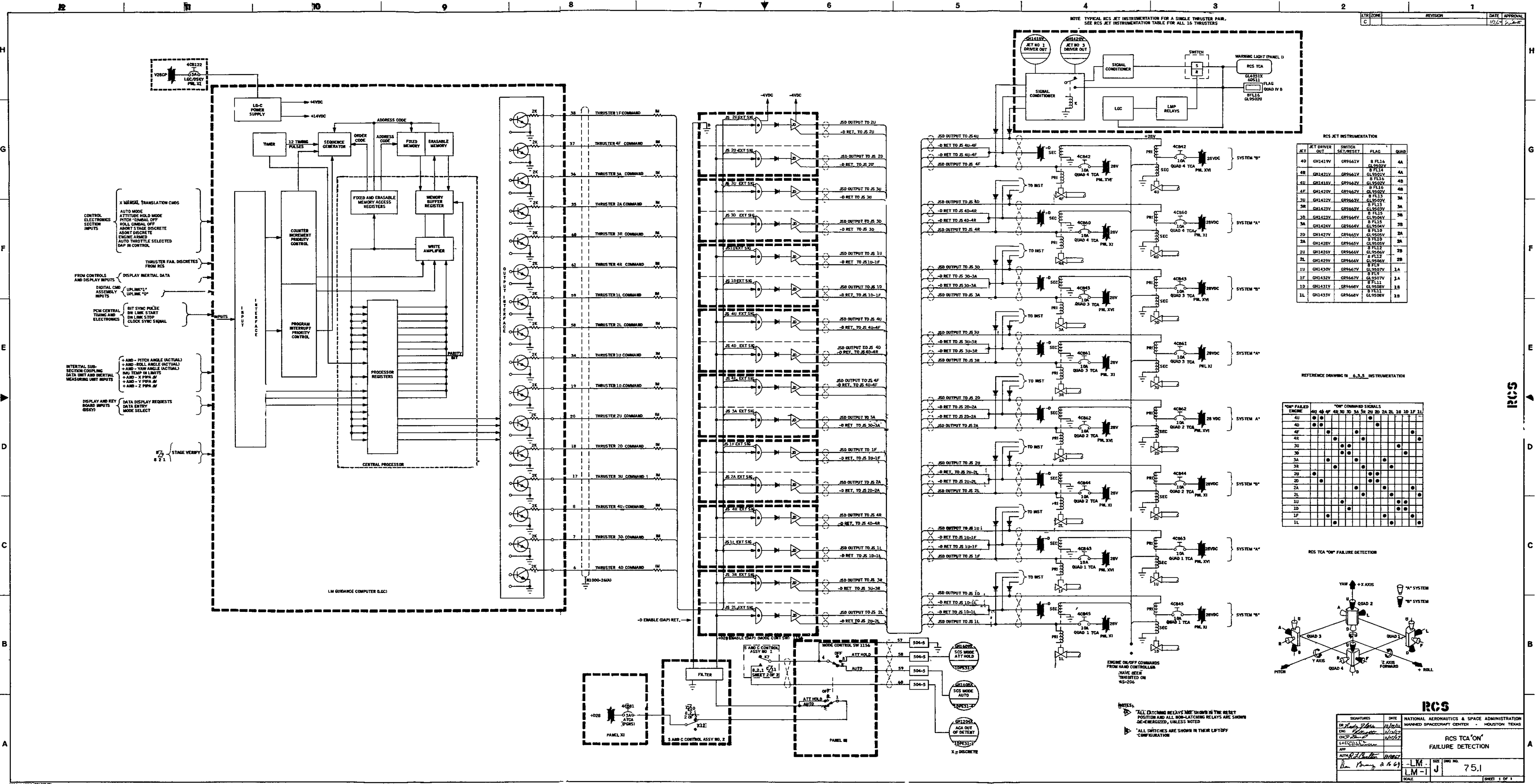
SIGNATURES		DATE	NATIONAL AERONAUTICS & SPACE ADMINISTRATION MANNED SPACECRAFT CENTER HOUSTON TEXAS	
DR/		12/27		
ENR		12/27		
CHKD		12/27		
APP'D		12/27		
AUTH		12/27		
GUIDANCE COUPLING DATA UNIT			L.M.	SIZE
			L.M.-I	E
			SCALE	DWG NO
				7.31
				SHEET 1 OF 1



NOTE- CH17 - CH27 ARE VACANT



SIGNATURES		DATE	NATIONAL AERONAUTICS & SPACE ADMINISTRATION	
DR	<i>Don Bray</i>	2/16/67	MANNED SPACECRAFT CENTER · HOUSTON TEXAS	
ENG	<i>Don Bray</i>	2/16/67		
CH	<i>Don Bray</i>	2/16/67		
M/T/L				
APP				
AUTH	<i>Don Bray</i>	2-16-67		
			LM	SIZE DWG NO
			LM-1	D 741
			SCALE	SHEET 1 OF 1



NOTE: TYPICAL RCS JET INSTRUMENTATION FOR A SINGLE THRUSTER PAIR. SEE RCS JET INSTRUMENTATION TABLE FOR ALL 16 THRUSTERS.

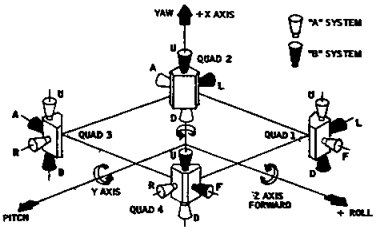
RCS JET INSTRUMENTATION

JET	JET DRIVER	SWITCH	FLAG	QUAD
4D	GH1419V	GR9661V	B FL13	4A
4E	GH1421V	GR9662V	B FL14	4A
4U	GH1418V	GR9662V	B FL13	4B
4F	GH1420V	GR9662V	B FL13	4B
3U	GH1422V	GR9663V	B FL13	3A
3R	GH1423V	GR9663V	B FL13	3A
3A	GH1423V	GR9663V	B FL13	3B
3B	GH1423V	GR9663V	B FL13	3B
2U	GH1420V	GR9664V	B FL13	2B
2L	GH1420V	GR9664V	B FL13	2B
1U	GH1430V	GR9667V	B FL11	1A
1F	GH1432V	GR9667V	B FL11	1A
1D	GH1431V	GR9668V	B FL11	1B
1L	GH1431V	GR9668V	B FL11	1B

REFERENCE DRAWING NO. 6-3-5 INSTRUMENTATION

RCS TCA "ON" FAILURE DETECTION

ENGINE	4D	4E	4R	3U	3A	3R	2U	2A	2L	1U	1F	1D	1L
4U	●	●	●	●	●	●	●	●	●	●	●	●	●
4F	●	●	●	●	●	●	●	●	●	●	●	●	●
4R	●	●	●	●	●	●	●	●	●	●	●	●	●
3U	●	●	●	●	●	●	●	●	●	●	●	●	●
3A	●	●	●	●	●	●	●	●	●	●	●	●	●
3R	●	●	●	●	●	●	●	●	●	●	●	●	●
2U	●	●	●	●	●	●	●	●	●	●	●	●	●
2A	●	●	●	●	●	●	●	●	●	●	●	●	●
2L	●	●	●	●	●	●	●	●	●	●	●	●	●
1U	●	●	●	●	●	●	●	●	●	●	●	●	●
1D	●	●	●	●	●	●	●	●	●	●	●	●	●
1F	●	●	●	●	●	●	●	●	●	●	●	●	●
1L	●	●	●	●	●	●	●	●	●	●	●	●	●



RCS TCA 'ON' FAILURE DETECTION

SIGNATURES	DATE	NATIONAL AERONAUTICS & SPACE ADMINISTRATION
DESIGNED BY: [Signature]	10/19/69	MANNED SPACECRAFT CENTER - HOUSTON, TEXAS
CHECKED BY: [Signature]	10/20/69	
APPROVED BY: [Signature]	10/20/69	
SCALE	LM-1	75.1

8.1 GENERAL

8.1.1 Control Electronics Section (CES) Functions

The CES operates in both the primary guidance control path and the abort guidance control path.

When operating as part of the primary guidance control path in conjunction with the PGNS, the CES provides the implementation of the control signals originating from the LGC as follows:

- A. Converts reaction control jet commands to the required electrical power to operate the RCS jet solenoid valves.
- B. Accepts discrete descent engine rotation commands. Upon receipt of a command, the descent engine is rotated about its gimbal axes at a constant angular rate until the command is removed.
- C. Accepts both LGC and manual engine ON/OFF commands and routes them to propulsion to fire or stop the descent or ascent engine.
- D. Accepts LGC and manual thrust commands to throttle the descent engine 10 to 100 percent of its range.

When operating in the abort guidance control path the CES performs the following functions:

- A. Accepts rate damping signals from the RGA's and fires the proper RCS jets to achieve attitude control.
- B. Accepts manual (LMP) +X translation commands and fires RCS jets to accelerate the LM in the desired direction.
- C. Automatically rotates the gimballed descent engine for trim control.
- D. Accepts manual (LMP) engine ON/OFF commands and routes them to the descent or ascent engine.
- E. Accepts manual (LMP) throttle commands to control the thrust of the descent engine.

8.1.2 Modes of Attitude Control

Two basic modes of attitude control are provided by the CES and are selectable on the control panel. One mode is fully automatic and one is

R-B

R-C

R-B

R-C

R-B

R-C

R-B

R-C

R-B

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semiautomatic. In LM-1 only the automatic mode is available.

- A. Automatic Mode - The automatic mode provides fully automatic attitude control of the LM.
- B. In AGS mode only a rate hold capability exists since no AGS is aboard LM-1.

R-C

### 8.1.3 Translation Control (RCS)

Both automatic and manual (LMP) translation control using the RCS thrusters are available. Automatic control consists of jet commands from the LGC to the jet drivers in the ATCA. These are used for translations of small velocity increments and ullage settling prior to main engine ignition after coasting phases. Manual control in PGNS operation consists of +X ON/OFF commands from the LMP by way of the LGC. In AGS operation only manual control is available. Control consists of +X ON/OFF commands from the LMP to the jet logic in the ATCA. The voltage is sufficient to saturate the pulse ratio modulators and give ON/OFF control of the RCS jets.

R-C

R-B

### 8.1.4 Attitude and Translation Control Assembly (ATCA)

The ATCA supplies the signals which control the firing of the reaction jets and the signals for automatic trim of the gimbaled descent engine in AGS operation. The dc voltages required in all of the CES subassemblies and the synchronized ac voltage for the RGA's, and LMP are also generated within this assembly. The input signals from the RGA's are processed in the ATCA and are directed to the appropriate jets and the descent engine control assembly.

R-C

Drawing 8.2.1 Sheet 1 of 2 shows a schematic diagram of the ATCA. In PGNS operation, only the LGC preamplifiers are enabled by the guidance selector switch. LGC jet commands are amplified by the preamplifiers and jet drivers and sent to the primary solenoids of the RCS. In AGS operation, only the abort preamplifiers are enabled and jet signals from

\*

the pulse ratio modulators are amplified and drive the RCS primary solenoids. Pitch, roll, and yaw signals are processed in three similar channels. The RGA rate signals are the only inputs to the ATCA for attitude control in the AGS mode. The gains of the summing amplifiers are changed when the LM is staged to account for the change in vehicle moment of inertia. The RGA ac signals are changed to dc by keyed demodulators and filters.

In the roll and pitch channels the demodulator output is sent to the DECA to control the trim of the gimballed descent engine. The deadband circuitry provides for either a wide deadband (+5 degrees) or a narrow deadband (+0.3 degrees in roll and pitch and +0.4 degrees in yaw) depending on the mission phase. In automatic and attitude hold modes, the signals from the deadband circuits are applied to the jet select logic. The jet select logic combines the attitude and translation inputs, determines whether two or four jets will fire to control rotation and X-axis translation, and applies the resultant signals to eight pulse ratio modulators. These pulse ratio modulators generate pulses which vary in width and frequency depending on the input voltage in order to control the duty ratio of the RCS jets. Each pulse ratio modulator controls two opposing jets. The jet to be fired is determined by the sign of the pulse ratio modulator input voltage.

#### 8.1.5 Descent Engine Control Assembly (DECA)

The DECA contains circuitry for controlling three functions of the descent engine. Engine throttling commands from the PGNS and LMP are processed and sent to the descent engine. PGNS or ATCA signals are processed for positioning the Gimbal Drive Actuators to control engine trim. ON/OFF commands are processed in the DECA to control descent engine ignition and shutdown. The schematic diagram of the DECA is shown in Drawing 8.3.1.

LMP throttle commands can be applied to the descent engine with the throttle control switch on the control panel in either the manual or automatic position. Manual throttle commands consists of ac voltages from the LMP applied to the DECA.

\*

LM  
AS-206  
REV B

The DECA demodulates and filters the signal and sends a proportional dc throttle voltage to the descent engine.

Automatic throttle signals can only be applied to the descent engine when the throttle control switch is in the automatic position. The LGC sends automatic throttle commands to the DECA in the form of pulses on one of two lines. Pulses on one line advance a forward-backward counter while pulses on the other line decrease the count. A dc voltage proportional to the count is generated and sent to the descent engine for automatic throttle control.

In PGNS operation automatic trim control is provided by the LGC. When the LGC determines descent engine trim is required, it sends a trim command to the DECA on either a trim positive or a trim negative line for the roll or pitch axis. The trim signal is routed through a malfunction logic circuit to a power switching circuit. The power switching circuit applies 400 cycle, 115 volts power to the proper Gimbal Drive Actuator. The GDA rotates the descent engine and sends a 400 cycle signal proportional to its position back to the DECA. The DECA demodulates and differentiates the feedback signal and applies it back to the malfunction logic circuit. If the GDA is not moving in the commanded direction, the malfunction logic generates a trim failed signal. This signal removes the 400 cycle power from the power switching circuit and sends TRIM FAILED signals to the LGC and Instrumentation.

R-B

In abort guidance operation, roll and pitch trim signals, are received from the roll and pitch error channels in the ATCA. A comparator and threshold circuit in the DECA generates trim negative or trim positive commands and sends them to the malfunction logic. The malfunction logic controls the power switching circuits the same as in PGNS operation.

#### 8.1.6 Gimbal Drive Actuator (GDA)

The two GDA's are low-speed electromechanical devices each containing a 115V 400 cps ac motor driving a screw jack and a position transducer. Under control of the DECA the GDA's rotate the descent



engine about the pitch and roll axes so that the thrust vector goes through the LM center of gravity. One GDA controls the pitch gimbal and the other controls the roll gimbal.

Each GDA is capable of extending or retracting 2 inches from the mid-position and will gimbal the descent engine a maximum of plus or minus 6 degrees about the LM Y- and Z-axis. The GDA's move at a constant speed and rotate the descent engine at a rate of 0.2 degrees per second. The position transducer receives 115V 400 cps from the DECA on its primary winding. The secondary voltage is 400 cps, 7.5 volts per inch travel from mid-position; in phase when extended and 180 degrees out of phase when retracted past the mid-position. The transducer output is sent to instrumentation for telemetry and to the DECA malfunction logic.

#### 8.1.7 CES Interfaces

The CES receives the following signals from the PGNS:

- A. ON/OFF commands for each of the 16 reaction control jets.
- B. ON/OFF commands for the ascent or descent engine.
- C. Descent engine trim commands.
- D. Thrust magnitude commands for the descent engine.
- E. 800 cycle per second power to excite the LMP.

The CES feeds the following signals to the PGNS in the primary mode:

- A. Gimbal fail signals.
- B. +X Translation ON/OFF Commands.

The CES provides the following to the descent engine:

- A. Ignition and shutdown commands
- B. Automatic and manual throttling commands.
- C. Rotation of the gimbal engine.

The CES also interfaces with the:

- A. Electrical Power Subsystem (EPS) - The CES receives required electrical power from the EPS
- B. Reaction Control Subsystem (RCS) - The CES provides the signals to actuate the RCS jet solenoids.
- C. Ascent Engine - The CES provides commands for ascent engine ignition and shutdown.

\*

- D. Instrumentation Subsystem - CES provides signals to the Instrumentation Subsystem for inflight monitoring.
- E. Environmental Control Subsystem (ECS) - The ECS provides mounting surfaces and thermal protection for the CES equipment.
- F. Structure Subsystem - The Structure Subsystem provides the area and mounting accommodations to house the CES equipment within the structure.
- G. Explosive Devices Subsystem (EDS) - The CES interfaces with the EDS for stage status information.

R-C

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LM-1  
REV C

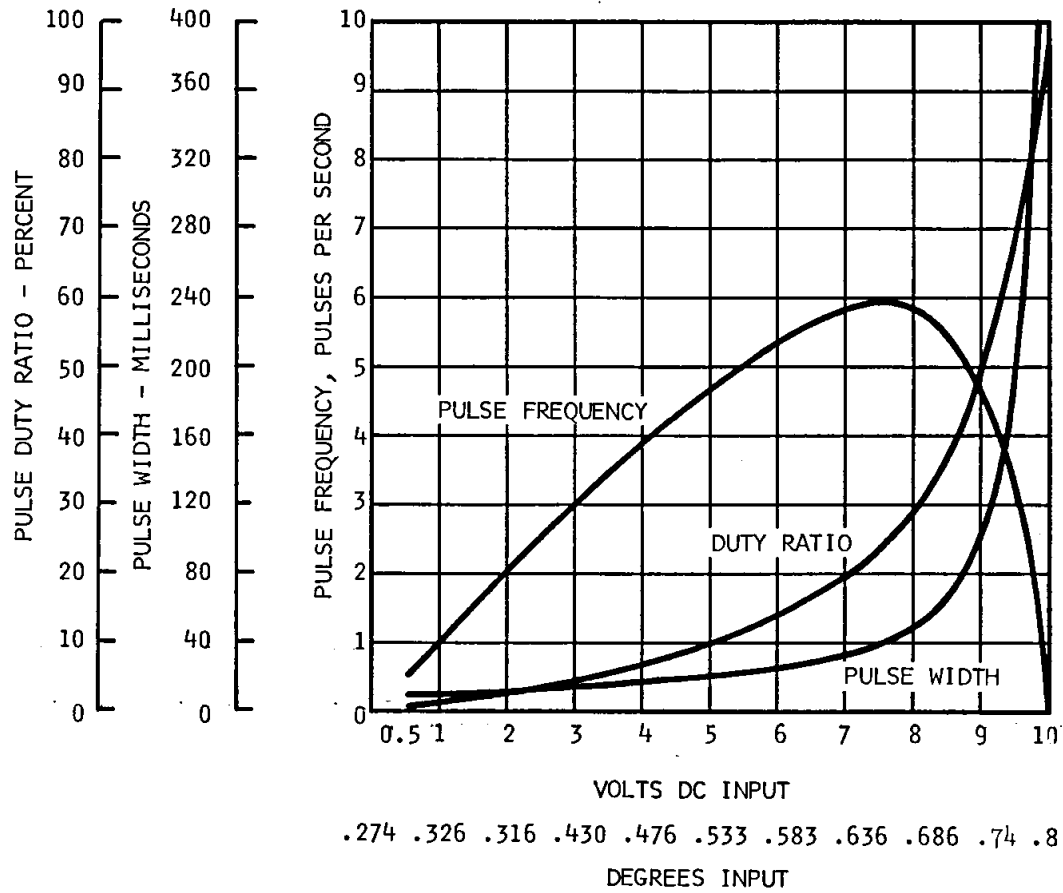
## 8.2 CONTROL ELECTRONICS SYSTEM GENERAL NOTES

- A. The Control Electronics System (CES) will have power applied and will be operating prior to launch and remain on throughout the mission. The primary guidance will utilize only a portion of the CES for control of the LM.
- B. Manual throttling of the Descent Engine System in degrees of 10, 30, 50, and 100 percent throttle settings can be tested if the PGNS fails AS-206 by the PRA. The reset position of the throttle is 30 percent.
- C. There will not be an automatic closed loop guidance for the PRA/AGS control during DPS and APS burns. Should a failure occur in the PGNS, the PRA will perform a minimum alternate propulsion test. The requirements for using the PRA/AGS control for a propulsion test will depend upon the time of failure of PGNS.

R-B

R-C

R-B



R-C

Figure 8-3 Performance of Pulse Ratio Modulator

\*

TABLE 8-2 PRELAUNCH STATUS OF SWITCH POSITIONS

SWITCH NUMBER	SWITCH TITLE	SWITCH POSITION
1-S-1	ENG ARM	OFF
1-S-2	ENG START	OFF
1-S-3	ENG STOP	OFF
1-S-4	ENG STOP	OFF
1-S-5	DES RATE	CENTER
1-S-6	X-TRANSLATION	4 JET
1-S-8	ENG GIMBAL	ENABLE
1-S-9	BAL CPL	ON
1-S-10	MAN THROTTLE	SYS ENG
1-S-11	THRUST CONTROL	AUTO
1-S-12	+X TRANSLATION	OFF
1-S-13	ABORT	GUARD DOWN-SW OFF
1-S-14	ABORT STAGE	GUARD DOWN-SW OFF
3-S-1	IMU CAGE	OFF
9-S-2	RATE ERROR MON	CMPTR
9-S-3	ATTITUDE MON	PGNS
9-S-4	ALT/RNG MON	ALT/ALT RT
9-S-6	GUID CONT	PGNS
9-S-7	RATE ERROR MON	CMPTR
9-S-8	SHFT/TRU	± 50°
9-S-9	MODE SELECT	PGNS
9-S-10	ATTITUDE MON	PGNS
9-S-11	RESET/CONTROL	(RESET) UP
9-S-12	TIMER CONTROL	CENTER POS
9-S-17	X POINTER SCALE	HI MULT
9-S-18	X POINTER SCALE	HI MULT

R-B

R-C

R-B

R-C

R-B

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LM-1  
REV C

TABLE 8-2 PRELAUNCH STATUS OF SWITCH POSITIONS (Concl'd)

SWITCH NUMBER	SWITCH TITLE	SWITCH POSITION	
11-S-1	GYRO TEST	OFF	
11-S-2	DEADBAND	MIN	
11-S-3	ATTITUDE CONTROL - PITCH	MODE CONTROL	
11-S-4	ATTITUDE CONTROL - ROLL	MODE CONTROL	
11-S-5	ATTITUDE CONTROL - YAW	MODE CONTROL	
11-S-6	MODE CONTROL	AUTO	
11-S-7	GYRO TEST	ROLL	
			R-C
12-S-17	AGS STATUS	OFF	
			R-C
17-S-1	MANUAL SLEW	CENTER	
17-S-2	SLEW RATE	LOW	R-B
17-S-3	R. R. MODE SEL	AUTO TRACK	R-C
17-S-5	LDG RADAR ANT	#1 DES	
17-S-6	RADAR TEST	OFF	R-B
17-S-8	TEST MONITOR	LDG RDR PWR: ALT XMTR	R-C
18-S-10	TEMP MONITOR	RNDZ	R-B
19-S-3	LMP TCA ISOLATION	ENABLE	R-C

\*

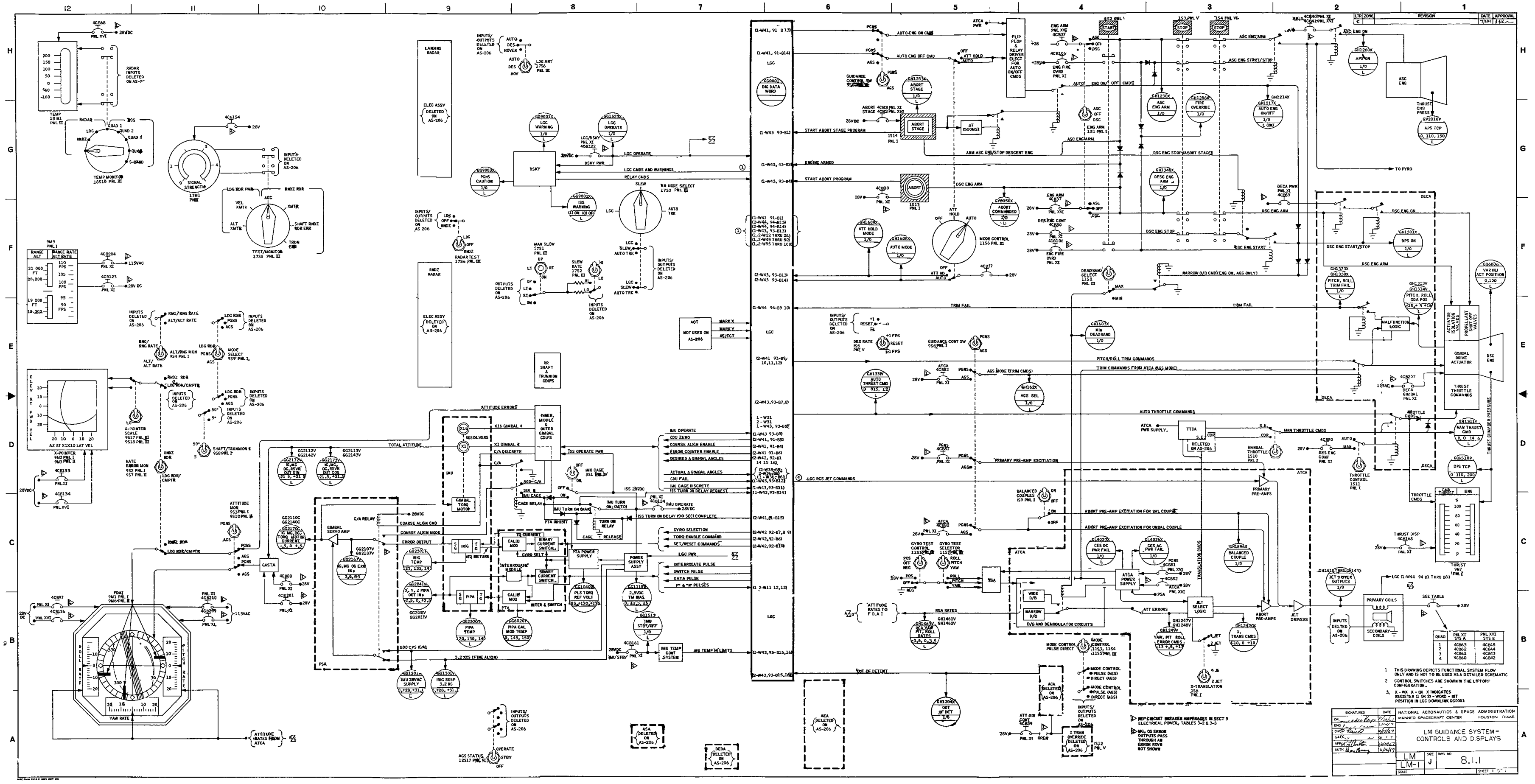
TABLE 8-3 PRELAUNCH STATUS OF CIRCUIT BREAKERS

CIRCUIT BREAKER NUMBER	TITLE	POSITION
4CB2	ABORT STAGE	CLOSED
4CB3	ABORT STAGE	CLOSED
4CB28	AEA	OPEN
4CB29	RNDZ PWR	OPEN
4CB37	ENG ARM	CLOSED
4CB40	AELD	CLOSED
4CB41	AELD	CLOSED
4CB59	ATT DIR CONT.	OPEN
4CB69	DECA PWR	CLOSED
4CB79	ASA	OPEN
4CB80	DES ENG CONT	CLOSED
4CB81	ATCA (PGNS)	CLOSED
4CB82	ATCA	CLOSED
4CB88	GASTA	OPEN
4CB105	LDG RDR	OPEN
4CB106	ENG FIRE OVERRIDE	CLOSED
4CB122	LGC/DSKY	CLOSED
4CB123	ALT/ALT RT RNG/CONTROL	OPEN
4CB124	IMU OPERATE	CLOSED
4CB126	FDAI	OPEN
4CB133	X-PNTR	OPEN
4CB134	X-PNTR	OPEN
4CB154	SIG STR DISP	OPEN
4CB155	RNDZ RDR OPR	OPEN
4CB156	RNDZ RDR STBY	OPEN
4CB157	LDG RDR	CLOSED
4CB161	IMU STBY	CLOSED
4CB179	LMP FEED	CLOSED & SLUGGED
4CB201	GASTA	OPEN

R-B

R-C

R-B

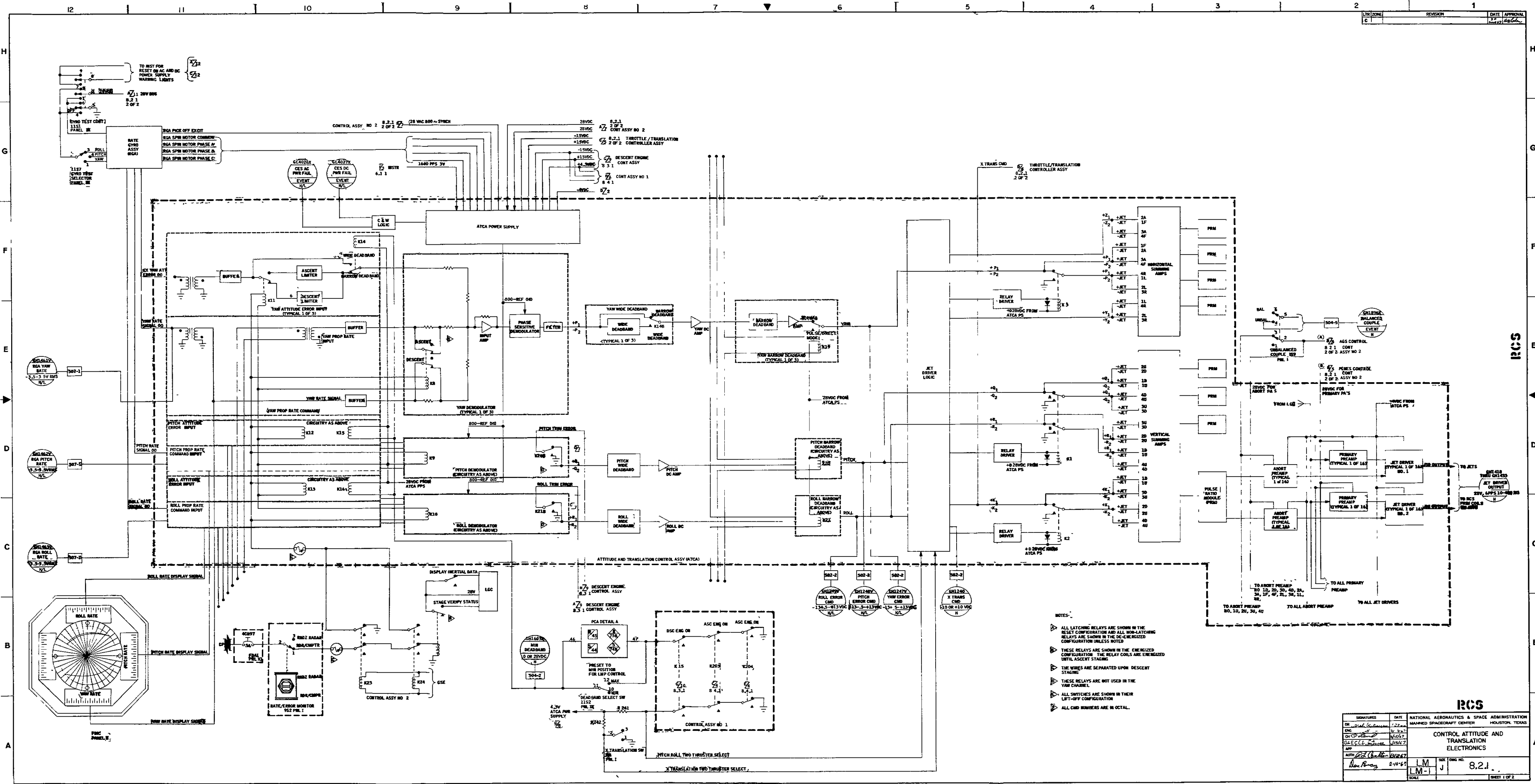


SIGNATURES	DATE	NATIONAL AERONAUTICS & SPACE ADMINISTRATION MANNED SPACECRAFT CENTER HOUSTON, TEXAS
DR. [Signature]	12/17/72	LM GUIDANCE SYSTEM- CONTROLS AND DISPLAYS
ENG. [Signature]	12/17/72	
DESIGN [Signature]	12/17/72	
AUTH. [Signature]	12/17/72	

LM	SIZE	DWG NO
LM-1	J	8.1.1
SCALE		SHEET 1 OF 1





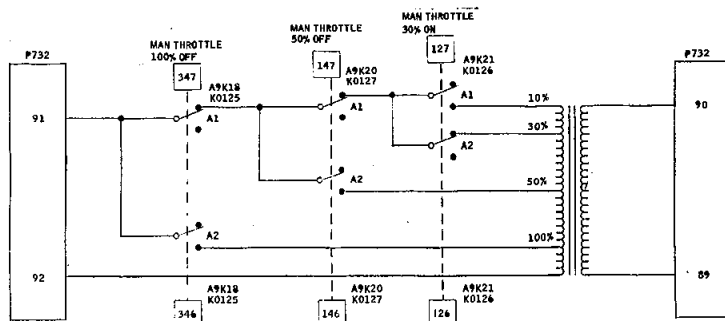
- NOTES:
- ALL LATCHING RELAYS ARE SHOWN IN THE RESET CONFIGURATION AND ALL NON-LATCHING RELAYS ARE SHOWN IN THE DE-ENERGIZED CONFIGURATION UNLESS NOTED.
  - THESE RELAYS ARE SHOWN IN THE ENERGIZED CONFIGURATION. THE RELAY COILS ARE ENERGIZED UNTIL ASCENT STAGING.
  - THE WIRES ARE SEPARATED UPON DESCENT STAGING.
  - THESE RELAYS ARE NOT USED IN THE YAW CHANNEL.
  - ALL SWITCHES ARE SHOWN IN THEIR LIFT-OFF CONFIGURATION.
  - ALL CMD NUMBERS ARE IN OBTAL.

SIGNATURES		DATE	NATIONAL AERONAUTICS & SPACE ADMINISTRATION	
DR	CHKD		MANNED SPACECRAFT CENTER HOUSTON, TEXAS	
<i>[Signature]</i>	<i>[Signature]</i>	12-22-67		
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<i>[Signature]</i>	<i>[Signature]</i>	12-22-67		
<i>[Signature]</i>	<i>[Signature]</i>	12-22-67		
<p>CONTROL ATTITUDE AND TRANSLATION ELECTRONICS</p>			<p>SIZE: 10x10 FORM NO. J REV: 8.2.1 PAGE: 1 OF 2</p>	

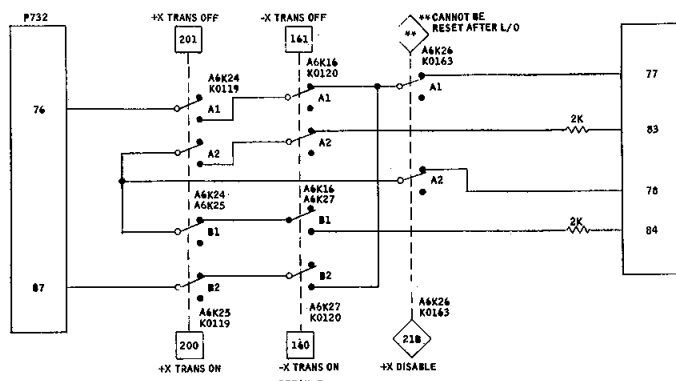
LM-1  
REV C

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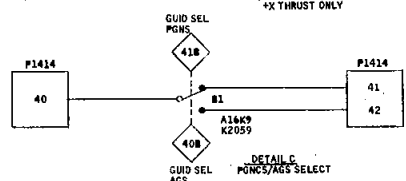
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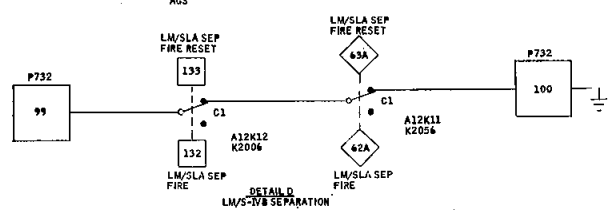
DETAIL A  
MANUAL THROTTLE CONTROL



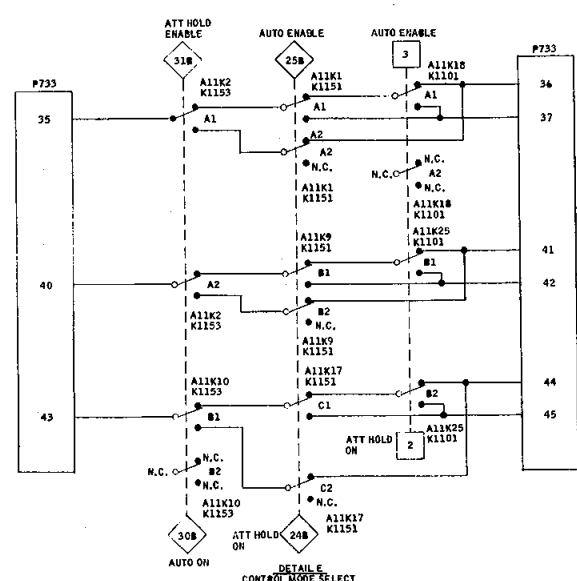
DETAIL B  
THRUST/TRANSLATION CONTROLLER  
+X THRUST ONLY



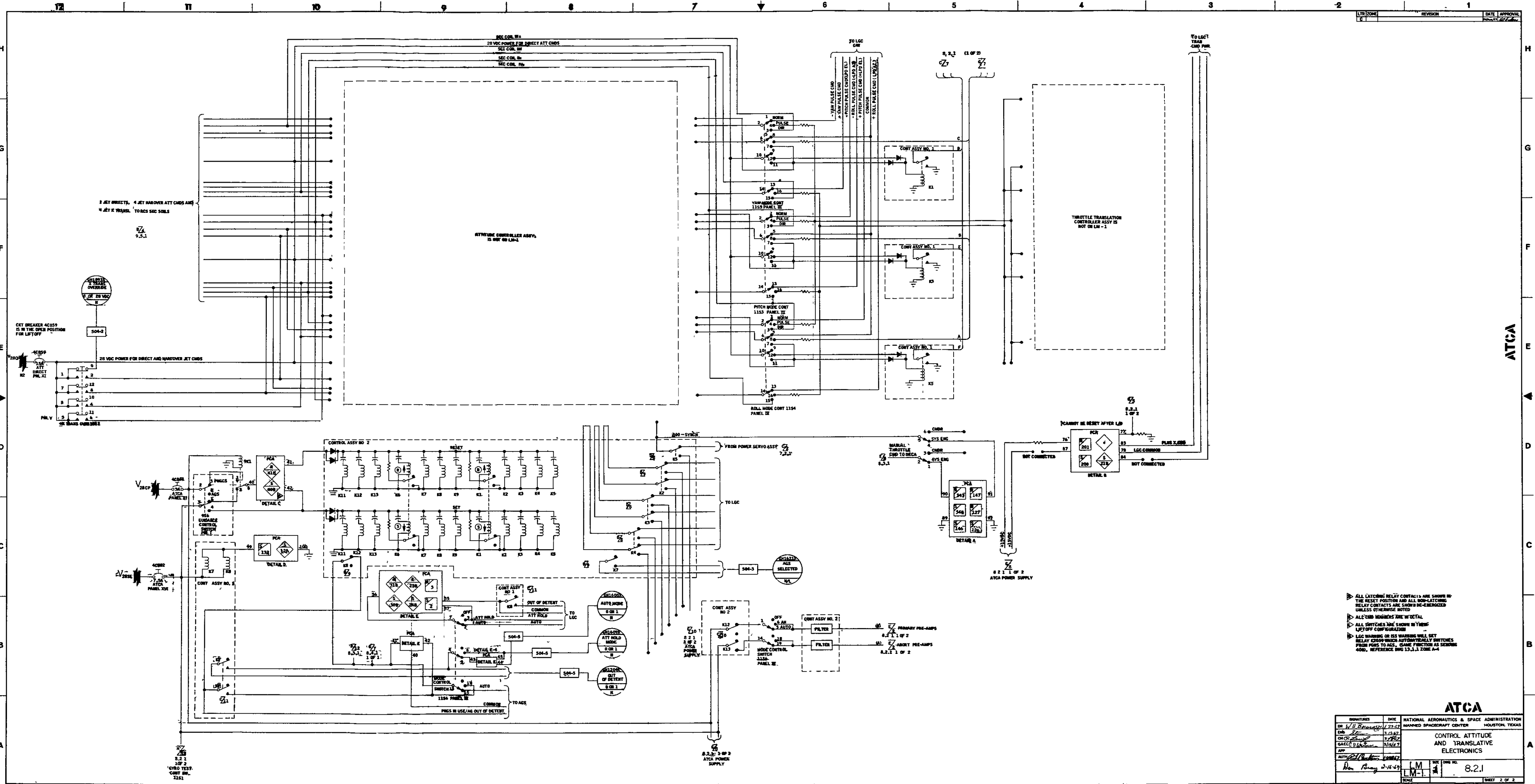
DETAIL C  
GUID SEL PONS/AGS SELECT



DETAIL D  
LM/S-IV SEPARATION



DETAIL E  
CONTROL MODE SELECT

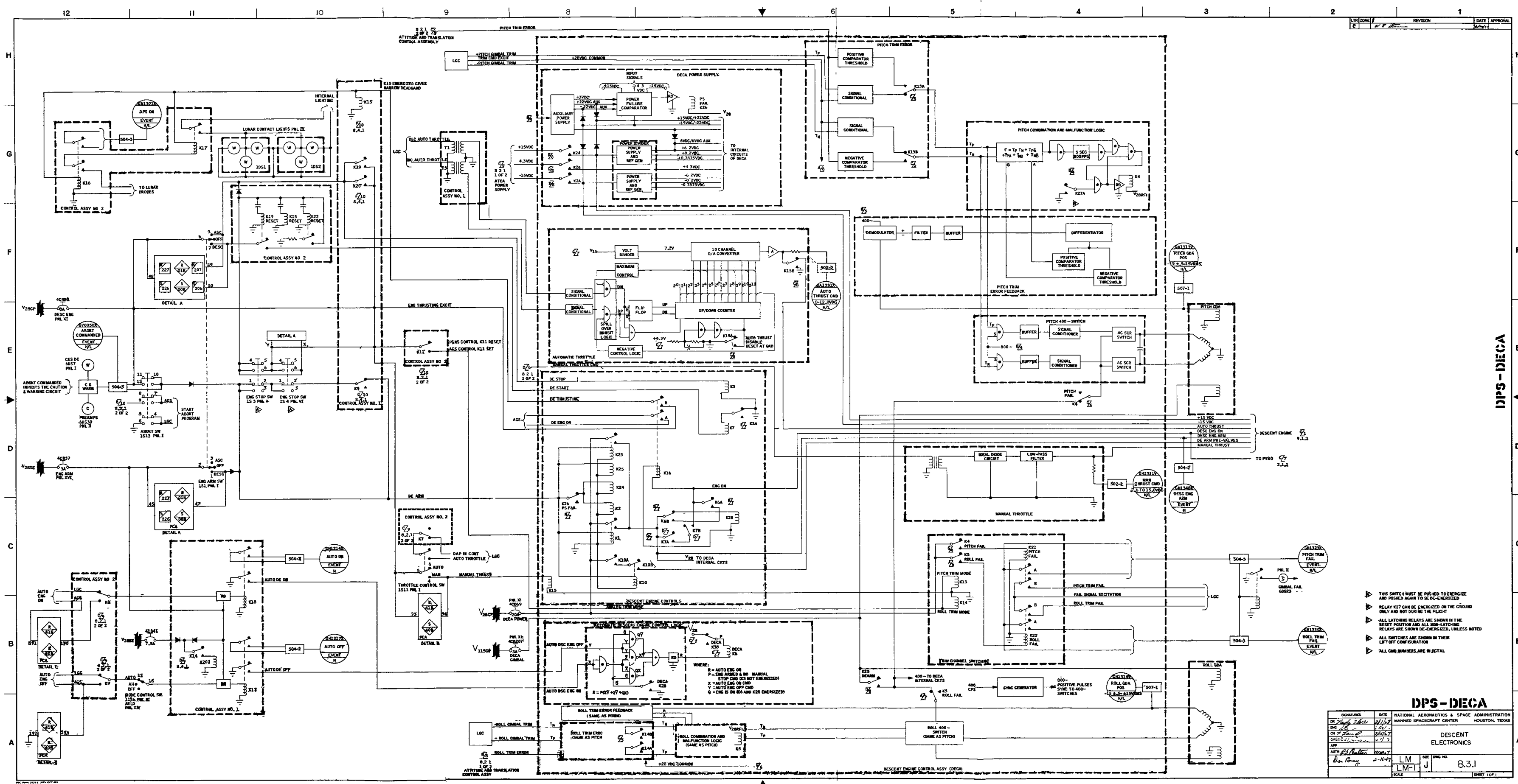


- ▶ ALL LATCHING RELAY CONTACTS ARE SHOWN IN THE RESET POSITION AND ALL NON-LATCHING RELAY CONTACTS ARE SHOWN DE-ENERGIZED UNLESS OTHERWISE NOTED
- ▶ ALL SWITCHES ARE SHOWN IN THEIR UP/OFF CONFIGURATION
- ▶ LCC WARNINGS OR DIS WARNINGS WILL SET RELAY SCRAM WHICH AUTOMATICALLY SWITCHES FROM POS TO ACS. SAME FUNCTION AS SCRAM 4000, REFERENCE DWG 13.1.1.1 ZONE A-4

REV		DATE		BY		CHKD		APP'D	
1	1	1	1	1	1	1	1	1	1
<b>ATCA</b> NATIONAL AERONAUTICS & SPACE ADMINISTRATION MANAGED SPACECRAFT CENTER HOUSTON, TEXAS <b>CONTROL ATTITUDE AND TRANSLATIVE ELECTRONICS</b>									
DR. H. J. B... DR. J. R. ... DR. C. ... DR. ... DR. ...								8.2.1 LM-1	

ATCA

8.2.1  
LM-1  
PAGE 2 OF 2



- ▶ THIS SWITCH MUST BE PUSHED TO ENERGIZE AND PUSHED AGAIN TO BE DE-ENERGIZED
- ▶ RELAY K27 CAN BE ENERGIZED ON THE GROUND ONLY AND NOT DURING THE FLIGHT
- ▶ ALL LATCHING RELAYS ARE SHOWN IN THE RESET POSITION AND ALL NON-LATCHING RELAYS ARE SHOWN DE-ENERGIZED, UNLESS NOTED
- ▶ ALL SWITCHES ARE SHOWN IN THEIR LEFT-OFF CONFIGURATION
- ▶ ALL CMD SWITCHES ARE IN ACTUAL

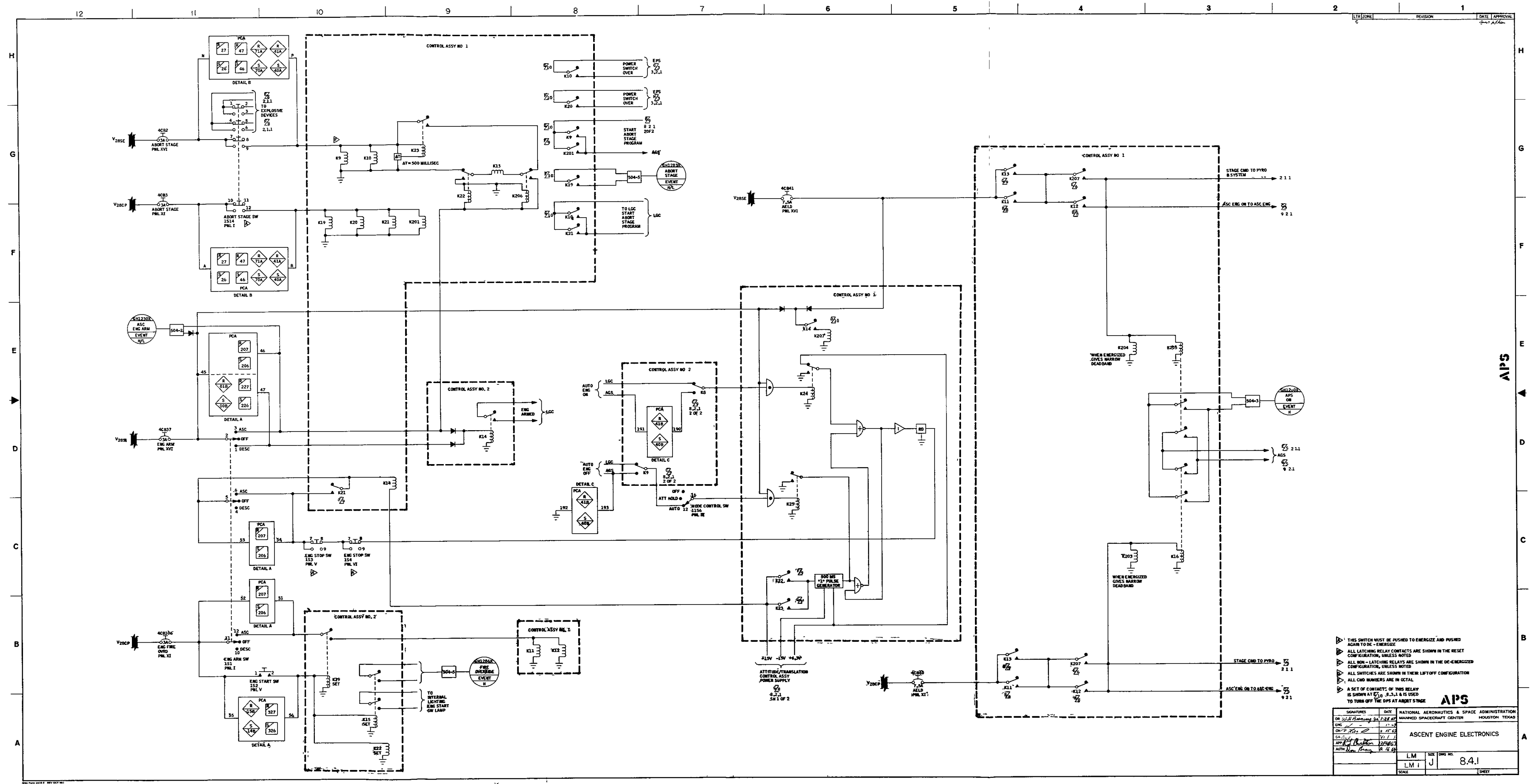
**DECA - DECA**

REVISIONS		DATE	NATIONAL AERONAUTICS & SPACE ADMINISTRATION MANNED SPACECRAFT CENTER HOUSTON, TEXAS
1	REVISED	11/17	DESIGNER: J. H. ...
2	REVISED	11/17	ENGINEER: J. H. ...
3	REVISED	11/17	CHECKER: J. H. ...
4	REVISED	11/17	APP. J. H. ...
5	REVISED	11/17	APP. J. H. ...
6	REVISED	11/17	APP. J. H. ...

SCALE	REV. NO.	DATE	BY	CHKD.	APPROVED
LM-1	J	8.3.1	J. H. ...	J. H. ...	J. H. ...

SHEET 1 OF 1



- ⚠ THIS SWITCH MUST BE PUSHED TO EMERGE AND PUSHED AGAIN TO RE-EMERGE
- ⚠ ALL LATCHING RELAY CONTACTS ARE SHOWN IN THE RESET CONFIGURATION, UNLESS NOTED
- ⚠ ALL NON-LATCHING RELAYS ARE SHOWN IN THE DE-ENERGIZED CONFIGURATION, UNLESS NOTED
- ⚠ ALL SWITCHES ARE SHOWN IN THEIR LIFT-OFF CONFIGURATION
- ⚠ ALL CMD NUMBERS ARE IN OCTAL
- ⚠ A SET OF CONTACTS OF THIS RELAY IS SHOWN AT 9 2.1 & IS USED TO TURN OFF THE DPS AT ABORT STAGE

SIGNATURES		DATE	NATIONAL AERONAUTICS & SPACE ADMINISTRATION MANNED SPACECRAFT CENTER HOUSTON, TEXAS	
OR	DATE	DATE		
ENG	12/1/68	12/1/68		
CH-P	12/1/68	12/1/68		
CA	12/1/68	12/1/68		
APP'D	12/1/68	12/1/68		
AUTH	12/1/68	12/1/68		

**ASCENT ENGINE ELECTRONICS**

LM	SIZE	DRWG NO.
LM I	J	84.1
SCALE		SHEET

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SECTION 9  
PROPULSION

LM-1  
REV C

9.1 REACTION CONTROL SYSTEM

9.1.1 General Description

The Reaction Control Subsystem (RCS) is composed of two parallel, independent systems ("A" system and "B" system). Each system contains identical components with the associated valves and plumbing necessary to deliver the propellants to the thrust chamber assemblies. Normally both systems are operated together, but the arrangement of the engines is such that complete rotational control in all axes is possible despite a failure of either system.

R-B

R-C

Helium pressurization is accomplished by an electrical RCS pressurization command to two parallel squib actuated isolation valves in each system.

Downstream are two series helium regulators which reduce the helium supply pressure for propellant tank pressurization. In normal operation, the upstream regulator is in control and reduces the pressure to the proper level, while the downstream regulator senses a demand and remains open as the sensed demand is below the setting.

R-B

Normally open propellant shutoff valves, located just downstream of the propellant tanks in each system, are capable of isolating the propellant tanks of either system in case of an upstream malfunction or depletion of propellants. These valves are operated in pairs (fuel and oxidizer) for each system by prime commands from the LGC, commands from the PRA, or RTC commands from the ground.

Normally closed fuel and oxidizer manifold crossfeed valves exist, which can be opened to supply either system's propellants to all sixteen thrusters in case of a failed system. These two valves are operated as a pair by prime commands from the LGC or commands from the PRA. No RTC control exists for the crossfeed valves.

In addition, normally closed ascent feed valves, connecting ascent propellants to both systems fuel and oxidizer manifolds independently, may be opened to conserve RCS propellants. It should be emphasized that ascent propellants may be utilized in the RCS thrusters only during positive "X" axis acceleration. These ascent interconnect feed valves

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are operated in pairs for each system by prime programmed commands from the LGC or by commands from the PRA. No RTC control is available for these valves. Also, during ascent feed operation, the main shutoff valves of the appropriate systems are closed and the crossfeed valves opened.

Normally open isolation valves exist in the propellant lines feeding thruster pairs, allowing the isolation of a thruster pair containing a failed open thruster. Through an onboard failure detection logic, the LGC senses an electrically failed thruster and automatically closes the appropriate isolation valves to isolate the failed pair. No PRA or RTC control of this function is available. The LGC is also capable of controlling the vehicle's attitude and translation in the X-axis only without using the isolated thruster pair.

R-C

Each of the four RCS engine clusters consists of four rocket engine assemblies, each delivering approximately 100 pounds thrust. The engine assembly consists of an oxidizer and fuel solenoid valves, injector head, and combustion chamber. Each solenoid valve is a fail safe (in closed position) electrical solenoid operated valve. The fuel valve provides a two millisecond fuel lag, which with the injector premix igniter cup insures smooth engine start in the pulse mode. The injector has eight unlike impinging doublets for main chamber ignition. Chamber cooling is provided by radiation and internal film cooling from eight fuel singlets along the injector outer periphery.

R-B

R-C

The RCS performs the following functions:

- A. Provides small thrust impulses to stabilize the LM during descent and ascent burns.
- B. Provides necessary thrust impulses to control the vehicle attitude and translation during all maneuvers.
- C. Provides necessary thrust impulses to accomplish separation maneuvers.
- D. Provides necessary thrust impulses to accomplish accelerations for ullage settling for the descent and ascent propellant tanks when required.



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LM-1  
REV C

The RCS is capable of operating in either a pulsed or a steady-state mode and is controllable by the LGC, or by a manual Attitude Controller Assembly (ACA) during manned flights. In "Normal" mode, attitude and translational maneuvers are accomplished by commands from the LGC of variable frequency and pulse width to the primary coils of the engines. In "Pulsed" mode, the LGC sends one pulse for each out-of-detent movement of the ACA to the primary coils and in "Direct" mode, the ACA sends commands directly to the secondary coils of the RCS engines.

R-B

R-C

R-B

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## 9.2 DESCENT PROPULSION SYSTEM (DPS)

### 9.2.1 General

- A. The descent engine is a throttleable engine over a 10:1 range and develops 10,500 pounds of thrust in a vacuum at full throttle and 1,050 pounds minimum thrust. It consists primarily of an ablative lined thrust chamber with a crushable, radiation cooled nozzle extension; a variable area injector; a pair of flow control valves; four electromechanical flow control actuators; and eight propellant shutoff valves. It is mounted in the center compartment of the descent stage and is pivoted at the throat of the combustion chamber on a gimbal ring that is an integral portion of the engine assembly. The ring is suspended in the structure, pivoted in a line 90 degrees opposite to the engine pivots, so that the engine is capable of being gimballed  $\pm 6$  degrees in any direction by means of vehicle mounted gimbal drive actuators. R-B
- The mechanical throttling scheme utilizes variable-area, cavitating venturi flow control valves mechanically linked to a variable area injector in order to separate propellant flow control and propellant injector functions so that each may be optimized without compromising the other, and to insure that propellant flow rates are made insensitive to downstream pressure variations in the injector and combustion chamber. At maximum thrust, operation is conventional. At approximately 70 percent thrust, cavitation commences in the valve throats. From this level down to minimum thrust, the valve functions as a cavitating venturi. As thrust is reduced, the actuator reduces the flow at the control valves and moves the injector sleeve to reduce the injector apertures. R-C
- B. The engine is activated and throttled by the LM Guidance Computer, which starts a sequence of events resulting in firing squibs and igniting the engine. R-B

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LM-1  
REV C

The propellants are nitrogen tetroxide and a 50/50 blend of Unsymmetrical Dimethyl Hydrazine (UDMH) and hydrazine called Aerozine 50. The freezing point of nitrogen tetroxide at standard conditions is 12°F; the boiling point is 70°F. The freezing point of Aerozine 50 at standard pressure is 21°F and the boiling point is 170°F.

R-B

### 9.2.2 Helium Storage Tank

Supercritical helium is stored in a double walled cryogenic storage container. It consists of an inner spherical tank with an outer jacket; the void between the tank and its jacket is filled with aluminized mylar insulation and evacuated to minimize heat transfer. The material used for the tank is titanium. The tank has associated fill and vent ports and a pressure relief device consisting of two burst discs, in series. Inside the inner tank is a helium/helium heat exchanger constructed of titanium tubing.

R-C

### 9.2.3 The Propellant Shutoff Valves

The shutoff valves are fuel pressure-actuated ball valves, fuel is introduced to the valve actuators through solenoid operated pilot valves, all of which are energized simultaneously during engine startup. During the start, the solenoids unseat the caged balls from the actuator inlet ports and seat them against the overboard vent ports. Fuel enters the actuator cavities; the actuator pistons connected to rack and pinion linkages twist the ball valves 90 degrees to the open position, permitting flow to the injector. The series parallel redundancy in the valve arrangement provides for positive start and cutoff. During shutdown, the solenoids are de-energized, opening the vent ports. The spring loaded actuators close the shutoff valves and residual actuating fuel is vented overboard into space. A mismatch circuitry is tied in with this system. It takes the output of eight magnetoswitches and puts them through a summing network. The output of this network is then telemetered to ground indicating any disparity in valve positions.

R-B

R-C

R-B

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#### 9.2.4 Propellant Quantity Gaging System (PQGS)

A capacitance type quantity gaging system is used to provide propellant quantity information via telemetry to the ground during positive "G" conditions. The PQGS will be a continuous gaging system with capabilities for gaging propellants in each descent stage tank between 95 percent of propellants remaining and one inch of the tank bottom. The accuracy of the system between 95 percent and 25 percent of the propellants remaining is  $\pm 1.0$  percent of full tank capacity. Between 25 percent of propellants remaining and one inch of the tank bottom, the system accuracy is  $\pm 0.5$  percent of full tank capacity. Due to component heating in a vacuum, the system is constrained to 15 minutes of operation at any one time, however, the total operating life is 5000 hours. The LGC is programed to automatically turn the PQGS ON and OFF before and after each burn. In addition the PQGS will provide a discrete signal when the propellant level is a predetermined distance from the tank bottom, nominally corresponding to 120 seconds engine operating time remaining at 25 percent thrust.

R-B

R-C

#### 9.2.5 Fuel/Helium Heat Exchanger

This heat exchanger absorbs heat from the engine fuel which has been circulated from the fuel tanks directly to the heat exchanger, before its ultimate delivery to the engine. It is a two pass heat exchanger. Helium from the storage tank absorbs heat from the fuel on the first pass, then flows back to the helium/helium heat exchanger inside of the storage tank, and then is reheated on the second pass.

R-B

R-C

#### 9.2.6 Thrust Chamber

The thrust chamber consists of a composite ablative cooled nozzle extension (area ratio of 16:1), a crushable radiation cooled nozzle extension (area ratio of 49:1), and a gimbal ring assembly. The ablative components are encased in a continuous titanium shell and jacketed in a stainless steel foil/glass wool composite thermal blanket. The radiation cooled nozzle extension is made from columbium. The nozzle extension is flanged to the titanium chamber shell. The gimbal assembly is located at the chamber throat plane and provides a  $\pm 6$  degree gimbal of the

R-B

R-C

R-B

R-C

R-C

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thrust vector during flight. The assembly is manufactured from aluminum alloy, except for the bearings, which are made of high strength steel.

#### 9.2.7 Flow Control Valves

Flow control valves are non-redundant venturis with movable pintle sleeves. Engine throttling is initiated by an electrical signal to the throttle actuator commanding an increase or decrease in engine thrust. Operation of the throttle actuator drives the linkage cross beam to a new position, thus repositioning the pintles in the flow control valves. This axial movement of the pintles results in decreasing or increasing the pintle flow areas the precise amounts to control propellant weight flow rate and thrust.

#### 9.2.8 Throttle Actuator

The throttle actuator is an electromechanical linear servoactuator powered by redundant motors. It is located between the fuel and oxidizer flow control valves on the engine head end. The output shaft of the actuator is attached to the throttle linkage. Three torque motors drive the jack screw. The actuator is designed to operate within specification using two motors, or at a reduced rate using only one. The actuator case is hermetically sealed to prevent cold welding in a vacuum environment. Although the actuator could operate without lubrication, a compound with a known off-gasing rate is included to maintain a small positive pressure if the actuator case leaks. Performance redundancy is provided by designing each of the three separate servo channels to have equal output performance. For a null-type or inoperative failure, two separate servo channels failing can be tolerated. The two malfunctioning motors will be driven along with the load by the one operating motor. In the case of a saturated or hardover-type failure of one servo channel, the load is effectively increased by the two operating motors which have the capability of overriding the malfunction and providing the required output performance.

R-B

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LM-1  
REV C

### 9.2.9 Pressure Regulators

There are two regulators, one in each parallel leg of the system, the primary leg being normally open and providing helium at 245 psia downstream. Each leg has a solenoid valve upstream of the regulator which is controlled from the cabin or maybe commanded from the ground. The secondary leg is normally closed (but may be opened as required). It also provides 245 psi downstream.

### 9.2.10 Quadcheck Valves

There are two such valves, one in each of the lines leading to the propellant tanks. They are made up of four check valves arranged in a series - parallel configuration, the primary purpose being to prevent propellant vapors from mixing in the upstream manifold.

R-B

### 9.2.11 Propellant Tanks (Titanium)

There are four propellant tanks, two each for oxidizer and fuel. They are interconnected on top and on bottom, within each system to insure equal usage and pressure. Each tank has a volume of 63 cubic feet.

### 9.2.12 Supercritical Helium

The helium pressure timeline begins with the loading of the supercritical helium, which is completed at about 15 hours before lift-off. At completion of loading the pressure is approximately 550 psia. Due to the heat transfer from the surroundings, the helium pressure increases at the rate of approximately 10 psi per hour until the descent engine is fired. During low level thrust, the pressure builds up at a rate of 200 psi per minute. Subsequently, after engine shutdown, the pressure rises sharply at about 50 psi per hour for 1 hour, after which time, the pressure again increases at the rate of 10 psi per hour.

R-C

The first descent burn pressure should start at about 750 psia and end with a pressure of about 900 psia. The second descent burn should start at about 1000 psia and reach a peak of about 1400 psia before the pressure starts decreasing. Too high a pressure (1870 to 1968 psia) could rupture the burst disc, thus terminating pressurization which results in degraded "limited blowdown" mode.

R-B

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an engine stop command automatically or the engine is disarmed by RTC.

2. Subsequent APS burns.

At the end of the FITH the system is fully pressurized and in operational standby mode. The engine may be ignited by either a normal programmed LGC fire command sequence or RTC fire override command. Either method fires the engine by opening the isolation and actuator isolation valves. Fuel pressure operates the actuator mechanism which opens both the oxidizer and fuel shutoff valves and allows propellant flow to the thrust chamber. Shutdown of the engine is accomplished by LGC command or RTC engine stop override.

9.3.2 Notes

- A. Pressure Reducing Regulators. This regulating system uses two regulators in a parallel arrangement, each regulator housing contains dual regulators in series. This arrangement provides the overall regulation system with added redundancy. Each regulator contains a pilot valve and seat assembly which modulates inlet pressure to control the opening of a main poppet valve and seat assembly, and reduces the upstream pressure to that required to provide correct propellant tank pressurization. Minimum operating inlet pressure is 500 psi for rated output. Below 500 psi the regulated output is  $179 \pm 1$  psi. R-B
- B. Propellant Shutoff Valves. The propellant shutoff valves are a series parallel arrangement of eight ball valves, four each, oxidizer and fuel. This arrangement is to insure continued operation of the engine in the event of valve failure. The valves are operated by a piston actuator assembly which is controlled by fuel pressure through solenoid isolation and actuator isolation valves. R-C

TABLE 9-1 CAPABILITIES AND LIMITATIONS APS, DPS, AND RCS

	APS	DPS	RCS	
<u>HELIUM SOURCE PRESS.</u>				
VOLUME	5800 IN <sup>3</sup>	5.87 FT <sup>3</sup>	920 IN <sup>3</sup>	R-B
PRESSURES				
BURST	5250 PSI	3420 PSI	7000 PSI	
PROOF	4660 PSI	2045 PSI	4650 PSI	
NOMINAL LIFTOFF PRESS.	3050 PSI	550 PSI	3050 PSI	R-C
<u>REGULATORS</u>				
CONFIGURATION	SERIES/PARALLEL	PARALLEL	SERIES	
CLASS I				
PRIMARY				
SETTING	184±4 PSI	245± <sup>3</sup> / <sub>2</sub> PSI	179±2 PSI	
LOCKUP	192±3 PSI	250± <sup>3</sup> / <sub>2</sub> PSI	188 PSI	
SECONDARY				
SETTING	190±4 PSI		185±2 PSI	R-B
LOCKUP	197±3 PSI		194 PSI	
CLASS II				
PRIMARY				
SETTING	176±4 PSI	245± <sup>3</sup> / <sub>2</sub> PSI		
LOCKUP	183±3 PSI	250± <sup>3</sup> / <sub>2</sub> PSI		
SECONDARY				
SETTING	182±4 PSI			
LOCKUP	189±3 PSI			
MINIMUM OPERATING PRESSURE	500 PSI	400 PSI	400 PSI	
<u>QUAD CHECK VALVES</u>				
PRESSURE				
BURST	810 PSI	810 PSI	750 PSI	
PROOF	540 PSI	540 PSI	500 PSI	
ΔP DROP	5 PSI	5 PSI	4±1 PSI	
CRACKING ΔP	2±5 PSI	2±.5 PSI	2±.5 PSI	



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TABLE 9-1 CAPABILITIES AND LIMITATIONS APS, DPS AND RCS (Cont'd.)

	APS	DPS	RCS	
<u>COMPATIBILITY VALVES</u>				
	SERIES/PARALLEL	SERIES		N/A
ACTUATION TIMES				
OPEN	0.1 SEC	0.1 SEC		N/A
PRESSURE DROP				
PROOF	0 PSI	0 PSI		N/A
BURST	540 PSI	540 PSI		N/A
	810 PSI	810 PSI		N/A
<u>TANK ASSEMBLY</u>				
BURST DISC RUPTURE	238±12 PSID	288±20 PSID	234±12 PSID	
BLEED VALVE				
CRACK	0 PSI	0 PSI	0 PSI	
RESEAT	20-80 PSI	20 PSI	80 PSI	
RELIEF VALVE				
CRACK	225 PSI	260 PSI	238±12 PSI	
FULL FLOW	250 PSI	275 PSI		
RESEAT	225 PSI	254 PSI	220 PSI	R-B
<u>PROP TANKS</u>				
VOLUME				
FUEL	34 FT <sup>3</sup>	126 FT <sup>3</sup>	1.91 FT <sup>3</sup>	R-C
OX	34 FT <sup>3</sup>	126 FT <sup>3</sup>	2.38 FT <sup>3</sup>	
PRESSURES				
BURST	375 PSI	405 PSI	375 PSI	
PROOF	333 PSI	358 PSI	333 PSI	
<u>FUEL HELIUM HEAT EXCHANGER</u>				
PRESSURES	N/A			N/A
PROOF FUEL	N/A	540 PSI		N/A
HELIUM	N/A	2200 PSI		N/A
BURST FUEL	N/A	810 PSI		N/A
HELIUM	N/A	3300 PSI		N/A
<u>MAIN SHUTOFF, TCA ISOL, X FEED,</u>				
<u>APS INNCT VALVES</u>				
ACTUATION TIMES	N/A	N/A		
OPEN	N/A	N/A		0.25 SEC
CLOSE	N/A	N/A		0.25 SEC

Table 9-1 CAPABILITIES AND LIMITATIONS APS, DPS, AND RCS (Cont'd)

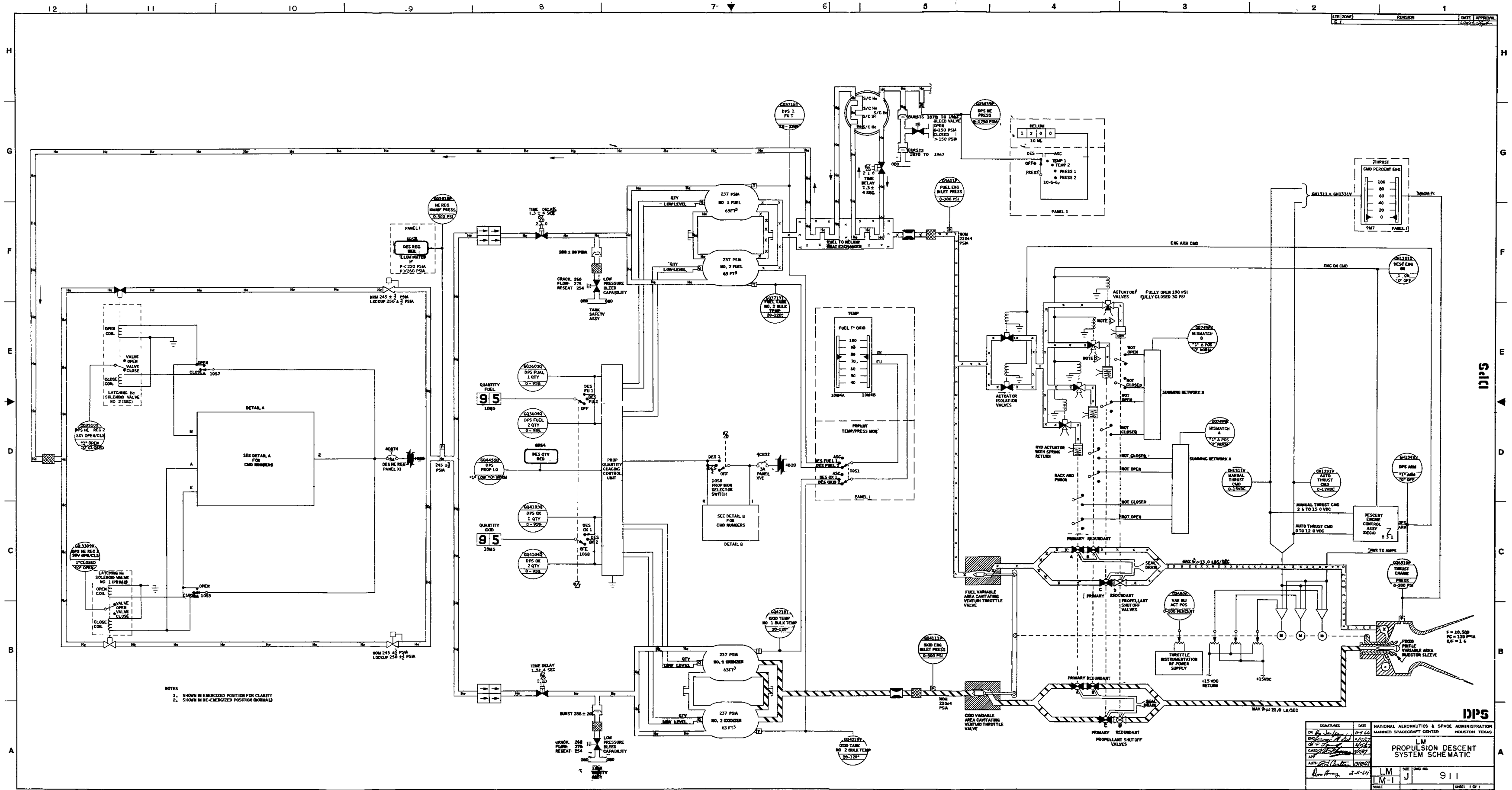
	APS	DPS	RCS
ACTUATION VOLTAGE			
MAX	N/A	N/A	32.0 VDC
MIN	N/A	N/A	18.0 VDC
PRESSURES	N/A	N/A	
PROOF	N/A	N/A	360 PSI
BURST	N/A	N/A	1050 PSI
DROP	N/A	N/A	2.0±.25 PSI
<u>ACTUATOR ISOLATION VALVES</u>			
ACTUATION TIMES			
OPEN	0.03 SEC	.03 SEC	N/A
CLOSE	0.03 SEC	0.03 SEC	N/A
ACTUATION VOLTAGE			
MAX	32V	32V	N/A
MIN	21V	21V	N/A
PRESSURES			
BURST	1350 PSI	750 PSI	N/A
PROOF	500 PSI	500 PSI	N/A
<u>PROPELLANT SHUTOFF VALVES</u>			
ACTUATION VOLTAGE			
MAX	32V	32V	N/A
MIN	21V	21.5V	N/A
PRESSURES			
OPEN			
CRACK	80 PSI	60 PSI	N/A
FULL OPEN	120 PSI	100 PSI	N/A
CLOSE			
START	70 PSI	90 PSI	N/A
FULL CLOSE	30 PSI	30 PSI	N/A
DROP			N/A
<u>ENGINES</u>			
NOMINAL THRUST	3500	10500-1050	100
COOLING	FILM & ABLATIVE COOLING	FILM & RADIATION	FILM & RADIATION
LIFE	<u>460</u> SEC	960 SEC	500 SEC PULSE 500 SEC STEADY STATE
INJECTOR TYPE	TRIPLET ORIFICES (2 OX & 1 FUEL) IN A GRID PATTERN ON INJECTOR FACE. ON OUTER PERIPHERY ORIFICES ARE DOUB-LETS (1 OX & 1 FU) TO PROVIDE REDUCED TEMP BARRIER AT ABLATIVE CHAMBER WALL	VARIABLE AREA	8 FUEL FOR COOL- ing 8 ON 8 FOR MAIN CHAMBER 1 ON 1 FOR PRE-IGNITER

R  
-C  
  
R-  
B  
  
  
  
R-  
C

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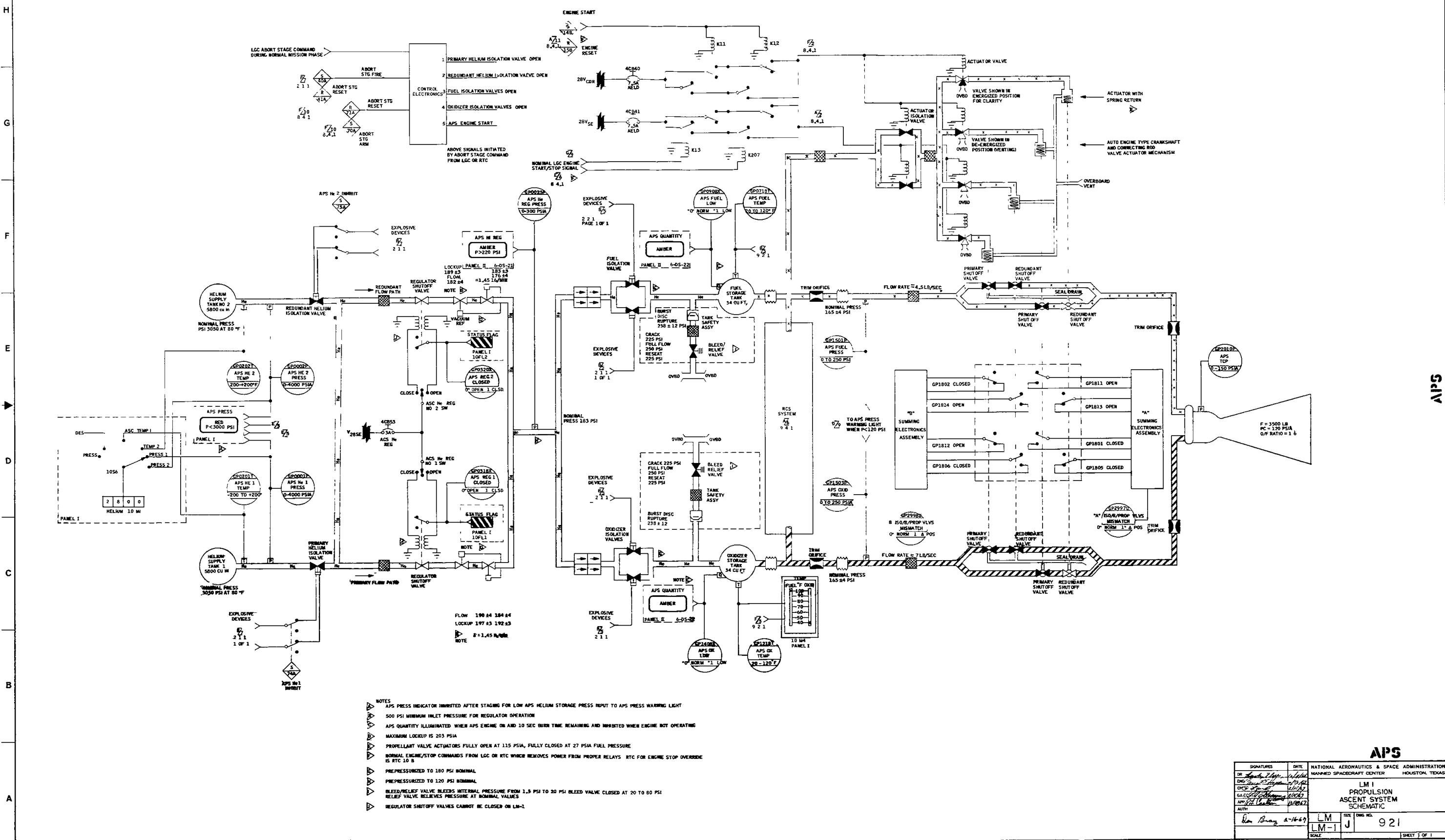
TABLE 9-1 CAPABILITIES AND LIMITATIONS APS, DPS, AND RCS (Concluded)

	APS	DPS	RCS	
O/F RATIO	1.6/1	1.6/1	2.0/1	
FLOW RATES				
OXID (lb/SEC)	7.0	21 (MAX)	0.24	R-B
FUEL (lb/SEC)	4.3	13 (MAX)	0.12	
THRUST CHAMBER PRESSURE	120 PSI	110 PSI (MAX)	96 PSI	R-C
MINIMUM OPERATING TIME	1.0 SEC	N/A	0.013 SEC	



NOTES  
 1. SHOWN IN ENERGIZED POSITION FOR CLARITY  
 2. SHOWN IN DE-ENERGIZED POSITION OTHERWISE

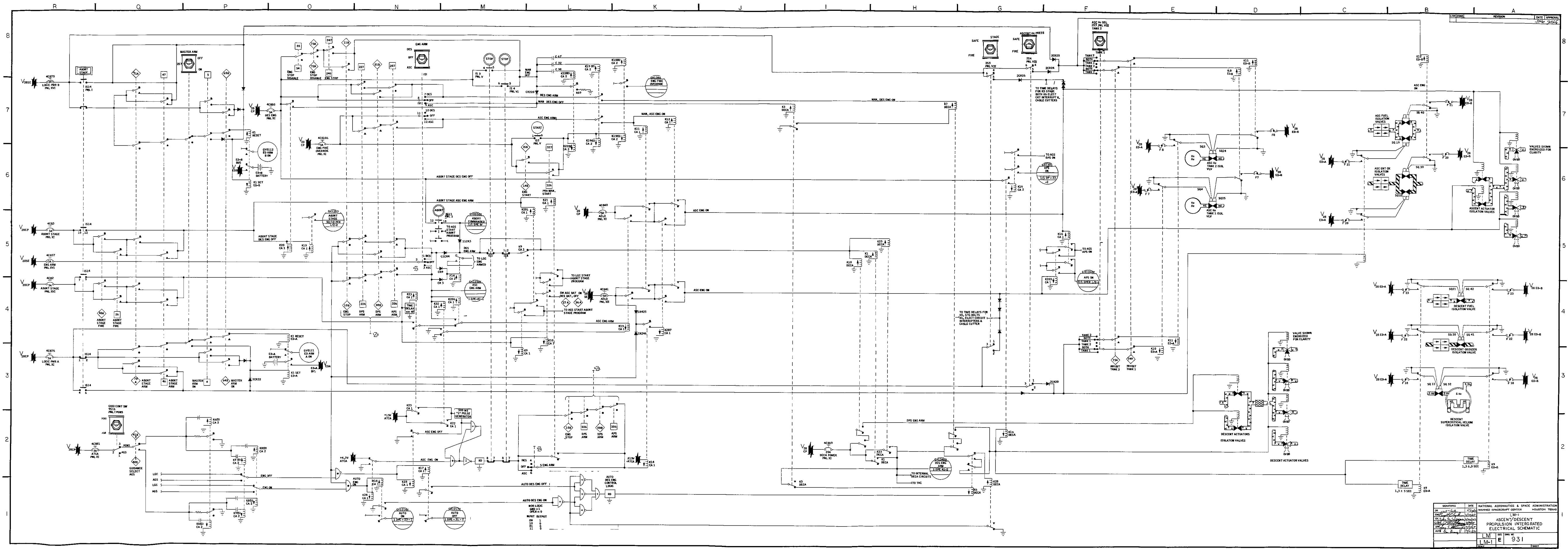
SIGNATURES		DATE	NATIONAL AERONAUTICS & SPACE ADMINISTRATION MANNED SPACECRAFT CENTER HOUSTON, TEXAS	
DR	<i>[Signature]</i>	10-1-68	LM PROPULSION DESCENT SYSTEM SCHEMATIC	
ENGR	<i>[Signature]</i>	10-1-68	LM-1	911
CHKD	<i>[Signature]</i>	10-1-68	SCALE	SWGT 1 OF 1
APP	<i>[Signature]</i>	10-1-68		
AUT	<i>[Signature]</i>	10-1-68		



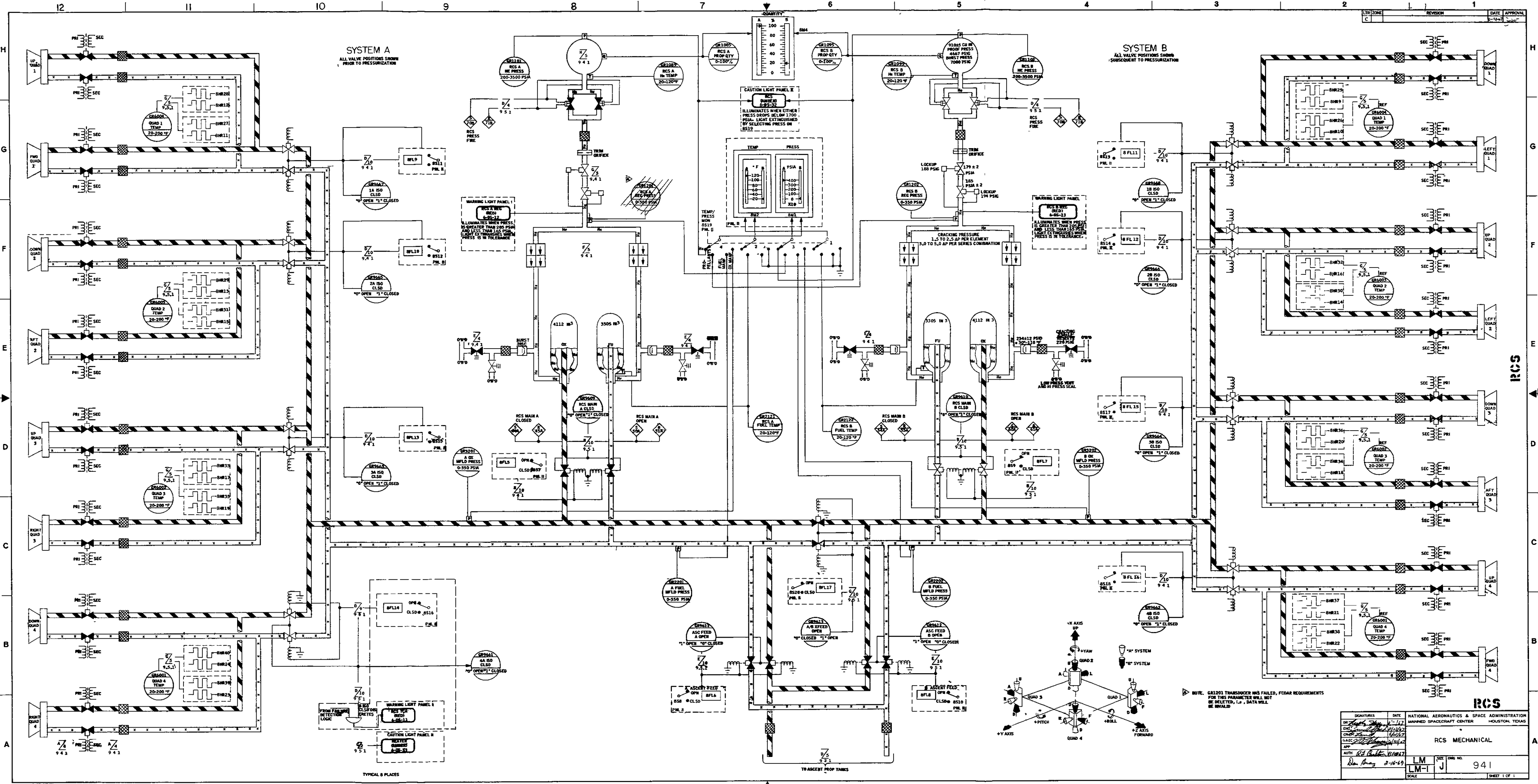
- NOTES
- ▶ APS PRESS INDICATOR INHIBITED AFTER STAGING FOR LOW APS HELIUM STORAGE PRESS INPUT TO APS PRESS WARNING LIGHT
  - ▶ 500 PSI MINIMUM INLET PRESSURE FOR REGULATOR OPERATION
  - ▶ APS QUANTITY ILLUMINATED WHEN APS ENGINE ON AND 10 SEC BURN TIME REMAINING AND INHIBITED WHEN ENGINE NOT OPERATING
  - ▶ MAXIMUM LOCKUP IS 203 PSIA
  - ▶ PROPELLANT VALVE ACTUATORS FULLY OPEN AT 115 PSIA, FULLY CLOSED AT 27 PSIA FUEL PRESSURE
  - ▶ NORMAL ENGINE/STOP COMMANDS FROM LGC OR RTC WHICH REMOVES POWER FROM PROPER RELAYS. RTC FOR ENGINE STOP OVERRIDE IS RTC 10 B
  - ▶ PREPRESSURIZED TO 180 PSI NOMINAL
  - ▶ PREPRESSURIZED TO 120 PSI NOMINAL
  - ▶ BLEED/RELIEF VALVE BLEEDS INTERNAL PRESSURE FROM 1.5 PSI TO 20 PSI BLEED VALVE CLOSED AT 20 TO 60 PSI
  - ▶ RELIEF VALVE RELIEVES PRESSURE AT NOMINAL VALUES
  - ▶ REGULATOR SHUTOFF VALVES CANNOT BE CLOSED ON LM-1

SIGNATURES		DATE	NATIONAL AERONAUTICS & SPACE ADMINISTRATION	
DR	W. J. ...	11/16/67	MANNED SPACECRAFT CENTER HOUSTON, TEXAS	
DES	...	11/16/67	LM-1 PROPULSION ASCENT SYSTEM SCHEMATIC	
CHK	...	11/16/67		
APP	...	11/16/67		
AUTH		W. J. ...	LM-1	921
			SCALE	SHEET 1 OF 1

APS



DATE	1/2/62	REVISION	1
BY	W. J. B. / J. W. B.	CHKD	W. J. B. / J. W. B.
APP'D		DATE	
NATIONAL AERONAUTICS & SPACE ADMINISTRATION MANNED SPACECRAFT CENTER HOUSTON, TEXAS			
LM-1 ASCENT/DESCENT PROPELLSION INTEGRATED ELECTRICAL SCHEMATIC			
LM-1	931		



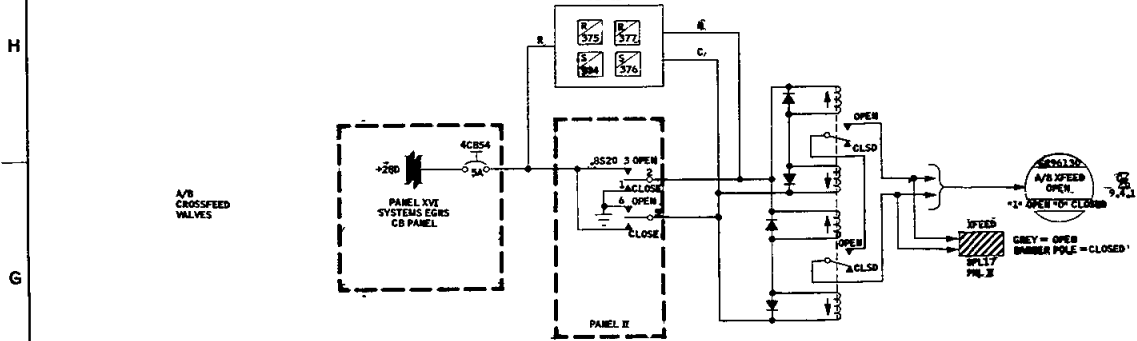
SYSTEM A  
ALL VALVE POSITIONS SHOWN  
PRIOR TO PRESSURIZATION

SYSTEM B  
ALL VALVE POSITIONS SHOWN  
SUBSEQUENT TO PRESSURIZATION

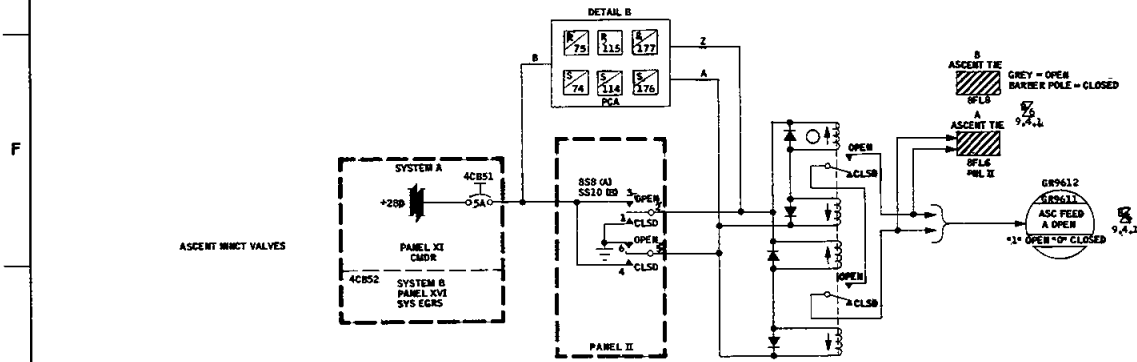
TYPICAL B PLACES

NOTE: G1201 TRANSDUCER HAS FAILED, FCDA REQUIREMENTS FOR THIS PARAMETER WILL NOT BE MET. I.e., DATA WILL BE INVALID

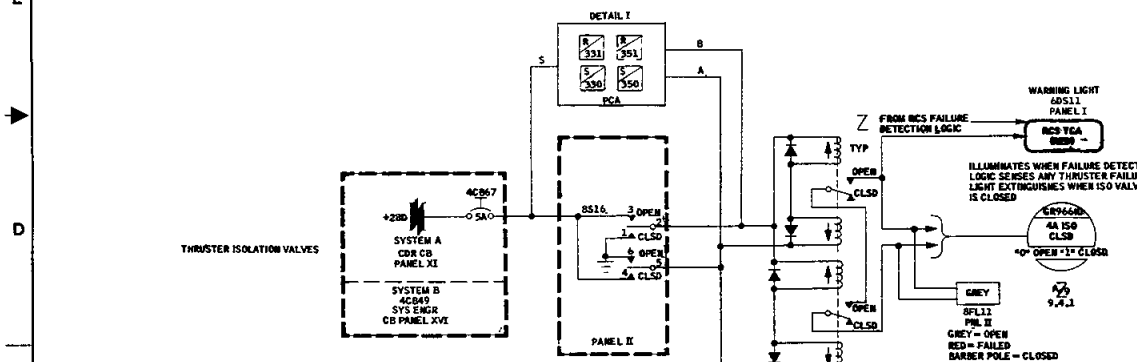
SIGNATURES		DATE	NATIONAL AERONAUTICS & SPACE ADMINISTRATION
DATE		1-17	MANNED SPACECRAFT CENTER HOUSTON, TEXAS
APP		2-18-69	
TITLE			RCS MECHANICAL
SCALE	LM-1 J	941	
SHEET 1 OF 1			



OPER	LAMP RELAY	DETAIL CODE
PRM ON	K0825A	374
PRM OFF	K0825A	375
PRM ON	K0826A	376
PRM OFF	K0826A	377

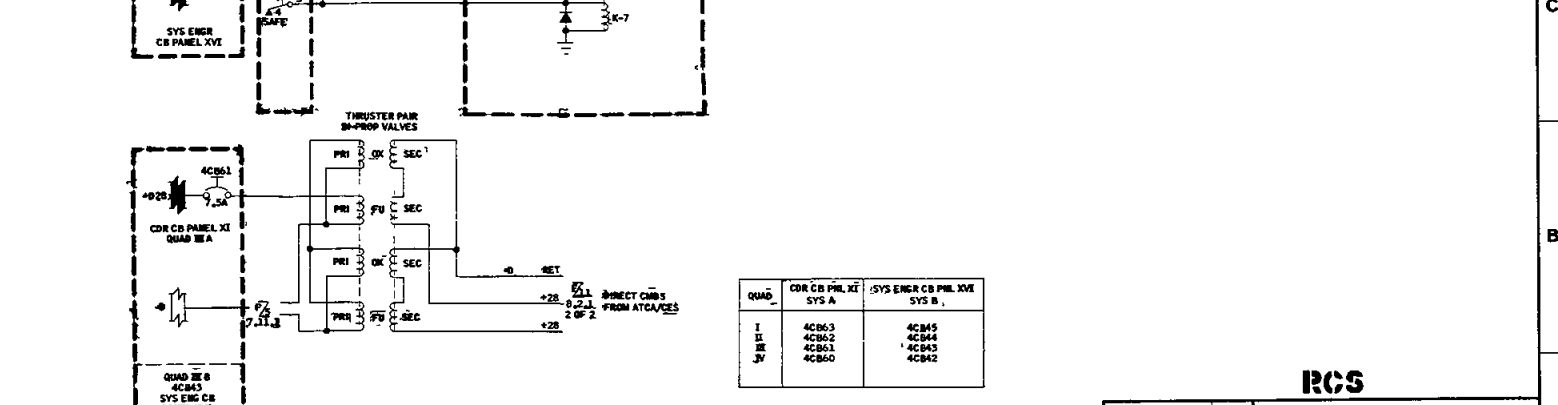
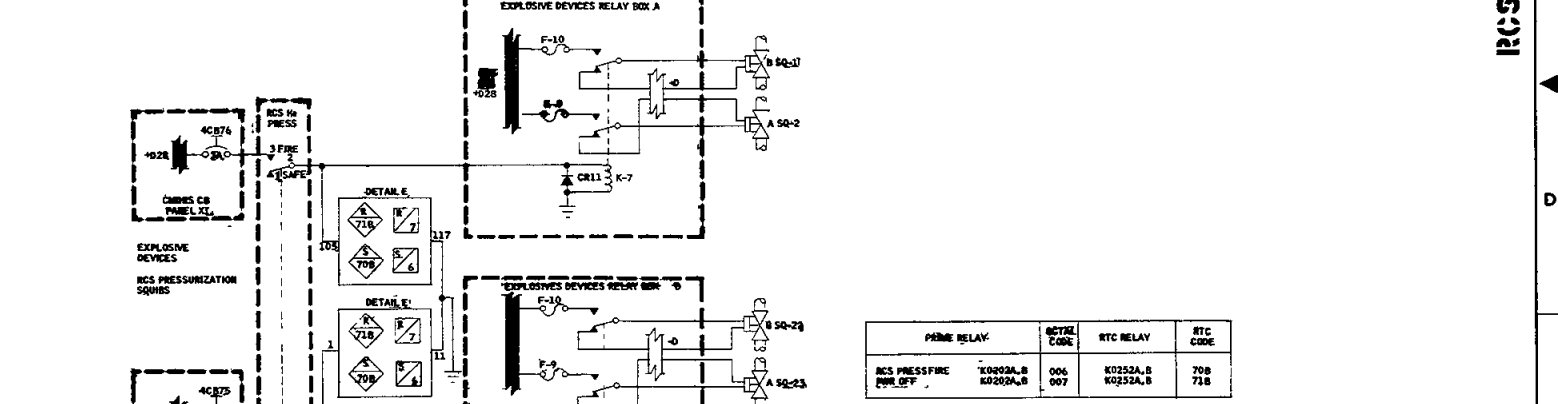
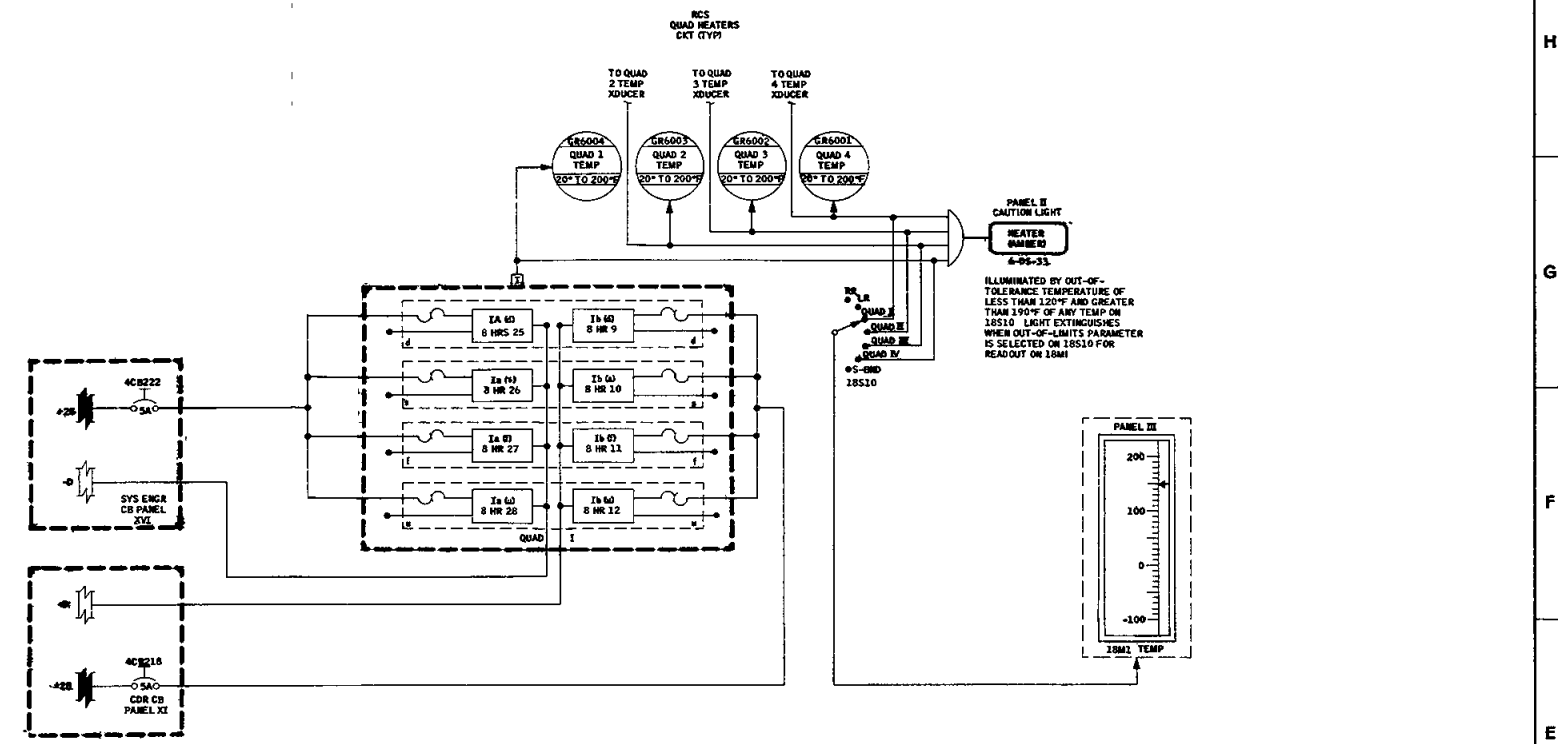


OPER	LAMP RELAY	DETAIL CODE
A OPEN	K0805A	074
A PRM OFF	K0805A	075
B OPEN	K0807A	076
B PRM OFF	K0807A	077
CLOSED	K0806A	114
A PRM OFF	K0806A	115
B CLOSED	K0808A	116
B PRM OFF	K0808A	117



THRUSTERS	PH. E INDICATIONS	FLAGS	CIRCUIT BREAKER LOCATION	OPER	LAMP RELAY	DETAIL CODE	OPER	LAMP RELAY	DETAIL CODE	OPER	LAMP RELAY	DETAIL CODE
1A B AND S	BS13	WFL11	4C849 PNL XVI	K0822A	054	K0822A	154	GR4276X	GR4268X	GR4269U		F
1B B AND F	BS13	WFL9	4C849 PNL XVI	K0822A	055	K0822A	155	GR4276X	GR4268X	GR4269U		F
1B U AND S	BS14	WFL12	4C849 PNL XVI	K0813A	014	K0814A	154	GR4274X	GR4264X	GR4264U		G
1B U AND F	BS12	WFL10	4C847 PNL XI	K0815A	230	K0814A	250	GR4273X	GR4265X	GR4265U		G
1B D AND F	BS17	WFL15	4C849 PNL XVI	K0819A	036	K0820A	156	GR4272X	GR4265X	GR4265U		H
1B U AND S	BS15	WFL13	4C847 PNL XI	K0811A	018	K0812A	156	GR4273X	GR4265X	GR4265U		H
1B D AND F	BS18	WFL16	4C849 PNL XVI	K0817A	270	K0818A	301	GR4270X	GR4262X	GR4262U		I
1B D AND S	BS16	WFL14	4C847 PNL XI	K0809A	350	K0810A	350	GR4269X	GR4261X	GR4261U		I

NAME	LAMP RELAY	DETAIL CODE	RTC RELAYS	RTC CODE
A OPEN	K0801A, B	274	K0851 A, B, C	99A
B OPEN	K0803A, B	275	K0851 A, B, C	51A
C OPEN	K0805A, B	276	K0851 A, B, C	66A
D OPEN	K0807A, B	277	K0851 A, B, C	61A
A CLOSED	K0802A, B	254	K0852 A, B, C	44A
B CLOSED	K0804A, B	255	K0852 A, B, C	45A
C CLOSED	K0806A, B	256	K0854 A, B, C	54A
D CLOSED	K0808A, B	257	K0854 A, B, C	55A



PRM RELAY	DETAIL CODE	RTC RELAY	RTC CODE
RCS PRESSURE	K0803A, B	006	K0252A, B
PRM OFF	K0803A, B	007	K0252A, B
			708
			718

QUAD	CR CB PNL XI	SYS EMER CB PNL XVI	SYS B
I	4C863	4C845	4C845
II	4C862	4C844	4C844
III	4C861	4C843	4C843
IV	4C860	4C842	4C842



\*  
side of the center section, formed by the beams (along the Z and Y axis), house the four main propellant tanks for the Descent Engine.

Additional support and strut assemblies are secured to the main beams forming diagonal bays or quadrants. The entire Descent Stage (top view) is shaped to form a modified octagon aluminum alloy. Outriggers extend from the ends of each of the two pairs of beams, providing for four points of attachment to the Spacecraft LM Adapter (SLA).

- C. The landing gear are removed from LM-1.

R-B

LM-1  
REV C

10.2 SYSTEM DATA

APPROXIMATE VEHICLE WEIGHTS	
SECTION	WEIGHT, LB
LM Ascent Stage (DRY)	4820.9
LM Descent Stage (DRY)	3564.6
RCS Propellants	551.8
DPS Propellants	17374.0
APS Propellants	5019.0
TOTAL	<u>31330.3</u>

R-B

R-C

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A. DCA System Description

The DCA consists of a UHF Receiver, two decoders and interface circuits of the LM Guidance Computer (LGC), Program Reader Assembly (PRA), and Program Coupler Assembly (PCA). The DCA will accept and process six each LGC commands, or two PRA commands, or two Real-Time Commands (RTC's) or two DCA Test Commands per second.

1. The bit configuration for each type of command is as follows:

a. LGC (22 Bits)

<u>1 2 3</u>	<u>4 5 6</u>	<u>7</u>	<u>8 9 10 11 12 13 14 15 16 17 18 19</u>
Vehicle Address	System Address	Synch Bit	Triple Redundant 5-Bit Word
			<u>20 21 22</u>

b. PRA (22 Bits)

<u>1 2 3</u>	<u>4 5 6</u>	<u>7 8 9 10 11 12</u>	<u>13</u>	<u>14</u>	<u>15</u>
Vehicle Address	System Address	Time Word	Clear	Forward Search	Reverse Search

<u>16</u>	<u>17 18 19 20 21 22</u>
Initiate	Fill Bits

c. RTC (12 Bits)

<u>1 2 3</u>	<u>4 5 6</u>	<u>7 8 9 10 11 12</u>
Vehicle Address	System Address	Command Function

d. DCA Test (22 Bits)

<u>1 2 3</u>	<u>4 5 6</u>	<u>7 8 9 10 11 12 13 14 15 16 17 18 19 20 21</u>
Vehicle Address	System Address	Test Word

2. The DCA Test Commands are used to test the operational capability of the DCA. The following test commands are available for the DCA checkout and analysis.

TEST	BIT CONFIGURATION		FUNCTION
	"1-6"	"7-22"	
DCA ENABLE	011 101	000 000 000 000 000 0	ENABLE BOTH DECODERS
DECODER A TEST	011 101	000 100 000 000 000 0	INHIBITS DECODER "A"
DECODER B TEST	011 101	001 000 000 000 000 0	INHIBITS DECODER "B"
DCA SELF TEST	011 101	001 100 000 000 000 0	SELF TESTS BOTH DECODERS

R-B

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R-C

R-B

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LM  
AS-206  
REV B

- 11 Control Electronics
- 13 Communications
- 20 Development Flight Instrumentation

\*

13.2 LM MISSION PROGRAMER (LMP) SYSTEM SCHEMATIC NOTES

A. The MASTER RESET function resets all prime relays except the following:

1. LND Radar (267)
2. C-Band Transponder (Off) (153)
3. Flight Control Auto Enable (3)

R-B

B. The automatic guidance switchover function switches from PGNS to AGS, enables the prime relay matrix to accept PRA commands and put the PRA in the "standby" mode.

C. LM/SLA antenna switchover is an automatic function occurring at LM/SLA separation. Two microswitches on the plus Y outrigger enable the switchover contacts at separation.

R-C

D. LMP Operational Capabilities

1. APS started by LGC/PRA can be stopped by "engine stop override" ground or prime relay command.
2. DPS can be started from ground by descent arm and engine start override.
3. DPS started by ground can be stopped by "engine stop override."
4. APS started by LGC abort stage prime relay cannot be stopped by ground engine stop override. To stop APS in this mode a prime relay master reset or PGNS/AGS - AGS select is required from the ground. An LGC updata instruction to the LGC to issue an auto engine off will stop the the engine in this mode.
5. APS cannot be started by a ground abort stage function when PGNS/AGS switch is in AGS.
6. APS may be started by an ascent arm prime relay and an engine start override RTC. An engine stop override RTC will stop the APS.
7. APS may be started by an ascent arm prime relay and an ascent on prime relay. An engine stop override RTC will

\*

stop the APS.

8. An APS started by PRA while in AGS select mode requires a ground descent engine arm to stop the ascent engine by RTC.
9. In the AGS mode, the FITH is accomplished with an "engine arm" of the ascent engine by prime relay and an "engine start override" by prime or RTC relays.
10. While in the AGS select mode, the normal "abort stage" function on the present LMP configured vehicle cannot be performed by either ground or prime relay.
11. The ground relays in the PCA must be in the initial "reset" position if the LGC/PRA mode is to operate normally. Except as listed below, all ground relays set by ground should be reset at the end of each operation.
12. The reset position of the manual throttle is 30 percent thrust in the LMP. A master reset RTC will perform this.
13. An abort stage signal should be sent prior to ascent engine operation. This provides for ascent helium pressurization on the unmanned LM.
14. If the ground isolates both ascent helium Tanks 1 and 2, the ascent propulsion system cannot be pressurized by either real-time ground commands, LMP, prime relays, or by an astronaut onboard.
15. A prime relay failure will require the PGNS/AGS switch to be in PGNS and an "abort stage" by ground command to start APS by the updata link control.
16. A PCA total power failure (circuit breaker) will disable the auto switchover from PGNS to AGS and will disable all prime relay control.
17. A PCA power supply failure will disable all prime relay control and will necessitate complete backup of the LM by ground commands. The auto function for direct interface from the LGC to LM would still function normally while in the PGNS mode of control.

TABLE 13-1 LM-1 PRA SEQUENCES

REV C

Sequence No.	Description	$\Delta T$ Sequence	Binary Time Word
I	Nominal Separation	1:47	111111
II	No Vent Separation	0:20	111110
III	Minimum Requirement Sequence	4:45	111101
IV	PRA Suborbit Sequence	1:15	111100
V	No DPS/FITH Minimum Requirement Sequence	2:25	111011
VII	Second APS	1:50	111001
XV	5-second APS (APS restart with abort sequence)	0:22	110001
XVI	Interconnect Closeout	0:10	110000

R-C

TABLE 13-2 LM-1 (AS-206A) PRA COMMAND/TIMELINE

LM-1  
REV C  
NEW PAGE

SEQUENCE 1 - NOMINAL SEP  
(BINARY TIME WORD 111111)

GENERAL DESCRIPTION: TOTAL SEQUENCE TIME EQUALS 1 MIN. 47 SEC. CONSISTS OF A 40 SEC. RCS COLD PURGE, THE RCS PRESSURIZATION ROUTINE, THE STANDARD SEPARATION/TRANSLATION MANEUVER, AND TURNS ON S-BAND COMMUNICATIONS.

USE: THIS SEQUENCE MAY BE USED UNDER THE FOLLOWING CONDITIONS.

- A. NOMINAL SPACECRAFT SEPARATION HAS NOT OCCURRED.
- B. THE RCS PRESSURIZATION ROUTINE ASSOCIATED WITH LGC MISSION PHASE 7 HAS NOT OCCURRED.
- C. SEE MISSION RULES.

IT WOULD BE DESIRABLE TO NOMINALLY LOAD THIS SEQUENCE PRIOR TO CRO AOS ON REV 1. IF THIS CANNOT BE ACCOMPLISHED, IT SHOULD BE LOADED ONLY ON AN AS REQUIRED BASIS.

TIME	FUNCTION	NOTES	TM VERIFICATION		CUE	PRIME OCTAL NO.
			MEAS ID	TITLE		
00:00	+X TRANS ON		GH1419V	JD 4D OUT	1	200
			GH1423V	JD 3D OUT	1	
			GH1427V	JD 2D OUT	1	
			GH1431V	JD 1D OUT	1	
00:40	+X TRANS OFF			+X JD'S	0	201
00:45	RCS MAIN A OPEN		GR9609U	A MAIN CL	0	274
	RCS MAIN B OPEN		GR9610U	B MAIN CL	0	276
	MASTER ARM ON		GY0111X	ED ARM A ON	0	4
00:46	RCS MAIN A OPEN RESET		GY0112X	ED ARM B ON	0	275
	RCS MAIN B OPEN RESET					277
00:47	RCS PRESS. FIRE		GR2201P	A FU P	172 PSIA	6
			GR2202P	B FU P	172 PSIA	
			GR3201P	A OX P	172 PSIA	
			GR3202P	B OX P	172 PSIA	
00:48	RCS PRESS. RESET					7

13-11a

R-C



TABLE 13-2 LM-1 (AS-206A) PRA COMMAND/TIMELINE (CONT'D)

GENERAL DESCRIPTION: TOTAL SEQUENCE TIME EQUALS 75 SEC. CONSISTS OF AN RCS PRESSURIZATION ROUTINE, THE STANDARD SEPARATION/TRANSLATION MANEUVER, A 5 SEC DPS BURN AT 10% THROTTLE, A 4 SEC COAST, RE-IGNITION OF THE DPS FOR 21 SEC AT 10% WITH 5 SEC AT 100% THROTTLE, ABORT STAGE WITH A 5 SEC APS BURN, COAST FOR 3 SEC, AND A 9 SEC APS BURN.

USE: THIS SEQUENCE MAY BE USED DURING MODE 3 AND THE INITIAL 15 SEC OF THE MODE 2 ABORT REGION IF AN LGC FAILURE OCCURS. IT MAY BE LOADED PRELIFTOFF AND SHOULD BE REPLACED WITH SEQUENCE 3 - MRS FOLLOWING NOMINAL SEPARATION. (SEE MISSION RULES)

SEQUENCE 4 PRA SUBORBIT SEQUENCE  
(BINARY TIME WORD 111100)

TIME	FUNCTION	NOTES	TM VERIFICATION		CUE	PRIME OCTAL NO.
			MEAS ID	TITLE		
00:00	MASTER ARM ON		GY0111X	ED ARM A ON	0	4
				ED ARM B ON	0	
00:02	RCS MAIN A OPEN		GR9609U	A MAIN CL	0	274
	RCS MAIN B OPEN		GR9610U	B MAIN CL	0	276
00:02	RCS PRESS. FIRE		GR2201P	A FU P	172 PSIA	6
			GR2202P	B FU P	172 PSIA	
			GR3201P	A OX P	172 PSIA	
			GR3202P	B OX P	172 PSIA	
00:03	RCS PRESS. RESET					7
00:04	+X TRANS ON		GH1419V	JD 4D OUT	1	200
			GH1423V	JD 3D OUT	1	
			GH1427V	JD 2D OUT	1	
			GH1431V	JD 1D OUT	1	
00:05	MAN THROTTLE-10% ON		GH1311V	MAN THRUST	2.6VDC	126
00:06	LM/SLA SEP ARM		K145-900	LM/S SEP A	1	72
			K146-900	LM/S SEP B	1	

TABLE 13-2 LM-1 (AS-206A) PRA COMMAND/TIMELINE (CONT'D)

LM-1  
REV C  
NEW PAGE

TIME	FUNCTION	NOTES	TM VERIFICATION		CUE	PRIME OCTAL NO.
			MEAS ID	TITLE		
	LM/SLA SEP FIRE RCS MAIN A OPEN RESET RCS MAIN B OPEN RESET		GH4222X	LM/SLA SEP	1	132 275 277
00:07	DPS ARM		GH1348X	DPS ARM	1	226
00:16	ENG START		GH1286X	FIRE O/R	1	326
00:17	ENG START RESET		GH1286X	FIRE O/R	0	327
00:21	ENG STOP O/R					246
00:22	ENG STOP RESET					247
00:26	ENG START		GH1286X	FIRE O/R	0	326
00:28	ENG START RESET					327
00:47	MAN THROTTLE-100% ON		GH1311V	MAN THRUST	14.6VDC	346
00:52	ABORT STG ARM					46
00:53	ABORT STG FIRE DPS RESET APS ARM		GH1283X GH1348X GH1230X	ABRT STGD DPS ARM APS ARM	0 1	26 227 206
00:58	ENG STOP O/R		GH1286X	FIRE O/R	0	246
01:00	ENG STOP RESET					247
01:03	ENG START		GH1286X	FIRE O/R	1	326
01:04	ENG START RESET					327
01:13	ENG STOP O/R		GH1286X	FIRE O/R	0	246
01:14	ENG STOP RESET					247
01:15	+X TRANS OFF			+X JD'S	0	201

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TABLE 13-2 LM-1 (AS-206A) PRA COMMAND/TIMELINE (CONT'D)

LM-1  
REV C  
NEW PAGE

SEQUENCE 5 - NO DPS/FITH MRS  
(BINARY TIME WORD 111011)

GENERAL DESCRIPTION: TOTAL SEQUENCE TIME EQUALS 2 MIN 29 SEC CONSISTS OF 12 SEC ULLAGE, AN ABORT STAGE SEQUENCE AND A 5.535 SEC APS BURN. THE SECOND APS BURN IS A BURN TO DEPLETION COUPLED WITH AN RCS INTERCONNECT TEST.

USE: IN THE EVENT OF DISABLED DPS

TIME	FUNCTION	NOTES	TM VERIFICATION		CUE	PRIME OCTAL NO.
			MEAS ID	TITLE		
00:00	MASTER ARM ON		GY0111X	ED ARM A ON ED ARM B ON	0	004
00:01	DPS RESET		GH1348X	DPS ARM	0	227
00:02	+X TRANS ON		GH1419V	JD 4D OUT	1	200
			GH1423V	JD 3D OUT	1	
			GH1427V	JD 2D OUT	1	
			GH1431V	JD 1D OUT	1	
00:07	ABORT STG ARM					046
00:14	ABORT STG FIRE APS ARM		GH1283X	ABRT STGD		026
	ENG START		GH1230X	APS ARM	1	206
			GH1286X	FIRE O/R	1	326
00:16	ENG START RESET					327
00:19	+X TRANS OFF			+X JD'S	0	201
00:20	ENG STOP O/R		GH1286X	FIRE O/R	0	246
00:21	ABORT STG FIRE RESET					027
	ENG STOP RESET					247
	ABORT STG RESET					047

TABLE 13-2 LM-1 (AS-206A) PRA COMMAND/TIMELINE (CONT'D)

LM-1  
REV C  
NEW PAGE

TIME	FUNCTION	NOTES	TM VERIFICATION		CUE	PRIME OCTAL NO.
			MEAS ID	TITLE		
00:44	+X TRANS ON		GH1419V	JD 4D OUT	1	200
			GH1423V	JD 3D OUT	1	
			GH1427V	JD 2D OUT	1	
			GH1431V	JD 1D OUT	1	
00:57	ENG START		GH1286X	FIRE O/R	1	326
00:58	ENG RESET		GH1286X	FIRE O/R	0	327
01:02	+X TRANS OFF			+X JD'S	0	201
01:06	ASC FEED ARM					176
01:07	ASC FEED A OPEN RCS MAIN A CLSD		GR9611U	A A/FEED	1	074
			GR9609U	A MAIN CL	1	254
01:08	ASC FEED A OPEN RESET RCS MAIN A CLSD RESET					075
						255
01:17	ASC FEED B OPEN RCS MAIN B CLSD		GR9612U	B A/FEED	1	076
			GR9610U	B MAIN CL	1	256
01:18	ASC FEED B OPEN RESET RCS MAIN B CLSD RESET					077
						257
01:27	X-FEED OPEN		GR9613U	X-FEED OP	1	374
01:28	X-FEED OPEN RESET					375
02:16	X-FEED CLSD		GR9613U	X-FEED OP	0	376
02:17	X-FEED CLSD RESET RCS MAIN A OPEN ASC FEED A CLSD					377
			GR9609U	A MAIN CL	0	274
			GR9611U	A A/FEED	0	114
02:18	RCS A OPEN RESET ASC FEED A CLSD RESET					275
						115
02:27	RCS MAIN B OPEN ASC FEED B CLSD		GR9610U	B MAIN CL	0	276
			GR9612U	B A/FEED	0	116
02:28	RCS MAIN B OPEN RESET ASC FEED B CLSD RESET					277
						117
02:29	ASC FEED RESET					177

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TABLE 13-2 LM-1 (AS-206A) PRA COMMAND/TIMELINE (CONT'D)

LM-1  
REV C  
NEW PAGE

SEQUENCE 7 - SEC APS  
(BINARY TIME WORD 111001)

GENERAL DESCRIPTION: TOTAL SEQUENCE EQUALS 1 MIN 50 SEC CONSISTS OF AN APS BURN TO DEPLETION COUPLED WITH AN RCS INTERCONNECT TEST.

USE: THIS SEQ IS TO BE USED IF A FAILURE IN THE LGC OCCURS AFTER THE FIRST APS BURN.

TIME	FUNCTION	NOTES	TM VERIFICATION		CUE	PRIME OCTAL NO.
			MEAS ID	TITLE		
00:00	APS ARM		GH1230X	APS ARM	1	206
00:07	+X TRANS		GH1419V	JD 4D OUT	1	200
			GH1423V	JD 3D OUT	1	
			GH1427V	JD 2D OUT	1	
			GH1431V	JD 1D OUT	1	
00:20	ENG START		GH1286X	FIRE O/R	1	326
00:21	ENG RESET					327
00:25	+X TRANS OFF			+X JD'S	0	201
00:27	ASC FEED ARM					176
00:28	ASC FEED A OPEN		GR9611U	A A/FEED	1	074
	RCS MAIN A CLSD		GR9609U	A MAIN CL	1	254
00:29	ASC FEED A OPEN RESET					075
	RCS MAIN A CLSD RESET					255
00:38	ASC FEED B OPEN		GR9612U	B A/FEED	1	076
	RCS MAIN B CLSD		GR9610U	B MAIN CL	1	256
00:39	ASC FEED B OPEN RESET					077
	RCS MAIN B CLSD RESET					257

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REC/TSG- 22

TABLE 13-2 LM-1 (AS-206A) PRA COMMAND/TIMELINE (CONT'D)

LM-1  
REV C  
NEW PAGE

TIME	FUNCTION	NOTES	TM VERIFICATION		CUE	PRIME OCTAL NO.
			MEAS ID	TITLE		
00:48	X-FEED OPEN		GR9613U	X-FEED OP	1	374
00:49	X-FEED OPEN RESET					375
01:37	X-FEED CLSD		GR9613U	X-FEED OP	0	376
01:38	X-FEED CLSD RESET					377
	RCS MAIN A OPEN		GR9609U	A MAIN CL	0	274
	ASC FEED A CLSD		GR9611U	A A/FEED	0	114
01:39	RCS MAIN A OPEN RESET					275
	ASC FEED A CLSD RESET					115
01:48	RCS MAIN B OPEN		GR9610U	B MAIN CL	0	276
	ASC FEED B CLSD		GR9612U	B A/FE	0	116
01:49	RCS MAIN B OPEN RESET					277
	ASC FEED B CLSD RESET					117
01:50	ASC FEED RESET					177

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TABLE 13-2 LM-1 (AS-206A) PRA COMMAND/TIMELINE (CONT'D)

LM-1  
REV C  
NEW PAGE

SEQUENCE NO. 15 5 SEC APS  
(BINARY TIME WORD 110001)

GENERAL DESCRIPTION: TOTAL SEQUENCE TIME EQUALS 0 MIN 22 SEC. CONSISTS OF AN ABORT STAGE SEQUENCE AND A 5 SEC APS BURN.

USE: THIS SEQUENCE MAY BE USED TO SEPARATE THE LM ASCENT STAGE ONLY FROM THE S-IVB. IT WOULD NOT BE REQUIRED UNLESS THERE ARE FAILURES ASSOCIATED WITH THE LM/SLA SEPARATION CIRCUITRY. (SEE MISSION RULES).

TIME	FUNCTION	NOTES	TM VERIFICATION		CUE	PRIME OCTAL NO.
			MEAS ID	TITLE		
00:00	+X TRANS ON		GH1419V	JD 4D OUT	1	200
			GH1423V	JD 3D OUT	1	
			GH1427V	JD 2D OUT	1	
			GH1431V	JD 1D OUT	1	
00:07	ENG START		GH1286V	FIRE O/R	1	326
00:11	MAN THROTTLE 100% ON MASTER ARM ON		GH1311V	MAN THRUST	14.6VDC	346
			GV0111X	ED ARM A ON ED ARM B ON	0	004
00:12	ABORT STG ARM					046
00:13	ABORT STG FIRE DPS RESET APS ARM		GH1238X	ABRT STGD		026
			GH1348X	DPS ARM	0	227
			GH1230X	APS ARM	1	206
00:19	ENG STOP O/R +X TRANS OFF ENG RESET		GH1286X	FIRE O/R	0	246
				+X JD'S	0	201
						327
00:20	APS RESET ENG STOP RESET		GH1230X	APS ARM	0	207
						247

13-11h  
FIG 13G-22

TABLE 13-2 LM-1 (AS-206A) PRA COMMAND/TIMELINE (CONT'D)

NEW PAGE

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TIME	FUNCTION	NOTES	TM VERIFICATION		CUE	PRIME OCTAL NO.
			MEAS ID	TITLE		
00:21	ABORT STG FIRE RESET ABORT STG RESET					027 047
00:22	MASTER ARM OFF MAN THROTTLE 100% OFF					005 347



TABLE 13-2 LM-1 (AS-206A) PRA COMMAND/TIMELINE (CONCL'D)

LM-1  
REV C  
NEW PAGE

SEQUENCE NO. 16 INTERCONNECT CLOSEOUT  
(BINARY TIME WORD 110000)

GENERAL DESCRIPTION: TOTAL SEQUENCE TIME EQUALS 0 MIN 10 SEC. CONSISTS OF A RCS MANIFOLD RECONFIGURATION (INTERCONNECT SHUTDOWN).

USE: THIS SEQUENCE MAY BE USED IF THE LGC FAILS DURING THE APS 2 BURN AND THE RCS ASCENT FEED IS OPEN. IT MAY BE LOADED UPON COMPLETION OF LGC MISSION PHASE 2 (DPS 2/FITH/APS 1). (SEE MISSION RULES).

TIME	FUNCTION	NOTES	TM VERIFICATION		CUE	PRIME OCTAL NO.
			MEAS ID	TITLE		
00:00	+X TRANS ON		GH1419V	JD 4D OUT	1	200
			GH1423V	JD 3D OUT	1	
			GH1427V	JD 2D OUT	1	
			GH1431V	JD 1D OUT	1	
00:01	X-FEED CLSD		GR9613U	X-FEED OP	0	376
	RCS MAIN A OPEN		GR9609U	A MAIN CL	0	274
	ASC FEED A CLSD		GR9611U	A A/FEED	0	114
	RCS MAIN B OPEN		GR9610U	B MAIN CL	0	276
	ASC FEED B CLSD		GR9612U	B A/FEED	0	116
00:02	X-FEED CLSD RESET					377
	RCS MAIN A OPEN RESET					275
	ASC FEED A CLSD RESET					115
00:03	RCS MAIN B OPEN RESET					277
	ASC FEED B CLSD RESET					117
00:04	ASC FEED RESET					177
00:10	+X TRANS OFF			+X JD'S	0	201

13-11-1

REC/ISS- 22

TABLE 13-2 LM-1 (AS-206A) PRA COMMAND/TIMELINE (CONT'D)

LM-1  
REV C  
NEW PAGE

TIME	FUNCTION	NOTES	TM VERIFICATION		CUE	PRIME OCTAL NO.
			MEAS ID	TITLE		
01:17	MASTER ARM SAFE					5
01:27	PLUS-X TRANS ON			+X JD'S	1	200
01:28	PRI S-BIND ENABLE		GT0994V	RCVR SIG	-4V	212
01:31	LM/SLA SEP ARM		K145-900 K146-900	LM/S SEP A LM/S SEP B	1 1	72
01:32	LM/SLA SEP FIRE		GL4222X	LM/SLA SEP	1	132
01:37	+X TRANS OFF LM/SLA SEP ARM RESET LM/SLA SEP FIRE RESET			+X JD'S	0	201 73 133
01:42	+X TRANS ON			+X JD'S	1	200
01:47	+X TRANS OFF			+X JD'S	0	201

13-11k

## NOTES:

CONSTRAINTS: DO NOT RUN THIS SEQUENCE WITH THE RCS PRESSURIZED AS PLUS-X TRANSLATION CAN BE ACTIVE FOR ONLY 20 SEC WITHOUT CAUSING DAMAGE TO DESCENT STAGE THERMAL INSULATION.

IF THE LGC FAILS PRIOR TO SEPARATION FROM THE S-IVB AND LM LIFETIME IS 1 REV, THIS SEQUENCE WILL BE USED (IF THE RCS HAS NOT BEEN PRESSURIZED) OVER THE WEST CALIFORNIA SHIP. THIS SEQUENCE WOULD BE FOLLOWED BY SEQUENCE III - MRS. (SEE MISSION RULES).



TABLE 13-2 LM-1 (AS-206A) PRA COMMAND/TIMELINE (CONT'D)

NEW PAGE

SEQUENCE NO. 3 - MRS  
(BINARY TIME WORD 111101)

GENERAL DESCRIPTION: TOTAL SEQUENCE TIME EQUALS 4 MIN. 45 SEC. CONSISTS OF A 36 SEC. DPS BURN (26 SEC. AT 10% THROTTLE AND 10 SEC. AT 100% THROTTLE), A 32 SEC. COAST, A 56 SEC. DPS BURN (26 SEC. AT 10% THROTTLE AND 30 SEC. AT 100% THROTTLE), ABORT STAGE WITH A 6 SEC. APS BURN, A 40 SEC. COAST, AND AN APS BURN WITH ASC INTERCONNECT (LENGTH OF BURN VARIABLE - RTC TERMINATION.)

USE: THIS SEQUENCE MAY BE USED SUBSEQUENT TO NOMINAL INSERTION TO ACCOMPLISH PRIMARY MISSION OBJECTIVES IN THE EVENT OF AN LGC FAILURE OR TIME CRITICAL FAILURE.

TIME	FUNCTION	NOTES	TM VERIFICATION		CUE	PRIME OCTAL NO.
			MEAS ID	TITLE		
00:00	MASTER ARM ON		GY0111X GY0112X	ED ARM A ON ED ARM B ON	0 0	4
00:05	DPS PQGS ARM (#1) DPS PQGS (#2) ON					344 324
00:06	DPS PQGS (#1) ON DPS PQGS ARM (#2)					364 304
00:07	DPS ARM		GH1348X	DPS ARM	1	226
00:15	+X TRANS ON		GH1419V GH1423V GH1427V GH1431V	JD 4D OUT JD 3D OUT JD 2D OUT JD 1D OUT	1 1 1 1	200
	MAN THROTTLE - 10% ON		GH1311	MAN THRUST	2.6VDC	126
00:23	ENG START		GH1286X	FIRE O/R	1	326
00:24	ENG START RESET					327
00:28	+X TRANS OFF			X JD'S	0	201

13-11m

REC/TSG-22

TABLE 13-2 LM-1 (AS-206A) PRA COMMAND/TIMELINE (CONT'D)

LM-1  
REV C

TIME	FUNCTION	NOTES	TM VERIFICATION		CUE	PRIME OCTAL NO.
			MEAS ID	TITLE		
00:49	MAN THROTTLE 100% ON		GH1311V	MAN THRUST	14.6VDC	346
00:59	ENG STOP O/R		GH1286X	FIRE O/R	0	246
01:01	ENG STOP RESET					247
	MAN THROTTLE-100% OFF		GH1331V	MAN THRUST	2.6VDC	347
	MAN THROTTLE-10% OFF		GH1311V	MAN THRUST	5.1VDC	127
01:04	DPS RESET		GH1348X	DPS ARM	0	227
01:22	DPS ARM		GH1348X	DPS ARM	1	226
01:23	+X TRANS ON		GH1419V	JD 4D OUT	1	200
			GH1423V	JD 3D OUT	1	
			GH1427V	JD 2D OUT	1	
			GH1431V	JD 1D OUT	1	
	MAN THROTTLE 10% ON		GH1311V	MAN THRUST	2.6VDC	126
01:31	ENG START		GH1286X	FIRE O/R	1	326
01:32	ENG RESET					327
01:36	+X TRANS OFF			+X JD'S	0	201
01:57	MAN THROTTLE 100% ON		GH1311V	MAN THRUST	14.6VDC	346
02:26	ABORT STG ARM					46
02:27	ABORT STG FIRE		GH1283X	ABRT STGD		25
	DPS RESET		GH1348X	DPS ARM	0	227
	APS ARM		GH1230X	APS ARM	1	206
02:33	ENG STOP O/R		GH1286X	FIRE O/R	0	246
02:34	MAN THROTTLE-100% OFF		GH1311V	MAN THRUST	2.6VDC	347
	MAN THROTTLE-10% OFF		GH1311V	MAN THRUST	5.1VDC	127
	DPS PQGS (#1) OFF					365
	DPS PQGS (#2) RESET					305
	DPS PQGS (#1) RESET					345
	DPS PQGS (#2) OFF					325

R-C

13-11n

TABLE 13-2 LM-1 (AS-206A) PRA COMMAND/TIMELINE (CONT'D)

LM-1  
REV C

TIME	FUNCTION	NOTES	TM VERIFICATION		CUE	PRIME OCTAL NO.
			MEAS ID	TITLE		
02:35	ABORT STG FIRE RESET ENG STOP RESET ABORT STG RESET					27 247 47
03:00	+X TRANS ON			+X JD'S		200
03:13	ENG START		GH1286X	FIRE O/R	1	326
03:14	ENG START RESET					327
03:18	+X TRANS OFF			+X JD'S	0	201
03:22	ASC FEED ARM					176
03:23	ASC FEED A OPEN RCS MAIN A CLSD		GR9611U GR9609U	A A/FEED A MAIN CL	1 1	74 254
03:24	ASC FEED A OPEN RESET RCS A CLSD RESET					75 255
03:33	ASC FEED B OPEN RCS MAIN B CLSD		GR9612U GR9610U	B A/FEED B MAIN CL	1 1	76 256
03:34	ASC FEED B OPEN RESET RCS MAIN B CLSD RESET					77 257
03:43	X-FEED OPEN		GR9613U	X FEED OP	1	374
03:44	X-FEED OPEN RESET					375
04:32	X-FEED CLSD		GR9613U	X FEED OP	0	376
04:33	X-FEED CLSD RESET RCS MAIN A OPEN ASC FEED A CLSD		GR9609U GR9611U	A MAIN CL A A/FEED	0 0	377 274 114
04:34	RCS A OPEN RESET ASC FEED A CLSD RESET					275 115

13-110

TABLE 13-2 LM-1 (AS-206A) PRA COMMAND/TIMELINE (CONT'D)

LM-1  
REV C

TIME	FUNCTION	NOTES	TM VERIFICATION		CUE	PRIME OCTAL NO.
			MEAS ID	TITLE		
04:43	RCS MAIN B OPEN		GR9610U	B MAIN CL	0	276
	ASC FEED B CLSD		GR9612U	B A/FEED	0	116
04:44	RCS B OPEN RESET					277
	ASC FEED B CLSD RESET					117
04:45	ASC FEED RESET					177

13-11D

NOTES:

1. SEQUENCE 3 SHOULD BE INITIATED OVER THE NEXT STATESIDE PASS. (SEE MISSION RULES).
  - A. IF THE LGC FAILS PRIOR TO SEPARATION AND LM LIFETIME IS 1 REV (WILL SEQUENTIALLY FOLLOW SEQUENCE 1 - NOMINAL SEP OR SEQUENCE 2 - NO VENT SEP DEPENDING ON WHETHER THE RCS HAS BEEN PRESSURIZED OR NOT).
  - B. IF THE LGC FAILS AFTER SEPARATION BUT PRIOR TO DPS 1.
  - C. IF THE LGC FAILS AFTER DPS 1 BUT PRIOR TO DPS 2 (AN EXTRA DPS BURN RESULTS).

TABLE 13-3 LMP REAL-TIME COMMANDS BY CODE (CONCLUDED)

LM-1  
REV C

CODE	MATRIX POINT	RELAY DESIGNATION	RELAY FUNCTIONAL DESIGNATION	COMMAND NAME
45B	10-3R	A17K11(R)	K0752A	ENVIRONMENTAL - SEC H <sub>2</sub> O RESET
50B	11-3S	A17K14(S)	K0751A	
51B	11-3R	A17K14(R)	K0751A	
54B	12-3S	A17K9(S)	K2060A	COMMUNICATIONS - DFI CAL ON
55B	12-3R	A17K9(R)K1(S)	K2060A,K2060B	
60B	13-3S	A17K7(S)	K0155A,B	SEC H <sub>2</sub> O FEED ENABLE
61B	13-3R	A17K7(R)	K0155A,B	SEC H <sub>2</sub> O FEED RESET
64B	14-3S	A11K4(S),K5(S)	K0251A,B	PYRO - MASTER ARM ON
65B	14-3R	A11K4(R),K5(R)	K0251A,B	PYRO - MASTER ARM OFF
70B	15-3S	A11K6(S),K7(S)	K0252A,B	RCS VALVES - RCS PRESS. FIRE
71B	15-3R	A11K6(R),K7(R)	K0252A,B	RCS VALVES - RCS PRESS. RESET
74B	16-3S	A11K8(S)	K1152A	FLT CONTR - DEADBAND MIN
75B	16-3R	A11K8(R)	K1152A	FLT CONTR - DEADBAND LMP CONTR

R-B  
R-C



TABLE 13-4 LMP PRIME (LGC&amp;/OR PRA SEQUENCED) COMMAND

LM-1  
REV C

OCTAL	DECIMAL CODE	RELAY DESIGNATION	RELAY FUNCTIONAL DESIGNATION	COMMAND NAME
2	2	A11K18(S),25(S)	K1101A, B	FLT CONTR - ATT HOLD ON
3	3	A11K18(R),25(R)	K1101A, B	FLT CONTR - AUTO ENABLE
4	4	A11K12(S),13(S)	K0201A, B	PYRO - MASTER ARM ON
5	5	A11K12(R),13(R)	K0201A, B	PYRO - MASTER ARM OFF
6	6	A11K14(S),15(S)	K0202A, B	RCS VALVES - RCS PRESS. FIRE
7	7	A11K14(R),15(R)	K0202A, B	RCS VALVES - RCS PRESS. RESET
<del>10</del>	<del>8</del>	<del>A10K21(S),27(S)</del>	<del>K0203B, A</del>	<del>LANDING GEAR DEPLOY FIRE OK</del>
<del>11</del>	<del>9</del>	<del>A10K21(R),27(R)</del>	<del>K0203B, A</del>	<del>LANDING GEAR DEPLOY OFF</del>
12	10	A12K14(S)	K0034	SPARE
13	11	A12K14(R)	K0034	SPARE
14	12	A13K8(S)	K0813A	RCS VALVES - RCS 1A OPEN
15	13	A13K8(R)	K0813A	RCS VALVES - RCS 1A OPEN RESET
16	14	A14K8(S)	K0811A	RCS VALVES - RCS 3A OPEN
17	15	A14K8(R)	K0811A	RCS VALVES - RCS 3A OPEN RESET
20	16	A11K19(S)	K0028	SPARE
21	17	A11K19(R)	K0028	SPARE
22	18	A11K20(S)	K0029	SPARE
23	19	A11K20(R)	K0029	SPARE
24	20	A11K21(S)	K0030	SPARE
25	21	A11K21(R)	K0030	SPARE
26	22	A11K26(S)	K0206	FLT CONTR - ABORT STG FIRE
27	23	A11K26(R)	K0206	FLT CONTR - ABORT STG FIRE RESET
<del>30</del>	<del>24</del>	<del>A10313(S),14(S)</del>	<del>K0204A, B</del>	<del>DPS HELIUM PRE PRESSURIZATION FIRE (DEM 283)</del>
<del>31</del>	<del>25</del>	<del>A10K13(R),14(R)</del>	<del>K0204A, B</del>	<del>DPS HELIUM PRE PRESSURIZATION OFF (LEM 283)</del>
<del>32</del>	<del>26</del>	<del>A12K26(S)</del>	<del>K1702A</del>	<del>LANDING RADAR SELF TEST ON</del>
<del>33</del>	<del>27</del>	<del>A12K26(R)</del>	<del>K1702A</del>	<del>LANDING RADAR SELF TEST OFF</del>
34	28	A13K9(S)	K0821A	RCS VALVES - RCS 1B OPEN
35	29	A13K9(R)	K0821A	RCS VALVES - RCS 1B OPEN RESET
36	30	A14K9(S)	K0819A	RCS VALVES - RCS 3B OPEN
37	31	A14K9(R)	K0819A	RCS VALVES - RCS 3B OPEN RESET
<del>40</del>	<del>32</del>	<del>A11K22(S)</del>	<del>K1103A</del>	<del>AGS STATUS ASA STANDBY/OPERATE</del>
<del>41</del>	<del>33</del>	<del>A1K22(R)</del>	<del>K1103A</del>	<del>AGS STATUS ASA WARMUP</del>
42	34	A11K23(S)	K1302A	COMMUNICATIONS S-BND PNG ON
43	35	A11K23(R)	K1302A	COMMUNICATIONS S-BND PNG OFF
44	36	A11K27(S)	K1102A	FLT CONTR DEADBAND LMP CONTR
45	37	A11K27(R)	K1102A	FLT CONTR DEADBAND LMP

13-16

R-B

TABLE 13-6 LM COMMAND CARD RELAY REFERENCE

LM-1  
REV C

RTC	PRIME	ON OR OPEN	SYSTEM	OFF OF CLOSE		RTC	PRIME RELAYS (FUN.)ON/OFF (MOD)ON/OFF		GND RELAYS (FUN.)ON/OFF (MOD)ON/OFF	
				PRIME						
<u>FLIGHT CONTROLS</u>										
25B	(AUTO EN)		ATT ENABLE		(ATT HOLD)	31B			K1151 A,B,C	A11K19,17
30B	(AUTO ON)	3	ATT ON	2	(ATT HOLD ON)	24B	K1101 A,B	A11K18, 25	K1151&53 A,B	A11K2,17
75B	(LMP CTR)	44	DEADBAND	45	◇(MIN)	74B	K1102 A	A11K27	K1152 A	A11K8
41B	(PHGS)	N/A	GUID SEL	N/A	(AGS)	40B			K2059 A,B,C, D	A16K17, 9,16,8
*** 34B	(RESET)	N/A	PRIME RELAY	N/A	(OFF)	35B			K2057 A,C	A16K5, 15
70A	(ARM)	46	ABORT STAGE	47	◇(RESET)	71A	K0205 A,B,C	A10K3,4,5	K0254 A,B,C	A10K9,10,11
43A/41A	(FIRE/FIRE RESET)	26/27	ABORT STAGE	N/A		N/A	K0206A	A11K26	K0257 A	A15K9
<u>EECOM</u>										
<u>PYRO</u>										
64B	(ON)	4	MASTER ARM	5	◇(OFF)	65B	K0201 A,B	A11K12,13	K0251 A,B	A11K4,5
<del>61A/62, 46A</del>	(ARM)/(ARM RESET)	72/73	LM/SLA SEP	N/A		47A	K2001 A,B	A12K3, A13K14	K0251 A,B	A11K4,5
62A/63A	FIRE/FIRE RESET	132/133	LM/SLA SEP	N/A	-	N/A	K2006 A,B,C	A12K12,20 A13K16	K0256 A,B	A10K2,7
<u>ELECTRICAL</u>										
N/A	-	N/A	BAT. 1	N/A	(OFF)	17A			K0458 A	A12K24
N/A	-	N/A	BAT. 2	N/A	(OFF)	22A			K0453 A	A12K16
N/A	-	N/A	BAT. 3	N/A	(OFF)	32A			K0459 A	A12K13
N/A	-	N/A	BAT. 4	N/A	(OFF)	37A			K0456 A	A12K22
N/A	-	N/A	BAT. 5	N/A	(OFF)	26A			K0451 A	A12K7
36A	B/U COR	N/A	BAT. 5	N/A	-	N/A			K0455 A	A12K21
N/A	-	N/A	BAT. 6	N/A	(OFF)	23A			K0454 A	A12K16
27A	B/U SE	N/A	BAT. 6	N/A	-	N/A			K0452 A	A12K8
16A	SEL	N/A	INVERT 2	N/A	-	N/A			K0457 A	A12K23
<u>ENVIRONMENT</u>										
24A/25A	(FEED/ RESET)	272/273	PRI H <sub>2</sub> O	N/A	-	N/A	K0704 A	A15K3	K0753 A	A15K2
44B/45B	(FEED/ RESET)	336/337	SEC H <sub>2</sub> O	N/A	-	N/A	K0703 A	A17K6	K0752 A	A17K11
60B	ENABLE		SEC H <sub>2</sub> O FEED COFF	61B	(RESET)					
N/A	(ON)	42	S-BAND RANGE	43	◇(OFF)	N/A	K1302 A	A11K23		
31A	(ENABLE)	212	PRI S-BND	213	◇(OFF)	30A	K1301 A	A15K5	K1352 A	A15K1
20A	(ON)	N/A	SEC S-BND	N/A	(OFF)	21A			K1351 A	A15K14
53A	(ON)	152	C-BND	153	(OFF)	+52A	K2005 A	A12K17	K0255 A,B	A10K1,6
54B	(ON)	354	DFI CAL	355	◇(OFF)	+55B	K0107 A,B	A6K19,11	K2060 A,B	A17K9,1

R-C

R-C

13-5  
64-5

\*\*\*CMD AVAILABILITY DEPENDS ON COCKPIT SW.

\*\*\*WARNING - DON'T SEND MASTER RELAY RESET DURING ASC ENG OPERATION.

◇INDICATES POSITION AFTER MASTER RELAY RESET IS GIVEN.

TABLE 13-6 LM COMMAND HARD RELAY REFERENCE (Concluded)

LM-1  
PEV C

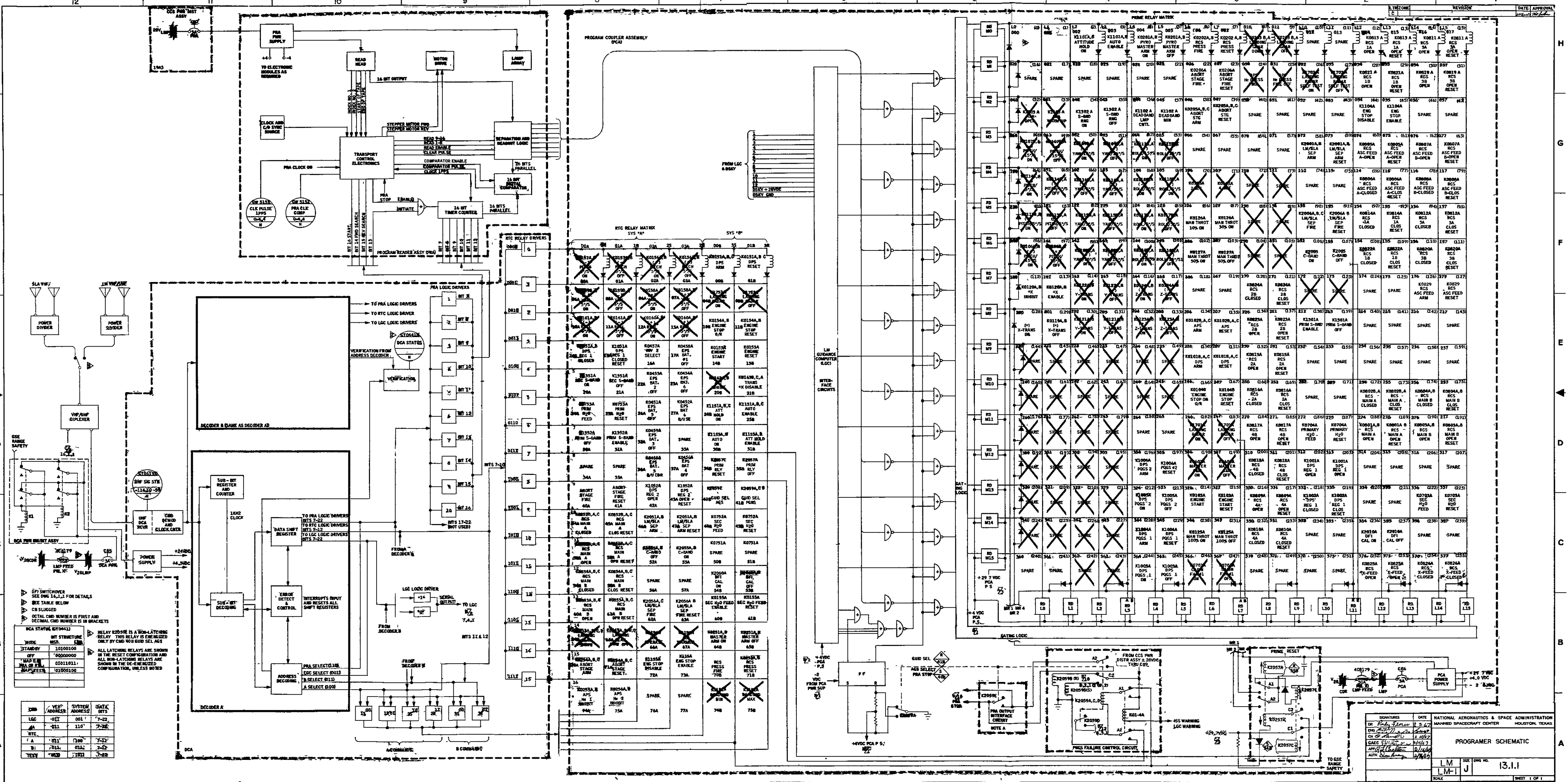
RTC	ON OR OPEN		SYSTEM	OFF OR CLOSE		RTC	PRIME RELAYS (FUNCTIONAL) ON/OFF (MOD) ON/OFF		GND RELAYS (FUN.) ON/OFF (MOD) ON/OFF	
	PRIME			PRIME						
			<u>PROPULSION THROTTLE CONTROL</u>							
N/A	100% CN	346	MAN THROTTLE	347	OFF	N/A	K0125 A	A9K18		
N/A	(50% CN)	146	MAN THROTTLE	147	50% OFF	N/A	K0127 A	A9K20		
N/A	(30% ON)	127	MAN THROTTLE	N/A		N/A	K0126 A	A1K21		
		126	MAN THROTTLE							
			<u>TRANSLATION CNTR</u>							
N/A	(ON)	200	+X TRANSLATION	201	(OFF)	N/A	K0119 A,B	A6K24,25		
N/A	----	N/A	+X		(DISABLE)	218**			/K0163 A,B,C	A8K26,A6K26 A7K26
			<u>ENG ON-OFF</u>							
N/A	L (ARM)	206	APS	207	(RESET)	N/A	K0102 A,B,C	A9K15,7,23		
003	L (ARM)	226	DPS	227	(RESET)	01B	K0101 A,B,C	A9K14,6,22	K0151 A,B,C	A9K16,8,14
14B/15B	(START/RESET)	326/327	ENG	N/A	----	N/A	K0103 A	A9K10	K0153 A	A9K11
10B	(OVERRIDE)	246	ENG STOP	247	(RESET)	11B	K0104 B	A9K4	K0154 A,B	A9K13,5
72A	(DISABLE)	54	ENG STOP	55	(ENABLE)	73A	K1104 A	A11K11	K1155 A	A11K24
74A	(INHIBIT)	N/A	APS HE. 1	N/A	----	N/A			K0255 A,B	A10K1,6
75A	(INHIBIT)	N/A	APS HE. 2	N/A	----	N/A			K0256 A,B	A10K2,7
			<u>DE REG VAL CNTR</u>							
N/A	(OPEN/RESET)	312/313	DPS REG 1	332/333	(CLOSE/RESET)	14A*/15A	K1001A/K1002A	A15K4/13		
N/A	----	N/A	DPS REG 2	N/A	(OPEN/RESET)	42A/43A				
			<u>DPS PQGS</u>							
N/A	(ARM)	344	PQGS #1	345	(RESET)	N/A	K1004A	A8K7		
N/A	(ON)	364	PQGS #1	365	(OFF)	N/A	K1003A	A8K8		
N/A	(ARM)	304	PQGS #2	305	(RESET)	N/A	K1006A	A8K4		
N/A	(ON)	324	PQGS #2	325	(OFF)	N/A	K1005A	A8K6		
			<u>RCS VALVES</u>							
70B/71B	(FIRE/RESET)	6/7	RCS PRESS.	N/A		N/A	K0202 A,B	A11K14,15	K0252 A,B	A11K6,7
N/A	(ARM)	176	ASC FEED	177	(RESET)	N/A	K0829 A	A13K3		
N/A	L (OPEN/RESET)	74/75	ASC FEED "A"	114/115	(CLOSE/RESET)	N/A	K0805/6 A	A13K3/4		
N/A	L (OPEN/RESET)	76/77	ASC FEED "B"	116/117	(CLOSE/RESET)	N/A	K0807/8 A	A14K3/4		
N/A	L (OPEN/RESET)	374/375	CROSSFEED	376/377	(CLOSE/RESET)	N/A	K0825/26 A	A17K2/4		
50A+/51A	L (OPEN/RESET)	274/275	RCS MAIN "A"	254/255	(CLOSE/RESET)	44A+/45A	K0801/02 A,B	A13K18,22/ 13,21	K0851/52 A,B,C	A13K6,5,20/ A13K2,1,19
60A+/61A	L (OPEN/RESET)	276/277	RCS MAIN "B"	256/257	(CLOSE/RESET)	54A+/55A	K0803/04 A,B	A14K18,22/ 13,21	K0853/54 A,B,C	A14K6,5,20/ A14K2,1,19
N/A	L (OPEN/RESET)	14/15	RCS 1 "A"	134/135	(CLOSE/RESET)	N/A	K0813/14 A	A13K8/10		
N/A	L (OPEN/RESET)	34/35	RCS 1 "B"	154/155	(CLOSE/RESET)	N/A	K0821/22 A	A13K9/11		
N/A	L (OPEN/RESET)	230/231	RCS 2 "A"	250/251	(CLOSE/RESET)	N/A	K0815/16 A	A16K3/4		
N/A	L (OPEN/RESET)	210/211	RCS 2 "B"	170/171	(CLOSE/RESET)	N/A	K0823/24 A	A16K2/1		
N/A	L (OPEN/RESET)	16/17	RCS 3 "A"	136/137	(CLOSE/RESET)	N/A	K0811/12 A	A14K8/10		
N/A	L (OPEN/RESET)	36/37	RCS 3 "B"	156/157	(CLOSE/RESET)	N/A	K0819/20 A	A14K9/11		
N/A	L (OPEN/RESET)	330/331	RCS 4 "A"	350/351	(CLOSE/RESET)	N/A	K0809/10 A	A16K12/11		
N/A	L (OPEN/RESET)	270/271	RCS 4 "B"	310/311	(CLOSE/RESET)	N/A	K0817/18 A	A16K14/13		

\*\*PERMANENTLY INHIBITS FUNCTION  
EN - ENABLE

L - INTERLOCK - UNLESS RESET CMD IS SENT, OTHER CMDs ARE INHIBITED

+ RTC - PERMANENTLY INHIBITS PRIME CMD CONTROL

NOTE: ON ALL VALUES WITH (OPEN/RESET) LISTED THE CMD IS OPEN AND  
OPEN RESET OR CLOSE AND CLOSE RESET.



RTS 17-22 (NOT USED)

RTS	BIT	FUNCTION
17-22	1	NOT USED
17-22	2	NOT USED
17-22	3	NOT USED
17-22	4	NOT USED
17-22	5	NOT USED
17-22	6	NOT USED
17-22	7	NOT USED
17-22	8	NOT USED
17-22	9	NOT USED
17-22	10	NOT USED
17-22	11	NOT USED
17-22	12	NOT USED
17-22	13	NOT USED
17-22	14	NOT USED
17-22	15	NOT USED

RTS 11 & 12

RTS	BIT	FUNCTION
11	1	NOT USED
11	2	NOT USED
11	3	NOT USED
11	4	NOT USED
11	5	NOT USED
11	6	NOT USED
11	7	NOT USED
11	8	NOT USED
11	9	NOT USED
11	10	NOT USED
11	11	NOT USED
11	12	NOT USED
11	13	NOT USED
11	14	NOT USED
11	15	NOT USED

RTS 7-10

RTS	BIT	FUNCTION
7	1	NOT USED
7	2	NOT USED
7	3	NOT USED
7	4	NOT USED
7	5	NOT USED
7	6	NOT USED
7	7	NOT USED
7	8	NOT USED
7	9	NOT USED
7	10	NOT USED

PROGRAMMER SCHEMATIC

DATE: 11/11/64

BY: [Signature]

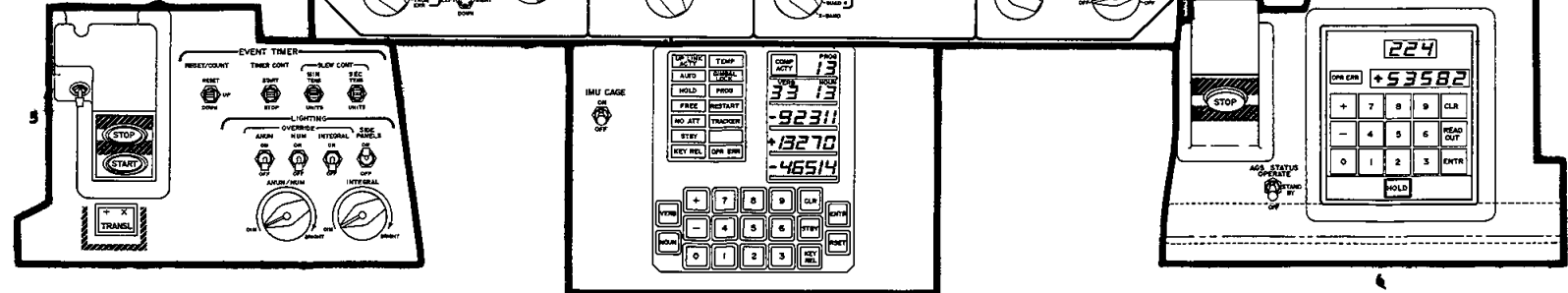
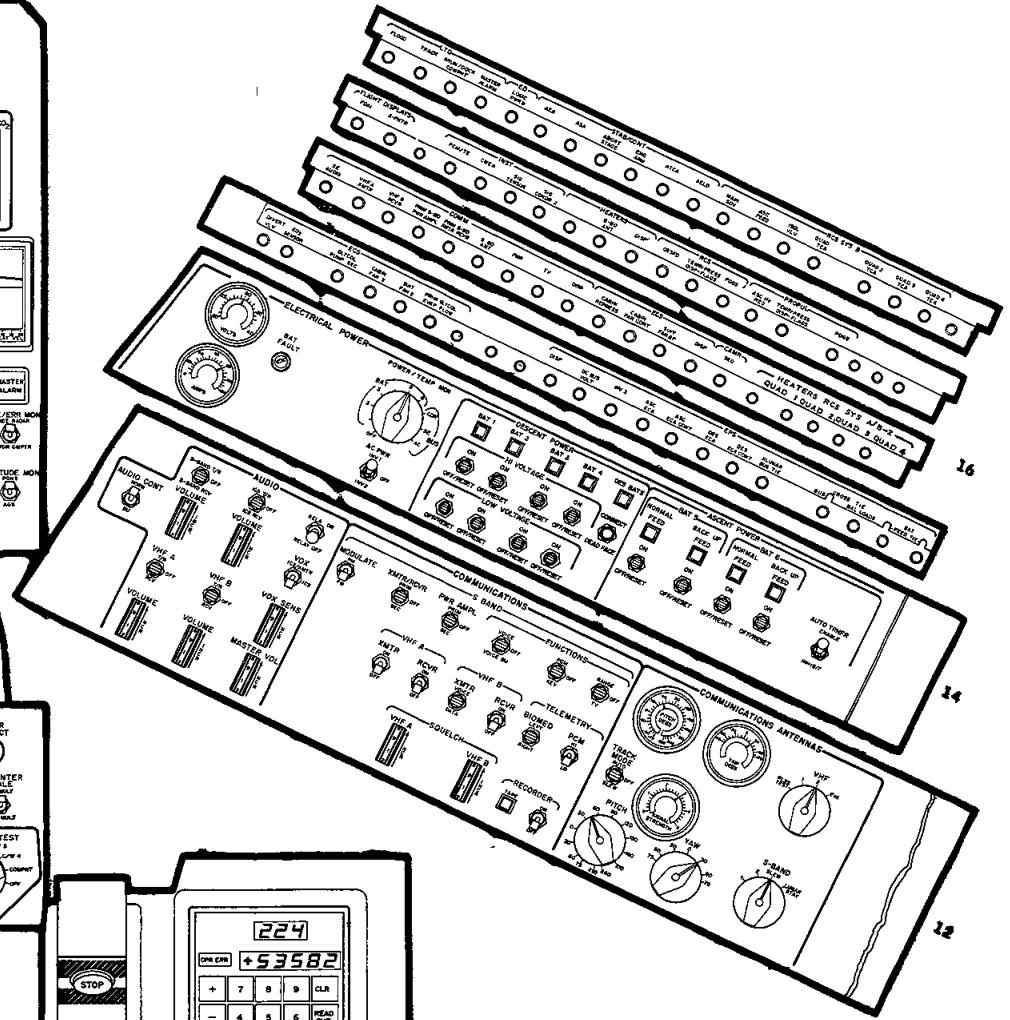
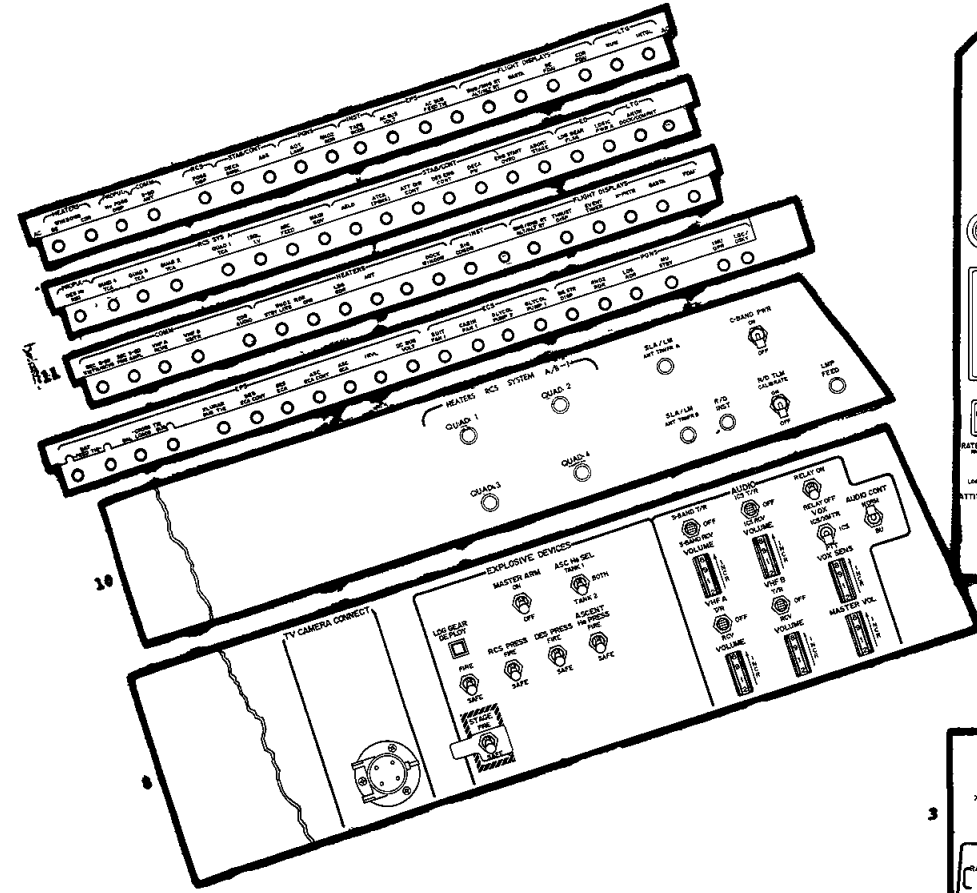
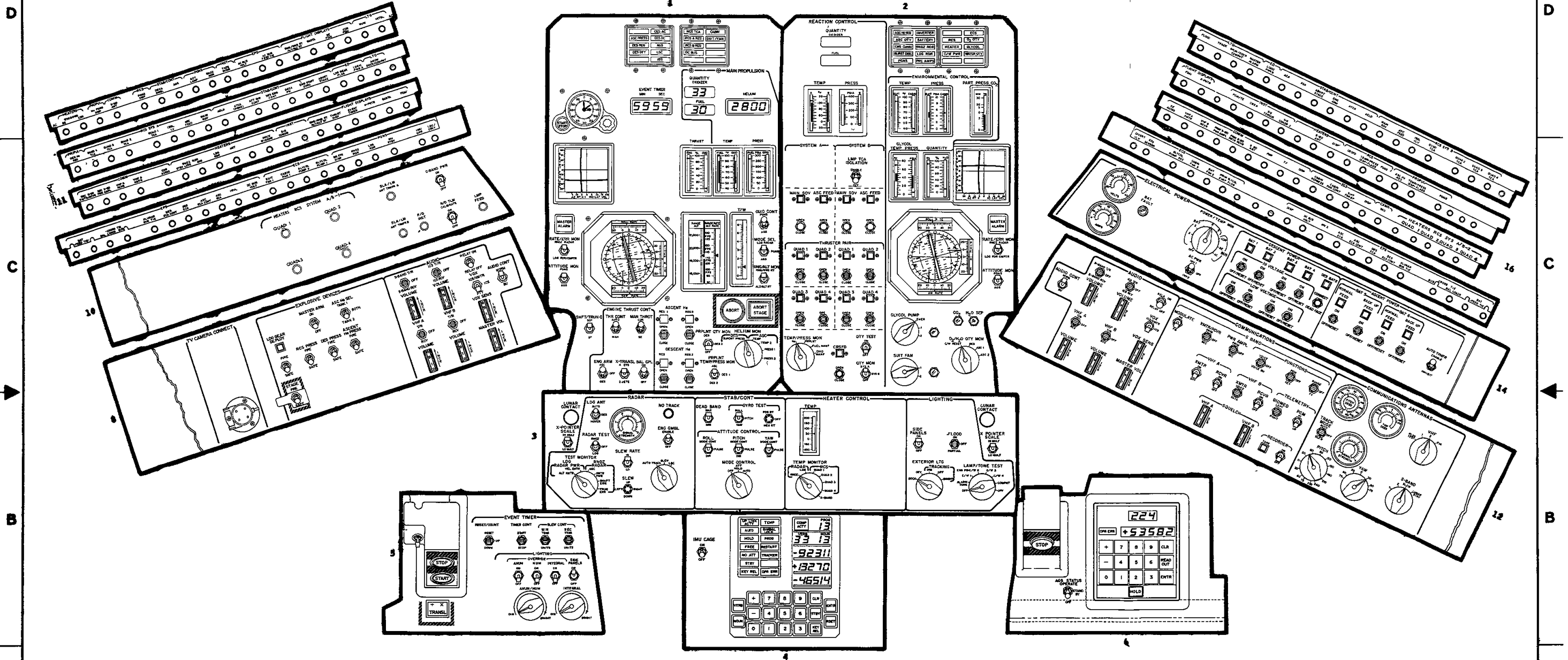
REVISION: 1

SCALE: 1:1

SHEET 1 OF 1

8 7 6 5 4 3 2 1

LTR ZONE	REVISION	DATE	APPROVAL
C		4/21/67	Good Knight



SIGNATURES		DATE	NATIONAL AERONAUTICS & SPACE ADMINISTRATION	
DR	<i>Sandra Boyd</i>	2/10/67	MANNED SPACECRAFT CENTER - HOUSTON TEXAS	
ENG	<i>Ed Lewis</i>	2-9-67		
CH	<i>Ed Lewis</i>	4/14/67		
GAEC	<i>Ed Lewis</i>	2-9-67		
APR	<i>Donald B. Kistner</i>	2/10/67		
AUTY	<i>Don Bray</i>	2-10-67		
			LM-1	DWG NO
			LM-1	15.1.1
			SCALE	SHEET 1 OF 1

\*

LM-1  
REV C

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16.2 SYSTEMS DATA

16.2.1 DF/COMM

A. VHF TRANSMITTER

- 1. RF POWER OUTPUT 10 WATTS
- 2. POWER INPUT 56 WATTS

B. C-BAND BEACON CHARACTERISTICS

- 1. RECEIVER
  - a. FREQUENCY 5690 MHZ
  - b. SENSITIVITY -70 dbm
  - c. INTERROGATION PULSE WIDTH 0.5 to 0.8  $\mu$ s
  - d. DECODER PULSE SPACING 3.5  $\pm$  0.1  $\mu$ s
- 2. TRANSMITTER
  - a. FREQUENCY 5765 MHZ
  - b. PULSE WIDTH 0.75  $\pm$  0.1  $\mu$ s
  - c. BEACON PULSE DELAY 3.0  $\pm$  0.1  $\mu$ s
  - d. PRF 0-2670 PPS
  - e. PEAK POWER OUTPUT 500 to 750 WATTS
  - f. PAVG (PEAK PWR - 750 WATTS) 0 to 1.5 WATTS
  - g. (PEAK PWR - 500 WATTS) 0 to 1 WATT

C. DCA RECEIVER CHARACTERISTICS

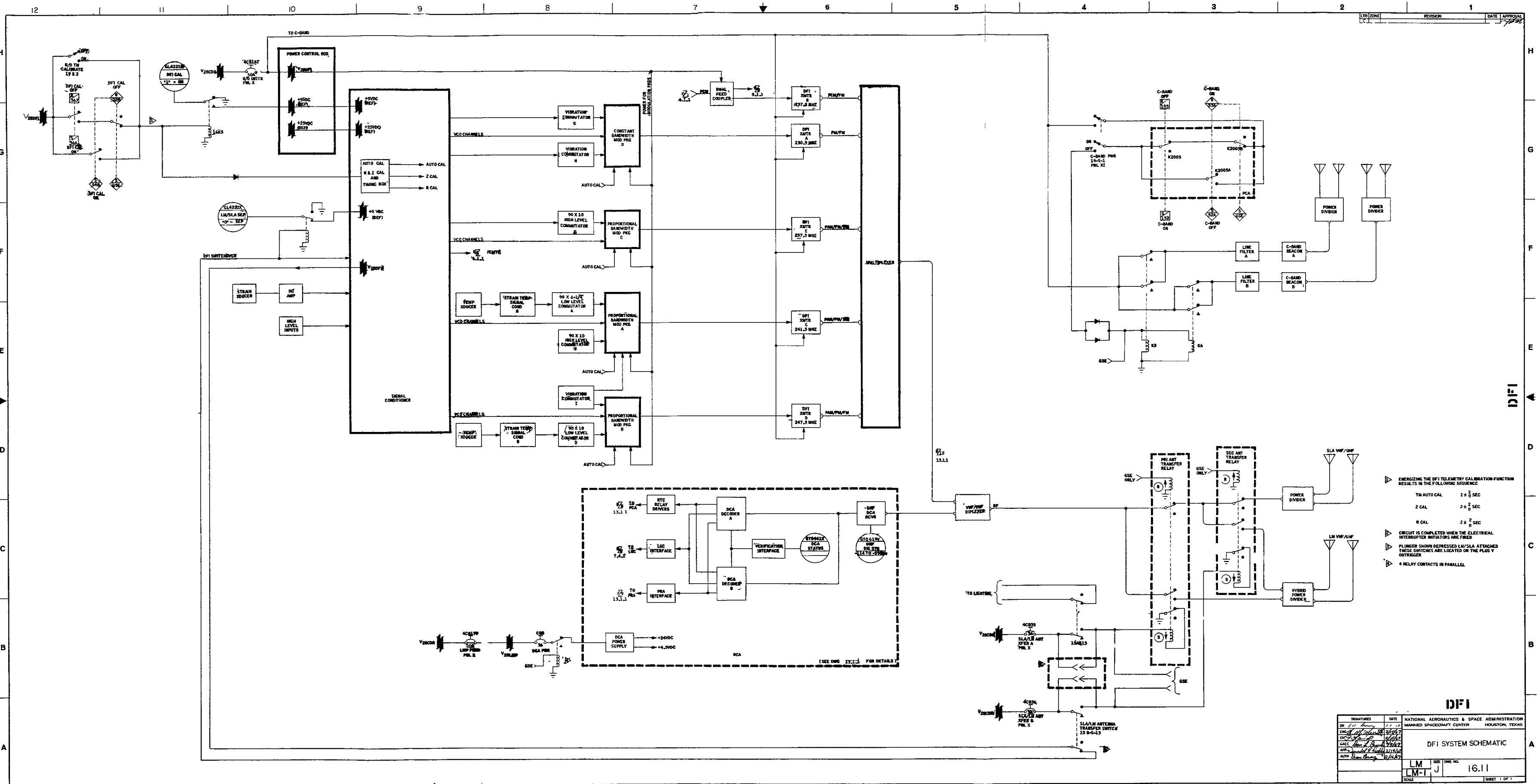
- 1. FREQUENCY 450 MHZ
- 2. SENSITIVITY -99 dbm

TABLE 16-1 PCM MEASUREMENTS AFFECTED BY DFICAL

MEAS NO.	MEAS DESCRIPTION	CAL APPLIED
0L4221X	DFICAL	INDICATES A "1" AND REMAINS "0" DURING CAL COMMAND

TABLE 16-2 PRELAUNCH STATUS OF SWITCH/CIRCUIT BREAKER POSITIONS

NAME	NUMBER	POSITION
SWITCH		
R/D TM CALIBRATE	1952 PBL X	OFF
C-BAND PWR	1951 PBL X	ON
CIRCUIT BREAKER		
R/D INST	4CB101	CLOSED
SLA/LM ANT XFER A	4CB35	CLOSED
SLA/LM ANT XFER B	4CB36	CLOSED
DCA PWR	CB5	CLOSED



- ▲ ENERGIZING THE DF-1 TELEMETRY CALIBRATION FUNCTION RESULTS IN THE FOLLOWING SEQUENCE
- TH AUTO CAL 2 ± 0 SEC
- Z CAL 2 ± 0 SEC
- R CAL 2 ± 0 SEC
- ▲ CIRCUIT IS COMPLETED WHEN THE ELECTRICAL INTERLOCK INITIATORS ARE FIRED
- ▲ FLINGER SHOWN DEPRESSED LM/SLA ATTACHED THESE SWITCHES ARE LOCATED ON THE PLUS V OUTRIGGER
- ▲ 4 RELAY CONTACTS IN PARALLEL

SIGNATURES		DATE	NATIONAL AERONAUTICS & SPACE ADMINISTRATION MANNED SPACECRAFT CENTER HOUSTON, TEXAS
DR	2-11	11-77	
CHK	10/10/77	11/77	
ESC	10/10/77	11/77	
APP	10/10/77	11/77	
AUTH	10/10/77	11/77	
DF-1 SYSTEM SCHEMATIC			
LM	J	16.11	
LM-1			
SCALE			(SHEET 1 OF 1)



**APOLLO**

**LM**

**LUNAR  
MODULE  
SYSTEMS  
HANDBOOK**

**VEHICLE LM-1**

**AS-204/LM-1  
REV C**



**FCD  
MSC  
NASA**