

MIT/IL PROGRAM CHANGE ROUTING SLIP

PCR/PCN # \_\_\_\_\_  
ANOMALY # L-1B-09

- COLOSSUS 2C
- COLOSSUS 2D
- COLOSSUS 2E
- COLOSSUS 2F

- LUMINARY 1B
- LUMINARY 1C
- LUMINARY 1D
- LUMINARY 1E

MIT Approved PCN

NASA Approved PCR  
 NASA Approved PCN

NASA Approved Software Anomaly  
 MIT Approved Software Anomaly

A. Coding

Begin coding immediately

Bruce McCoy

ACTION: \_\_\_\_\_

Program Supervisor's Approval: Maryout Kamelton

Do not code until new GSOP material has been approved by the MIT Mission Design Review Board (MDRB) and distributed.

B. GSOP Preparation

Prepare GSOP revisions for MDRB consideration

ACTION: \_\_\_\_\_

Technical Committee Meeting not required.

Technical Committee Meeting(s) held on \_\_\_\_\_  
Attendees: \_\_\_\_\_

C. KSC Testing and Checkout

Review for possible impact on KSC testing and checkout

ACTION: \_\_\_\_\_

D. Other Programs Affected

Review for corresponding changes in \_\_\_\_\_

ACTION: \_\_\_\_\_

Special Instructions

Project Manager- Russell H. Turner

Date 10-31-69

# MIT/IL SOFTWARE ANOMALY REPORT

MIT REPORT NO. <b>L-1B-09</b>
PROGRAM <b>LUMINARY</b>
PROGRAM REVISION <b>99, 116</b>

1.1 ORIGINATOR: <b>R. COVELLI</b>	1.2 ORGANIZATION: <b>MIT/IL</b>	1.3 DATE: <b>10/28/69</b>	1.4 ORIGINATOR CONTROL NO.
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1.5 DESCRIPTION OF ANOMALY:  
 If a restart occurs during a radar read, the following radar read may be incorrect. If this happens in R12, the state vector may be incorrectly updated.

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1.6 DESCRIPTION OF RUN:  
 Apollo 11 flight. There were two incorrect altitude readings in powered descent after software restarts.

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- MIT ANALYSIS -

2.1 CAUSE:  
 See Digital Development Memo #483, "LGC Radar Timing," by Allen Harano, 26 August 1969.

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2.2 RECOGNITION:  
 Monitor radar data on downlink.

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2.3 MISSION EFFECT:  
 With the current landing radar weighting functions, an altitude error of up to 4400 ft. could be introduced into the state vector. In the worst possible case;

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1 AVOIDANCE PROCEDURE:  
 None

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1 RECOVERY PROCEDURE:  
 Subsequent radar updates will correct the state vector.

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1 PROGRAM CORRECTION:  
 Inhibit incorporation of landing radar data on the first radar read after a restart.

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2.7 RECOMMENDED DISPOSITION (Fix, Work-around, etc):  
 Fix in LUMINARY 1C.

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2.8 RECOMMENDED RE-TESTING:  
 Digital simulation with restarts to verify that the radar data is not incorporated after a restart.

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2.9 MIT/IL SIGNATURE: <i>R. Covelli</i>	2.10 DATE: <b>11-31</b>
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3.1 NASA DIRECTION:

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4.1 CLOSING ACTION TAKEN:

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3.2 NASA/MSC SIGNATURE:	3.3 ORGANIZATION:	3.4 DATE:	4.2 SIGNATURE:	4.3 ORGANIZATION:	4.4 DATE:
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## 2.3 Mission Effect, cont'd.

the radar might indicate zero altitude. The altitude update,  $\Delta R$ , is then given by:

$$\Delta R_{\max} = W_h \Delta H = W_h (0 - H) = -W_h H$$

The present weighting function is

$$W_h = .35 (1 - H/50000)$$

so that

$$\Delta R_{\max} = -.35 H (1 - H/50000)$$

The following table gives the value of the update as a function of altitude in the case where the radar gives a zero reading:

H	$\Delta R_{\max}$
50000 ft.	0 ft.
40000	-2800
30000	-4200
25000	-4375
15000	-3675
10000	-2800
5000	-1675 (would fail reab. test)
1000	- 333

In Apollo 11, the two bad readings gave altitude errors of -1000 ft. and -272 ft., which was much less than the maximum possible error.