

# Satisfiability in the Triguarded Fragment of First-Order Logic

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**Abstract.** Most *Description Logics (DLs)* can be translated into well-known decidable fragments of first-order logic  $\mathbb{FO}$ , including the *guarded fragment*  $\mathbb{GF}$  and the *two-variable fragment*  $\mathbb{FO}^2$ . Given their prominence in DL research, we take closer look at  $\mathbb{GF}$  and  $\mathbb{FO}^2$ , and present a new fragment that subsumes both. This fragment, called the *triguarded fragment* (denoted  $\mathbb{TGF}$ ), is obtained by relaxing the standard definition of  $\mathbb{GF}$ : quantification is required to be guarded only for subformulae with *three* or more free variables. We show that satisfiability of equality-free  $\mathbb{TGF}$  is  $\text{N2EXPTIME}$ -complete, but becomes  $\text{NEXPTIME}$ -complete if we bound the arity of predicates by a constant (a natural assumption in the context of DLs). Finally, we observe that many natural extensions of  $\mathbb{TGF}$ , including the addition of equality, lead to undecidability.

## 1 Introduction

*Description Logics (DLs)* are a family of logic-based knowledge representation languages, usually suitably limited to ensure the decidability of basic reasoning problems [2, 3]. Many properties of DLs can be explained by seeing them as *fragments* of (function-free) first-order logic (denoted  $\mathbb{FO}$  in this paper). In fact, most DLs fall into well-known decidable fragments of  $\mathbb{FO}$ , implying not only decidability, but also complexity results, model-theoretic properties, and limits of expressiveness. For instance, many standard DLs are subsumed by  $\mathbb{FO}^2$ , the fragment of  $\mathbb{FO}$  with at most two variables [8]. For  $\mathbb{FO}^2$  without equality, the satisfiability problem has been known to be decidable for over five decades due to Scott [20]. The decidability of satisfiability in  $\mathbb{FO}^2$  in the presence of equality is known since 1975 due to Mortimer [16], with the worst-case optimal  $\text{NEXPTIME}$  upper bound known since over two decades [13].

An alternative explanation for the decidability of DLs is the fact that they can often be translated into the *guarded fragment*  $\mathbb{GF}$  of  $\mathbb{FO}$  [1] (see also [11] for a discussion). Satisfiability checking in  $\mathbb{GF}$  is  $\text{2EXPTIME}$ -complete in general, but it is  $\text{EXPTIME}$ -complete under the assumption that the arities of predicates are bounded by a constant [12]. The latter is particularly important because many standard DLs are  $\text{EXPTIME}$ -complete for consistency checking, while their  $\mathbb{FO}$  translations use predicate symbols of arity at most two. We note that the connection between DLs and  $\mathbb{GF}$  is somewhat more robust than that between DLs and  $\mathbb{FO}^2$ , which can be observed if we look beyond consistency checking

in DLs. Most notably, conjunctive query answering, which is decidable for most DLs, remains decidable for  $\mathbb{GF}$ , but becomes undecidable for  $\mathbb{FO}^2$  [5, 18].

Given the importance of  $\mathbb{GF}$  and  $\mathbb{FO}^2$  to research in DLs, in this paper we take a deeper look at them, and study a new fragment of  $\mathbb{FO}$  that subsumes both  $\mathbb{GF}$  and  $\mathbb{FO}^2$ . The fragment is called the *triguarded fragment* (denoted  $\mathbb{TGF}$ ), and it is obtained by relaxing the standard definition of  $\mathbb{GF}$ . In  $\mathbb{GF}$ , existential and universal quantification can only be used in (sub)formulae of the form  $\exists \mathbf{x}.(R(\mathbf{t}) \wedge \psi)$  or  $\forall \mathbf{x}.(R(\mathbf{t}) \rightarrow \psi)$ , where  $R(\mathbf{t})$  is an atomic formula such that  $\mathbf{t}$  contains *all* free variables of  $\psi$  (the atom  $R(\mathbf{t})$  “guards” the formula  $\psi$ ). In  $\mathbb{TGF}$ , guardedness of quantification is required only in case  $\psi$  has *three* or more free variables (hence the name “triguarded”). This entails that quantification can be used in an unrestricted way for formulae with at most two free variables, and hence  $\mathbb{FO}^2$  gets included in  $\mathbb{TGF}$  seamlessly.

After providing a simple definition of  $\mathbb{TGF}$ , we study its satisfiability problem. To this end, we first consider a slightly different problem: we study satisfiability of formulae of  $\mathbb{GF}$  in the presence of a built-in binary predicate  $U$  that contains all pairs of domain elements. In DL parlance, we consider the extension of  $\mathbb{GF}$  with the *universal role*, and thus this fragment is denoted  $\mathbb{GFU}$ . Since the predicate  $U$  can be used to provide “spurious” guards to formulae with up to two free variables,  $\mathbb{GFU}$  adds to  $\mathbb{GF}$  precisely the expressivity needed to capture  $\mathbb{TGF}$ , and thus in the paper we mainly focus on  $\mathbb{GFU}$  instead of  $\mathbb{TGF}$ .

We show that in the equality-free case, satisfiability of formulae in  $\mathbb{GFU}$  (and in  $\mathbb{TGF}$ ) is  $\text{N2EXPTIME}$ -complete. We establish the upper bound by characterizing the satisfiability of a formula in  $\mathbb{GFU}$  via *mosaics*, where a mosaic is a special (finite) collection of *types* that can be used to build a model for the input formula. The matching lower bound can be obtained by a reduction from the tiling problem of a doubly exponential grid. We then consider the assumption that predicate arities are bounded by a constant. In this case, the mosaic construction gives rise to a  $\text{NEXPTIME}$  upper bound for satisfiability of formulae without equality. We note that  $\mathbb{FO}^2$  is already  $\text{NEXPTIME}$ -hard (even without equality), which means that in the bounded-arity setting  $\mathbb{TGF}$  and  $\mathbb{GFU}$  do not have higher complexity than  $\mathbb{FO}^2$ . Finally, we show that satisfiability of  $\mathbb{TGF}$  and  $\mathbb{GFU}$  formulae with equality is undecidable (interestingly, the complexity of satisfiability in  $\mathbb{GF}$  and  $\mathbb{FO}^2$  is insensitive to the presence of equality).

The fragment  $\mathbb{GFU}$  is similar to the fragment  $\mathbb{GF}^{\times 2}$  of [10], which extends  $\mathbb{GF}$  with *cross products* (allowing to capture statements like “all elephants are bigger than all mice” as in [19]). The difference is that  $\mathbb{GF}^{\times 2}$ , inspired by the database view, imposes a separation into a set of ground facts (the data) and a constant-free theory (the schema) [9]. Under this restriction on expressiveness (which is only implicit in [10]),  $\mathbb{GF}^{\times 2}$  is in fact subsumed by the fragment  $\mathcal{GF}|\mathcal{FO}^2$  from [14]. Using a resolution-based procedure, satisfiability in  $\mathcal{GF}|\mathcal{FO}^2$  was shown to be in  $2\text{EXPTIME}$ , and in  $\text{NEXPTIME}$  in case of bounded predicate arities [14]. Instead of resolution, the proof of the  $2\text{EXPTIME}$  upper bound for  $\mathbb{GF}^{\times 2}$  in [10] uses a reduction to satisfiability in plain  $\mathbb{GF}$ . As we shall see, the unrestricted availability of constants is key in the  $\text{N2EXPTIME}$ -hardness of full  $\mathbb{GFU}$  and  $\mathbb{TGF}$ , and thus is the main distinguishing feature of the fragments introduced

in this paper. We note that the undecidability of GFU and TGF in the presence of equality can be inferred from [14] (Section 4.2.3), where a reduction from satisfiability in the *Goldfarb class* is presented, and it can be applied to our fragments. Instead, in this paper we provide a more direct undecidability proof by a reduction from the tiling problem for an infinite grid.

## 2 Preliminaries

We assume the reader is familiar with the syntax and semantics of FO, and thus here we only present some notation. We use  $\mathbf{N}_P$ ,  $\mathbf{N}_C$  and  $\mathbf{N}_V$  to denote the countably infinite, mutually disjoint sets of *predicate symbols*, *constants* and *variables*, respectively. We will mostly use (possibly subscripted)  $P$ ,  $R$ ,  $B$  and  $H$  as predicate symbols. Given a formula  $\varphi$ , we use  $\mathbf{N}_C(\varphi)$  and  $\mathbf{N}_P(\varphi)$  to denote the set of constants and the set of predicate symbols that appear in  $\varphi$ , respectively. Elements of  $\mathbf{N}_C \cup \mathbf{N}_V$  are called *terms*. An *atom* (or, *atomic formula*) is an expression of the form  $R(\mathbf{t})$ , where  $\mathbf{t}$  is an  $n$ -tuple of terms, where  $n$  is the *arity* of the predicate symbol  $R \in \mathbf{N}_P$ . For convenience, given a tuple  $\mathbf{t} = \langle t_1, \dots, t_n \rangle$  of terms, we sometimes view  $\mathbf{t}$  as the set  $\{t_1, \dots, t_n\}$ . Given a tuple  $\mathbf{x}$  of variables, an  $\mathbf{x}$ -*assignment* is any function  $f : \mathbf{N}_C \cup \mathbf{N}_V \rightarrow \mathbf{N}_C \cup \mathbf{N}_V$  such that (i)  $f(y) \in \mathbf{N}_C$  for all  $y \in \mathbf{x}$ , and (ii)  $f(t) = t$  for all  $t \notin \mathbf{x}$ . Given a tuple  $\mathbf{t} = \langle t_1, \dots, t_n \rangle$  of terms and an  $\mathbf{x}$ -assignment  $f$ , we let  $f(\mathbf{t}) = \langle f(t_1), \dots, f(t_n) \rangle$ . The semantics of formulae is given using *interpretations*. An interpretation is a pair  $\mathcal{I} = (\Delta^{\mathcal{I}}, \cdot^{\mathcal{I}})$ , where  $\Delta^{\mathcal{I}}$  is a non-empty set (called *domain*), and  $\cdot^{\mathcal{I}}$  is a function that maps (i) every constant  $c \in \mathbf{N}_C$  to an element  $c^{\mathcal{I}} \in \Delta^{\mathcal{I}}$ , and (ii) every predicate symbol  $R \in \mathbf{N}_P$  to an  $n$ -ary relation over  $\Delta^{\mathcal{I}}$ , where  $n$  is the arity of  $R$ . We assume that 0-ary predicate symbols  $\top$  and  $\perp$  belong to  $\mathbf{N}_P$ , and they have the usual (built-in) meaning. The equality predicate  $\approx$  also belongs to  $\mathbf{N}_P$ , and has the fixed meaning  $\approx^{\mathcal{I}} = \{(e, e) \mid e \in \Delta^{\mathcal{I}}\}$  for all interpretations  $\mathcal{I}$ . We write  $\mathcal{I} \models \varphi$ , if an interpretation  $\mathcal{I}$  is a model of a closed formula (or, a sentence)  $\varphi$ . We use  $\text{free}(\varphi)$  to denote the set of free variables in a formula  $\varphi$ .

## 3 The Triguarded Fragment

We are now ready to introduce the *triguarded fragment* of FO. Essentially, it is a relaxed variant of GF where guards are only required when quantifying over formulae with three or more free variables.

**Definition 1.** *The triguarded fragment TGF of first-order logic with equality is defined as the smallest set of formulae closed under the following rules:*

- (1) *Every atomic formula belongs to TGF.*
- (2) *TGF is closed under the propositional connectives  $\neg$ ,  $\wedge$ ,  $\vee$  and  $\rightarrow$ .*
- (3) *If  $x$  is a variable, and  $\varphi$  is a formula in TGF with  $|\text{free}(\varphi)| \leq 2$ , then  $\exists x.\varphi$  and  $\forall x.\varphi$  also belong to TGF.*
- (4) *If  $\mathbf{x}$  is a non-empty tuple of variables,  $\varphi$  is a formula in TGF,  $\alpha$  is an atom, and  $\text{free}(\varphi) \subseteq \text{free}(\alpha)$ , then  $\exists \mathbf{x}.\alpha \wedge \varphi$  and  $\forall \mathbf{x}.\alpha \rightarrow \varphi$  also belong to TGF.*

Observe that if we consider only the items (1), (2) and (3) in Definition 1 as legal rules to build formulae, we can build all formulae of  $\text{FO}$  that use at most 2 variables, and thus  $\text{FO}^2 \subseteq \text{TGF}$ . If we consider the items (1), (2) and (4) in Definition 1, we can build all guarded formulae, and thus  $\text{GF} \subseteq \text{TGF}$ . The syntax of  $\text{TGF}$  also allows us to build formulae that are neither in  $\text{GF}$  nor in  $\text{FO}^2$ , witnessed by formulae like

$$\forall x \forall y. ((R_1(x, a) \wedge R_2(y, b)) \rightarrow \exists z. R_3(x, y, z)).$$

Our main goal in this paper is to understand the computational complexity of satisfiability in  $\text{TGF}$ . To this end, we concentrate on a slightly different logic, which is effectively equivalent to  $\text{TGF}$ , but which makes presentation significantly easier. In particular, there is a simple extension of  $\text{GF}$  that allows us to capture  $\text{TGF}$ . Intuitively,  $\text{TGF} \not\subseteq \text{GF}$  because  $\text{TGF}$  allows “unguarded” quantification in front of formulae  $\varphi$ , but only in case  $\varphi$  has no more than 2 free variables. If we have the availability of a binary predicate whose extension always contains all pairs of domain elements, we can use it to guard  $\varphi$ . In particular, we consider next the binary *universal role* predicate  $\text{U} \in \text{N}_P$ , whose extension is fixed to be  $\text{U}^{\mathcal{I}} = \Delta^{\mathcal{I}} \times \Delta^{\mathcal{I}}$  for all interpretations  $\mathcal{I}$ . Note that in  $\text{FO}$ ,  $\text{FO}^2$  and  $\text{TGF}$ , the built-in predicate  $\text{U}$  does not add expressiveness, because it can be axiomatized using an ordinary binary predicate  $U$  and the sentence  $\phi = \forall x \forall y. U(x, y)$ ; thus we can safely allow  $\text{U}$  to be used as a predicate symbol in formulae of  $\text{FO}$ ,  $\text{FO}^2$  and  $\text{TGF}$ . Since  $\phi$  is not in  $\text{GF}$ , the addition of the built-in  $\text{U}$  to  $\text{GF}$  makes a big difference (as we shall see from complexity results). We now formally define  $\text{GFU}$ , which extends  $\text{GF}$  with  $\text{U}$ , and in fact adds to  $\text{GF}$  the necessary expressivity to capture  $\text{TGF}$ .

**Definition 2.** *Let  $\text{GFU}$  be the set of formulae of  $\text{TGF}$  that can be built using the items (1), (2) and (4) of Definition 1 only, possibly using the predicate  $\text{U}$  in atomic formulae.*

By using the  $\text{U}$  predicate as a guard for formulae with at most 2 free variables, we can convert any  $\text{TGF}$  formula into an equivalent formula in  $\text{GFU}$ . For instance, the above example formula can be transformed into the equivalent  $\text{GFU}$  formula

$$\forall x \forall y. (\text{U}(x, y) \rightarrow ((R_1(x, a) \wedge R_2(y, b)) \rightarrow \exists z. R_3(x, y, z))).$$

**Proposition 1.** *For any  $\varphi \in \text{TGF}$ , we can build in polynomial time an equivalent formula  $\varphi' \in \text{GFU}$ . Moreover,  $\text{N}_P(\varphi') \subseteq \text{N}_P(\varphi) \cup \{\text{U}\}$ .*

Due to Proposition 1, in order to check satisfiability in  $\text{TGF}$ , it suffices to focus on the satisfiability problem for  $\text{GFU}$ , and thus in the rest of the paper we focus on  $\text{GFU}$ .

## 4 Characterizing Satisfiability via Mosaics

In this section, we study  $\text{GFU}$  in the equality-free setting, and provide a finite representation of models of satisfiable  $\text{GFU}$  formulae, which will be the basis of

the satisfiability checking algorithm. In particular, we show that an equality-free GFU formula  $\varphi$  has a model iff there exists a *mosaic* for  $\varphi$ , which is a relatively small set of building blocks that can be used to build a model for  $\varphi$ . In this way, checking satisfiability of  $\varphi$  reduces to checking the existence of a mosaic for  $\varphi$ .

To simplify the structure of GFU formulae we use a suitable (*Scott-like*) *normal form*, which is not much different from the ones used, e.g., in [13, 12].

**Definition 3 (Normal Form).** *A sentence  $\varphi \in \text{GFU}$  is in normal form if it has the form  $\bigwedge_{\psi \in \mathbf{A}} \psi \wedge \bigwedge_{\psi \in \mathbf{E}} \psi$ , where  $\mathbf{A}$  contain sentences of the form*

$$\forall \mathbf{x}. (R(\mathbf{t}) \rightarrow (\neg H_1(\mathbf{v}_1) \vee \dots \vee \neg H_n(\mathbf{v}_n) \vee H_{n+1}(\mathbf{v}_{n+1}) \vee \dots \vee H_m(\mathbf{v}_m))), \quad (1)$$

and  $\mathbf{E}$  contain sentences of the form

$$\forall \mathbf{x}. (R(\mathbf{u}) \rightarrow \exists \mathbf{y}. H(\mathbf{v})). \quad (2)$$

We use  $\mathbf{A}(\varphi)$  and  $\mathbf{E}(\varphi)$  to denote the sets  $\mathbf{A}$  and  $\mathbf{E}$  of a formula  $\varphi$  as above. For a sentence  $\psi = \forall \mathbf{x}. (R(\mathbf{u}) \rightarrow \exists \mathbf{y}. H(\mathbf{v}))$ , we let  $\text{width}(\psi)$  denote the number of variables that appear in  $\mathbf{v}$ . For a formula  $\varphi$  as above,  $\text{width}(\varphi)$  is the maximal  $\text{width}(\psi)$  over all  $\psi \in \mathbf{E}(\varphi)$ .

As usual, in case  $m = 0$ , the empty disjunction in (1) stands for  $\perp$ . Note that since (1) and (2) are in GFU, each variable that appears in  $\mathbf{v}_1, \dots, \mathbf{v}_m$  also appears in  $\mathbf{t}$ , and each variable that appears in  $\mathbf{v}$  also appears in  $\mathbf{u}$ . Observe that the sentence in (1) can be equivalently written as

$$\forall \mathbf{x}. (R(\mathbf{t}) \wedge H(\mathbf{v}_1) \wedge \dots \wedge H_n(\mathbf{v}_n) \rightarrow H_{n+1}(\mathbf{v}_{n+1}) \vee \dots \vee H_m(\mathbf{v}_m)). \quad (3)$$

For presentation reasons, in what follows we will mostly use the form (3) instead of (1) when speaking about sentences in  $\mathbf{A}$ . Note that (3) closely resembles a (guarded) disjunctive Datalog rule with  $R(\mathbf{t})$  a guard atom.

The following statement shows that we can focus on formulae in normal form.

**Proposition 2.** *For any formula  $\varphi \in \text{GFU}$ , we can construct in polynomial time a formula  $\varphi' \in \text{GFU}$  in normal form such that (a)  $\varphi$  is satisfiable iff  $\varphi'$  is satisfiable, and (b) the translation does not increase the arity of predicate symbols, i.e., there is no predicate symbol in  $\varphi'$  whose arity is strictly greater than the arity of every predicate symbol in  $\varphi$ .*

To define mosaics, we need the notion of a *type* for a formula  $\varphi$ . Types will form mosaics, and they can be seen as patterns (interpretations of restricted size) for building models of  $\varphi$ .

**Definition 4 (Types).** *A type  $\tau$  for a formula  $\varphi$  is any set of ground atoms with predicate symbols from  $\mathbf{N}_P(\varphi)$ . We let  $\text{dom}(\tau)$  denote the set of constants that appear in a type  $\tau$ , and let  $\mathcal{I}(\tau)$  denote the interpretation such that (i)  $\Delta^{\mathcal{I}(\tau)} = \text{dom}(\tau)$ , and (ii)  $P^{\mathcal{I}(\tau)} = \{\mathbf{t} \mid P(\mathbf{t}) \in \tau\}$  for all predicate symbols  $P$ . For a sentence  $\varphi$ , we write  $\tau \models \varphi$  if  $\mathcal{I}(\tau) \models \varphi$ . Given a set of constants  $F$ , we let  $\tau|_F = \{P(\mathbf{t}) \in \tau \mid \mathbf{t} \subseteq F\}$ , i.e.,  $\tau|_F$  is the restriction of  $\tau$  to atoms whose all arguments are included in  $F$ .*

Of particular interest in our treatment is how a distinguished element of some type “looks like” in terms of the predicates it satisfies and its relationship to constants. This information is captured using *unary types*, in which we abstract from the concrete target constant by replacing it with a special variable.

**Definition 5 (unary types).** *Assume a formula  $\varphi \in \mathbb{GFU}$  and let  $x^\varphi$  be a special variable associated with  $\varphi$ . We let  $\text{base}(\varphi)$  denote the set of all atoms  $P(\mathbf{t})$  such that  $\mathbf{t} \subseteq \mathbf{N}_C(\varphi) \cup \{x^\varphi\}$  and  $P \in \mathbf{N}_P(\varphi)$ . Any subset  $\sigma \subseteq \text{base}(\varphi)$  is called a unary type for  $\varphi$ . Assume a constant  $c$ , and let  $f$  be the function such that (i)  $f(x^\varphi) = c$ , and (ii)  $f(d) = d$  for all  $d \in \mathbf{N}_C$ . For a type  $\tau$ , we define the unary type  $\tau|_c^\varphi = \{R(\mathbf{t}) \in \text{base}(\varphi) \mid R(f(\mathbf{t})) \in \tau\}$ .*

We are now ready to define mosaics, which will act as witnesses to satisfiability of  $\mathbb{GFU}$  formulae (without equality). Roughly, a mosaic for a formula  $\varphi$  is a pair  $(\mathcal{M}, \mathcal{X})$ , where  $\mathcal{X}$  is a collection of “placeholder” constants, and  $\mathcal{M}$  is a set of types for  $\varphi$ . In order to be a proper witness to satisfiability, a mosaic must satisfy a collection of conditions. In particular, they ensure that in case  $\varphi$  is satisfiable, we will be able to construct a model by arranging together (possibly multiple) *instances* of types from  $\mathcal{M}$ . Intuitively, by an instance of a type  $\tau \in \mathcal{M}$  we mean a concrete structure that is obtained by replacing the placeholder constants from  $\mathcal{X}$  with concrete domain elements.

**Definition 6 (Mosaic).** *A mosaic for a sentence  $\varphi \in \mathbb{GFU}$  in normal form is a pair  $(\mathcal{M}, \mathcal{X})$ , where  $\mathcal{M}$  is a set of types for  $\varphi$  and  $\mathcal{X} \subseteq \mathbf{N}_C \setminus \mathbf{N}_C(\varphi)$ , satisfying the following:*

- (A)  $|\mathcal{X}| \leq \text{width}(\varphi)$ ;
- (B) For all  $\tau \in \mathcal{M}$ ,  $\text{dom}(\tau) \subseteq \mathbf{N}_C(\varphi) \cup \mathcal{X}$ ;
- (C) For all  $\tau, \tau' \in \mathcal{M}$ ,  $\tau|_{\mathbf{N}_C(\varphi)} = \tau'|_{\mathbf{N}_C(\varphi)}$ ;
- (D)  $\mathbf{U}(t, v) \in \tau$  for all  $\tau \in \mathcal{M}$  and each pair  $t, v \in \text{dom}(\tau)$ ;
- (E)  $\tau \models \psi$  for all  $\tau \in \mathcal{M}$  and all  $\psi \in \mathbf{A}(\varphi)$ ;
- (F) If  $\tau \in \mathcal{M}$ ,  $\forall \mathbf{x}.(R(\mathbf{t}) \rightarrow \exists \mathbf{y}.H(\mathbf{v})) \in \mathbf{E}(\varphi)$ , and  $R(g(\mathbf{t})) \in \tau$  for some  $\mathbf{x}$ -assignment  $g$ , then there is some  $\tau' \in \mathcal{M}$  such that:
  - (a)  $H(h(g(\mathbf{v}))) \in \tau'$  for some  $\mathbf{y}$ -assignment  $h$ ;
  - (b)  $\tau|_F = \tau'|_F$ , where  $F = \mathbf{N}_C(\varphi) \cup \{g(x) \mid x \in \mathbf{x} \cap \mathbf{v}\}$ .
- (G) If  $t_1 \in \text{dom}(\tau_1) \cap \mathcal{X}$  and  $t_2 \in \text{dom}(\tau_2) \cap \mathcal{X}$  for some  $\tau_1, \tau_2 \in \mathcal{M}$ , then there exists a type  $\tau \in \mathcal{M}$  and a pair  $v_1, v_2$  with  $\text{dom}(\tau) \cap \mathcal{X} = \{v_1, v_2\}$  such that (i)  $v_1 \neq v_2$ , (ii)  $\tau_1|_{t_1}^\varphi = \tau|_{v_1}^\varphi$ , (iii)  $\tau_2|_{t_2}^\varphi = \tau|_{v_2}^\varphi$ .

Intuitively, the conditions (A-G) ensure the following. (A) requires that only a small number of placeholder constants is used. Due to (B), types in mosaics only refer to original constants of the formula and the small number of placeholder constants. The conditions (A) and (B) are important to ensure the relatively small size of mosaics. The condition (C) forces the types to agree on the participation of constants in predicates. (D) requires  $\mathbf{U}$  to be correctly interpreted locally (i.e., within the individual types), and (E) requires each type to

(locally) satisfy all sentences from  $\mathbf{A}(\varphi)$ . The condition (F) ensures that for each type locally satisfying the body of some sentence from  $\mathbf{E}(\varphi)$ , we find a matching type where also the head of that sentence is satisfied. Using (G) we make sure that any two representatives of unnamed domain elements (in terms of unary types) found across the types also occur together in one type.

The following soundness and completeness theorems show that mosaics properly characterize satisfiability of equality-free  $\mathbb{G}\mathbb{F}\mathbb{U}$  formulae (and, due to Proposition 1, of equality-free  $\mathbb{T}\mathbb{G}\mathbb{F}$  formulae).

**Theorem 1 (Completeness).** *Let  $\varphi \in \mathbb{G}\mathbb{F}\mathbb{U}$  be a formula in normal form. If  $\varphi$  is satisfiable, then there exists a mosaic  $(\mathcal{M}, \mathcal{X})$  for  $\varphi$ .*

*Proof (Sketch).* Assume that  $\varphi$  has some model  $\mathcal{J}$ . Since  $\varphi$  is equality-free, we can make the standard name assumption (SNA):  $\mathbf{N}_{\mathbb{C}}(\varphi) \subseteq \Delta^{\mathcal{J}}$  and  $c^{\mathcal{I}} = c$  for all  $c \in \mathbf{N}_{\mathbb{C}}(\varphi)$ . Now, let  $\mathcal{I}$  be obtained from  $\mathcal{J}$  by duplicating all anonymous individuals. Formally, let  $\Delta_{anon} = \Delta^{\mathcal{J}} \setminus \mathbf{N}_{\mathbb{C}}(\varphi)$  and  $\Delta^{\mathcal{I}} = \mathbf{N}_{\mathbb{C}}(\varphi) \cup \{1, 2\} \times \Delta_{anon}$ . Let  $\pi : \Delta^{\mathcal{I}} \rightarrow \Delta^{\mathcal{J}}$  such that  $\pi(c) = c$  for  $c \in \mathbf{N}_{\mathbb{C}}(\varphi)$  and  $\pi((i, e)) = e$  otherwise.

Now we let  $\mathbf{t} \in P^{\mathcal{I}}$  if  $\pi(\mathbf{t}) \in P^{\mathcal{J}}$ . As  $\varphi$  does not contain equality,  $\mathcal{J} \models \varphi$  implies  $\mathcal{I} \models \varphi$ . This duplication of anonymous individuals makes sure that for every non-constant domain element  $e$ ,  $\mathcal{I}$  contains a twin element  $\tilde{e}$  different from  $e$  but with the same unary type. This property turns out to be crucial to show part (G) of the mosaic definition.

We show how to extract from  $\mathcal{I}$  a mosaic  $(\mathcal{M}, \mathcal{X})$  for  $\varphi$ . We can assume, w.l.o.g., that  $\Delta^{\mathcal{I}} \subseteq \mathbf{N}_{\mathbb{C}}$  and that  $c^{\mathcal{I}} = c$  for all  $c \in \mathbf{N}_{\mathbb{C}}(\varphi)$ .

Let  $\mathcal{X}$  be any set with  $\mathcal{X} \subseteq \mathbf{N}_{\mathbb{C}}$ ,  $\mathcal{X} \cap \Delta^{\mathcal{I}} = \emptyset$ , and  $|\mathcal{X}| = \text{width}(\varphi)$ . We say a type  $\tau$  can be *extracted* from  $\mathcal{I}$  if  $\tau$  can be obtained from  $\mathcal{I}$  in 4 steps:

- (a) Take any  $S \subseteq \Delta^{\mathcal{I}}$  such that  $\mathbf{N}_{\mathbb{C}}(\varphi) \subseteq S$  and  $|S| - |\mathbf{N}_{\mathbb{C}}(\varphi)| \leq \text{width}(\varphi)$ .
- (b) Let  $\tau^* = \{P(\mathbf{t}) \mid \mathbf{t} \subseteq S \wedge \mathbf{t} \in P^{\mathcal{I}}\}$ .
- (c) Let  $f$  be any injective function from  $\text{dom}(\tau^*) \setminus \mathbf{N}_{\mathbb{C}}(\varphi)$  to  $\mathcal{X}$ .
- (d) Let  $\tau$  be the type obtained from  $\tau^*$  by replacing every occurrence of  $c \in \text{dom}(\tau^*) \setminus \mathbf{N}_{\mathbb{C}}(\varphi)$  by  $f(c)$ .

The set  $\mathcal{M}$  contains all types  $\tau$  that can be *extracted* from  $\mathcal{I}$ . It is not difficult to see that the constructed  $(\mathcal{M}, \mathcal{X})$  is a mosaic for  $\varphi$ .  $\square$

**Theorem 2 (Soundness).** *Let  $\varphi \in \mathbb{G}\mathbb{F}\mathbb{U}$  be a formula in normal form. If there exists a mosaic  $(\mathcal{M}, \mathcal{X})$  for  $\varphi$ , then  $\varphi$  is satisfiable.*

*Proof (Sketch).* Assume a mosaic  $(\mathcal{M}, \mathcal{X})$  for  $\varphi$ . An *instantiation* for a type  $\tau \in \mathcal{M}$  is any injective function  $\delta$  from  $\text{dom}(\tau) \cap \mathcal{X}$  to  $\mathbf{N}_{\mathbb{C}} \setminus \mathcal{X}$ . Given such  $\tau$  and  $\delta$ , we use  $\delta(\tau)$  to denote the type that is obtained from  $\tau$  by replacing every occurrence of a constant  $c \in \text{dom}(\tau) \cap \mathcal{X}$  by  $\delta(c)$ . Our goal is to show how to inductively construct a possibly infinite sequence  $\mathcal{S} = (\tau_0, \delta_0), (\tau_1, \delta_1), \dots$  of pairs  $(\tau_j, \delta_j)$ , where  $\tau_j \in \mathcal{M}$  and  $\delta_j$  is an instantiation for  $\tau_j$ , such that  $\bigcup_{i \geq 0} \delta_i(\tau_i) \models \varphi$ .

In the base case, we let  $\tau_0$  be an arbitrary type from  $\mathcal{M}$ , and let  $\delta_0$  be any instantiation for  $\tau_0$ .

For the inductive case, suppose  $(\tau_0, \delta_0), \dots, (\tau_{i-1}, \delta_{i-1})$  have been defined, where  $i > 0$ . We show how define the next segment  $(\tau_i, \delta_i), \dots, (\tau_m, \delta_m)$  of  $\mathcal{S}$ , where  $m \geq i$  (we indeed may attach to  $\mathcal{S}$  multiple new elements in one step). To this end, choose the smallest index  $0 \leq j \leq i - 1$  satisfying the following condition: there is  $\forall \mathbf{x}.(R(\mathbf{t}) \rightarrow \exists \mathbf{y}.H(\mathbf{v})) \in \mathbf{E}(\varphi)$ , and  $R(g(\mathbf{t})) \in \delta_j(\tau_j)$  for some  $\mathbf{x}$ -assignment  $g$ . If such  $j$  does not exist, the construction of  $\mathcal{S}$  is complete, and we can proceed to  $(\star)$  below, where we argue that  $\bigcup_{0 \leq k < i} \delta_k(\tau_k) \models \varphi$ . We assume that the above  $j$  exists. We first show in  $(\dagger)$  how to define  $(\tau_i, \delta_i)$ , and then in  $(\ddagger)$  how to define the remaining  $(\tau_{i+1}, \delta_{i+1}), \dots, (\tau_m, \delta_m)$ .

$(\dagger)$  From the  $\mathbf{x}$ -assignment  $g$  construct the following  $\mathbf{x}$ -assignment  $h$ . For every  $x \in \mathbf{x}$ , (i) let  $h(x) = g(x)$ , if  $g(x) \in \text{dom}(\tau_j)$ , and (ii) let  $h(x) = \delta_j^-(g(x))$ , if  $g(x) \notin \text{dom}(\tau_j)$ . Since  $R(g(\mathbf{t})) \in \delta_j(\tau_j)$ , we get  $R(h(\mathbf{t})) \in \tau_j$ . Since the condition (F) is satisfied by the mosaic, there exists a type  $\tau' \in \mathcal{M}$  such that

1.  $H(f(g(\mathbf{v}))) \in \tau'$  for some  $\mathbf{y}$ -assignment  $f$ ;
2.  $\tau|_F = \tau'|_F$ , where  $F = \mathbf{N}_C(\varphi) \cup \{g(x) \mid x \in \mathbf{x} \cap \mathbf{v}\}$ .

We let  $\tau_i = \tau'$ , and define an injective function  $\delta_i$  from  $\text{dom}(\tau_i) \cap \mathcal{X}$  to  $\mathbf{N}_C \setminus \mathcal{X}$  as follows. For every  $c \in \text{dom}(\tau_i) \cap \mathcal{X}$ , we let  $\delta_i(c) = \delta_j(c)$  in case  $c \in \{h(x) \mid x \in \mathbf{x} \cap \mathbf{v}\}$ , and otherwise we let  $\delta_i(c)$  be a fresh constant, i.e., a constant that does not appear in  $\mathbf{N}_C(\varphi)$  or in the range of any instantiation built so far.

$(\ddagger)$  Let  $N$  be the set of all constants that were freshly introduced in  $\mathcal{S}$  by  $\delta_i$ , i.e.,  $N$  is the set of all  $\delta_i(c)$  such that  $c \in \text{dom}(\tau_i) \cap \mathcal{X}$  but  $c \notin \{h(x) \mid x \in \mathbf{x} \cap \mathbf{v}\}$ . Intuitively, in order to properly deal with the  $\mathbf{U}$  predicate, we need to find in  $\mathcal{M}$  proper types to connect every  $c \in N$  with the relevant remaining constants of the sequence  $\mathcal{S}$  constructed so far. Let  $(d_1, d'_1), \dots, (d_n, d'_n)$  be an enumeration of all pairs  $(d, d')$  such that  $d \in N$  and  $d' \in \bigcup_{0 \leq k \leq i-1} \text{ran}(\delta_k)$ , i.e.  $d'$  is any constant that appears in the sequence  $\mathcal{S}$  constructed so far but  $d' \notin N \cup \mathbf{N}_C(\varphi)$ . The definition of the segment  $(\tau_{i+1}, \delta_{i+1}), \dots, (\tau_m, \delta_m)$  of  $\mathcal{S}$  in this inductive step is as follows. We let  $m = i + n$ , and for each  $1 \leq k \leq n$ , we select  $(\tau_{i+1+k}, \delta_{i+1+k})$  as described next.

Assume an arbitrary  $1 \leq k \leq n$ . We let  $c = \delta_i^-(d_k)$ , and let  $\tau = \tau_l$  for some  $0 \leq l \leq i$  such that  $d'_k \in \text{ran}(\delta_l)$ . Let  $c' = \delta_l^-(d'_k)$ . Due to Condition (G) in the definition of mosaics, there exists a type  $\tau^* \in \mathcal{M}$  such that (i)  $\text{dom}(\tau) \cap \mathcal{X} = \{v_1, v_2\}$  for some  $v_1, v_2$  with  $v_1 \neq v_2$ , (ii)  $\tau|_c^\varphi = \tau^*|_{v_1}^\varphi$ , and (iii)  $\tau|_{c'}^\varphi = \tau^*|_{v_2}^\varphi$ . Then we set  $\tau_{i+1+k} = \tau^*$ , and let  $\delta_{i+1+k} = \{(v_1, d_k), (v_2, d'_k)\}$ .

$(\star)$  The above completes the construction of a candidate model for  $\varphi$ . It is not too difficult to see that  $\bigcup_{i \geq 0} \delta_i(\tau_i) \models \varphi$ .  $\square$

## 5 Complexity of TGF without Equality

Using the characterization of the previous section, we can infer worst-case optimal upper bounds for satisfiability checking in GFU, and thus in TGF.

**Theorem 3.** *Deciding satisfiability of TGF and of GFU formulae without equality is N2EXPTIME-complete. The problem is NEXPTIME-complete under the assumption that predicate arities are bounded by a constant.*



*Proof (Sketch).* Due to Propositions 1 and 2, it suffices to show the two upper bounds for GFU formulae in normal form. Due to Theorems 1 and 2, we can decide the satisfiability of a formula  $\varphi \in \text{GFU}$  in normal form by checking the existence of a mosaic for  $\varphi$ . Our approach is to non-deterministically guess a pair  $(\mathcal{M}, \mathcal{X})$  of a set  $\mathcal{M}$  of types over  $\text{Np}(\varphi)$  together with a set of constants  $\mathcal{X}$  of cardinality at most  $\text{width}(\varphi)$ , and then verify that  $(\mathcal{M}, \mathcal{X})$  is indeed a mosaic for  $\varphi$ . Note that given a candidate  $(\mathcal{M}, \mathcal{X})$  as input we can check in polynomial time whether  $(\mathcal{M}, \mathcal{X})$  satisfies all the conditions given in Definition 6. Observe that the number of ground atoms over the signature of  $\varphi$  with arguments from  $\text{Nc}(\varphi) \cup \mathcal{X}$  is bounded by  $|\text{Np}(\varphi)| \cdot (|\text{Nc}(\varphi)| + \text{width}(\varphi))^k$ , where  $k$  the maximal arity of predicates in  $\varphi$ . Consequently, we can restrict ourselves to candidates  $(\mathcal{M}, \mathcal{X})$ , where  $\mathcal{M}$  has no more than  $2^{|\text{Np}(\varphi)| \cdot (|\text{Nc}(\varphi)| + \text{width}(\varphi))^k}$  types. Since this bound is double exponential in the size of  $\varphi$ , but only single exponential under the assumption that  $k$  is a constant, the two upper bounds follow.

The matching lower bound for the bounded arity follows from the complexity of  $\text{FO}^2$  [13]. N2EXPTIME-hardness for unbounded arity follows from a reduction from the tiling problem of a grid of doubly exponential size [7].  $\square$

## 6 Undecidability of TGF with Equality

In the presence of equality, we can show the undecidability of satisfiability of GFU (and hence of TGF) by a reduction from the tiling problem for an infinite grid [7].<sup>1</sup> We can construct a GFU formula with equality such that its universal model represents an  $\mathbb{N} \times \mathbb{N}$  grid. Thereby, the domain elements of the model correspond to grid positions and every position is connected to its upper neighbor by a binary predicate  $V$  and to its right neighbor by a binary predicate  $H$ .

In the following, we omit leading universal quantifiers; all formulae are sentences. We start our modeling by ensuring there is exactly one leftmost, bottom-most position of the grid, i.e., the “origin”.

$$\begin{aligned} & \exists x. \text{Orig}(x) \\ & \text{U}(x, y) \wedge \text{Orig}(x) \wedge \text{Orig}(y) \rightarrow x \approx y \end{aligned}$$

Any two domain elements co-occur together with the origin in a ternary auxiliary predicate  $\text{ChkFunc}$ .

$$\text{U}(x, y) \rightarrow \exists z. \text{ChkFunc}(x, y, z) \wedge \text{Orig}(z)$$

Intuitively,  $\text{ChkFunc}(x, y, z)$  indicates that we will enforce that if  $z$  is connected with both  $x$  and  $y$  by predicate  $V$  (or  $H$ ), then  $x$  and  $y$  must coincide; in other words, as  $x$  and  $y$  are arbitrary elements,  $z$  has only one outgoing  $V$ -connection and one outgoing  $H$ -connection. The following two sentences implement this.

$$\begin{aligned} & \text{ChkFunc}(x, y, z) \wedge H(z, x) \wedge H(z, y) \rightarrow x \approx y \\ & \text{ChkFunc}(x, y, z) \wedge V(z, x) \wedge V(z, y) \rightarrow x \approx y \end{aligned}$$

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<sup>1</sup> As mentioned in the introduction, this undecidability result can be inferred from the undecidability of the Goldfarb class, using the reduction in [14] (Section 4.2.3).

In particular, this makes sure that the origin has exactly one right and one upper neighbor. Also, we propagate this “local functionality” enforcing predicate along the (known to be unique)  $V$ - and  $H$ -connections.

$$\begin{aligned} \text{ChkFunc}(x, y, z) &\rightarrow \exists w. \text{ChkFunc}(x, y, w) \wedge H(z, w) \\ \text{ChkFunc}(x, y, z) &\rightarrow \exists w. \text{ChkFunc}(x, y, w) \wedge V(z, w) \end{aligned}$$

With these axioms alone, the corresponding universal model would resemble an infinite binary tree, with the origin as root and every node having (exactly) one  $H$ -successor and (exactly) one  $V$ -successor. The next axioms make sure that for every element  $e$  in our structure, the element reached from  $e$  via an  $H$ - $V$ -path coincides with the element reached from  $e$  via a  $V$ - $H$ -path, using another auxiliary 5-ary predicate  $\text{ChkSq}$  which is handled in a way that  $\text{ChkSq}(x, y, z_1, z_2, z_3)$  is only entailed whenever  $z_1$  has  $z_2$  as right neighbor and  $z_3$  as upper neighbor.

Again, we start ensuring this for  $e$  being the origin and then work our way through the structure along the (unique)  $H$ - and  $V$ - connections.

$$\begin{aligned} \text{U}(x, y) &\rightarrow \exists z_1 z_2 z_3. \text{ChkSq}(x, y, z_1, z_2, z_3) \wedge \text{Orig}(z_1) \wedge H(z_1, z_2) \wedge V(z_1, z_3) \\ \text{ChkSq}(x, y, z_1, z_2, z_3) &\rightarrow \exists w_1 w_2. \text{ChkSq}(x, y, z_2, w_1, w_2) \wedge H(z_2, w_1) \wedge V(z_2, w_2) \\ \text{ChkSq}(x, y, z_1, z_2, z_3) &\rightarrow \exists w_1 w_2. \text{ChkSq}(x, y, z_3, w_1, w_2) \wedge H(z_3, w_1) \wedge V(z_3, w_2) \end{aligned}$$

Finally, we ensure that if  $\text{ChkSq}(x, y, z_1, z_2, z_3)$  holds and  $x$  is the right neighbor of  $z_2$  and  $y$  is the upper neighbor of  $z_3$ , that then  $x$  and  $y$  must coincide.

$$\text{ChkSq}(x, y, z_1, z_2, z_3) \wedge V(z_2, x) \wedge H(z_3, y) \rightarrow x \approx y$$

This finishes our modeling of the infinite grid. It is now straightforward to model a tiling on top of this, and we obtain the following theorem.

**Theorem 4.** *Checking satisfiability of TGF formulae with equality is undecidable. The same applies to GFU formulae with equality.*

## 7 Further Undecidable Extensions

In this section, we will review further natural extensions of TGF and find that they lead to undecidability.

*Relaxing guardedness further.* Unguarded quantification of subformulae with three variables would allow to express any formula of the three-variable fragment of  $\mathbb{FO}$ , denoted  $\mathbb{FO}^3$ , for which satisfiability is undecidable (as  $\mathbb{FO}^3$  contains the class of  $\mathbb{FO}$  sentences with quantifier prefix  $\forall\exists\forall$  which is undecidable [15]).

*Counting.*  $\mathbb{FO}^2$  can be extended by counting quantifiers of the shape  $\exists^{=n}$ ,  $\exists^{\leq n}$ , and  $\exists^{\geq n}$ , yielding a logic denoted  $\mathbb{C}^2$ . This extension (which helps to capture DLs with cardinality restrictions) by itself does not lead to an increase in complexity of satisfiability checking [17]. Yet, this enrichment is detrimental when mixing it with the guarded fragment: via the  $\mathbb{C}^2$  sentence  $\forall x. \exists^{=1} y. F(x, y)$  we can enforce that  $F$  must be interpreted as a functional binary relation. Yet, adding a functional relation to  $\mathbb{GF}$  is known to cause undecidability [12].

*Conjunctive Queries.* Instead of asking for satisfiability of a TGF theory, an often considered problem stemming from database theory is also if it entails a Boolean conjunctive query (i.e., an existentially quantified conjunction of atoms). However, conjunctive query entailment has been shown to be undecidable already for  $\text{FO}^2$  alone [18]. This also shows that any attempt of extending TGF such that it incorporates  $\text{FO}$  fragments that can express negated Boolean conjunctive queries (such as the unary negation fragment [21] or the guarded negation fragment [4]) will lead to undecidability.

*Loose guardedness.* It has been shown that GF remains decidable if the guardedness restriction is relaxed, leading to notions such as the loosely guarded fragment, the packed fragment or the clique-guarded fragment. For most restrictive notion of those, the loosely guarded fragment [6], the guard does not need to be one atom containing all free variables, rather it can be a conjunction of atoms with the property that any pair of free variables occurs together in one of those conjuncts. It is not hard to see that in the presence of the  $\text{U}$  predicate (or if such a predicate can be axiomatized as in TGF), we can create a “loose guard”  $\bigwedge_{\{x,y\} \subseteq \mathbf{x}} \text{U}(x, y)$  for any set  $\mathbf{x}$  of free variables. This allows to quantify over the full domain, hence every  $\text{FO}$  formula is equivalent to such a loosely guarded one. Consequently, a hypothetical “loosely triguarded fragment” would be as expressive as  $\text{FO}$ , hence undecidable.

## 8 Conclusion

In this paper, we have introduced the triguarded fragment of  $\text{FO}$  which subsumes both GF and  $\text{FO}^2$ . We clarified the computational complexity of satisfiability checking in this fragment, both for the bounded and unbounded arity case. We discussed that diverse natural extensions of the fragment lead to undecidability.

While both GF [12] and  $\text{FO}^2$  [16] are known to have the finite model property, the status of TGF in this respect is still open. On a first glance, it seems the arguments for establishing the finite model property of the two fragments are incompatible and neither can be easily adapted to show that property for TGF. Still, we conjecture that TGF has the finite model property which would imply that satisfiability and finite satisfiability (and their complexity) coincide.

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