

High-concurrency Solution for Intelligent Connected Vehicle Race Based on Cloud Computing

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Abstract

Based on the existing high-concurrency solutions, this paper studies the high-concurrency solutions for intelligent connected vehicle race based on cloud computing, and verifies the effectiveness of the scheme by designing the scheduling method of the intelligent networked car race platform and high-concurrency tests. The experimental results show that the designed scheduling method of the intelligent networked car event platform can meet the high concurrency requirements of the event, especially when international communication is affected by the epidemic, ensuring the participation of domestic and foreign teams in the competition and effective technical exchanges. It has a relatively broad application prospect.

Keywords

Cloud computing, intelligent connected automobile events, high concurrency demand, cloud simulation platform

1. Introduction

As a new generation of information technology and transportation integrated development product, intelligent network vehicle is an important content of Chinese scientific and technological innovation support to accelerate the construction of transportation power. At present, virtual simulation is an indispensable link in automobile research and development^[1], and its status is constantly improving in the industry background of accelerating the development of autonomous driving^[2]. In addition, virtual simulation testing is characterized by high efficiency, strong test repeatability, safety, reliability and low cost, which is the direction and trend of future autonomous vehicle testing^[3]. Therefore, based on cloud computing^[4], the intelligent driving simulation competition is held, and the intelligent connected vehicle simulation development and verification are taken as the entry point, and the scientific research and research of intelligent connected vehicle are combined with the industrial competition to escort the technological development of intelligent connected vehicle virtual simulation.

Held at present, the related intelligent driving simulation cases are less, part of the event to take the form of the client game, is bad for the contestants from different regions are more, not all teams playing online at the same time, also can't see the real time teams scores ranking situation, there is no guarantee that the game fair, fair and open, Especially when international exchanges are affected by the epidemic, it is not conducive for international teams to participate in competitions and technical exchanges. In addition, they lack experience in dealing with a large number of participants accessing the interface of the competition platform and high concurrency requests. Once there is a high concurrent demand^[5], the website may be paralyzed due to the heavy traffic^[6], which further leads to the failure of the competition.

In the intelligent connected vehicle event based on cloud computing, due to the large number of participating teams and competition items, it is difficult to meet the high concurrency requirements of multiple teams in the same practice period, especially during the official competition, when all participating teams go online at the same time and run the competition questions at the same time. In addi-



tion, in order to meet the fairness, fairness and openness of the competition, it is necessary to ensure that the competition environment of the participants is consistent. Therefore, it is necessary to invent a high concurrency solution of intelligent connected auto race based on cloud computing. This can ensure the success of the intelligent connected car event, promote the technical exchanges among the participating teams, and help the implementation of domestic intelligent connected technology.

Based on the existing high-concurrency solutions, this paper studies the high-concurrency solutions of intelligent connected auto races based on cloud computing. By designing the scheduling method of the intelligent connected vehicle event platform^[7] and verifying the effectiveness and reliability of the scheme through highly concurrent testing, it provides a reference for the intelligent connected vehicle event based on cloud computing in the industry.

2. The experiment design

2.1. Design of scheduling method for intelligent Connected car race platform

In this experimental design, teams need to enter the corresponding contest interface by using their account and password on the competition login interface. After confirming the information on the question interface, manually start the question. In this case, the contest server automatically queries the current K8s cluster resource usage and determines whether there are idle resources available. If it determines that there are no idle resources available, the server directly enters the queuing mechanism. If it is determined that there are idle resources available, the server directly starts the virtual engine (UE4 is used in this experiment) and determines whether UE4 is successfully started. If the startup fails, the monitoring page is displayed. If the startup is successful, the server accounts for a period of time and checks whether an algorithm is connected within this period. If no algorithm is added, the server automatically stops the UE4 running process. If an algorithm is connected, the server will directly run the questions until the end of the questions and calculate the results. (see **Figure 1**).

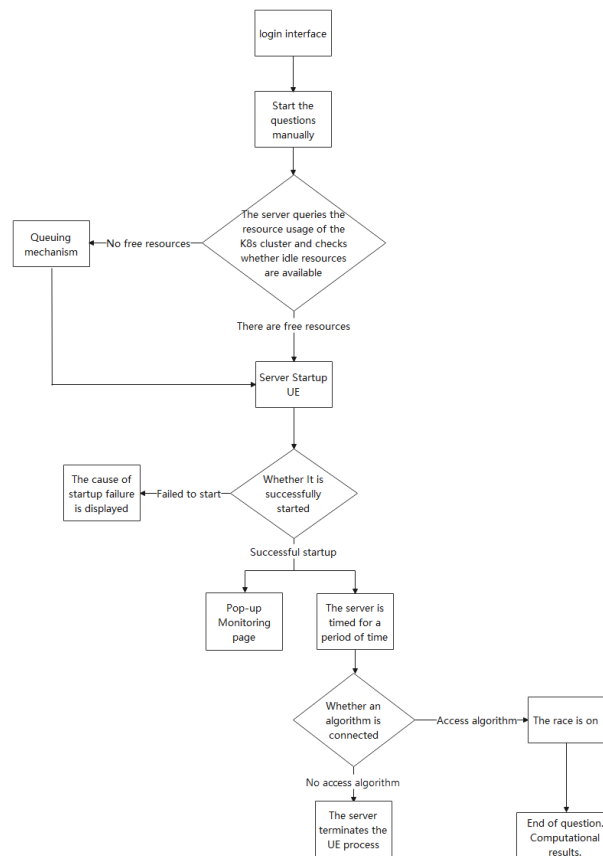


Figure 1 Design of scheduling method for intelligent Connected car race platform

2.1.1. Queuing mechanism design

In this experiment, the queuing mechanism is applied to the case that the server used in the contest determines that there is no idle resource available after automatically querying the current K8s cluster resource usage.

When the server automatically checks and determines that no idle resources are available, the current team will directly enter the queue, and the number of people in the queue will be increased by one. The current queue number is displayed. After that, it is up to the teams to choose whether to wait. If the team chooses not to wait, it will exit the queue directly, and the number of people in the queue will be increased or decreased by one. If you choose to continue waiting, the interface updates the number of people in line in real time.

When the server automatically queries that there are idle resources in the current K8s cluster resources, the team can choose whether to start the contest. If a team fails to manually click the start button in time within the time specified by the system, the team will directly exit the queue, lose the qualification and need to queue up again. If the team manually clicks the start button in time within the time specified by the system, the server will directly start UE4, and the current queue of the team will end (**Figure 2**).

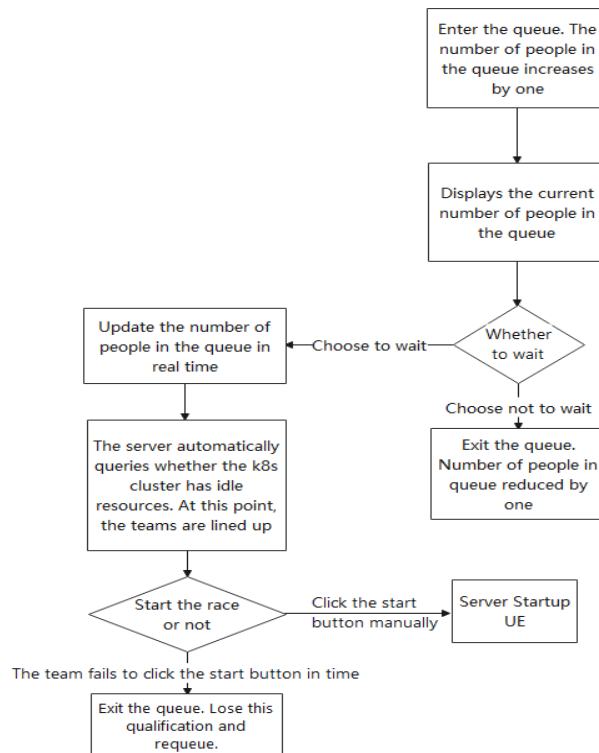


Figure 2 Queuing mechanism design

2.1.2 Design of K8s deployment scheme

This experiment adopts the container arrangement scheme of Kubernetes(K8s)[8]. The minimum number of program units can be infinitely extended by K8s technology. If the number of access reaches the load value, the hardware is configured as a new Node by kubectl (command), which can be put into use immediately after the startup, reducing the time of configuring the running environment(Figure 3).

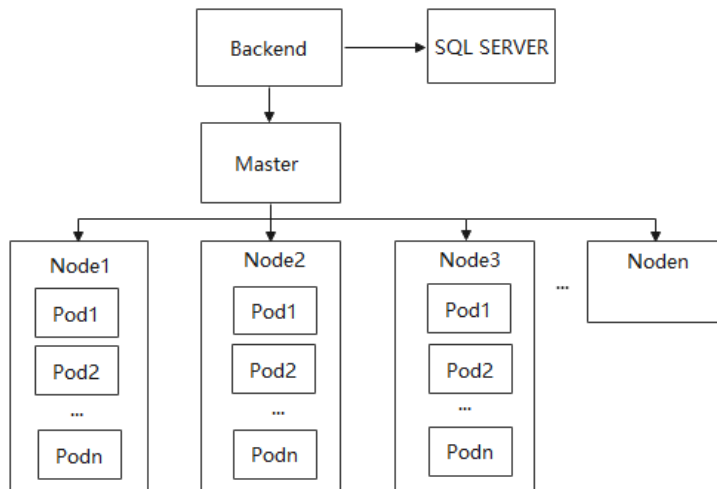


Figure 3 Design of K8s deployment scheme

In addition, K8s could manage multiple management nodes ^[9], reducing the access load of a single management node. It also greatly reduces the possibility of system outages. In addition, it facilitates node scaling and expansion management, achieves high concurrency, all containers, supports Web interface access, and automatically adjusts hardware resources based on requirements. Each task runs in Docker container, isolated from each other, and does not affect each other to maximize the use of physical hardware resources. At the same time, it ensures the convenience of deployment and expansion, and ensures the requirement of high concurrency for hundreds of people to go online simultaneously.

2.1.3. Design of algorithm access scheme

In this experiment, the algorithm access scheme design is applicable to the server accounting time for a period of time after UE4 is successfully started. And judge whether there is an algorithm access in this period of time.

In this experiment, the algorithm invokes the login interface for authentication. At the same time, verify that the user name and password are valid, and verify that the user has a running question. If the preceding authentication fails, the interface returns the failure cause, and the algorithm connection process ends. If the above verification is successful, the algorithm will call the Web interface to obtain the access key and the communication address. Then, the Web interface is called to obtain the installation sensor information of the main vehicle. Next, the algorithm invokes the UE4 interface with the secret key to send the start instruction. Next, the algorithm calls UE4 interface to obtain sensor data and master vehicle data, makes decisions, and sends control instructions according to the decisions. Finally, after running the questions, the questions are finished and the scores are calculated(**Figure 4**).

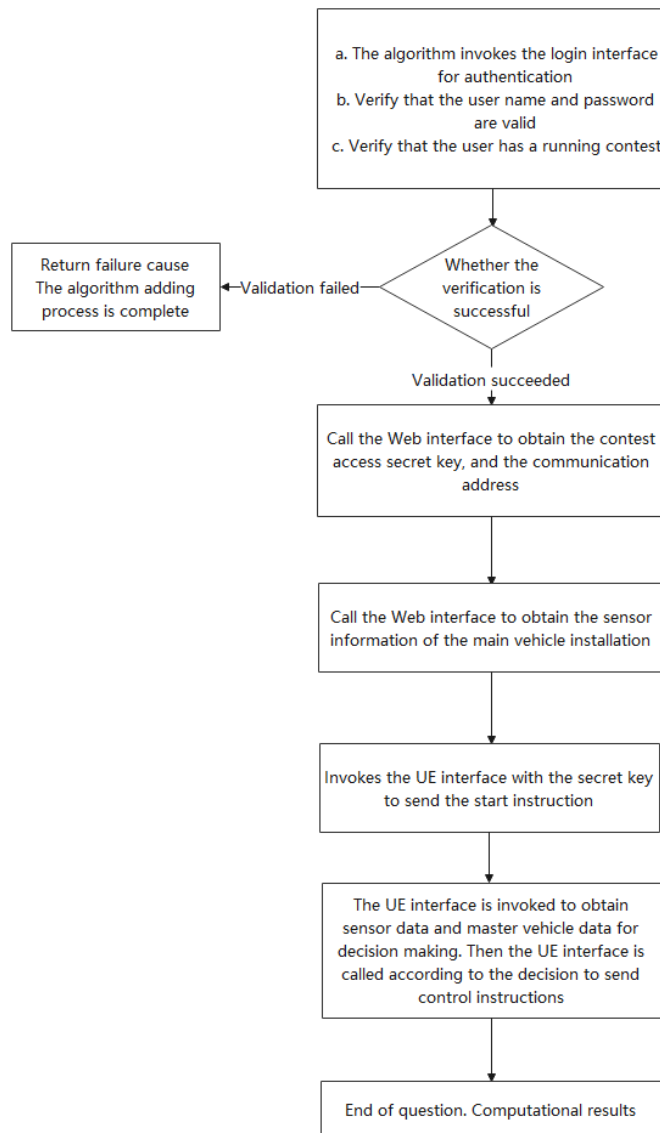


Figure 4 Design of algorithm access scheme

2.2. Test concurrency experimental design

In this experiment, after completing the design of the scheduling method for the intelligent connected car race platform, it is necessary to carry out a high concurrency test on this method, so as to verify that this experiment can finally solve the high concurrency requirements of intelligent connected car race based on cloud computing. Therefore, the high concurrency test is carried out from the following two aspects^[10].

2.2.1. Experimental design of single server concurrency test

This experiment first needs to test how many UE4 can run on a single server. According to the requirements of this experimental competition, different kinds of sensors are installed for different kinds of questions. For example, only millimeter wave radar is installed in the decision control class, and only camera is installed in the perception class. Therefore, in this experiment, the decision control and perception questions are respectively run on the same K8s server, and the running conditions of the two different questions are represented by the number of UE4 runs. (as shown in **Table 1**)

Table 1 K8s server parameters in this experiment

| | |
|---|---|
| Server model | p2v.2xlarge.8 |
| vCPUs internal storage | 64vCPUs 64GB |
| CPU | Intel SkyLake 6151 3.0GHz |
| Base/maximum bandwidth | 4/10 Gbit/s |
| The Intranet receives and sends packets | 500000 |
| Features | GPU: 1 * NVIDIA V100 / 1 * 16G |
| Image | Ubuntu 16.04 server 64bit with Tesla Driver 4 18.67 and Cuda 10.1(40GB) |
| System disk | 4T |
| Bandwidth | 300M/s |

2.2.2. Experimental design of single server concurrency test

After determining the number of UE4s running on a single K8s server, a high concurrency test experiment is required based on the overall race high concurrency requirements. (The high concurrency test environment required by the experiment is shown in **Table 2** and **Table 3**) For example, in this experiment, 100 UE4s are run in the same time period. Therefore, this experiment will set up a test environment and carry out high concurrency tests for 100 UE4s running in the same time period from four aspects: time characteristics, resource utilization, capacity and compliance of performance efficiency(**Figure 5**) .

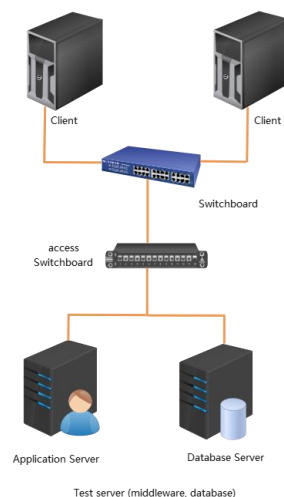


Figure 5 Test environment topology

Table 2 High concurrency test coverage table

| Serial number | Test item | Test content |
|---------------|--|--|
| 1 | Time characteristic | The corresponding time, processing time and throughput when the product performs its functions under specified conditions. |
| 2 | Resource utilization | CPU utilization and memory utilization when executing test tasks. |
| 3 | Load | Whether the maximum number of concurrent users, communication bandwidth, transaction throughput and other parameters meet the requirements. |
| 4 | Compliance with performance efficiency | Whether the product complies with the requirements specification, product description, etc., as well as the performance and efficiency requirements in the standard. |

Table 3 High concurrency test environment

| Testing the hardware environment | | | |
|----------------------------------|--------------------------|---|---|
| Serial number | The name of the hardware | Configuration | Usage |
| 1 | The test PC | CPU:30GHZ Internal Storage: 176G The hard disk: 40G The operating system: windows server 2016 std. Bandwidth: 100M/s | Deploying pressure Tools |
| Testing the Software environment | | | |
| Serial number | The name of the Software | Version number | Usage |
| 1 | Python | 3.6.5rc1 | Running the test script |
| 2 | The operating system | windows server 2016 std. | The pressure script is deployed on the Windows server |

3. Results analysis

Based on the scheduling method of intelligent connected car race platform, this method is tested with high concurrency in this experiment. The individual server concurrency was first tested to determine the amount of UE4 a single server could run. This was followed by a high concurrency test for large-scale events (this experiment required running 100 UE4 high concurrency tests in the same time period). Finally, after several rounds of testing and code tuning, the experimental results are as follows:

3.1. Single server concurrency test result

According to the different question types of the competition, this experiment selected six types of scenes in the competition: stationary front vehicle (straight line), pedestrian crossing the road (no cover), curved road, obstructed front vehicle, horizontal parking, vertical parking, automatic driving (low dynamic traffic flow). After 8 tests, the test results are shown in **Figure 6**. Marked red indicates that the server runs at a frame rate below 20fps, and marked green indicates that the server runs at a frame rate above 20fps.

| Serial number | Scene type | Sensor Type | Test1 | Test2 | Test3 | Test4 | Test5 | Test6 | Test7 | Test8 |
|---------------|--|----------------------------|---------|---------|--------|--------|--------|--------|--------|--------|
| Scene1 | The vehicle ahead is stationary (going straight) | Only cameras | 70.557 | 58.331 | 47.228 | 36.521 | 25.305 | 18.86 | 16.265 | 14.339 |
| | | Only millimeter wave radar | 113.84 | 81.799 | 75.09 | 45.149 | 31.241 | 31.893 | 22.59 | 18.81 |
| Scene2 | Pedestrian crossing the road (no blocking) | Only cameras | 76.086 | 66.724 | 53.807 | 40.241 | 30.855 | 24.943 | 19.163 | 17.069 |
| | | Only millimeter wave radar | 118.927 | 104.235 | 86.066 | 62.664 | 53.938 | 36.826 | 30.562 | 23.166 |
| Scene3 | Curved road, blocked by vehicles ahead | Only cameras | 21.093 | 20.698 | 18.765 | 18.644 | 16.916 | 15.002 | 14.627 | 13.402 |
| | | Only millimeter wave radar | 38.041 | 37.882 | 33.509 | 29.226 | 25.794 | 21.784 | 18.924 | 17.476 |
| Scene4 | Parallel parking | Only cameras | 65.032 | 60.168 | 54.258 | 34.463 | 24.264 | 19.329 | 16.659 | 15.05 |
| | | Only millimeter wave radar | 109.632 | 82.158 | 69.323 | 54.731 | 37.948 | 30.597 | 23.38 | 19.684 |
| Scene5 | Vertical parking | Only cameras | 77.367 | 71.194 | 65.067 | 45.947 | 39.511 | 24.039 | 19.109 | 17.012 |
| | | Only millimeter wave radar | 113.995 | 109.501 | 88.376 | 73.974 | 47.58 | 36.372 | 29.139 | 25.094 |
| Scene6 | Automatic driving (low dynamic traffic flow) | Only cameras | 38.59 | 44.968 | 35.852 | 27.066 | 19.959 | 17.691 | 14.958 | 13.005 |
| | | Only millimeter wave radar | 75.273 | 69.429 | 40.62 | 34.498 | 29.829 | 24.324 | 18.846 | 16.131 |

Figure 6 Test the concurrency of a single server in different scenarios

In order to further guarantee the smooth operation of a single K8s server, this experiment further averages the number of UE4 running in the above different scenarios. In addition, if the frame rate of a single server is above 24fps, it is qualified. Therefore, after calculation, the number of UE4 questions in decision control category and running perception category can be run by a single server is 6 and 5 respectively (as shown in **Table 4**).

Table 4 Test the concurrency of a single server in different scenarios

| Type of Competition Question | Quantity (unit) | Frame rate (fps) | Amount of bandwidth (Mbps) |
|--|-----------------|------------------|----------------------------|
| Decision control questions (only millimeter wave radar is installed) | 1 | 94.95 | 21.8 |
| | 2 | 80.83 | 43.6 |
| | 3 | 65.49 | 65.4 |
| | 4 | 50.04 | 87.2 |
| | 5 | 37.72 | 108.8 |
| | 6 | 30.29 | 130.4 |
| | 7 | 23.90 | 152 |
| | 8 | 20.04 | 173.6 |
| Perceptual questions (only cameras are installed) | Quantity (unit) | Frame rate (fps) | Amount of bandwidth (Mbps) |
| | 1 | 61.45 | 43.2 |
| | 2 | 53.68 | 86.4 |
| | 3 | 45.82 | 129.9 |
| | 4 | 33.81 | 172.8 |
| | 5 | 26.13 | 216 |
| | 6 | 19.97 | 259.2 |
| | 7 | 16.79 | 302.4 |
| 8 | 14.97 | 345.6 | |

Because the event needs to run both decision control and perception questions at the same time, this experiment finally determines that the number of UE4 that can be run by a single K8s server is 5.

3.2.High concurrency test results applied to large events

According to the requirement that a single K8s server can run 5 UE4, 20 K8s servers are selected for the high concurrency test of 100 concurrency. Then the monitoring data is randomly selected and the maximum value is recorded. After several rounds of testing and code tuning, the monitoring data is extracted as follows:

This highly concurrent test involves a total of 5 interfaces (system login, running the contest, obtaining the data of the main vehicle, obtaining the monitoring data, and the algorithm). In addition, 100 concurrent tests can be started in both the running contest and the data acquisition history, so the concurrency test passes (as shown in **Table 5**).

Table 5 Result of 100 Concurrent tests started in the same period

| Test project | Test scene | Expected indicators | Actual indicators | Test result |
|--------------|-------------------------|-------------------------|-------------------------|-------------|
| 1 | System Login | 100 concurrent quantity | 100 concurrent quantity | Pass |
| 2 | Running questions | 100 concurrent quantity | 100 concurrent quantity | Pass |
| 3 | Obtain ego vehicle data | 100 concurrent quantity | 100 concurrent quantity | Pass |
| 4 | Obtain monitoring data | 100 concurrent quantity | 100 concurrent quantity | Pass |
| 5 | Algorithm | frame rate>30fps | 28<frame rate<30fps | Pass |

4. Conclusion

In this paper, the high concurrency solution of intelligent connected auto race based on cloud computing is studied. By designing the scheduling method of the intelligent connected car race platform, and through high concurrency test, the validity and reliability of the scheme are verified. The competition is further ensured through the cloud server, which guarantees the high concurrent demand of the intelligent connected car event based on cloud computing for competitors from different regions to go online at the same time. At the same time, it also ensures that all teams can see the ranking of each team in real time. In addition, ensure that the competition is fair, impartial and open. Especially when international exchanges are affected by the epidemic, it guarantees the participation of domestic and foreign teams in competitions and effective technical exchanges, and has a broad application prospect.

5. Reference

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