

DISPLAYS

MIT Instrumentation Laboratory

DG Memo No. 571

TO: Distribution

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SUBJECT: Preliminary DSKY Displays for Programs and Routines (AS204)

PRELIMINARY DSKY DISPLAYS FOR PROGRAMS AND ROUTINES (AS 204)

	<u>DISPLAY</u>	<u>UNITS</u>	<u>REMARKS</u>
P11	V N		
	R1 Gamma I	.01 DEG	Flight Path Angle
	R2 VI	.1 FPS	Velocity Inertial
	R3 H	.1 NM	Altitude above pad
P12	V N		
	R1 G Max	.1 G	
	R2 Delta V Ins	.1 FPS	Velocity reqd. for insertion
	R3 TFF	Min-sec.	
	V N		
	R1 Delta R	.1 NM	At SIVB shutdown
	R2 Delta V Ins	.1 FPS	
	R3 TFF	Min-sec.	
	DO R34		
	<u>FL</u> V N		Do orbit parameter ACK
	R1 Perigee alt.	.1 NM	
	R2 Apogee alt.	.1 NM	
	R3 TFF (if perigee less than 300000 ft)	Min-sec.	
	<u>FL</u> V N		Select Program 00
P21	FL V N		Load Pitch Angle
	R1 Pitch Angle	.01 DEG	X Axis Pitch Angle
Poss.	FL V N		Make decision to continue
	R1 TTE	Min-sec.	Time to Gimbal lock
	DO R1		
Poss.	<u>FL</u> V50 N		Perform G&N att. control selection in SCS
	<u>R1</u> Code		
	DO R21		
Poss.	<u>FL</u> V N		Align AGCU
	R1-OG CDU (present)	.01 DEG	CDU angle
	R2-IG	"	" "
	R3-MG	"	" "

	FL V N			Select G&N Att. Cont.
	R1-OG CDU (final)	.01	DEG	CDU Angle
	R2- IG		"	" "
	R3-MG		"	" "
Poss.	<u>FL</u> V N			Select G&N att. Cont.
P22	FL V50 N			Perform request auto
	R1 Code			optics positioning
Poss.	DO R28			
	<u>FL</u> V50 N			Perform entry of target
	R1 Code			data
Star:	V N			
	R1 Star code			
or LDMK:	V N			
	R1 Lat.	.01	DEG	
	R2 Long.	.01		
	R3 Alt.	.1	NM	Alt above equatorial
				radius
Poss.	FL V50 N			Perform OSS switch to AG
	R1 Code			mode
Poss.	FL N			Target beyond optics
	V N			limits
	R2 SA	.01	DEG	Required shaft angle
	<u>R3 TA</u>	.01	DEG	Required trunnion angle
DO	R27			
	<u>FL</u> V51			Please mark
	FL V21 N30			Load star code
or	<u>FL</u> V24 N36			Load landmark data

	FL	V	N			Do orbital parameter ACK
	R1					Orbital parameters
	R2					(undefined)
	R3					
P23	FL	V51				Please mark
	FL	V	N			Do optics angles ACK
	R1	SA		.01	DEG	Shaft angle
	R2	TA		.01	DEG	Trunnion angle
	FL	V	N			Do time ACK
	R1	GET			Hrs.	Time of mark
	R2	GET			Min.	
	R3	GET		.01	Sec.	
P27	FL	V 21N01				Do Data Load
	R3	Address				
	V	N				
	R1	Pos., vel. or time.	Octal			Pos., vel. and time in double precision. 14 loads of 5 digits reqd
	R3	Address				Specifies data load
	FL	V50	N			Perform enter
	R1	Code				

P31

DO R35

FL V N

For TIG ACK

R1 TIG Hrs. (Get)

Time to ignition

R2 TIG Min.

R3 TIG .01 Sec.

FL V N

For Apogee/Perigee ACK

R1 Lat. .01 DEG

R2 Long .01 DEG

R3 Alt. .1 NM

FL V N

For delta V ACK

R1 Delta V allow .1 FPS

R2 Delta V tail off .1 FPS

R3

FL V N

For trim angle ACK

R1 Pitch trim .01 DEG

SPS trim angle

R2 Yaw trim .01 DEG

SPS trim angle

FL V N

Do data ACK

R1 Alt. .1 NM

Alt. of apogee or perigee

R2 Delta V reqd. .1 FPS

SPS Delta V reqd. for
maneuver

R3 Miss .1 NM

Miss distance to apogee
or perigee

FL V N

Set clocks

R1 TTE Hrs.

Time to apogee or perigee

R2 TTE Min.

R3 TTE Sec.

DO R31				
<u>FL V N</u>				Set Delta V counter
R1 Delta V	.1	FPS		
FL V37 N51				Select program
FL V N				Maneuver SC or DO IMU/CSM A1.
R1 OG CDU	.01	DEG		CDU Angle
R2 IG CDU	.01	DEG		
R3 MG CDU	.01	DEG		
DO R1				
Poss. <u>FL V50 N</u>				Perform G&N att. control selection in SCS
R1 Code				
DO R21				
Poss. <u>FL V N</u>				Align AGCU
R1-OG CDU (present)	.01	DEG		CDU angle
R2-IG	"	"	"	" "
R3-MG	"	"	"	" "
FL V N				Select G&N Att. Cont.
R1-OG CDU (final)	.01	DEG		CDU Angle
R2-IG	"	"	"	" "
R3-MG	"	"	"	" "
Poss. <u>FL V N</u>				Select G&N Att. Cont.

P32

DO R36

FL V N

R1 Lat .01 DEG

R2 Long .01 DEG

Do Lat-Long data ACK

Lat of splash point

FL V N

R1 Delta V allow .1 FPS

R2 Delta V tail-off .1 FPS

Do Delta V data ACK

FL V N

R1 Pitch trim .01 DEG

R2 Yaw trim .01 DEG

Do trim angle ACK

SPS engine bell trim

FL V N

R1 TIG Hrs.

R2 TIG Min.

R3 TIG .01 Sec.

Do TIG ACK

Time of SPS Ignition

FL V N

R1 Gamma .01 DEG

R2 Delta R .1 NM

R3

Do Data ACK

Flight path angle

Miss distance

FL V N

R1 TTI Hrs.

R2 TTI Min.

R3 TTI Sec.

Set clocks

Time to ignition

DO R31

FL V N

R1 Delta V .1 FPS

Set Delta V counter

FL V37 N51

Select program

FL V N

Maneuver SC or DO IMU/CSM align.

R1 OG CDU .01 DEG

CDU angle

R2 IG CDU .01 DEG

CDU angle

R3 MG CDU .01 DEG

CDU angle

DO R1

Poss FL V50 N

Perform G&N att. control selection in SCS

R1 Code

DO R21

Poss FL V N

Align AGCU

R1 OG CDU (present) .01 DEG

CDU angle

R2 IG "

" "

R3 MG "

" "

FL V N

Select G&N att. control

R1 OG CDU (final) .01 DEG

CDU angle

R2 IG "

" "

R3 MG "

" "

Poss FL V N

Select G&N att. control

P41 or P42

<u>DO R2</u>		
Poss. <u>FL V50 N</u>		Perform Delta V mode
<u>R1 Code</u>		selection in SCS
FL V N		Align AGCU
R1 OG CDU	.01 DEG	CDU Angle
R2 IG CDU	.01 DEG	CDU Angle
R3 MG CDU	.01 DEG	CDU Angle
V N		
R1 TTE	Min-sec.	Time to thrusting
R2 VG	.1 FPS	Velocity to be gained
<u>DO R37</u>		
At TIG-20 Sec.		
R3 Delta VM	.1 FPS	Meas. delta V along SC X axis
<u>FL V N</u>		Set SPS engine ON
V N		
R1 TG	Min-sec.	Time to go to thrust cut-off
R2 VG	.1 FPS	Velocity to be gained
R3 TFF (P42 only)	Min-sec.	Time of free fall
<u>DO R24</u>		
<u>None</u>		
<u>DO R34</u>		
FL V N		Do orbit parameter ACK
R1 Perigee Alt.	.1 NM	
R2 Apogee Alt.	.1 NM	
R3 TFF (if perigee less than 300000 ft)	Min-sec.	

P46

FL V50 N
R1 Code

Perform prepare AGC
for thrusting

DO R24

None

FL V50 N
R1 Code

Perform terminate
program

P47

FL V50 N
R1 Code

Perform prepare AGC for
thrusting

DO R24

None

FL V50 N
R1 Code

Perform termination of
program

P51

LEB Checkout of displays

DO R1

Poss. FL V50 N
R1 Code

Perform G&N att. control
selection in SCS

FL V50 N
R1 Code

Perform star acquisition

DO R27

FL V51

Please mark

FL V21 N30

Load star code

or FL V24 N36

Load landmark data

DO R27

FL V51

Please mark

FL V21 N30

Load star code

or FL V24 N36

Load landmark data

DO R29

V N

Data good

R1 - angle diff. .01 DEG

or FL V N

Data bad

R1 - angle diff. .01 DEG

P52

Poss. V01 N31
R1 Code

Nav stars not visible

DO R4

Poss. DO R25

None

DO R28

Poss. FL V50 N
R1 Code

Perform entry of target
data

Star: V N
R1 Star code

or LDMK: V N

R1 Lat. .01 DEG

R2 Long. .01 DEG

R3 Alt. .1 NM

Alt above equatorial
radius

Poss. FL V50 N
R1 Code

Perform OSS switch to A
mode

Poss. FL N

Target beyond optics li

V N

R2 SA .01 DEG

Required shaft angle

R3 TA .01 DEG

Required trunnion angle

DO R27

FL V51

Please mark

FL V21 N30

Load star code

or FL V24 N36

Load landmark data

//

DO R30

1. FL V N

Accept or reject torquin
angles

R1 X GYRO .01 DEG

R2 Y GYRO .01 DEG

R3 Z GYRO .01 DEG

or 2. V N

Indicates data good

R1 X GYRO .01 DEG

R2 Y GYRO .01 DEG

R3 Z GYRO .01 DEG

FL V50 N

Perform fine align check
request

R1 Code

DO R21 (if not in P52)

Poss. FL V N

Align AGCU

R1-OG CDU (present) .01 DEG

CDU angle

R2-IG "

" "

R3-MG "

" "

FL V N

Select G&N att. cont.

R1-OG CDU (final) .01 DEG

CDU angle

R2-IG "

" "

R3-MG "

" "

Poss. FL V N

Select G&N att. cont.

=====

P53

DO R1

Poss. FL V50 N
R1 Code

Perform G&N att. control
selection in SCS

DO R25

None

DO R21

Poss. FL V N

Align AGCU

R1-OG CDU (present) .01 DEG

CDU angle

R2-IG " "

" "

R3-MG " "

" "

FL V N

Select G&N att. control

R1-OG CDU (final) .01 DEG

CDU angle

R2-IG " "

" "

R3-MG " "

" "

Poss. FL V N

Select G&N att. control

DO R4

Poss. DO R25

None

DO R28

Poss. FL V50N
R1 Code

Perform entry of target
data

Star: V N
R1 Star Code

or LDMK V N

R1 Lat. .01 DEG

R2 Long. .01 DEG

R3 Alt. .1 NM

Alt above equatorial
radius

Poss. FL V50 N
R1 Code

Perform OSS switch to AGC
mode

Poss. FL N		Target beyond optics limit
V N		
R2 SA	.01 DEG	Required shaft angle
R3 TA	.01 DEG	Required trunnion angle
<u>DO R27</u>		
FL V51		Please mark
FL V21 N30		Load star code
or <u>FL V24 N36</u>		Load landmark data
<u>DO R28</u>		
Poss. FL V50 N		Perform entry of target
R1 Code		data
Star: V N		
R1 Star code		
or LDMK: V N		
R1 Lat.	.01 DEG	
R1 Long.	.01 DEG	
R3 Alt.	.1 NM	Alt above equatorial radius
Poss. FL V50 N		Perform OSS switch to AGC
R1 Code		mode
Poss. FL N		Targets beyond optics limit
V N		
R2 SA	.01 DEG	Required shaft angle
R3 TA	.01 DEG	Required trunnion angle
<u>DO R27</u>		
FL V51		Please mark
FL V21 N30		Load star code
or <u>FL V24 N36</u>		Load landmark data

DO R28

Poss. FL V50 N
R1 Code

Perform entry of target
data

Star: V N
R1 Star code

or LDMK: V N

R1 Lat. .01 DEG
R2 Long. .01 DEG
R3 Alt. .1 NM

Alt above equatorial
radius

Poss. FL V50 N
R1 code

Perform OSS switch to AGC
mode

Poss. FL N

Target beyond optics limit

V N

R2 SA .01 DEG

Required shaft angle

R3 TA .01 DEG

Required trunnion angle

DO R27

FL V51

Please mark

FL V21 N30

Load star code

or FL V24 N36

Load landmark data

DO R29

V N

Data good

R1 - angle diff. .01 DEG

or FL V N

Data bad

R1 - angle diff. .01 DEG

DO R30

1. FL V N

Accept or reject torquing angles

R1 X GYRO .01 DEG

R2 Y GYRO .01 DEG

R3 Z GYRO .01 DEG

or 2. V N

Indicates data good

R1 X GYRO .01 DEG

R2 Y GYRO .01 DEG

R3 Z GYRO .01 DEG

FL V50 N

Perform fine align check request

R1 Code

DO R21 (if not in P52)

Poss. FL V N

Align AGCU

R1-OG CDU (present) .01 DEG

CDU angle

R2-IG "

" "

R3-MG "

" "

FL V N

Select G&N att. control

R1-OG CDU (final) .01 DEG

CDU angle

R2-IG "

" "

R3-MG "

" "

Poss. FL V N

Select G&N att. control

P61	FL V N		Set clocks
	R1 G Max.	.1 G	
	R2 Delta R	.1 NM	Miss distance
	R3 TFF	Min-sec.	
	<u>DO R1</u>		
Poss.	FL V50 N		Perform G&N att. control
	<u>R1 Code</u>		selection in SCS
	<u>DO R21</u>		
	FL V N		Align AGCU
	R1-OG CDU (present)	.01 DEG	CDU angle
	R2-IG	"	" "
	R3-MG	"	" "
	FL V N		Select G&N att. cont.
	R-OG CDU (final)	"	CDU angle
	R2-IG	"	" "
	R3-MG	"	" "
Poss.	<u>FL V</u> N		Select G&N att. cont.

P62

V N

R1 G Max. .1 G
 R2 Delta R .1 NM
 R3 TFF Min-sec.

FL V50 N
 R1 Code

Perform CM/SM separation

DO R3

FL V50 N
 R1 Code

Perform monitor mode
 selection in SCS
 Perform G&N entry mode
 selection in SCS

FL V50 N
 R1 Code
 DO R21

Poss. FL V N

R1-OG CDU (present) .01 DEG
 R2-IG " "
 R3-MG " "

Align AGCU

CDU angle

" "

" "

FL V N

Select G&N att.

R1-OG CDU (final) .01 DEG

CDU angle

R2-IG "

" "

R3-MG "

" "

Poss. FL V N

Select G&N att. control

P63

V N

R1 Beta .01 DEG

Commanded bank angle

R2 Delta R (entry) .1 NM

Predicted miss from aim point

R3 G .1 G

Present G

P71

V N

R1 G Max.	.1 G
R2 Delta V Ins	.1 FPS
R3 TFF	Min-sec.

DO R24

None

DO R1

Poss. FL V50 N
R1 Code

Perform G&N att. control selection in SCS

V N

R1 Delta R	.1 NM
R2 Delta V Ins	.1 FPS
R3 TFF	Min-sec.

P72

V N

R1 Delta R	.1 NM
R2 Delta V Ins	.1 FPS
R3 TFF	Min-sec.

Flash if thrust to recovery area feasible

Flash if contingency abort is feasible

Updated every - sec.

P73	FL V N		Set clocks
	R1 TTI	Min-sec.	Time to ignition
	R2 VG	.1 FPS	Velocity to be gained
	R3 TFF	Min-sec.	Time of free fall
	<u>DO R21</u>		
Poss.	<u>FL V N</u>		Align AGCU
	R1-OG CDU (present)	.01 DEG	CDU angle
	R2-IG	"	" "
	R3-MG	"	" "
	<u>FL V N</u>		Select G&N att. cont.
	R1-OG CDU (final)	.01 DEG	CDU angle
	R2-IG	"	" "
	R3-MG	"	" "
	<u>FL V N</u>		Select G&N att. cont.
	<u>V N</u>		
	R1 TTI	Min-sec.	
	R2 VG	.1 FPS	
	R3 TFF	Min-sec.	
	<u>DO R2</u>		
Poss.	<u>FL V50 N</u>		Perform Delta V mode
	<u>R1 Code</u>		selection in SCS
	<u>DO R37</u>		
	At TIG-20 Sec.		
	R3 Delta VM	.1 FPS	Meas. delta V along SC
			X axis.
	<u>FL V N</u>		Set SPS engine ON

V N

R1 TG

Min-sec.

Time to go to cut-off

R2

R3

DO R24

None

FL V37 N61

Select program

P74 FL V N

Set clocks

R1 TTI

Min-sec.

Time to ignition

R2 VG

.1 FPS

Velocity to be gained

R3 TFF

Min-sec.

Time of free fall

DO R21

Poss. FL V N

Align AGCU

R1-OG CDU (present)

.01 DEG

CDU angle

R2-IG

"

" "

R3-MG

"

" "

FL V N

Select G&N att. cont.

R1-OG CDU (final)

.01 DEG

CDU angle

R2-IG

"

" "

R3-MG

"

" "

Poss. FL V N

Select G&N att. cont.

V N

R1 TTI

R2 VG

R3 TFF

DO R2			
<u> </u>			
Poss. FL V50 N			Perform Delta V mode
<u>R1 Code</u>			selection in SCS
DO R37			
<u> </u>			
AT TIG-20 Sec.			
R3 Delta VM	.1	FPS	Meas. delta V along SC
			X axis
FL V N			Set SPS engine ON
<u> </u>			
V N			
R1 TG		Min-sec.	Time to cut-off
DO R24			
<u> </u>			
None			
<u> </u>			
FL V N			Press enter
<u> </u>			
DO R34			
<u> </u>			
FL V N			Do orbit parameter ACK
R1 Perigee Alt.	.1	NM	
R2 Apogee Alt.	.1	NM	
R3 TFF (if perigee			
less than 300000 ft)		Min-sec.	
<u> </u>			
FL V37 N21			Select program

ROUTINEUNITSREMARKS

R1	Poss. FL V50 N R1 Code			Perform G&N att. control selection in SCS
	DO R22			
R2	Poss. FL V50 N R1 Code			Perform Delta V mode selection in SCS
	DO R22			
R3	FL V50 N R1 Code			Perform monitor mode selection in SCS
	Poss. FL V50 N R1 Code			Perform G&N entry mode selection in SCS
R4	Poss. DO R25 DO R28 DO R27 DO R28 DO R27 DO R29 DO R30 DO R21 (if not in P52)			
R21	Poss. FL V N R1-OG CDU (present) R2-IG R3-MG FL V N R1-OG CDU (final) R2-IG R3-MG	.01 DEG " " .01 DEG " "		Align AGCU CDU angle " " " " Select G&N att. cont. CDU angle " " " "
	Poss. FL V N			Select G&N att. cont.

R22 NONE

R23 Key in desired data display A, B or C

A. Flash V50 N
R1 - Code

Perform Long. entry

R1 Long .01 DEG

Flash V N

Do time ACK

R1 Long .01 DEG

R2 TTE Min-sec.

B. Flash V50 N
R1 - Code

Perform time entry

R1 GET Hrs.

R2 GET Min.

R3 GET Sec.

Flash V N

Do Lat-Long ACK

R1 Lat. .01 DEG

R2 Long. .01 DEG

R3 Azimuth .01 DEG

C. Flash V N

Do DEC and TTE ACK

R1 DEC .01 DEG

R2 TTE Min-sec.

R3

R24 NONE

R25 NONE

R27	FL V51			Please mark
	FL V21 N30			Load star code
	or FL V24 N36			Load landmark data
	Poss. FL V04 N31 - R1 Code			Less than min. or max. than max. marks
R28	Poss. FL V50 N			Perform entry of target data
	R1 Code			
	Star: V N			
	R1 Star Code			
	or LDMK: V N			
	R1 Lat.	.01	DEG	
	R2 Long.	.01	DEG	
	R3 Alt.	.1	NM	Alt. above equatorial radiu
	Poss. FL V50 N			Perform OSS switch to AGC mode
	R1 Code			
	Poss. FL N			Target beyond optics limits
	V N			
	R2 SA	.01	DEG	Required shaft angle
	R3 TA	.01	DEG	Required trunnion angle
R29	V N			Data good
	R1 - angle diff.	.01	DEG	
	or FL V N			Data bad
	R1 - angle diff.	.01	DEG	
R30	1. FL V N			Accept or reject torquing angles
	R1 X GYRO	.01	DEG	
	R2 Y GYRO	.01	DEG	
	R3 Z GYRO	.01	DEG	

or 2. V N

Indicates data good

R1 X GYRO .01 DEG
R2 Y GYRO .01 DEG
R3 Z GYRO .01 DEG

FL V50 N
R1 Code

Perform fine align check
request

R31

FL V N
R1 Delta V .1 FPS

Set Delta V Counter

R34

FL V N
R1 Perigee Alt. .1 NM
R2 Apogee Alt. .1 NM
R3 TFF (if perigee Min-sec.
less than 300000 ft)

Do orbit parameter ACK

R35

FL V N
R1 TIG Hrs. (Get)
R2 TIG Min.
R3 TIG .01 Sec.

For TIG ACK
Time of ignition

FL V N
R1 Lat. .01 DEG
R2 Long. .01 DEG
R3 Alt. .1 NM

For Apogee/Perigee ACK

FL V N
R1 Delta V allow .1 FPS
R2 Delta V tail off .1 FPS
R3

For delta V ACK

FL V N
R1 Pitch trim .01 DEG
R2 Yaw trim .01 DEG

For trim angle ACK
SPS trim angle
SPS trim angle

R36	FL V N			Do Lat-Long data ACK
	R1 Lat	.01	DEG	Lat of splash point
	R2 Long	.01	DEG	
	FL V N			Do Delta V Data ACK
	R1 Delta V allow	.1	FPS	
	R2 Delta V tail off	.1	FPS	
	FL V N			Do trim angle ACK
	R1 Pitch trim	.01	DEG	SPS engine bell trim
	R2 Yaw trim	.01	DEG	
R37	At TIG-20 Sec.			
	R3 Delta VM	.1	FPS	Meas. delta V along SC X axis.
	FL V N			Set SPS engine ON
R38	FL V N			
	DO R24			

MIT Instrumentation Laboratory

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Appendix I

DEFINITIONS* FOR

APOLLO COMPUTER LOGIC CHECKLIST INTERFACE

- VI - Inertial velocity. In ft/sec to nearest .1 ft/sec.
- VG - Velocity to be gained. In ft/sec to nearest .1 ft/sec.
- DELTA V INS - Velocity required for insertion to a safe orbit. This value will be displayed whether such a delta V is within SPS capability or not. Update every sec. In ft/sec to nearest .1 ft/sec.
- DELTA V REQUIRED - SPS Delta V required to accomplish maneuver. In ft/sec to nearest .1 ft/sec.
- DELTA VM - Measured Delta V along SC + X axis starting from zero at start of display. In ft/sec to nearest .1 ft/sec.
- DELTA V COUNTER - AGC calculated value of velocity to be set into Delta V remaining counter. In ft/sec to nearest .1 ft/sec.
- DELTA V ALLOWABLE - Maximum amount of Delta V to be used in ft/sec to nearest .1 ft/sec.
- DELTA V TAILOFF - SPS engine Delta V after receipt of engine off command. In ft/sec to nearest .1 ft/sec.
- ALT - Altitude of apogee above equatorial radius if perigee is located over ground target or altitude of perigee if apogee is located over ground target. In nautical miles to nearest .1 nm.

* From MIT flight crew procedures work group.

- H - Vehicle altitude above the launch pad. In nautical miles to nearest .1 nm.
- LAT - Latitude in degrees to nearest .01 deg.
- LONG - Longitude in degrees to nearest .01 deg.
- DEC - Declination in degrees to nearest .01 deg.
- AZ - Azimuth in degrees to nearest .01 deg.
- DELTA R - Miss distance along ground track from discrete recovery area for free fall and entry. Assumes up lift equal to .17 times drag and no out of plane force during entry. Polarity indicates posigrade (+) or retrograde (-) burn required to hit recovery area. In nautical miles to nearest .1 nm.
- MISS - Minimum distance from computed ground track to stored desired lat and long of apogee or perigee whichever stored. + if track passes north of desired point. - if track passes south of desired point. In nautical miles to nearest .1 nm.
- DELTA R - Predicted miss distance from aim point. Polarity (entry) indicates lift required (+ up, - down) to drive Delta R to zero. In nautical miles to nearest .1 nm.
- TFF - Time of free fall to 300,000 ft altitude above equatorial radius. In minutes and seconds to nearest second. Max reading is 59 59.
- TG - Time to go to engine cut off. In min and sec to nearest sec.
- TTI - Time from now to ignition. In min and sec (1 register) or hrs, min, and sec (3 registers) dependent on program to nearest sec.
- TIG - Time of SPS ignition (GET). In hrs, min, sec to nearest sec.

- GET - Ground elapsed time measured from lift off. In hrs-min-sec to nearest sec.
- GAMMA I - Flight path angle: angle between inertial velocity and the local horizontal. In degrees to nearest .01 degree.
- BETA - Commanded bank angle. In degrees to nearest .01 deg.
- PITCH ANGLE - Angle measured from the forward horizontal positively about the negative orbital angular momentum vector to the SC X axis. + for SC Y axis in direction of negative angular momentum vector and - for SC Y axis in direction of positive angular momentum vector. In degrees to nearest .01 degree.
- SA - Optics shaft angle. In degrees to nearest .01 deg.
- TA - Optics trunnion angle. In degrees to nearest .01 deg.
- OG CDU - Outer gimbal angle. In degrees to nearest .01 deg.
- IG CDU - Inner gimbal angle.
- MG CDU - Middle gimbal angle.
- PITCH TRIM -
- YAW TRIM - SPS engine bell trim angles at ignition from data taken from fuel loading charts.
- G - Present G. In G's to nearest .1G.
- G MAX - Max predicted G for free fall and entry at bank angle of 60 deg (L/D max .34). In G's to nearest .1G.