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MIT Instrumentation Laboratory

DG Memo No. 571
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FROM: R. A. Larson, J. C. Dunbar

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SUBJECT: A Summary of DSKY Displays for Programs and
Routines for AS 204 — extracted from R507

MIT Instrumentation Laboratory

DG Memo No. 571
(Revision A)

DEFINITIONS* FOR
APOLLO COMPUTER LOGIC CHECKLIST INTERFACE

- VG - Magnitude of the velocity to be gained by the thrusting maneuver. In ft/sec to nearest ft/sec.
- VI - Inertial velocity. In ft/sec to nearest ft/sec.
- DELTA V INS - Total Delta V required for orbital insertion. If a two burn insertion is required, it includes both burns. In ft/sec to nearest ft/sec.
- DELTA V REQUIRED - SPS Delta V required to accomplish maneuver. In ft/sec to nearest ft/sec.
- DELTA VM - Measured Delta V along SC + X axis starting from zero at start of display. In ft/sec to nearest ft/sec.
- DELTA V RSS - The RSS magnitude of Delta V measured. In ft/sec to nearest ft/sec.
- DELTA V (SCS) - AGC calculated value of velocity to be set into Delta V remaining counter. In ft/sec to nearest ft/sec.
- DELTA V ALLOWABLE - Maximum amount of Delta V to be used. In ft/sec to nearest ft/sec.
- DELTA V TAILOFF - SPS engine Delta V after receipt of engine off command. In ft/sec to nearest ft/sec.
- DELTA V DIFF - Magnitude of the difference between the velocity state vector before and after incorporation of the landmark sighting data. In ft/sec to nearest ft/sec.

* From MIT flight crew procedures work group.

T GIM LOC - Time to gimbal lock if local vertical is started now. In minutes and seconds to nearest second.

TFF - Time of free fall to 300,000 ft altitude above mean equatorial radius. In minutes and seconds to nearest second. Max. reading is 59 59.

TG - Time to go to engine cut off. In minutes and seconds to nearest second.

TTI - Time to go to SPS ignition. In min and sec (1 register) to nearest sec or hrs, min, and sec (3 registers) dependent on program to nearest .01 sec.

TIG - Time of SPS ignition (GET). In hrs, min, sec to nearest .01 sec.

T MARK - Time of mark (GET), in hrs, min, sec to nearest .01 sec.

PER - Period of desired orbit. In hrs, min, sec to nearest .01 sec.

DELTA T BURN - Desired SPS burn time. In min and sec to nearest sec.

T MAX DEC - First time of arrival (GET) at maximum orbital declination after a specified time (GET). In hrs, min, sec to nearest .01 sec.

T PERM IG - Earliest possible time (GET) of SPS ignition. In hrs, min, sec to nearest .01 sec.

T PERM LONG - Earliest permissible time (GET) of next arrival at the specified longitude. In hrs, min, sec to nearest .01 sec.

T PERM DEC - Earliest permissible time (GET) of next time of orbit maximum declination. In hrs, min, sec to nearest .01 sec.

T LAT LONG - Time (GET) at which LAT and LONG of vehicle position is desired. In hrs, min, sec to nearest .01 sec.

T LONG - Time (GET) at which vehicle will be at specified longitude. In hrs, min, sec to nearest .01 sec.

GET - Ground elapsed time measured from lift off. In hrs, min, sec to nearest .01 sec.

ALT - Altitude of desired orbit above mean equatorial radius at the specified ground point. In nautical miles to nearest .01 NM. This value should be zero if circular orbit is desired.

IND ALT - Computed altitude above mean equatorial radius. In nautical miles to nearest .1 NM.

H - Vehicle altitude above the launch pad. In nautical miles to nearest .1 NM.

PERIGEE ALT - Altitude of perigee above the mean equatorial radius. In nautical miles to nearest .1 NM.

APOGEE ALT - Altitude of apogee above the mean equatorial radius. In nautical miles to nearest .1 NM.

LAT - Latitude. Plus is north. In degrees to nearest .01 deg.

LONG - Longitude. Plus is east. In degrees to nearest .01 deg.

DEC - Declination. In degrees to nearest .01 deg.

AZ - Azimuth. In degrees to nearest .01 deg.

MAX DEC - The first maximum declination of the orbit after a specified time (GET). In degrees to nearest .01 degree.

LAT SPLASH - Latitude of desired splash point. In degrees to nearest .01 degree. + is North.

LONG SPLASH - Longitude of desired splash point. In degrees to nearest .01 degree. + is East.

DELTA P - Magnitude of the difference between the position state vector before and after incorporation of the landmark sighting data. In nautical miles to nearest .1 NM.

DELTA R - Miss distance along ground track from discrete recovery area for free fall and entry. Assumes up lift equal to .17 times drag and no out of plane force during entry. Polarity indicates overshoot (+) or undershoot (-) of recovery area. In nautical miles to nearest .1 NM.

G - Present G. In G's to nearest .1G.

G MAX - Max predicted G for free fall and entry at bank angle of 60 deg (L/D max = .34). In G's to nearest .1G.

STAR ANGLE DIFF - Difference between actual and indicated angles between star vector #1 and star vector #2. In degrees to nearest .01 degree.

X GYRO, Y GYRO, Z GYRO - Gyro torquing angles. The angle through which each gyro must be torqued to complete the fine alignment. All angles in degrees to nearest .001 degree.

GAMMA I - Inertial flight path angle: angle between inertial velocity and the local horizontal. In degrees to nearest .01 degree.

BETA - Commanded bank angle. In degrees to nearest .01 deg.

PITCH ANGLE - Angle measured positively going up from forward local horizontal to SC X align. In degrees to nearest .01 degree. +00001 (in R2) for heads up or -00001 for heads down.

SHAFT - Optics shaft angle. In degrees to nearest .001 deg.

TRUNNION - Optics trunnion angle. In degrees to nearest .001 deg.

OG ROLL - Outer gimbal angle. In degrees to nearest .01 deg.

IG PITCH - Inner gimbal angle. In degrees to nearest .01 deg.

MG YAW - Middle gimbal angle. In degrees to nearest .01 deg.

PITCH TRIM and YAW TRIM - SPS engine bell trim angles at ignition from data taken from fuel loading charts and vehicle fuel gauges. In degrees to nearest .01 deg.

DISPLAY

UNITS

REMARKS

Program 11

V16 N40

R1 - GAMMA I

R2 - VI

R3 - H PAD

xxx. xx DEG

xxxxx. Ft/sec

xxxx. x NM

Monitor launch

Program 12

V 16 N41

R1 - G MAX

R2 - PERIGEE ALT

R3 - TFF

xxxx. x G

xxxx. x NM

xx-xx MIN-SEC

Monitor launch

FL V 16 N42

R1 - DELTA R

R2 - PERIGEE ALT

R3 - TFF

xxxx. x NM

xxxx. x NM

xx-xx MIN-SEC

Request Proceed

Monitor Launch

DO R34

orbital parameter display

Program 17

V16 N40

R1 - GAMMA I

R2 - VI

R3 - H

xxx. xx DEG

xxxxx. Ft/sec

xxxx. x NM

To monitor abort
parameter

Program 21

FL V24 N06

FL V16 N36

R1 - T GIM LOC

DO RI

DO R21

xx-xx MIN-SEC

Load pitch angle and heads
up or down

Request proceed

Att. control mode check

Attitude maneuver

<u>DISPLAY</u>	<u>UNITS</u>	<u>REMARKS</u>
<u>Program 22</u>		
FL V50 N25		Please perform manual optics positioning Auto optics positioning Sighting mark Request proceed
R1 - 00011		
DO R28 (if desired)		
DO R27		
FL V06 N75		
R1 DELTA P	xxxxx. Ft	
R2 DELTA V	xxxxx. Ft/sec	
<u>Program 23</u>		
FL V51		Request MARK
FL V06 N57		
R1 - SHAFT ANGLE	xxx.xx DEG	To transmit data on down TLM
R2 - TRUNNION ANGLE	xxx.xx DEG	
FL V06 N34		
R1 - T MARK HRS	xxxxx. HRS	
R2 - T MARK MIN	xxxxx. MIN	
R3 - T MARK SEC	xxx.xx SEC	
<u>Program 27</u>		
V05 N31		
R1 - 00410		Program alarm if P27 not allowed
FL V21 N01		Request data load
R1 - BLANK		
R2 - BLANK		
R3 - UPADR		(Repeated as required)
FL V21 N02		Request octal identifier to load corrected data
R1 - BLANK		
R2 - BLANK		
R3 - UPADR		(Repeated as required)

DISPLAY

UNITS

REMARKS

Program 31

DO R35

Prethrust orbit change data
load

FL V06 N45

R1 - PERIGEE ALT

xxxx.x NM

Request proceed or exit
To evaluate data

R2 - APOGEE ALT

xxxx.x NM

R3 - DELTA V REQD

xxxxx. Ft/sec

FL V06 N35

R1 - TTI HRS

xxxxx. HRS

Request proceed
To set DET

R2 - TTI MIN

xxxxx. MIN

R3 - TTI SEC

xxx.xx SEC

DO R31

Backup Delta V Counter

FL V50 N07

R1 - 00051

Please perform or exit
Select P51

FL V06 N17

R1 OG ROLL

xxx.xx DEG

Request proceed or exit
To evaluate IG angle

R2 IG PITCH

xxx.xx DEG

R3 MG YAW

xxx.xx DEG

DO R1

Att. control mode check

DO R21

Att. maneuver

FL V50 N07

R1 - 00041

Please perform
Select P41

<u>DISPLAY</u>	<u>UNITS</u>	<u>REMARKS</u>
<u>Program 32</u>		
DO R36		Prethrust return to earth data load
FL V06 N34		<u>Request proceed</u>
R1 - TIG HRS	xxxxx. HRS	To evaluate data
R2 - TIG MIN	xxxxx. MIN	
R3 - TIG SEC	xxx. xx SEC	
FL V06 N47		<u>Request proceed or exit</u>
R1 - GAMMA I	xxx. xx DEG	Data coordination
R2 - DELTA R	xxxx. x NM	with ground
FL V06 N35		<u>Request proceed</u>
R1 - TTI HRS	xxxxx. HRS	To update DET
R2 - TTI MIN	xxxxx. MIN	
R3 - TTI SEC	xxx. xx SEC	
FL V50 N07		Please perform or exit
R1 - 00051		Select P51
FL V06 N17		<u>Request proceed or exit</u>
R1 - OG ROLL	xxx. xx DEG	To evaluate IG angle
R2 - IG PITCH	xxx. xx DEG	
R3 - MG YAW	xxx. xx DEG	
DO R1		Att. cont. mode ck.
DO R21		Att. maneuver
FL V50 N07		Please perform
R1 - 00042		

<u>DISPLAY</u>	<u>UNITS</u>	<u>REMARKS</u>
<u>Program 33</u>		
DO R33		Prethrust SPS MIN IMPULSE
FL V06 N45		Request proceed
R1 - APOGEE ALT	xxxx. x NM	Evaluate data
R2 - PERIGEE ALT	xxxx. x NM	
R3 - DELTA V REQD	xxxxx. Ft/sec	
FL V06 N35		Request proceed
R1 - TTI HRS	xxxxx. HRS	Evaluate data
R2 - TTI MIN	xxxxx. MIN	
R3 - TTI SEC	xxx. xx SEC	
DO R 31		Backup Delta V Counter
FLV50 N07		Please perform or exit
R1 - 00051		Select P51
FL V06 N17		Request proceed or exit
R1 OG ROLL	xxx. xx DEG	To evaluate IG angle
R2 IG PITCH	xxx. xx DEG	
R3 MG YAW	xxx. xx DEG	
DO R1		Att. control mode check
DO R21		Att. maneuver
FL V50 N07		Please perform
R1 - 00043		Select P43

<u>DISPLAY</u>	<u>UNITS</u>	<u>REMARKS</u>
<u>Program 41 and 42</u>		
DO R2		Thrust cont. mode ck.
FL V16 N20		<u>Request proceed</u>
R1 - OG ROLL	xxx. xx DEG	To align AGCU
R2 - IG PITCH	xxx. xx DEG	
R3 - MG YAW	xxx. xx DEG	
V16 N51		
R1 - TTL	xx-xx MIN-SEC	To update DET
R2 - VG	xxxxx. Ft/sec	
R3 - 00000		
DO R37		SPS ignition
V16 N51		
R1 - TG	xx-xx MIN-SEC	To monitor burn
R2 - VG	xxxxx. Ft/sec	
R3 - DELTA VM	xxxxx. Ft/sec	
IF P42: V16 N52		
R1 - TG	xx-xx MIN-SEC	To monitor burn
R2 - VG	xxxxx. Ft/sec	
R3 - TFF	xx-xx MIN-SEC	
FL V06 N51 (IF P41)		<u>Request proceed</u>
R1 TG	xx-xx MIN-SEC	To monitor cut-off
R2 VG	xxxxx. Ft/sec	
R3 DELTA VM	xxxxx. Ft/sec	
FLV06 N52 (IF P42)		<u>Request proceed</u>
R1 TG	xx-xx MIN-SEC	To monitor cut off
R2 VG	xxxxx. Ft/sec	
R3 TFF	xx-xx MIN-SEC	
DO R34		Orbital parameter display
IF P42: FL V50 N07		Please perform
R1 - 00001		

<u>DISPLAY</u>	<u>UNITS</u>	<u>REMARKS</u>
<u>Program 43</u>		
DO R2		Thrust control mode check
FL V16 N20		Request proceed
R1 - OG ROLL	xxx.xx DEG	For AGCU align
R2 - IG PITCH	xxx.xx DEG	
R3 - MG YAW	xxx.xx DEG	
V16 N50		
R1 - TTI	xx-xx MIN-SEC	
R2 - DELTA T BURN	xx-xx MIN-SEC	
R3 - 00000		
DO R37		SPS engine ignition
V06 N50		
R1 - TTI	xx-xx MIN-SEC	
R2 - DELTA T BURN	xx-xx MIN-SEC	
R3 - DELTA VM	xxxxx. Ft/sec	
DO R34		Orbit parameter display
<u>Program 46</u>		
FL V50 N25		Please perform
R1 - 00035		Prepare AGC for thrusting
FL V16 N13		Request proceed
R1 DELTA V (RSS)	xxxxx. Ft/sec	
<u>Program 47</u>		
FL V50 N25		Please perform
R1 - 00035		Prepare AGC for thrusting
FL V16 N13		Request proceed
R1 DELTA V (RSS)	xxxxx. Ft/sec	

DISPLAY

UNITS

REMARKS

Program 51

DO R1

Att. control mode check

FL V50 N25

Please perform

R1 - 00015

DO R27

Sighting mark for star #1

DO R27

Sighting mark for star #2

DO R29

Star data test

Program 52

V01 N31

Program Alarm if stars
not visible

R1 - 402

DO R4

Common alignment

Program 53

DO R1

Att. control mode check

DO R25

Coarse align

DO R21

Attitude maneuver

DO R4

Common alignment

FL V50 N07

Please perform selection
of P00

R1 - 00000

<u>DISPLAY</u>	<u>UNITS</u>	<u>REMARKS</u>
<u>Program 61</u>		
V05 N31		Program alarm for IMU
R1 - 1106		orientation unsatisfactory
FL V16 N53		Request proceed
R1 - G MAX	xxxx. x G	
R2 - TFF	xx-xx MIN-SEC	Set TFF in DET
DO R1		Att. control mode check
DO R21		Attitude maneuver
<u>Program 62</u>		
DO R3		Entry control mode check
FL V50 N25		Please perform CM/SM sep.
R1 - 00041		
DO R21		Attitude maneuver
<u>Program 63</u>		
V16 N54		
R1 - BETA	xxx. xx DEG	
R2 - G	xxxx. x G	
R3 - IND ALT	xxxx. x NM	
<u>Program 64</u>		
V16 N54		
R1 - BETA	xxx. xx DEG	Monitor entry
R2 - G	xxx. xx G	
R3 - IND ALT	xxxxx. 10 FT	

DISPLAY

UNITS

REMARKS

Program 71

V16 N41

R1 - G MAX

R2 - PERIGEE ALT

R3 - TFF

xxxx. x G

xxxx. x NM

xx-xx MIN-SEC

DO R1

Att. control mode check

V16 N42

R1 - DELTA R

R2 - PERIGEE ALT

R3 - TFF

xxxx. x NM

xxxx. x NM

xx-xx MIN-SEC

Program 72

FL V16 N62

R1 - DELTA R

R2 - DELTA V INS

R3 - TFF

xxxx. x NM

xxxxx. Ft/sec

xx-xx MIN-SEC

Request proceed or exit

POSS FL R2

If contingency orbit feasible

POSS FL R1

If thrusting to discrete re-
covery area feasible

<u>DISPLAY</u>	<u>UNITS</u>	<u>REMARKS</u>
<u>Program 73</u>		
FL V16 N52		<u>Request proceed</u>
R1 TTI	xx-xx MIN-SEC	To set DET
R2 VG	xxxxx. Ft/sec	
R3 TFF		
DO R21		Attitude maneuver
DO R2		Thrust control mode check
V16 N51		
R1 - TTI	xx-xx MIN-SEC	Recall display
R2 - VG	xxxxx. Ft/sec	
R3 - 00000		
DO R37		SPS engine ignition
V16 N52		
R1 - TG	xx-xx MIN-SEC	Monitor burn
R2 - VG	xxxxx. Ft/sec	
R3 - TFF	xx-xx MIN-SEC	

DISPLAY

UNITS

REMARKS

Program 74

FL V16 N52

R1 - TTI

R2 - VG

R3 - TFF

xx-xx MIN-SEC

xxxxx. Ft/sec

xx-xx MIN-SEC

Request proceed

DO R21

Att. Maneuver

DO R2

Thrust control mode check

V16 N51

R1 - TTI

R2 - VG

R3 - 00000

xx-xx MIN-SEC

xxxxx. Ft/sec

SPS ignition

DO R37

V16 N51

R1 - TG

R2 - VG

R3 - DELTA VM

xx-xx MIN-SEC

xxxxx. Ft/sec

xxxxx. Ft/sec

Request proceed

FL V06 N51

R1 - TG

R2 - VG

R3 - DELTA VM

Orbit parameter display

DO R34

<u>DISPLAY</u>	<u>UNITS</u>	<u>REMARKS</u>
<u>Program 75</u>		
FL V16 N46		Request proceed
R1 - TTI	xx-xx MIN-SEC	SET DET
R2 - VG	xxxxx. Ft/sec	
R3 - PERIGEE ALT	xxxx. x NM	
FL V06 N70		Request proceed
R1 PITCH TRIM	xxx. xx DEG	Evaluate data
R2 YAW TRIM	xxx. xx DEG	
R3 DELTA V TAILOFF	xxxxx. Ft/sec	
DO R21		Attitude maneuver
DO R2		Thrust control mode check
V16 N51		
R1 - TTI	xx-xx MIN-SEC	Set DET
R2 - VG	xxxxx. Ft/sec	
R3 - 00000		
DO R37		SPS engine ignition
V16 N51		
R1 - TTI	xx-xx MIN-SEC	
R2 - VG	xxxxx. Ft/sec	
R3 - DELTA VM	xxxxx. Ft/sec	
DO R24		Delta V monitor
FL V06 N51		Request proceed
R1 - TG	xx-xx MIN-SEC	
R2 - VG	xxxxx. Ft/sec	
R3 - DELTA VM	xxxxx. Ft/sec	
DO R34		Orbital parameter display

<u>DISPLAY</u>	<u>UNITS</u>	<u>REMARKS</u>
<u>Routine 1</u> If not in G&N att cont: FL V50 N25 R1 - 00001		Attitude control mode check Please perform G&N att cont select
<u>Routine 2</u> If not in G&N DELTA V: FL V50 N25 R1 - 00002		Thrust control mode check Please perform G&N DELTA V mode select
<u>Routine 3</u> FL V50 N25 R1 - 00004 If not in G&N entry mode FL V50 N25 R1 - 00003		Entry control mode check Please perform SCS att control mode select Please perform G&N entry mode select
<u>Routine 4</u> DO R25 (IF P52) DO R28 DO R27 DO R28 DO R27 DO R29 DO R30 DO R21 (IF not P52)		Common alignment Coarse align Auto optics positioning for star #1 Sighting mark for star #1 Auto optics positioning for star #2 Sighting mark for star #2 Star data test Fine align Attitude maneuver

DISPLAY

UNITS

REMARKS

Routine 21

FL V16 N20

R1 - OG ROLL

R2 - IG PITCH

R3 - MG YAW

xxx. xx DEG

xxx. xx DEG

xxx. xx DEG

Attitude maneuver

Request proceed
present gimbal angles

FL V06 N17

R1 - OG ROLL

R2 - IG PITCH

R3 - MG YAW

xxx. xx DEG

xxx. xx DEG

xxx. xx DEG

Request proceed
desired gimbal
angles

FL V50 N25

R1 - 00007

Please perform
attitude trim maneuver
enable

Routine 22

V03 N31

R1 - 405

For alarm situation
Program alarm code

<u>DISPLAY</u>	<u>UNITS</u>	<u>REMARKS</u>
<u>Routine 23</u>		
A. If V65 entered:		
FL V22 N44		Request load longitude
FL V25 N34		Request load T PERM LONG
FL V06 N34		Request proceed
R1 - T LONG	xxxxxx. HRS	
R2 - T LONG	xxxxxx. MIN	
R3 - T LONG	xxx. xx SEC	
B. If V66 entered:		
FL V25 N34		Request load T LAT LONG
FL V06 N44		
R1 - LAT	xxx. xx DEG	
R2 - LONG	xxx. xx DEG	
R3 - 00000		
C. If V67 entered:		
FL V25 N34		Request load T PERM DEC
FL V06 N44		Request proceed
R1 - NAX DEC	xxx. xx DEG	
R2 - 00000		
R3 - 00000		
FL V06 N34		Request proceed
R1 - T MAX DEC	xxxxxx. HRS	
R2 - T MAX DEC	xxxxxx. MIN	
R3 - T MAX DEC	xxx. xx SEC	
<u>Routine 24</u>		
		Delta V Monitor
	No DSKY displays	
<u>Routine 25</u>		
		Coarse Alignment
	No DSKY displays	
<u>Routine 27</u>		
FL V51		Sighting mark
FL V21 N30		Please mark
FL V25 N44		Load star data
		Load landmark data

DISPLAY

UNITS

REMARKS

Routine 28

Auto optics positioning

A. If this is P22:

FL V06 N44

R1 - LAT

xxx. xx DEG

R2 - LONG

xxx. xx DEG

R3 - ALT

xxxx. x NM

Request proceed

B. If this is not P22:

FL V06 N30

R1 - STAR CODE

Request proceed

If not in AGC mode:

FL V50 N25

R1 - 00013

Please perform
switch to AGC mode

If optics angles
excessive:

FL V05 N31

R1 - 00402

V16 N57

R1 - SHAFT

xx. xxx DEG

R2 - TRUNNION

xx. xxx DEG

Routine 29

Stardata test

If data good:

V06 N05

R1 - STAR ANGLE

xxx. xx DEG

DIFF

If data bad:

FL V06 N05

R1 - STAR ANGLE

xxx. xx DEG

DIFF

Request proceed

DISPLAY

UNITS

REMARKS

Routine 30

If data good:

V06 N67

R1 - X GYRO

xx. xxx

Data evaluation

R2 - Y GYRO

xx. xxx

R3 - Z GYRO

xx. xxx

If data bad:

FL V06 N67

R1 - X GYRO

xx. xxx

Request proceed

R2 - Y GYRO

xx. xxx

Data evaluation

R3 - Z GYRO

xx. xxx

FL V50 N25

R1 - 00014

Please perform

Fine align check

Routine 31

FL V06 N14

R1 - DELTA V (SCS)

Backup Delta V Counter Display

Request proceed

DISPLAY

UNITS

REMARKS

Routine 33

FL V06 N34

R1 - TIG - HRS

xxxxx. HRS

R2 - TIG - MIN

xxxxx. MIN

R3 - TIG - SEC

xxx. xx SEC

Minimum impulse data load

Request proceed

FL V06 N44

R1 - LAT

xxx. xx DEG

R2 - LONG

xxx. xx DEG

R3 - ALT

xxxx. x NM

Request proceed

Load parameters

FL V06 N45

R1 - PER HRS

xxxxx. HRS

R2 - PER MIN

xxxxx. MIN

R3 - PER SEC

xxx. xx SEC

Request proceed

Load period of
desired orbit

FL V06 N70

R1 - PITCH TRIM

xxx. xx DEG

R2 - YAW TRIM

xxx. xx DEG

R3 - DELTA V TAILOFF

xxxxx. Ft/sec

Request proceed

Load data

FL V06 N35

R1 - DELTA T BURN

xxxxx. HRS

R2 - DELTA T BURN

xxxxx. MIN

R3 - DELTA T BURN

xxx. xx SEC

Request proceed

Load data

<u>DISPLAY</u>	<u>UNITS</u>	<u>REMARKS</u>
<u>Routine 34</u>		Orbit parameter display
If not in P42:		
FL V06 N43		<u>Request proceed</u>
R1 - PERIGEE ALT	xxxx. x NM	Evaluate parameters
R2 - APOGEE ALT	xxx. x NM	
R3 - TFF	xx-xx MIN-SEC	
(TFF displayed only if PERIGEE is less than 300,000 ft)		
If PERIGEE is less than 300,000 ft:		
FL V06 N34		<u>Request proceed</u>
R1 T PERIGEE HRS	xxxxx. HRS	
R2 T PERIGEE MIN	xxxxx. MIN	
R3 T PERIGEE SEC	xxx. xx SEC	
If in P42:		
FL V16 N64		<u>Request proceed</u>
R1 LAT SPLASH	xxx. xx DEG	Evaluate parameters
R2 LONG SPLASH	xxx. xx DEG	
R3 TFF	xx-xx MIN-SEC	
<u>Routine 35</u>		Prethrust orbit change load data
FL V06 N34		<u>Request proceed</u>
R1 - TIG HRS	xxxxx. HRS	Load data
R2 - TIG MIN	xxxxx. MIN	
R3 - TIG SEC	xxx. xx SEC	
FL V06 N44		<u>Request proceed</u>
R1 - LAT	xxx. xx DEG	Load data
R2 - LONG	xxx. xx DEG	
R3 - ALT	xxxx. x NM	
FL V06 N45		<u>Request proved</u>
R1 - PER HRS	xxxxx. HRS	Load data
R2 - PER MIN	xxxxx. MIN	
R3 - PER SEC	xx-xx SEC	
FL V06 N70		<u>Request proceed</u>
R1 - PITCH TRIM	xxx. xx DEG	Load data
R2 - YAW TRIM	xxx. xx DEG	
R3 - DELTA V TAILOFF	xxxxx. Ft/sec	

<u>DISPLAY</u>	<u>UNITS</u>	<u>REMARKS</u>
<u>Routine 36</u>		Return to earth data load
FL V06 N44		<u>Request proceed</u>
R1 - LAT SPLASH	xxx.xx DEG	Load data
R2 - LONG SPLASH	xxx.xx DEG	
FL V06 N12		<u>Request proceed</u>
R1 - DELTA V ALLOW	xxxxx. Ft/sec	Load data
R2 - DELTA V TAILOFF	xxxxx. Ft/sec	
FL V06 N70		<u>Request proceed</u>
R1 - PITCH TRIM	xxx.xx DEG	Load data
R2 - YAW TRIM	xxx.xx DEG	
R3 - DELTA V TAILOFF	xxxxx. Ft/sec	
FL V06 N34		<u>Request proceed</u>
R1 - TIG PERM HRS	xxxxx. HRS	Load data
R2 - TIG PERM MIN	xxxxx. MIN	
R3 - TIG PERM SEC	xxx.xx SEC	
<u>Routine 37</u>		SPS Engine Ignition
V16 N51		
R1 - TTI	xx-xx MIN-SEC	
R2 - VG	xxxxx. Ft/sec	
R3 - DELTA VM	xxxxx. Ft/sec	To check ullage
FL V50 N11		<u>Please perform</u>
R1 - TTI	xx-xx MIN-SEC	Perform engine on enable
R2 - VG	xxxxx. Ft/sec	Monitor ignition
R3 - DELTA VM	xxxxx. Ft/sec	

DISPLAY

UNITS

REMARKS

Routine 38

FL V50 N11

V16 N51

R1 - TTI

R2 - VG

R3 - DELTA VM

or

V16 N52

R1 - TG

R2 - VG

R3 - TFF

xx-xx MIN-SEC

xxxxx. Ft/sec

xxxxx. Ft/sec

xx-xx MIN-SEC

xxxxx. Ft/sec

xx-xx MIN-SEC

SPS Engine thrust fail

Please perform

Perform engine on enable

Recalls displays