

# Conditioning and Evidence

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## Introduction

There are many measures of uncertainty out there. Sometimes they appear to conflict. For example, classical or frequency probability supports *significance testing*. Bayesian probability, in the same situation, would call for conditioning on the evidence. *Evidential probability* resolves many of these conflicts in an intuitively plausible way, and in a way that admits of real world semantic justification in terms of frequencies. In what follows we will briefly and informally characterize evidential probability, examine some of the situations in which conflict can arise, and explore the tension between classical statistics and Bayesian conditioning. Finally we shall exhibit the semantic justification underlying the resolution of these conflicts.

## Evidential Probability

On the view laid out in (Kyburg and Teng 2001), probability measures the total support that a body of evidence gives a hypothesis. As John Maynard Keynes insightfully observed (Keynes 1952), probabilities in this sense are not totally ordered: they form a lattice with 0 and 1 as extremes. Evidential probability requires that all probabilities be related to relative frequencies, but since these relative frequencies are only approximately known, the corresponding probabilities are intervals rather than being real valued: the probability of the sentence  $S$ , relative to the body of knowledge  $E$  is  $P(S|E) = [p, q]$ , where  $p \leq q$ . All probabilities are conditional in the sense that they are relative to evidence. But it is not the case that all probabilities can be represented as real valued: the quest for objectivity leads to interval probabilities. Under the natural partial order ( $[p, q] < [r, s]$  if and only if  $q < r$ ) we do obtain a lattice.

In slightly more detail: Let  $\Gamma_\delta$  be a set of sentences that represents our evidence, including both background knowledge and data. We write  $\ulcorner \% \overline{\eta}(\tau, \rho, p, q) \urcorner$  for the statement: the proportion of objects in the reference class  $\rho$  that satisfy the target formula  $\tau$  lies between  $p$  and  $q$ , where  $\tau$  and  $\rho$  are canonical target and reference terms characteristic of the language (ultimately we need a procedure for choosing between languages) and  $p$  and  $q$  are real variables or

fractions in canonical form. If  $\ulcorner S \equiv \tau(\alpha) \urcorner$ ,  $\ulcorner \rho(\alpha) \urcorner$ , and  $\ulcorner \% \overline{\eta}(\tau, \rho, p, q) \urcorner$  are all in  $\Gamma_\delta$ , then  $[p, q]$  is a *candidate* for the evidential probability of  $S$ .

The problem is that there are many such candidates; this is the well known “problem of the reference class.” There are three principles that can be used to resolve this problem, and they are precisely the principles that will allow us to deal with the tension between classical and Bayesian statistics. Let us say that two intervals *conflict* just in case neither is included in the other. Thus  $[0.3, 0.5]$  and  $[0.4, 0.7]$  conflict, as do  $[0.1, 0.5]$  and  $[0.8, 1.0]$ , but  $[0.5, 0.6]$  and  $[0.4, 0.6]$  do not, nor do  $[0.5, 0.5]$  and  $[0.0, 1.0]$  conflict.

The three principles are these:

1. If two statistical statements conflict and the first is based on a marginal distribution while the second is based on the full joint distribution, ignore the first. This gives conditional probabilities pride of place *when they conflict with the corresponding marginal probabilities*.

*Example:* Suppose we have 30 black and 30 white balls in a collection  $C$ . The relative frequency of black balls among balls in  $C$  is 0.5, and this could serve as a probability that ball  $a \in C$  is black. But if the members of  $C$  are divided into three containers, one of which contains 12 black balls and 28 white balls, and two of which each contain 9 black balls, and one white ball, then if  $a$  is selected by a procedure that consists of (1) selecting an urn, and (2) selecting a ball from that urn, the relative frequency of black balls is 0.70, and this is the appropriate probability that  $a$  is black.

|       | urn 1 | urn 2 | urn 3 |    |
|-------|-------|-------|-------|----|
| black | 12    | 9     | 9     | 30 |
| white | 28    | 1     | 1     | 30 |

2. If two statistical statements conflict and the second employs a reference class that is included in the first, ignore the first. This embodies the well known principle of *specificity*.

*Example:* Suppose we have a population of birds in a zoo, and that 95% of them can fly. The other 5% are penguins, and can't fly. Given that a bird is to be selected from the zoo (chosen, for example, by its acquisition number), the frequency with which it will be a flyer is 0.95, and this is also the appropriate probability that it can fly. Given that it is a *penguin* that is to be selected, the frequency of flyers is 0, and that is the probability that it can fly.

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3. If a statistical statement that survives (1) and (2) mentions an interval that includes every interval mentioned by other survivors of (1) and (2), it may be ignored. We may call this the principle of relative vacuity.

*Example:* Suppose we are considering a toss of a coin. The coin has been extensively tested, and we know that it yields heads between 0.4 and 0.6 of the time. It is being tossed by an expert whose record supports the hypothesis that he gets heads between 0.48 and 0.56 of the time. Of course we also know that coin tosses in general yield heads very nearly half the time — say between 0.495 and 0.505 of the time. There is nothing that *conflicts* with [0.495,0.505], so the more specific relative frequencies ([0.40,0.60],[0.48,0.56]) can legitimately be ignored.

We obtain a probability interval from these principles by taking it to be the *cover* of the conflicting intervals that cannot be ignored on one of these three grounds. In many cases — for example, those involving well calibrated gambling apparatus — we can get quite precise probabilities from the application of these principles. Whether this is always the case is something we will briefly consider later.

### Conditioning

There is no conflict between conditioning and relative frequencies. The classic founding fathers — Neyman, Fisher, Pearson — all understood Bayes' theorem to be a theorem, and took it to be applicable under appropriate conditions — namely, when there was knowledge of prior distributions.

As Levi (Levi 1980, Chapter 16) showed, there is a conflict between conditioning and direct inference, the foundation of evidential probability. Kyburg has argued against the universality of conditioning, though direct inference sometimes supports it. There is a problem to be faced, but it is a straight-forward technical one; this is the problem generated by approximate knowledge. Conditional probability is easy enough to characterize on the basis of point valued probabilities; but when we must be concerned with intervals or sets of probability functions things are more complicated. Let us observe, first, that most statements of the form  $\ulcorner \% \bar{\eta}(\tau, \rho, p, q) \urcorner$  are in our bodies of knowledge because they follow from distribution statements that are accepted in our bodies of knowledge. These distribution statements have the form: the random quantity  $Q$  has a distribution in  $R$  belonging to the nonempty set of distributions  $\mathcal{D}$ . If  $\mathbf{b}$  is a Borel set, we may note that

$$\% \bar{x}(Q(\bar{x}) \in \mathbf{b}, \bar{x} \in R, \inf_{D \in \mathcal{D}} \left\{ \int_{\mathbf{b}} dD \right\}, \sup_{D \in \mathcal{D}} \left\{ \int_{\mathbf{b}} dD \right\})$$

has just the form we stipulated for statistical knowledge in the previous section. As before,  $Q$  and  $R$  are constrained to be target and reference terms.

From here to interval-valued conditional probabilities is a simple hop: condition on each of the underlying distributions for which the conditional distribution is defined.

*Example:* Suppose our domain is rolls of a die. What we know of this die is that it is either fair (the distribution corresponds to a frequency function uniform over the six outcomes) or it is biased in favor of one

and against two, corresponding to a frequency function  $\langle 3/12, 1/12, 1/6, 1/6, 1/6, 1/6 \rangle$ . The probability of a five on the next roll is  $[1/6, 1/6]$  since  $1/6$  is both the inf and sup. The probability of a one is  $[1/6, 3/12]$ . The *conditional* probability of a one given an odd outcome on the next roll is obtained from the set of conditional distributions corresponding to the frequency functions  $\{\langle 1/3, 1/3, 1/3 \rangle, \langle 3/7, 2/7, 2/7 \rangle\}$  and is  $[2/6, 3/7]$ .

### Significance Testing

Significance testing is one of the most frequently applied forms of statistical inference. The general pattern is to formulate a hypothesis to be tested, which will be rejected just in case a particular kind of observation is made. The observation is one that would be very unlikely were that hypothesis to be true. Thus rejecting the hypothesis, when it is true, will occur rarely.

*Example:* Suppose we want to test the hypothesis  $H_1$  that supplementary vitamin  $Z$  improves performance in the broad jump. Of course we must make this hypothesis more precise (how much  $Z$ ? How much improvement? In what class of people?) But assuming we have done that, the time honored way of proceeding is to obtain a sample of that class, to divide them (at random) into an experimental group and a control group, and to test the corresponding null hypothesis  $H_0$  that there is *no* difference between the two groups, or rather that any observed difference between the two groups is due to chance. We *reject*  $H_0$  if we observe a result in the comparison of the two groups that is too large, i.e., falls in the rejection region  $R$  of our test.

The *size* of our significance test is the chance of falsely rejecting the null hypothesis; or, given that we have observed an outcome in the rejection region, it is the chance that the null hypothesis is true (anyway). If the size of the test is 0.05, and we have observed a point in the rejection region, the probability of  $H_0$  is  $[0.05, 0.05]$ . Note that if we obtain a result that is not in the rejection region, we can draw no conclusion at all; this is why Fisher (Fisher 1971) regarded significance testing as only a preliminary of scientific inquiry.

Of course this is assuming no conflict. One way in which there could be conflict is that the test is a randomized one, in which an auxiliary experiment determines that the rejection region is  $R_1$ , characterized by a frequency of false rejection 0.014, with probability 0.60, or  $R_2$ , characterized by a frequency false rejection of 0.105. In that way we can achieve a mixture of the two unrandomized experiments with an long run false rejection rate of 0.05. But both unrandomized experiments conflict with 0.05, and, typically, we will know the outcome of the auxiliary experiment, and thus the specific rule we followed. Specificity rules out  $[0.05, 0.05]$  in favor of one or the other of the more specific alternatives.

Another, more interesting, way in which there could be conflict is as a result of prior knowledge. If the prior probability of  $H_0$  is the whole interval  $[0, 1]$ , then the posterior probability will cover the same interval, and conditioning would leave us with the uninformative interval; this is ruled out by (3). But if the prior probability of the null hypothesis is not the vacuous interval  $[0, 1]$ , then we may be led to the

conditional probability. When will this be? When the conditional probability conflicts with  $[.05,0.05]$ , which will be the case, for a conditional probability  $[s, t]$ , when  $t$  is less than 0.05 or  $s$  is more than 0.05.

Let  $B$  be our background knowledge, and  $R$  be the rejection region, and let

$$\begin{aligned} P(H_0|B) &= [p, q] \\ P(R|H_0 \wedge B) &= [r, r] \\ P(R|\overline{H_0} \wedge B) &= [x, y] \\ P(H_0|R \wedge B) &= [s, t] \end{aligned}$$

The lower and upper conditional probabilities are

$$s = \frac{pr}{pr + (1-p)y} \quad \text{and} \quad t = \frac{qr}{qr + (1-q)x}$$

We have a conflict with the significance test just in case either  $t$  is less than 0.05 or  $s$  is greater than 0.05. The following table gives a feel for when there is conflict ( $s > 0.05$ ).

|   |       |       |       |       |       |
|---|-------|-------|-------|-------|-------|
| y | 0.15  | 0.25  | 0.50  | 0.75  | 0.95  |
| p | 0.136 | 0.208 | 0.345 | 0.441 | 0.500 |

Note that whether or not there is conflict depends on the upper probability of the rejection region given  $H_0$ , as well as the lower probability of  $H_0$ . Thus if the probability of  $H_0$  is  $[0.20,0.40]$  and the probability of a point in the rejection region, given that  $H_0$  is false is  $[0.10,0.80]$ , then (since the probability of a point in the rejection region  $R$ , given  $H_0$ , is 0.05 by hypothesis)  $P(H_0|R \wedge B) = \frac{[0.20 * 0.05]}{[(0.20 * .05) + (0.80) * 0.80]}, \frac{[0.40 * .05]}{[(0.40 * 0.05) + (0.60 * 0.10)]} = [0.015, 0.250]$ , which does not conflict with  $[0.05,0.05]$ , while the corresponding calculation when the probability, given the denial of  $H_0$ , of a point in the rejection region is  $[0.10,0.20]$  yields  $[0.058,0.250]$ , which *does* conflict with  $[0.05,0.05]$ . Similar considerations concern the other possibility of conflict.

## Hypothesis Testing

In significance testing we are testing a hypothesis  $H_0$  against its denial. In general, the denial of the null hypothesis is not very informative. In the ideal hypothesis testing case, we test one hypothesis  $H_0$  against a specific alternative,  $H_1$ . We associate such a test, construed as leading to the rejection of  $H_0$ , with two kinds of error: error of the first kind, or type I error, consists in erroneously rejecting  $H_0$ , and error of the second kind consists in mistakenly failing to reject  $H_0$ . The size of a test,  $\alpha$ , is the probability that it will commit an error of type I. The power of a test,  $1 - \beta$ , is the probability that it will avoid committing an error of type II; it is the probability of obtaining a point in the rejection region under  $H_1$ .

The two kinds of error that can be made may both be bounded. In the case of testing a simple hypothesis against a simple alternative, both may be quite precise; and this may provide us with interval bounds on the error of applying a particular test. If the probability of making an error of the first kind is  $\alpha$ , and the probability of making an error of the second kind is  $\beta$ , then the probability of making an error (before conducting the test) is  $[\alpha, \beta]$ , assuming  $\alpha < \beta$ .

But of course when we have conducted the test, we *know* how the test came out, and so we know whether or not  $H_0$

was rejected. If  $H_0$  was rejected we know that the probability of error is (in this simple, idealized case) exactly  $\alpha$ . If  $H_0$  was not rejected, our error, if any, was that we *failed* to reject  $H_0$ , even though it was false, i.e., even though  $H_1$  was true, and so the probability of error is  $\beta$ . In either case we have a precise probability with which to contrast the results of Bayesian inference.

In general, of course, we are not testing a precise hypothesis against a precise alternative. The hypothesis tested,  $H_0$ , may be composite. Nevertheless, we can typically find a value of  $\alpha$  that will provide an upper bound for the probability of mistakenly rejecting  $H_0$ . The probability of error of the first kind may thus be the interval  $[0, \alpha]$ , or the probability of *not* making an error in rejecting the hypothesis tested is  $[1 - \alpha, 1]$ . Again, typically, we find it even more difficult to find a lower bound for the power of a test; what is done is to seek a test of  $H_0$  against  $H_1$  for which  $\alpha$  is bounded above, and for which the probability of error of the second kind is minimized among the set of alternatives  $H_1$  being contemplated. (In general  $H_0$  and  $H_1$  are exclusive, but not exhaustive.

After the test, this leaves us back in the significance testing state of affairs: if  $H_0$  is rejected, we can assign a probability — perhaps the interval  $[1 - \alpha, 1]$  — to its denial, but if  $H_0$  is not rejected we are left only with the “conclusion” that the test in question did not reject  $H_0$ ; the probability of  $H_0$  may remain the whole interval  $[0,1]$ .

The status of Bayesian inference differs sharply in the two cases, according to whether  $H_0$  is rejected or not. When  $H_0$  is “rejected at the  $\alpha$  level,” the existence of a set of prior distributions that, conditioned on the same evidence, yields a posterior probability that *conflicts* with  $[1 - \alpha, 1]$  undermines that rejection, according to the first rule. On the other hand, when the test *fails to reject*  $H_0$ , the relevant truth frequency of  $H_0$  may be the whole interval  $[0,1]$ , and *any* (objective) prior distribution that yields a non-vacuous posterior dominates, according to the third rule.

## Confidence Intervals

Inference leading to confidence intervals can be presented as depending on a lot of background knowledge (for example, in inferring the length of a table from its measurement we make use of our knowledge that the distribution of errors of measurement is Normal), but it is also possible to infer confidence intervals *without* background knowledge. This case is particularly interesting as helping to establish the possibility of *objective* statistical knowledge.

Let  $B$  be a finite set of objects; let some of these objects belong also to  $C$ . Let  $r$  be the proportion of  $B$ 's that are  $C$ . For any value of  $r$ , we can easily enough compute upper  $U(r)$  and lower  $L(r)$  bounds that constitute the shortest interval into which we can, with a relative frequency of at least 0.95, expect the proportion of  $C$ 's in a sample of  $N$   $B$ 's to fall. Of course this depends on  $r$ . But this shortest interval is longest for  $N/2$  or  $(N + 1)/2$ . In short, we can know, a priori, that 95% to 100% of the  $N$ -membered samples of  $B$  are *representative* in the sense that the sample corresponds to a point between the set of upper  $U(r)$  bounds and the

set of lower  $L(r)$  bounds. These functions are not continuous — they are step functions — but that need not bother us since we are dealing in intervals anyway. It did bother Fisher, who made much of the invertibility of the quantity — the so-called fiducial quantity — on which the fiducial inference is based. For this reason he denied the validity of the method of confidence limits. (Fisher 1956, p.65–66) If  $f$  is the observed relative frequency of  $C$ 's in our sample, then the corresponding bounds on  $r$  are given by  $r_l^* = U^{-1}(f)$  and  $r_u^* = L^{-1}(f)$  (we adopt the conservative minimum or maximum if we hit a point of discontinuity).

This proportion can give rise to a probability *provided* the three conditions mentioned earlier are satisfied: There is no interval conflicting with  $[0.95,1.0]$  that is based on a distribution of which the distribution just described is a marginalization. There is no subset of the set of  $N$ -membered samples that carries a conflicting interval for the conclusion. And the cover of the set of intervals meeting the first two requirements is not properly included in  $[0.95,1.0]$ . We will now look at examples of how each of these conditions may be violated.

Suppose that the population of  $B$ 's belongs to a collection of populations, within which we know something about the distribution of the proportion of  $C$ 's, for example, that the proportion is itself distributed according to the density function  $e^{-x}$ . In this case, of course, we would want to condition on this prior density in order to obtain a posterior distribution for the proportion of  $C$ 's. We calculate the conditional probability that  $r \in [U^{-1}(f), L^{-1}(f)]$ . It may *conflict* with the interval  $[0.95,1.0]$ . If it does, then since the interval  $[0.95,1.0]$  is derived from the marginal distribution that takes account only of the sampling distribution, and ignores the prior density of the proportion, it is the conditioned density that determines the posterior distribution. This rules out the probability interval  $[0.95,1.0]$  for  $r \in [U^{-1}(f), L^{-1}(f)]$ , and gives rise to a different 0.95 interval for  $r$ , if we have a precise prior probability, or a different  $[0.95,p]$  interval if we are conditioning on a set of priors.

If we have a prior distribution, and if it leads by conditioning to a probability conflicting with the confidence of the confidence interval analysis, it is conditioning that determines the probability interval. But if our knowledge of prior distributions is vague, so that the upper and lower bounds include the confidence  $[1 - \alpha, 1]$  as a proper subinterval the confidence interval analysis may go through.

Can specificity undermine the confidence interval analysis? Yes. Suppose that the  $B$ 's are kernels of corn in a railroad car, and that  $C$  is the set of cracked kernels. If the sample of  $N$  is taken from the upper surface of the corn in the car, we would not want to regard the sample as probably representative. But this is because it comes from a special set of  $N$ -membered samples in which we know that cracked kernels have lower likelihood of appearing than in  $N$  membered samples in general. In this case, specificity rules out our confidence interval inference. Note that it is not the mere existence of a more specific reference class that undermines the confidence interval inference, but the fact that we have grounds for assigning a measure *conflicting* with  $[0.95,1.0]$  to the conclusion.

Finally, suppose we have a set of prior distributions, each of which give rise to a conditional measure for  $r \in [U^{-1}(f), L^{-1}(f)]$  that falls within the interval  $[0.95,1.0]$ . If the cover of these conditional measures is a proper subinterval of  $[0.95,1.0]$ , then the confidence interval is ruled out as a probability by our third condition: that of relative vacuity. It can be shown (Kyburg and Teng 2001, p. 257–258) that a confidence analysis based on a smaller sample can be ruled out by a larger sample in the same way.

## Generalities

In general, the most common application of confidence interval analysis takes for granted an approximate prior distribution. In an extraordinarily influential article about weighing potatoes, Savage and Edwards (Savage *et al.* 1963) make the case that the particular prior distribution one brings to a measurement problem doesn't ordinarily matter very much. One supposes that the error of measurement is approximately normally distributed with a mean of about zero; whatever your prior opinion about the weight of a potato, within reason, your posterior opinion after weighing it will be quite precise.

On the present analysis prior opinion can be allowed to be vague. If it is vague enough, conditioning on it will simply yield a probability interval that is less precise than the interval resulting from the assumed approximate normal distribution of error, and thus may be ruled out. It is not that conditioning on your prior distribution for the weight of the potato yields a result that is swamped by the result of measurement, but that this prior distribution is so vague as to be eliminated on grounds of relative vacuity.

The general principle followed here is worth reflecting on. On the one hand, we would like to use the most *specific* and *relevant* information we have as a guide to an unseen instance. But this principle leads us toward reference classes about which we have very little information. We should base the probability of death of a candidate Smith for life insurance on a class of individuals "just like" him. But this will be a small class, about which we have relatively little actual data. An extreme point of view would accept this conclusion: frequencies lead us to the interval  $[0,1]$ , so we are thrust back into subjectivity.

We should also base the probability for candidate Smith on the relative frequency in a class about which we have much data. We can apply the maximum amount of data by taking as reference class all U. S. citizens. But this seems wrong, too. To be sure, the estimate of relative frequency becomes ever more precise, as we expand the data, but it also becomes less relevant.

Thus we are led to ways in which we can use the data from larger reference classes; Pollock (Pollock 1990) and Levi (Levi 1980) have worked on this problem from a philosophical point of view. Our own approach, illustrated above, takes *conflict* among statements embodying statistical knowledge to be the key: one has to "do something" only when confronted with conflicting relative frequencies. In two cases, we have a principled way of adjudicating the conflict: first, when the conflict arises between an analysis that makes use

of conditioning on an objective prior probability and an analysis that does not; and second, when the two conflicting statistical generalizations concern reference classes, one of which is (known to be) a subclass of the other. When we have conflict that cannot be dealt with in either of these ways, we accommodate the conflict by taking the probability (not any relative frequency) to be the *cover* of the conflicting intervals.

Note that this deals nicely with the uniqueness of Mr. Smith. What we know about the relative frequency of death within a year in the very small class consisting of Mr. Smith alone,  $\{\text{Smith}\}$ , is that it is 0 or 1. Therefore, on our view, it does not conflict with anything. Therefore we may ignore it, just as our knowledge of coins (or of physics) allows us to ignore the fact that our tests of a particular dime give us reason to believe that it yields heads between 0.42 and 0.55 of the time. It is not merely intervals  $[0.0, 1.0]$  that can be ignored, but relatively uninformative intervals in general.

### Semantic Justification

In this section we shall show that the set of finite models of our language that render our background knowledge true is related to evidential probability in the following way. If the probability of a statement  $S$  is the interval  $[p, q]$ , then the proportion of those models that satisfy  $S$  lies between  $p$  and  $q$ . There is thus a connection between what is probable and what happens for the most part.

First let us specify the language. It is to be a first order logical language, with two sorts of variables, one for real numbers and one for empirical objects. The domain of empirical objects is to be finite, so that proportions are always well defined. The truth conditions for statements of the form  $\ulcorner \% \bar{\eta}(\tau, \rho, p, q) \urcorner$  are just what you would expect. If  $\bar{\eta}$  consists of  $n$  free variables, then the reference class for this statistical statement is the set of  $n$ -tuples that satisfy the formula  $\rho$ . The statement is *true* just in case the proportion of the set of  $n$ -tuples that satisfy  $\rho$  that also satisfy the target formula  $\tau$  lies in the interval  $[p, q]$ .

For example, let “ $L$ ” stand for “is apparently longer than”. Then a plausible principle from the theory of apparent measurement is that if  $x$  is apparently longer than  $y$  and  $y$  is apparently longer than  $z$ , then almost always  $x$  will be apparently longer than  $z$ . We represent this by the formula “ $\% \langle x, y, z \rangle (L(x, z), L(x, y) \wedge L(y, z), 0.99, 1.0)$ ,” which will be true just in case at least 99% of the triples  $x, y, z$  for which “ $L(x, y) \wedge L(y, z)$ ” is true are triples in which “ $L(x, z)$ ” is true. (Note that the variable  $y$  has no occurrence in the target formula “ $L(x, z)$ ”.) This is no doubt true. (Of course we can *stipulate* that *really* being longer than should be transitive, but then we can no longer be sure of our judgments.)

Consider a particular sentence  $S$  of our language whose probability is  $[p, q]$ . In the simplest case there is a single reference class that gives rise to the probability of  $S$ . Let  $K$  be the body of knowledge and data relative to which we obtain this probability. The statement  $\ulcorner \% \bar{\eta}(\tau, \rho, p, q) \urcorner$  is part of  $K$ , as are  $\ulcorner \rho(\alpha) \urcorner$  and  $\ulcorner S \equiv \tau(\alpha) \urcorner$ . What we claim is that the proportion of interpretations of our language, the

proportion of models of our language, that render  $S$  true lies between  $p$  and  $q$ .

The interpretation of the reference formula  $\rho$  will be a certain set of  $n$ -tuples from the domain of our interpretation. (In the example, this is a certain set of triples  $\ulcorner \langle x, y, z \rangle \urcorner$ ; note that we may sample these triples and obtain a confidence interval for the relative frequency with which they satisfy “ $L(x, z)$ ”.) Since we have stipulated that of these tuples between  $p$  and  $q$  will make the formula  $\tau$  true (at least 99% of the triples  $\ulcorner \langle x, y, z \rangle \urcorner$  will make the formula “ $L(x, z)$ ” true), and since the variable assignment can be made *after* the interpretation of the term  $\alpha$  has been made, the proportion of *models* of  $K$  in which  $\ulcorner \tau(\alpha) \urcorner$  is true lies between  $p$  and  $q$ . In short, whenever the probability of  $S$ , relative to background and evidence  $K$  is in the interval  $[p, q]$ , the proportion of models (or worlds) making this evidence true in which  $\ulcorner \tau(\alpha) \urcorner$  or  $S$  is true also lies in the interval  $[p, q]$ .

This is subject to the constraint that the reference class be univocal. Of course, given the richness of our language, this will never be quite true. If the proportion of  $A$ 's that are  $B$ 's lies in  $[p, q]$  so does the proportion of singleton  $\{A\}$ 's that are singleton  $\{B\}$ 's. This need not bother us, since it is the same interval that is mentioned. What does concern us is the existence of statistical conflicts that are not adjudicated by our two rules. Suppose that one bit of statistical knowledge gives rise to the interval  $[0.4, 0.6]$  and another bit of statistical knowledge gives rise to  $[0.5, 0.7]$ , and neither of the rules applies. Then the probability is the cover  $[0.4, 0.7]$ . It turns out (Kyburg and Teng 2001, pp 240–241) that a sensible notion of partial validity yields the result that the relevant proportion in the actual world lies between the upper and lower values of the interval cover. Probabilities reflect facts about the world, and these facts impose objective constraints on our statistical inferences.

### Objectivity

We have been making much of the “objectivity” of evidential probability, and the role that it can therefore play in statistical inference. What this objectivity comes to is that if two scientists share the same data and background knowledge, they assign the same probability to any statement  $S$ . This objectivity doesn't amount to much if they don't share data and background knowledge. As a subjectivist might say: there is no problem of adjudicating different opinions if the opinions are the same. On the subjective view defended by Savage (Savage 1954) and Jeffrey (Jeffrey 1983) it becomes a fortunate accident in the sociology of scientific inquiry that people agree. Our claim is that there are objective grounds underlying the usual cases of agreement, and that these grounds can also be called upon in the case of disagreement.

Let us consider two scientists,  $S_1$ , whose body of knowledge is  $K_1$ , and  $S_2$ , whose body of knowledge is  $K_2$ .  $S_1$  has data  $D_1$  and  $S_2$  has data  $D_2$ . In order for  $S_1$  and  $S_2$  to arrive at the same evidential probabilities,  $K_1 \cup D_1$  must be *evidentially* equivalent to  $K_2 \cup D_2$ . What this requires is that the same triples of sentences,  $\ulcorner \rho(\alpha) \urcorner$ ,  $\ulcorner \tau(\alpha) \urcorner$ , and

$\lceil \% \bar{\eta}(\tau, \rho, p, q) \rceil$  must be consequences of  $K_1 \cup D_1$  as are consequences of  $K_2 \cup D_2$ .

Consider  $D_1$  and  $D_2$ . First, there is a very strong commitment in science to protecting the integrity of data. As the scandals of the past few years attest, the shock and bitterness that accompany even the suspicion of scientific dishonesty show how deeply scientists are committed to truthfulness with regard to their data. This commitment means that in most cases we may take published data at face value. If there are data in  $D_1$  that are lacking in  $D_2$ , and  $S_2$  is informed of them, he may with considerable confidence (but not “perfect” confidence) import that data into  $D_2$ . Second, scientific observations and experiments are taken to be replicable, so that, at least in principle,  $S_2$  can make the observations, perform the experiments, that gave rise to to  $S_1$ 's data. The possibility of replication is certainly limited, however. Many experiments are expensive and time-consuming to run, or hedged about with regulations. Many observations require specialized equipment. Thus the possibility of replication remains hypothetical for most scientists. Nevertheless, at the level of data most people accept the ideal of objectivity.

The other way in which two bodies of knowledge can differ is in the inferential contents — in the sets of sentences  $K_1$  and  $K_2$ . These sets of sentences are *inferred* from other evidence. Deductive inference is clearly objective. We claim that inductive inference is also objective; we take it that scientific acceptance is a matter of evidential probability. When the evidence renders the lower probability of a hypothesis high enough, that hypothesis is worthy of belief. This would be objective, since evidential probability is objective.

How high a probability is necessary for acceptance? Obviously that can't be answered in general. But in a given context it may make sense to reject hypotheses at the  $\epsilon$  level: A probability of  $\epsilon$  of being in error is, in that context, not worth bothering about.  $1 - \epsilon$  is thus the probability that corresponds to practical certainty in that context. As we have already suggested, evidence cannot plausibly be required to be absolutely certain. So how certain must the evidence be, relative to which you regard something as so acceptably probable — i.e. so probable as to be “practically certain”? It seems intuitively clear that we should make greater demands on *evidence* than on *practical certainty*. One suggestion (Kyburg 1990) is to take the corresponding level to be  $1 - \epsilon/2$ . This suggestion has the virtue of allowing any two evidential certainties to be conjoined as a practical certainty, and has the additional virtue of being systematic. An alternative would be to set the acceptance level for evidence to be  $1 - \epsilon/n$ ; then  $n$  pieces of evidence could be conjoined in a single practical certainty.

## Conclusion

We have claimed that evidential probability provides an objective framework for adjudicating conflicts within statistical inference — especially conflicts between classical and Bayesian inference. There are still several issues to be faced.

*The language.* We have assumed that for our statistical purposes we employ a first order language with rich resources. We have already noted that the reference terms and

the target terms must be constrained. We may well also want “meaning postulates” such as “being longer-than is transitive” to be part of our language. For these reasons we need a principled and objective way of choosing between languages on the basis of a body of knowledge, such as that hinted at in (Kyburg 1990).

*Background knowledge.* We have already mentioned some of the difficulties in sharing background knowledge. We require commitment to honesty with regard to data, among other things. But these difficulties are attenuated in real science, where a group of people concerned with a single subject matter tend to share large parts of their bodies of scientific knowledge. Where this requirement becomes more problematic is in areas that involve knowledge from several disciplines. And we not only must be able to focus on a shared body of knowledge, we must, if we are to automate inference, agree on a formalization.

*Broad intervals.* Another thing we need to worry about is whether, in realistic cases, we are forced to such broad intervals that the probabilities are not useful for inference or for computing expectations as a basis for decision. In some areas, such as insurance, in which the use of something close to evidential probability is common, this doesn't happen. But in general we will only be able to tell this when we have sizable bodies of knowledge expressed formally.

*Evidential Probability.* Despite these questions, epistemological probability has an important role to play where imprecise prior knowledge competes with classical statistics. It can help when our statistical knowledge is imprecise and varied. It is important in general to seek objectivity in probabilistic knowledge: the probable should happen for the most part.

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