

# A Novel High-performance Implementation of CRYSTALS-Kyber with AI Accelerator

Lipeng Wan<sup>1,2,3</sup>, Fangyu Zheng<sup>1,3,\*</sup> (✉), Guang Fan<sup>1,2,3</sup>, Rong Wei<sup>1,2,3</sup>, Lili Gao<sup>1,2,3</sup>, Yuewu Wang<sup>1,2,3</sup>, Jingqiang Lin<sup>4</sup>, and Jiankuo Dong<sup>5</sup>

<sup>1</sup> State Key Laboratory of Information Security, Institute of Information Engineering, Chinese Academy of Sciences, Beijing, China

<sup>2</sup> School of Cyber Security, University of Chinese Academy of Sciences, Beijing, China

<sup>3</sup> Data Assurance and Communication Security Research Center, Chinese Academy of Sciences, Beijing, China

<sup>4</sup> School of Cyber Security, University of Science and Technology of China, Hefei, China

<sup>5</sup> School of Computer Science, Nanjing University of Posts and Telecommunications, Nanjing, China

**Abstract.** Public-key cryptography, including conventional cryptosystems and post-quantum cryptography, involves computation-intensive workloads. With noticing the extraordinary computing power of AI accelerators, in this paper, we further explore the feasibility to introduce AI accelerators into high-performance cryptographic computing. Since AI accelerators are dedicated to machine learning or neural networks, the biggest challenge is how to transform cryptographic workloads into their operations, while ensuring the correctness of the results and bringing convincing performance gains.

After investigating and analysing the workload of NVIDIA AI accelerator, Tensor Core, we choose to utilize it to accelerate the polynomial multiplication, usually the most time-consuming part in lattice-based cryptography. We take measures to accommodate the matrix-multiply-and-add mode of Tensor Core and make a trade-off between precision and performance, to leverage it as a high-performance NTT box performing NTT/INTT through CUDA C++ WMMA APIs. Meanwhile, we take CRYSTALS-Kyber, the candidate to be standardized by NIST, as a case study on RTX 3080 with the Ampere Tensor Core. The empirical results show that the customized NTT of polynomial vector ( $n = 256, k = 4$ ) with our NTT box obtains a speedup around 6.47x that of the state-of-the-art implementation on the same GPU platform. Compared with the AVX2 implementation submitted to NIST, our Kyber-1024 can achieve a speedup of 26x, 36x, and 35x for each phase.

**Keywords:** Lattice-Based Cryptography · Polynomial Multiplication Over Rings · NTT · AI accelerator · Tensor Core · Kyber.

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\* Fangyu Zheng is the corresponding author (E-mail: [zhengfangyu@iie.ac.cn](mailto:zhengfangyu@iie.ac.cn))

## 1 Introduction

Quantum computing and Shor’s algorithm [31] have raised concern about the security of conventional public-key schemes, such as widely used RSA and ECDSA. A new class of cryptosystems with anti-quantum property, which is known as post-quantum cryptography (PQC, sometimes referred to as quantum-proof, quantum-safe, or quantum-resistant), is in urgent need. To this end, National Institute of Standards and Technology (NIST) has initiated a process to solicit, evaluate, and standardize one or more quantum-resistant public-key cryptographic algorithms in 2017 [24].

The security of quantum-resistant schemes is based on different mathematical hard problems, while the lattice-based hardness is the most prevailing one. On the other hand, performance is an important metric in the evaluation, and thus many research efforts are made to improve the efficiency of lattice-based cryptography (LBC). Generally speaking, for the cryptographic schemes based on lattice related problem, such as Ring-LWE [18], Module-LWE [6,16], and Module-LWR [3], polynomial multiplication (over the ring  $R_q$ ) and hash functions are the time-consuming parts. The hash functions mainly involve bit operations, which can be accelerated by the commercial off-the-shelf products with processor-aided accelerations (e.g., SHA extension in Intel and ARM CPU [28]). In this way, the principal efforts in LBC acceleration focus on the polynomial multiplication.

There are many methods to accelerate the polynomial multiplication. Apart from adopting the Karatsuba [15] and Toom-Cook algorithms [32], the more prevailing practice is to exploit Number Theoretic Transform (NTT) for the case  $n|(q-1)$ , where  $q$  is the modulus and  $n$  is the dimension. CRYSTALS-Kyber [5,29], Kyber for short, the candidate to be standardized by NIST PQC [22], even integrates a customized NTT into its algorithms to improve the efficiency.

Meanwhile, many solutions have been proposed for the specific platforms to make full use of the hardware features and get better achievable performance. Taking the advantage of vector instructions, Lyubashevsky *et al.* [19] presented an AVX2 optimized NTT and applies it to NTRU. Similarly, Seiler [30] implemented NewHope with AVX2 optimized NTT. With the help of many-thread parallelism and high throughput of GPU (precisely, CUDA core), Gupta *et al.* [12] implemented three different classes of post-quantum algorithms on NVIDIA Tesla V100. The main optimized technique of the work [12] is to reorganize the data storage sequence to facilitate continuous memory access. Gao *et al.* [10] also improved the performance of NewHope on NVIDIA MX150 and GTX1650. As for the resource-constrained devices, the proposed solutions might be more dedicated. Thanks to the flexibility of FPGA in programming, Xing and Li [34] presented a compact hardware implementation of Kyber on FPGA with many customized optimizations from the perspective of hardware. And Greconic *et al.* [11] presented implementations of the lattice-based digital signature scheme Dilithium for ARM Cortex-M3 and ARM Cortex-M4.

On the other hand, many manufacturers have designed high-performance AI (artificial intelligence) accelerators, such as Google TPU [8], Apple M1 [13], and NVIDIA Tensor Core [14], to meet the needs of AI applications. Compared with other general-purpose processors, AI accelerator generally focuses on low-precision arithmetic, novel data-flow architectures, or in-memory computing capability, and often has extremely stronger computing power. For instance, NVIDIA has claimed that Tesla V100’s Tensor Cores can deliver up to 125 Tensor TFLOPS for training and inference applications. And NVIDIA Jetson Xavier NX brings supercomputer performance up to 21 TOPS while the power is up to 15W. However, little research has been proposed on how to apply this kind of accelerators to other fields such as high-performance cryptographic computing. Our previous work [33] exploits Volta Tensor Core for byte-level modulus scheme LAC [17], but it does not involve module-lattice and NTT, which are more widely used.

The primary motivation of this paper is to bring the extraordinary computing power of the AI accelerator to the area of cryptographic acceleration. Since AI accelerators are dedicated to machine learning or neural networks, the biggest challenge is how to transform cryptographic operations into their workloads, while ensuring the correctness of the results and bringing convincing performance gains. The contributions of our work are as follows:

- Firstly, our work forms a framework for an AI accelerator to accelerate module-lattice based cryptography. Through this framework, we can efficiently convert the workload of cryptographic primitives into the operation of the AI accelerator.
- Secondly, we present an NTT box based on NVIDIA AI accelerator, Tensor Core, under the proposed framework. The NTT box is efficient to perform NTT/INTT, especially when the dimension  $n$  is relatively small.
- Finally, we evaluate the novel proposed method for Kyber, a well-known PQC scheme, as a case study. To the best of our knowledge, it is the first attempt at implementing Kyber with an AI accelerator. Compared with the state-of-the-art implementation, our *polyvec-ntt* in Kyber can obtain a speedup of 6.47x on the same GPU platform.

## 2 Preliminary

In this section, we give a basic background of Kyber, NTT and Tensor Core.

### 2.1 Notation & Definition

**Notation.** For a prime  $q$ ,  $\mathbb{Z}_q = \{0, 1, \dots, q-1\}$  is the residue class ring modulo  $q$ . Define the ring  $R_q = \mathbb{Z}_q[x]/(x^n + 1)$ , which means the coefficients are from  $\mathbb{Z}_q$ .  $\mathbb{Z}_q^n$  represents  $n$  coefficients from  $\mathbb{Z}_q$ . Regular font letters denote elements in  $R_q$  (which includes elements in  $\mathbb{Z}_q$ ) and bold lower-case letters represent vectors with coefficients in  $R_q$ . By default, all vectors will be column vectors. Bold upper-case letters are matrices. For a vector  $\mathbf{v}$  (or matrix  $\mathbf{A}$ ),  $\mathbf{v}^T$  (or  $\mathbf{A}^T$ ) means its

transpose, and  $\mathbf{v}[i]$  denotes its  $i$ -th entry (with indexing starting at zero). For a matrix  $\mathbf{A}$ ,  $\mathbf{A}[i][j]$  denotes the entry in row  $i$ , column  $j$  (again, with indexing starting from zero). The rank  $k$  represents that a polynomial vector contains  $k$  polynomials, and a matrix contains  $k \times k$  polynomials. For a finite field  $F = \mathbb{Z}_q$ , the primitive  $n$ -th root  $\omega$  of unity exist whenever  $n|(q-1)$ , where  $\omega^n \equiv 1 \pmod{q}$ .

**Module-LWE.** A lattice is the set of all integer linear combinations of some linearly independent vectors belonging to the euclidean space. Most lattice-based cryptographic schemes are built upon the assumed hardness of the Short Integer Solution (SIS) [1] and Learning With Errors (LWE) [27] problems. The LWE problem was popularized by Regev [27] who showed that solving a random LWE instance is as hard as solving certain worst-case instances of certain lattice problems. This assumption states that it is hard to distinguish the uniform distribution from  $(\mathbf{A}, \mathbf{A}\mathbf{s} + \mathbf{e})$ , where  $\mathbf{A}$  is a uniformly-random matrix in  $\mathbb{Z}_q^{n \times n}$ ,  $\mathbf{s}$  is a uniformly-random vector in  $\mathbb{Z}_q^n$ , and  $\mathbf{e}$  is chosen from some distribution. Later, Lyubashevsky *et al.* [18] introduced a similar adaptation for LWE, called Ring-LWE, which showed that it is also hard to distinguish a variant of the LWE distribution from the uniform one over certain polynomial rings. Combining the security advantages of LWE and the flexibility of Ring-LWE, Langlois *et al.* [16] demonstrated the worst-case to average-case reductions for module lattices. Intuitively, the size of matrix  $\mathbf{A}$  in Module-LWE is  $k \times k$ , where  $k$  is the rank. The elements in the matrix are vectors selected from  $\mathbb{Z}_q^n$ .

## 2.2 Description of CRYSTALS-Kyber

Kyber is an IND-CCA2-secure post-quantum key exchange mechanism. The security of Kyber is based on the hardness of solving the LWE problem in module lattices.

The submission to NIST PQC [25] lists three different parameter sets, Kyber-512, Kyber-768, and Kyber-1024, aiming at different security levels roughly equivalent to AES-128, AES-192, and AES-256, respectively. The parameters are listed in Table 1, where  $\eta_1$  and  $\eta_2$  are the parameters of centered binomial distribution (CBD).

Table 1: Parameter sets for Kyber version 3

	$n$	$k$	$q$	$\eta_1$	$\eta_2$
Kyber-512	256	2	3329	3	2
Kyber-768	256	3	3329	2	2
Kyber-1024	256	4	3329	2	2

The key generation, encryption, and decryption are described in Algorithm 1, 2, and 3. In the **KeyGen** phase,  $d$  is a random number,  $\rho$  and  $\sigma$  are fixed-length intermediate variables generated by  $d$  through hash function  $G$ . The

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**Algorithm 1** KYBER.CPAPKE.KeyGen(): key generation

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**Ensure:** Secret key  $sk$ , Public key  $pk$ .

- 1:  $d \leftarrow \mathbf{Random}()$
- 2:  $(\rho, \sigma) := G(d)$
- 3:  $\hat{\mathbf{A}} \leftarrow \mathit{Gen\_matrix\_A}(\rho)$ ,  $\hat{\mathbf{A}} \in R_q^{k \times k}$  in NTT domain
- 4:  $\mathbf{s} \leftarrow \mathit{Sample\_s}(\sigma)$ ,  $\mathbf{s} \in R_q^k$  from  $B_{\eta_1}$
- 5:  $\mathbf{e} \leftarrow \mathit{Sample\_e}(\sigma)$ ,  $\mathbf{e} \in R_q^k$  from  $B_{\eta_1}$
- 6:  $\hat{\mathbf{s}} := \mathit{NTT}(\mathbf{s})$
- 7:  $\hat{\mathbf{e}} := \mathit{NTT}(\mathbf{e})$
- 8:  $\hat{\mathbf{t}} := \hat{\mathbf{A}} \circ \hat{\mathbf{s}} + \hat{\mathbf{e}}$
- 9: **return**  $pk := \mathit{Encode}(\hat{\mathbf{t}}||\rho)$ ,  $sk := \mathit{Encode}(\hat{\mathbf{s}})$

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parameter  $\hat{\mathbf{A}}$  is a  $k \times k$  polynomial matrix generated by  $\rho$ . The parameters  $\mathbf{s}$  and  $\mathbf{e}$  are polynomial vectors generated through different sample functions but same distribution  $B_{\eta_1}$ . The final parameters need to be compressed and encode. In the

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**Algorithm 2** KYBER.CPAPKE.Enc(): encryption

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**Require:** Public key  $pk$ , Message  $m$ , Random seed  $r$

**Ensure:** Ciphertext  $c$

- 1:  $(\hat{\mathbf{t}}, \rho) \leftarrow \mathit{Decode}(pk)$
- 2:  $\hat{\mathbf{A}}^T \leftarrow \mathit{Gen\_matrix\_A^T}(\rho)$ ,  $\hat{\mathbf{A}}^T \in R_q^{k \times k}$  in NTT domain
- 3:  $\mathbf{r} \leftarrow \mathit{Sample\_r}(r)$ ,  $\mathbf{r} \in R_q^k$  from  $B_{\eta_1}$
- 4:  $\mathbf{e}_1 \leftarrow \mathit{Sample\_e_1}(r)$ ,  $\mathbf{e}_1 \in R_q^k$  from  $B_{\eta_2}$
- 5:  $e_2 \leftarrow \mathit{Sample\_e_2}(r)$ ,  $e_2 \in R_q$  from  $B_{\eta_2}$
- 6:  $\hat{\mathbf{r}} := \mathit{NTT}(\mathbf{r})$
- 7:  $\mathbf{u} := \mathit{NTT}^{-1}(\hat{\mathbf{A}} \circ \hat{\mathbf{r}}) + \mathbf{e}_1$
- 8:  $v := \mathit{NTT}^{-1}(\hat{\mathbf{t}}^T \circ \hat{\mathbf{r}}) + e_2 + \mathit{Decompress}(m)$
- 9: **return**  $c_1 := \mathit{Encode}_u(\mathbf{u})$ ,  $c_2 := \mathit{Encode}_v(v)$

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Enc phase, the public key  $pk$  will be decoded first. Here, we need to emphasize that  $e_2$  and  $v$  are polynomials rather than vectors. The ciphertext  $c$  consists of two parts:  $c_1$  and  $c_2$ , which are obtained from  $\mathbf{u}$  and  $v$  with different encode. Correspondingly, in the Dec phase, these two parts need to be decoded with different functions first. Then the NTT and the subsequent INTT are performed.

### 2.3 Number Theoretic Transform

In general, Number Theoretic Transform (NTT) is one of the most prevailing approaches to improve polynomial multiplication over the ring. Simplemindedly, NTT is the finite field form of discrete Fourier transform (DFT), which transforms a sequence of  $n$  numbers  $\mathbf{v} := \{v_0, v_1, \dots, v_{n-1}\}$  into another sequence

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**Algorithm 3** KYBER.CPAPKE.Dec(): decryption

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**Require:** Secret key  $sk$ , Ciphertext  $c$ **Ensure:** Message  $m$ 1:  $\mathbf{u} := \text{Decode}_u(c)$ 2:  $v := \text{Decode}_v(c)$ 3:  $\hat{\mathbf{s}} := \text{Decode}(sk)$ 4: **return**  $m := \text{Compress}(v - NTT^{-1}(\hat{\mathbf{s}} \circ NTT(\mathbf{u})))$ 

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numbers  $\mathbf{X} := \{X_0, X_1, \dots, X_{n-1}\}$ . That can be defined by:

$$X_k = \sum_{j=0}^{n-1} v_j \cdot \omega^{jk} \quad (1)$$

where  $\omega$  is a primitive  $n$ -th root of unity, namely,  $\omega^n \equiv 1 \pmod{q}$ . The inverse transform (INTT) is given as:

$$v_j = n^{-1} \sum_{k=0}^{n-1} X_k \cdot \omega^{-jk} \quad (2)$$

$n^{-1}$  denotes the inverse of  $n$ , where  $n \cdot n^{-1} \equiv 1 \pmod{q}$ .

The fast NTT is based on the idea of divide and conquer, similar to fast Fourier transform (FFT) [9], and can perform the polynomial multiplication with the complexity of  $O(n \log n)$ . However, in practice, the usage of fast NTT can achieve acceleration only when  $n$  is relatively large.

**NTT-based multiplication.** Generally, NTT-based multiplication needs  $q \equiv 1 \pmod{n}$  to ensure the existence of the  $n$ -th roots of unity, where  $n$  is a power of 2. In a finite field, the NTT multiplication of two vectors  $\mathbf{a}$  and  $\mathbf{b}$  needs to append  $n$  zeros to each vector. Then, the product can be obtained by:

$$\mathbf{c} = INTT(NTT(\mathbf{a}_{padding}) \cdot NTT(\mathbf{b}_{padding})) \quad (3)$$

The zero-padding can be avoided to perform NTT-based polynomial multiplication over the ring  $\mathbb{R}_q = \mathbb{Z}_q/f(x)$ , with the well-known negative wrapped convolution (NWC). However, the NWC requires the existence of the  $2n$ -th roots of unity, namely,  $q \equiv 1 \pmod{2n}$ .

## 2.4 Fast Modular Reduction

It is necessary to conduct modular reduction for the product of two coefficients or the sum of several products. The native module operation ‘%’ is expensive, even if it might be optimized at the low level of the computer, but that is unspecified. In practice, fast modular reductions like Montgomery reduction [21], and Barrett reduction [4] are utilized, sometimes along with a lazy strategy which means that the reduction is done only before overflow.

**Montgomery reduction.** Montgomery reduction [21] allows modular arithmetic to be performed efficiently when the modulus is large. Let  $N$  be a positive integer, and let  $R$  and  $T$  be integers such that  $R > n$ ,  $\gcd(n, R) = 1$ , and  $0 \leq T < NR$ . The Montgomery reduction of  $T \bmod q$  with respect to  $R$  is defined as the value  $TR^{-1} \bmod q$ , where  $R$  is a power of 2 and  $R^{-1}$  is the modular inverse of  $R$ . The calculation steps could be as (4).

$$\begin{aligned} m &:= (T \bmod R)k \bmod R, \\ t &:= (T + mN)/R \end{aligned} \tag{4}$$

if  $t \geq N$  return  $t - N$  else return  $t$ .

where  $k = \frac{R(R^{-1} \bmod N) - 1}{N}$ . Note that  $R$  is usually a power of 2, and multiplications and integer divides can be realized by shift, which is cheap.

**Barrett reduction.** Barrett reduction is another reduction algorithm introduced in 1986 by P.D. Barrett [4] to eliminate division operation in computer.

Let  $s = 1/q$  be the inverse of  $q$  as a floating point number. Then

$$T \bmod q = T - \lfloor Ts \rfloor q$$

where  $\lfloor \cdot \rfloor$  denotes the floor function. Barrett reduction approximates  $1/q$  with a value  $m/2^k$  where  $m = 2^k/q$ . Then the reduction can be converted into (5) and becomes cheap. Since  $\lfloor 2^k/q \rfloor$  can be pre-computed, and dividing  $T$  by  $2^k$  is just a right-shift.

$$T \bmod q = T - \lfloor T/2^k \rfloor \lfloor 2^k/q \rfloor \cdot q \tag{5}$$

## 2.5 AI Accelerator and Tensor Core

**AI accelerator.** Due to the explosive growth of AI applications, general-purpose processors are hard to meet the needs of machine learning. Therefore, a dedicated AI accelerator, an application-specific integrated circuit with a more specific design, may gain far more efficiency. The well-known AI accelerators include Google TPU, Apple M1, M1 MAX, M1 Pro, and ARM NPU. These accelerators mainly focus on optimized memory use and lower precision arithmetic to accelerate calculation and increase the throughput.

**Tensor Core.** In December 2017, NVIDIA released the 1st generation Tensor Core (on Volta architecture) which is just for tensor calculations. Tensor Cores are designed to carry 64 GEMMs (General Matrix Multiplication) per clock cycle on  $4 \times 4$  matrices, containing FP16 values (16-bit floating-point numbers) or FP32 (the *float* format). A year later, NVIDIA launched the Turing architecture Tensor Core which has been updated to support other data formats, such as INT8 (8-bit integer values). In the latest Ampere architecture, NVIDIA has improved the performance (256 GEMMs per cycle, up from 64), and added further data formats, shown in Table 2.

Compared with other AI accelerators, Tensor Core exposes interfaces at different levels and has some flexibility in its programming. CUDA has provided several tools to leverage Tensor Core, including library cuBLAS and cuDNN, and CUDA C++ WMMA (Warp Matrix Multiply Accumulate) API.

Table 2: Precision Supported by Multiple Generations of Tensor Core

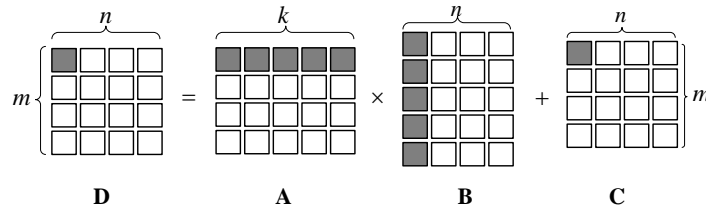
	Volta	Turing	Ampere
<b>Precision</b>	<i>FP16</i>	<i>FP16, INT8, INT4, INT1</i>	<i>FP64, TF32, bfloat16, FP16, INT8, INT4, INT1</i>

### 3 Design

In this section, we analyze the workload of Tensor Core at first, then demonstrate the transformation from cryptographic primitives to operation of Tensor Core. Finally, we illustrate the trade-off between performance and precision.

#### 3.1 Analysis of Tensor Core Dedicated Workload

**Warp level matrix operation.** Up to now, Tensor Core can only support operations at the warp level, usually 32 threads. The warp matrix function requires co-operation from all threads in the warp, and perform  $\mathbf{D} = \mathbf{A} \times \mathbf{B} + \mathbf{C}$ , where  $\mathbf{A}$ ,  $\mathbf{B}$ ,  $\mathbf{C}$ ,  $\mathbf{D}$  are matrices with specific size, as shown in Fig. 1.

Fig. 1: A warp-level  $m$ - $n$ - $k$  matrix operation

It is further complicated by threads holding only a fragment (a type of opaque architecture-specific ABI data structure) of the overall matrix, with the developer not allowed to make assumptions on how the individual parameters are mapped to the registers participating in the matrix multiply-accumulate. There are also some restrictions on matrix size. Generally,  $k$  is fixed to 16, and  $m$  can be 8, 16, or 32 ( $n$  corresponds to 32, 16, or 8).

**FMA operation.** Meanwhile, Tensor Core performs FMA mixed-precision operation, which means low-precision input and high-precision output, described in Fig. 2. For example, on the Ampere architecture, the input can be INT8 (*char*) and the output can be INT32 (*int*). Table 3 represents the various combinations of element types of input matrices and input/output accumulators.



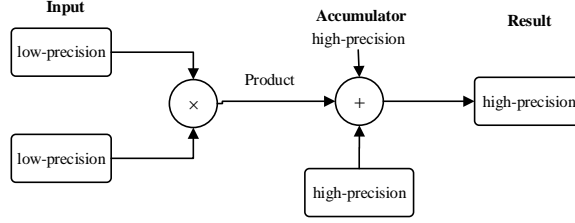


Fig. 2: Tensor Core mixed-precision operation

Table 3: Precision combinations supported by Tensor Core

<b>Matrix A</b>	<i>FP16</i>	<i>unsigned char</i>	<i>signed char</i>	<i>bfloat16</i>	<i>TF32</i>	<i>FP64</i>
<b>Matrix B</b>	<i>FP16</i>	<i>unsigned char</i>	<i>signed char</i>	<i>bfloat16</i>	<i>TF32</i>	<i>FP64</i>
<b>Accumulator C and D</b>	<i>FP32</i>	<i>INT32</i>	<i>INT32</i>	<i>FP32</i>	<i>FP32</i>	<i>FP64</i>

### 3.2 Transformation from Cryptographic Workload to Tensor Core Dedicated Operation

**NTT in Kyber.** Similar to NewHope-Compact [2], Kyber reduces its modulus from 12289 to 3329, which naturally improves the efficiency. The security strength is regulated by the rank  $k$  with a fixed dimension  $n = 256$ . However, this means the  $2n$ -th roots do not exist and the negative wrapped convolution is not applicable. On the contrary, Kyber absorbs the idea like the Chinese Remainder Theorem (CRT) for the modular polynomial, formally,  $\mathbb{Z}_q/(f(x) \cdot g(x)) \cong \mathbb{Z}_q/f(x) \times \mathbb{Z}_q/g(x)$ , and integrates the customized NTT in its algorithm to reduce conversion between different domains.

The defining polynomial  $(X^{256} + 1)$  factors into 128 polynomials of degree 2 modulo  $q$ , and can be written as

$$X^{256} + 1 = \prod_{i=0}^{127} (X^2 - \zeta^{2i+1}) = \prod_{i=0}^{127} (X^2 - \zeta^{2\mathbf{br}_7(i)+1})$$

where  $\mathbf{br}_7(i)$  for  $i = 0, 1, \dots, 127$  is the bit reversal of the unsigned 7-bit integer  $i$ . Therefore, the NTT of a polynomial  $f \in R_q$  is a vector of 128 polynomials of degree 1, and can be written as

$$NTT(f) = \hat{f} = (\hat{f}_0 + \hat{f}_1 X, \hat{f}_2 + \hat{f}_3 X, \dots, \hat{f}_{254} + \hat{f}_{255} X)$$

with

$$\hat{f}_{2i} = \sum_{j=0}^{127} f_{2j} \zeta^{(2\mathbf{br}_7(i)+1)j} \quad (6)$$

$$\hat{f}_{2i+1} = \sum_{j=0}^{127} f_{2j+1} \zeta^{(2\mathbf{br}_7(i)+1)j} \quad (7)$$

where  $\zeta$  is the 256-th root of unity. The powers of  $\zeta$  are also called twiddle factors. It is stressed that even though  $\hat{f}$  is written as a polynomial in  $R_q$ , it has no algebraic meaning as such.

**Computing NTT with matrix operation.** The prevailing strategy of performing polynomial multiplication with NTT is to adopt the divide and conquer method. However, in practice, this approach has an advantage only when  $n$  is large enough. Moreover, it needs to manipulate each coefficient iteratively, which conflicts with the matrix operating mode.

As aforementioned, Kyber exploits a customized NTT in its algorithms like Equation (6) and (7). In fact, only  $n/2$  coefficients of a vector are really involved in an NTT result. In addition, frequent interruptions during in-memory computing to access external memory will seriously increase the delay of the program. Based on the above observations, we decide to adopt a straightforward routine combined with techniques such as pre-computation. We assemble several polynomials that need to be processed into a matrix (Matrix **A**) and place the twiddle factors into another one (Matrix **B**). The computing mode we adopt is shown in Fig. 3. In this way, this computing model can make full use of SIMT (Single Instruction Multiple Threads) to perform NTT on multiple polynomials at once.

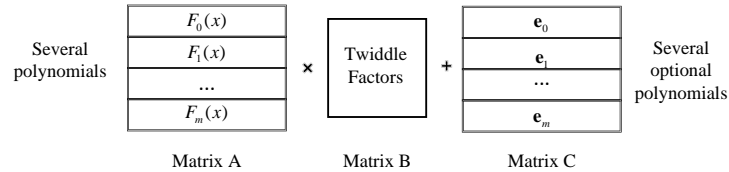


Fig. 3: The computing mode adopted

### 3.3 The Multiple Precision Representation

As mentioned in Table 3, Ampere Tensor Core can support several precision combinations. We test the performance of different precision on NVIDIA RTX 3080 and list the results in Table 4. Generally speaking, lower precision often corresponds to higher computing speed. The choice of data type in cryptographic algorithm should be based on its accurate representation range and performance. For example, the bit length to exactly represent modulus  $q = 3329$  (12289) is 12 (14). Then, only the mantissa of FP64 (*double*), which is 52 bits, can cover the case. However, the speed would be particularly slow. To this end, we suggest exploiting multiple-precision representation to make a trade-off, namely, using two or more lower-precision elements to represent a coefficient.

In the case study of Kyber, we split a 12-bit coefficient into two 6-bit parts represented by INT8. Because the performance of INT8 is much higher than that of other floating-point types on Tensor Core.

Table 4: Performance of different precision combinations

	<i>bfloat16</i>	<i>FP16</i> ( <i>half</i> )	<i>TF32</i>	<i>FP64</i> ( <i>double</i> )	<i>INT8</i> ( <i>char</i> )
<b>Exponent</b> (bits)	8	5	8	11	-
<b>Mantissa</b> (bits)	7	10	10	52	7
<b>Performance</b> <sup>•</sup>	25.89×	28.69×	9.93×	1×	60.56×

<sup>•</sup> The values are to compensate the performance difference caused by different precisions of Tensor Core. The evaluation is conducted with CUDA samples (without shared memory), and the results are scaled on the performance of FP64.

**Internal workflow of NTT box.** With the multiple-precision representation, we make Tensor Core play the role of the NTT box as an individual module. The caller could simply load the sorted data into the box and get results quickly. The internal workflow of the NTT box is shown in Fig. 4. Several sorted polynomials are distilled into a matrix, which is then first loaded into the fragment matrix in the form of tiles.

Meanwhile, the pre-computed table will also be loaded into fragment matrix\_b. Then, MMA is conducted. The results will be performed modular reduction to ensure that the coefficients of the target polynomial are less than  $q$ .

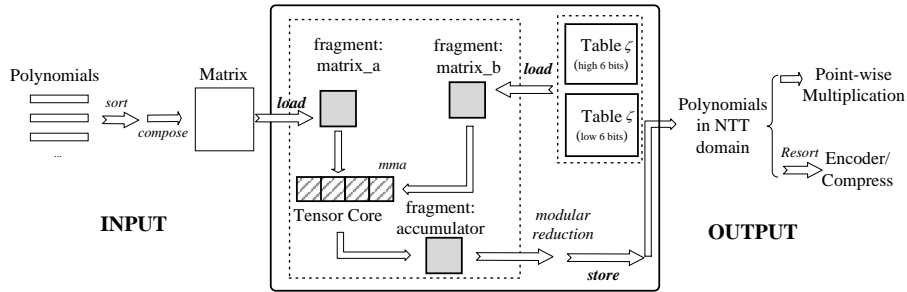


Fig. 4: The workflow of NTT box

## 4 Implementation Details

In this section, we elaborate on the technical details of our implemented prototype. First, we show the overall architecture of our system and the collaboration between the various modules. Next, we introduce two types of NTT: basic-NTT for smaller modulus with achieving higher performance, and split-NTT for larger modulus. Then, we explain some non-trivial optimization techniques.

#### 4.1 Overview

Our prototype is based on CUDA Toolkit 11.1. CUDA programming can support a large number of concurrent threads. In our implementation, each thread holds one instance, and these threads execute in SIMD (SIMT) mode. Although the specific procedures might be slightly different for different phases, the high-level overview could be like Fig. 5.

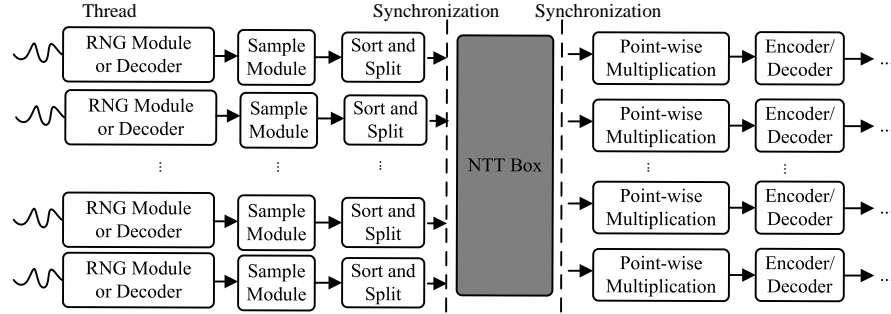


Fig. 5: General overview of implemented Kyber

**The collaboration between modules.** The function of the RNG module is to extend the random seed and get the required parameters, just like the key derivation function (KDF). After obtaining the seed from a RNG module or decoder, Kyber will generate matrix or sample polynomial vectors based on the seed. On the basis of Equation (6) and (7), for a polynomial, the elements with even (or odd) terms participate in the same NTT. Therefore, before entering the NTT box, we sort each polynomial so that even (or odd) entries are continuous in memory. When the program needs to perform NTT, it will synchronize between threads in the same thread block, and then input the data into the NTT box.

#### 4.2 The Basic-NTT and Split-NTT

However, we can only load a fixed size tile into a fragment every time, while the target matrix is much larger. We have made two scanning methods, according to the raw precision of the data to be processed. For the parameters whose element value is less than 8 bits (256, or 128 for signed number), such as secret  $\mathbf{s}$  and random noise  $\mathbf{r}$ ,  $\mathbf{e}$  generated from CBD, with at most 3 significant bits, we apply a basic-NTT method, shown in Fig. 6.

In this method, we only need to split the twiddle factors into  $T_h$  and  $T_l$ , and directly represent the input data with INT8 type. Both input and output are sorted according to parity items as  $M_e$ ,  $M_o$ ,  $R_e$  and  $R_o$ , to satisfy the requirement of contiguous memory access. Note that  $\beta$  in Fig. 6 represents the base of multiple precision representation, and the multiplication by  $b$  can be done by left shifting.

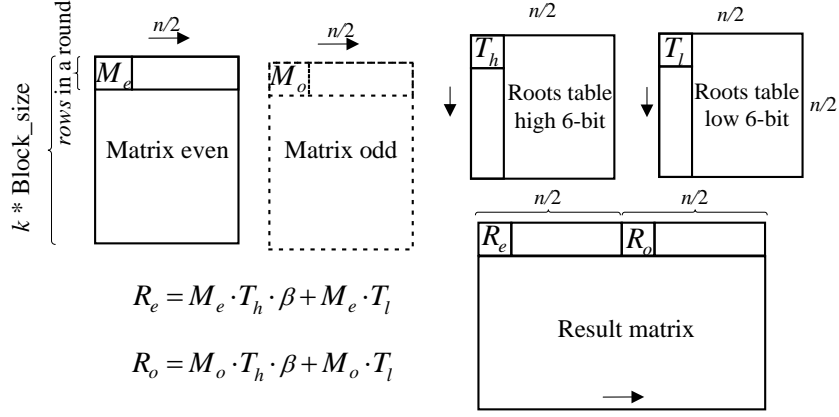


Fig. 6: Scanning of basic-NTT

As for the case that the coefficient is larger than 8 bits, such as INTT in Kyber, we employ a split-NTT scanning method and the details are shown in Fig 7. The input data is sorted first and then split. The temporary sums, like

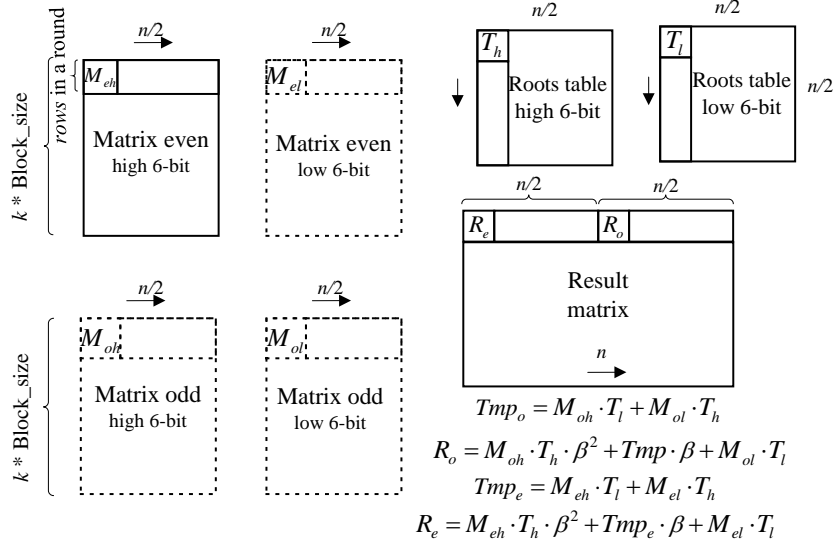


Fig. 7: Scanning of split-NTT

$Tmp_e$  and  $Tmp_o$  in Fig. 7, can be used to reduce a shift operation.

All data matrices have  $n$  columns, while the number of rows can be adjusted according to the rank  $k$  and the number of threads in a block.

### 4.3 Pre-computed Table of Twiddle Factors

Since the powers  $\zeta^{2\mathbf{br}_7(i)+1}$  can be known in advance, then all the twiddle factors can be pre-computed and stored in the memory before the procedure. When NTT is executed, these values can be obtained by directly looking up the table instead of multiplying, like the original implementation.

Additionally, intermediate results need to be performed by Montgomery reduction. After that, the result of Equation (4) is in Montgomery format and needs to be converted into the normal format by multiplying  $R$ . Therefore, the value  $R$  can be absorbed as  $\zeta^{2\mathbf{br}_7(i)+1} \cdot R \pmod q$  to save a multiplication. According to Equation (1) and (2), our pre-computed table of NTT and INTT could be:

$$\begin{bmatrix} \zeta^{0 \times 2\mathbf{br}_7(0)} R & \zeta^{0 \times 2\mathbf{br}_7(1)} R & \dots & \zeta^{0 \times 2\mathbf{br}_7(127)} R \\ \zeta^{1 \times 2\mathbf{br}_7(0)} R & \zeta^{1 \times 2\mathbf{br}_7(1)} R & \dots & \zeta^{1 \times 2\mathbf{br}_7(127)} R \\ \vdots & \vdots & \ddots & \vdots \\ \zeta^{127 \times 2\mathbf{br}_7(0)} R & \zeta^{127 \times 2\mathbf{br}_7(1)} R & \dots & \zeta^{127 \times 2\mathbf{br}_7(127)} R \end{bmatrix}_{128 \times 128} \quad (8)$$

$$\begin{bmatrix} n^{-1} \zeta^{-0 \times 2\mathbf{br}_7(0)} R & n^{-1} \zeta^{-0 \times 2\mathbf{br}_7(1)} R & \dots & n^{-1} \zeta^{-0 \times 2\mathbf{br}_7(127)} R \\ n^{-1} \zeta^{-1 \times 2\mathbf{br}_7(0)} R & n^{-1} \zeta^{-1 \times 2\mathbf{br}_7(1)} R & \dots & n^{-1} \zeta^{-1 \times 2\mathbf{br}_7(127)} R \\ \vdots & \vdots & \ddots & \vdots \\ n^{-1} \zeta^{-127 \times 2\mathbf{br}_7(0)} R & n^{-1} \zeta^{-127 \times 2\mathbf{br}_7(1)} R & \dots & n^{-1} \zeta^{-127 \times 2\mathbf{br}_7(127)} R \end{bmatrix}_{128 \times 128} \quad (9)$$

Note that the transpose of the matrix can be determined by the flag parameter of the built-in function. In addition, the NTT results are:

$$\begin{aligned} \tilde{f}_{2i} &= \sum_{j=0}^{127} f_{2j} \zeta^{(2\mathbf{br}_7(i)+1)j} R \\ \tilde{f}_{2i+1} &= \sum_{j=0}^{127} f_{2j+1} \zeta^{(2\mathbf{br}_7(i)+1)j} R \end{aligned} \quad (10)$$

### 4.4 Point-wise Multiplication and Modular Reduction

**Point-wise multiplication.** In Kyber, the polynomial multiplication  $h(x) = f(x) \cdot g(x)$  has also been redefined. Let  $\hat{h} = \hat{f} \circ \hat{g} = NTT(f) \circ NTT(g)$  denote the basecase multiplication consisting of the 128 products written as:

$$\hat{h}_{2i} + \hat{h}_{2i+1}X = (\hat{f}_{2i} + \hat{f}_{2i+1}X)(\hat{g}_{2i} + \hat{g}_{2i+1}X) \pmod{(X^2 - \zeta^{2\mathbf{br}_7(i)+1})}$$

Specifically, the product coefficients can be written as:

$$\begin{aligned} \hat{h}_{2i} &= \hat{f}_{2i}\hat{g}_{2i} + \hat{f}_{2i+1}\hat{g}_{2i+1}\zeta^{2\mathbf{br}_7(i)+1} \\ \hat{h}_{2i+1} &= \hat{f}_{2i}\hat{g}_{2i+1} + \hat{f}_{2i+1}\hat{g}_{2i} \end{aligned} \quad (11)$$

The point-wise multiplication can be performed with the Karatsuba algorithm [15] to decrease the times of multiplication, and the calculation form of results are listed in Equation (12).

$$\begin{aligned}\hat{h}_{2i} &= \hat{f}_{2i}\hat{g}_{2i} + \hat{f}_{2i+1}\hat{g}_{2i+1}\zeta^{2br(i)+1} \\ \hat{h}_{2i+1} &= (\hat{f}_{2i} + \hat{f}_{2i+1})(\hat{g}_{2i} + \hat{g}_{2i+1}) - (\hat{f}_{2i}\hat{g}_{2i} + \hat{f}_{2i+1}\hat{g}_{2i+1})\end{aligned}\quad (12)$$

**One round lazy modular reduction.** For CBD generated vectors, the biggest sum in NTT should be less than  $n'q \cdot 2^3$  (where  $n' = 128$ ), which is 22 bits. As mentioned earlier, Tensor Core performs FMA operation, then and the accumulator, represented in INT32, can still cover the range intermediate sum. For a polynomial whose coefficient is up to  $q - 1$ , we use two 6-bit elements to represent the value. Therefore,  $n'q \cdot 2^6$  (25 bits) will not cause overflow. Then, only a round fast modular reduction is needed for the final NTT result.

## 5 Performance Evaluation and Discussion

In this section, we present our evaluation results firstly, including the performance of the NTT box, and Kyber-512, Kyber-768, Kyber-1024, and perform a comparative analysis with related works. Finally, we discuss the scalability and security of our solution.

### 5.1 Results of NTT/INTT

Firstly, we test the performance of the two types of NTT. There is no significant discriminative between NTT and INTT except for the pre-computed twiddle factor tables. Since INTT does not involve small coefficients in Kyber, we only evaluate the split-INTT (for INT16). The results are listed in Table 5. For split-NTT, when the thread block size is 128, the performance can reach 247.2 MOPS.

Table 5: The performance of NTT, **Total\_case=69632, Grid\_size=136,  $n = 256$**

Operation	Input Type	Block size	Time elapsed (ms)	Performance (MOPS)
<b>split-NTT</b>	INT16	128	0.281632	247.2
		256	0.356992	195.1
<b>basic-NTT</b>	INT8	128	0.183296	379.9
		256	0.217088	320.8
<b>split-INTT</b>	INT16	128	0.277376	251.0
		256	0.357376	194.8

**Related work comparison.** We also compare the customized NTT of polynomial vector (*poly\_vec*,  $n = 256$ ,  $k = 4$ ) with the counterparts on CPU and GPU, and can obtain a speedup of at least 8.1x. Furthermore, we test the provided source code on our machine and still get about 6.47x improvement. The results are shown in Table 6.

Table 6: Comparison of *polyvec\_ntt* in KYBER,  $n = 256$ ,  $k = 4$ 

	Device	Architecture	Time (ns) <sup>°</sup>
Ref	W2123	Skylake-W	6,464
Gupt <i>et al.</i> [12]	G1060	Pascal	378.1
	P6000	Pascal	202.3
	V100	Volta	135
	R3080	Ampere	107.81 *
Ours	R3080	Ampere	16.65

<sup>°</sup> The average time cost by each instance.

\* The code in [12] is downloaded from <https://github.com/nainag/PQC> and tested on RTX3080.

In fact, Tensor Core is also supported with V100, but not exploited in [12]. Although the gain mainly comes from AI accelerator hardware, the key lies in our fine manipulation to adapt the cryptographic workload into its operating mode. Our Tensor Core based NTT box involves the pre-computed tables of twiddle factors instead of the idea of divide and conquer. Because the initial control granularity of butterfly operation is at single element level, which conflicts with the matrix mode and might make the control very complicated. More importantly, interrupting computation frequently to access memory can severely impact performance when utilizing Tensor Cores.

## 5.2 Results of Kyber

The security strength recommended by the original author is Kyber-768 ( $k = 3$ ) [29]. In addition, we also test Kyber-512 ( $k = 2$ ) and Kyber-1024 ( $k = 4$ ), and the results are shown in Fig. 8.

**Related work comparison.** The previous implementations of Kyber are based on various platforms, targeting different scenarios and following different design ideas. The FPGA based implementations such as [34], are mainly committed to using fewer hardware resources to reach more achievable performance. The CPU based optimizations such as [5] tend to use vector set instructions for acceleration. Unlike FPGA solutions, in which the improved algorithms are mainly conducted through hardware programming, the hardware circuit of our proposal can no longer be changed, and accelerations can only be carried out around the characteristics it exposes.



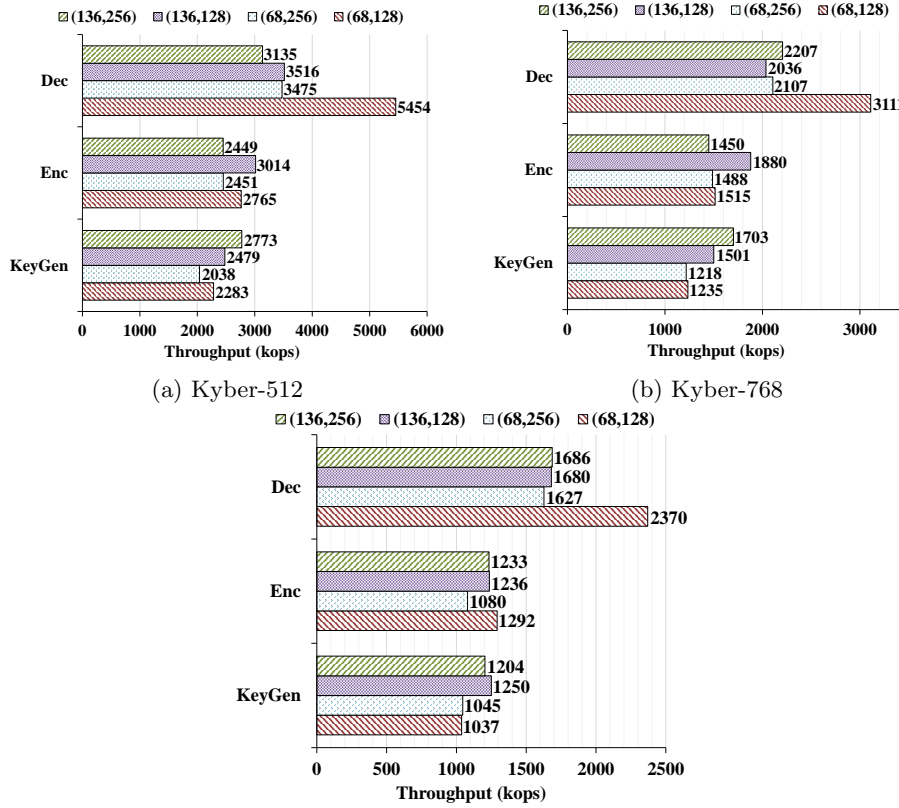


Fig. 8: The performance of Kyber-512, Kyber-768, Kyber-1024.

Table 7 lists the average time cost on Kyber-1024 of related works. Compared to resource-constrained devices, we can achieve two orders of magnitude performance improvement. For the optimized AVX2 version Kyber-1024, our prototype can obtain a speedup of approximately 26x, 36x, and 35x for KeyGen, Enc, and Dec respectively. Note that we have not optimized the hash algorithm yet.

### 5.3 Discussion

**Security.** The security issue is also an important aspect of cryptographic implementation. An important countermeasure against side-channel attacks is masking [7,26]. The core concept of masking is to split the sensitive variables into multiple shares. There are two split methods, one is Boolean split, which is suitable for block ciphers, and the arithmetic split. The PQC scheme can be combined with either or both. The multi-precision representation used in our work is actually an arithmetic split, so it can be considered that it can enhance the protection against side-channel attacks.

Table 7: Comparison of average time cost on Kyber-1024 with related works.

	<b>Platform</b>	<b>KeyGen</b> ( $\mu$ s)	<b>Enc</b> ( $\mu$ s)	<b>Dec</b> ( $\mu$ s)	<b>KX<sup>o</sup></b> (k/s)
Pakize Sanal et al. [28]	Apple A12 @2.49 GHz (AES accelerator)	38.23	37.35	36.55	13.4
PQClean [20]	ARM Cortex-A75 @2.8 GHz	137.54	170.25	195.0	3.0
Xing, Y et al. [34]	Xilinx Artix-7	58.2	67.9	86.2	6.93
C-Ref [29]	Intel Core i7-4770K @3.5 GHz (Haswell)	87.8	99.0	113.3	4.97
AVX2-Ref [29]	Intel Core i7-4770K @3.5 GHz (Haswell)	21.01	27.81	22.61	22.9
<b>This work</b>	NVIDIA GeForce RTX 3080	<b>0.80</b>	<b>0.77</b>	<b>0.42</b>	<b>819.7</b>

<sup>o</sup> computed by  $\frac{ab}{a+b}$ , where  $a, b$  are the throughput of KeyGen and Dec.

For Tensor Core itself, as far as we know, it can be treated as an atomic instruction parallel execution unit for calculating with a fixed amount of cycles. According to [23], it is almost impossible to perform a timing attack on parallel AI accelerators so far.

Meanwhile, techniques against side-channel timing leakage, such as eliminating conditional statements in CUDA kernel functions, are also involved in our work, even though they are not the main focus. Tensor Core operations involve no secret-related conditional branch, and the related memory access (pre-computed tables) is secret-irrelevant. In a nutshell, the AI accelerator we introduce will not bring additional security risks.

**Scalability.** With the upgrade of hardware products, we believe the restrictions would be fewer, and the control interfaces provided could be with finer granularity, which would make them become much more versatile. Though the study case in this paper is a PQC scheme, the proposed solution and techniques might provide reference for other computation-sensitive schemes like homomorphic encryption, of which the polynomial multiplication is also a time-consuming part. Furthermore, in practice, the implementation would be more solid with the optimizations for CUDA hardware, such as multiple working streams, shared memory, and multi-threaded cooperation.

## 6 Conclusion and Future Work

In this paper, we propose an NTT box based on NVIDIA AI accelerator, Tensor Core. After that, we present a high performance implementation of CRYSTALS-Kyber with our NTT box and achieve considerable performance improvement. Our work illustrates the tremendous potential of Tensor Core in LBC acceleration. We believe that AI accelerators will become more versatile, and support more operations and precisions. In the future, the subsequent work would cover more lattice-based cryptographic schemes, especially homomorphic encryption (HE) which urgently requires high efficiency for the wider application.

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