

Improving NLP Entity Annotations via Ontological Knowledge

Marco Rospocher



Context: Knowledge Extraction

Kia has hired Peter Schreyer as chief design officer.

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Organization

Kia has hired Peter Schreyer as chief design officer.

NLP Tasks:

- Named Entity Recognition and Classification (NERC)

Context: Knowledge Extraction

Organization

dbpedia:Kia_Motors

Kia has hired Peter Schreyer as chief design officer.

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- Named Entity Recognition and Classification (NERC)
- Entity Linking (EL)

Context: Knowledge Extraction



NLP Tasks:

- Named Entity Recognition and Classification (NERC)
- Entity Linking (EL)
- Semantic Role Labeling (SRL)

...

Motivating Examples

Lincoln is based in Michigan.


Motivating Examples

Lincoln is based in Michigan.

Stanford CoreNLP

<http://nlp.stanford.edu:8080/corenlp>

1 Lincoln is based in Michigan.



The image shows a screenshot of the Stanford CoreNLP interface. The sentence "1 Lincoln is based in Michigan." is displayed. The word "Lincoln" is highlighted with a pink box and labeled "Org" above it. The words "Michigan" and "is based in" are grouped together and labeled "Location" above them. A black icon of a building and two people is positioned below the "Lincoln" label.

Motivating Examples


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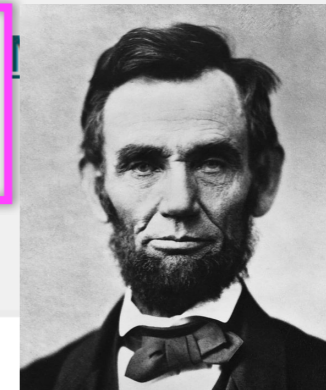
Org Location



<http://demo.dbpedia-spotlight.org>

Lincoln is based in

dbpedia:Abraham_Lincoln



Motivating Examples


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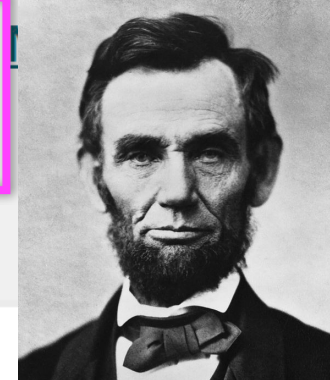
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San Jose is one of the strongest hockey team.

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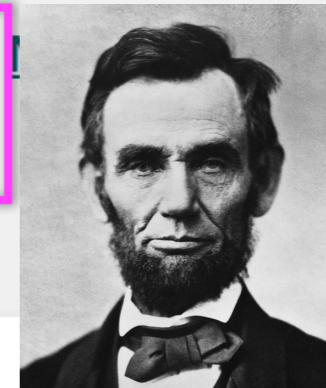
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dbpedia:San_Jose_Sharks



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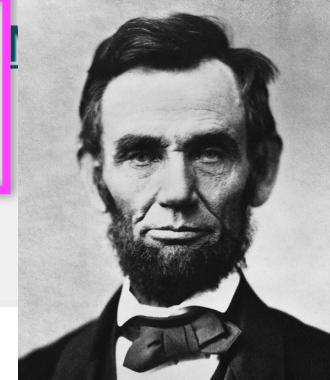
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<http://nlp.stanford.edu:8080/corenlp>

1 San Jose is one of the strongest hockey team.


Location Team



<http://demo.dbpedia-spotlight.org>

San Jose is one of the strongest hockey team.

dbpedia:San_Jose_Sharks



Abstracting

... token₁ token₂ token₃ token₄ token₅ token₆

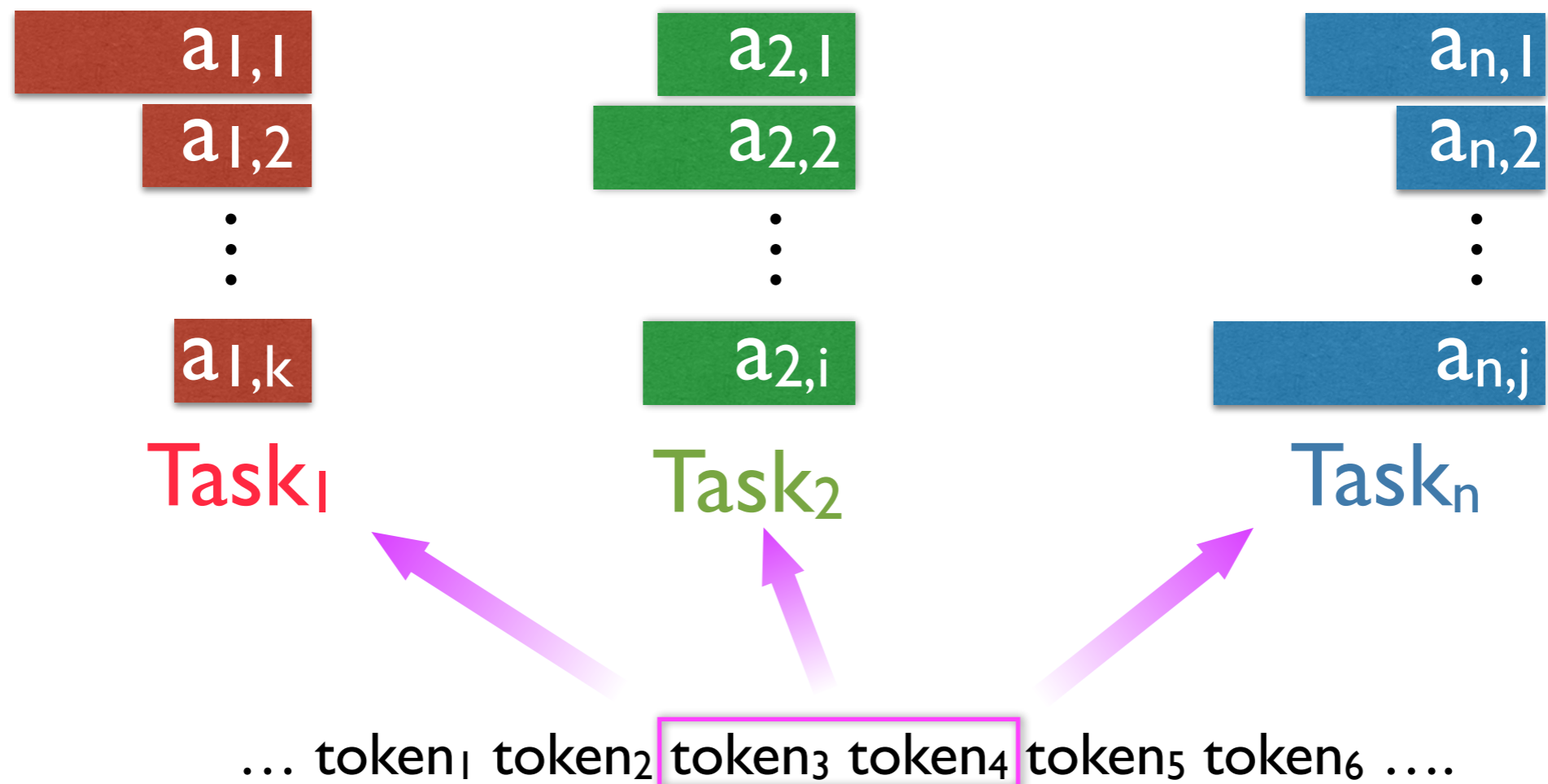
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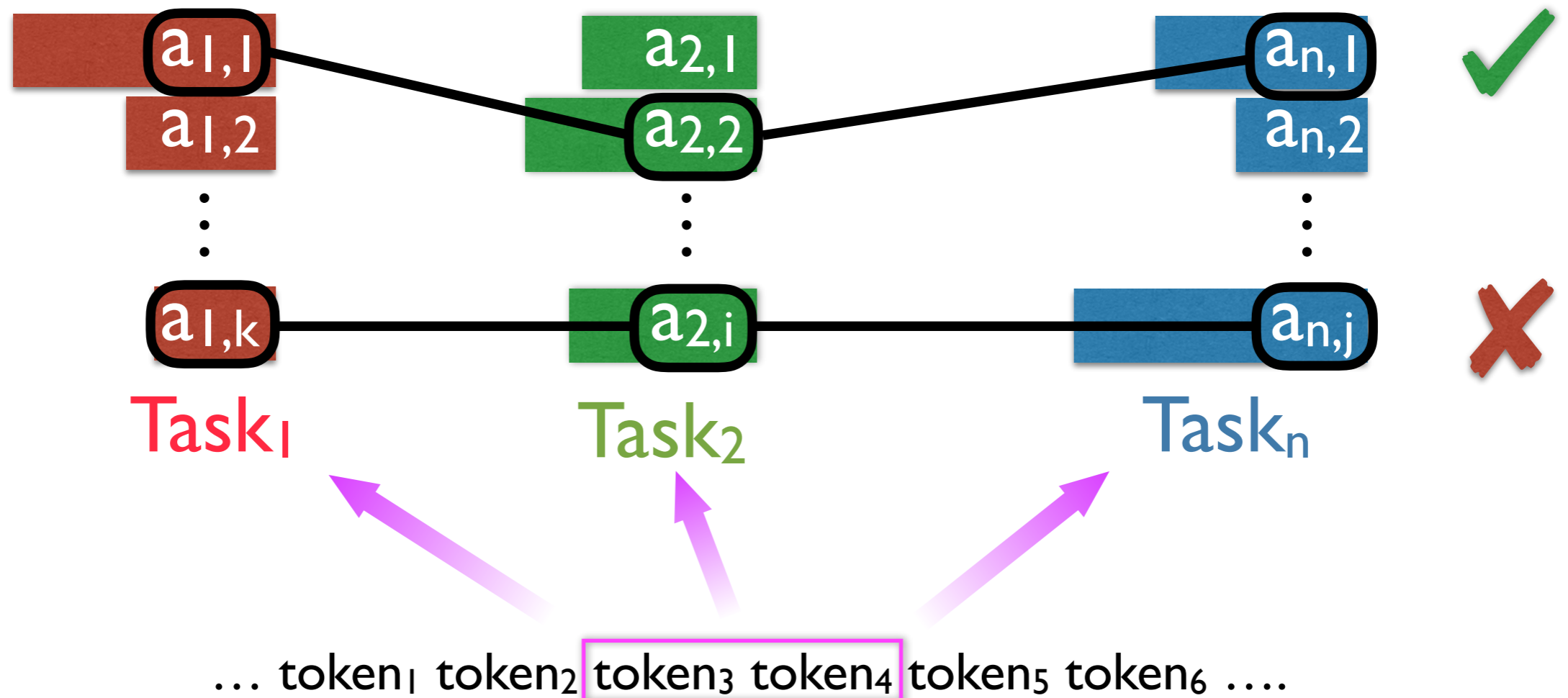
Abstracting



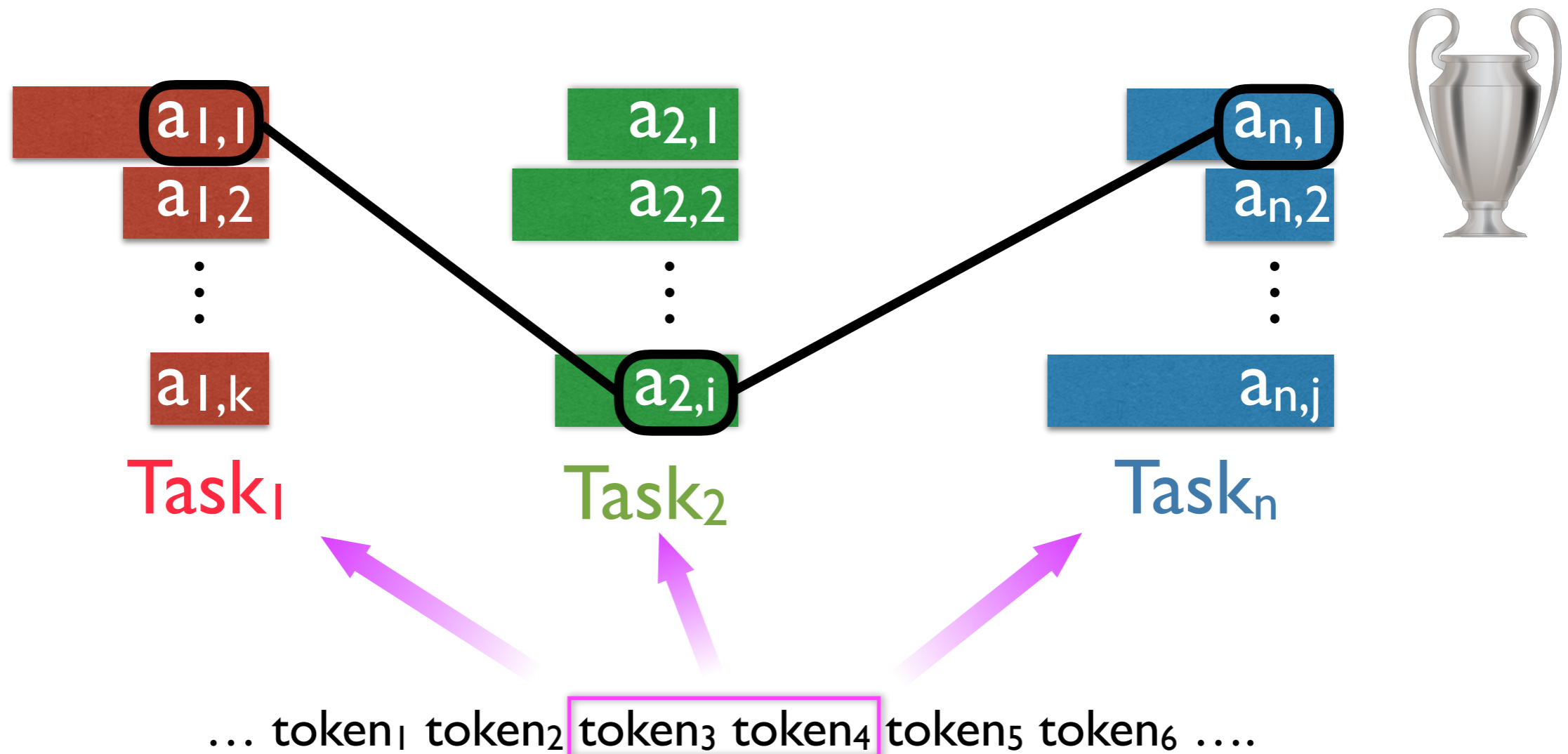
Abstracting



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Abstracting

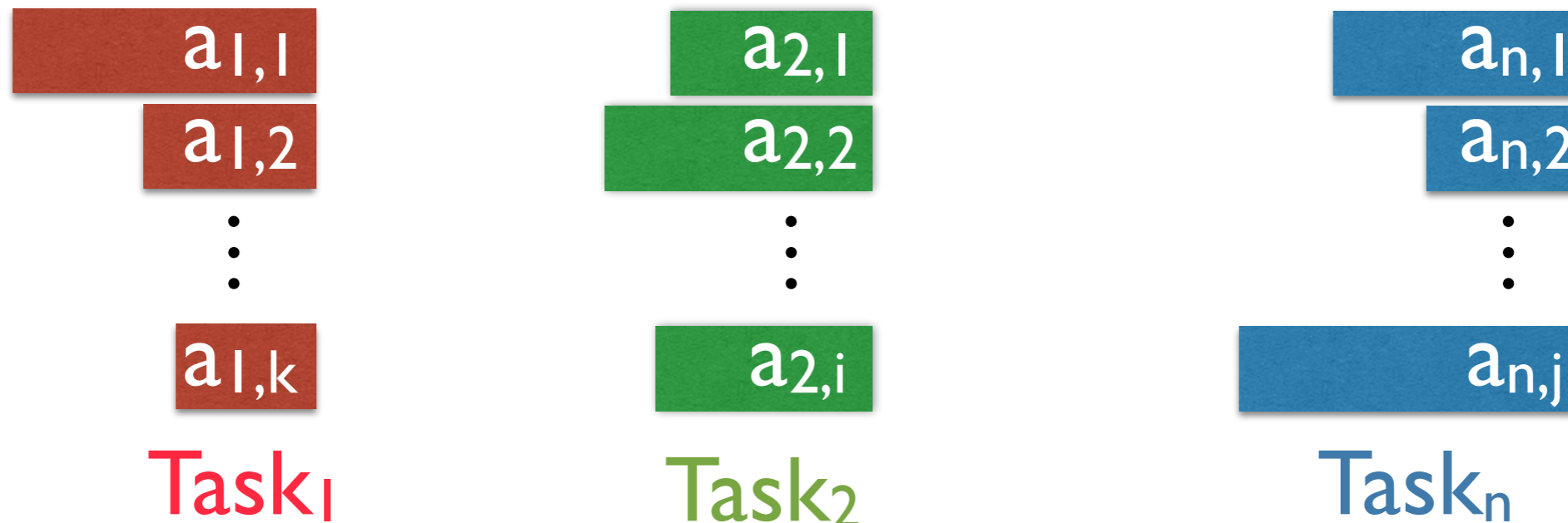
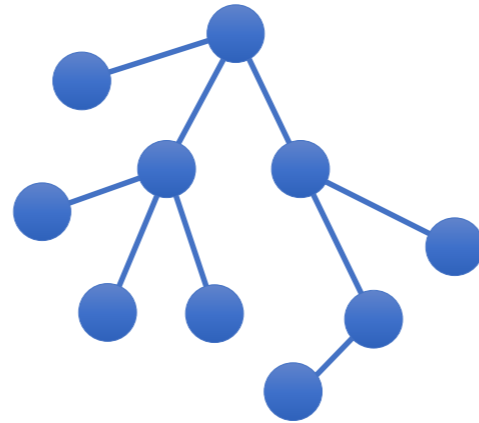


RESEARCH PROBLEM

How can we assess and improve the coherence of the various NLP annotations on an entity mention?

In a nutshell

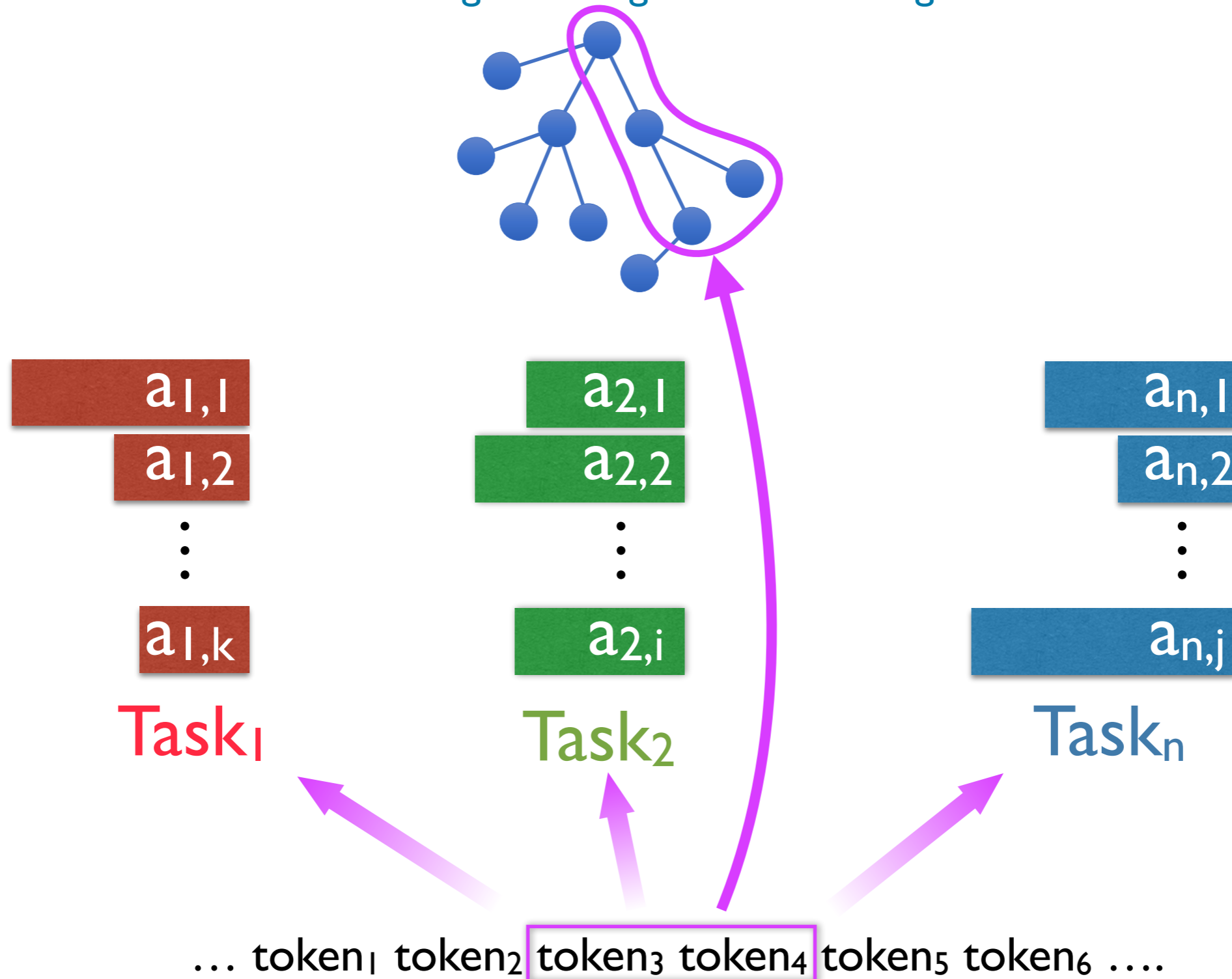
ontological background knowledge



... token₁ token₂ token₃ token₄ token₅ token₆

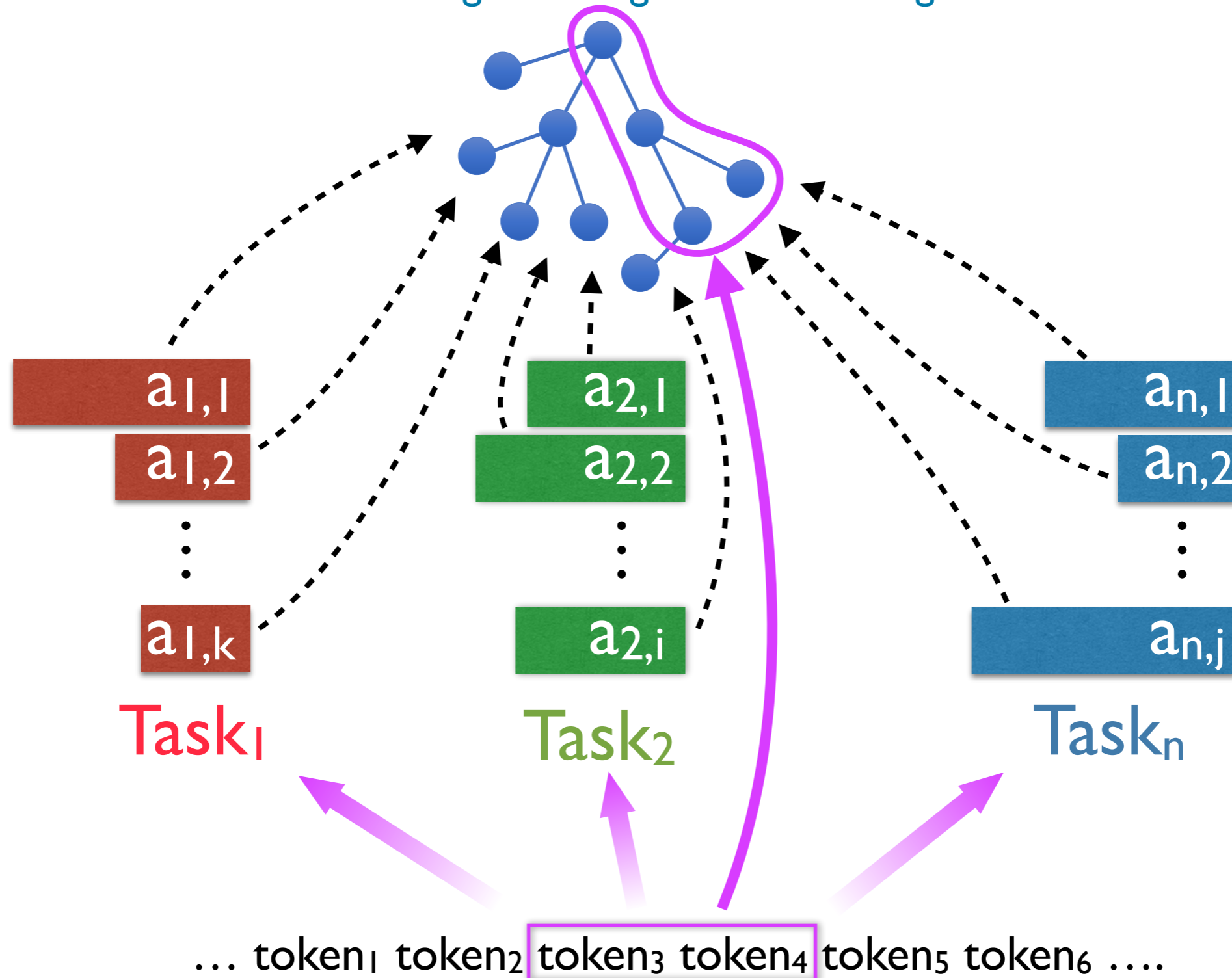
In a nutshell

ontological background knowledge



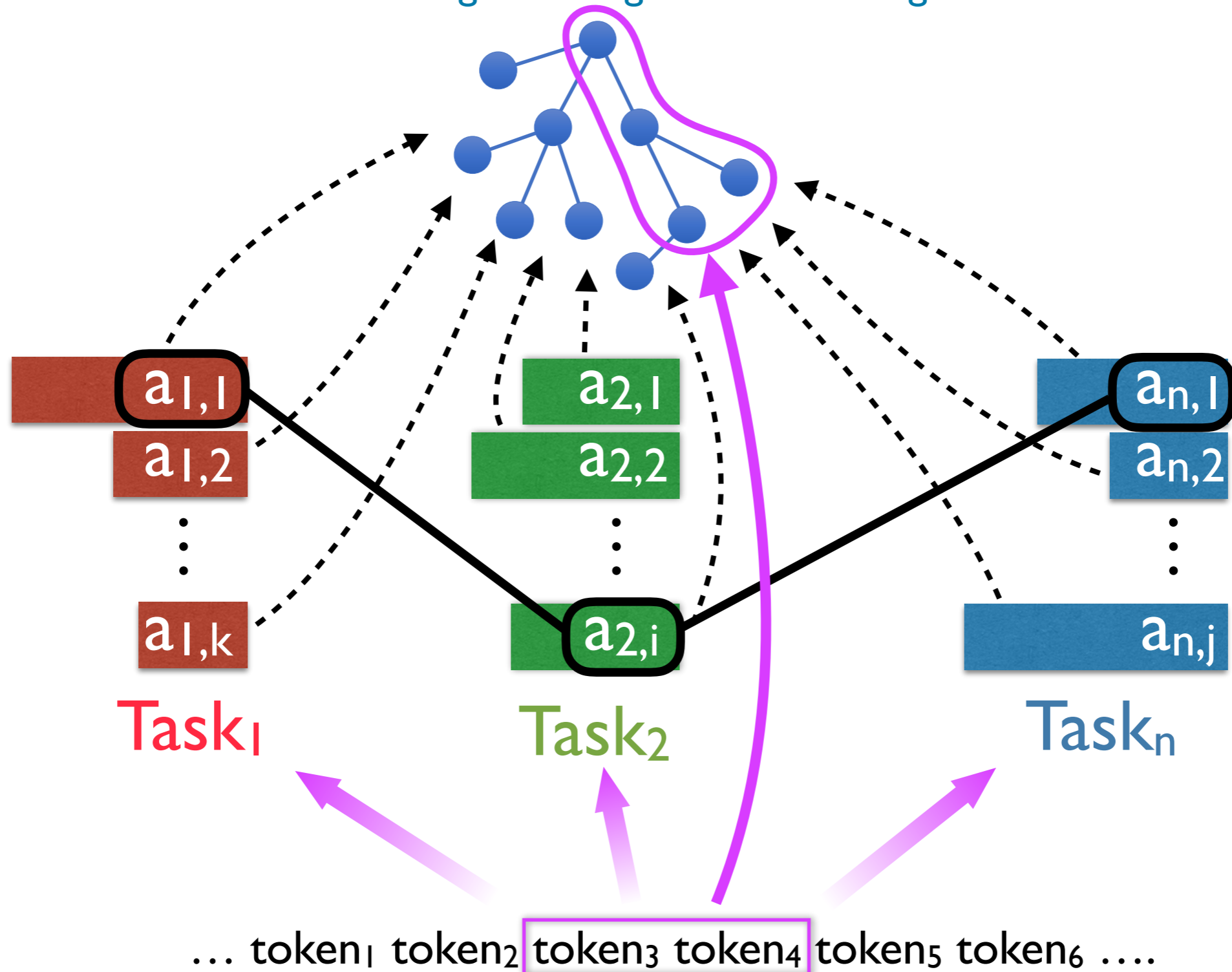
In a nutshell

ontological background knowledge



In a nutshell

ontological background knowledge



Contributions



Marco Rospocher, Francesco Corcoglioniti

Joint Posterior Revision of NLP Annotations via Ontological Knowledge

IJCAI-18



Marco Rospocher

An Ontology-Driven Probabilistic Soft Logic Approach to Improve NLP Entity Annotations

ISWC-18

Contributions

- A concrete instantiation of the **models for NERC and EL** (using YAGO as ontological knowledge)
- **Application** of the NERC and EL models **to revise** the annotations of **Stanford NER** and **DBpedia Spotlight**

Contributions



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JPARK

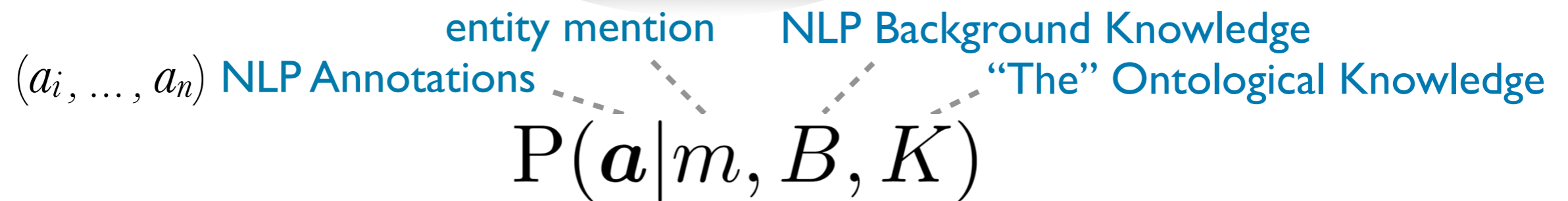


The JPARK Model

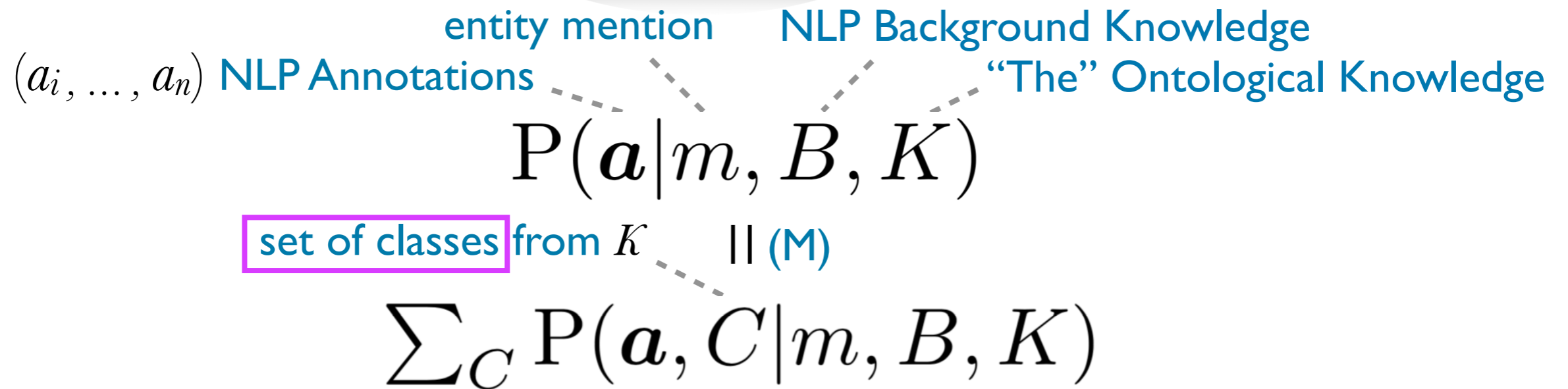


$$P(\mathbf{a}|m, B, K)$$

The JPARK Model



The JPARK Model



The JPARK Model



(a_i, \dots, a_n) NLP Annotations entity mention NLP Background Knowledge “The” Ontological Knowledge

$$P(\mathbf{a} | m, B, K)$$

set of classes from K || (M)

$$\sum_C P(\mathbf{a}, C | m, B, K)$$

|| (CP)

$$P(C | m, B, K) \cdot P(\mathbf{a} | m, B, K, C)$$

The JPARK Model



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|| (CIA-I)

$$\prod_i P(a_i | m, B, K, C)$$

The JPARK Model



entity mention NLP Background Knowledge
 NLP Annotations “The” Ontological Knowledge
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|| (CIA-I)

$$\prod_i P(a_i | m, B, K, C)$$

|| (CP)

$$\frac{\prod_i P(a_i, C | m, B, K)}{P(C | m, B, K)^n}$$

The JPARK Model



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set of classes from K || (M)

$$\sum_C P(\mathbf{a}, C | m, B, K)$$

||

$$\frac{\prod_i P(a_i, C | m, B, K)}{P(C | m, B, K)^{n-1}}$$

The JPARK Model

The logo for JPARK features the word "JPARK" in a bold, black, sans-serif font. A thick, black, curved line arches over the letters "PARK", resembling a stylized eye or a protective shield. Below this arch is a lighter, semi-transparent version of the same arch, creating a shadow effect.

$$P(C|m, B, K)$$

$$P(a_i, C|m, B, K)$$

The JPARK Model

The logo for JPARK consists of the letters 'JPARK' in a bold, blue, sans-serif font. Below the letters is a thick, black, curved line that resembles a stylized eye or a wide smile. This line has a subtle gradient and a slight shadow underneath, giving it a three-dimensional appearance.

$$P(C|m, B, K) \stackrel{(M^*)}{=} \left(\prod_i \sum_{a_i} P(a_i, C|m, B, K) \right)^{\frac{1}{n}}$$

$$P(a_i, C|m, B, K)$$

The JPARK Model



$$P(C|m, B, K) \stackrel{(M^*)}{=} \left(\prod_i \sum_{a_i} P(a_i, C|m, B, K) \right)^{\frac{1}{n}}$$

$$P(a_i, C|m, B, K) \stackrel{(CP)}{=} P(a_i|m, B, K) \cdot P(C|a_i, m, B, K)$$

The JPARK Model



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(CIA-2) ||

$$P(a_i|m, B)$$

The JPARK Model



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(CIA-2) ||

|| (CIA-3)

$$P(a_i|m, B)$$

$$P(C|a_i, K)$$

The JPARK Model



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(CIA-2) ||

|| (CIA-3)

$$P(a_i|m, B)$$

$$P(C|a_i, K)$$

confidence score

The JPARK Model



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(CIA-2) ||

$$P(a_i|m, B)$$

confidence score

|| (CIA-3)

$$P(C|a_i, K)$$

learned from data

The JPARK Model



$$P(\mathbf{a}|m, B, K)$$

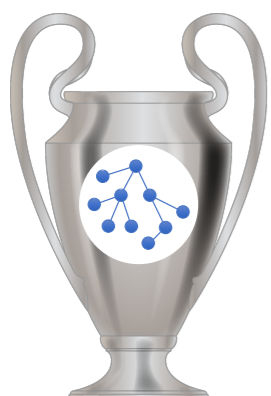


$$P(a_i|m, B)$$



$$P(C|a_i, K)$$

The JPARK Model



$$= \arg \max_{\mathbf{a}} P(\mathbf{a} | m, B, K)$$

$$P(a_i | m, B)$$

$$P(C | a_i, K)$$

JPARK



NERC and EL Model

Ontological Background Knowledge

6,016,695 entities

Taxonomy of 568,255 classes



yAGO
select knowledge

[Suchanek et al., 2007]

Ontological Background Knowledge

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+



WIKIPEDIA

The Free Encyclopedia

(only ingoing links)

Estimating $P(C|a_{\text{NERC}}, K)$

Leverage a **gold standard corpus** G annotated with NERC types and ontological classes (or EL annotations)

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Leverage a **gold standard corpus** G annotated with NERC types and ontological classes (or EL annotations)

$$\approx \frac{\overset{\text{\# co-occurences}}{n_G(C, a_{\text{NERC}})}}{\sum_{C'} n_G(C', a_{\text{NERC}})}$$

Estimating $P(C|a_{\text{NERC}}, K)$

$$\frac{n_G(C, a_{\text{NERC}})}{\sum_{C'} n_G(C', a_{\text{NERC}})}$$

Estimating $P(C|a_{\text{NERC}}, K)$

$$\alpha \cdot P(C|K) + (1 - \alpha) \cdot P(C|a_{\text{NERC}}, G) \\ \parallel \\ \frac{n_G(C, a_{\text{NERC}})}{\sum_{C'} n_G(C', a_{\text{NERC}})}$$

Estimating $P(C|a_{\text{NERC}}, K)$

$$\alpha \cdot P(C|K) + (1 - \alpha) \cdot P(C|a_{\text{NERC}}, G)$$
$$\parallel \qquad \qquad \qquad \parallel$$
$$\frac{n_K(C)}{\sum_{C'} n_K(C')}$$
$$\frac{n_G(C, a_{\text{NERC}})}{\sum_{C'} n_G(C', a_{\text{NERC}})}$$

Prior (popularity based
on entity ingoing links)

Estimating $P(C|a_{\text{NERC}}, K)$

$$\alpha \cdot P(C|K) + (1 - \alpha) \cdot P(C|a_{\text{NERC}}, G)$$
$$\parallel \qquad \qquad \qquad \parallel$$
$$\frac{n_K(C)}{\sum_{C'} n_K(C')}$$
$$\frac{n_G(C, a_{\text{NERC}})}{\sum_{C'} n_G(C', a_{\text{NERC}})}$$

Prior (popularity based on entity ingoing links)

Consider only class sets restricted to **popular classes**


Estimating $P(C|a_{\text{EL}}, K)$

Leverage **alignments** between EL Knowledge Base and  **yAGO**
select knowledge

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Leverage **alignments** between EL Knowledge Base and  **yAGO**
select knowledge

$$\mathbf{1}_{\{C_K(a_{\text{EL}})\}}(C) \begin{cases} 1 & \text{entity } a_{\text{EL}} \text{ is "instance" of } C \\ 0 & \text{otherwise} \end{cases}$$

 **classes of the entity from linking**

JPARK



Application and Evaluation

Tools

- **NERC: Stanford CoreNLP** [Finkel et al., 2005]

- **EL: DBpediaSpotlight** [Daiber et al., 2013]

NERC+EL Datasets

- AIDA CoNLL-YAGO [Hoffart et al., 2011]
- MEANTIME [Minard et al., 2016]
- TAC-KBP [Ji et al., 2011]

NERC+EL Datasets

- AIDA CoNLL-YAGO [Hoffart et al., 2011]

$P(C|a_{\text{NERC}}, K)$ learned from AIDA CoNLL-YAGO (**train**)

- MEANTIME [Minard et al., 2016]

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Research Question

Does the JPARK posteriori joint revision of the annotations from Stanford NER and DBpedia Spotlight, via YAGO, **improve** their NERC and EL performances?

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Stanford CoreNLP



JPARK



Stanford CoreNLP

Results

		type			link			type+link		
		<i>P</i>	<i>R</i>	<i>F</i> ₁	<i>P</i>	<i>R</i>	<i>F</i> ₁	<i>P</i>	<i>R</i>	<i>F</i> ₁
AIDA (5616)	<i>standard</i>	.943	.875	.908	.662	.652	.656	.634	.625	.630
	<i>with JPARK</i>	.950	.881	.914	.671	.654	.662	.655	.637	.646
	Δ	.007	.006	.006	.009	.002	.006	.021	.012	.016
MEANTIME (792)	<i>standard</i>	.882	.695	.777	.703	.556	.621	.635	.502	.561
	<i>with JPARK</i>	.914	.720	.805	.705	.557	.622	.670	.530	.592
	Δ	.032	.025	.028	.002	.001	.001	.035	.028	.031
TAC-KBP (4969)	<i>standard</i>	.911	.652	.760	.401	.423	.412	.367	.386	.376
	<i>with JPARK</i>	.926	.663	.772	.412	.426	.419	.389	.402	.395
	Δ	.015	.011	.012	.011	.003	.007	.022	.016	.019

Bold = statistical significant (approx. rand. test)

Results

		type			link			type+link		
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ISWC-18





Don't miss: 21 Nov 2018
Lise Getoor Keynote!



in a nutshell (1/3)

1.2 : $\text{WorksFor}(b, c) \wedge \text{BossOf}(b, e) \rightarrow \text{WorksFor}(e, c)$



in a nutshell (1/3)

weight 1.2 : $\text{WorksFor}(b, c) \wedge \text{BossOf}(b, e) \rightarrow \text{WorksFor}(e, c)$



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variable



in a nutshell (1/3)

$$\underbrace{1.2}_{\text{weight}} : \text{WorksFor}(\underbrace{b, c}_{\text{variable}}) \wedge \underbrace{\text{BossOf}(b, e)}_{\text{predicate}} \rightarrow \text{WorksFor}(e, c)$$



in a nutshell (1/3)

$$\underbrace{1.2}_{\text{weight}} : \underbrace{\text{WorksFor}(b, c)}_{\text{variable}} \wedge \underbrace{\text{BossOf}(b, e)}_{\text{predicate}} \rightarrow \underbrace{\text{WorksFor}(e, c)}_{\text{atom}}$$



in a nutshell (1/3)

$$\text{weight } \underline{1.2} : \frac{\text{body}}{\text{variable } \underline{b, c} \wedge \text{predicate } \underline{\text{BossOf}(b, e)} \rightarrow \text{atom } \underline{\text{WorksFor}(e, c)}}$$



in a nutshell (1/3)

$$\text{weight } \underline{1.2} : \frac{\text{body}}{\text{variable } \underline{b, c} \wedge \text{predicate } \underline{\text{BossOf}(b, e)}} \rightarrow \frac{\text{head}}{\text{atom } \underline{\text{WorksFor}(e, c)}}$$



in a nutshell (1/3)

1.2 : $\text{WorksFor}(b, c) \wedge \text{BossOf}(b, e) \rightarrow \text{WorksFor}(e, c)$

grounding

$\text{WorksFor}(\textit{John}, \textit{FBK})$



in a nutshell (1/3)

1.2 : $\text{WorksFor}(b, c) \wedge \text{BossOf}(b, e) \rightarrow \text{WorksFor}(e, c)$

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$\text{WorksFor}(\textit{John}, \textit{FBK})$
soft-truth value $\in [0, 1]$



in a nutshell (1/3)

1.2 : $\text{WorksFor}(b, c) \wedge \text{BossOf}(b, e) \rightarrow \text{WorksFor}(e, c)$

grounding

$\text{WorksFor}(\textit{John}, \textit{FBK})$
soft-truth value $\in [0, 1]$

Interpretation $I : \{\text{ground atoms}\} \rightarrow [0, 1]^n$



in a nutshell (2/3)

Lukasiewicz
t-norm/co-norm

$$I(a_1) \wedge I(a_2) = \max\{I(a_1) + I(a_2) - 1, 0\}$$

$$I(a_1) \vee I(a_2) = \min\{I(a_1) + I(a_2), 1\}$$

$$\neg I(a_1) = 1 - I(a_1)$$



in a nutshell (2/3)

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t-norm/co-norm

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$$\neg I(a_1) = 1 - I(a_1)$$

rule is satisfied iff $I(\text{body}) \leq I(\text{head})$



in a nutshell (2/3)

Lukasiewicz
t-norm/co-norm

$$I(a_1) \wedge I(a_2) = \max\{I(a_1) + I(a_2) - 1, 0\}$$

$$I(a_1) \vee I(a_2) = \min\{I(a_1) + I(a_2), 1\}$$

$$\neg I(a_1) = 1 - I(a_1)$$

rule is satisfied iff $I(\text{body}) \leq I(\text{head})$

distance to satisfaction $d(r) = \max\{0, I(\text{body}) - I(\text{head})\}$



in a nutshell (2/3)

Lukasiewicz
t-norm/co-norm

$$I(a_1) \wedge I(a_2) = \max\{I(a_1) + I(a_2) - 1, 0\}$$

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$\text{WorksFor}(\text{John}, \text{FBK}) \wedge \text{BossOf}(\text{John}, \text{Jack}) \rightarrow \text{WorksFor}(\text{Jack}, \text{FBK})$



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0.6

0.6

0.5



$\text{WorksFor}(\text{John}, \text{FBK}) \wedge \text{BossOf}(\text{John}, \text{Jack}) \rightarrow \text{WorksFor}(\text{Jack}, \text{FBK})$



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distance to satisfaction $d(r) = \max\{0, I(\text{body}) - I(\text{head})\}$

0.6	0.6	0.5	✓
WorksFor(<i>John</i> , <i>FBK</i>)	\wedge BossOf(<i>John</i> , <i>Jack</i>)	\rightarrow WorksFor(<i>Jack</i> , <i>FBK</i>)	
0.8	0.9	0.3	✗



in a nutshell (2/3)

Lukasiewicz
t-norm/co-norm

$$I(a_1) \wedge I(a_2) = \max\{I(a_1) + I(a_2) - 1, 0\}$$

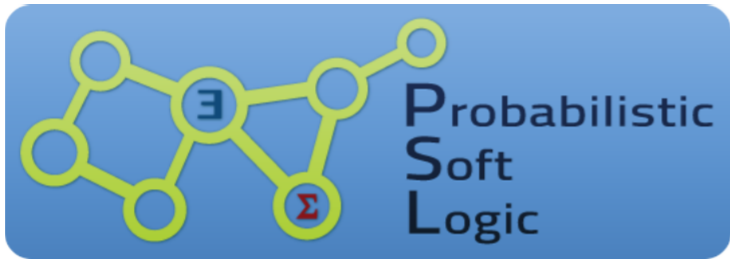
$$I(a_1) \vee I(a_2) = \min\{I(a_1) + I(a_2), 1\}$$

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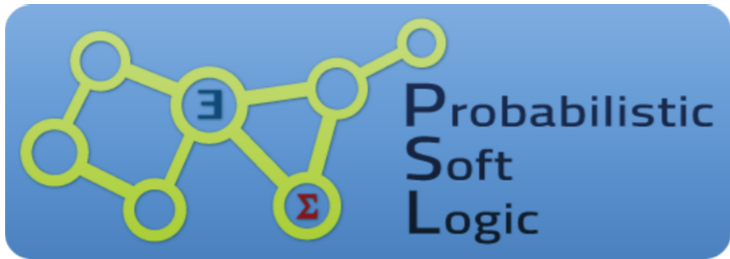
distance to satisfaction $d(r) = \max\{0, I(\text{body}) - I(\text{head})\}$

0.6	0.6	0.5	✓
WorksFor(<i>John</i> , <i>FBK</i>)	∧ BossOf(<i>John</i> , <i>Jack</i>)	→ WorksFor(<i>Jack</i> , <i>FBK</i>)	
0.8	0.9	0.3	✗
		$d(r) = 0.4$	



in a nutshell (3/3)

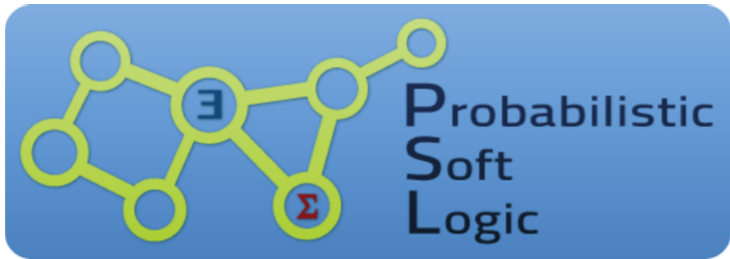
$$f(I) = \frac{1}{Z} \exp \left[- \sum_{r \in R} w_r d(r)^p \right]$$



in a nutshell (3/3)

$$f(I) = \frac{1}{Z} \exp \left[- \sum_{r \in R} w_r d(r)^p \right]$$

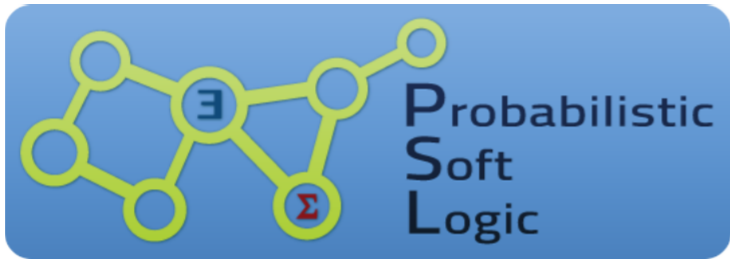
constant \nearrow



in a nutshell (3/3)

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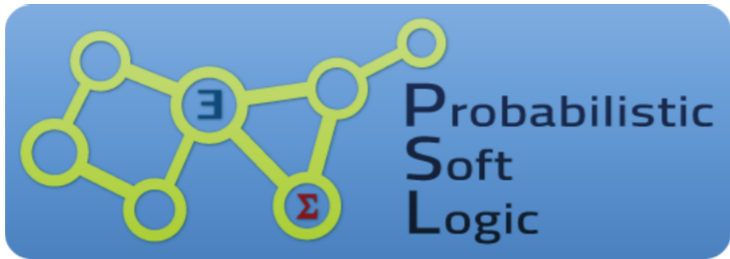
constant \nearrow \nwarrow all rules



in a nutshell (3/3)

$$f(I) = \frac{1}{Z} \exp \left[- \sum_{r \in R} w_r d(r)^p \right]$$

constant \nearrow $\frac{1}{Z}$ \nwarrow weight \nearrow w_r \nwarrow all rules \nearrow $\sum_{r \in R}$

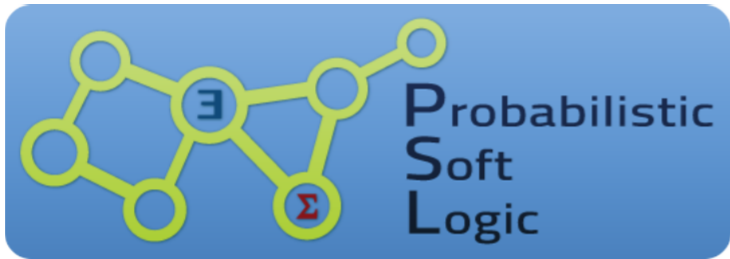


in a nutshell (3/3)

weight distance to satisfaction

$$f(I) = \frac{1}{Z} \exp \left[- \sum_{r \in R} w_r d(r)^p \right]$$

constant \nearrow \nwarrow all rules



in a nutshell (3/3)

$$f(I) = \frac{1}{Z} \exp \left[- \sum_{r \in R} w_r d(r)^p \right]$$

constant \rightarrow $\frac{1}{Z}$

weight \rightarrow w_r

distance to satisfaction \rightarrow $d(r)$

$\{1,2\}$ \rightarrow p

all rules \rightarrow $\sum_{r \in R}$



in a nutshell (3/3)

$$f(I) = \frac{1}{Z} \exp \left[- \sum_{r \in R} w_r d(r)^p \right]$$

constant \nearrow $\frac{1}{Z}$ \nwarrow weight \nearrow distance to satisfaction \nwarrow $\{1,2\}$
 \nwarrow all rules \nearrow

Most Probable Explanation (MPE): overall interpretation with the maximum probability

PSL
TEA

PSL
4
EA

NLP annotations → Classes

Classes → Annotation coherence

NLP annotations Classes

M mention

A_i^T candidate annotation for task T on M

c ontological class from background knowledge K

NLP annotations Classes

M mention

A_i^T candidate annotation for task T on M

c ontological class from background knowledge K

$$w(M, A_i^T) : \text{Ann}_T(M, A_i^T) \wedge \text{ImpCl}_T(A_i^T, c) \rightarrow \text{ClAnn}_T(M, A_i^T, c)$$

NLP annotations Classes

M mention

A_i^T candidate annotation for task T on M

c ontological class from background knowledge K

NLP annotation

$$w(M, A_i^T) : \underline{\text{Ann}_T(M, A_i^T)} \wedge \text{ImpCl}_T(A_i^T, c) \rightarrow \text{ClAnn}_T(M, A_i^T, c)$$

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confidence score

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confidence score

implied class

NLP annotations Classes

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A_i^T candidate annotation for task T on M

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NLP annotation

implied class annotation

$$\underline{w(M, A_i^T)} : \underline{\text{Ann}_T(M, A_i^T)} \wedge \underline{\text{ImpCl}_T(A_i^T, c)} \rightarrow \underline{\text{ClAnn}_T(M, A_i^T, c)}$$

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confidence score

implied class



NLP annotations Classes

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A_i^T candidate annotation for task T on M

c ontological class from background knowledge K



NLP annotation

implied class annotation

$$\underline{w(M, A_i^T)} : \underline{\text{Ann}_T(M, A_i^T)} \wedge \underline{\text{ImpCl}_T(A_i^T, c)} \rightarrow \underline{\text{ClAnn}_T(M, A_i^T, c)}$$

confidence score

implied class



NLP annotations Classes

M mention

A_i^T candidate annotation for task T on M

c ontological class from background knowledge K



NLP annotation



implied class annotation

$$\underline{w(M, A_i^T)} : \underline{\text{Ann}_T(M, A_i^T)} \wedge \underline{\text{ImpCl}_T(A_i^T, c)} \rightarrow \underline{\text{ClAnn}_T(M, A_i^T, c)}$$

confidence score

implied class



NLP annotations  Classes

$\text{ImpCl}_{NERC}(t, c)$

NLP annotations Classes

$$\text{ImpCl}_{NERC}(t, c)$$

Leverage a **gold standard corpus** G annotated with NERC types and ontological classes (or EL annotations)

NLP annotations Classes

$$\text{ImpCl}_{NERC}(t, c)$$

Leverage a **gold standard corpus** G annotated with NERC types and ontological classes (or EL annotations)

$$1.0 : \text{Gold}_{NERC}(m, t) \wedge \text{ImpCl}_{NERC}(t, c) \rightarrow \text{Gold}_C(m, c)$$

$$1.0 : \text{Gold}_{NERC}(m, t) \wedge \neg \text{ImpCl}_{NERC}(t, c) \rightarrow \neg \text{Gold}_C(m, c)$$

NLP annotations Classes

$$\text{ImpCl}_{NERC}(t, c)$$

Leverage a **gold standard corpus** G annotated with NERC types and ontological classes (or EL annotations)

$$1.0 : \checkmark \text{Gold}_{NERC}(m, t) \wedge \text{ImpCl}_{NERC}(t, c) \rightarrow \checkmark \text{Gold}_C(m, c)$$

$$1.0 : \checkmark \text{Gold}_{NERC}(m, t) \wedge \neg \text{ImpCl}_{NERC}(t, c) \rightarrow \neg \checkmark \text{Gold}_C(m, c)$$

NLP annotations Classes

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$$1.0 : \checkmark \text{Gold}_{NERC}(m, t) \wedge \text{ImpCl}_{NERC}(t, c) \rightarrow \checkmark \text{Gold}_C(m, c)$$

$$1.0 : \checkmark \text{Gold}_{NERC}(m, t) \wedge \neg \text{ImpCl}_{NERC}(t, c) \rightarrow \neg \checkmark \text{Gold}_C(m, c)$$

$$\text{ImpCl}_{EL}(e, c)$$

NLP annotations Classes

$$\text{ImpCl}_{NERC}(t, c)$$

Leverage a **gold standard corpus** G annotated with NERC types and ontological classes (or EL annotations)

$$1.0 : \checkmark \text{Gold}_{NERC}(m, t) \wedge \text{ImpCl}_{NERC}(t, c) \rightarrow \checkmark \text{Gold}_C(m, c)$$

$$1.0 : \checkmark \text{Gold}_{NERC}(m, t) \wedge \neg \text{ImpCl}_{NERC}(t, c) \rightarrow \neg \checkmark \text{Gold}_C(m, c)$$

$$\text{ImpCl}_{EL}(e, c)$$

Leverage **alignments** between EL Knowledge Base and Background Knowledge K

NLP annotations \rightarrow Classes

$$\text{ImpCl}_{NERC}(t, c)$$

Leverage a **gold standard corpus** G annotated with NERC types and ontological classes (or EL annotations)

$$1.0 : \checkmark \text{Gold}_{NERC}(m, t) \wedge \text{ImpCl}_{NERC}(t, c) \rightarrow \checkmark \text{Gold}_C(m, c)$$

$$1.0 : \checkmark \text{Gold}_{NERC}(m, t) \wedge \neg \text{ImpCl}_{NERC}(t, c) \rightarrow \neg \checkmark \text{Gold}_C(m, c)$$

$$\text{ImpCl}_{EL}(e, c) \begin{cases} 1 & \text{entity } e \text{ is instance of } c \\ 0 & \text{otherwise} \end{cases}$$

Leverage **alignments** between EL Knowledge Base and Background Knowledge K

Classes Annotation coherence

$$w_1 : \text{CIAnn}_{NERC}(m, t, c) \wedge \text{CIAnn}_{EL}(m, e, c) \rightarrow \text{Ann}_{PSL}(m, t, e)$$

$$w_2 : \text{CIAnn}_{NERC}(m, t, c) \wedge \neg \text{CIAnn}_{EL}(m, e, c) \rightarrow \neg \text{Ann}_{PSL}(m, t, e)$$

$$w_3 : \neg \text{CIAnn}_{NERC}(m, t, c) \wedge \text{CIAnn}_{EL}(m, e, c) \rightarrow \neg \text{Ann}_{PSL}(m, t, e)$$

Classes Annotation coherence

coherence estimation

$$w_1 : \text{CIAnn}_{NERC}(m, t, c) \wedge \text{CIAnn}_{EL}(m, e, c) \rightarrow \text{Ann}_{PSL}(m, t, e)$$

$$w_2 : \text{CIAnn}_{NERC}(m, t, c) \wedge \neg \text{CIAnn}_{EL}(m, e, c) \rightarrow \neg \text{Ann}_{PSL}(m, t, e)$$

$$w_3 : \neg \text{CIAnn}_{NERC}(m, t, c) \wedge \text{CIAnn}_{EL}(m, e, c) \rightarrow \neg \text{Ann}_{PSL}(m, t, e)$$

Classes Annotation coherence

coherence estimation

$$w_1: \text{CIAnn}_{NERC}(m, t, c) \wedge \text{CIAnn}_{EL}(m, e, c) \rightarrow \text{Ann}_{PSL}(m, t, e)$$

$$w_2: \text{CIAnn}_{NERC}(m, t, c) \wedge \neg \text{CIAnn}_{EL}(m, e, c) \rightarrow \neg \text{Ann}_{PSL}(m, t, e)$$

$$w_3: \neg \text{CIAnn}_{NERC}(m, t, c) \wedge \text{CIAnn}_{EL}(m, e, c) \rightarrow \neg \text{Ann}_{PSL}(m, t, e)$$

hyperparameters

MPE Inference

- Determine soft-truth value of Ann_{PSL} for all combination of annotations for a given mention
- Best combination: highest soft-truth value of Ann_{PSL}
- Trust model prediction only if above a given threshold

Example

Lincoln is based in Michigan.

Example

Lincoln is based in Michigan.

0.9 : $\text{Ann}_{NERC}(\text{L}, \text{ORG}) \wedge \text{ImpCl}_{NERC}(\text{ORG}, c) \rightarrow \text{ClAnn}_{NERC}(\text{L}, \text{ORG}, c)$

0.1 : $\text{Ann}_{NERC}(\text{L}, \text{PER}) \wedge \text{ImpCl}_{NERC}(\text{PER}, c) \rightarrow \text{ClAnn}_{NERC}(\text{L}, \text{PER}, c)$

Example

Lincoln is based in Michigan.

0.9 : $\text{Ann}_{NERC}(\text{L}, \text{ORG}) \wedge \text{ImpCl}_{NERC}(\text{ORG}, c) \rightarrow \text{ClAnn}_{NERC}(\text{L}, \text{ORG}, c)$

0.1 : $\text{Ann}_{NERC}(\text{L}, \text{PER}) \wedge \text{ImpCl}_{NERC}(\text{PER}, c) \rightarrow \text{ClAnn}_{NERC}(\text{L}, \text{PER}, c)$

0.5 : $\text{Ann}_{EL}(\text{L}, \text{A. Lincoln}) \wedge \text{ImpCl}_{EL}(\text{A. Lincoln}, c) \rightarrow \text{ClAnn}_{EL}(\text{L}, \text{A. Lincoln}, c)$

0.3 : $\text{Ann}_{EL}(\text{L}, \text{Lincoln MC}) \wedge \text{ImpCl}_{EL}(\text{Lincoln MC}, c) \rightarrow \text{ClAnn}_{EL}(\text{L}, \text{Lincoln MC}, c)$

0.2 : $\text{Ann}_{EL}(\text{L}, \text{Lincoln UK}) \wedge \text{ImpCl}_{EL}(\text{Lincoln UK}, c) \rightarrow \text{ClAnn}_{EL}(\text{L}, \text{Lincoln UK}, c)$

Example

Lincoln is based in Michigan.

$$0.9 : \text{Ann}_{NERC}(L, \text{ORG}) \wedge \text{ImpCl}_{NERC}(\text{ORG}, c) \rightarrow \text{ClAnn}_{NERC}(L, \text{ORG}, c)$$

$$0.1 : \text{Ann}_{NERC}(L, \text{PER}) \wedge \text{ImpCl}_{NERC}(\text{PER}, c) \rightarrow \text{ClAnn}_{NERC}(L, \text{PER}, c)$$

$$0.5 : \text{Ann}_{EL}(L, \text{A. Lincoln}) \wedge \text{ImpCl}_{EL}(\text{A. Lincoln}, c) \rightarrow \text{ClAnn}_{EL}(L, \text{A. Lincoln}, c)$$

$$0.3 : \text{Ann}_{EL}(L, \text{Lincoln MC}) \wedge \text{ImpCl}_{EL}(\text{Lincoln MC}, c) \rightarrow \text{ClAnn}_{EL}(L, \text{Lincoln MC}, c)$$

$$0.2 : \text{Ann}_{EL}(L, \text{Lincoln UK}) \wedge \text{ImpCl}_{EL}(\text{Lincoln UK}, c) \rightarrow \text{ClAnn}_{EL}(L, \text{Lincoln UK}, c)$$

$$10 : \text{ClAnn}_{NERC}(m, t, c) \wedge \text{ClAnn}_{EL}(m, e, c) \rightarrow \text{Ann}_{PSL}(m, t, e)$$

$$10 : \text{ClAnn}_{NERC}(m, t, c) \wedge \neg \text{ClAnn}_{EL}(m, e, c) \rightarrow \neg \text{Ann}_{PSL}(m, t, e)$$

$$10 : \neg \text{ClAnn}_{NERC}(m, t, c) \wedge \text{ClAnn}_{EL}(m, e, c) \rightarrow \neg \text{Ann}_{PSL}(m, t, e)$$

The logo consists of the letters 'PSL' stacked vertically above the number '4', which is positioned above the letters 'EA'. The 'P' and 'S' are connected to the 'L', and the '4' is connected to the 'E'. The letters are in a black, serif font.

PSL
4
EA

Application and Evaluation

Background Knowledge

6,016,695 entities

Taxonomy of 568,255 classes



yAGO
select knowledge

[Suchanek et al., 2007]

Tools

- **NERC: Stanford CoreNLP** [Finkel et al., 2005]

- **EL: DBpediaSpotlight** [Daiber et al., 2013]

NERC+EL Datasets

- AIDA CoNLL-YAGO [Hoffart et al., 2011]
- MEANTIME [Minard et al., 2016]
- TAC-KBP [Ji et al., 2011]

NERC+EL Datasets

- AIDA CoNLL-YAGO [Hoffart et al., 2011]
ImpCl_{NERC} learned from AIDA CoNLL-YAGO (**train**)
- MEANTIME [Minard et al., 2016]
- TAC-KBP [Ji et al., 2011]

ImpCl_{NERC}

PER (4522)	ORG (4564)
PhysicalEntity100001930 (.991)	YagoPermanentlyLocatedEntity (.945)
CausalAgent100007347 (.988)	Abstraction100002137 (.945)
Object100002684 (.963)	YagoLegalActorGeo (.938)
YagoLegalActorGeo (.963)	YagoLegalActor (.925)
Whole100003553 (.962)	Group100031264 (.924)
YagoLegalActor (.961)	SocialGroup107950920 (.923)
LivingThing100004258 (.960)	Organization108008335 (.914)
Organism100004475 (.960)	Association108049401 (.642)
Person100007846 (.960)	Club108227214 (.637)
WikicatLivingPeople (.850)	Unit108189659 (.340)

LOC (6689)	MISC (2764)
YagoPermanentlyLocatedEntity (.986)	YagoPermanentlyLocatedEntity (.843)
YagoLegalActorGeo (.967)	YagoLegalActorGeo (.679)
PhysicalEntity100001930 (.909)	PhysicalEntity100001930 (.614)
Object100002684 (.907)	Object100002684 (.609)
YagoGeoEntity (.905)	YagoGeoEntity (.591)
Location100027167 (.889)	Location100027167 (.572)
Region108630985 (.883)	Region108630985 (.571)
District108552138 (.866)	AdministrativeDistrict108491826 (.568)
AdministrativeDistrict108491826 (.865)	District108552138 (.568)
Country108544813 (.524)	Country108544813 (.549)

Research Question

Does the ontology-driven **PSL4EA** a posteriori joint revision of the annotations from Stanford NER and DBpedia Spotlight, **improve** their NERC and EL performances?

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Stanford CoreNLP



Results

		type			link			type+link		
		<i>P</i>	<i>R</i>	<i>F₁</i>	<i>P</i>	<i>R</i>	<i>F₁</i>	<i>P</i>	<i>R</i>	<i>F₁</i>
AIDA (5616)	<i>standard</i>	.943	.875	.908	.662	.652	.656	.634	.625	.630
	<i>with PSL4EA</i>	.947	.879	.912	.670	.659	.665	.646	.635	.640
	Δ	.004	.004	.004	.008	.007	.009	.012	.010	.010
MEANTIME (792)	<i>standard</i>	.882	.695	.777	.703	.556	.621	.635	.502	.561
	<i>with PSL4EA</i>	.902	.711	.795	.714	.564	.630	.667	.527	.589
	Δ	.020	.016	.018	.011	.008	.009	.032	.025	.028
TAC-KBP (4969)	<i>standard</i>	.911	.652	.760	.401	.423	.412	.367	.386	.376
	<i>with PSL4EA</i>	.925	.662	.772	.408	.430	.419	.384	.404	.394
	Δ	.014	.010	.012	.007	.007	.007	.017	.018	.018

bold = statistical significant (approx. rand. test)

Results

		type			link			type+link		
		<i>P</i>	<i>R</i>	<i>F</i> ₁	<i>P</i>	<i>R</i>	<i>F</i> ₁	<i>P</i>	<i>R</i>	<i>F</i> ₁
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Results

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bold = statistical significant (approx. rand. test)

Research Question

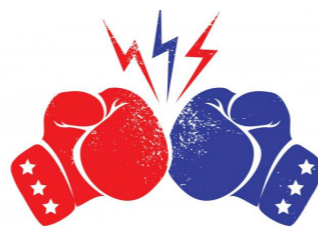
Does the ontology-driven **PSL4EA** a posteriori joint revision of the annotations from Stanford NER and DBpedia Spotlight, **improve** their NERC and EL performances?

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JPARK



PSI
4
EA

		type			link			type+link		
		<i>P</i>	<i>R</i>	<i>F</i> ₁	<i>P</i>	<i>R</i>	<i>F</i> ₁	<i>P</i>	<i>R</i>	<i>F</i> ₁
AIDA (5616)	<i>with JPARK</i>	.007	.006	.006	.009	.002	.006	.021	.012	.016
	<i>with PSL4EA</i>	.004	.004	.004	.008	.007	.009	.012	.010	.010
MEANTIME (792)	<i>with JPARK</i>	.032	.025	.028	.002	.001	.001	.035	.028	.031
	<i>with PSL4EA</i>	.020	.016	.018	.011	.008	.009	.032	.025	.028
TAC-KBP (4969)	<i>with JPARK</i>	.015	.011	.012	.011	.003	.007	.022	.016	.019
	<i>with PSL4EA</i>	.014	.010	.012	.007	.007	.007	.017	.018	.018



		type			link			type+link		
		<i>P</i>	<i>R</i>	<i>F</i> ₁	<i>P</i>	<i>R</i>	<i>F</i> ₁	<i>P</i>	<i>R</i>	<i>F</i> ₁
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- ✓ very fast
- ✓ simple model construction

		type			link			type+link		
		<i>P</i>	<i>R</i>	<i>F</i> ₁	<i>P</i>	<i>R</i>	<i>F</i> ₁	<i>P</i>	<i>R</i>	<i>F</i> ₁
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✓ very fast

✓ simple model construction

✓ intuitive formulation

✓ extensible to cross-mention information

Conclusions

- **Ontological knowledge does really help** improving NLP entity annotations
- Two approaches:  
- Instantiation of the models for the **NERC** and **EL** tasks

Conclusions

- **Empirical confirmation** (3 datasets) of the capability of the models to improve the quality of the annotations
- Applicable to “any” NERC and EL tools
- Future Work:
 - application to **other tasks** (e.g., SRL)
 - application to **fine-grained NERC**
 - Testing different background knowledge (e.g., **DBpedia, Wikidata**)
 - **cross-mention** coherence



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BPMN Ontology

dkm.fbk.eu/bpmn-ontology



Event & Situation Ontology
github.com/newsreader/eso



github.com/dkmfbk/TeXOwl

