

# Optimal Multiple Assignments with $(m,m)$ -Scheme for General Access Structures

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**Abstract**—Given the number  $n$  of the participants, one can solve an integer programming on  $2^n$  variables to construct an optimal multiple assignment with threshold schemes for general access structure. In this paper, we focus on finding optimal multiple assignments with  $(m,m)$ -schemes. We prove that most of the variables in the corresponding integer programming take the value of 0, while the remaining variables take the values of either 0 or 1. We also show that given a complete access structure, an optimal scheme may be obtained directly from the scheme by Ito, Saito, and Nishizeki (Secret sharing scheme realizing any access structure, in Globecom 1987).

**Keywords**—multiple assignments, threshold scheme, integer programming, access structure.

## I. INTRODUCTION

In a secret sharing scheme (SSS) [1], [2], a dealer  $P_0$  distributes a secret among several participants  $P = \{P_1, \dots, P_n\}$ , and a pair of algorithms, a distribution algorithm and a reconstruction algorithm, are involved. Given a secret  $s$  in a finite domain  $S$ , the dealer  $P_0$  runs the distribution algorithm to compute the shares  $s_i, (i = 1, \dots, n)$  which are further sent to the participant  $P_i, (i = 1, \dots, n)$ , respectively. The qualified subset of  $P$  can take their shares as input of the reconstruction algorithm to re-derive the secret  $s$ . We say a SSS is *perfect* if any unqualified subset of  $P$  can not get any information about  $s$ .

An *access structure*  $\Gamma = \{\mathcal{A}, \mathcal{F}\}$  contains two families of subsets of  $P$  and is *monotone* in the sense that, if a subset  $U$  is in the access structure, all sets that contain  $U$  as a subset should also form part of the access structure. A SSS realizes  $\Gamma = \{\mathcal{A}, \mathcal{F}\}$  over  $S$  if: 1) it shares secret in  $S$ ; 2) the subset of  $P$  in  $\mathcal{A}$  is qualified; and 3) the subset of  $P$  in  $\mathcal{F}$  is unqualified. It is known [6], [7] that there exist SSSs which realize any monotone access structure  $\Gamma$  over a given  $S$ . In a  $(k,n)$ -threshold access structure,  $\mathcal{A}$  contains all subset of  $P$  that has at least  $k$  participants. A SSS realizing  $(k,n)$ -threshold access structure is a  $(k,n)$ -threshold SSS. If any subset of  $P$  belongs to either  $\mathcal{A}$  or  $\mathcal{F}$ , we call the access structure *complete*.

Generally, the efficiency of a SSS is measured by entropy. The entropies of the secret  $s$  and shares  $s_i, (i = 1, \dots, n)$  satisfy  $H(s_i) \geq H(s)$ , for every perfect SSS and any given access structure [3], [4], [5]. An access structure  $\Gamma$  is *ideal* over  $S$  if there exists a SSS realizing  $\Gamma$  over  $S$  such that  $H(s) = H(s_i), i = 1, \dots, n$ .  $\Gamma$  is *universally ideal* if  $\Gamma$  is ideal over every finite  $S$ . The  $(k,n)$ -threshold access structure

over  $S$  where  $|S| > n$  is ideal, and can be realized by the scheme proposed in [1]. Although many types of ideal access structures have been studied [8], [9], [10], [11], [12], [13], [14], [15], [16], [17], [18], it is an open problem to characterize the ideal access structure. Brickell and Davenport [9] explore this problem with matroids. Beigel and Chor [10] show that an access structure is universally ideal if and only if it is ideal over binary and ternary domains. The character of weighted threshold secret sharing is given in [21].

More generally, another open problem is to find the optimal SSS for general access structure. Benoloh and Leichter [7] propose a SSS for general access structure by combining several  $(m,m)$ -thresholds SSSs, which is simple but inefficient and is extended by [19], [20]. Comparing with the method in [7], [19], [20] that use the information of qualified subsets, Itoh, Saito and Nishizeki [6], [28] realize an access structure from the information of the unqualified subsets. [6], [28] use a single  $(m,m)$ -threshold SSS to realize general access structure and thus are applicable to visual secret sharing schemes [24], [25]. The SSS in [6], [28] is not efficient, especially for a  $(k,n)$ -threshold access structure with  $k \neq n$ . A modified method [22] can achieve a better efficiency for a nearly  $(k,n)$ -threshold access structure. The SSSs in [6], [28], [22] are *multiple assignment schemes* and assign multiple primitive shares for each participant where the primitive shares are selected from the shares set of a single  $(k,m)$ -threshold SSS. [23], [26] propose independently a novel method to obtain the optimal efficiency among all multiple assignment schemes by solving integer programming (IP, for short), and the method is extended in [27] to incomplete and/or ramp access structures. The complexity of solving an integer programming problem is related to the cardinality of the constraint variables set.

Generally, constructing a multiple assignment scheme for a given access structure with  $(k,m)$ -scheme will obtain higher efficiency than with  $(m,m)$ -scheme [23], [26]. But in some cases, constructing scheme from  $(m,m)$ -scheme is the only choice [29], [30]. For example, as  $(k,m)$ -threshold access structure is not universally ideal but  $(m,m)$ -threshold access is, there exists some domain  $S$  such that there is no ideal  $(k,m)$ -threshold SSS over  $S$ . Another example, only  $(m,m)$ -threshold SSSs are appropriate to construct a visual secret sharing scheme.

In this paper, we propose a method to reduce the number

of constraint variables in the integer programming problem [23], [26], [27]. We prove that the integer programming problem will be simplified to a 0-1 programming problem if the multiple assignment scheme is constructed with  $(m, m)$ -threshold SSSs. We also show that the scheme in [6] attains the optimal efficiency among all multiple assignment schemes which are constructed with  $(m, m)$ -threshold SSSs to realize a given complete access structure.

This paper is organized as follows. In Section 2, we give the definitions of SSSs and introduce the main result of [23], [26]. In Section 3, we point out that some constraint variables of the integer programming problem in [23], [26] take the value of 0, and further prove that the integer programming problem will be simplified to a 0-1 programming problem if the multiple assignment scheme is constructed with  $(m, m)$ -threshold SSSs. We show in Section 4 that the scheme in [6] achieves the optimal efficiency if all multiple assignment schemes are constructed with  $(m, m)$ -threshold SSSs to realize a given complete access structure. Conclusions are drawn in Section 5.

## II. PRELIMINARIES

### A. Definitions

Let  $P$  be a finite set and  $\mathcal{A}, \mathcal{F} \subseteq 2^P$ , we say  $\Gamma = \{\mathcal{A}, \mathcal{F}\}$  is monotone if:

$$\begin{cases} A \in \mathcal{A} \Rightarrow \forall A' \supseteq A, A' \in \mathcal{A} \\ F \in \mathcal{F} \Rightarrow \forall F' \subseteq F, F' \in \mathcal{F} \\ \mathcal{A} \cap \mathcal{F} = \emptyset \end{cases} \quad (1)$$

Let  $\Pi$  be a SSS. Suppose the dealer  $P_0$  wants to share a secret  $s \in S$  among  $P = \{P_1, \dots, P_n\}$  and the share of participant  $P_i$  is  $s_i = \mathbf{E}(i, s, r)$ ,  $(1 \leq i \leq n)$ . For a subset of participants  $A = \{P_{i_1}, \dots, P_{i_t}\} \subseteq P$ , if there exists a reconstruction algorithm  $\mathbf{D}_A$  such that

$$\forall s \in S, r \in R : s = \mathbf{D}_A(s_{i_1}, \dots, s_{i_t}) \quad (2)$$

then  $A$  is a qualified subset of  $\Pi$ . If such an algorithm does not exist,  $A$  is a unqualified subset of  $\Pi$ .

Let  $\mathcal{A}_\Pi$  be the family of all qualified subsets of  $\Pi$ , and  $\mathcal{F}_\Pi$  be the family of all unqualified subsets of  $\Pi$ . Define the access structure of  $\Pi$  as  $\Gamma_\Pi \stackrel{\text{def}}{=} \{\mathcal{A}_\Pi, \mathcal{F}_\Pi\}$ . It is obvious that  $\Gamma_\Pi$  is monotone and  $\mathcal{A}_\Pi \cup \mathcal{F}_\Pi = 2^P$ . We say  $\Pi$  realizes  $\Gamma = \{\mathcal{A}, \mathcal{F}\}$  if  $\mathcal{A} \subseteq \mathcal{A}_\Pi, \mathcal{F} \subseteq \mathcal{F}_\Pi$ .

Monotonicity implies that  $\mathcal{A} \cap \mathcal{F} = \emptyset$  for every access structure. It is obvious that if  $\mathcal{A} \cup \mathcal{F} = 2^P$ , then  $\Gamma$  is complete, otherwise  $\Gamma$  is incomplete.

As an access structure must be monotone, we can define the family  $\mathcal{A}^-$  of *minimal* qualified subsets and the family  $\mathcal{F}^+$  of *maximal* unqualified subsets:

$$\begin{cases} \mathcal{A}^- \stackrel{\text{def}}{=} \{A \in \mathcal{A} : \forall P_i \in A, A - \{P_i\} \notin \mathcal{A}\} \\ \mathcal{F}^+ \stackrel{\text{def}}{=} \{F \in \mathcal{F} : \forall P_i \in P - F, F \cup \{P_i\} \notin \mathcal{F}\} \end{cases} \quad (3)$$

$\Gamma_0 = \{\mathcal{A}^-, \mathcal{F}^+\}$  is called the *basis* of  $\Gamma = \{\mathcal{A}, \mathcal{F}\}$ . It is easy to check that there is a unique basis  $\Gamma_0$  corresponding to a given access structure  $\Gamma$ , and vice versa. Thus monotonicity can also be described as below [28]:

**Theorem 1:** ([28])  $\mathcal{A}, \mathcal{F} \subseteq 2^P$  are monotone if and only if it holds that

$$\forall A \in \mathcal{A}^-, F \in \mathcal{F}^+, A \not\subseteq F$$

A SSS realizes  $\Gamma = \{\mathcal{A}, \mathcal{F}\}$  means that any subset  $A \in \mathcal{A}$  is qualified, while any subset  $F \in \mathcal{F}$  is unqualified. A SSS realizes  $\Gamma = \{\mathcal{A}, \mathcal{F}\}$  if and only if:

$$\begin{cases} \forall A \in \mathcal{A}^- : A \text{ is qualified} \\ \forall F \in \mathcal{F}^+ : F \text{ is unqualified} \end{cases} \quad (4)$$

A  $(k, n)$ -threshold scheme is a perfect SSS which realizes the complete  $(k, n)$ -threshold access structure.

The efficiency of a SSS is measured by the term *information rate*. The *information rate* of  $P_i$  is defined as  $\rho_i = H(S_i)/H(S)$ . Since there may be  $n$  different  $\rho_i$  in a SSS, one may define the *average information rate*  $\bar{\rho}$  and *worst information rate*  $\check{\rho}$  respectively:

$$\begin{aligned} \bar{\rho} &\stackrel{\text{def}}{=} \frac{1}{n} \sum_{i=1}^n \rho_i \\ \check{\rho} &\stackrel{\text{def}}{=} \max\{\rho_i, 1 \leq i \leq n\} \end{aligned}$$

### B. Multiple Assignment Schemes

Let  $\Omega = \{w_1, \dots, w_m\}$  be the primitive shares set of a  $(k, m)$ -threshold SSS over  $S$  and  $\psi : P \rightarrow 2^\Omega$  be a map which assigns each participant a subset of  $\Omega$ . For a subset  $X \subseteq P$  of participants, the primitive shares set held by  $X$  is  $\Psi(X) \stackrel{\text{def}}{=} \bigcup_{P_i \in X} \psi(P_i)$ . If there exists a map  $\psi$  s.t.

$$\begin{cases} \forall A \in \mathcal{A}^- : |\Psi(A)| \geq k \\ \forall F \in \mathcal{F}^+ : |\Psi(F)| \leq k - 1 \end{cases} \quad (5)$$

then we can find a perfect SSS realizing  $\Gamma$ . We call the map  $\psi$  a *multiple assignment map*, and the corresponding SSS a *multiple assignment scheme*.

Each primitive share in a  $(k, m)$ -threshold SSS has the same information entropy as the secret. Thus,  $\rho_i, \bar{\rho}, \check{\rho}$  for a multiple assignment scheme can be calculated as follows:

$$\begin{cases} \forall P_i \in P : \rho_i = |\psi(P_i)| \\ \bar{\rho} = \frac{1}{n} \sum_{i=1}^n |\psi(P_i)| \\ \check{\rho} = \max\{|\psi(P_i)|, 1 \leq i \leq n\} \end{cases} \quad (6)$$

In [6], [28], the authors provide a multiple assignment scheme to construct the primitive shares set by using a  $(m, m)$ -threshold SSS. This method can achieve a feasible solution for the integer programming problem [23], [26], [27] and is reviewed below.

**Construction 1:** ([6]) Let  $\mathcal{F}^+ = \{F_1, \dots, F_m\}$  be the family of maximal unqualified subsets of an access structure, and  $\Omega = \{w_1, \dots, w_m\}$  be the primitive shares set of a  $(m, m)$ -threshold SSS. The multiple assignment map  $\psi : P \rightarrow 2^\Omega$  is defined as:

$$\psi(P_i) = \{w_j : P_i \notin F_j; j = 1, \dots, m\}.$$

One can verify that the SSS constructed by Construction 1 realizes the corresponding access structure. Indeed,  $\forall F \in$

$\mathcal{F}, \exists F_j \in \mathcal{F}^+$  such that  $F \subseteq F_j$ , so it follows that  $w_j \notin \Psi(F) = \bigcup_{P_i \in F} \psi(P_i)$ . On the other hand,  $\forall A \in \mathcal{A}$  and  $\forall F_j \in \mathcal{F}^+$ , it holds that  $\exists P_i \in A - F_j$ , so  $w_j \in \psi(P_i)$ , and this means that  $\Psi(A) = \Omega$ .

### C. Optimal Multiple Assignment Schemes

One can construct *optimal multiple assignment schemes* by solving integer programming [23], [26].

We know that,  $\forall 0 < j < 2^n, \exists$  unique  $j_i \in \{0, 1\}, (i = 1, \dots, n)$  such that  $j = \sum_{i=1}^n j_i 2^{i-1}$ . Let  $\Omega_j$  be the set of primitive shares owned by all participants in subset  $X_j \stackrel{\text{def}}{=} \{P_i | j_i = 1, P_i \in P\}$  and denote  $x_j$  as  $|\Omega_j|$ . For subset  $X = \{P_{i_1}, P_{i_2}, \dots, P_{i_l}\} \subseteq P$ , we define  $j_X \stackrel{\text{def}}{=} \bigvee_{k=1}^l j_{i_k}$  where  $\vee$  is the bitwise OR operation. Obviously,  $\Psi(X)$  contains the  $x_j$  primitive shares iff.  $j_X = 1$ . As  $\{\Omega_j | 0 < j < 2^n\}$  is a partition of the primitive shares set  $\Omega$ , we have

$$\begin{cases} \forall P_i \in P : |\psi(P_i)| = \sum_{j_i=1} x_j \\ \forall X \subseteq P : |\Psi(X)| = \sum_{j_X=1} x_j \end{cases} \quad (7)$$

Equation (5) implies that a multiple assignment scheme realizes  $\Gamma = \{\mathcal{A}, \mathcal{F}\}$  iff.

$$\begin{cases} \forall A \in \mathcal{A}^- : \sum_{j_A=1} x_j \geq k \\ \forall F \in \mathcal{F}^+ : \sum_{j_F=1} x_j \leq k - 1 \\ \forall 0 < j < 2^n : x_j \geq 0 \\ k \geq 0 \end{cases} \quad (8)$$

For any given access structure  $\Gamma$ , the primitive shares in the multiple assignment scheme by construction 1 are selected from a  $(m, m)$ -threshold SSS, which gives a feasible solution for constraints (8).

Equation (6) tells us that given  $\Gamma = \{\mathcal{A}, \mathcal{F}\}$ , the problem of finding a multiple assignment scheme with optimal average information rate is equivalent to the following integer programming problem:

$$\begin{aligned} & \text{minimize: } \sum_{i=1}^n \sum_{j_i=1} x_j \\ & \text{s.t:} \\ & \begin{cases} \forall A \in \mathcal{A}^- : \sum_{j_A=1} x_j \geq k \\ \forall F \in \mathcal{F}^+ : \sum_{j_F=1} x_j \leq k - 1 \\ \forall 0 < j < 2^n : x_j \geq 0 \\ k \geq 0 \end{cases} \end{aligned} \quad (9)$$

and the problem of finding a multiple assignment scheme with optimal worst information rate is equivalent to the following

integer programming problem:

$$\begin{aligned} & \text{minimize: } d \\ & \text{s.t:} \\ & \begin{cases} \forall A \in \mathcal{A}^- : \sum_{j_A=1} x_j \geq k \\ \forall F \in \mathcal{F}^+ : \sum_{j_F=1} x_j \leq k - 1 \\ \forall 1 \leq i \leq n : \sum_{j_i=1} x_j \leq d \\ \forall 0 < j < 2^n : x_j \geq 0 \\ k \geq 0, d \geq 0 \end{cases} \end{aligned} \quad (10)$$

### III. MULTIPLE ASSIGNMENT SCHEMES WITH $(m, m)$ -SCHEMES

Every multiple assignment scheme has a unique assignments set  $\{x_j | x_j \geq 0, 0 < j < 2^n\}$  when the scheme is fixed. On the other hand, every set  $\{x_j | x_j \geq 0, 0 < j < 2^n\}$  determines a multiple assignment scheme, and if  $\{x_j | x_j \geq 0, 0 < j < 2^n\}$  satisfies equation (8), then the corresponding multiple assignment scheme realizes the given access structure  $\Gamma = \{\mathcal{A}, \mathcal{F}\}$ .

For any given  $\Gamma = \{\mathcal{A}, \mathcal{F}\}$ , we can obtain the optimal multiple assignment scheme by finding the optimal solution of the IP problems (9) or (10) [23], [26]. The complexity of integer programming is related with the number of variables and the constraints on variables: less variables or more strict constraints on variables will decrease the computing complexity on finding solution of IP. Our coming arguments are towards this.

**Theorem 2:**  $x_{2^n-1}$  must be zero in every optimal solution of IP (9) and (10).

*Proof:* 1)For IP (9): Otherwise, let  $\bar{k}, \bar{x}_j, (0 < j < 2^n, \bar{x}_{2^n-1} > 0)$  be an optimal solution of IP (9). Consider  $k = \bar{k} - \bar{x}_{2^n-1}, x_j = \bar{x}_j, (0 < j < 2^n - 1), x_{2^n-1} = 0$ , it is easy to find that the later is a feasible solution of IP (9) and has a less objective value, which is conflict with the optimality of  $\bar{k}, \bar{x}_j, (0 < j < 2^n, \bar{x}_{2^n-1} > 0)$ .

2)For IP (10): Otherwise, let  $\bar{k}, \bar{d}, \bar{x}_j, (0 < j < 2^n, \bar{x}_{2^n-1} > 0)$  be an optimal solution of IP (10). Consider  $k = \bar{k} - \bar{x}_{2^n-1}, d = \bar{d} - \bar{x}_{2^n-1}, x_j = \bar{x}_j, (0 < j < 2^n - 1), x_{2^n-1} = 0$ , it is easy to find that the later is a feasible solution of IP (10) and has a less objective value, which is conflict with the optimality of  $\bar{k}, \bar{d}, \bar{x}_j, (0 < j < 2^n, \bar{x}_{2^n-1} > 0)$ . ■

Theorem 2 says that there is no primitive shares held by all participants in any optimal multiple assignment schemes.

In some cases, primitive shares must be selected from a  $(m, m)$ -scheme. Next we will focus on this condition. In fact, we can get the optimal multiple assignment scheme from  $(m, m)$ -schemes with minimal average information rate from

IP (11):

$$\begin{aligned} & \text{minimize: } \sum_{i=1}^n \sum_{j_i=1} x_j \\ & \text{s.t:} \\ & \left\{ \begin{array}{l} \forall A \in \mathcal{A}^- : \sum_{j_A=1} x_j = m \\ \forall F \in \mathcal{F}^+ : \sum_{j_F=1} x_j \leq m-1 \\ m = \sum_{j=1}^{2^n-1} x_j \\ \forall 0 < j < 2^n : x_j \geq 0 \end{array} \right. \end{aligned} \quad (11)$$

Also, optimal multiple assignment scheme with  $(m, m)$ -schemes with minimal worst information rate can be constructed from IP (12):

$$\begin{aligned} & \text{minimize: } d \\ & \text{s.t:} \\ & \left\{ \begin{array}{l} \forall A \in \mathcal{A}^- : \sum_{j_A=1} x_j = m \\ \forall F \in \mathcal{F}^+ : \sum_{j_F=1} x_j \leq m-1 \\ \forall 1 \leq i \leq n : \sum_{j_i=1} x_j \leq d \\ m = \sum_{j=1}^{2^n-1} x_j \\ \forall 0 < j < 2^n : x_j \geq 0 \end{array} \right. \end{aligned} \quad (12)$$

Obviously, IP (11) and (12) have same constraints (13):

$$\left\{ \begin{array}{l} \forall A \in \mathcal{A}^- : \sum_{j_A=1} x_j = m \\ \forall F \in \mathcal{F}^+ : \sum_{j_F=1} x_j \leq m-1 \\ m = \sum_{j=1}^{2^n-1} x_j \\ \forall 0 < j < 2^n : x_j \geq 0 \end{array} \right. \quad (13)$$

Let  $\wedge$  be the bitwise AND operation, then we have:

**Theorem 3:** For every feasible solution satisfying constraints (13), the following holds:

$$\left\{ \begin{array}{l} \forall 0 < j < 2^n : \bigwedge_{A \in \mathcal{A}^-} j_A = 0 \Rightarrow x_j = 0 \\ \forall F \in \mathcal{F}^+ : \sum_{j_F=0} x_j \geq 1 \\ \forall 0 < j < 2^n : x_j \geq 0 \end{array} \right. \quad (14)$$

On the other hand, every solution satisfying constraints (14) will also satisfy constraints (13). In others words, constraints (13) are equal to constraints (14).

*Proof:* 1) We first prove: If  $x_j, (0 < j < 2^n)$  satisfy constraints (14), then constraints (13) hold.

1.1):  $\forall A \in \mathcal{A}^- : \sum_{j_A=1} x_j = m$ . From  $\forall 0 < j < 2^n :$

$\bigwedge_{A \in \mathcal{A}^-} j_A = 0 \Rightarrow x_j = 0$ . we get the result:  $m = \sum_{j=1}^{2^n-1} x_j = \sum_{A \in \mathcal{A}^-} \sum_{j_A=1} x_j$ . Obviously,  $\forall A \in \mathcal{A}^- : \bigwedge_{A \in \mathcal{A}^-} j_A = 1 \Rightarrow \bigwedge_{A \in \mathcal{A}^-} j_A = 1$ , but  $\forall 0 < j < 2^n : x_j \geq 0$ , so  $m = \sum_{A \in \mathcal{A}^-} \sum_{j_A=1} x_j \leq$

$$\sum_{j_A=1} x_j \leq \sum_{j=1}^{2^n-1} x_j = m$$

1.2):  $\forall F \in \mathcal{F}^+ : \sum_{j_F=1} x_j \leq m-1$ . Because  $j_X$  is either 0 or 1 for every subset  $X \subseteq P$ , we have  $\forall F \in \mathcal{F}^+ : \sum_{j_F=1} x_j +$

$\sum_{j_F=0} x_j = \sum_{j=1}^{2^n-1} x_j$  then  $\forall F \in \mathcal{F}^+ : \sum_{j_F=0} x_j \geq 1$  is equal to  $\forall F \in \mathcal{F}^+ : \sum_{j_F=1} x_j \leq m-1$

2) Now we will prove: If  $x_j, (0 < j < 2^n)$  satisfy constraints (13), then constraints (14) hold.

2.1):  $\forall 0 < j < 2^n : \bigwedge_{A \in \mathcal{A}^-} j_A = 0 \Rightarrow x_j = 0$ .

Otherwise, there is a  $\bar{j}, (0 < \bar{j} < 2^n)$  and a subset  $A \in \mathcal{A}^-$  such that  $x_{\bar{j}} \geq 1, \bar{j}_A = 0$ , but this means

$$\sum_{j_A=1} x_j \leq \sum_{j \neq \bar{j}} x_j = m - x_{\bar{j}} \leq m-1$$

2.2):  $\forall F \in \mathcal{F}^+ : \sum_{j_F=0} x_j \geq 1$ .

We have just proved this in 1.2). ■

From Theorem 3, if  $\bigwedge_{A \in \mathcal{A}^-} j_A = 0$ , then  $x_j$  will be zero.

This means that we can delete all these  $x_j$ s from the integer programming and thus decrease the complexity. We can also obtain more strict constraints on the remaining  $x_j$ s in the following theorem.

**Theorem 4:** If  $\bar{x}_j, (0 < j < 2^n, \bar{x}_{\bar{j}} \geq 2)$  is a feasible solution satisfying constraints (14), then  $x_j = \bar{x}_j, (0 < j \neq \bar{j} < 2^n), x_{\bar{j}} = 1$  is another feasible solution satisfying constraints (14). Furthermore,  $\rho_i, (P_i \in P), \bar{\rho}, \bar{\rho}$  for the later solution are not greater than those for the former solution, respectively.

*Proof:* It's easy to check that  $x_j = \bar{x}_j, (0 < j \neq \bar{j} < 2^n), x_{\bar{j}} = 1$  is another feasible solution satisfying constraints (14). If we denote  $f_i$  as the number of primitive shares held by  $P_i$  in the former solution and  $g_i$  the number of primitive shares held by  $P_i$  in the later solution, then we have

$$f_i - g_i = \begin{cases} 0 & \bar{j}_i = 0 \\ \bar{x}_{\bar{j}} - 1 \geq 1 & \bar{j}_i = 1 \end{cases} \quad (15)$$

which means  $\rho_i$  for the later solution is less than or equal to the one for the former solution. From the definition of  $\bar{\rho}, \bar{\rho}$ , we complete the proof. ■

Theorem 4 says that integer programming for finding optimal multiple assignment schemes with  $(m, m)$ -schemes can be reduced to 0-1 programming. In other words, the constraints (14) can be changed to the constraints (16):

$$\left\{ \begin{array}{l} \forall 0 < j < 2^n : \bigwedge_{A \in \mathcal{A}^-} j_A = 0 \Rightarrow x_j = 0 \\ \forall F \in \mathcal{F}^+ : \sum_{j_F=0} x_j \geq 1 \\ \forall 0 < j < 2^n : x_j \in \{0, 1\} \end{array} \right. \quad (16)$$

#### IV. MULTIPLE ASSIGNMENT SCHEMES WITH $(m, m)$ -SCHEMES FOR COMPLETE ACCESS STRUCTURE

We now consider multiple assignment schemes from  $(m, m)$ -schemes for complete access structure. Surprisingly, we can get an optimal scheme without solving the 0-1 programming. This is expressed as follows.

First,  $\forall S \subseteq P$ , denote  $j(S) = \sum_{i=1}^n j_{(i,S)} 2^{i-1}$  where

$$j_{(i,S)} = \begin{cases} 0 & P_i \in S \\ 1 & P_i \in P - S. \end{cases}$$

**Theorem 5:** Let  $\{\mathcal{A}^-, \mathcal{F}^+\}$  be the basis for a complete access structure, then the equation (16) leads to constraints (17):

$$\forall F \in \mathcal{F}^+, x_{j(F)} = 1 \quad (17)$$

*Proof:*  $\forall F \in \mathcal{F}^+$ , primitive shares not owned by participants in  $F$  must be owned by all participants in  $P - F$ . Otherwise, suppose  $P_i \in P - F$  does not own some primitive shares which are not owned by participants in  $F$ , then this shares are not owned by participants in  $F \cup \{P_i\}$ , and this means that  $F \cup \{P_i\}$  is an unqualified subset, but this is contradictory with  $F \in \mathcal{F}^+$ . Up to now, we proved that if  $P_i \in P - F, j_i = 0$ , then  $x_j = 0$ . On the other hand, from  $\forall F \in \mathcal{F}^+ : \sum_{j \in F} x_j \geq 1$  and  $\forall 0 < j < 2^n : x_j \in \{0, 1\}$ , It follows that if  $F \in \mathcal{F}^+$  then  $x_{j(F)} = 1$ . ■

Set

$$x_j = \begin{cases} 1 & \exists F \in \mathcal{F}^+ \text{ such that } j = j(F) \\ 0 & \text{others.} \end{cases} \quad (18)$$

Theorem 5 tells us that solution assigned by (18) is a feasible solution to constraints (16). Furthermore, for every participant  $P_i \in P$  there is no solution satisfying constraints (16) such that: the number of primitive shares owned by  $P_i$  in this solution is less than the one in solution assigned by (18). In other words, solution assigned by (18) is optimal for every participant  $P_i \in P$ . As a result, this solution achieves the minimal  $\rho_i, (P_i \in P), \bar{\rho}, \check{\rho}$ . Note that the solution assigned by (18) is the same as that by [6].

## V. CONCLUSION

We consider multiple assignment schemes with  $(m, m)$ -schemes in this paper. Our contributions are two-fold: 1) most variables in the corresponding integer programming in such a case will be vanished, and the remaining variables take the value of either 0 or 1; 2) when the access structure is complete, then the optimal scheme can be constructed directly by the method [6]. One open problem is to simplify the 0-1 programming for non-complete access structure.

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