Eilmer4: the next step in the UQ simulation codes for high-enthalpy flows

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Motivation and History Gas dynamic formulation and code implementation Example – hemisphere in shock tube List of Contributors

# Motivation – High-enthalpy Flows



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 An application of high-enthalpy flow from your grand-parents' days.

► Not much has changed.

## Motivation – Computational Fluid Dynamic Tools



# Eilmer in a nutshell



- Eulerian/Lagrangian description of the flow (finite-volume, 2D axisymmetric or 3D).
- Transient, time-accurate, optionally implicit updates for steady flow.
- Shock capturing plus shock fitting boundary.
- Multiple block, structured and unstructured grids.
- Parallel computation on a cluster computer, using MPI in Eilmer2,3 and shared memory in dgd/Eilmer4.
- High-temperature nonequilibrium thermochemistry (GPU).
- Dense-gas thermodynamic models and rotating frames of reference for turbomachine modelling.
- Turbulence models: Baldwin-Lomax and  $k-\omega$ .
- Coupling to radiation and ablation codes for aeroshell flows.
- ...plus conjugate heat transfer and MHD

## Origins

- in the late 1980s, the state of the art for scramjet simulations involving reactive flow was JP Drummond SPARK code
- Flow solver component based on Bob McCormack's (1969) finite-difference shock-capturing technique.
- All configuration hard-coded into the Fortran source code and compiled to run on a Cray supercomputer.
- In the 1980s, a new CFD technology (upwind flux) was being developed by the applied mathematics people and parallel computing environments were being developed by the computer science people (cluster computers).
- Dec 1990: following a CFD lesson on the chalk-board from Bob Walters and Bernard Grossman, *cns4u* was started with the intention to be like SPARK but with new technology

### Development of Eilmer

- ▶ 1993 built *sm3d*, a space-marching code for 3D scramjet flows
- 1995 through 1999: the postgrad years expanded scope of experimentation and application
- 1996: code reformulation around fluxes (frequent discussions with Mike Macrossan); all code still in C with a preprocessor having a little command interpreter built in.
- ▶ 1997: discovered scripting languages Tcl and Python
- May 2003: scriptit.tcl provided fully programmable environment for simulation-preparation.
- ► Aug 2004: *Elmer* began as a hybrid code using Python and C.
- Jun 2005: rewrite of Elmer(2) in C alone.
- ▶ Jul 2006: rewrite *Elmer2* in C++ and, in 2008, call it *Eilmer3*. Class-based implementation was easier to extend.

Eilmer – Let's do it right, again.

Fred Brooks, in the "Mythical Man-Month: Essays on software engineering"

Sooner or later the first system is finished, and the architect, with firm confidence and a demonstrated mastery of the class of systems, is ready to build a second system. ...

This second is the most dangerous system a man ever designs. ...

The general tendency is to over-design the second system, using all the ideas and frills that were cautiously sidetracked on the first one.

We're OK, this is not our *second* system. cns4u, mbcns, mbcns2, Elmer, Elmer2, Eilmer3 ... Eilmer4.

## Eilmer4 - think big, but control the complexity.



- ▶ Jun 2015+: rebuild in the D and Lua programming languages.
- Heather Muir has been working on the unstructured-grid generator. based on the paving algorithm.

### Mathematical gas dynamics (in differential form)

Conservation of mass:

$$\frac{\partial}{\partial t}\rho + \nabla \cdot \rho \mathbf{u} = 0 \tag{1}$$

Conservation of species mass:

$$\frac{\partial}{\partial t}\rho_i + \nabla \cdot \rho_i \mathbf{u} = -\left(\nabla \cdot \mathbf{J}_i\right) + \dot{\omega}_i \tag{2}$$

Conservation of momentum:

$$\frac{\partial}{\partial t}\rho \mathbf{u} + \nabla \cdot \rho \mathbf{u} \mathbf{u} = -\nabla \rho - \nabla \cdot \left\{ -\mu (\nabla \mathbf{u} + (\nabla \mathbf{u})^{\dagger}) + \frac{2}{3}\mu (\nabla \cdot \mathbf{u})\delta \right\}$$
(3)

Conservation of total energy:

$$\frac{\partial}{\partial t}\rho E + \nabla \cdot (e + \frac{p}{\rho})\mathbf{u} = \nabla \cdot [k\nabla T + \sum_{s=1}^{N_v} k_{v,s}\nabla T_{v,s}] + \nabla \cdot \left[\sum_{i=1}^{N_s} h_i \mathbf{J}_i\right] \\ - \left(\nabla \cdot \left[\left\{-\mu(\nabla \mathbf{u} + (\nabla \mathbf{u})^{\dagger}) + \frac{2}{3}\mu(\nabla \cdot \mathbf{u})\delta\right\} \cdot \mathbf{u}\right]\right) - Q_{\mathsf{rad}} \quad (4)$$

Conservation of vibrational energy:

$$\frac{\partial}{\partial t}\rho_{i}e_{v,i}+\nabla\cdot\rho_{i}e_{v,i}\mathbf{u}=\nabla\cdot[k_{v,i}\nabla\mathcal{T}_{v,i}]-\nabla\cdot e_{v,i}\mathbf{J}_{i}+Q_{\mathcal{T}-V_{i}}+Q_{V-V_{i}}+Q_{\mathsf{Chem}-V_{i}}-Q_{\mathsf{rad}_{i}}$$
(5)

## More maths...

Thermodynamic model of the gas... Finite-rate chemical kinetics... Radiation energy exchange... Boundary conditions... Features:

- ▶ 3D from the beginning, 2D as a special case
- structured- and unstructured-meshes for complex geometries
- refined thermochemistry
- moving meshes (Jason Qin and Kyle Damm)
- simplified and generalized boundary conditions
- coupled heat transfer
- shared-memory parallelism for multicore workstation use
- block-marching for speed (nenzfr and nozzle design)

## Code structure

 D language data storage and solver, with embedded Lua interpreters for preprocessing, user-controlled run-time configuration in boundary conditions and source terms and thermochemical configuration.

Compute update for convective + molecular transport.

next time step Compute influence of finite-rate chemical reactions.

Compute non-equilibrium energy redistribution.

for s=1 to n do: clear flux data apply pre-reconstruction action detect shock points reconstruct flow data at cell interfaces compute convective fluxes apply post-convective-flux action apply pre-spatial-derivative action compute spatial derivatves apply post-diffusion flux action add source terms, if any compute time derivatives of conserved quantities update cell-average conserved quantities for stage s decode conserved quantities to all flow quantities

# Collecting the low-hanging fruit of parallelism

```
1
         // First-stage of gas-dynamic update.
2
3
         shared int ftl = 0; // time-level within the overall convective-update
         shared int gtl = 0; // grid time-level remains at zero for the non-moving grid
 4
         if (GlobalConfig.apply bcs in parallel) {
 5
             foreach (blk: parallel(gasBlocks.1)) {
6
                 if (blk.active) { blk.applvPreReconAction(sim time. gtl, ftl); }
7
8
         } else {
9
             foreach (blk; gasBlocks) {
                 if (blk.active) { blk.applyPreReconAction(sim time, gtl, ftl); }
10
11
             }
12
         }
13
```

Notes:

- Need to keep most data thread local.
- D Compiler expands "parallel" into code that hands out tasks to the default ThreadPool.

### How far have we gone, in lines of source code.

At 60 lines per page, the Eilmer4 code is equivalent to a 1200 page document.



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# Verification and Validation Examples

Verification:

- Are we solving the equations correctly?
- Compare with numerical solutions from other codes.
- Manufactured solution that we must match (using special source terms and boundary conditions).

Validation:

- Are we solving the correct gas-dynamic equations?
- Compare with experimental measurements.

#### Example: hemispherical probe in shock-tube flow

- Rose & Stark, 1958
- Approximate as a 2D, axisymmetric flow around a hemisphere.



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### Input script – gas model and flow

```
config.title = "Rose and Stark experiment"
R = 6.6e-3 -- nose radius, metres
-- free stream conditions taken from Table 1, Entry 5
nsp, nmodes, gmodel = setGasModel('cea-lut-air.lua')
p_init = 6.7 -- Pa
p_inf = 535.6 -- Pa
T_inf = 2573.5 -- K
vx_inf = 2436.5 -- m/s
inflow = FlowState:new{p=p_inf, T=T_inf, velx=vx_inf}
initial = FlowState:new{p=p_init, T=T_inf}
```

Notes:

- user's input script is Lua source code
- arguments to function calls delimited by ()
- tables delimited by {}
- object model by convention as described in lerusalimschy's book "Programming in Lua"

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## Input script – geometry definition

```
-- Set up the geometry for defining the grid
a = Vector3:new{x=0.0, y=0.0}
b = Vector3:new{x=-R, y=0.0}
c = Vector3:new{x=-1.5*R, y=0.0}, Vector3:new{x=-1.5*R, y=R},
Vector3:new{x=-R, y=2*R}, Vector3:new{x=0.0, y=3*R} }
-- Set up surface and grid
sphere_edge = Arc:new{p0=b, p1=c, centre=a}
psurf = makePatch{north=Line:new{p0=d[#d], p1=c}, south=Line:new{p0=d[1], p1=b},
east=sphere_edge, west=Bezier:new{points=d}
cf_radial = RobertsFunction:new{end0=false, end1=true, beta=1.2}
grid = StructuredGrid:new{purface=spurf, niv=ni+1, njv=nj+1,
cf_ict={north=cf_radial, south=cf_radia}}
```

Notes:

- Fully-parametric grid generator is available.
- Table entries are mostly named. This is an advantage for large numbers of parameters and helps to make your input script self-documenting.
- Also, could import grids. Good for complex geometries because you may use your favourite gridding tool.

## Input script – flow-domain with boundary conditions

dofile("sketch-domain.lua")

Notes:

- May define many blocks on a single grid.
- We attach boundary conditions to the domain and specify the initial flow condition.

- Boundary conditions default to class WallBC\_WithSlip.
- Some boundary conditions need extra information.

## Results - evolution of the temperature field



- Characteristic time  $\tau = \frac{R}{V_{x,\infty}} = 2.7 \,\mu \text{s.}$
- Start viscous effects at  $2\tau$ .
- Start shock-fitting at  $3\tau$ .
- Run simulation to  $10\tau$ .
- Temperature range shown is 451 K to 3331 K.

#### Results - heat transfer distribution around sphere



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#### Results - stagnation-point heat transfer



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### The Many Contributors

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