Fast and Distributed Mechanisms

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Today's talk

- What is a mechanism? Why and when do we want a mechanism?
- The trouble with mechanisms: a constrained design space
- Designing local mechanisms: how to implement mechanisms as fast distributed algorithms
- Open problems and future directions

What is a mechanism?

- Mechanism is a game and an algorithm (ex: an auction)
 - There is a set of agents that are strategic participants with private information (ex: valuation for the item to be assigned)
 - Agents participate by strategically revealing some of their private information (ex: bid for the item)
 - (ex: give the item to the highest bidder)
 - item, others get nothing)

Based on the information revealed, the mechanism assigns an outcome

Each agent gains some *utility* based on the outcome (ex: winner gets

- Primary goal (default): *Maximise total utility* of the agents (total welfare)
 - To do this, the algorithm should somehow know the private inputs of the agents?
 - Solution concept: design truthful (incentive-compatible) mechanisms, where *revealing the truth is a dominant strategy* for the agents
- Sidenote: Revelation principle states that we can always consider mechanisms where only interaction is agents revealing their information

Designing mechanisms

Example: Sealed bid auction

- (to maximise welfare)
- bid (*first-price auction*)
- *highest bid* and bid just above it (instead of its true valuation)
 - Not truthful, difficult to participate in

Goal: assign a single indivisible item to the agent that values it the most

• If we just ask the agents, each will bid infinity! There must be a cost

The classic solution: assign to the *highest bidder*, winner pays its own

Problem: to optimise its own utility, winner must guess the second-

Example: Sealed bid auction

- (second-price auction)
- Truthful:
 - every winning bid: true value second price
 - larger payment than gained utility

• To fix this, we design a new auction that "bids optimally" for the winner: the highest bidder gets the item and pays the second-highest bid

• If agent's true valuation is the highest bid, it gets the same utility for

• If agent's true valuation is not the highest bid, overbidding results in

"The" truthful mechanism: Vickrey-Clarke-Groves (VCG)

- Second-price auction is a special case of the (only) general truthful mechanism (*with non-trivial guarantees)
- Each agent submits their private information, mechanism computes the assignment that maximises total utility (!)
- The VCG-framework can be used for essentially any optimisation problem

- Each agent gets their utility + a payment function p consisting of two parts:
 - + The total utility of all other agents (the incentive) - The total utility of all other agents in the assignment that maximises this sum (normalisation)
- Normalisation term independent of agent's bid
- Utility + incentive = total utility: should report the truth so that the algorithm can maximise with respect to it!

The VCG mechanism

The problem with the VCG

- The VCG-mechanism is computationally infeasible for many interesting problems
- What if we just switch the optimal solution to the best efficiently computable solution?
 - Unfortunately this does not work! Each agent wants to find the report that maximises total utility, and this *might not be the truth!*
 - When all agents do this in parallel, behaviour is highly unpredictable (just like first-price auction)

Greedy mechanisms

- It is known that in certain settings, greedy algorithms can be turned into mechanisms
- - Each agent v is a node in a graph and has a (private) weight w(v)
 - Utility: w(v) if chosen and no neighbour chosen, 0 otherwise
 - Goal is to *find an independent set of large weight*

Example (from our work): maximum weight independent set (MWIS)

Simple greedy algorithm

• The following simple algorithm is known to compute a Δ -approximation (where Δ = maximum degree) [Sakai et al., 2003]

Repeatedly pick the node with the the long with its neighbours

- *Mechanism:* each agent reports its weight, find an independent set using the greedy algorithm, replacing weights with what agents reported
- Payments: each selected agent pays the critical price = the smallest bid that would have led to it being selected

Repeatedly pick the node with the largest weight into the set and remove

Truthfulness

- "bids optimally" for the winners
- higher bids, and vice versa
- will lead to non-positive utility.

This is again the format of the second-price auction: the mechanism

The algorithm has to be monotone: selected nodes are still selected with

• **Pf.** If truth is above the critical price, any bid above it will produce the same (non-negative) utility. If truth is below the critical price, overbidding

Distributed setting

- Now each agent is an entity in a communication network
- Computation proceeds in synchronous rounds, and in each round each agent can exchange messages with its neighbours and update its state
- At some point each agent must announce its own output
- We aim for local algorithms: number of communication rounds much lower than the size of the network

A distributed mechanism

- To make the greedy algorithm distributed, instead of choosing the global maximum, choose all local maxima (approximation retained)
- The main loop of the greedy algorithm can easily be implemented in a distributed setting: agents keep checking if they are the local maximum, join if yes, and stop if a neighbour joins
- The issue is the running time: there might be a long chain of increasing values that takes *O(n)* rounds to resolve (fast sequential, slow distributed)

Dealing with long chains

- allowed values)
- If done right, the mechanism is still truthful
- Loss in the quality of the solution depending on **K**

• To deal with this, we *discretise the values* (i.e. round reported values to K

- If message sizes are not bounded, easy without overhead!
 - **T**-round mechanism \rightarrow Gather full **T**-neighbourhood to each node, simulate mechanism with each possible bid to determine the critical price
- Non-trivial for bounded messages!
 - MWIS-mechanism: selected nodes determine the largest neighbour that is not already blocked by some other neighbour

Computing the payments

Our work

- exist (to be submitted soon)
- sampling colourings
 - <u>https://arxiv.org/abs/2402.16532</u>

• We present greedy distributed mechanisms for (weighted) independent set, dominating set, vertex cover, and coloring (their "natural" interpretations as mechanism design tasks) + a general framework when such mechanisms

• We also study stable matching: characterise the most general special case that has a fast distributed mechanism, show how to break ties fairly by

First examples of local mechanisms (*Distributed Algorithmic Mechanism* **Design** has focused on global problems such as routing or leader election)

Implementing distributed mechanisms

- One of the advantages of distributed mechanisms would be eliminating the need for a centralised entity that runs the whole mechanism
- In our analysis the *algorithm itself is not game-theoretic*, only the reporting of the private information
- Can we make the execution also resilient against strategic behaviour?
 - E.g. agent might not pass on message correctly or delete them altogether

Greedy mechanisms and beyond

- Proving that a "greedy" algorithm with a non-static score is monotone can be tricky
 - Lot of work in turning more convoluted greedy algorithms into mechanisms
- In the centralised setting there are other approaches such as linear programming
- Arguments from computational hardness of lying profitably: different arguments for the distributed setting

Distributed tie-breaking

- In sequential mechanisms tie-breaking is essentially trivial
- In distributed mechanisms, if not done carefully, it might blow up the running time (long chains of dependencies created by tie-breaking)
- We resolve this issue by computing a colouring: tie-breaking is consistent and length of chains is bounded by the number of colours
 - Tie-breaking problem: orient the conflict graph such that it is a DAG and the distance reachable along the orientation from any node is bounded