

RGB and LUT based Cross Attention Network for Image Enhancement

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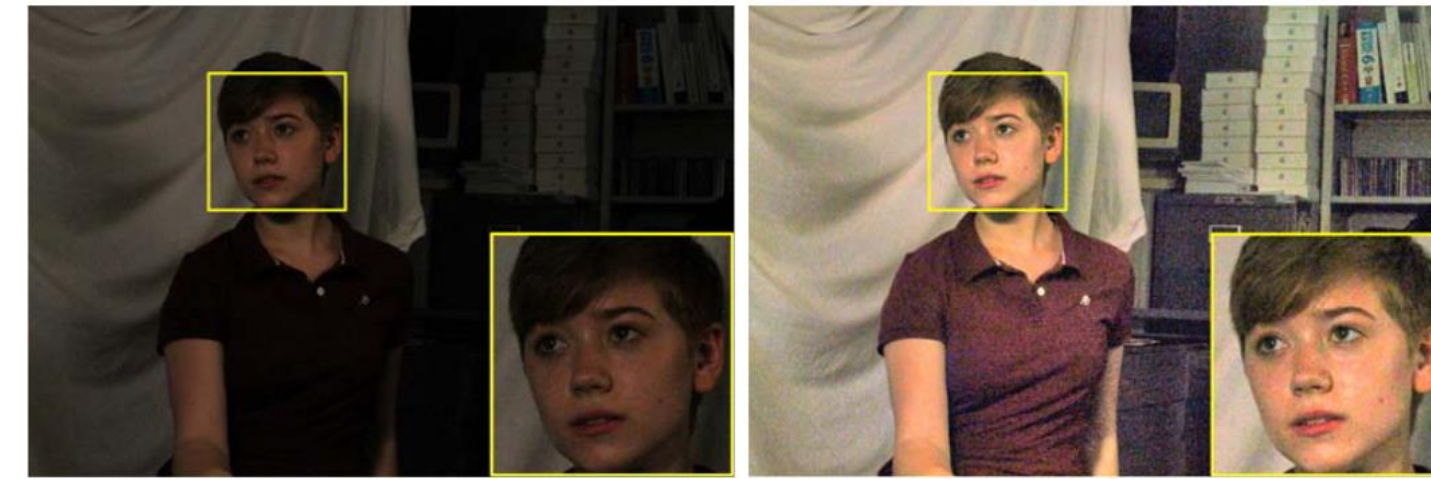
Problem Description

- Image enhancement aims at adapting low-light conditions and distorted colors.
- Single input might lead to image enhancement bias.

Challenge



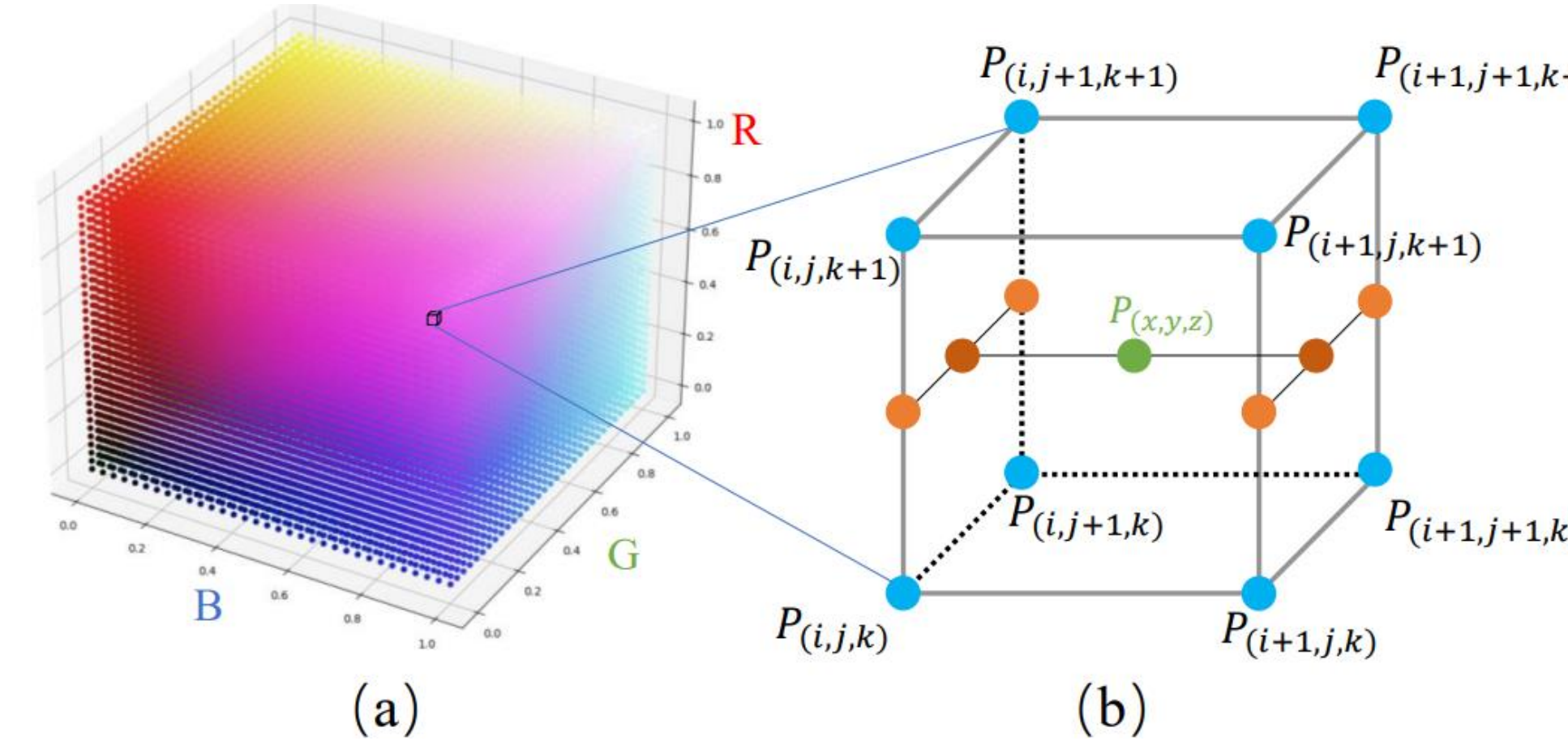
Details Missing



Noise

Method

3D LUT involves: look-up table and trilinear interpolation.

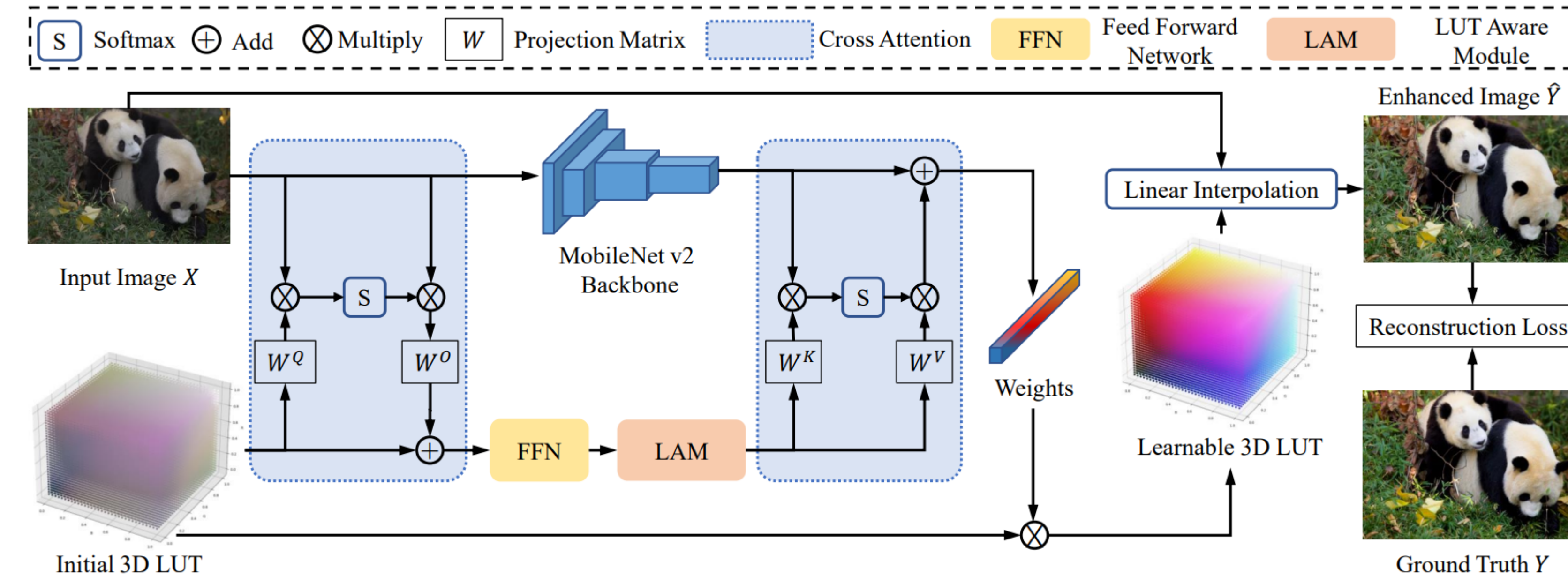


Input image I , the converted image O through the 3D LUT:

$$O_{(x,y,z)} = \psi(I_{(i,j,k)}^R, I_{(i,j,k)}^G, I_{(i,j,k)}^B)$$

(i, j, k) are the pixel coordinates of the image in RGB space, and $\psi(\cdot)$ is defined as the learnable LUT weight

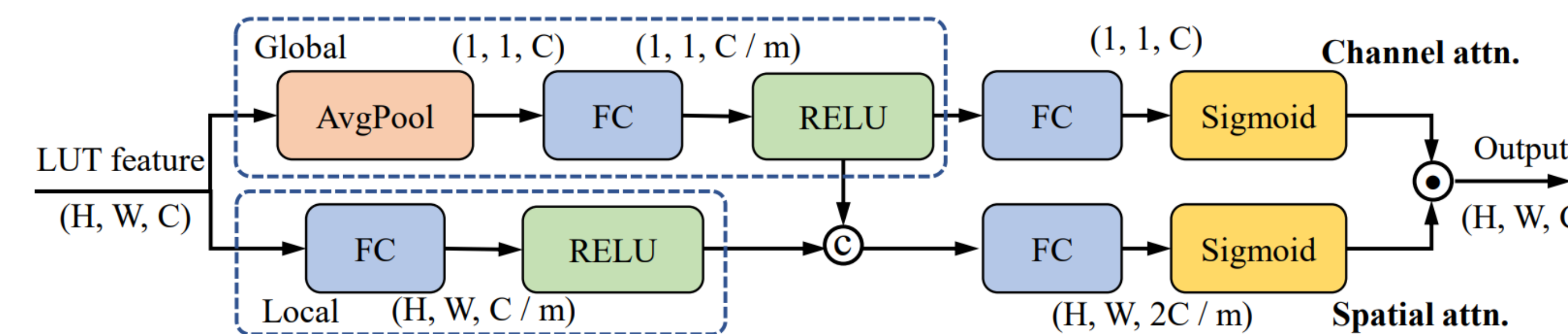
Pipeline



Two-way Interactive Bridge

$$\begin{aligned} \text{image} \leftarrow \text{LUT}: \mathcal{A}_{X \rightarrow L} &= [\text{Attn}(\tilde{l}_i W_i^Q, \tilde{x}_i, \tilde{x}_i)]_{i=1:h} W^O \\ \text{image} \rightarrow \text{LUT}: \mathcal{A}_{L \rightarrow X} &= [\text{Attn}(\tilde{x}_i, \tilde{l}_i W_i^K, \tilde{z}_i W^V)]_{i=1:h} \end{aligned}$$

LUT Attention Module



Channel global attention and Spatial local attention

Experimental Results

Table 1: Quantitative comparisons state-of-the-art methods on the FiveK. Table 2: Quantitative comparisons state-of-the-art methods on the HDR.

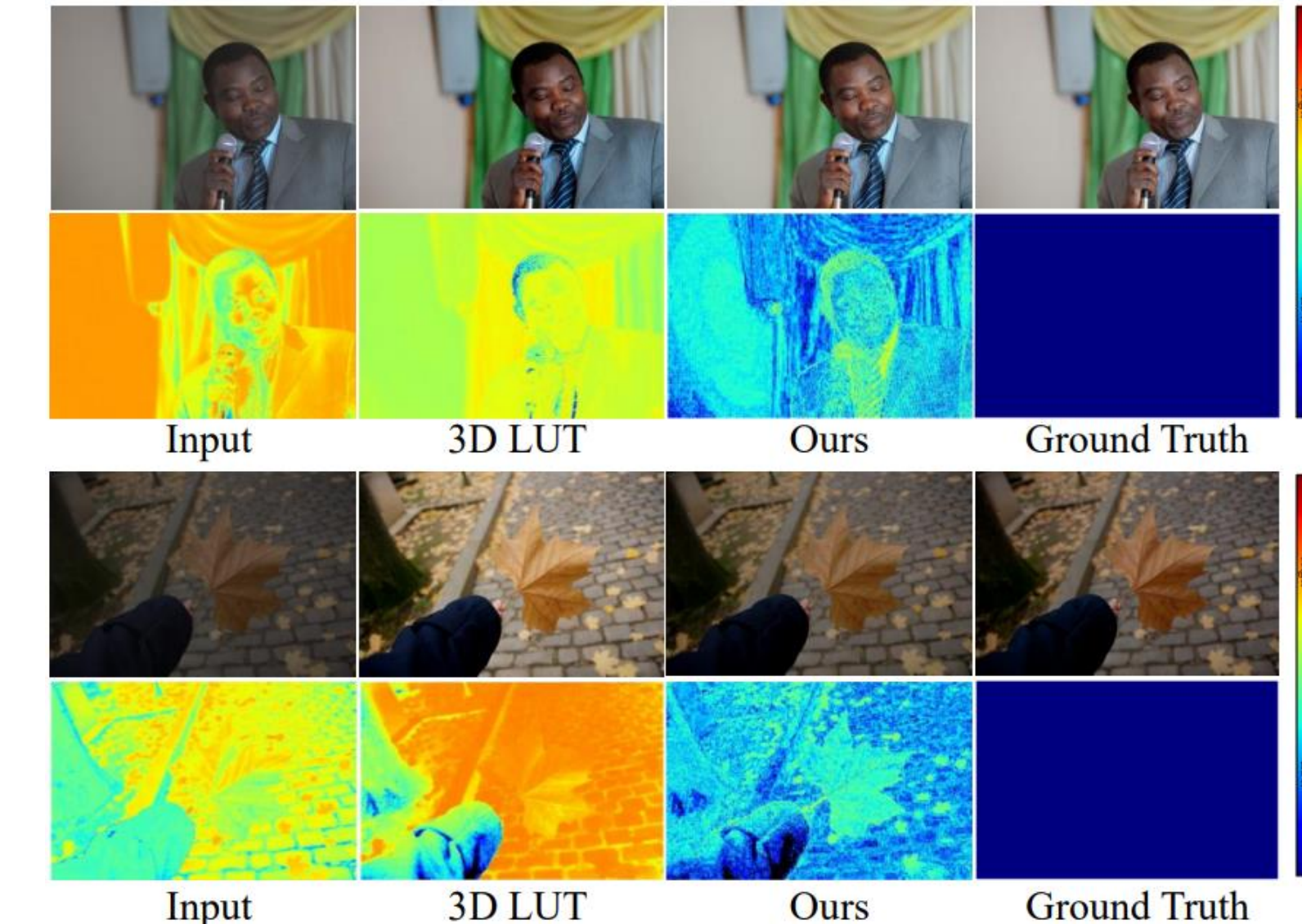
Method	PSNR ↑	ΔE_{ab} ↓	SSIM ↑
Dis-Rec [10]	21.98	10.42	0.856
HDRNet [11]	24.32	8.49	0.912
DeepLPIF [12]	24.73	7.99	0.916
CSRNet [13]	25.17	7.75	0.924
3D LUT [14]	25.21	7.61	0.922
STAR-DCE [15]	24.50	-	0.893
AdaInt [16]	25.28	7.48	0.925
CANet (Ours)	25.49	7.25	0.925

Method	PSNR ↑	ΔE_{ab} ↓	SSIM ↑
Camera Raw	19.86	14.98	0.791
UPE [17]	21.21	13.05	0.816
DPE [18]	22.56	10.45	0.872
HDRNet [11]	23.04	8.97	0.879
3D LUT [14]	23.54	7.93	0.885
CANet (Ours)	23.82	7.85	0.890

Our proposed method outperforms related image enhancement methods on **FiveK** and **HDR** datasets

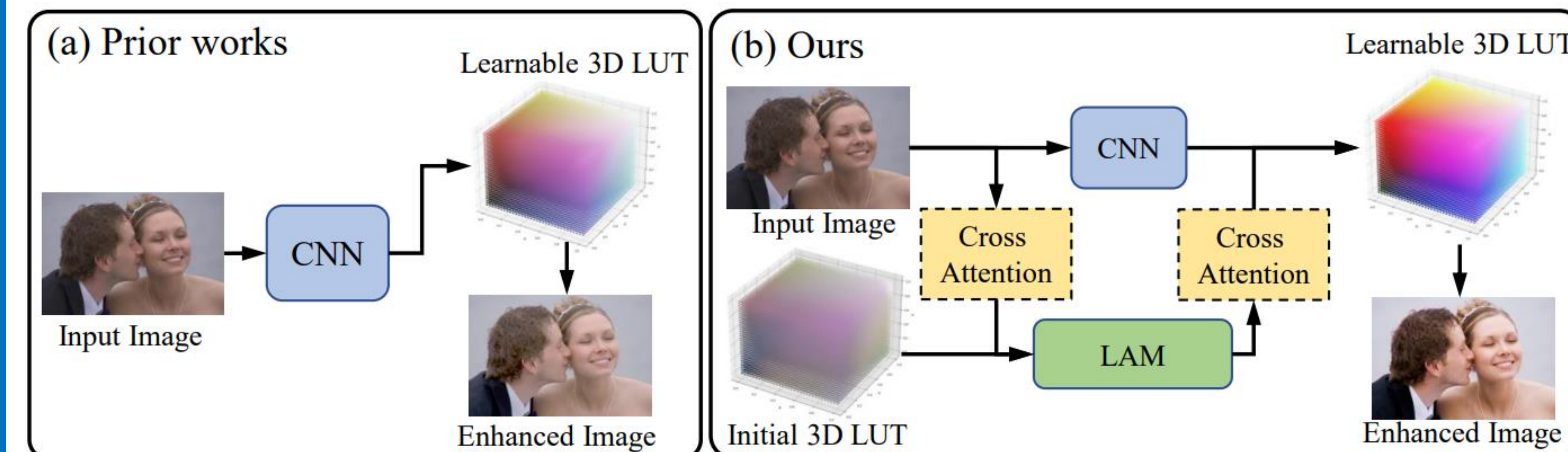
Table 3: Effectiveness comparisons of latest methods on the MIT FiveK.

Method	Params ↓	PSNR ↑	SSIM ↑	Runtime ↓
3D LUT [14]	593.5K	25.21	0.922	1.99ms
AdaInt [16]	619.7K	25.49	0.926	2.56ms
SepLUT [19]	119.8K	25.47	0.921	2.25ms
DualNet [20]	11.25M	25.42	0.917	56.12ms
4D LUT [21]	924.4K	24.96	0.924	5.75ms
FlexiCurve [22]	130K	24.74	0.920	2.82ms
CANet (Ours)	1.52M	25.49	0.925	8.55ms



- Our method leverages a parallel learning process requires more model parameters but remains within the **real-time requirement**
- Visual results demonstrate our CANet produces the color transformation is **closest** to the ground-truth

Motivation



- (a) 3D LUT learns the color transform through a **serial schema from only single image**, it is difficult to model the precise relationship between semantic and color transform

- (b) We take **image and LUT features** into consider, and adopt **cross attention architecture** and **LUT-aware module** to construct the fine-grained LUT

Contribution

- A novel CANet adapts to uses the cross attention architecture to fuse image and LUT feature in a parallelize way
- A LUT-Aware Module fuse multi-channel and spatial attention features for enhancing the color transform
- We conduct comprehensive experiments on FiveK and HDR, the results show that our model outperforms state-of-the-art methods