# **Notes: Intro to Time Series and Forecasting – Ch6 Nonstationary and Seasonal Time Series Models**

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05/09/2019

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## **When data is not stationary**

- Implication of not stationary: sample ACF or sample PACF do not rapidly decrease to zero as lag increases
- What shall we do?
	- $-$  Differencing, then fit an ARMA  $\rightarrow$  ARIMA
	- − Transformation, then fit an ARMA
	- − Seasonal model → SARIMA

#### **A non-stationary exmaple: Dow Jones utilities index data**

```
library(itsmr); ## Load the ITSM-R package
par(mfrow = c(1, 3));plot.ts(dowj, main = 'Raw data');
acf(dowj); pacf(dowj);
```


#### **After differencing**

 $par(mfrow = c(1, 3));$ dowj\_diff = dowj[**-length**(dowj)] **-** dowj[**-**1]; **plot.ts**(dowj\_diff, main = 'Data after differencing'); **acf**(dowj\_diff); **pacf**(dowj\_diff);



#### <span id="page-5-0"></span>**ARIMA model: definition**

• Autoregressive integrated moving-average models (ARIMA): Let *d* ∈ N, then series  $\{X_t\}$  is an ARIMA $(p, d, q)$  process if

$$
Y_t = (1 - B)^d X_t
$$

is a **causal** ARMA(*p, q*) process.

• Difference equation (DE) for an ARIMA(*p, d, q*) process

$$
\phi^*(B)X_t = \phi(B)(1 - B)^d X_t = \theta(B)Z_t, \quad \{Z_t\} \sim \text{WN}(0, \sigma^2)
$$

- $-\phi(z)$ : polynomial of degree p, and  $\phi(z) \neq 0$  for  $|z| \leq 1$ − *θ*(*z*): polynomial of degree *q*  $-\phi^*(z) = \phi(z)(1-z)^d$ : has a zero of order *d* at  $z = 1$
- An ARIMA process with *d >* 0 is NOT stationary!

#### **ARIMA mean is not dertermined by the DE**

 $\bullet$   $\{X_t\}$  is an ARIMA $(p, d, q)$  process. We can add an arbitrary polynomial trend of degree  $d − 1$ 

$$
W_t = X_t + A_0 + A_1t + \dots + A_{d-1}t^{d-1}
$$

with  $A_0, \ldots, A_{d-1}$  being any random variables, and  $\{W_t\}$  still satisfies the same ARIMA(*p, d, q*) difference equation

- In other words, the ARIMA DE determines the second-order properties of  $\{(1 - B)^d X_t\}$  but not those of  $\{X_t\}$ 
	- − For parameter estimation: *φ*, *θ*, and *σ* <sup>2</sup> are estimated based on  $\{(1 - B)^d X_t\}$  rather than  $\{X_t\}$
	- − For forecast, we need additional assumptions

## **Fit data using ARIMA processes**

- Whether to fit a finite time series using
	- − non-stationary models (such as ARIMA), or
	- − directly using stationary models (such as ARMA)?
- If the fitted stationary ARMA model's *φ*(·) have zeros very close to unit circles, then fitting an ARIMA model is better
	- − Parameter estimation is stable
	- − The differenced series may only need a low-order ARMA
- Limitation of ARIMA: only permits data to be nonstationary in a very special way
	- − Non-stationary: can have zeros anywhere on the unit circle |*z*| = 1
	- − ARIMA model: only has a zero of multiplicity *d* at the point *z* = 1

### <span id="page-8-0"></span>**Natural log transformation**

- When data variance increases with mean, it's common to apply log transformation before fitting the data using ARIMA or ARMA.
- When does log transfomation work well? Suppose that

$$
E(X_t) = \mu_t, \quad Var(X_t) = \sigma^2 \mu_t^2
$$

Then by first-order Taylor expansion of  $\log(X_t)$  at  $\mu_t$ :

$$
\log(X_t) \approx \log(\mu_t) + \frac{X_t - \mu_t}{\mu_t} \implies Var\left[\log(X_t)\right] \approx \frac{Var(X_t)}{\mu_t^2} = \sigma^2
$$

The data after log transformation  $log(X_t)$  has a constant variance

- Note: log transformation can only be applied to positive data
- Note: If  $Y_t = \log(X_t)$ , then because expectation and logarithm are not interchangeable,

$$
\hat{X}_t \neq \exp(\hat{Y}_t)
$$

#### **Generalize the log transformation: Box-Cox transformation**

• Box-Cox transformation

$$
f_{\lambda}(x) = \begin{cases} \frac{x^{\lambda} - 1}{\lambda}, & x \ge 0, \lambda > 0\\ \log(x), & x > 0, \lambda = 0 \end{cases}
$$

- − Usual range: 0 ≤ *λ* ≤ 1*.*5
- − Common values: *λ* = 0*,* 0*.*5
- Note:  $\lim_{\lambda\to 0} f_{\lambda}(x) = \log(x)$
- Box-Cox transformation can only be applied to non-negative data

### <span id="page-10-0"></span>**Unit root test for AR**(1) **process**

- $\{X_t\}$  is an AR(1) process:  $X_t \mu = \phi_1(X_{t-1} \mu) + Z_t$
- Equivalent DE:

$$
\nabla X_t = X_t - X_{t-1} = \phi_0^* + \phi_1^* X_{t-1} + Z_t
$$

 $-$  where  $\phi_0^* = \mu(1 - \phi_1)$  and  $\phi_1^* = \phi_1 - 1$ 

- − Regressing ∇*X<sup>t</sup>* onto 1 and *Xt*−1, we get the OLS estimator *φ*ˆ<sup>∗</sup> 1 and its standard error  $SE(\hat \phi_1^*)$
- Augmented Dickey-Fuller test for  $AR(1)$ 
	- $-$  Hypotheses:  $H_0: \phi_1 = 1 \leftrightarrow H_1: \phi_1 < 1$
	- $-$  Equivalent hypotheses:  $H_0: \phi_1^* = 0 \leftrightarrow H_1: \phi_1^* < 0$
	- − Test statistic: limit distribution under *H*<sub>0</sub> is not normal or t

$$
\hat{\tau} = \frac{\hat{\phi}_1^*}{SE(\hat{\phi}_1^*)}
$$

− Rejection region: reject *H*<sup>0</sup> if

$$
\begin{cases} \hat{\tau} < -2.57 & (90\%) \\ \hat{\tau} < -2.86 & (95\%) \\ \hat{\tau} < -3.43 & (99\%) \end{cases} \tag{11}
$$

## **Unit root test for AR**(*p*) **process**

- AR(*p*) process:  $X_t \mu = \phi_1(X_{t-1} \mu) + \cdots + \phi_n(X_{t-n} \mu) + Z_t$
- Equivalent DE:

$$
\nabla X_t = \phi_0^* + \phi_1^* X_{t-1} + \phi_2^* \nabla X_{t-1} + \dots + \phi_p^* \nabla X_{t-p+1} + Z_t
$$

- $-$  where  $\phi_0^* = \mu(1 \sum_{i=1}^p \phi_i), \phi_1^* = \sum_{i=1}^p \phi_i 1$ , and  $\phi_j^* = -\sum_{i=j}^p \phi_i$ for  $i > 2$
- − Regressing ∇*X<sup>t</sup>* onto 1*, Xt*−1*,* ∇*Xt*−1*,* · · · *,* ∇*Xt*−*p*+1, we get the OLS estimator  $\hat{\phi}_{1}^{*}$  and its standard error  $SE(\hat{\phi}_{1}^{*})$
- Augmented Dickey-Fuller test for AR(*p*)
	- $-$  Hypotheses:  $H_0: \phi_1^* = 0 \leftrightarrow H_1: \phi_1^* < 0$
	- − Test statistic:

$$
\hat{\tau} = \frac{\hat{\phi}_1^*}{SE(\hat{\phi}_1^*)}
$$

− Rejection region: same as augmented Dickey-Fuller test for AR(1)

#### **Implement augmented Dickey-Fuller test in R**

```
library(tseries);
## Note: the lag k here is the AR order p
adf.test(dowj, k = 2);
```
##

```
## Augmented Dickey-Fuller Test
```
##

```
## data: dowj
```

```
\## Dickey-Fuller = -1.3788, Lag order = 2, p-value = 0.8295
```

```
## alternative hypothesis: stationary
```
#### <span id="page-13-0"></span>**Forecast an ARIMA**(*p,* 1*, q*) **process**

•  $\{X_t\}$  is ARIMA $(p, 1, q)$ , and  $\{Y_t = \nabla X_t\}$  is a causal ARMA $(p, q)$ 

$$
X_t = X_0 + \sum_{j=1}^t Y_j, \quad t = 1, 2, \dots
$$

• Best linear predictor of  $X_{n+1}$ 

$$
P_n X_{n+1} = P_n(X_0 + Y_1 + \dots + Y_{n+1}) = P_n(X_n + Y_{n+1}) = X_n + P_n(Y_{n+1}),
$$

- − *P<sup>n</sup>* means based on {1*, X*0*, X*1*, . . . , Xn*}, or equivalently,  $\{1, X_0, Y_1, \ldots, Y_n\}$  $−$  To find  $P_n(Y_{n+1})$ , we need to know  $E(X_0^2)$  and  $E(X_0Y_j)$ , for  $i = 1, \ldots, n + 1.$
- A sufficient assumption for  $P_n(Y_{n+1})$  to be the best linear predictor in term of  ${Y_1, \ldots, Y_n}$ :  $X_0$  is uncorrelated with  $Y_1, Y_2, \ldots$

### **Forecast an ARIMA**(*p, d, q*) **process**

- The observed ARIMA $(p, d, q)$  process  $\{X_t\}$  satisfies *Y*<sub>*t*</sub> =  $(1 - B)^d X_t$ , *t* = 1*,* 2*, . . . , {Y<sub>t</sub>}* ∼ causal ARMA(*p, q*)
- Assumption: the random vector (*X*1−*d, . . . , X*0) is uncorrelated with  $Y_t$  for all  $t > 0$
- One-step predictors  $\hat{Y}_{n+1} = P_n Y_{n+1}$  and  $\hat{X}_{n+1} = P_n X_{n+1}$ :

$$
X_{n+1} - \hat{X}_{n+1} = Y_{n+1} - \hat{Y}_{n+1}
$$

• Recall: the *h*-step predictor of  $ARMA(p, q)$  for  $n > \max(p, q)$ :

$$
P_n Y_{n+h} = \sum_{i=1}^p \phi_i P_n Y_{n+h-i} + \sum_{j=h}^q \theta_{n+h-1,j} (Y_{n+h-j} - \hat{Y}_{n+h-j})
$$

• *h*-step predictor of ARIMA $(p, d, q)$  for  $n > \max(p, q)$ :

$$
P_n X_{n+h} = \sum_{i=1}^{p+d} \phi_i^* P_n X_{n+h-i} + \sum_{j=h}^q \theta_{n+h-1,j} (X_{n+h-j} - \hat{X}_{n+h-j})
$$

where  $\phi^*(z) = (1-z)^d \phi(z) = 1 - \phi_1^* z - \cdots - \phi_{p+d}^* z^{p+d}$ 

## <span id="page-15-0"></span>**Seasonal ARIMA (SARIMA) Model: definition**

• Suppose *d, D* are non-negative integers. {*Xt*} is a seasonal ARIMA $(p, d, q) \times (P, D, Q)$ <sup>s</sup> process with period *s* if the differenced series

$$
Y_t = (1 - B)^d (1 - B^s)^D X_t
$$

is a causal ARMA process defined by

 $\phi(B)\Phi(B^s)Y_t = \theta(B)\Theta(B^s)Z_t, \quad \{Z_t\} \sim \text{WN}(0, \sigma^2)$ 

where

$$
\phi(z) = 1 - \phi_1 z - \dots - \phi_p z^p, \quad \Phi(z) = 1 - \Phi_1 z - \dots - \Phi_P z^P
$$
  

$$
\theta(z) = 1 + \theta z + \dots + \theta_q z^q, \quad \Theta(z) = 1 + \Theta z + \dots + \Theta_Q z^Q
$$

- ${Y<sub>t</sub>}$  is causal if and only if neither  $\phi(z)$  or  $\Phi(z)$  has zeros inside the unit circle
- Usually,  $s = 12$  for monthly data

## **Special case: seasonal ARMA (SARMA)**

• Between-year model: for monthly data, each one of the 12 time series is generated by the same ARMA(*P, Q*) model

 $\Phi(B^{12})Y_t = \Theta(B^{12})U_t, \quad \{U_{j+12t}, t \in \mathbb{Z}\} \sim \text{WN}(0, \sigma_U^2)$ 

- SARMA(*P, Q*) with period *s*: in the above between-year model, the period 12 can be changed to any positive integer *s*
	- $-$  If  $\{U_t, t \in \mathbb{Z}\}\sim \text{WN}(0, \sigma_U^2)$ , then the ACVF  $γ(h) = 0$  unless *h* divides *s* evenly. But this may not be ideal for real life application! E.g., this Feb is correlated with last Feb, but not this Jan.
- General SARMA $(p, q) \times (P, Q)$  with period *s*: incorporate dependency between the 12 series by letting {*Ut*} be ARMA:

 $\Phi(B^s)Y_t = \Theta(B^s)U_t, \quad \phi(B)U_t = \theta(B)Z_t, \quad \{Z_t\} \sim \text{WN}(0, \sigma^2)$ 

− Equivalent DE for the general SARMA:

 $\phi(B)\Phi(B^s)Y_t = \theta(B)\Theta(B^s)Z_t$ 

## **Fit a SARIMA Model**

- Period *s* is known
- 1. Find *d* and *D* to make the difference series {*Yt*} to look stationary
- 2. Examine the sample ACF and sample PACF of {*Yt*} at lags being multiples of *s*, to find orders *P, Q*
- 3. Use  $\hat{\rho}(1), \ldots, \hat{\rho}(s-1)$  to find orders  $p, q$
- 4. Use AICC to decide among competing order choices
- 5. Given orders (*p, d, q, P, D, Q*), estimate MLE of parameters  $(\phi, \theta, \Phi, \Theta, \sigma^2)$

#### <span id="page-18-0"></span>**Regression with ARMA errors: OLS estimation**

• Linear model with ARMA errors  $\mathbf{W} = (W_1, \dots, W_n)'$ :

 $Y_t = \mathbf{x}'_t \boldsymbol{\beta} + W_t$ ,  $t = 1, \ldots, n$ ,  $\{W_t\} \sim \text{causal ARMA}(p, q)$ 

- − Note: each row is indexed by a different time *t*!
- $-$  Error covariance  $\mathbf{\Gamma}_n = E(\mathbf{WW}')$
- Ordinary least squares (OLS) estimator

$$
\hat{\boldsymbol{\beta}}_{\textsf{OLS}} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{Y}
$$

- − Estimated by minimizing (**Y** − **X***β*) 0 (**Y** − **X***β*)
- − OLS is unbiased, even when errors are dependent!

#### **Regression with ARMA errors: GLS estimation**

• Generalized least squares (GLS) estimator

$$
\hat{\boldsymbol{\beta}}_{\textsf{GLS}} = (\mathbf{X}' \mathbf{\Gamma}_n^{-1} \mathbf{X})^{-1} \mathbf{X}' \mathbf{\Gamma}_n^{-1} \mathbf{Y}
$$

− Estimated by minimizing the weighted sum of squares

$$
(\mathbf{Y} - \mathbf{X}\boldsymbol{\beta})'\mathbf{\Gamma}_n^{-1}(\mathbf{Y} - \mathbf{X}\boldsymbol{\beta})
$$

− Covariance

$$
Cov\left(\hat{\boldsymbol{\beta}}_{\text{GLS}}\right) = (\mathbf{X}' \mathbf{\Gamma}_n^{-1} \mathbf{X})^{-1}
$$

− GLS is the best linear unbiased estimator, i.e., for any vector **c** and any unbiased estimator *β*ˆ, we have

$$
\mathrm{Var}(\mathbf{c}'\hat{\boldsymbol{\beta}}_{\text{GLS}}) \leq \mathrm{Var}(\mathbf{c}'\hat{\boldsymbol{\beta}})
$$

## **When** {*Wt*} **is an AR**(*p*) **process**

• We can apply *φ*(*B*) to each side of the regression equation and get uncorrelated, zero-mean, constant-variance errors

 $\phi(B)$ **Y** =  $\phi(B)$ **X** $\beta$  +  $\phi(B)$ **W** =  $\phi(B)$ **X** $\beta$  + **Z** 

• Under the transformed target variable

$$
Y_t^* = \phi(B)Y_t, \quad t = p+1, \dots, n
$$

and the transformed design matrix

$$
X_{t,j}^* = \phi(B)X_{t,j}, \quad t = p+1, \dots, n, \quad j = 1, \dots, k
$$

the OLS estimator is the best linear unbiased estimator

• Note: after the transformation, the regression sample size reduces to  $n - p$ 

## **Regression with ARMA errors: MLE**

- MLE of  $\beta$ ,  $\phi$ ,  $\theta$ ,  $\sigma^2$  can be estimated by maximizing the Gaussian likelihood with error covariance **Γ***<sup>n</sup>*
- An iterative scheme
	- 1. Compute  $\hat{\boldsymbol{\beta}}_{\mathsf{OLS}}$  and regression residuals  $\mathbf{Y} \mathbf{X}\hat{\boldsymbol{\beta}}_{\mathsf{OLS}}$
	- 2. Based on the estimated residuals, compute MLE of the ARMA(*p, q*) parameters
	- 3. Based on the fitted ARMA model, compute  $\hat{\boldsymbol{\beta}}_{\mathsf{GLS}}$
	- 4. Compute regression residuals **Y** − **X***β*ˆ GLS, and return to Step 2 until estimators stabilize
- Asymptotic properties of MLE: If {*Wt*} is a causal and invertible ARMA, then
	- − MLEs are asymptotically normal
	- − Estimated regression coefficients are asymptotically independent of estimated ARMA parameters

#### **References**

- Brockwell, Peter J. and Davis, Richard A. (2016), *Introduction to Time Series and Forecasting, Third Edition*. New York: Springer
- Weigt, George (2018) *ITSM-R Reference Manual* <http://www.eigenmath.org/itsmr-refman.pdf>
- R package tseries <https://cran.r-project.org/web/packages/tseries/index.html>