# Skeletal Growth Estimation Using Radiographic Image Processing and Analysis

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Abstract—An automated knowledge-based vision system for skeletal growth estimation in children is reported in this paper. Images were obtained from hand radiographs of 32 male and 25 female children of age 1–16 yr. Phalanx bones were automatically localized and segmented using hierarchical inferences and active shape models, respectively. A number of shape descriptors were obtained from the segmented bone contour to quantify skeletal growth. From these descriptors, a feature vector was selected for a regression model and a Bayesian estimator. The estimation accuracy was 84% for females and 82% for males. This level of accuracy is comparable to that of expert pediatric radiologists, which suggests that the proposed approach has a potential application in pediatric medicine.

*Index Terms*—ASM segmentation, Bayesian estimation, feature extraction, skeletal growth assessment.

#### I. Introduction

KELETAL age assessment is often required in diagnosing or monitoring growth disorders, or in some cases as an aid to predicting ultimate height. The two main methods used in pediatric radiology are attributed to Greulich and Pyle [1] and Tanner and Whitehouse (TW2) [2]. Both methods are based on assessment of bone morphology from hand radiographs. However, such manual assessment procedures tend to be laborious and prone to inter and intra observer inconsistency. An automated assessment process, based on digital image analysis, is thus highly desirable, and considerable effort has been dedicated toward this aim. Conventional image analysis methods have been applied for bone segmentations and classifications [3]–[7]. Pal et al. [8] proposed an algorithm based on fuzzy logic to automate skeletal age assessment based on TW2 [2]. Levitt et al. suggested an artificial intelligence approach based on Bayesian inference to localize and segment phalanges [9]. However, these techniques attained limited success due to faint bone edges and significant intensity variation throughout the hand radiographic image. In our approach, we used knowledge-based techniques, such as hierarchical inferences and active shape models (ASM) to localize and segment bones, respectively [10], [11]. A number of shape descriptors were obtained from the segmented bone contour to quantify skeletal growth. These descriptors were particularly selected to reflect

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growth-related shape variations in the metaphysis-epiphysis junction. A Bayesian classifier was then applied to the descriptors to estimate skeletal growth. The paper is organized as follows. In Section II, bone localization and segmentation methods are described. Bone shape descriptors are presented in Section III. Section IV presents a Bayesian approach for age estimation. Discussion and concluding remarks are provided in Section V.

# II. BONE LOCALIZATION AND SEGMENTATION

# A. Hierarchical Bone Localization

Hand radiographs are characterized by a large optical density range due to varying levels of X-ray absorption by bones and soft tissue. For example, distal phalanges are thinner and appear darker than proximal phalanges and carpal bones. Therefore, global bone edge detection schemes often fail when applied to digitized radiographic images, and alternative local schemes must be used. In our approach, anatomical and intensity inferences were used in order to localize bones prior to boundary detection. A hierarchical approach was used to "locate and infer" starting from the hand object in the radiographic image and terminating with bone localization. Binary thresholding was used to segment the hand to produce a hand silhouette, and a concave-convex detection algorithm was then applied to localize the finger tips and bases. Finally, anatomical knowledge of the finger was used in addition to gray-level information to localize bones [12].

# B. Active Shape Models Training

Bone contour detection, using active shape models, is based on active deformation of an approximate contour superimposed on the localized bone. This deformation is constrained by prior ASM training, and, for this purpose, we used a training set of 57 sample bones from 32 male and 25 female children, at various stages of normal skeletal growth.

A bone is considered to be a class of shapes described by a set of points known as a point distribution model (PDM). Fig. 1 shows an n-point PDM of the middle phalanx of the middle finger. In this study, n was set to 38 and the PDM points were manually assigned to salient locations of the phalanx to ensure that variation of the PDM points over the training set corresponded to growth-related development. Since we are only interested in shape variations during growth, all sample PDMs were aligned by scaling, rotation, and translation with respect

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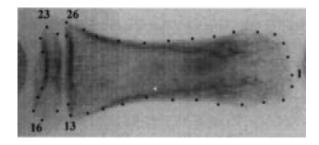


Fig. 1. Phalanx PDM.

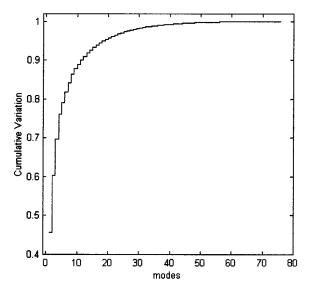


Fig. 2. Cumulative contour variations for the 76 modes in the feature space.

to an arbitrary reference PDM. The mean PDM and the covariance matrix were then calculated, and variation modes were obtained from the eigenvectors and eigenvalues of the covariance matrix. The most significant variation modes were generated by the eigenvectors corresponding to the larger eigenvalues. Therefore, a small number of modes were sufficient to describe most variations, and new shapes could then be approximated by applying the most significant modes to the Hotelling transform [11] as follows:

$$\hat{c} \approx m_c + Pb$$
 (1)

where  $\hat{c}$  is the approximated shape which defines the contour space,  $m_c$  is the mean shape, P is a matrix whose columns are the eigenvectors responsible for the most significant variation modes, and b is a vector of weights which defines the feature space. Fig. 2 shows the cumulative contour variations for all 76 (2n) modes. The cumulative variations revealed that the first 35 modes corresponded to 99% of contour variations. Therefore, these modes were chosen and higher modes that corresponded to very small variations were discarded to improve computational efficiency. New shapes could therefore be reconstructed by varying vector b. To ensure shape plausibility, each element  $b_i$  of the weight vector b was limited to the Mahalonobis distance based on the 97% confidence interval [11], i.e.,

$$|b_i| \le 3\sqrt{\lambda_i} \tag{2}$$

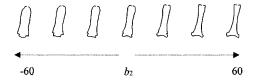


Fig. 3. Contour shape deformations due to the variations of the second mode.

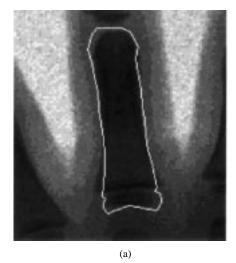
where  $b_i$  and  $\lambda_i$  are the *i*th element of vector  $\boldsymbol{b}$  and the *i*th eigenvalue of the covariance matrix, respectively. Each element of vector  $\boldsymbol{b}$  is responsible for one mode of shape variations. Fig. 3 shows the shape variations caused by varying  $b_2(\lambda_2=408)$  between -60 and +60.

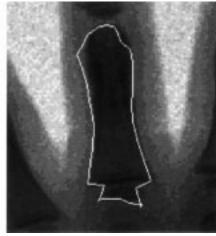
#### C. Bone Contour Detection

The mean bone contour shape is obtained from the ASM training set and is used as the initial contour  $c_0$  in an iterative algorithm to detect the test bone contour. Also, from hierarchical localization, we have a priori knowledge of the scaling (A), rotation  $(\theta)$ , and translation (S) necessary to superimpose the initial contour on the test bone. The iterative algorithm is summarized in the Appendix. At each iteration, an image contour displacement is generated using the maximum image derivative along lines normal to the previous contour PDM. The derivative can be approximated using methods such as the Sobel, derivative of Gaussian, or the multiscale derivative of Gaussian [13]–[15]. In this study, the derivative of Gaussian was used to estimate the image derivative. The image contour displacement produces a change in scaling (dA), rotation  $(d\theta)$ , and translation (dS). A scaling and rotation transformation is then applied on the tentative image contour to produce a displacement in the local frame contour. A new feature vector  $b_n$  is then obtained which is tested for plausibility using the criterion in step 7). Finally, the new local frame and image contours are updated in steps 8) and 9), respectively. The iterative algorithm stops when consecutive contour differences reach a set threshold. Fig. 4 shows three iterations of the ASM contour detection algorithm, namely the 1st, 4th, and the final 12th iteration. The residual errors were small ( $\pm 1$  pixel) and were considered to be acceptable by expert pediatric radiologists, based on qualitative assessment.

#### III. BONE SHAPE DESCRIPTIONS

An important growth feature of the phalanx bone is the junction between the epiphysis and metaphysis joints whose shape characteristics change at different stages of growth. To quantify these changes, a number of shape descriptors were developed in order to produce a feature vector for age estimation. The most effective descriptors were selected by using the finite interception test at a 5% level of significance [16]. These descriptors were the principal component coefficient (PCC), moment of the proximal end of a phalanx (MOM), and epiphysis width to metaphysis width ratio (EMR). They exhibited strong correlation with growth as given in Table I and as further demonstrated in the scatter diagrams of Fig. 5. The remainder of this section describes the methods used to obtain these descriptors.





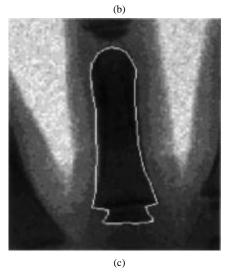


Fig. 4. ASM contour fitting. (a) Iteration 1. (b) Iteration 4. (c) Iteration 12.

TABLE I
CORRELATION COEFFICIENTS OF THE
SHAPE DESCRIPTORS WITH RESPECT TO GROWTH AGE

| Descriptors | Correlation Coefficients |         |
|-------------|--------------------------|---------|
|             | Males                    | Females |
| MOM         | 0.84                     | 0.72    |
| PCC         | 0.77                     | 0.83    |
| EMR         | 0.89                     | 0.87    |

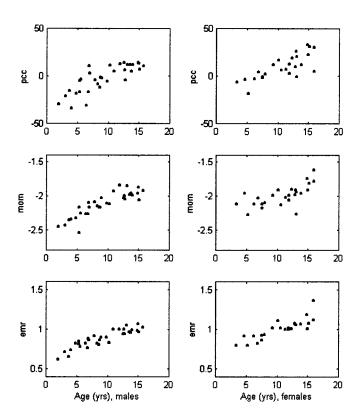


Fig. 5. Scatter diagrams of shape descriptors with respect to growth age.

TABLE II

CORRELATION OF THE FIRST FOUR PRINCIPAL COMPONENT COEFFICIENTS
WITH GROWTH

| Element | Male  | Female |
|---------|-------|--------|
| bl      | 0.04  | 0.19   |
| b2      | 0.77  | 0.83   |
| b3      | -0.43 | 0.13   |
| b4      | -0.39 | 0.05   |

# A. Principal Component Coefficients (PCC)

The ASM algorithm outlined in the Appendix generates a weight vector **b**, which is used in the Hotelling transform of (1) to compose the detected contour. A feature space is considered for feature extraction purposes. Its origin corresponds to the mean shape and the axes are represented by eigenvectors of the covariance matrix of the contour variations. Therefore, a point in the 2n-dimensional (2n = 76) contour space represents any PDM contour with n points. In the feature space, variations along each eigenvector with respect to the mean contour, represented by the weight vector  $\boldsymbol{b}$ , correspond to displacement of a 2n-dimensional point representing the contour in the contour space. However, since the first 35 modes are responsible for most contour variations, a 35-dimensional feature space is used to reconstruct a 2n-point contour using the Hotelling transform. Therefore, the feature space weight vector **b**, also known as principal component coefficients (PCCs), can represent a contour detected by the ASM algorithm. The first four principal components were computed and their correlation with growth is shown in Table II. The second coefficient (b2) exhibited the highest correlation (0.77 and 0.83 for males and females, respectively) and was selected by the finite interception test for inclusion in the

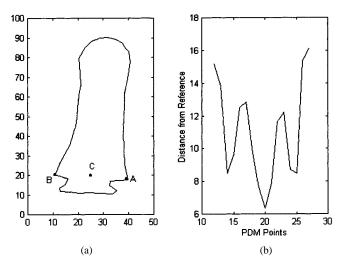


Fig. 6. (a) Phalanx PDM and (b) signature of the proximal end.

growth estimation feature vector. This result is further demonstrated in Fig. 3, where variations of b2 correspond to significant shape variations in the epiphysis.

#### B. Shape Moments (MOM)

The PCC is a global contour shape parameter that describes phalanx development including the epiphysis region. To obtain a finer scale representation of the epiphysis, its shape moment was measured as a local parameter to describe epiphysis development. To generate the shape moment, three reference PDM points are chosen, as shown in Fig. 6: two at the epiphysis—metaphysis joint (A & B) and one midway between them (C). The contour between A and B is then traversed clockwise, and the Euclidean distance to reference point C is measured to generate a 1-D signature representation of epiphysis contour variations [13]. Different order moments of this signature were calculated; however, only the fourth-order moment was selected by the finite interception test for inclusion in the estimation feature vector.

# C. Epiphysis-to-Metaphysis Ratio (EMR)

The metamorphosis of the epiphysis is used by expert pediatric radiologists as an important indicator of growth. Its genesis occurs at the early stages of skeletal growth (around 1 year). The epiphysis then grows in size relative to normal skeletal growth and eventually, at the latest growth stages, fuses with the phalanx metaphysis [2]. This development of the epiphysis—metaphysis junction is illustrated in Fig. 7. To quantify this growth-related development, we defined a descriptor to measure the ratio of epiphysis width to metaphysis width in the phalanx PDM. This is obtained, as indicated in Fig. 1, from the Euclidean distance between PDM points (16, 23) for the epiphysis and (13, 26) for the metaphysis.

# IV. AGE ESTIMATION

The feature vector [PCC MOM EMR], selected by the finite interception test was used to model growth by calculating linear regression equations from the training set (32 males and 25 females) [17]. Table III shows the slopes of the regression lines

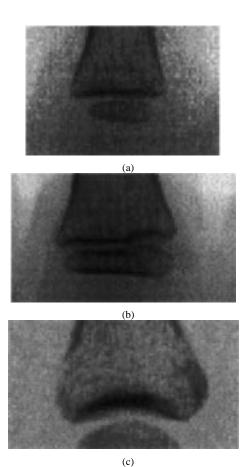


Fig. 7. Proximal part of the proximal phalanx for: (a) 4-, (b) 8-, and (c) 16-yrold growth stages.

TABLE III
REGRESSION LINE SLOPES FOR THE SHAPE DESCRIPTORS WITH RESPECT TO
GROWTH AT A 95% CONFIDENCE INTERVAL

| Descriptors | Slopes (Males)    | Slopes (Females)  |
|-------------|-------------------|-------------------|
| MOM         | 19.047 ± 7.990    | 19.224 ± 10.720   |
| PCC         | $0.221 \pm 0.102$ | $0.248 \pm 0.120$ |
| EMR         | 33.478 ± 13.349   | 27.473 ± 12.697   |

computed by using student-t distribution, for the descriptors discussed in Section IV with a 95% confidence interval.

Using the Bayes principle in decision-making theory [18], an age value "a" is estimated to minimize the risk function

$$R = \int_{\theta} \pi(\theta) L(\theta, a) f(\mathbf{x}|\theta) d\theta \tag{3}$$

where  $\theta$  is the true age, and  $\pi(\theta)$  is the prior probability function which is assumed uniform, since all age groups occur with equal probability.  $L(\theta, a)$ , and  $f(x|\theta)$  are the loss and Gaussian sample distribution functions, respectively, given as

$$L(\theta, a) = 1 - \exp\left(-\frac{1}{2}\left(\frac{\theta - a}{\Delta}\right)^2\right) \tag{4}$$

$$f(\boldsymbol{x}|\theta) = -\frac{\exp\left[-\frac{1}{2}(\boldsymbol{x} - \boldsymbol{m}_{\theta})^{T}\boldsymbol{C}^{-1}(\boldsymbol{x} - \boldsymbol{m}_{\theta})\right]}{\sqrt{(2\pi)^{3}|\boldsymbol{C}|}}$$
(5)

TABLE IV VARIANCE INFERENCE FOR THE SHAPE DESCRIPTORS USING THE CHI-SQUARE DISTRIBUTION AT A 95% CONFIDENCE INTERVAL

| Descriptors | Variance       |                |
|-------------|----------------|----------------|
|             | Males          | Females        |
| MOM         | (0.009, 0.022) | (0.014, 0.041) |
| PCC         | (92.1, 238.3)  | (54.3, 157.6)  |
| EMR         | (0.002, 0.005) | (0.004, 0.010) |

where  $\Delta$  is the estimation resolution (0.5 yr),  $\boldsymbol{x}$  is the descriptor parameter vector,  $\boldsymbol{m}_{\theta}$  is its mean vector determined from the regression curve for a given age  $\theta$ , and  $\boldsymbol{C}$  is the covariance matrix of the descriptors over the training set. Since the prior probability is uniform, the sample distribution function plays a significant role in estimating growth age using the Bayesian approach. This is more accurate than a simple regression algorithm or a canonical-correlation-based approach where a sample distribution function is not considered.

Without loss of generality, we assume the same variance for all age groups. An interval estimation of variance for different descriptors is inferred by using the Chi-square distribution with 95% confidence interval. This is shown in Table IV.

By minimizing the risk function of (3), we then have

$$\int_0^{16} \frac{(\theta - a)}{\Delta^2} \exp\left(-\frac{(\theta - a)^2}{2\Delta^2}\right) \cdot \exp\left(-\frac{1}{2}(\mathbf{x} - \mathbf{m}_{\theta})^T \mathbf{C}^{-1}(\mathbf{x} - \mathbf{m}_{\theta})\right) d\theta = 0. \quad (6)$$

The estimated age "a" was computed using the trapezoidal numerical integration method.

A hold-one-out approach was used, where one sample was excluded and C and  $m_{\theta}$  were obtained from the remaining data set in order to estimate the age of the excluded sample. Using the feature vector [PCC MOM EMR], the Bayesian algorithm produced 82%  $\pm$ 3% and 84%  $\pm$ 3% accuracy for males and females, respectively. The mean error was estimated with a 95% confidence interval. The estimation error was higher for very young children, which could be attributed to the assumption of equal variance for all age groups. We suggest that a more sophisticated model for variance, which requires far more samples for both sexes, would lead to a lower relative error.

# V. DISCUSSION AND CONCLUSIONS

In the past, skeletal age assessment has been tedious and unreliable due to human interaction in pediatric age assessment. This process could be facilitated by the automated system presented in this paper. The main processing blocks of the system such as segmentation, description, and estimation are typical constituents of most computer vision solutions for healthcare systems. However, a number of unique characteristics pertaining to hand radiographs have necessitated a knowledge-based approach to both bone segmentation and localization. A number of inferences was made from anatomical and optical density knowledge of hand radiographs. The large optical density range has meant that a global segmentation approach, such as conventional edge detection or thresholding could not be used. A local knowledge-based segmentation approach based on active shape models proved to be a

robust alternative; however, for this approach, hierarchical bone localization was a prerequisite. Quantitative assessment of the segmentation accuracy is extremely difficult in medical images due to the fuzzy nature of object edges, and qualitative assessment becomes a viable alternative. This is particularly the case for skeletal assessment when the manual detection of such fuzzy edges is in itself coarse and subjective.

At the next level of the analysis hierarchy, a set of three parameters describing bone shape was extracted to quantify the appearance variations of bones with respect to growth age. A shape descriptor (PCC) was obtained from ASM segmentation by using the Hotelling transformation from the data to the feature space. The other two descriptors were the shape moment of the proximal part of the phalanx (MOM), and the ratio of epiphysis width to metaphysis width (EMR). These descriptors exhibited large correlation with growth and were selected by the finite interception test (at a 5% level of significance) for the age estimation feature vector. Other descriptors that also correlated to growth were discarded by the test. This could be explained by a colinear relationship with correlation.

Age estimation based on the Bayesian principle was applied to the significant growth-related parameters, and this has yielded a level of accuracy (>82%) comparable to that of pediatric radiologists. Other authors have reported lower accuracy (75% and 63%) based on computer image analysis of the phalanx and carpal regions, respectively [6]. It should be noted that skeletal age estimation could be further improved, using the proposed system in this paper, by using more samples to accurately model the shape descriptors' variance.

At different stages of maturity, it is possible for various bones to be more advanced or retarded due to growth abnormality. Therefore, a more precise estimation may be achieved by segmenting more bones in a hand radiograph. However, carpal bones appear in the later stages of growth and are continuously deformed throughout the growth process. In these cases, more general-purpose localization and contour detection methods such as genetic algorithms and active contour models are suggested to initially approximate the bone shape. This shape approximation would then be improved by continuing the segmentation process using the ASM algorithm.

The proposed automated assessment system, in this paper, is robust and reliable and free from inter–intra inconsistencies, which can result from different radiologists' assessment or even from the same radiologist at different times. Experience shows that these inconsistencies can be up to 15%. Furthermore, age assessments based on methods proposed by medical atlases such as the TW2 method relate only to the populations considered in the atlases, whereas the proposed approach can be adapted to other populations with different growth rates. The only requirement is that growth estimation is obtained from the training set of the target population.

### APPENDIX

# SUMMARY OF THE ASM CONTOUR DETECTION ALGORITHM

 $C_n$  is the detected contour in the *n*th iteration,  $E_n$  the edge point candidates.  $\theta_n$ ,  $A_n$ , and  $S_n$  are contour direction, scale, and center parameters, respectively.  $c_n$  is a local frame where

model training is achieved. M(.)[.] is a transformation operator used to scale and rotate PDM points.  $b_n$  is a principal component coefficient vector corresponding to the contour. P is a matrix whose columns are the eigenvectors of the contour covariance matrix.  $\lambda_i$  is the *i*th eigenvalue of the contour covariance matrix.

For iteration n = 1 until  $|C_n - C_{n-1}| < \varepsilon$ :

- 1)  $E_n = (x_n, y_n)|_{\max \nabla f(x_n, y_n)}$ 2)  $dC_n = \overline{C_{n-1}E_n}$
- 3) Compute  $dS_n$ ,  $d\Theta_n$ ,  $dA_n$
- 4)  $S_n = S_{n-1} + dS_n$ ,  $\theta_n = \theta_{n-1} + d\theta_n$ ,  $A_n = A_{n-1}(1 + d\theta_n)$
- 5)  $d\mathbf{c}_{n} = M(A_{n}^{-1}, -\theta_{n})[C_{n-1} + d\mathbf{C}_{n} S_{n}] \mathbf{c}_{n-1}$ 6)  $\mathbf{b}_{n} = \mathbf{b}_{n-1} + \mathbf{P}^{T} d\mathbf{c}_{n}$
- 7) for each element i in  $b_n$  if  $|b_{n,i}| > 3\sqrt{\lambda_i}$  then  $b_{n,i} =$
- 8)  $\widehat{\boldsymbol{c}}_n \approx \boldsymbol{m}_c + \boldsymbol{P} \boldsymbol{b}_n$ 9)  $\boldsymbol{C}_n = M(A_n, \theta_n)[\widehat{\boldsymbol{c}}_n] + \boldsymbol{S}_n$ .

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