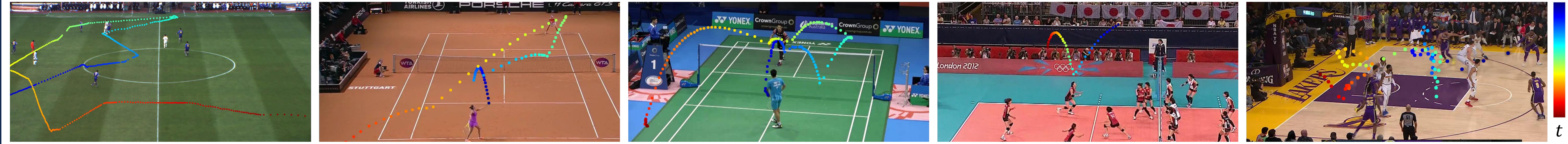


## TL; DR

- We propose a new **SBDT** baseline, **WASB**.
- We introduce a new evaluation protocol using 5 **SBDT** datasets from different sports (⚽🏸🎾🏐🏀). 6 **SOTA** methods are (re-)implemented for fair comparison.
- Experiments show that **WASB** substantially outperforms **SBDT** SOTAs on all the datasets.

## Sports Ball Detection & Tracking (SBDT)

Input: a (sports) video clip, Output: a  $(x, y)$ -coordinate of a sports ball (if visible) for each frame



## Dataset & Codebase

- **SBDT** datasets from 5 different sport categories: ⚽🏸🎾🏐🏀
- Volleyball 🏐 and Basketball 🏀 are newly introduced by us
- for Soccer ⚽ and Basketball 🏀, new annotations are provided

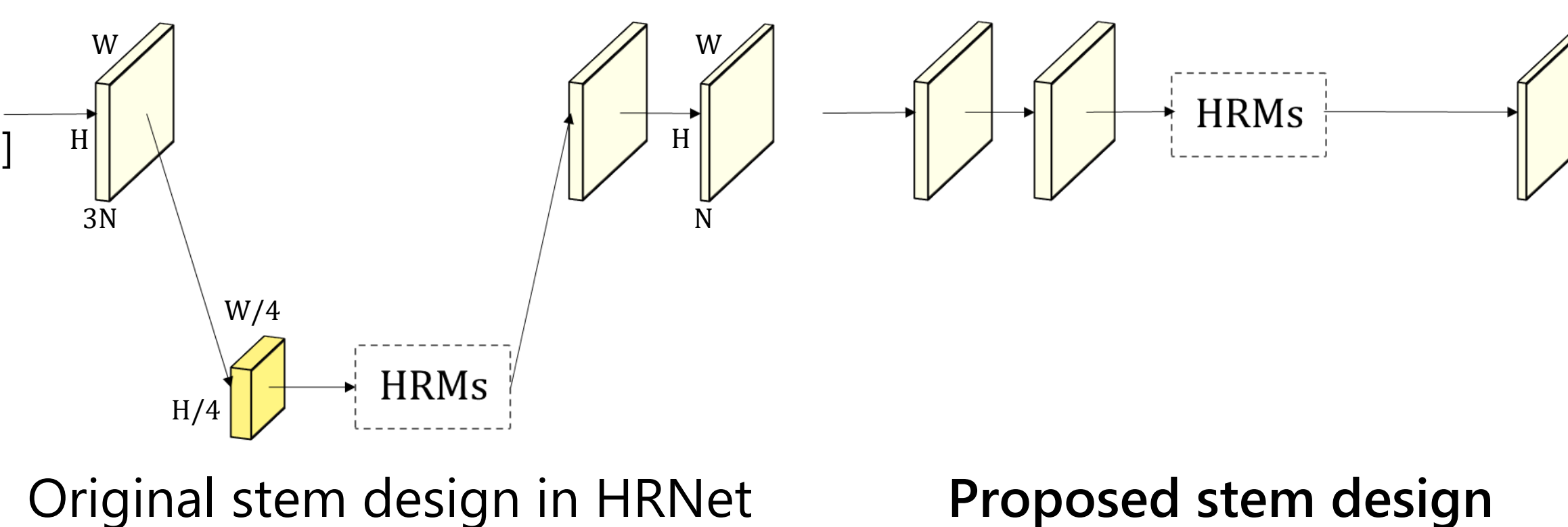
	Train						Test			
	resolution	FPS	games	clips	frames	disp.[pixel]	games	clips	frames	disp.
Soccer [19]	1920 × 1080	25	1	4	11994	10.4 ± 10.0	1	2	5999	15.7 ± 13.0
Tennis [32]	1280 × 720	30	7	65	14160	15.3 ± 13.0	3	30	5675	13.6 ± 10.2
Badminton [75]	1280 × 720	30	26	172	78558	11.8 ± 12.2	3	29	12656	12.5 ± 12.9
Volleyball	1280 × 720	N/A	39	3493	143213	14.4 ± 11.4	16	1337	54817	15.1 ± 11.5
Basketball	1920 × 1080	N/A	70	3392	244224	33.7 ± 21.8	11	432	31104	33.9 ± 21.4

- 6 **SOTA SBDT** methods, 2 of which (★) are minorly updated by us
- DeepBall [1], DeepBall-Large★, BallSeg [2], TrackNetV2 [3], ResTrackNetV2★, MonoTrack [4]

## Widely Applicable Strong Baseline (WASB)

### 1. High-Resolution Feature Extraction Model

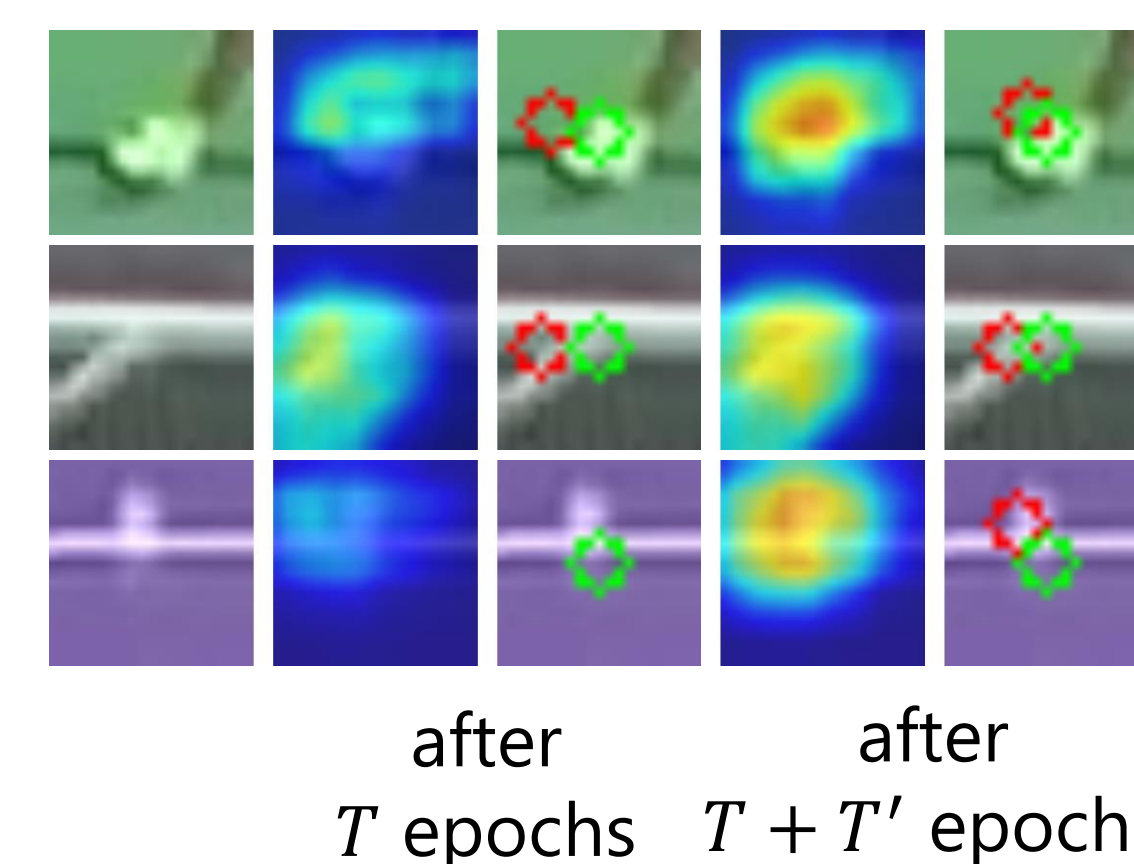
- High-Resolution Modules (HRMs) of small HRNet [5]
- Stem without strides to feed higher-resolution features to HRMs
- Multi-In Multi-Out (MIMO) design ( $N = 3$ )



### 2. Position-Aware Model Training

- Train a model that predicts heatmaps representing ball positions
- Focal-loss [6] with binary ground truth (GT) during the first  $T$  epochs
- Quality focal loss [7] with real-valued GT during remaining  $T'$  epochs

Binary GT							Real-valued GT							
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	1	1	1	0	0	0	0.73	0.86	0.73	0	0	0	0
0	1	1	1	1	0	0	0.73	1	1	1	0.73	0	0	0
0	1	1	1	1	0	0	0.86	1	1	1	0.86	0	0	0
0	1	1	1	1	0	0	0.73	1	1	1	0.73	0	0	0
0	0	1	1	1	0	0	0	0.73	0.86	0.73	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0



### 3. A Bunch of Tricks during Inference

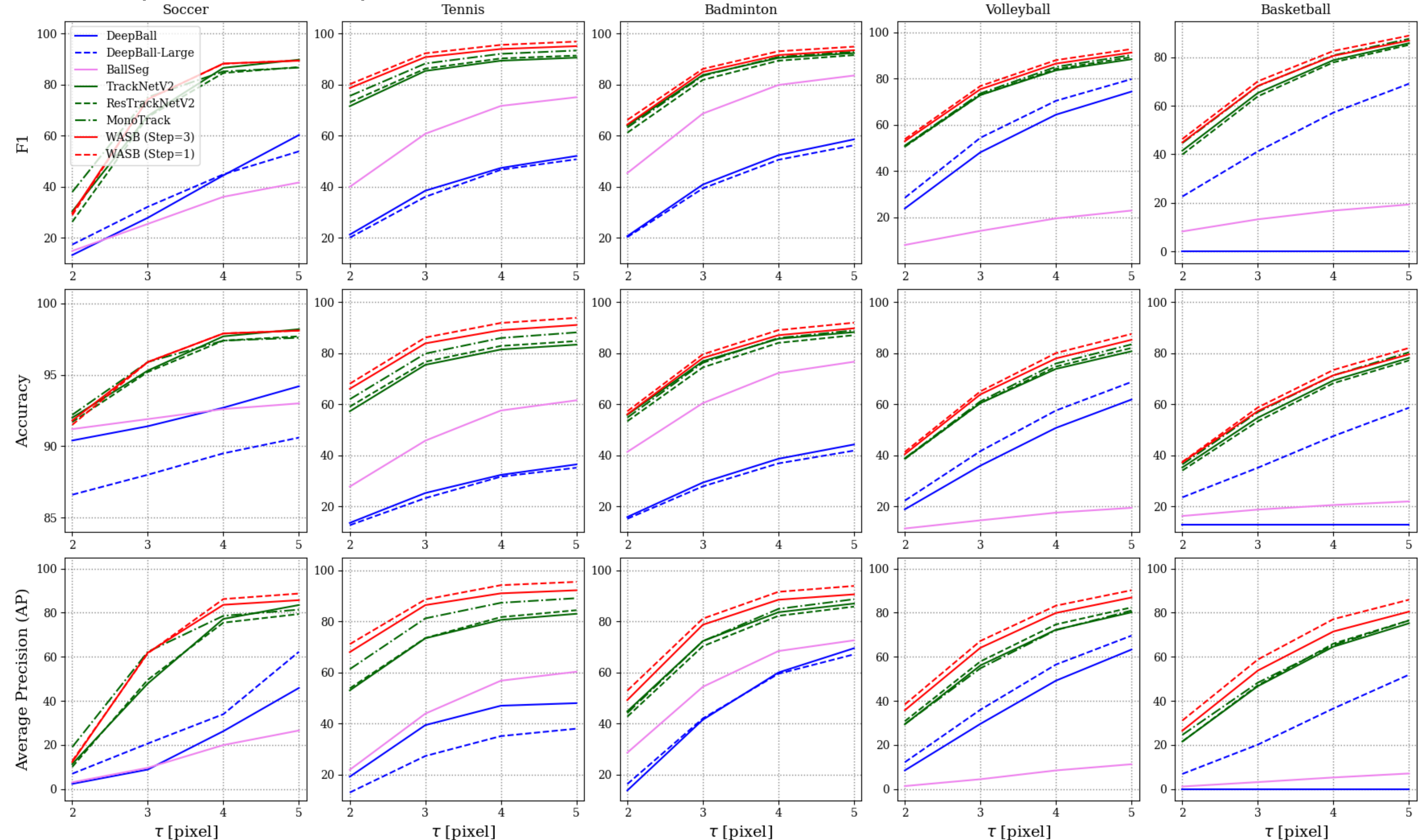
- prediction of each ball position (i.e.,  $(x, y)$ -coordinate) as a center of heatmap values in a detected blob
- online tracking with local motion model to take long-term temporal consistency into account
- oversampling the same image in different MIMO combinations to produce diverse detection candidates

## Results

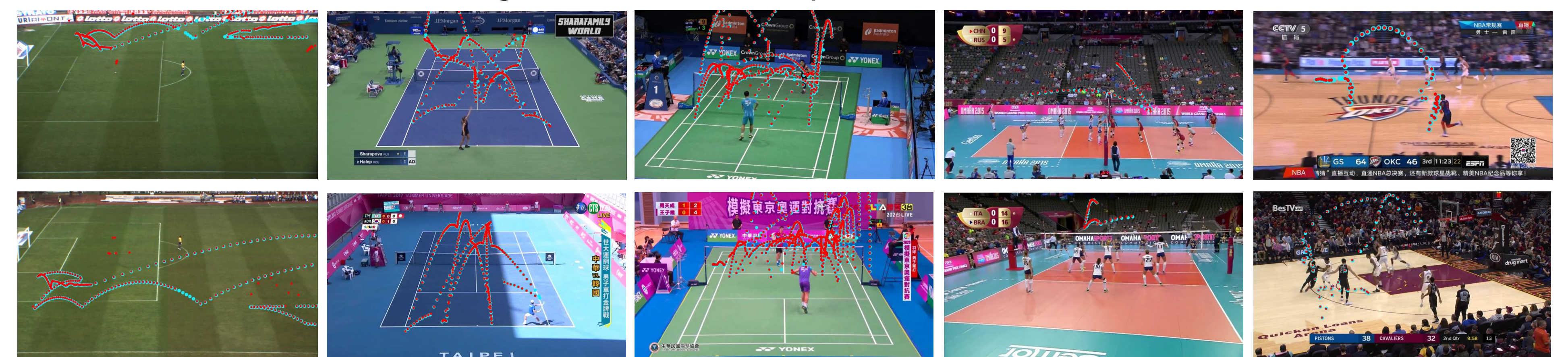
- Comparison on 5 datasets from different sports (distance threshold  $\tau = 4$ [pixel])

	# param.	Soccer				Tennis				Badminton				Volleyball				Basketball			
		F1 ↑	Acc. ↑	AP ↑	FPS ↑	F1	Acc.	AP	FPS	F1	Acc.	AP	FPS	F1	Acc.	AP	FPS	F1	Acc.	AP	FPS
DeepBall [40, 41]	0.1M	44.5	92.7	26.3	44.6	47.4	32.3	47.0	52.1	52.4	38.6	60.0	57.1	64.4	50.7	49.2	21.1	0.0	12.9	0.0	30.3
DeepBall-Large	1.0M	44.9	89.5	34.0	42.0	46.7	31.6	35.1	47.7	50.6	36.8	59.5	53.0	70.4	57.5	56.5	21.1	57.2	47.5	36.6	30.9
BallSeg [80]	12.7M	36.1	92.6	20.0	64.8	71.7	57.5	56.8	62.7	79.9	72.2	68.4	75.0	19.5	17.5	8.5	18.2	16.8	20.5	5.3	29.5
TrackNetV2 [75]	11.3M	86.6	97.7	77.2	66.0	89.4	81.4	80.6	55.3	90.5	85.6	83.6	77.0	83.6	73.8	72.3	17.6	78.8	69.3	64.6	28.0
ResTrackNetV2	1.2M	84.6	97.4	75.5	56.2	90.3	82.8	81.7	59.0	89.4	84.0	82.2	71.3	84.2	74.7	74.7	28.6	77.9	68.2	66.0	38.2
MonoTrack [50]	2.9M	85.2	97.4	78.6	58.0	92.1	85.9	87.3	64.1	90.9	85.9	84.9	75.5	85.1	75.9	72.1	19.7	80.8	71.3	65.3	32.1
WASB (Ours, Step=3)	1.5M	88.3	97.9	83.6	55.7	94.0	89.0	91.0	58.2	91.6	87.0	88.5	70.4	86.5	77.9	79.9	18.0	80.6	71.3	71.5	30.2
WASB (Ours, Step=1)	1.5M	88.2	97.9	86.2	23.6	95.6	91.8	94.2	35.2	93.1	89.0	91.6	34.3	88.0	80.0	83.2	15.8	82.6	73.4	77.1	22.3

- Comparison on 5 sports datasets with different  $\tau$



- Qualitative results (blue: ground truth, red: precision)



[1] DeepBall: Deep Neural-Network Ball Detector, in VISAPP, 2019.  
 [2] Real-time CNN-based Segmentation Architecture for Ball Detection in a Single View Setup, in ACM MM Workshops, 2019.  
 [3] TrackNetV2: Efficient Shuttlecock Tracking Network, in ICPAI, 2020.  
 [4] MonoTrack: Shuttle Trajectory Reconstruction from Monocular Badminton Video, in CVPRW, 2022.

[5] Deep High-Resolution Representation Learning for Visual Recognition, in TPAMI, 2020.  
 [6] Focal Loss for Dense Object Detection, in ICCV, 2017.  
 [7] Generalized Focal Loss: Learning Qualified and Distributed Bounding Boxes for Dense Object Detection, in NeurIPS, 2020.