Vision-Flan: Scaling Human-Labeled Tasks in Visual Instruction Tuning

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Abstract

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Despite vision-language models' (VLMs) remarkable capabilities as versatile visual assistants, two substantial challenges persist within the existing VLM frameworks: (1) lacking task diversity in pretraining and visual instruction tuning, and (2) annotation error and bias in GPT-4 synthesized instruction tuning data. Both challenges lead to issues such as poor generalizability, hallucination, and catastrophic forgetting. To address these challenges, we construct VISION-FLAN, the most diverse publicly available visual instruction tuning dataset to date, comprising 187 diverse tasks and 1,664,261 instances sourced from academic datasets, and each task is accompanied by an expert-written instruction. In addition, we propose a two-stage instruction tuning framework, in which VLMs are firstly finetuned on VISION-FLAN and further tuned on GPT-4 synthesized data. We find this two-stage tuning framework significantly outperforms the traditional single-stage visual instruction tuning framework and achieves the state-of-the-art performance across a wide range of multi-modal evaluation benchmarks. Finally, we conduct in-depth analyses to understand visual instruction tuning and our findings reveal that: (1) GPT-4 synthesized data does not substantially enhance VLMs' capabilities but rather modulates the model's responses to human-preferred formats; (2) A minimal quantity (e.g., 1,000) of GPT-4 synthesized data can effectively align VLM responses with human-preference; (3) Visual instruction tuning mainly helps largelanguage models (LLMs) to understand visual features. Our dataset and models are publicly available at https://github.com/VT-NLP/ Vision-Flan.

1 Introduction

Recent vision-language models (VLMs) (Liu et al., 2023e; Li et al., 2023d; Dai et al., 2023), built upon pre-trained large-language models (LLMs) (Chiang et al., 2023; Gao et al., 2023) and pretrained

image encoders (Sun et al., 2023), have shown impressive capabilities as general visual assistants. Besides the unimodal encoders, the main ingredients of these VLM frameworks encompass: (1) a bridging module, such as the MLP layers in the LLaVA model (Liu et al., 2023e; Li et al., 2023d), that establishes connections between the pretrained image encoders and LLMs, (2) large-scale textimage pairs (Schuhmann et al., 2022) used for pre-training the bridging module, and (3) GPT-4 synthesized visual instruction tuning datasets (Liu et al., 2023e; Li et al., 2023b) to align the responses of VLMs with human preferences (i.e., following users' instruction to generate detailed and helpful responses). Despite their notable successes, we identify two remaining challenges that merit further investigation.

Firstly, the data used in the pre-training stage is dominated by the image captioning task, which lacks diversity, resulting in limited generalizability of VLMs (Chen et al., 2023c; Zhang et al., 2023). For instance, the LLaVA model (Liu et al., 2023e) performs poorly on the optical character recognition (OCR) task due to the absence of instances related to text detection during pre-training (Zhang et al., 2023). Several recent studies address this problem by further fine-tuning VLMs on instruction tuning datasets covering more tasks (Zhang et al., 2023; Hu et al., 2023; Liu et al., 2023d) such as visual question answering and OCR but the coverage of the tasks is still limited.

Secondly, most of the existing visual instruction tuning datasets (Liu et al., 2023e; Li et al., 2023b; Yin et al., 2023) are synthetically generated via GPT-4 by repurposing text annotations such as captions or dense captions from existing computervision datasets to generate new tasks, such as visual dialogue, Complex VQA and detail captions. While they enable VLMs to generate fluent and detailed responses aligned with human preferences, the lack of task diversity, spurious co-occurring pat**Relational and Analogical** Visual Reasoning



Instruction: Each image has 8 images labeled as Image 1 to Image 8. These 8 images follow a specific pattern. Detect the pattern and select the next image in the sequence from the 8 available . options

Target: Option 6

Document-Level OCR



Instruction: Detect all the text in the imaae Target: The texts are: CHESAPEAKE 'S FINEST; FREH FISH DAILY; CAPTAIN: WHITE: FA: MP & LOBSTER JUMBO CRABS CO; CRA.



Instruction: I will give you a radiology image (scan of a body part). Analyze it and answer the question given in the input text. Input: Does the patient have a central line red? placed? Target: Yes

Class Classification



Instruction: Taxonomic category is a rank or group of organisms developed on the basis of their characteristics. Identify the class of the organism in the image Target: The class of the organism in the image is Magnoliopsida

Aircraft Manufacturer Classification



Instruction Determine the manufa the provided aircraft image. The manufacturer refers to the company that designs, builds, and assembles the aircraft possessing the expertise and experience in the aviation industry necessary for production and delivery. Target: British Aerospace

a on Sentiment



Instruction: You are provided with a picture, write a caption with a specific sentiment (positive or negative) related to the picture Nrite a caption with a positive sentiment for the given image Target: a very nice looking tray filled with some excellent looking food





Instruction For the given p the artist name. Also provide the genre and stvle. if possible

Target: This artwork was created by Pyoti Konchalovsky. It falls under the genre of still life and showcases Post Impressionism style of painting.

Answer and Rational Generation



Instruction Answer the question and provide an explanation Input: The question is: What kind of precipitation is at the top of the mountain? Target: The answer is snow because the mountain tops are white

Figure 1: Sample tasks in VISION-FLAN. Instruction denotes a task instruction crafted by annotators. Input means text input in the given task, and Target is the target response based on the instruction.

terns between objects, and long-form outputs may cause severe hallucination (Liu et al., 2023c; Li et al., 2023g; Liu et al., 2023a; Zhou et al., 2023), and catastrophic forgetting - VLMs fail to maintain a similar classification performance on basic detection tasks, such as MNIST (LeCun, 1998) and CIFAR-10 (Krizhevsky et al., 2009), compared to the zero-shot performance of their vision encoders (Zhai et al., 2023).

To address both challenges, we introduce VISION-FLAN, the most diverse public-available visual instruction tuning dataset consisting of 187 tasks drawn from academic datasets, covering perception tasks such as object detection and OCR, domain-specific tasks such as image-quality classification and image-style classification, complex reasoning tasks such as graph understanding and geometric question answering, and many more. Each task in VISION-FLAN is accompanied by an expertwritten instruction. We show some sample tasks from VISION-FLAN in Figure 1 and provide the full list of tasks in Appendix J.

In addition, we introduce a two-stage instruction tuning framework. In the first stage, we utilize the pre-trained LLaVA model (Liu et al., 2023e) as our initial model, and finetune it on VISION-FLAN to gain diverse capabilities, resulting in the VISION-FLAN BASE model. However, due to the concise nature of target outputs in academic datasets, the

responses generated by VISION-FLAN BASE tend to be brief and not aligned with human preferences. Therefore, in the second stage, we further finetune VISION-FLAN BASE using a minimal amount of GPT-4 synthesized data. This step aims to adjust the model's outputs to be more in line with human preferences, resulting in the VISION-FLAN CHAT model.

Our experimental results demonstrate that highquality human annotations from VISION-FLAN significantly enhance the capabilities of both VISION-FLAN BASE and VISION-FLAN CHAT while reducing the risk of hallucination and catastrophic forgetting. The two-stage instruction tuning framework enables VISION-FLAN CHAT to achieve better human preference alignment using much less GPT-4 synthesized data compared to the state-of-the-art VLMs. Finally, we perform extensive analysis to understand visual instruction tuning including the roles of human-labeled and GPT-4 synthesized data, and the impacts of various training strategies. Our investigation yields several key insights:

- Increasing the number of human-labeled tasks in visual instruction tuning can substantially enhance VLMs' capabilities across extensive evaluation benchmarks.
- · GPT-4 synthesized data does not substantially enhance VLMs capabilities and yields marginal improvements in the VLMs' perfor-

mance on comprehensive evaluation benchmarks, such as MME (Fu et al., 2023) and MM-Bench (Liu et al., 2023f).

- A minimal quantity (1,000) of GPT-4 synthesized data is sufficient to align VLMs' responses with human preferences. Notably, increasing GPT-4 synthesized data does not correspond to a proportional enhancement in alignment and introduces hallucination and bias into the VLMs.
- Visual instruction tuning mainly enhances the ability of large-language models (LLMs) to process and understand visual features. The training of the bridging module, which maps visual features to the embedding space of LLMs, is predominantly achieved during the pre-training phase.

2 VISION-FLAN

2.1 Collection Pipeline

We carefully design an annotator selection process to identify qualified annotators, which involves 2 iterations of training and testing. More details of the selection process and compensation can be found in Appendix A.1. In the end, we hire 7 out of 21 candidates as our annotators and all of them are graduate students in computer science. To ensure the diversity and quality of the tasks in VISION-FLAN, we design a rigorous annotation pipeline with four major steps:

Existing dataset collection and pre-processing: Two expert researchers (i.e., senior Ph.D. students in the fields of natural language processing and computer vision) search online and identify highquality vision-language datasets. The datasets are then equally distributed to 7 annotators to download and preprocess the datasets. Each processed instance consists of an image, an instruction (the task definition from the original dataset with minor modifications), a text input if applicable, and a target output.

Creating new tasks: The two expert researchers and annotators also discuss potential new tasks that could be derived from the existing annotations. We derive new tasks by combining the annotations of two or more existing tasks on a dataset. For example, in the Concadia dataset (Kreiss et al., 2022), each instance consists of an image caption and a knowledge snippet related to the image. We propose a new task to predict both the caption and the background knowledge given an image, which is a free-form generation task. The new target output is formed by concatenating the caption with the knowledge snippet. We also develop new tasks by creating more basic versions of the original tasks. For example, given the object detection annotations in MSCOCO (Lin et al., 2014), we propose an object selection task in which we provide a list of objects and ask the model to select the object that appears in the image (the negative options are created by sampling objects that appear in other images but not in the given image). The expert researchers and annotators manually solve 20 instances for each newly developed task. If the human predictions match the target outputs, this new task is considered valid.

Iteratively refining the task instructions and output templates: For existing tasks, we ask annotators to write instructions based on the original task definitions with minor modifications. For newly developed tasks, the annotators write instructions by discussing with the expert researchers. Once an annotator finishes writing a new instruction, one of the two expert researchers is randomly assigned to examine the instances and provide feedback for revising the instruction. This step iterates repeatedly until the instruction meets our requirements. We require the instruction to be clear, easy to understand, and can be correctly executed by a human. Each task together with its associated dataset and instruction is then added to the pool of candidate tasks for VISION-FLAN.

Verifying the quality of each task: From the candidate task pool, two expert researchers, including a native English speaker, work together to select the high-quality tasks where the instruction is fluent and effectively conveys the intended task and the task does not overlap with other tasks.

Based on these four steps, we finally collect 187 high-quality tasks, and for each task, we randomly sample 10,000 instances from its corresponding dataset. If a dataset contains less than 10,000 instances, we include all of them. We name the dataset as VISION-FLAN, consisting of 1,664,261 instances for 187 tasks in total. We include references to all the datasets used in VISION-FLAN in Appendix H and show an instance for each task in Appendix J.

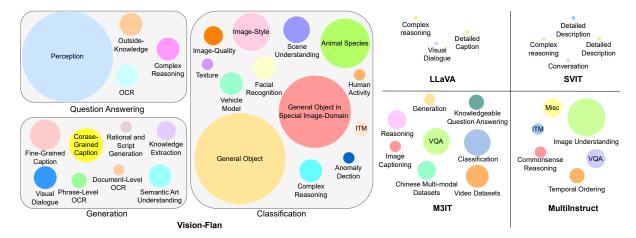


Figure 2: Comparison of task diversity between VISION-FLAN and previous visual instruction tuning datasets. LLaVA and SVIT report very coarse-grained categories of tasks. Each circle represents a task category and the radius is proportional to the number of tasks in that category. The radius of circles for different datasets are comparable.

Dataset	Instances #	Tasks #	Source
LLaVA (Liu et al., 2023e)	150K	3	Synthetic
LAMM (Yin et al., 2023)	196K	8	Synthetic
VL-Qwen (Bai et al., 2023a)	350K	Unknown	Private
M ³ IT (Li et al., 2023e)	2.4M	40	Synthetic
mPlug-Owl (Ye et al., 2023)	150K	3	Synthetic
Shikra (Chen et al., 2023a)	156K	4	Synthetic
SVIT (Zhao et al., 2023)	4.2M	4	Synthetic
MultiInstruct (Xu et al., 2023)	510K	62	Public
VISION-FLAN (Ours)	1.6M	196	Public

Table 1: Comparison between VISION-FLAN and existing visual instruction tuning datasets.

2.2 Comparison with Existing Datasets

Table 1 presents a comparison between existing visual instruction tuning datasets and VISION-FLAN. For existing visual instruction tuning datasets, we directly adopt the numbers of tasks and instances reported in their original papers. The majority of these datasets are generated using proprietary language models, such as ChatGPT¹ and GPT-4², and exhibit a narrow range of task diversity. VL-Qwen (Bai et al., 2023a) is a recently introduced large-scale dataset annotated by humans but remains inaccessible to the public. Although Multi-Instruct (Xu et al., 2023) is based on publicly available datasets, it mainly focuses on visual grounding tasks and only contains 29 tasks that do not involve region-specific information. In contrast, VISION-FLAN encompasses a significantly more diverse array of tasks, offering a three-times increase compared to the number of tasks in MultiInstruct.

In Figure 2, we compare the task categories covered by VISION-FLAN and other datasets. Tasks within VISION-FLAN are first categorized into three primary groups: *Question Answering, Classification*, and *Generation*, and each of these primary groups is further divided into specific, fine-grained categories. For instance, within the *Classification* group, the *General Object* category involves classifying objects in images into various concepts, such as "fish", "car", and "dog". Contrastingly, the *Vehicle Model* category demands the models to accurately identify specific car brands or models, like "Toyota" and "Camry". The visualization in Figure 2 clearly demonstrates the superior diversity and volume of tasks in VISION-FLAN compared to existing datasets. We list tasks in each category in Appendix I.

3 VISION-FLAN Finetuning

Model Architecture We adopt the same VLM architecture as LLaVA (Liu et al., 2023d) and denote it as LLaVA-Architecture. As shown in Figure 3, it consists of a pre-trained vision encoder, a pre-trained large language model, and two layers of MLPs to connect them. In the vision-language pre-training phase of the LLaVA-Architecture, both the pre-trained vision encoder and large language model remain frozen, and only the MLP layers are trained on a large-scale image captioning dataset (Schuhmann et al., 2022). We leverage this pre-trained LLaVA model, without any visual instruction tuning, as our initial model and finetune it on VISION-FLAN. During visual instruction tuning, we finetune both the MLP layers and the language model while keeping the vision encoder frozen.

Two-stage Visual Instruction Tuning Contrary to prior approaches (Liu et al., 2023d; Dai et al.,

https://openai.com/blog/chatgpt

²https://openai.com/research/gpt-4

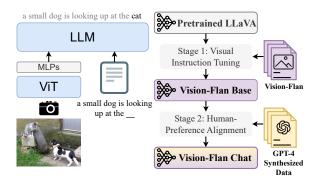


Figure 3: The left of the figure shows the LLaVA-Architecture and the right of the figure shows the two-stage visual instruction tuning pipeline.

2023) that mix human-labeled data with GPT-4 synthesized data for visual instruction tuning, our study introduces a two-stage instruction tuning pipeline. As shown in Figure 3, in the first stage, we finetune the VLM on all 187 tasks of VISION-FLAN to acquire diverse capabilities and name the resulting model as VISION-FLAN BASE. However, due to the brevity of target outputs presented in academic datasets, the responses from VISION-FLAN BASE are not in human-preferred formats. Hence, we further finetune VISION-FLAN BASE on GPT-4 synthesized data to align the model's outputs with human preference. We denote the yielded model as VISION-FLAN CHAT. This training framework requires minimal GPT-4 synthesized data while providing deep insights into the distinct contributions of human-labeled and GPT-4 synthesized data in visual instruction tuning.

Implementation Details We leverage LLaVA-Architecture with Vicuna-13B v1.5 (Chiang et al., 2023), CLIP-ViT-L-336px (Radford et al., 2021) and two layers of MLP as our VLM. For the firststage instruction tuning, we finetune the MLP layers and the language model on VISION-FLAN for 1 epoch with a learning rate 2e-5 and per device batch size 16 on 8 A100 GPUs. For the second-stage instruction tuning, we further finetune the MLP layers and the language model on 1,000 instances randomly sampled from the LLaVA dataset (Liu et al., 2023e) with learning rate 1e-5 and per device batch size 8 on 8 GPUs for 128 steps. In the following sections, we use LLaVA dataset and GPT-4 synthesized data interchangeably.

4 Experiment Setup

Evaluation Datasets We evaluate the models on several widely adopted multimodal evaluation benchmark datasets including *multiple-choice* benchmarks: **MMbench** (Liu et al., 2023f), **MME** (Fu et al., 2023), and **MMMU**; *free-form generation* benchmarks: **MM-Vet** (Yu et al., 2023) and **LLaVA-Bench**; the *hallucination* benchmark: **POPE** (Li et al., 2023g), and *catastrophic forgetting* benchmarks: **CIFAR-10 and CIFAR-100** (Krizhevsky et al., 2009), **MNIST** (LeCun, 1998), and **miniImageNet** (Vinyals et al., 2016). More details of the evaluation datasets can be found in Appendix B.

Evaluation Protocols For MMbench, MME, MM-Vet, LLaVA-Bench, POPE and MMMU, we strictly follow their official implementations of evaluation code to evaluate the performance of each model. For datasets that do not have official evaluation codes including CIFAR-10, CIFAR-100, MNIST, and miniImageNet, we leverage the state-of-the-art open-source LLM, Vicuna 1.5 13B, to perform the evaluation and report the averaged performance on these four datasets in the CF column in Table 2. More details of evaluation protocols can be found in Appendix C.

Baselines We compare our models with several recent state-of-the-art vision-language models, including **BLIP-2** (Li et al., 2023d), **Instruct-BLIP** (Dai et al., 2023), **Shikra** (Chen et al., 2023a), **LLaVA** (Liu et al., 2023e), **Qwen-VL**, **Qwen-VL-Chat** (Bai et al., 2023b), and **LLaVA-1.5** (Liu et al., 2023d). The LLMs and image encoders used in all baselines are shown in Table 2. Details of baselines can be found in Appendix D.

5 Results and Analysis

5.1 Main Results

As demonstrated in Table 2, VISION-FLAN BASE achieves state-of-the-art performance on comprehensive evaluation benchmarks including MME, MM-Bench and MMMU, while reducing hallucination and catastrophic forgetting. However, we observe that VISION-FLAN BASE scores significantly lower on the LLaVA-Bench dataset in comparison to VLMs trained using GPT-4 synthesized data. We attribute this discrepancy to the conciseness and brevity of target outputs within academic datasets. As shown in Figure 1, VQA tasks frequently yield outputs comprising a single or a few words. Even outputs of many generation tasks are typically confined to one or two succinct sentences. Training on these tasks leads VISION-FLAN BASE to generate brief responses, which are not aligned with human

Model	LLM	Image Encoder	MM-Bench	MME	MMMU	LLaVA-Bench	MM-Vet	Pope	CF
BLIP-2	FlanT5-XXL	ViT-g/14	-	1293.8	34.0	-	22.4	85.3	-
InstructBlip	Vicuna-13B	ViT-g/14	36.0	1212.8	33.8	58.2	25.6	78.9	-
Mini-GPT4	Vicuna-13B	ViT-g/14	24.3	581.67	27.6	-	-	-	-
Shikra	Vicuna-13B	ViT-L/14	58.8	-	-	-	-	-	-
LLaVA	Vicuna-13B v1.5	CLIP-ViT-L-336px	38.7	1151.6	-	70.8	33.4	75.3	-
Qwen-VL	Qwen-7B	ViT-bigG	38.2	-	-	-	-	-	-
Qwen-VL-Chat	Qwen-7B	ViT-bigG	60.6	1487.5	32.9	73.6	-	-	72.1
LLaVA 1.5	Vicuna-13B v1.5	CLIP-ViT-L-336px	66.7	<u>1531.3</u>	33.6	70.7	<u>35.4</u>	83.6	73.3
VISION-FLAN BASE	Vicuna-13B v1.5	CLIP-ViT-L-336px	69.8	1537.8	34.4	38.5	33.4	85.9	87.2
Second-Stage Tuning	Second-Stage Tuning with 1,000 GPT-4 Synthesized Instances								
VISION-FLAN CHAT	Vicuna-13B v1.5	CLIP-ViT-L-336px	<u>67.6</u>	1490.6	<u>34.3</u>	78.3	38.0	86.1	<u>84.0</u>

Table 2: Comprehensive evaluation of VLMs on widely adopted benchmark datasets. CF denotes the averaged performance of VLMs on four catastrophic forgetting benchmarks.

preferences. Conversely, through the second-stage tuning on a mere 1,000 GPT-4 synthesized data instances, VISION-FLAN CHAT achieves significant performance improvement on LLaVA-Bench, a benchmark measuring human-preference alignment, while maintaining a relatively lower rate of hallucination and catastrophic forgetting. To better understand why VISION-FLAN models are better than current VLMs, we conduct two case studies focusing on OCR and Entity Recognition and analyze both quantitative and qualitative results in Appendix E.2.

Another finding in Table 2 is that compared to VISION-FLAN BASE, VISION-FLAN CHAT achieves slightly inferior performance on comprehensive evaluation benchmarks demonstrating the bias and hallucination inevitably introduced by the GPT-4 synthesized data, which is discussed in detail in Section 5.2.

5.2 Effect of Human-Labeled and GPT-4 Synthesized Datasets



Figure 4: Performance on four comprehensive benchmarks versus the number of training tasks.

Effect of Task Diversity in VISION-FLAN Figure 4 illustrates the relationship between the number of tasks from VISION-FLAN employed during visual instruction tuning and the performance of VISION-FLAN BASE across four comprehen-

sive evaluation benchmarks. It's apparent that as the number of tasks increases, the performance of VISION-FLAN BASE on all datasets is improved. To evaluate the impact of varying numbers of instances from different tasks, we fix the total amount of instances used for visual instruction tuning and experiment with different numbers of tasks. As demonstrated in Table 3, when the number of training instances is constant, augmenting the number of tasks significantly enhances model performance. These findings substantiate our hypothesis that *the diverse array of human-labeled tasks within* VISION-FLAN *is essential for improving the capabilities of VLMs*.

# of Tasks	# of Instances per Task	MMB	MME	Pope	MMMU
Training w	ith 100,000 Instances				
10	10,000	58.3	723.9	81.0	32.6
187	500	58.8	1314.3	83.3	33.3
Training w	ith 200,000 Instances				
20	10,000	58.8	897.3	83.4	31.8
187	1,000	63.5	1373.5	83.6	33.7

Table 3: Comparison of VISION-FLAN BASE trained with a fixed total amount of data instances.

Effect of GPT-4 Synthesized Data on Comprehensive Evaluation Benchmarks Furthermore, we analyze if GPT-4 synthesized data can improve the model's performance on comprehensive evaluation benchmarks and show the results in Figure 5. Further tuning VISION-FLAN BASE on GPT-4 synthesized data instances does not lead to performance improvement. Tuning pretrained LLaVA model on a small amount of GPT-4 synthesized data (100) can improve its performance on MME but further increasing the number of training instances does not lead to any improvement. We also observe a similar trend on the MM-Bench dataset and report the result in Appendix E.1. These observations are in line with recent findings in LLMs: GPT-4 synthesized data does not improve model's

capability but rather modulates the responses towards human-preferred formats (Jain et al., 2023; Gudibande et al., 2023).

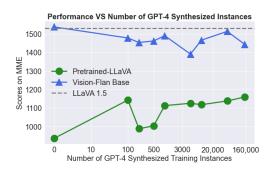


Figure 5: Effect of the number of GPT-4 synthesized training instances on MME. The dashed gray line indicates the performance of LLaVA 1.5.

Effect of GPT-4 Synthesized Data on Human-**Preference Alignment** When utilizing our proposed two-stage tuning framework, we find that by performing a second-stage finetuning on a mere 1,000 GPT-4 synthesized instances from the LLaVA dataset, VISION-FLAN CHAT achieves significantly better performance (78.5 v.s. 38.5) on the LLaVA-Bench dataset. This observation leads us to raise the question: Is extensive finetuning on large-scale GPT-4 synthesized datasets necessary for aligning VLMs with human preferences? To answer it, we finetune both VISION-FLAN BASE and pretrained LLaVA model on different numbers of GPT-4 synthesized instances ranging from 100 to 158,000, and show the results in Figure 6. As we can see, with 1,000 instances, VISION-FLAN BASE achieves a score of 78.3 and further increasing the number of training instances leads to a performance drop. A similar trend can also be seen for the pretrained LLaVA model.

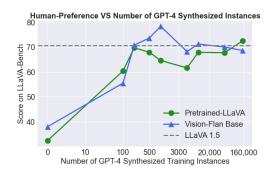


Figure 6: Effect of the number of GPT-4 synthesized instances on human preference alignment. The dashed gray line indicates the performance of LLaVA 1.5.

GPT-4 Synthesized Data Causes Hallucination and Bias Concurrent work (Liu et al., 2023c)

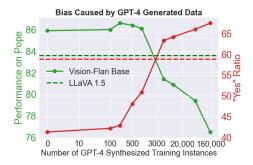


Figure 7: Effect of the number of GPT-4 synthesized training instances on the hallucination benchmark and the ratio of "Yes". The dashed lines indicate the performance of the state-of-the-art LLaVA 1.5 model.

identifies that hallucination in current VLMs can be caused by their bias toward positive answers (i.e., "Yes"). In Figure 7, we explicitly show the relationship between hallucination, the ratio of "Yes", and the number of training instances from GPT-4 synthesized dataset. As the number of GPT-4 synthesized instances increases, the model's responses are biased towards the answer "Yes" even if the objects are not in the images, causing the model to hallucinate. This observation suggests that a small amount of GPT-4 synthesized training instances is preferred to avoid hallucination and bias in VLMs.

5.3 Single-stage Tuning on Mixed Data Vs. Two-stage Tuning

In this section, we compare the performance of two training strategies based on the same pretrained LLaVA model: (1) finetuning it on the mix of VISION-FLAN and the LLaVA dataset; (2) finetuning it utilizing VISION-FLAN and 1,000 instances from the LLaVA dataset with our two-stage tuning method. As illustrated in Table 4, the performance of VLMs finetuned on the mix of VISION-FLAN and GPT-4 synthesized data is notably inferior compared to VISION-FLAN CHAT trained through our two-stage tuning framework.

Method	# of LLaVA	MME	LLaVA-Bench	MM-Vet
Mixed Data	1,000	1364.0	52.7	36.6
Mixed Data	158,000	1317.9	63.9	36.8
Two-stage	1,000	1490.6	78.3	38.0

Table 4: Comparison between single-stage finetuningon mixed data and two-stage finetuning.

5.4 Effect of Newly Created Tasks

In the data collection phase of VISION-FLAN, we collaborate with annotators to derive 65 novel tasks from pre-existing annotations. To evaluate the impact of these newly introduced tasks, we conducted

an experiment where a VISION-FLAN BASE was trained exclusively on the existing tasks and its performance was compared against the VISION-FLAN BASE trained on all tasks, including the new additions. The comparative results are presented in Table 5. The outcomes distinctly demonstrate the advantages of expanding the task set through the utilization of existing annotations.

Model Name	MME	MM-Bench	Pope
VISION-FLAN BASE	1537.8	69.8	85.9
VISION-FLAN BASE w/o New Tasks	1379.8	67.3	84.6

Table 5: Comparison between finetuning VISION-FLAN BASE on all tasks and finetuning VISION-FLAN BASE only on existing tasks.

5.5 Contributions of Tasks from Different Task Groups

Understanding the contribution of each task to the models' performance is crucial for visual instruction tuning. However, training a model on each task in VISION-FLAN can impose significant computational cost. Instead, we propose a group-level analysis of task contributions. As illustrated in Figure 2, tasks are categorized into three primary groups: Question Answering (QA), Classification, and Generation. We train three VISION-FLAN CHAT models on VISION-FLAN, each time excluding all tasks from one primary group, and show their performance in Table 6.

Model Name	MME	Pope	LLaVA-Bench	MM-Vet
VISION-FLAN CHAT	1537.8	86.1	78.3	38.0
w/o QA	1211.6	83.3	73.5	37.9
w/o Classification	1376.6	84.9	75.4	37.3
w/o Generation	1390.9	83.8	68.1	36.2

Table 6: Contributions of different tasks group to the performance of VISION-FLAN CHAT.

Our findings indicate that: (1) the inclusion of generation tasks markedly enhances the model's capability in free-form generation tasks, as evidenced by performance on LLaVA-Bench; (2) QA tasks and classification tasks contribute significantly to model's performance MME, and (3) synergistic interactions between different task groups lead to further performance enhancements.

5.6 What is Essentially Improved in VLMs during Visual Instruction Tuning

In LLaVA-Architecture, the MLP layers map the visual features from a vision encoder into the embedding space of LLMs. The LLMs then interpret the

LLM	MLPs	MM-Bench	MME	LLaVA-Bench	Pope
×	×	45.0	936.3	32.4	51.9
×	1	52.4	1107.3	39.1	83.3
1	×	69.2	1495.5	39.3	85.6
\checkmark	1	69.8	1537.8	38.5	85.9

Table 7: Effect of tuning different modules in VISION-FLAN BASE. \checkmark denotes the module is tuned and \checkmark denotes the module is frozen during visual instruction tuning.

visual features and follow text instructions to generate responses. In Table 7, we show the results of training different modules during visual instruction tuning and observe that solely tuning MLPs causes a significant performance drop compared to tuning both MLPs and LLMs during visual instruction tuning. However, tuning LLMs with frozen MLPs results in similar performance as tuning both modules, demonstrating that visual instruction tuning mainly enables LLMs to better understand visual features while MLPs have been sufficiently learned during pretraning. To further support this claim, we replace the instruction-tuned MLPs in VISION-FLAN BASE and VISION-FLAN CHAT with the pretrained MLPs from the pre-trained LLaVA model, and show that with the pretrained MLPs, both models can retain more than 90% of performance on most tasks as shown in Table 8. We also compute the Pearson Correlation Coefficient between the parameters of pretrained MLPs and instruction-tuned MLPs, and find that their correlation coefficient is higher than 0.99.

Model	MMB	MME	LLaVA-Bench	Pope
VISION-FLAN BASE	69.8	1537.8	38.5	85.9
+ Pretrained MLP	68.0	1403.1	36.4	84.0
VISION-FLAN CHAT	67.6	1490.6	78.3	86.1
+ Pretrained MLP	65.7	1332.2	73.8	85.4

Table 8: Results of replacing visual instruction tuned MLPs with pretrained MLPs. Gray rows show the performance of the original models and yellow rows show the performance after replacing instruction-tuned MLPs with pretrained MLPs.

6 Related Work

Instruction tuning (Wei et al., 2022) is first introduced in NLP and has been adapted to the visuallanguage domain. MultiInstruct (Xu et al., 2023) propose the first human-label multi-modal instruction tuning dataset for improving the zero-shot performance of pre-trained VLMs. LLaVA (Liu et al., 2023e) leverage GPT-4 to repurpose text annotations such as captions or dense captions from existing computer-vision datasets to generate visual dialogues, Complex VQA and detail captions for visual instruction tuning. Following LLaVA, mPLUG-Owl (Ye et al., 2023), LAMM (Yin et al., 2023), MIMIC-IT (Li et al., 2023a) and Macaw-LLM (Lyu et al., 2023) leverage proprietary LLMs such as GPT-4 and ChatGPT to further extend the instruction tuning tasks into 3D-domain, multipleimages and videos, and increase the amount of training instances. MiniGPT-4 (Zhu et al., 2023) utilizes ChatGPT to refine output from the pretrained VLM itself. InstructBLIP (Dai et al., 2023) and LLaVA-1.5 (Liu et al., 2023d) mix the humanannotated and GPT4 synthesized datasets to enhance visual instruction tuning.

Several recent work explores different strategies to improve visual instruction tuning. StableLLaVA (Li et al., 2023f) and VPG-C (Li et al., 2023c) generate both images and texts using Stable Diffusion (Rombach et al., 2022) or Blended Diffusion (Avrahami et al., 2022) to alleviate domain bias and encourage VLMs attend to visual details. (Liu et al., 2023b) demonstrate the bias introduced by positive instructions and introduce negative instruction examples for improving robustness. Shikra (Chen et al., 2023a) incorporate visual grounding tasks in visual instruction tuning to improve the VLM's referential capability. LLaVAR (Zhang et al., 2023) and BLIVA (Hu et al., 2023) leverage OCR tools and GPT-4 to generate tasks helping VLMs to understand text in images. (Lu et al., 2023) and SVIT (Zhao et al., 2023) empirically study the effect of scaling the size of VLMs and the size of GPT-4 synthesized dataset. Two concurrent works (Wang et al., 2023a; Chen et al., 2023b) directly prompt GPT-4V with images as input to generate visual instruction tuning data and achieve superior performance. Additional related work can be found in Appendix G.

Unlike all prior work, our work mainly focuses on scaling human-labeled tasks in visual instruction tuning to improve VLMs' capabilities. Additionally, we perform extensive analysis to understand the characteristics of human-labeled and GPT-4 synthesized data and draw meaningful conclusions.

7 Conclusion

We construct VISION-FLAN, the most diverse public-available visual instruction tuning dataset, consisting of 187 diverse tasks and 1,664,261 instances collected from academic datasets, and each task is accompanied by an expert-written instruction. We demonstrate that VLMs trained on VISION-FLAN with proposed two-stage tuning framework achieve state-of-the-art performance on comprehensive evaluation benchmarks. Additionally, we perform extensive analysis and reveal the distinct contributions of human-labeled and GPT-4 synthesized data in visual instruction tuning.

8 Limitations

All the tasks included in VISION-FLAN are in English, which confines the usage of our dataset and models to English speaking populations. Future work should extend VISION-FLAN with multilingual tasks. In addition, all the tasks in VISION-FLAN only consists of a single image. Many realworld vision-language tasks require the model to take multiple images as inputs, such as script generation (Qi et al., 2024) and multimodal entity linking (Yao et al., 2024). Thus, future work should explore vision-language tasks that involve multiple images or videos.

Our analysis mainly focuses on the GPT-4 synthesized visual instruction tuning dataset. Recently, as the GPT-4V 3 becomes publicly available, there are some concurrent works (Wang et al., 2023a; Chen et al., 2023b) prompting GPT-4V with images as inputs to generate visual instruction tuning data. Future work can analyze the effect of tuning VLMs on such datasets and identify the advantages and disadvantages.

In our experiments, we mainly focus on the LLaVA-Architecture (Liu et al., 2023e) due to its strong performance and high efficiency. However, there are other foundation architectures such as Q-former in BLIP2 (Li et al., 2023d) and Perceiver Resampler in Flamingo (Alayrac et al., 2022). More diverse VLM architectures can be explored in the future to draw more general conclusions.

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³https://openai.com/research/ gpt-4v-system-card

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A More Details on the Annotation Process of VISION-FLAN

A.1 Annotator Selection

Due to the complexity of the annotation task, we carefully design a selection process to select qualified annotators. Specifically, at beginning, the authors send out emails looking for graduate students in computer science who are interested in NLP and multi-modal learning. A group of 21 graduate computer science students signed up for a tutorial section. In the tutorial section, two PhD students in NLP explain the requirements for writing instructions, downloading the dataset and processing raw datasets into a unified format. After the tutorial, each candidate is assigned with three datasets and they have totally three days to process the raw datasets and write instructions. In the end, each candidate submits their annotations and two PhD students provide feedback to each candidate. The candidates then have two days to modify their instructions or formats based on the feedback. After two days, the candidates submit their final version of annotations and two PhD students discuss the quality of the annotations case by case. In the end, 7 out of 21 students were selected as qualified annotators. The compensation is 15\$ per hour.

B Evaluation Datasets

We evaluate our models on several widely used multimodal evaluation benchmark datasets: (1) **MMbench** (Liu et al., 2023f) is a comprehensive evaluation benchmark measuring VLM's capabilities from 20 dimensions. (2)**MME** (Fu et al., 2023) measures VLM's perception and cognition capabilities based on 14 diverse tasks. (3) **MM-Vet** (Yu et al., 2023) focuses on measuring the integration of various capabilities of VLMs, including OCR, recognition, knowledge, spatial awareness, math, and language generation. (4) **LLaVA-Bench** (Liu et al., 2023e) evaluates the instruction following and chat ability of VLMs in diverse daily-life visual tasks. (5) **POPE** (Li et al., 2023g) is an evaluation benchmark that probes object hallucination in VLMs. (6) **MMMU** (Yue et al., 2023) evaluates VLMs on multi-discipline tasks that require college-level subject knowledge and deliberate reasoning.

We also evaluate the newly proposed catastrophic forgetting problem (Zhai et al., 2023) of VLMs on 4 datasets: **CIFAR-10 and CIFAR-100** (Krizhevsky et al., 2009), **MNIST** (LeCun, 1998), and **miniImageNet** (Vinyals et al., 2016). We report the averaged performance of VLMs on the four benchmarks in the CF column of Table 2.

C Evaluation Protocols

For MM-Bench, MME, MM-Vet, LLaVA-Bench, POPE and MMMU, we use their official implementations of evaluation code⁴ to evaluate the performance. Specifically, the evaluation scripts of MMbench and MM-Vet call GPT-4 API to evaluate the correctness of a prediction given the target output and produce a binary score (0 or 1). Similarly, the evaluation of LLaVA-Bench also leverages GPT-4, and in addition to the target outputs, the evaluation method considers detail descriptions of images. The evaluation results are scores indicating not only the correctness but the human-preference of the predictions. MME and POPE are binary classification tasks and their evaluation is based on string matching between the predictions and target labels.

D Baselines

We compare our method with recent visionlanguage models. All the baselines listed below have similar architectures which consist of a pretrained LLM, a pretrained image encoder, and a bridging module that connects them. **BLIP-2** (Li et al., 2023d) utilizes the Q-Former to bridge a pretrained image encoder with a pretrained LLM, and achieves strong zero-shot capabilities. Instruct-BLIP (Dai et al., 2023) is a visual-instructiontuned BLIP-2 (Li et al., 2023d) model. The instruction tuning dataset is a mixture of 13 academic datasets and the LLaVA (Liu et al., 2023e) dataset. Shikra (Chen et al., 2023a) focuses more on the object grounding capability and is instruction tuned on referential dialogue dataset and LLaVA dataset (Liu et al., 2023e), both of which are synthetically generated via GPT-4. LLaVA (Liu et al., 2023e) is the first VLM finetuned on GPT-4 synthesized visual instruction tuning dataset and achieves remarkable performance as a general-purpose visual chatbot. Qwen-VL and Qwen-VL-Chat (Bai et al., 2023b) are recently proposed VLMs based on Qwen (Bai et al., 2023a) language model and are trained on a large-scale (50 million instances) private visual instruction tuning dataset. LLaVA-1.5 (Liu et al., 2023d) is a LLaVA model trained on a mixture of shareGPT⁵, LLaVA (Liu et al., 2023e) and 8 academic image-text datasets.

E Additional Results

E.1 Effect of GPT-4 synthesized data on comprehensive evaluation benchmarks

We show additional results in Figure 8 to support our claim that training on GPT-4 synthesized data can not effectively improve VLMs' performance on comprehensive evaluation benchmarks. As we can observe, adding more training instances from the LLaVA dataset does not improve VISION-FLAN BASE's performance on MM-Bench.

E.2 Why VLMs Trained on VISION-FLAN are Better than State-of-the-Art VLMs?

In this section, we perform two case studies to explain why models trained on VISION-FLAN can perform better compared to state-of-the-art VLMs.

E.2.1 Case Study on OCR

When we manually check the predictions of VISION-FLAN CHAT and compare them to other VLMs, the first trend we observe is that VISION-FLAN CHAT can better perform OCR as shown in Figure 10. To quantify this observation, we evaluate LLaVA, LLaVA 1.5 and our models on the challenging TextOCR dataset (Singh et al., 2021). We ask the VLMs to predict all the text on each

⁴https://github.com/BradyFU/

Awesome-Multimodal-Large-Language-Models/ tree/Evaluation

https://mmbench.opencompass.org.cn/leaderboard https://github.com/yuweihao/MM-Vet https://github.com/haotian-liu/LLaVA/blob/ main/docs/LLaVA_Bench.md

https://github.com/RUCAIBox/POPE

https://github.com/MMMU-Benchmark/MMMU

⁵https://sharegpt.com/

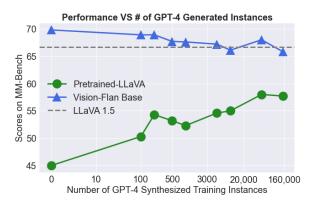


Figure 8: Effect of increasing the number of GPT-4 synthesized training instances on the comprehensive evaluation benchmark, namely MM-Bench. The dashed gray line indicates the performance of the-state-of-the-art LLaVA 1.5 model.

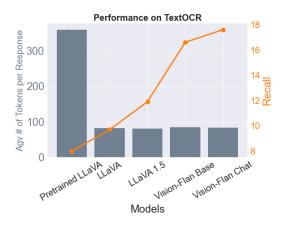


Figure 9: Performance of various VLMs on TextOCR. The gray bars shows the averaged number of tokens per prediction and the orange line show the recall of predictions.

image and check the overlap between the target list of text pieces and the predictions. As shown in Figure 9, the recall of VISION-FLAN BASE and VISION-FLAN CHAT is much higher compared to LLaVA 1.5 while the averaged numbers of predicted tokens per response are similar.

E.2.2 Case Study on Entity Recognition

We also spot that models trained on VISION-FLAN can better identify entities in an image while LLaVA 1.5 simply captions the appearance of entities in an image. A qualitative example is shown in Figure 11.

To compute quantitative results, we randomly sample 1,000 images with their captions from the WIT dataset (Srinivasan et al., 2021), in which the images are from Wikipedia pages and the captions commonly contain entities appearing in the im-

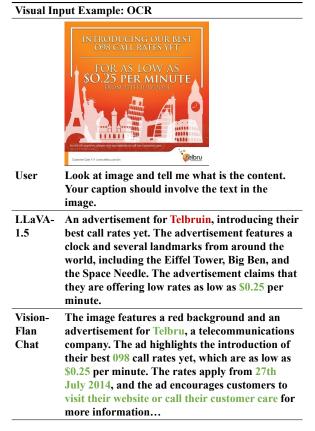


Figure 10: An example from TextCap to show that Vision-Flan allows VLMs to better recognize text.

ages. We prompt VLMs to introduce the entities in the image with some background knowledge. We leverage the EntityRecognizer from spaCy⁶ to recognize the entities in both predictions and ground truth captions and compute the percentage of target entities appearing in the predictions. As shown in Figure 12, it is clear that VISION-FLAN BASE and VISION-FLAN CHAT predict more entities in their responses (gray bars) and have higher coverage of entities (orange line) compared to LLaVA 1.5.

F Additional Analysis

F.1 The Bridging Module Can Be Shared Across LLMs with Same Architecture

Recent studies (Jain et al., 2023) in aligning and finetuning LLMs suggest that alignment happens very localized with pruning of a few weights or neurons to alter the style and format of outputs from LLMs, and does not substantially change the parameter space of LLMs. Following this finding, we hypothesize that *the MLP layers that map visual features into LLMs' embedding space*

⁶https://spacy.io/api/entityrecognizer

Model	MM-Bench	MME	LLaVA-Bench	Pope
Pretrained LLaVA-Architecture	45.0	936.3	32.4	51.9
+ LLaMA 2 Chat	45.3 (100.6)	557.0 (59.5)	59.2 (182.7)	66.9 (128.9)
VISION-FLAN BASE w/ frozen LLM	52.4	1107.3	41.6	83.3
+ LLaMA 2 Chat	46.6 (88.9)	1095.8 (99.0)	56.4 (135.6)	80.9 (97.1)
VISION-FLAN BASE	69.8	1537.8	38.5	85.9
+ LLaMA 2 Chat	47.2 (67.6)	852.6 (55.4)	69.9 (181.6)	66.1 (76.9)
VISION-FLAN CHAT	67.6	1490.6	78.3	86.1
+ LLaMA 2 Chat	47.0 (69.5)	869.6 (59.3)	74.6 (95.3)	65.8 (76.4)

Table 9: Results of replacing Vicuna 1.5 with LLaMA 2 Chat in four VLMs. The gray rows denote the performance of original models and blue rows denote the performance of the VLMs after replacing the LLMs. The number in each bracket denotes the percentage of VLMs' performance after integration of LLaMA 2 Chat, compared to their original performance.



Figure 11: An example from MM-Vet to show that Vision-Flan allows VLMs to better recognize entities.

can be shared across LLMs with identical architecture but are tuned on different text alignment datasets. As shown in Table 9, we take four different models including VISION-FLAN BASE w/ frozen LLM which is finetuned on VISION-FLAN but with LLMs kept frozen as a case study, and directly replace their LLMs (Vicuna v1.5) with offthe-shelf LLaMA 2 Chat model. During inference, we use the official prompting template of LLaMA 2 chat instead of Vicuna v1.5. The results demonstrate that MLPs can be shared between LLMs with the same architecture but trained on different alignment datasets. An interesting observation is that

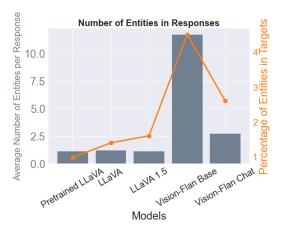


Figure 12: Performance of various VLMs on Entity Recognition. The gray bars show the average number of entities per response and the orange line shows the percentage of entities in the target response that appears in the prediction.

there is a significant performance boost on LLaVA-Bench after we swap in LLaMA 2 Chat. If we finetune both the MLPs and the LLMs in VISION-FLAN BASE and VISION-FLAN CHAT, we observe a remarkable performance drop when we swap in LLaMA 2 chat. This is understandable because the LLaMA 2 chat can not effectively interpret visual features compared to the visual-instruction-tuned Vicuna v1.5.

F.2 Discrepancy Between Evaluation Benchmarks

In Table 2 and 9, we identify large performance discrepancy between multiple-choice benchmarks (e.g., MME and MM-Bench) and LLaVA-Bench on several models. Specifically, in Table 2, LLaVA achieves a score of 70.8 on LLaVA-Bench, comparable to the performance level of LLaVA 1.5. In contrast, LLaVA's performance on MME and MM-Bench is markedly lower, with scores of 1151.6 and

38.7, respectively, compared to LLaVA 1.5, which scores 1531.3 and 66.7. Furthermore, this trend is also evident in Table 9. Upon substituting the LLMs in VISION-FLAN BASE and VISION-FLAN CHAT with off-the-shelf LLaMA 2 Chat, both models exhibit a notable decline in performance on MME and MM-Bench, while maintaining comparable performance on LLaVA-Bench. Our hypothesis posits that LLaVA-Bench does not require LLM's strong understanding of the visual features, but rather relies on the language-prior of LLMs (Lin et al., 2023). Furthermore, the data synthesized by GPT-4 facilitates the model's ability to generate long-form responses, aligning with the preferences of the evaluation metric, namely, GPT-4 itself.

G Additional Related Work

Vision-Language Models. Previous works (Li et al., 2019; Chen et al., 2020; Tan and Bansal, 2019; Su et al., 2020; Wang et al., 2023b) mainly pretrain vision-language models (VLMs) from scratch with a unified masked-language modeling (MLM) objective (Devlin et al., 2019), which can impose significant training cost and inferior performance. Recently, a line of works proposes to build VLMs from the off-the-shelf visual encoders and LLMs by introducing a small amount of bridging parameters that maps visual features into the embedding space of LLMs. Flamingo (Alayrac et al., 2022) presents a VLM that is capable of processing interleaved image-text inputs and generating responses based on the visual content. It proposes Perceiver Resampler as the bridging module to connect the frozen LLM and visual encoder. OFA (Wang et al., 2022) proposes a sequence-tosequence learning framework that maps images to discrete visual tokens and feeds the discrete visual tokens into LLMs. BLIP-2 (Li et al., 2023d) introduces O-Former to bridge pre-trained and frozen vision and language models, based on which, MiniGPT-4 (Zhu et al., 2023) further adds a linear projector to bridge the gap between the visual encoder and language model encoder. LLaVA (Liu et al., 2023e) introduces a projector to fuse visual information into a large language model and unfreezes language model during visual instruction tuning.

H Datasets Used in VISION-FLAN

Dataset & Reference	Tasks
CINIC-10 (Darlow et al., 2018)	 animal recognition in low resolution image shipping method recognition in low resolution image transportation option recognition in low resolution image animal presence classification in low resolution image object shipping object presence in low resolution image
MSCOCO (Lin et al., 2014)	 nultiple choice VQA short image captioning appliance recognition furniture recognition kitchen object recognition vehicle recognition animal recognition sports object recognition image text matching image text selection
FairFace (Kärkkäinen and Joo, 2021)	 human age classification human gender classification human race classification
IconQA (Lu et al., 2021b)	 abstract diagram understanding fill in blank in abstract diagram understanding
ImageNet-A (Hendrycks et al., 2021b)	1. object recognition of natural adversarial examples
ImageNet-C (Hendrycks and Dietterich, 2019)	 blur type classification coarse-grained image corruption classification weather type classification fine-grained image corruption classification
InfographicVQA (Mathew et al., 2022)	1. VQA2. document level VQA
SemArt (Garcia and Vogiatzis, 2018)	 painting time frame recognition painting type recognition painting school recognition painting technique recognition detailed image description
Set5 (Bevilacqua et al., 2012)	1. object recognition in low resolution image
TextCaps (Sidorov et al., 2020) VisDial (Das et al., 2019)	 image captioning with reading comprehension visual dialogue with short context visual dialogue with medium context visual dialogue with long context visual dialogue with very long context
STL-10 (Coates et al., 2011)	1. object recognition
Places365 (Zhou et al., 2018) Office-31 (Saenko et al., 2010)	 scene classification image domain and office object classification office object recognition

Dataset & Reference	Tasks
LSUN (Yu et al., 2015)	1. scene classification
FGVC-Aircraft (Maji et al., 2013)	1. aircraft family classification
	2. aircraft manufacturer classification
	3. aircraft variant classification
	4. aircraft model classification
DeepFashion (Liu et al., 2016)	1. cloth texture classification
CUB-200-2011 (Wah et al., 2011)	1. bird species recognition
CLEVR (Johnson et al., 2017)	1. VQA in 3D rendered images
	2. question answer matching
	3. visual dialogue in 3D rendered images
	4. VQA in 3D rendered images with multiple
	questions
CLEVR-CoGenT (Johnson et al., 2017)	1. VQA in 3D rendered images
	2. question answer matching
	3. VQA in 3D rendered images with multiple
	questions
A-OKVQA (Schwenk et al., 2022)	1. rationales generation
	2. answer rationale generation
	3. outside knowledge VQA
AI2D (Kembhavi et al., 2016)	1. diagram VQA
AID (Xia et al., 2017)	1. aerial scene classification
Caltech-256 (Griffin et al., 2007)	1. object recognition
CoVA (Kumar et al., 2022)	1. webpage recognition
DeepWeeds (Olsen et al., 2018)	1. weed species recognition
ExDark (Loh and Chan, 2019)	1. object recognition in low light environments
FFHQ-Text (Zhou and Shimada, 2021)	1. facial attribute textual descriptions generation
FlickrLogos-27 (Kalantidis et al., 2011)	1. logo recognition
FoodLogoDet-1500 (Hou et al., 2021)	1. food logo recognition
ImageNet-R (Hendrycks et al., 2021a)	1. object recognition in diverse image domain
	2. image style classification
ImageNet-Sketch (Wang et al., 2019)	1. object recognition in sketch
JHU-CROWD++ (Sindagi et al., 2019)	1. scene classification
MNIST-M (Ganin et al., 2017)	1. number recognition
MVTecAD (Bergmann et al., 2021)	1. object anomaly detection
	2. industrial item recognition

Dataset & Reference	Tasks
NABirds (Horn et al., 2015)	1. bird species recognition in north America
	2. bird body parts detection
Road-Anomaly (Lis et al., 2019)	1. road anomaly detection
SCUT-CTW1500 (Liu et al., 2017)	1. curve text detection in the wild
Total-Text (Chng et al., 2020)	1. scene text detection and recognition
VisDA-2017 (Peng et al., 2017)	1. object recognition in 3D rendered image
	2. multiple choice object recognition in 3D ren-
	dered image
Yoga-82 (Verma et al., 2020)	1. yoga pose recognition
Caltech101 (Fei-Fei et al., 2004)	1. object recognition
	2. living organism classification
Cars (Krause et al., 2013)	1. car brand maker and year classification
	2. car brand classification
Core50 (Lomonaco and Maltoni, 2017)	1. object recognition
NUS-WIDE (Chua et al., 2009)	1. animal presence classification
ObjectNet (Barbu et al., 2019)	1. object recognition
Places205 (Zhou et al., 2014)	1. indoor outdoor classification
300w (Sagonas et al., 2016)	1. indoor outdoor classification
Yahoo (Farhadi et al., 2009)	1. object recognition
LFW (Huang et al., 2007)	1. celebrity recognition
model-vs-human (Geirhos et al., 2019)	1. image-style classification
Office-Home (Venkateswara et al., 2017)	1. object recognition
Winoground (Thrush et al., 2022)	1. image caption matching
ConceptualCaptions (Sharma et al., 2018)	1. conceptual image captioning
KVQA+image question answer (Shah et al.,	1. knowledge-aware VQA
2019)	2. visual entity recognition
MemeCap (Hwang and Shwartz, 2023)	1. meme understanding
PlotQA (Methani et al., 2020)	1. VQA over scientific plots
SentiCap (Mathews et al., 2016)	1. image captioning conditioned on sentiment
VQA-E (Li et al., 2018)	1. VQA
	2. short image captioning
VQG (Mostafazadeh et al., 2016)	1. visual question generation
	2. short image captioning

Dataset & Reference	Tasks	
WIT (Srinivasan et al., 2021)	1. background knowledge extraction	
WikiArt (Tan et al., 2019)	1. artist genre style recognition	
VQA-RAD (Lau et al., 2019)	1. VQA in radiology	
VOC2007 (Everingham et al., 2010)	1. multiple object recognition	
VizWiz (Gurari et al., 2020)	1. answering visual questions from blind people	
	2. captioning image taken by blind people	
	3. quality issue classification of image taken by	
	blind people	
ViQuAE (Lerner et al., 2022)	1. knowledge based VQA about entities	
ST-VQA (Biten et al., 2019)	1. scene text VQA	
Stanford Dogs (Khosla et al., 2011)	1. dog species classification	
Sketch (Eitz et al., 2012)	1. living organism classification in sketch	
	2. object recongnition in sketch	
RAVEN (Zhang et al., 2019)	1. relational and analogical visual reasoning	
PICKAPIC (Kirstain et al., 2023)	1. image prompt generation	
PACS (Li et al., 2017)	1. object recognition in art painting	
	2. object recognition in cartoon	
	3. object recognition in photograph	
	4. dog image style classification	
	5. elephant image style classification	
	6. giraffe image style classification	
	7. guitar image style classification	
	8. horse image style classification	
	9. house image style classification	
	10. person image style classification	
NOCAPS (Agrawal et al., 2019)	1. multiple short captions generation	
Localized Narratives (Pont-Tuset et al., 2020)	1. COCO detailed image captioning	
	2. flickr30k detailed image captioning	
	3. open images detailed image captioning	
	4. ade20k detailed image captioning	
INATURALIST (Horn et al., 2018)	1. class classification	
	2. family classification	
	3. genus classification	
	4. Latin English name classification	
	5. order classification	
	6. phylum classification	
	7. supercategory classification	
HICO (Chao et al., 2015)	1. human activity detection	
GEOMETRY3K (Lu et al., 2021a)	1. geometry question answering	
FUNSD (Guillaume Jaume, 2019)	1. text detection in noisy scanned documents	
FLICKR30K (Plummer et al., 2017)	1. multiple captions generation	
DVQA (Kafle et al., 2018)	1. chart question answering	
DTD (Cimpoi et al., 2014)	1. coarse grained texture classification	
	2. multiple texture detection	

Dataset & Reference	Tasks	
DOMAIN NET (Peng et al., 2019)	1. object recognition in clip art	
	2. object recognition in infograph	
	3. object recognition in painting	
	4. object recognition in quickdraw	
	5. object recognition in real image	
	6. image style classification	
DOCVQA (Mathew et al., 2020)	1. document level VQA	
DAQUAR (Malinowski and Fritz, 2014)	1. VQA	
CONCADIA (Kreiss et al., 2022)	1. caption with background knowledge	
	2. short image captioning	
Visual7W (Zhu et al., 2016)	1. VQA object attribute	
VQAv2 (Goyal et al., 2017)	1. general VQA	
	2. question image matching	
Visual Genome(Krishna et al., 2017)	1. spatial relationship question answering	
OK-VQA(Marino et al., 2019)	1. outside knowledge VQA	
ScienceQA (Lu et al., 2022)	1. VQA	
	2. explanation generation	
OCR-VQA (Mishra et al., 2019)	1. VQA by reading text in image	
wikiHow-image (Yang et al., 2021)	1. next step generation	
	2. image text step ordering	
	3. immediate next step selection	
	4. text image step ordering	
SciCap (Hsu et al., 2021)	1. figure captioning	
LAD (Zhao et al., 2019)	1. detailed object description generation	
Dark Zurich (Sakaridis et al., 2019)	1. time of the day classification	
RAF-DB (Li and Deng, 2019)	1. human emotion detection	
GQA (Hudson and Manning, 2019)	1. spatial relationship question answering	
VQA (Antol et al., 2015)	1. color	
	2. activity recognition	
	3. counting	
	4. object presence	
	5. object recognition	
	6. positional reasoning	
	7. scene recognition	
	8. sentiment understanding	
	9. sport recognition	
	10. utility affordance	
Multimodal Factual Checking (Yao et al., 2023)	1. multimodal factual checking	

I Task Categories in VISION-FLAN

Category	Tasks
Perception	1. CLEVR-CoGenT VQA in 3D rendered images
	2. CLEVR-CoGenT question answer matching
	3. CLEVR-CoGenT VQA in 3D rendered images
	with multiple questions
	4. CLEVR VQA in 3D rendered images with
	multiple questions
	5. GQA spatial relationship question answering
	6. VQA color
	7. VQA activity recognition
	8. VQA counting
	9. VQA object presence
	10. VQA object recognition
	11. VQA positional reasoning
	12. VQA scene recognition
	13. VQA sentiment understanding
	14. VQA sport recognition
	15. VQA utility affordance
	16. VQA-E VQA
	17. VQAv2 general VQA
	18. Visual Genome spatial relationship question
	answering
	19. CLEVR question answer matching
	20. VizWiz answering visual questions from blind
	people
	21. DAQUAR VQA
	22. MSCOCO multiple choice VQA
	23. Visual7W VQA object attribute
	24. CLEVR VQA in 3D rendered images
Outside Knowledge	1. KVQA knowledge aware VQA
	2. VIQUAE knowledge based VQA about entities
	3. VQARAD VQA in radiology
	4. OK-VQA outside knowledge VQA
	5. A-OKVQA outside knowledge VQA
Reasoning	1. GEOMETRY3K geometry question answering
	2. IconQA abstract diagram understanding
	3. IconQA fill in blank in abstract diagram under-
	standing
	4. InfographicVQA VQA
	5. InfographicVQA document level VQA
	6. ScienceQA VQA
	7. AI2D diagram VQA
OCR	1. DOCVQA document level VQA
	2. DVQA chart question answering
	3. PlotQA VQA over scientific plots
	4. OCR-VQA VQA by reading text in image
	5. ST-VQA scene text VQA

Category	Tasks
Document-Level OCR	1. FUNSD text detection in noisy scanned docu-
	ments
	2. SCUT-CTW1500 curve text detection in the
	wild
	3. Total-Text scene text detection and recognition
Phrase-Level OCR	1. CoVA webpage recognition
	2. FlickrLogos-27 logo recognition
	3. FoodLogoDet-1500 food logo recognition
Knowledge Extraction	1. CONCADIA caption with background knowl-
	edge
	2. KVQA visual entity recognition
	3. WIT background knowledge extraction
Semantic Art Understanding	1. Semart painting time frame recognition
	2. Semart painting type recognition
	3. Semart painting school recognition
	4. Semart painting technique recognition
	5. Semart detailed image description
	6. WikiArt artist genre style recognition
Visual Dialogue	1. CLEVR visual dialogue in 3D rendered images
	2. Visdial visual dialogue with short context
	3. Visdial visual dialogue with medium context
	4. Visdial visual dialogue with long context
	5. Visdial visual dialogue with very long context
Rational and Script Generation	1. ScienceQA explanation generation
	2. A-OKVQA rationales generation
	3. A-OKVQA answer rationale generation
	4. MemeCap meme understanding
	5. wikiHow-image next step generation
	6. VQG visual question generation
Coarse-grained Captioning	1. ConceptualCaptions conceptual image caption-
	ing
	2. FLICKR30K multiple captions generation
	3. NOCAPS multiple short captions generation
	4. PICKAPIC image prompt generation
	5. VizWiz captioning image taken by blind people
	6. VQA-E short image captioning7. VQG short image captioning
	8. MSCOCO short image captioning
	9. CONCADIA short image captioning
	9. CONCADIA short image captioning

Category	Tasks
Fine-grained Captioning	1. LAD detailed object description generation
	2. FFHQ-Text facial attribute textual descriptions
	generation
	3. Localized Narratives COCO detailed image
	captioning
	4. Localized Narratives flickr30k detailed image
	captioning
	5. Localized Narratives open images detailed im-
	age captioning
	6. Localized Narratives ade20k detailed image
	captioning
	7. SciCap figure captioning
	8. SentiCap image captioning conditioned on sen-
	timent
	9. TextCaps image captioning with reading com-
	prehension
Scene Classification	1. 300w indoor outdoor classification
	2. AID aerial scene classification
	3. Dark-Zurich time of the day classification
	4. JHU-CROWD scene classification
	5. LSUN scene classification
	6. Places205 indoor outdoor classification
	7. places365 scene classification
Animal Classification	1. CUB-200-2011 bird species recognition
	2. DeepWeeds weed species recognition
	3. INATURALIST class classification
	4. INATURALIST family classification
	5. INATURALIST genus classification
	6. INATURALIST Latin English name classifica-
	tion
	7. INATURALIST order classification
	8. INATURALIST phylum classification
	9. INATURALIST supercategory classification
	10. NABirds bird species recognition in north
	America
	11. NUS-WIDE animal presence classification
	12. STANFORD DOGS dog species classification
	13. NABirds bird body parts detection

Category	Tasks	
Vehicle Classification	1. Cars car brand maker and year classification	
	2. Cars car brand classification	
	3. FGVC-Aircraft aircraft family classification	
	4. FGVC-Aircraft aircraft manufacturer classifi-	
	cation	
	5. FGVC-Aircraft aircraft variant classification	
	6. FGVC-Aircraft aircraft model classification	
Human Activity	1. HICO human activity detection	
	2. RAF-DB human emotion detection	
	3. Yoga-82 yoga pose recognition	
Facial Recognition	1. LFW celebrity recognition	
	2. Fairface human age classification	
	3. Fairface human gender classification	
	4. Fairface human race classification	
Anomaly Detection	1. Road-Anomaly road anomaly detection	
	2. MVTecAD object anomaly detection	
General Object	1. Caltech-256 object recognition	
	2. Caltech101 object recognition	
	3. Caltech101 living organism classification	
	4. Core50 object recognition	
	5. ImageNet-A object recognition of natural ad-	
	versarial examples	
	6. MNIST-M number recognition	
	7. MVTecAD industrial item recognition	
	8. ObjectNet object recognition	
	9. Office-Home object recognition	
	10. Office-31 image domain and office object clas-	
	sification	
	11. Office-31 office object recognition	
	12. STL-10 object recognition	
	13. Set5 object recognition in low resolution im-	
	age	
	14. VOC2007 multiple object recognition	
	15. MSCOCO appliance recognition	
	16. MSCOCO furniture recognition	
	17. MSCOCO kitchen object recognition18. MSCOCO vehicle recognition	
	19. MSCOCO animal recognition	
	20. MSCOCO sports object recognition	
	21. Yahoo object recognition	

Category	Tasks
Complex Reasoning	1. RAVEN relational and analogical visual rea-
	soning
	2. Multimodal Factual Checking multimodal fac-
	tual checking
	3. wikiHow-image image text step ordering
	4. wikiHow-image immediate next step selection
	5. wikiHow-image text image step ordering
Image Text Matching	1. MSCOCO image text matching
	2. Winoground image caption matching
	3. MSCOCO image text selection
	4. MSCOCO question image matching
General Object Classification in Special Image	1. DOMAIN NET object recognition in clip art
Domain	2. DOMAIN NET object recognition in infograph
	3. DOMAIN NET object recognition in painting
	4. DOMAIN NET object recognition in quick-
	draw
	5. DOMAIN NET object recognition in real im-
	age
	6. ExDark object recognition in low light environ-
	ments
	7. ImageNet-R object recognition in diverse im-
	age domain
	8. ImageNet-Sketch object recognition in sketch
	9. PACS object recognition in art painting
	10. PACS object recognition in cartoon
	11. PACS object recognition in photograph
	12. SKETCH living organism classification in
	sketch
	13. SKETCH object recognition in sketch
	14. Cinic-10 animal recognition in low resolution
	image 15. Cinic-10 shipping method recognition in low
	resolution image
	16. Cinic-10 transportation option recognition in
	low resolution image
	17. Cinic-10 animal presence classification in low
	resolution image
	18. Cinic-10 object shipping object presence in
	low resolution image
	19. VisDA-2017 object recognition in 3D ren-
	dered image
	20. VisDA-2017 multiple choice object recogni-
	tion in 3D rendered image
	tion in 5D fondorou iniugo

Category	Tasks
Image-Style Classification	1. DOMAIN-NET image style classification
	2. ImageNet-R image style classification
	3. PACS dog image style classification
	4. PACS elephant image style classification
	5. PACS giraffe image style classification
	6. PACS guitar image style classification
	7. PACS horse image style classification
	8. PACS house image style classification
	9. PACS person image style classification
	10. Model-vs-human image style classification
Image Quality Classification	1. ImageNet-C blur type classification
	2. ImageNet-C coarse-grained image corruption
	classification
	3. ImageNet-C weather type classification
	4. ImageNet-C fine-grained image corruption
	classification
	5. VizWiz quality issue classification of image
	taken by blind people
Texture Classification	1. DTD coarse grained texture classification
	2. DTD multiple texture detection
	3. DeepFashion cloth texture classification

J VISION-FLAN Tasks

J.1 Generation Tasks

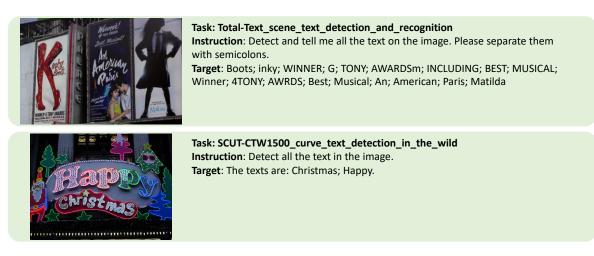


Figure 13



Task: FUNSD_text_detection_in_noisy_scanned_documents Instruction: Identify all the text in the image. Any ordering of the text is acceptable. Each chunk of text should be surrounded by double quotes and separated by commas. Target: "Description", "Displays", "BRANDS", "Adjustment", "Carlton", "Amount", "Displays", "31,000.00", "(31,000.00)", "Distribution:", "", "5/5", "", "0.00", "Date", "Date", "Date", "THE AMERICAN TOBACCO COMPANY", "APPROVED MARKETING PROJECT EXPENSE RECOMMENDATION", "S0002 Supp

2", "Private Stock", "Current Budget", "\$ 7,569,000.00", "Revised Budget", "\$ 7,569,000.00", "\$ 0.00", "CAR- MMT- DSP", "PRV- MMT- DSP", "Prepared By:", "Approved By:", "Approved By:", "Prepared By:", ", "Accounting File", "Project No", "Offer Description", "Charge Code"

Figure 14

		Image: A control of the cont
	Visinge Dolt	

Task: CoVA_webpage_recognition Instruction: What is the name of the website based on the given image? Target: The name of the website is www.amazon.com.



Task: FlickrLogos-27_logo_recognition Instruction: Detect and provide the logo name in the image. Target: The logo is Ford.



Task: FoodLogoDet-1500_food_logo_recognition Instruction: What is the logo of the food product in the image? Target: The logo in the image is Del Monte.

Figure 15





Task: CONCADIA_caption_with_background_knowledge

Instruction: Caption this image. Along with the caption, give me some background knowledge regarding this image. **Target**: The beginning of the Regularis Concordia, drafted by thelwold in hermeneutic style. David Woodman gives a translation of the start of a charter drafted by "thelstan A", S 416 issued on 12 November 931:

Task: KVQA_visual_entity_recognition

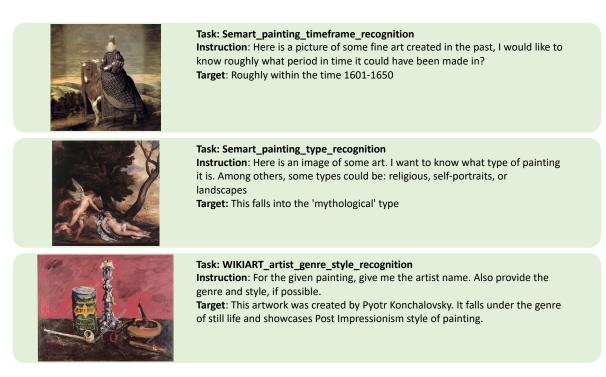
Instruction: You are provided with a picture. Write a caption for the image mentioning the name of the people present in the image and also their occasion depicted.

Target: Tryggve Gran in Antarctica (1911)



Task: WIT_background_knowledge_extraction Instruction: Give me some background knowledge about this image. In your answer, you should include named entities. Target: Alexandrovskaya Square is a city square of Taganrog.

Figure 16





Task: Semart_painting_school_recognition

Instruction: I would like to know what school of art this painting could be from. Some possible schools of art are Italian, German, or Spanish among others

Target: This painting comes from the school of French art



Task: Semart_painting_technique_recognition

Instruction: Can you please tell me what technique is used to create the painting in this picture? Among some other techniques, it could be an oil painting?

Target: This painting uses Tempera and gold on paper, mounted on wood, 23 x 16 \mbox{cm}

Figure 18



Task: Semart_detailed_image_description

Instruction: Here is a picture of fine art, can you please give me a long description describing all of its details?

Target: Here is a description: The earliest reference to the painting appears in Francisco de los Santos, Descripción . . . del Escorial, published in 1657, when it was in the sacristy of the Pantheon: ' . . . commonly called the "Glory of El Greco" on account of the Glory above, but there is also represented, below, Purgatory and Hell, and on the other side, the Church Militant, with an immense number of the Faithful in adoration, raising their hands and eyes to Heaven, and among them Philip II; in the middle of the Glory is the Name of Jesus adored by Angels . . . signifying the words of Saint Paul In Nomine Jesu omne genu, flectatur Caelestium, Terrestrium, & Infernorum' (Saint Paul, Epistle to the Philippians, II, 10).The subject, then, is the Adoration of the Name of Jesus, a Jesuit counterpart of the Adoration of the Lamb, and incorporates the 'Church Militant', represented by the Holy League...

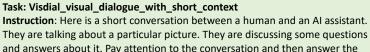
Figure 19





Task: Visdial_visual_dialogue_with_medium_context

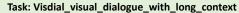
Instruction: This is a short conversation between two people, represented as A and B. They are talking about the given picture and are discussing some questions about it. Pay attention to the conversation and answer the question.
Input: A: what color is the counter? B: black tile A: can you see a microwave? B: no A: what color appliance? B: white A: is it a modern kitchen? B: i'd say so Question: is the sink stainless steel?
Target: no



and answers about it. Pay attention to the conversation and then answer the question at the end. Input: Human: any people? Assistant: no Human: any animals? Assistant: no

Question: is t it city? Target: Assistant: no





Instruction: Here is a conversation between 2 people. They are talking about a picture and discussing some questions and answers about it. Read the conversation and then answer as the next person. Input: Person1: how many motorcycles? Person2: 20 Person1: what color are they? Person2: black and white Person1: how many men? Person2: 20 Person1: is this in a city? Person2: no Person1: any women? Person2: no Person1: is a town? Person2: no Question: are they in leather? Target: Person2: yes



Task: Visdial_visual_dialogue_with_very_long_context

Instruction: Here is a detailed conversation between a person and a robot. They are discussing some questions and answers about a picture. From the conversation, answer the question as the robot.

Input: Human: what kind of uniform are the men wearing? Robot: they look like military Human: how many men would you guess there are? Robot: there are 3 men and a civilian woman Human: what color is the plane? Robot: white Human: what is the woman doing? Robot: talking to 1 of the men and pointing at the side of the plane Human: does the plane have writing on it? Robot: some numbers but i cannot make them out Human: does it look like a military plane? Robot: i think so but it is a close up, so hard to tell Human: are there any other planes in the image? Robot: yes i see parts of 2 others in the background Question: what is the woman wearing? Target: Robot: a white and blue dress

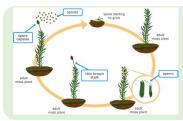
Figure 21



Task: CLEVR_visual_dialogue_in_3D_rendered_images

Instruction: You are given some question and answer pairs as dialogue history, and you will answer the question at the end based on the image.

Input: What number of large blue matte things are the same shape as the big green matte object? 0 \n Is the number of red shiny objects left of the small red shiny object greater than the number of small gray metallic spheres? no \nDo the green thing to the left of the red object and the large thing that is right of the tiny red object have the same shape? no \nIs there any other thing that is the same size as the red metal object? yes \nWhat number of cubes are either big rubber things or tiny yellow rubber objects? 0 \nDoes the large sphere have the same material as the green cylinder? no \nThe large thing that is behind the matte ball in front of the matte thing that is on the right side of the large green metal cylinder is what shape? **Target**: cylinder





Task: ScienceQA_explanation_generation

Instruction: Given a question and its answer, explain the rational behind the answer.

Input: Question: What can happen to the spores after they are released? Answer: They can grow into an adult moss plant.

Target: After they are released, spores can land on the ground and germinate. When spores germinate, they grow into adult moss plants. Unlike sperm and eggs, spores do not fuse.

Task: A-OKVQA_rationales_generation

Instruction: Provide 3 rationales for the given question and answer. Input: The question is: What kind of precipitation is at the top of the mountain? The answer is: snow. Target: The 3 rationales are: 1. The change in the atmosphere causes fog in

higher elevations. 2. The precipitation is snow. 3. The mountain tops are white.



Task: A-OKVQA_answer_rationale_generation

Instruction: Answer the question and provide an explanation. Input: The question is: What is the age of this woman? Target: The answer is 60 because She is older with grey hair but not really old yet.

Figure 23



Task: MemeCap_meme_understanding

Instruction: Interpret and explain the meaning of the given Meme. **Target**: Meme poster is trying to convey that don't like seeing their schoolmates outside school and will do anything to hide from them.







Task: Wikihow_next_step_generation

Instruction: The goal is to "Magazine Roll-Ups". Given current step specified by the content of the image and you have finished all previous steps: Zip up the sides of your boots in readiness for storing. Roll up an unwanted magazine and insert into one boot. Roll up a second unwanted magazine and insert it into the other boot. Put your boots in a standing up position in your shoe storage area.. What is the next step?

Target: Put your boots in a standing up position in your shoe storage area.

Task: VQG_visual_question_generation

Instruction: Given an image, generate a relevant question about the content of the image.

Target: What was being delivered?



Task: VQG_short_image_captioning Instruction: Given an image, you will generate a very abstract caption for the image.

Target: Exterior of a brown house

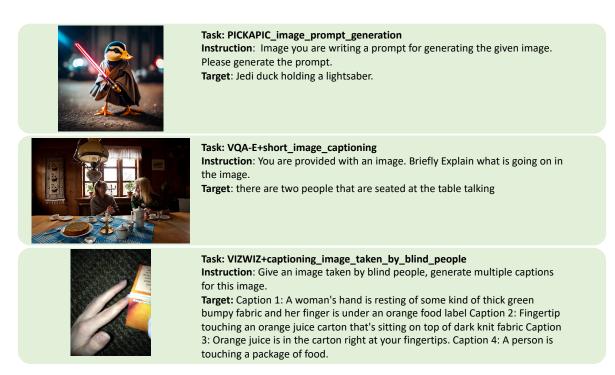


Task: MSCOCO_short_image_captioning Instruction: In this task, you are given an image and you will need to generate a short caption to describe it. Target: A very cute stuffed animal with a candy bar.



Task: CONCADIA _short_image_captioning Instruction: Can you describe the visual appearance of this image in one sentence? Target: Red-and-white-striped lighthouse, behind a stand of palm trees

Figure 25





Elon Musk to Twitter employees: "Go hard or go home!" Twitter employees: *go home* Flon Musk:



Task: ConceptualCaptions_conceptual_image_captioning

Instruction: In this task, you will generate a short caption for the given image. The image could depict various scenes, objects, or people. Your goal is to provide a short and accurate caption that describes the main elements the image. Pay attention to the details, such as colors, objects, actions, and interactions between elements, to create a meaningful and informative caption.

Target: actor arrives at the premiere.

Task: FLICKR30K_multiple_captions_generation

Instruction: Each image has something going on. Carefully analyze the image and generate 5 short captions for each image.

Target: Caption 1: A young woman intently looking at something while another woman in a hat looks on. Caption 2: A young girl in glasses observes something in the distance. Caption 3: a teenager and her mom at a public place. Caption 4: A blond girl is fixing her sunglasses. Caption 5: A woman adjusts her sunglasses.

Figure 27





Task: VIZWIZ_captioning_image_taken_by_blind_people

Instruction: Give an image taken by blind people, generate multiple captions for this image.

Target: Caption 1: A woman's hand is resting of some kind of thick green bumpy fabric and her finger is under an orange food label Caption 2: Fingertip touching an orange juice carton that's sitting on top of dark knit fabric Caption 3: Orange juice is in the carton right at your fingertips. Caption 4: A person is touching a package of food.

Task: NOCAPS_multiple_short_captions_generation

Instruction: Give me a list of 10 short captions for this image. Target: Caption 1: Group of people playing polo on bicycles on blacktop. Caption 2: A man riding a bicycle wearing a hat. Caption 3: Individuals playing a game consisting of riding on bicycles and hitting a ball with mallets. Caption 4: Three men in jackets playing croquet on bicycles. Caption 5: some people are playing hockey with their bicycle. Caption 6: Three people that are riding bicycles around on a basketball court. Caption 7: Several people ride bikes on what appears to be park asphalt. Caption 8: A group of people are riding the bicycle and playing hockey. Caption 9: Four people riding bicycles and playing polo while on a concrete pad near many houses. Caption 10: Four people playing polo on their bicycles on pavement.





Task: LOC-NARRATIVES_COCO_detailed_image_captioning Instruction: I want to know more about this image. Can you please describe it in detials?

Target: In this picture there are elephants at the right and left side of the image, there is water, grass land and rocks at the right and left side of the image, there are trees and dried grass at the background area of the image.

Task: LOC-NARRATIVES_flickr30k_detailed_image_captioning Instruction: Please give me a detailed caption about the input image. Target: In this image, there are two children in different color t-shirts, playing on an inflatable. One of these children is holding a toy and smiling. In the background, there are other toys, wooden objects and a person.



Task: LOC-NARRATIVES_open_images_detailed_image_captioning Instruction: What is going in this image? Give me a detailed description. Target: In this picture I can see food items in the jars with lids, which are on the wooden object, and there is blur background.

Figure 29





Task: LAD_detailed_object_description_generation Instruction: I'll give you an image. What is the main object in it? Please

describe the main object in great details. **Target**: The object in the image is touring car. It is white, is big (compared to cars), weighs tons, is long, moves fast, has doors, has seats, has windows, has a engine, has a horn, has a steering wheel, has a brake, has a number plate, has four wheels, has lights, can move, can be driven, can carry a small number (≤ 10) of passengers, can carry a large quantity (> 1 tons) of goods, is for engineering, is for rescue, is for civil use, is for family, consumes diesel oil, can be used on urban roads, can be used on rural roads, is safe, is made of metal, is made of plastic, is expensive



Task: LOC-NARRATIVES_ade20k_detailed_image_captioning

Instruction: Can you give me a detailed description about this image? **Target**: In this picture we can see few people and poles on the ground and we can see fences. In the background we can see a building with windows and we can see the name board.

Figure 31



Task: FFHQ-Text_facial_attribute_textual_descriptions_generation Instruction: Generate some detailed descriptions for the face in the given image. Your description should contain the age, color of eyes, skin color and other facial attributes.

Target: This woman turns her face towards the front side. This girl is about 15 to 20 years old and has big brown eyes with double eyelids, bushy flat eyebrows and medium white to olive skin. A woman has bushy, medium flat eyebrows, brown eyes with double eyelids and a square face. This girl has a medium flat nose, a big natural mouth opened and a heart-shaped face. This woman is about 25 to 32 years old with long wavy brown hair cover up ears, square shape face and olive skin. This woman has small brown eyes with double eyelids, thick flat eyebrows, a big vegetable nose and a big natural mouth opened. A girl with a heart-shaped face, olive freckled skin and medium wavy cape blond hair cover up ears. A woman has medium wavy cape brown hair cover up ears and medium white to olive skin.

J.2 Classification Tasks



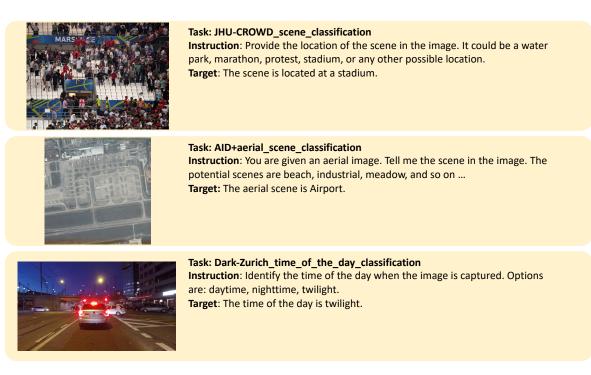
Task: LSUN_scene_classification

Instruction: In this task you will be provided with a picture of a scene (dining room, bedroom, kitchen, outdoor church, and so on) and you have to classify images into their corresponding scene categories. Your answer should be the name of the place. Options: (a) tower (b) classroom (c) dining room (d) bedroom (e) kitchen (f) church outside (g) living room (h) conference room (i) restaurant **Target:** (h) conference room

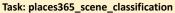
Task: Places205_indoor_outdoor_classification

Instruction: In this task, you have to identify if the place or scene pictured is indoor or outdoor. In the image is among a total of 205 classes such as Hospital, Bridge, Courtyard, Motel,.... The classes of the images are a diverse set of places or scenes. Pay attention to the details as some of the images may contain an object that relates to a specific place while some images may directly show the place or scenary. So, your answer should be the place or scene shown in the image Options: (a) Outdoor (b) Indoor **Target**: (b) Outdoor

Figure 33





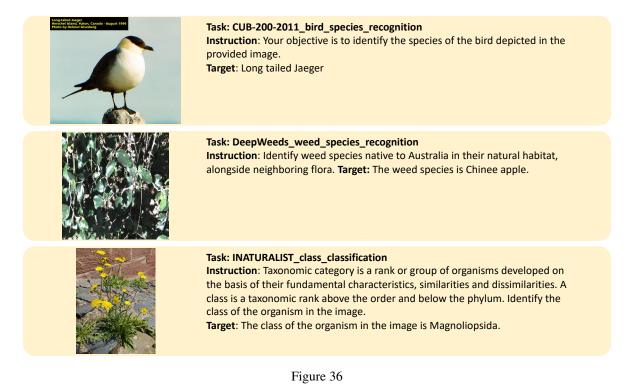


Instruction: Your task involves analyzing an image of a scene and identifying the appropriate name for that particular scene. Examples of scene names could include airfield, airplane cabin, airport terminal, alcove, alley, amphitheater, amusement arcade, etc. **Target**: plaza

Task: 300w_indoor_outdoor_classification

Instruction: In this task, you will be presented with an image depicting a human portrait image. Your objective is to accurately classify the image by identifying the two categories it belongs to which are indoor and outdoor. To do so, carefully examine the visual elements present in the image, such as the background, people's clothes and any distinguishing features that can provide valuable clues for determining the category. For instance, if a person is at a baseball game outdoors, the category is outdoors. Once you have determined the category, provide your answer as the name of the category. **Target**: Outdoor

Figure 35



15317





Task: INATURALIST_family_classification Instruction: The family is a taxonomic rank above the genus and below the order. Identify the family of the organism in the image. Target: The family of the organism in the image is Ranunculaceae.

Task: INATURALIST_genus_classification Instruction: The genus is a taxonomic rank above the species and below the family. Identify the genus of the organism in the image. Target: The genus of the organism in the image is Esox.



Task: INATURALIST_Latin_English_name_classification

Instruction: Identify the organism in the image. Give the english name(also called common name) followed by the scientific name(also called latin name). For example : "The organism in the image is Common Earthworm. Its scientific name is Lumbricus terrestris.

Target: The organism in the image is Blue-breasted Cordonbleu. Its scientific name is Uraeginthus angolensis.

Figure 37

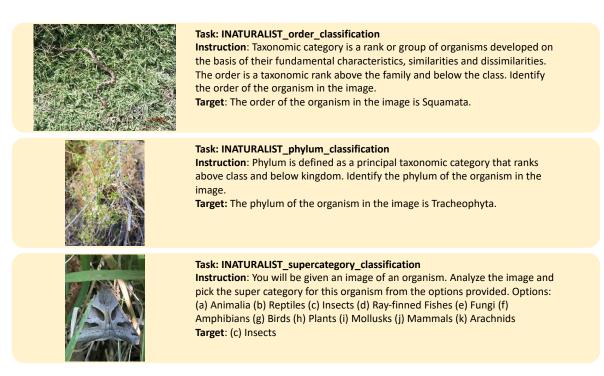




Figure 39



Task: STANFORD_DOGS_dog_species_classification Instruction: Identify the breed of the dog in the image. Some sample classes are dhole, giant schnauzer, and leonberg. Target: The dog breed is an Italian greyhound



Figure 40

Task: FGVC-Aircraft_aircraft_family_classification

Instruction: From the image provided to you, guess the family of the aircraft. Hint: Family: A family represents a collection of aircraft models produced by the same manufacturer, sharing common characteristics, design principles, or technological platforms. **Target**: Spitfire



Task: FGVC-Aircraft_aircraft_manufacturer_classification

Instruction: Determine the manufacturer of the provided aircraft image. The manufacturer refers to the company that designs, builds, and assembles the aircraft, possessing the expertise and experience in the aviation industry necessary for production and delivery. Target: British Aerospace



Task: FGVC-Aircraft_aircraft_variant_classification

Instruction: Your objective is to analyze an aircraft image and provide the variant of the aircraft. (e.g., A300B4). Variant: A variant indicates a variation of a particular aircraft model, often incorporating specific modifications, improvements, or customizations compared to the base model. Target: Yak-42

Task: FGVC-Aircraft_aircraft_model_classification



Instruction: Your objective is to analyze an aircraft image and provide the manufacturer, family, and variant of the aircraft in the specified order: manufacturer; family; variant (e.g., Airbus; A300; A300B4). Manufacturer: The manufacturer refers to the company that designs, builds, and assembles the aircraft, possessing the expertise and experience in the aviation industry necessary for production and delivery. Family: A family represents a collection of aircraft models produced by the same manufacturer, sharing common characteristics, design principles, or technological platforms. Variant: A variant indicates a variation of a particular aircraft model, often incorporating specific modifications, improvements, or customizations compared to the base model. Target: Dornier; Dornier 328; Dornier 328

Task: Cars_car_brand_maker_and_year_classification



Instruction: In this task, based on the given image dataset of different cars, you have to identify the model + car make + Year of Make of a car in the image among a total of 196 categories such as Audi A5 Coupe 2012, BMW 3 Series Sedan 2012, Bentley Arnage Sedan 2009,... Pay attention to details such as the size, logo, type of the car to identify the model. So by looking at a car image, Give your answer in the following format: Model of the Car++Make of the Car++Year of Make

Target: GMC Savana Van 2012

Figure 42



Task: Cars_car_brand_classification

Instruction: In this task, you have to identify the brand of the car such as Audi, BMW, Bentley,... This means you have to identify the company which manufactured the car. For this, you need to look at the logo shown in the car image. Based on the detailing shown for the car image, the company model of the car can be identified. So, your answer should be the brand name of the car. Target: Aston Martin

Figure 43



Task: HICO_human_activity_detection Instruction: Answer a simple question. What is the person in the image doing? If there is no action being performed, describe the main object in the image. Target: A person is skateboarding.



Task: RAF_DB_human_emotion_detection Instruction: Give me details about the human in the image. What is their gender, race and age? What emotion are they depicting? Target: The gender of the person is male. Their age range is 4-19 and their race is Asian. The emotion of the person in the image is Sadness.



Task: Yoga-82_yoga_pose_recognition Instruction: What is the name of the yoga pose? Target: The yoga pose is Extended Revolved Triangle Pose or Utthita Trikonasana.

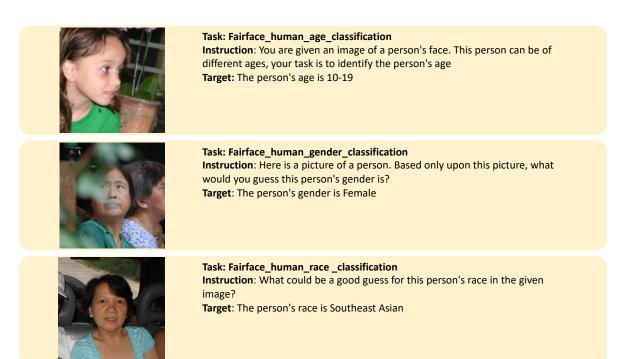


Figure 45



Task: LFW_human_face_recognition

Instruction: In this task, you will be presented with a face image of an individual. Your objective is to accurately classify the image by identifying the person's identity it represents. To accomplish this, you must meticulously examine the facial features present in the image, such as the shape and structure of the face, eyes, nose, mouth, hair, and any other distinguishing features such as moles, scars, or birthmarks that can provide valuable clues for determining the identity. For instance, certain facial proportions, distinct eye color, or unique hair style could be defining characteristics of an individual's identity. Just as one might identify a bicycle by its wheels or a sunflower by its petals in other datasets, in this case, a person can be identified by their unique set of facial features. Once you've made an informed determination based on these visual clues, provide your answer as the identity of the person. **Target**: Pete Sampras



Task: Road-Anomaly_road_anomaly_detection Instruction: Detect the unusual dangers which can be encountered by a vehicle on the road.

Target: The dangers are lost tires.



Task: MVTecAD_object_anomaly_detection

Instruction: The primary objective of this task is to accurately identify the type and cause of anomalies in the object present in the provided image. The image depicts a specific category of object and texture, and within this category, there are defect-free images as well as images exhibiting different types of defects. Your task is to carefully examine the image and meticulously identify the specific type and cause of any deviations from the normal appearance of the object or texture. Pay close attention to irregularities in lines, shading, color scheme, and level of detail. Additionally, analyze the unique characteristics of the category, including shape, color, and texture. Your focus should be on precisely identifying the particular type and cause of the anomaly. The potential anomalies to consider encompass a wide range, such as gray strokes, bent objects, holes, missing wires, and more. **Target:** The anomaly is combined.

Figure 47



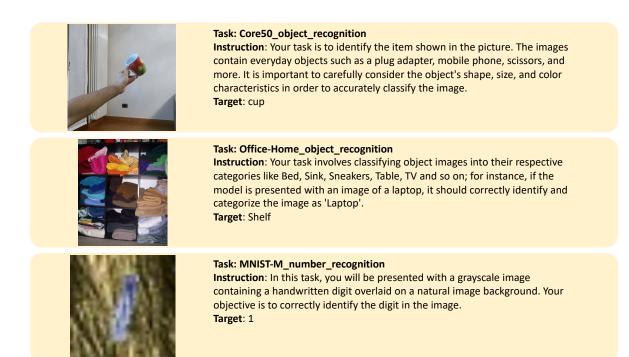


Figure 49



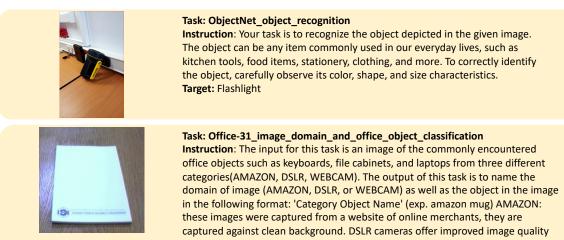


Task: ImageNet-A_object_recognition_of_natural_adversarial_examples Instruction: In this task, given an image, please identify what the image

contains a. The image could contain, among other things, animals, birds, daily objects, insects Options: (a) The provided image contains a lorikeet (b) The provided image contains a lion (c) The provided image contains an armadillo (d) The provided image contains a baseball player (e) The provided image contains a tricycle (f) The provided image contains a rugby ball (g) The provided image contains a jack-o'-lantern (h) The provided image contains a canoe **Target:** (a) The provided image contains a lorikeet

Task: MVTecAD_industrial_item_recognition

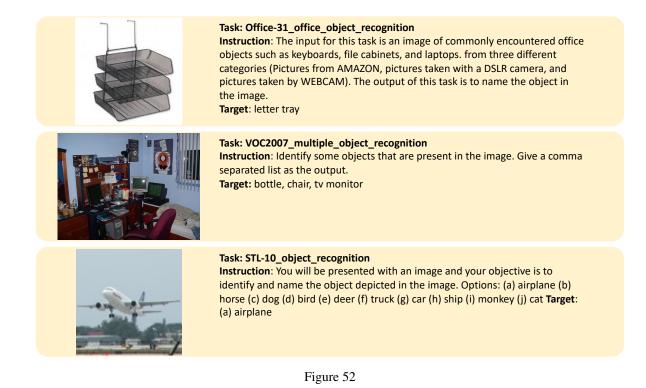
Instruction: Your objective is to classify an image based on its corresponding object category. The image provided encompasses a diverse range of industrial items, including a bottle, cable, carpet, and more. Focus on the overall visual appearance of the image, paying attention to details such as lines, shading, color scheme, and level of detail. It is crucial to analyze the distinctive characteristics of the object, such as its shape, color, and texture, as these features may vary significantly between different object categories. Once you have completed the classification process, output the appropriate object name based on your analysis. Target: The object is a pill.



when compared to standard webcams.

Target: webcam paper notebook

Figure 51



15324



Task: Set5_object_recognition_in_low_resolution_image Instruction: In this task, recognize the subject in the image from among 5 subjects, namely - baby, bird, butterfly, head, woman. Target: The subject in the image is a bird



Task: Yahoo_object_recognition

Instruction: In this task, you are given an image from a dataset, which contains images from different categories of animals, objects, and vehicles. These categories further divide into subcategories. Your job is to classify the given image into one of these subcategories, which could be anything from an aeroplane to a zebra. Your classification should be based on key identifiers like size, shape, color, distinctive features, and the context or environment depicted in the image. For example, if you're given an image of a zebra, your answer would simply be zebra. Remember that images could be of objects or vehicles as well. Your answer should be a single word representing the appropriate subcategory for the image, emphasizing specificity beyond the broad categories. **Target**: building

Figure 53



Task: MSCOCO_appliance_recognition

Instruction: Given an image of a common electronic appliance from around the house, identify the type of object it is. It could be an appliance that is commonly used in the kitchen to cook or store food. Options: (a) This image contains an oven (b) This image contains a microwave (c) This image contains a toaster (d) This image contains a refrigerator (e) This image contains a sink **Target:** (e) This image contains a sink



Task: MSCOCO_furniture_recognition

Instruction: Given an image of a piece of furniture in a house, identify the type of furniture. It is usually used to make the house look better and can be made of different kinds of material. Options: (a) This image contains a dining table (b) This image contains a bed (c) This image contains a toilet (d) This image contains a chair (e) This image contains a couch (f) This image contains a potted plant

Target: (d) This image contains a chair

Figure 54





Task: MSCOCO_kitchen_object_recognition

Instruction: Given an image of something from the kitchen, identify what it could be. The image could be of cooking tools or items that are used for eating. It could also be used for serving food or storing it. Options: (a) This image contains a bottle (b) This image contains a cup (c) This image contains a wine glass (d) This image contains a fork (e) This image contains a knife (f) This image contains a bowl (g) This image contains a spoon

Target: (a) This image contains a bottle

Task: MSCOCO_vehicle_recognition

Instruction: Given an image of a vehicle, identify the kind of vehicle it is. The vehicle can be of different types; it could be something used, personal, or public transport. It could carry one or more people at the same time. Options: (a) This image contains a bus (b) This image contains a bicycle (c) This image contains a boat (d) This image contains an airplane (e) This image contains a motorcycle (f) This image contains a train (g) This image contains a truck (h) This image contains a car **Target**: (b) This image contains a bicycle

Task: MSCOCO_animal_recognition

Instruction: Given an image of an animal, identify the kind of animal in the image. The picture could be of more popular animals that are visible around zoos or are sometimes domesticated at home. They could also sometimes be found in the wild. Options: (a) This image contains a cat (b) This image contains a dog (c) This image contains a cow (d) This image contains a bear (e) This image contains a sheep (f) This image contains a bird (g) This image contains an elephant (h) This image contains a zebra (i) This image contains a giraffe (j) This image contains a horse **Target**: (h) This image contains a zebra

Task: MSCOCO_sports_object_recognition

Instruction: Given an image of sporting goods, identify what the object is. It could be used to play a team sport or an individual activity. The objects can also be used in different kinds of sports and sometimes make it easier for the wearer to play the sport. Options: (a) This image contains a ski (b) This image contains a surfboard (c) This image contains a frisbee (d) This image contains a baseball bat (e) This image contains a tennis racket (f) This image contains a baseball glove (g) This image contains a kite (h) This image contains a snowboard (i) This image contains a sports ball **Target:** (j) This image contains a sports ball

Figure 56



Task: Wikihow_image_text_step_ordering

Instruction: You are doing Dipping Pine Cones in Paint. Is the step "Twist the end of a bamboo skewer into the top of the pine cone." the next or previous step to the step in the image? Options: (a) next (b) previous **Target**: (b) previous





Task: Wikihow_immediate_next_step_selection

Instruction: You are doing Using an Oven to Dry Cilantro. What is the next step to step in the image? Options: (a) Store the dried cilantro leaves in an airtight container. (b) Preheat your oven to 250 °F (121 °C). (c) Remove the tray from the oven and let it cool for 10 minutes. (d) Spread the leaves on the baking tray to form 1 layer. (e) Wash the cilantro to remove dirt and debris. **Target:** (c) Remove the tray from the oven and let it cool for 10 minutes.

Task: Wikihow_text_image_step_ordering

Instruction: The goal is to "Thawing with a Microwave". Given the current step "Remove the plastic wrap and inspect your dough.", Is the picture the next or the previous step? Options: previous next Target: next

PEDOPHILIA is now LEGAL in CALIFORNIA. SB-145 passed! Now a 21 year old can have sex with an 11 year old, and not be listed on the sex registry as a sex offender. This is unbelievable California!

Task: multimodal_factual_checking

Instruction: Context: Our Rating A widely-shared Facebook post claimed California had legalized 'pedophilia,' and that 'Now a 21 year old can have sex with an 11 year old, and not be listed on the sex registry as a sex offender.' That post and many like it are simply wrong. They grossly distort the proposals in state SB 145, which aims to eliminate a disparity in how LGBTQ young people are treated on California's sex offender registry. The legislation would eliminate automatic sex offeder registration for young adults who are convicted of having voluntary anal or oral sex with a minor and are within 10 years of age of the victim. Instead, a judge would make that decision, just as existing law allows judges to decide whether to place offenders in cases involving vaginal intercourse on the registry. The bill would not, in any fashion, make it legal for any adult to have any type of sex with a minor. The only change involves giving a judge discretion over whether to list an offender on the sex registry for certain sex acts. We rate the claims in the Facebook post Pants on Fire. PANTS ON FIRE - The statement is not accurate and makes a ridiculous claim. Does the context support "PEDOPHILIA is now LEGAL in CALIFORNIA. Now a 21 year old can have sex with an 11 year old, and not be listed on the sex registry as a sex offender."? Options: (a) not sure (b) no (c) yes Target: A1: (b) no

Figure 58

Image 1	image 2	Image 3	knage 4
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00	$\bigcirc \bigcirc$		
knage 5	image 6	image 7	knage 8
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Option 1	Option 2	Option 3	Option 4
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Option 5	Option 6	Dation 7	Qptice 8
Option 5		V	Option 8
	Option 6	Option 7	
Option 5	Option 6	Option 7	Option 8

Task: RAVEN_relational_and_analogical_visual_reasoning Instruction: Each image has 8 images labeled as Image 1 to Image 8. These 8 images follow a specific pattern. Detect the pattern and select the next image in the sequence from the 8 available options. Target: Option 4

Figure 59



Task: image_text_matching

Instruction: Does "A woman in blue and purple holds a snowboard while standing in the snow." describes image? Options: (a) the description matches the image (b) the text is not a description of the image **Target**: (a) the description matches the image



Task: Winoground+image_caption_matching

Instruction: In this task, you will be provided with an image and two captions. Your task is to identify which of the two captions correctly describes the image. Options: (a) the white wall will soon be painted blue (b) the blue wall will soon be painted white

Target: (a) the white wall will soon be painted blue



Task: image_text_selection

Instruction: Which option in the options that is the caption of the image. Options: (a) A couple of laptops with one sitting on a microwave. (b) Two older women are preparing for a dinner. (c) A desk with a computer monitor, printer and cd rack. (d) A girl preparing to put condiments on her dinner plate. (e) A man is taking an image on his phone of a bus. **Target**: (d) A girl preparing to put condiments on her dinner plate.



Task: question_image_matching

Instruction: In this task, you need to decide if the image has enough information to answer "What does this man have hanging from his neck?" Options: (a) I can answer the question based on the image (b) I can not anser the question based on the image Tarret: (b) I can not asser the question based on the image

Target: (b) I can not anser the question based on the image

Figure 61



Task: DOMAIN-NET_object_recognition_in_clip_art

Instruction: Clip art is defined as simple pictures or symbols used in documents and presentations. The input is a clip art image. Identify the main object in the image. Target: zigzag



Task: DOMAIN-NET_object_recognition_in_infograph Instruction: An info graph is a visual image like a poster that is used to represent information or data about any object. For this task, the input will be a info graph. Identify the main object of the info graph. Target: toaster

Evenzation Childrood Drees

Task: DOMAIN-NET_object_recognition_in_painting Instruction: The input for this task is a painting. Identify the main object in the painting.

Target: see saw

Figure 62

Task: DOMAIN-NET_object_recognition_in_quickdraw Instruction: In this task, the input will be a rough sketch of something. Identify the main object depicted in the rough sketch. Target: dumbbell



Task: DOMAIN-NET_object_recognition_in_real_image Instruction: Identify the main object in the image. Target: blueberry



Task: ExDark_object_recognition_in_low_light_environments Instruction: The given image is taken in low-light environments. Identify the object in the image, including bicycle, boat, bottle, bus, car, and other objects. Target: The object is Bicycle.





Task: ImageNet-R_object_recognition_in_diverse_image_domain

Instruction: Your task is to classify the image using various categories. You need to carefully observe the details of the object in the image, including its shape, color, and texture, as these characteristics may vary across different renditions. Output the appropriate object name as the result of your classification process. **Target**: great white shark

Task: ImageNet_object_recognition_in_sketch

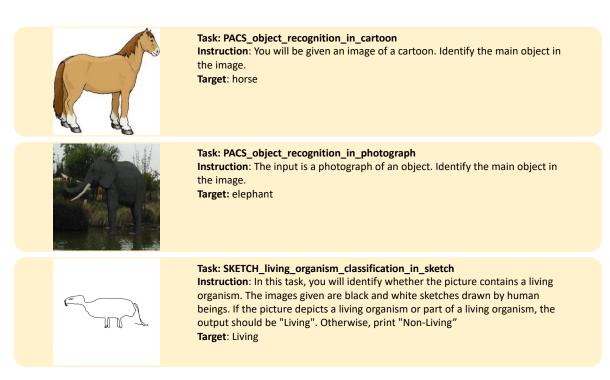
Instruction: You are given a sketch of an object. Tell me the name of the object in the image.

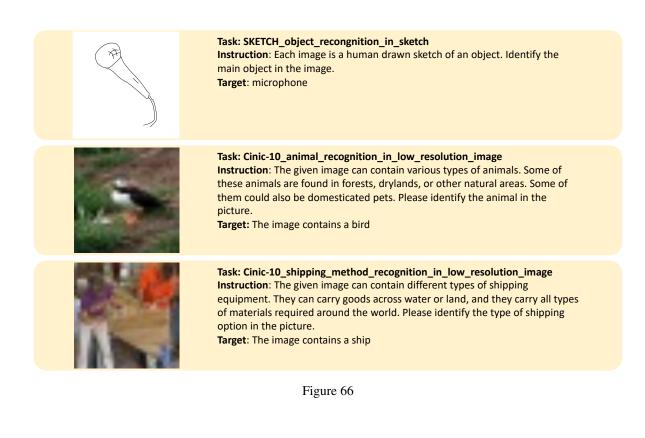
TargetThe sketch is a iron.

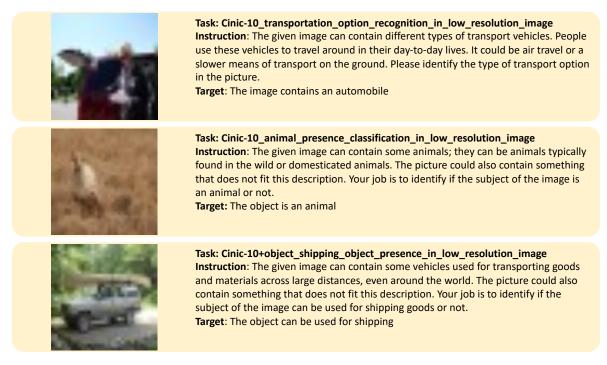


Task: PACS_object_recognition_in_art_painting Instruction: You will be given an art painting image as input. Identify the main object in the image. Target: dog

Figure 64







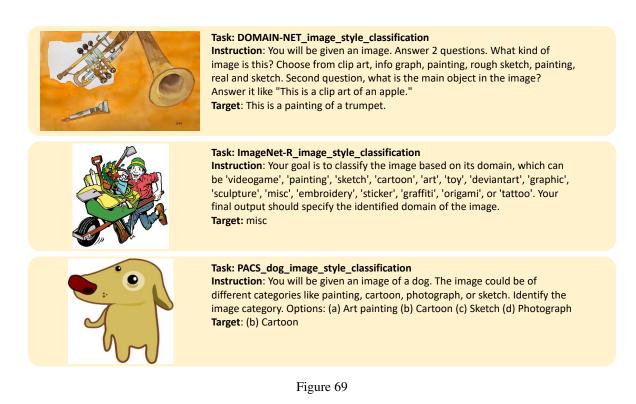


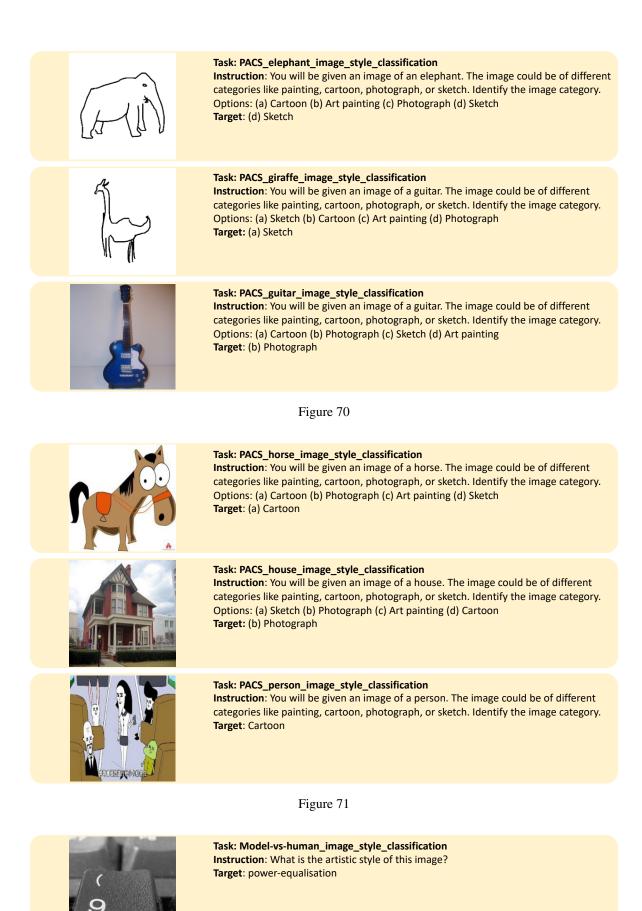


Task: VisDA-2017_object_recognition_in_3D_rendered_image

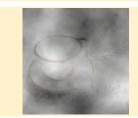
Instruction: Your task is to classify an image based on its corresponding object category. The image contains a variety of objects distributed among 12 categories, including aeroplane, horse, knife, person, plant, and others. To accurately classify the image, carefully analyze its visual characteristics, such as shape, color, texture, and spatial context relations, as these attributes can vary significantly across different domains. Once you have identified the object category of the image, output the appropriate label for your classification. **Target:** plant

Task: VisDA-2017_multiple_choice_object_recognition_in_3D_rendered_image Instruction: You are given an image which contains a 3D rendered object. Your goal is to identify the category of the object present in the image from the given options. Options: (a) knife (b) horse (c) train (d) bus (e) plant (f) skateboard (g) car (h) bicycle (i) truck (j) aeroplane Target: (i) truck









Task: ImageNet-C_blur_type_classification

Instruction: Given a blurred picture, identify the type of blur in the image, it can be blurred in different ways Options: (a) The image is corrupt, the specific corruption type is Glass blur (b) The image is corrupt, the specific corruption type is Defocus blur (c) The image is corrupt, the specific corruption type is Motion blur (d) The image is corrupt, the specific corruption type is Zoom blur

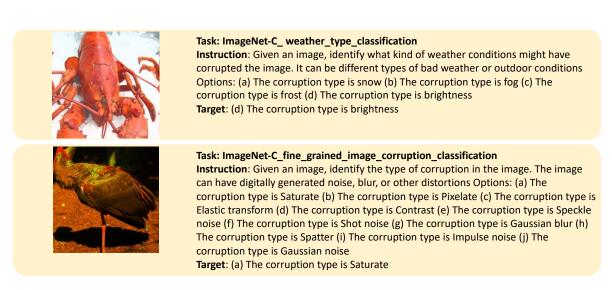
Target: (b) The image is corrupt, the specific corruption type is Defocus blur

Task: ImageNet-C_ coarse_grained_image_corruption_classification Instruction: In this task, identify the type of corruption given a corrupted image. It could be digitally altered, contain natural distortions or contain other corruptions Options: (a) The corruption type is weather (b) The corruption type is blur (c) The corruption type is noise (d) The corruption type is digital Target: (a) The corruption type is weather



Task: Vizwiz_quality_issue_classification_of_image_taken_by_blind_people Instruction: Explain why the image quality is bad. Options: (a) rotation (b) bad framing (c) too bright (d) no flaws (e) blur (f) too dark (g) other (h) obscured Target: (b) bad framing

Figure 73





Task: DTD+coarse_grained_texture_classification

Instruction: Texture is defined as the feel, appearance or consistency of a surface or substance from a human's perspective. Detect the primary texture represented in the image. Target: cracked



Task: DeepFashion_cloth_texture_classification Instruction: Can you write a very short description of the cloth? Target: The cloth is an Abstract Mirrored Print Dress.



Task: DTD_multiple_texture_detection Instruction: Texture is defined as the feel, appearance or consistency of a surface or substance from a human's perspective. Detect all the textures in the image. Present it as a comma separated list Target: porous

J.3 VQA Tasks



Task: GQA_spatial_relationship_question_answering Instruction: Answer the following question about the spatial relationship of objects in the given image. Your answer should be one or two words. Input: The sign is on what? Target: pole



Task: MSCOCO_multiple_choice_VQA

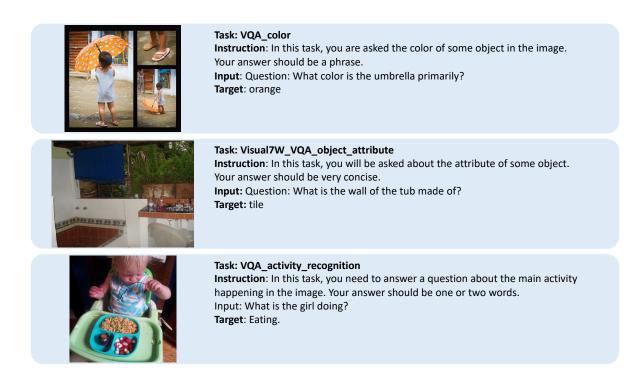
Instruction: Answer the given question by selecting an option. Inputs: What is green on the plate? Options: (a) Salad. (b) Garnish. (c) Broccoli. (d) Tomato. Target: (b) Garnish.



Task: VQA-E_VQA

Instruction: You are provided with an image and a question related to the image. Answer the question based on the information given in the image. Your answer should be a short phrase. Input: How many players are there? Target: 3

Figure 76

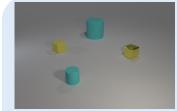


Task: CLEVR_VQA_in_3D_rendered_images



Instruction: The input for this task is an image of 3D-rendered objects and a question that fall into different categories. The questions fall into five classes of tasks: Exist, Count, Compare Integer, Query Attribute, and Compare Attribute. The task here is to answer the question. Given me a very short answer.

Input: How many other metal cubes have the same color as the tiny shiny block? Target: 0

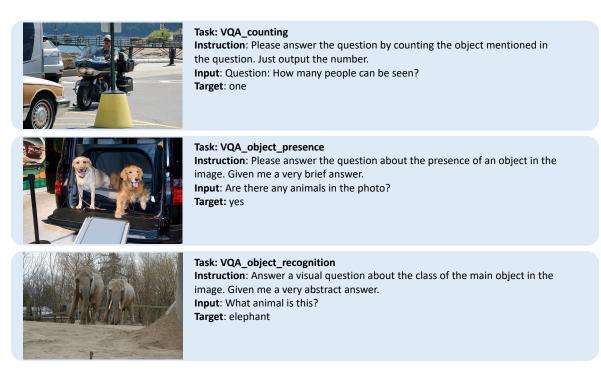


Task: CLEVR-CoGenT_VQA_ in_3D_rendered_images_with_multiple_questions Instruction: The input for this task is an image of 3D-rendered objects and a set of questions that fall into different categories. The questions fall into five classes of tasks: Exist, Count, Compare Integer, Query Attribute, and Compare Attribute. The output of this task is a set of answers to the given questions for each image. The answers should be generated based on the content of the image and the category of the question. The output should be in the form of text. The output should be in the format of "A1: YOUR ANSWER A2 YOUR ANSWER ..."

Input: Q1: Are there any other things that are the same color as the metallic cube? Q2: The matte thing that is in front of the small yellow metal thing has what shape? Q3: What is the size of the cyan thing that is left of the cyan matte cylinder behind the yellow matte thing? Q4: Does the yellow thing that is in front of the tiny yellow rubber block have the same shape as the tiny thing that is in front of the tiny metal block? ...

Target: A1: yes A2: cylinder A3: small A4: no A5: yes A6: 2 A7: large A8: no A9: rubber

Figure 78







the presented image and provide an answer to the question. Given me a very short answer.

Task: VQA_positional_reasoning

Input: What is to the right of cake? Target: fork

Task: VQA_scene_recognition

Instruction: You are asked a question about the scene in the image. Answer the question with one or two words. Input: Is this indoor or outdoor? Target: indoor

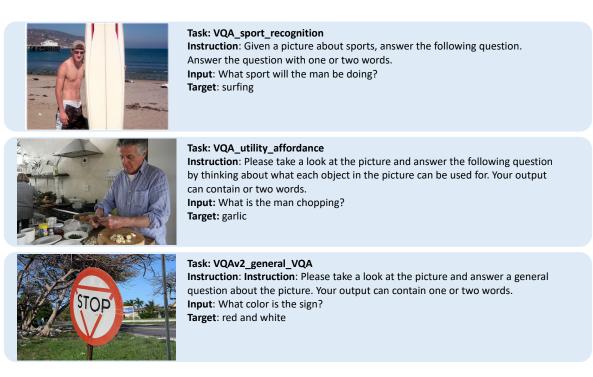
Instruction: In this task, the goal is to understand the location of objects within



Task: VQA_sentiment_understanding

Instruction: In this task, you will be asked a question regarding the emotion conveyed in the image. I need a short and concise answer. Input: The question is Is this dog happy? Target: yes

Figure 80





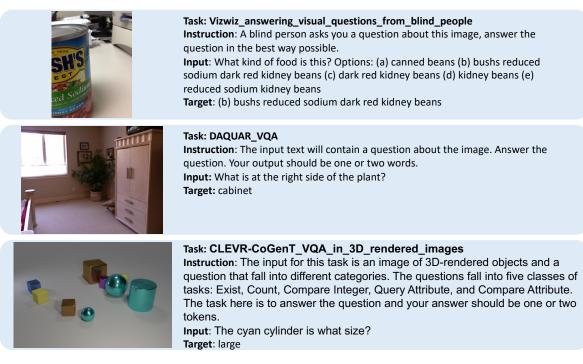
Task: Visual-Genome_spatial_relationship_question_answering Instruction: You are asked a question about the spatial relationship of objects in the image. Answer question with a short phrase. Input: What is on the pizza? Target: Ham

Task: CLEVR-CoGenT_question_answer_matching

Instruction: In this task, you will be presented with an image containing 3Drendered objects along with a set of questions and corresponding answers. Your goal is to correctly match each question with its corresponding answer based on the visual content of the image. The output format should follow this pattern: Q1A3, Q2A5, Q3A2, Q4A1, Q5A1, indicating the question number followed by the corresponding answer number.

Input: Q1: How many other objects are there of the same color as the rubber ball? Q2: Is the color of the shiny object that is right of the cyan rubber cylinder the same as the big cylinder? Q3: What is the yellow object that is in front of the tiny cyan cylinder made of? Q4: Is the material of the large purple object the same as the large sphere? Q5: There is a yellow metal block that is behind the cyan rubber object; does it have the same size as the tiny cyan cylinder? ... **Target:** Q1A5 Q2A7 Q3A8 Q4A6 Q5A6 Q6A3 Q7A2 Q8A1 Q9A4

Figure 82



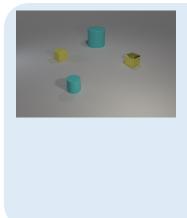
Task: CLEVR-question_answer_matching



Instruction: You will be given an Image of 3D-rendered objects, a number of Questions and same number of Answers. The task here is to match the questions to the right answers according to the image you see. The format of the output shoud be something like: Q1A3,Q2A5,Q3A2,Q4A1,Q5A1 **Input**: Q1: There is a shiny thing right of the big ball that is in front of the matte object in front of the matte cylinder; what is its shape? Q2: Is there any other thing that has the same size as the cube? Q3: Are there more balls that are behind the green metal sphere than rubber objects right of the gray matte ball? Q4: Is there a metal sphere on the right side of the rubber object on the left side of the yellow rubber thing?

Target: Q1A2 Q2A3 Q3A3 Q4A3 Q5A6 Q6A3 Q7A1 Q8A5 Q9A4

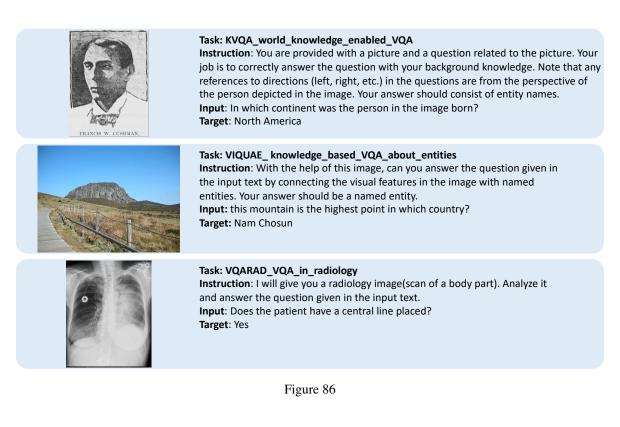
Figure 84



Task: CLEVR_VQA_in_3D_rendered_images_with_multiple_questions Instruction: The input for this task is an image of 3D-rendered objects and a set of questions that fall into different categories. The questions fall into five classes of tasks: Exist, Count, Compare Integer, Query Attribute, and Compare Attribute. The output of this task is a set of answers to the given questions for each image. The answers should be generated based on the content of the image and the category of the question. The output should be in the form of text.

Input: Q1: Are there any other things that are the same color as the metallic cube? Q2: The matte thing that is in front of the small yellow metal thing has what shape? Q3: What is the size of the cyan thing that is left of the cyan matte cylinder behind the yellow matte thing? Q4: Does the yellow thing that is in front of the tiny yellow rubber block have the same shape as the tiny thing that is in front of the tiny metal block? ...

Target: A1: yes A2: cylinder A3: small A4: no A5: yes A6: 2 A7: large A8: no A9: rubber







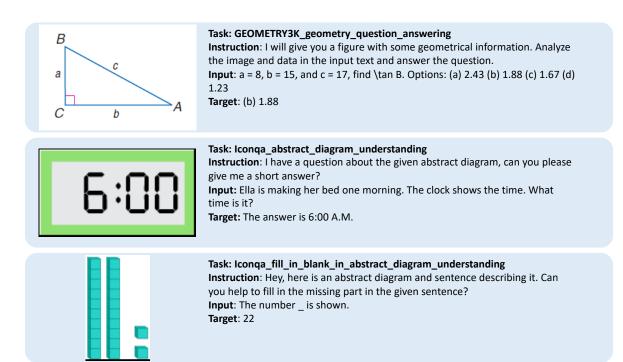
Task: OK-VQA_outside_knowledge_VQA

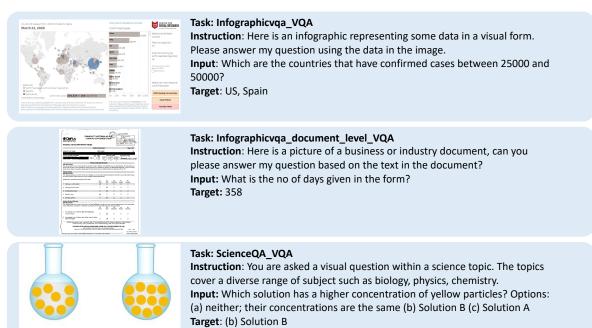
Instruction: Answer the following question about an image using your background knowledge outside of the given image. Your answer should be one or two words. Input: What activity might these vehicles been used for? Target: transportation

Task: A-OK-VQA _outside_knowledge_VQA

Instruction: Answer the question about the image. To correctly answer the question, you need think about knowledge outside the image. Your answer should be very short. Input: What time period of the day is it? Target: afternoon.

Figure 87



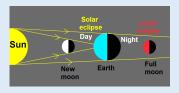


Solvent volume: 40 mL Solvent volume: 40 mL

Solution A

Solution B

Figure 89



Task: AI2D_diagram_VQA

Instruction: Answer the multiple-choice question based on the diagram. The answer should be one of the choices. The question is: Input: What provides the earth with solar energy? The choices are: (A) None of the above; (B) Sun; (C) New Moon; (D) Full Moon. Target: The answer is: (B).

Figure 90

	Task: DOCVQA_document_level_VQA Instruction: Check the image and answer the question given in the input text. Input: what is the reporting date mentioned ? Target: 5/4/98 - 7/17/98
Most preferred objects of different cutegories page voice basiset mitror metal 0 20 40 00 80 100	Task: DVQA_chart_question_answering Instruction: I am trying to analyze this chart. Can you answer the question given in the input text? Input: Is each bar a single solid color without patterns? Target: no
DAY- BOOMPACT	Task: OCR-VQA_VQA_by_reading_text_in_image Instruction: You are asked a question about the given image. Answer the question by reading the text written on the image. Input: Which year's calendar is this? Target: 2016