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## **EDITORIAL**

## IEEE ACCESS SPECIAL SECTION EDITORIAL: FLYING AD HOC NETWORKS: CHALLENGES, POTENTIALS, FUTURE APPLICATIONS, AND WAY FORWARD

The theory and operations of data dissemination in wireless scenarios have endless applications based on the characteristics of underlying networks. The wireless networks that do not rely on any pre-existing infrastructure such as wireless sensor networks (WSNs), wireless mesh networks (WMNs), wireless body area networks (WBANs), or Mobile Ad hoc Networks have gained much attention due to their smart applications. Such types of wireless networks are categorized under wireless ad hoc networks with no central administration. With the rapid development in the applications of such types of ad hoc networks, Flying Ad hoc networks, commonly known as unmanned aerial vehicles (UAVs), have recently captured the attention of vendors and investors due to the flying nature of the entities. The UAV is officially called drone, which has the ability to fly without a human pilot aboard. The network of drones or UAVs has commercially gained popularity because of its applications such as surveillance, agriculture, and photography. For instance, the new applications that are being developed for Flying Ad hoc Network (FANET) bring up new challenges such as multipath propagations, severe shadowing, traffic load balancing, mobility, congestion, and high error rates, which usually result in degradation of the network. On the contrary, the applications developed and enabled in FANET may also result in collision with commercial flights due to the highlighted challenges.

Commercial flight companies have reported to the Federal Aviation Administration (FAA) about the tremendous increase of more than 50% in unmanned vehicles in 2019. However, such an increase in UAVs results in an increase in the network traffic of FANET that may lead to an unbalanced traffic distribution and collision. In order to cope with such kinds of challenges, the network traffic of the aforementioned network must be distributed to such a degree that it should neither disturb the commercial flights nor any UAV in the network.

This Special Section has provided a platform for researcher and practitioners from both academia and industry in the area of FANETs.

We published one invited article from highly reputed researchers working in the area of FANETs. The invited article, authored by Dapper e Silva *et al.*, "STFANET:

SDN-Based Topology Management for Flying Ad Hoc Network," addresses the orientation of UAVs and their management using software-defined network (SDN) for FANET. The main objective is to provide a communication link among independent nodes in the network by establishing and maintaining a FANET topology. Simulation results carried out for the military settings show the efficiency of the proposed protocol by achieving 25% of packet loss in the data plane, 1.5 ms of latency, and 71% of connectivity on average in a dynamic scenario.

Nine other high-quality articles have been included in this Special Section from leading researchers and their research groups around the world working on state-of-the-art and revolutionary research aspects of FANET and its applications.

The first contribution, authored by Sharma et al., is "Secure and Reliable Resource Allocation and Caching in Aerial-Terrestrial Cloud Networks (ATCNs)," which addresses the issues of efficient resource allocation and content-caching in a highly dynamic network environment as employed in FANET type networks like ATCNs. For this purpose, the resources in such types of network have been allocated reliably and securely using cog-chain protocol by establishing a virtual communication mechanism between the nodes and the content caching servers. The cog-chain provides an easy way of implementation to provide secure authentication with authorization with lightweight facilities. The proposed cog-chain protocol is validated through consequential gains by means of signaling overheads, computational time, and reliability. It is suggested in the article that cog-chain can be applied to several integrated and hierarchical networks to resolve several issues related to security and integrity to allocate the resources in a secure and reliable manner.

The next article entitled "BICSF: Bio-Inspired Clustering Scheme for FANETs," by Khan *et al.*, proposes a scheme for energy aware cluster formation and cluster head election on the basis of Glowworm Swarm Optimization (GSO) algorithm. In addition, the authors have proposed an efficient cluster management algorithm using behavioral study of Krill Herd (KH). The performance of BICSF is evaluated, and the results show that the proposed BICSF outperforms other clus-



tering algorithms with bio-inspired features with reference to energy consumption, delivery success ratio, cluster building time, and lifetime.

In the article entitled "The Broadcast Storm Problem in FANETs and the Dynamic Neighborhood-Based Algorithm as a Countermeasure," by Pires et al., the authors discuss the broadcast storm that is generated while maintaining the UAVs coordination by allowing all the nodes in the network to continuously forward the required messages, so that each node in the network knows the condition of the network in order to proceed with the transmission of message through wireless medium in a contention-based environment. In addition, they have proposed an innovative Dynamic Neighborhood-Based (DNB-BSP) algorithm. The proposed algorithm was evaluated through computer simulations and was validated based on outdoor experiments. The results reveal that the proposed mechanism as compared to flooding scenario reduces the duplicate messages in the network by more than 98% and message delivery ratio by more than 95%.

In the article "Exploiting Dual Connectivity for Handover Management in Heterogeneous Aeronautical Network," by Wang *et al.*, the authors address the problem of handover management and its overhead using stochastic optimization with queue backlog. In addition, they proposed a mechanism to schedule the traffic with dual connectivity in heterogeneous aeronautical network to provide handover management. Furthermore, they tried to transform stochastic optimization problem to deterministic using the Lyapunov optimization theory. Afterward, they proposed optimal and feasible strategies. It has been concluded that the handover overhead would be minimal if the baseline strategy is utilized instead of the conventional optimal strategy.

In the article "Adaptive Hello Interval in FANET Routing Protocols for Green UAVs," by Mahmud and Cho, the authors highlight the issue of exchanging 1-hop hello messages. These messages are exchanged with the neighbors in a periodic manner, after a defined interval. However, this may increase the message overhead and energy consumption. Considering this problem, they have proposed a mechanism to determine hello intervals based on mission environment parameters in real-time scenarios and attributes, such as with the UAV speed, transmission range, number of UAVs deployed in the network, and the volume of the allowed airspace. The analysis performed through the simulation has shown that the proposed mechanism has saved an average of 25% energy compared to AODV and 23% compared to OLSR.

The next article "Robust RFID based 6-DoF Localization for Unmanned Aerial Vehicles," by Zhang *et al.*, proposes an enhanced UAV system with a Radio-Frequency Identification (RFID) to investigate UAVs for indoor applications without using the Global Positioning System (GPS) service in order to precisely and accurately localize a UAV. In addition, the authors proposed an algorithm using Bayesian filter to track the RFID tags, through the position of the tags using phase measurements of the RFID tag responses in a global

coordinate system, which is referred to as radio-frequency UAV (RFUAV). The performance of the proposed work has been tested in an indoor environment. The system is capable of measuring 2.5 degree orientation error and 0.04 m position error

The article "A Traffic-Aware Approach for Enabling Unmanned Aerial Vehicles (UAVs) in Smart City Scenarios," by El-Sayed *et al.*, addresses the problem of high computation capabilities and latency in smart cities with fixed infrastructure to support efficient vehicular applications. The authors proposed a solution called SWIM that uses network edges as mobile RSUs in situations and areas where fixed infrastructure is not feasible to deploy because of cost and time constraints. Additionally, the authors use such networks in an urban area and apply them where severe traffic is generated temporarily. This traffic may create congestion; therefore, they have designed a strategy that can relocate the edges as per the need with respect to the condition of the traffic and the congestion behavior.

Another article titled "Channel Measurement and Resource Allocation Scheme for Dual-Band Airborne Access Networks," by Zhang *et al.*, highlights objectives such as wide coverage, long continuous work, and high throughput for ground users. The constraints have been applied with limited power supply, frequency reuse, and large propagation distance. The authors have proposed a hybrid-spectrum scheme for aerial base stations (ABS) on the airship. Additionally, the ABS employed multiple bands to provide continuous connectivity for ground users. These bands are UHF and S bands. The results showed that the airship network performance has been significantly improved by using the proposed mechanism.

In the last article entitled "Joint Resource Allocation and Trajectory Control for UAV-Enabled Vehicular Communications," by Deng *et al.*, the authors discuss vehicular communications based on unmanned-aerial-vehicles to highlight the problem of resource allocation. In this work, UAV is used to act as a temporary cellular base station. A 3-partite graph matching algorithm is used to enhance the channel conditions and mobility of UAV in disaster situations in order to restore vehicular communication. The article concluded that the proposed algorithm only achieves a maximum weighted matching for 3-partite graph instead of achieving the optimal solution.

In conclusion, we are thankful to all the researchers who submitted their original articles to our Special Section. Along with this, we are also extremely appreciative of the contributions and time spent by the reviewers in providing their constructive comments, recommendations, and suggestions. Furthermore, we also would like to acknowledge the cooperation of the IEEE Access editorial staff members and the guidance from the Editor-in-Chief. Moreover, we hope that this Special Section on Flying *Ad hoc* Networks: Challenges, Potentials, Future Applications, and Way Forward will contribute to the knowledge base and will benefit the research community at large.

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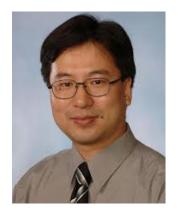
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