# Matching and orbital integrals

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#### 1 Motivation

Consider a tulple of reductive groups over a number field  $F_0$ 

$$H_1 \hookrightarrow G \hookleftarrow H_2$$

and choose a good test function  $f = \prod_v f_v \in C_c^{\infty}(G(\mathbb{A}))$ . Main part of **RTF** is an equality

"Spectral Side" = "Geometric Side"

$$\sum_{\pi \text{ irr cusp auto rep of } G} (\ldots) = \sum_{\gamma \in H_1(F_0) \backslash G(F_0) / H_2(F_0)} Vol_{\gamma} \int_{(H_1 \times H_2)_{\gamma}(\mathbb{A}) \backslash H_1 \times H_2(\mathbb{A})} f dh_1 dh_2$$

**Idea**: For any matrix  $A = (a_{ij})_{n \times n}$ ,  $\sum \lambda_i = \sum a_{ii}$ .

Variants: twist by a character  $\eta$ , action of  $\overline{H}$  on a good G-variety X (e.g a symmetric space), (semi-)linearization...

**Warning**: There are big convergence issues. This is why we like regular semisimple orbits (as the orbit is closed, the restriction of f is still compactly supported, and the volume factor is easy to compute).

**Slogan.** Comparison of RTFs is a very useful tool (JL, base change, GGP...). **How**?

- Match (regular semisimple) orbits (study the orbit space)
- Match orbit integrals (existence of transfer)
- Fundamental lemma
- Choose good test functions to separate terms (density, base change, multiplicity)

#### When?

Why do we expect such comparison on the geometric side? One importance case is **the twist case**: the action of H on X and H' on X' over  $F_0$  are different, but become the same after base change to large field. And we get untwist/matching after taking quotient by showing the twist does not change the orbits.

# 2 Jacquet-Rallis case

Twist of conjugation action of  $GL_{n-1}$  on  $GL_n$  and on  $\begin{bmatrix} GL_{n-1} & * \\ * & 0 \end{bmatrix}$ .

In the Jacquet-Rallis setting, let  $F/F_0$  be separable quadratic extension of p-adic fields or number fields.

So we have

•  $GL_n$  side:  $H' = GL_{n-1}$  acts on

$$S_n = \{ \gamma \in Res_{F/F_0} GL_n | \bar{\gamma}\gamma = 1 \}$$

and on

$$S_{n-1} \times V'_{n-1} \hookrightarrow Res_{F/F_0} \begin{bmatrix} GL_{n-1} & * \\ * & 0 \end{bmatrix}$$

by conjugation.

•  $U_n$  side: H = U(V) acts on

$$G = U(V^{\#}) = \{g \in Res_{F/F_0} GL_n | {}^t \bar{g}Jg = J\}$$

and on

$$U(V) \times V \hookrightarrow Res_{F/F_0} \begin{bmatrix} GL_{n-1} & * \\ * & 0 \end{bmatrix}$$

by conjugation.

**Theorem 1.** There is a natural (not just as sets!) bijection of regular semisimple orbits

$$\coprod_{V} [U(V^{\#})(F_0)]_{rs} \cong [S_n(F_0)]_{rs} \quad (1)$$

and

$$\coprod_{V} [(U(V) \times V)(F_0)]_{rs} \cong [(S_{n-1} \times V'_{n-1})(F_0)]_{rs} \quad (2)$$

where V runs over  $\mathbf{Herm}_{n-1}$ , the set of isomorphism classes of n-1 dimensional non-degenerate  $F/F_0$  Hermitian spaces.

Before giving a proof, let's make some observations. If  $F = F_0 \times F_0$  is split, then the action at both sides becomes the standard conjugation action of  $GL_{n-1}$ . The theorem is obvious (even without rs assumption) in this case.

**Remark 1.** One will see later the rs assumption is neccesary in the proof for general case. In fact, the comparison fails for all orbits in general. Over  $\mathbb{R}$ , one can easily see this by connectedness. The whole orbit space (non-Hausdorff in general) essentially looks like this (picture of a sphere with "a fat circle" in the middle, remove the "fat circle" we get the regular semisimple orbits; we split the sphere in the middle to obtain matching on both sides.)

In general, as  $F \otimes_{F_0} F \cong F \times F$ , after a base change from  $F_0$  to F we arrive at the split case. And the embeddings e.g  $S_n(F_0) \hookrightarrow GL_n(F)$  can be thought as embeddings of  $F_0$ -points to F-points (up to an automorphism).

Use the standard pairing on  $F^{n-1}$  given by  $(x,y) = \sum_i x_i \bar{y}_i$  we get the trivial Hermitian space  $V_0$  and  $V_0^\#$ . Compare  $U(V_0^\#) = \{{}^t \bar{g}g = 1\}$  with  $S_n = \{\bar{\gamma}\gamma = 1\}$  (more precisely, compare the actions), we see

**Proposition 1.** The action of H' on  $S_n$  and  $H = U(V_0)$  on  $G = U(V_0^{\#})$  is  $F/F_0$ -twist of each other, the twist is given by the transpose anti-involution on  $GL_n/F$ . Similar result holds for the variant version.

Then let's recall the notation of regular semisimpleness. Let a reductive group H act on a smooth affine variety X over  $F_0$ , we say  $x \in X(F_0)$  is **regular semisimple** if Hx is Zariski closed and  $H_x$  is trivial. This condition satisfies faithful flat descent, so we expect it's representable.

**Fact**: There exists an open subscheme  $X_{rs}$  of X parametrizing rs points. In practice (which is true in our case),  $X_{rs}$  is non-empty, affine and dense.

Example 1.  $\mathbb{G}_m$  acts on  $\mathbb{A}^1$ .

**Example 2.** Interesting example:  $SO(2)(\mathbb{R})$  acts on  $\mathbb{R}^2$  by rotation, geometry is different over  $\mathbb{R}$  and  $\mathbb{C}$ .

Then one may imagine  $X_{rs}/H$  (which exists as a scheme) parametrizing regular semisimple orbits. But it's a general phenomenon that  $(X/H)(F_0) \neq X(F_0)/H(F_0)$  for non-algebraically closed field  $F_0$ , and one has to consider H-torsors. By definition,

$$(X/H)(F_0) = \coprod_{\alpha \in H^1(F_0, H)} X_{\alpha}(F_0)/H_{\alpha}(F_0)$$

where  $T_{\alpha}$  is the *H*-torsor corresponding to  $\alpha$ ,  $H_{\alpha} = Aut(T_{\alpha})$ ,  $X_{\alpha} = (X \times T_{\alpha})/H$ .

**Proposition 2.**  $H^1(F_0, GL_{n-1}) = 1$ , and  $H^1(F_0, U(V_0))$  is in bijection with isomorphism classes of n-1-dimensional  $F/F_0$ -hermitian spaces.

*Proof.* The first one is Hilbert Satz 90, the second proof is similar to how one identifies  $GL_n$  torsors with rank n vector bundles.

Return to the theorem, one gets that LHS of (1) is  $(U(V_0^{\#})_{rs}//U(V_0))(F_0)$ , and RHS is  $((S_n)_{rs}//GL_{n-1})(F_0)$ . To finish the proof, we use the following proposition which says the twist is trivial on the quotient:

**Proposition 3.**  $x \to {}^t x$  is identity on  $(GL_n)_{rs}//GL_{n-1}$ . Therefore,

$$U(V_0^{\#})_{rs}//U(V_0) \cong (S_n)_{rs}//GL_{n-1}.$$

*Proof.* For our purpose, we only need to look at field-valued points. This reduces to checking that for any regular semisimple matrix  $g \in GL_n(E)$  (E can be any field), g is  $GL_{n-1}(E)$  conjugate to  ${}^tg$ , which will be done in next section.

The proof of (2) in the theorem is similar.

# 3 Concrete matching of elements

The above conceptual explanation indicates that to prove mathching of orbits, it's useful to consider the embedding

$$U(V)(F_0) \times V(F_0) \hookrightarrow \begin{bmatrix} GL_{n-1} & * \\ * & 0 \end{bmatrix} (F) \longleftrightarrow S_{n-1}(F_0) \times V'_{n-1}(F_0)$$

. Note the stabilizer of a regular semisimple element is trivial hence two regular semisimple elements are  $H(F) = GL_{n-1}(F)$ -conjugated iff they are  $H(F_0)$ -conjugated. So we have embedded LHS and RHS of (1) and (2) into a common large orbit space, and only need to do matching there.

**Definition 1.** (g, u) and  $(\gamma, u_1, u_2)$  is matched iff they are conjugated by  $GL_{n-1}(F)$  in  $M_{n\times n}(F)$ .

The geometry of  $GL_{n-1}$  action on  $GL_n$  is summarized as the following theorem (the variant version is similar).

**Theorem 2.** Let E be any field,  $g = \begin{bmatrix} A & u \\ v & d \end{bmatrix} \in GL_n(E)$ . Then

- 1. g is regular semisimple iff  $e, ge, \ldots, g^{n-1}e$  form a basis of  $E^n$  and  $e^*, e^*g, \ldots, e^*g^{n-1}$  form a basis of  $(E^n)^*$  iff  $u, Au, \ldots, A^{n-2}u$  form a basis of  $E^{n-1}$  and  $v, vA, \ldots, vA^{n-2}$  form a basis of  $(E^{n-1})^*$  iff  $det((vA^{i+j}u)_{0\leq i,j\leq n-2})\neq 0$  (so regular semisimple elements form an non-empty affine open subset).
- 2. For regular semisimple g, define inv(g) as the data  $det(\lambda I + A) \in E[\lambda]$ ,  $vA^iu$  (i = 0, ..., n-2) and d. Then for regular semisimple  $g_1, g_2, g_1 \sim g_2$  iff  $inv(g_1) = inv(g_2)$ .

*Proof.* We give a sketch. If n = 2, the action is

$$\begin{bmatrix} t^{-1} & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} A & u \\ v & d \end{bmatrix} \begin{bmatrix} t & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} A & a^{-1}u \\ av & d \end{bmatrix}$$

Let "  $t \to 0$  or  $\infty$ ", we see the orbit is closed iff  $uv \neq 0$  or u = v = 0 (if  $uv = t \neq 0$  then the orbit is defined by  $\{uv = t\}$  hence is closed), regular semisimple iff  $uv \neq 0$ , so the theorem is true.

The proof for general case is similar. (1.) is easy except the first equivalence: for one side e.g if  $e, ge, \ldots, g^{n-1}e$  does not form a basis of  $E^n$ , then g has a proper invariant subspace, so g look like  $\begin{bmatrix} * & * \\ 0 & * \end{bmatrix}$  under another basis, then choose scalar matrix t as above and let  $t \to \infty$ , the limit point is fixed by all  $t \neq 0$ , so the orbit is not closed or the stabilizer is not trivial. For another side, if hg = gh for  $h \in GL_{n-1}(E)$ , as he = e we know  $hg^ie = g^ie$ , but  $g^ie$  form a basis, so h = id hence the stabilizer of h is trivial. For the closedness, one need to use limit argument to classify all closed orbits.

The proof of (2.) is easy: if  $inv(g_1) = inv(g_2)$ , define  $h \in GL_{n-1}$  by sending  $A_1^i u_1$  to  $A_2^i u_2$  ( $i = 0, \ldots, n-2$ ). As they are both basis of  $E^{n-1}$ , this is well-defined, use the equality of invariants to show  $hg_1h^{-1}(g_1^i e) = g_2(g_2^i e)$  hence  $hg_1h^{-1} = g_2$ .

Corollary 1. For any regular semisimple matrix  $g \in GL_n(E)$ , g is  $GL_{n-1}(E)$  conjugate to  ${}^tg$ .

**Remark 2.** This is the analog of the classical result that any  $n \times n$  matrix is conjugated to its transpose. Here the result is not true for arbitary matrix: consider  $\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$ .

**Remark 3.** One can prove the matching concretely. For example, take  $\gamma \in S_n(F_0)_{rs}$ , as  $\gamma \sim {}^t \gamma$ , there is a  $x \in GL_{n-1}(F)$  s.t  $x \gamma x^{-1} = {}^t \gamma$ . Applying the conjugation we get  $\bar{x} \bar{\gamma} \bar{x}^{-1} = {}^t \bar{\gamma}$ , use  $\bar{\gamma} \gamma = 1$  we get  $\bar{x} \gamma \bar{x}^{-1} = {}^t \gamma$  hence  $\bar{x} = x$  as  $Stab(\gamma) = 1$ . Similarly,  ${}^t x = x$  so  $x \in \mathbf{Herm}_{n-1}$ . Therefore,

$$^t \bar{\gamma} x \gamma x^{-1} = {}^t \bar{\gamma}^t \gamma = 1$$

so  $\gamma \in U(x \oplus 1)_{rs}$ .

In conclusion, we get the matching of regular semisimple orbits, and it's time to discuss the matching of orbit integral.

### 4 Smooth transfer

Recall

**Theorem 3.** we have the following classification of n-dimensional non-degenerate  $F/F_0$ -Hermitian spaces over local and global fields:

- (Split case) only the trivial one,  $U(\langle,\rangle) = GL_n$ ;
- $(\mathbb{C}/\mathbb{R})$  any V is isomorphic to  $V_{p,q}$  defined by  $diag1_p, -1_q$  where p, q are two natural number with p+q=n.  $V_{p,q}$  are not isomorphic to each other, but  $U(p,q):=U(V_{p,q})\cong U(q,p)$ .
- (p-adic field) det :  $\mathbf{Herm}_n \cong F_0^{\times}/NF^{\times} \cong \mathbb{Z}/2 = \{0,1\}$ . For n odd,  $U(V_0) \cong U(V_1)$  are quasi-split. For n even,  $U(V_0) \not\cong U(V_1)$  and only  $U(V_0)$  is quasi-split.
- $\bullet$  (totally real field) certain local-global principle holds.

For the proof in the p-adic case, one firstly checks n = 1 and n = 2, and use that any V with dimension  $\geq 3$  has isotropic vectors to do induction.

Now we define orbit integrals as in the Jacquet-Rallis setting. Let  $F/F_0$  be a quadratic extension of p-adic fields and  $\eta$  be the associated quadratic character of  $F_0^{\times}$  by local class field theory.

**Definition 2.** For  $f' \in \mathcal{S}(S_n(F_0))$  i.e a locally constant function with compact support on  $S_n(F_0)$ , and  $\gamma \in S_n(F_0)_{rs}$ , we define the orbital integral as

$$O(\gamma, f', s) := \int_{H} f'\left(h\gamma h^{-1}\right) |\det(h)|^{-s} \eta(h) dh$$

and define  $O(\gamma, f) = w(\gamma)O(\gamma, f', 0)$ , where the transfer factor  $w(\gamma)$  is certain non-zero number which we don't define here.

On the unitary side, for  $g \in \mathrm{U}\left(V^{\#}\right)\left(F_{0}\right)_{\mathrm{rs}}$  and  $f \in \mathcal{S}\left(\mathrm{U}\left(V^{\#}\right)\left(F_{0}\right)\right)$  we define

$$\operatorname{Orb}(g,f) := \int_{\mathrm{U}(V)(F_0)} f\left(h^{-1}gh\right) dh$$

Note the twist by  $\eta$  on the  $GL_n$  side, and it's necessary to have the transfer factor  $\omega(\gamma)$  in the definition (to make it only depends on the orbit). And the product of all local transfer factors is 1, hence it does not effect the global matching.

**Definition 3.** A function  $f' \in \mathcal{S}(S_n(F_0))$  and a pair of functions  $(f_0, f_1) \in S(U(V_0^{\#})(F_0)) \times S(U(V_1^{\#})(F_0))$  are transfers of each other if for each  $i \in \{0, 1\}$  and each  $g \in U(V_i^{\#})(F_0)_{rs}$ , we have

$$Orb(g, f_i) = Orb(\gamma, f')$$

whenever  $\gamma \in S_n(F_0)_{rs}$  matches g.

The variant version is defined similarly, so is the Lie-algebra version.

**Theorem 4.** In the *p*-adic case, the smooth transfer always exists.

The idea is to firstly reduce to the Lie-algebra version using Cayley map, then because of the local constancy of orbit integral (which is one feature of p-adic fields), one only need to prove the existence around every points. Use Harish-Chandra's semisimple descent (understanding orbital integrals in terms of slice representations, and induction, one gets the existence away from the center (the centralizer has small dimension, this reduced to low rank case.). Finally the compatibility of transfer and Fourier transform solves the remaining case (use Fourier transform to get from center to regular ones). The n=1 case is explicit and important for induction.

The fundamental lemma: in the statement, we need  $F/F_0$  be unramified, so there is a self-dual lattice inside  $V_0$  hence  $U(V_0)(F_0)$  has a hyperspecial subgroup.

## References

- [1] S. Rallis, G. Schiffmann, Multiplicity one conjectures. arXiv preprint https://arxiv.org/abs/0705.2168.
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