# MINYOUNG HWANG

EDUCATION	
Massachusetts Institute of Technology (MIT) M.S. & Ph.D. in AeroAstro & CSAIL	Cambridge, MA 09/2024 - Current
<ul> <li>Seoul National University (SNU)</li> <li>M.S. in Electrical and Computer Engineering</li> <li>Thesis: "Meta-Explore: Exploratory Hierarchical Vision-and-Language Navigation Using Scene Object Spectrum</li> </ul>	Seoul, Korea 09/2021 - 08/2023 Grounding"
<ul><li>B.S. in Electrical and Computer Engineering</li><li>Thesis: "Video Inference for Human Motion with Texture Generation"</li></ul>	03/2017 - 08/2021
Daejeon Science High School for the Gifted Major: Mathematics	Daejeon, Korea 03/2014 – 02/2017
Representative Honors	
<i>Kwanjeong Education Foundation (KEF) Scholarship,</i> KEF <i>Presidential Science Scholarship</i> (Field: Mathematics), Ministry of Science and ICT <i>NeurIPS 2023 Scholar Award</i> <i>Google Student Travel Grants</i> (up to 3 students / year, top international conferences) <i>Talent Award of Korea</i> (Field: Mathematics), Ministry of Education <i>Training Lineup for IMO (International Mathematical Olympiad)</i> , Top 18 students in Ke	2024 - 2029 2017 - 2020 10/2023 03/2023 11/2015 orea 05/2016
PUBLICATIONS	
MotIF: Motion Instruction Fine-tuning In Submission, 2024	Hwang et al.
<b>Promptable Behaviors: Personalizing Multi-Objective Rewards from Human Prefere</b> The IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR), June 2024	ences Hwang <i>et al.</i>
Sequential Preference Ranking for Efficient Reinforcement Learning from Human Fee Neural Information Processing Systems (NeurIPS), Dec. 2023	edback Hwang et al.
Meta-Explore: Exploratory Hierarchical Vision-and-Language Navigation Using Scene Object Spectrum Grounding The IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR), June 2023	Hwang et al.
Improving Image-Goal Navigation with Visual Language Grounding via Image Captie Conference on Information and Control Systems (CICS), Oct. 2022	oning Hwang et al.
Geometric Understanding of Reward Function in Multi-Agent Visual Exploration International Conference on Control, Automation and Systems (ICCAS), Oct. 2021	Hwang et al.
Wanna be Engineer34 members of STEM (InMegaStudy Books, 202134 members of STEM (In	cluding Hwang, M.)
Work Experience	
Carnegie Mellon University (CMU) Research Intern	Pittsburgh, PA 01/2024 – 06/2024

- Connecting Language to Actions & the World (CLAW) Lab (Prof. Yonatan Bisk)
- How human preferences are communicated in natural language to a robotic agent

## Allen Institute for Artificial Intelligence (AI2)

Research Intern

- Perceptual Reasoning and Interaction Research (PRIOR)
- Promptable Behaviors: Personalizing Multi-Objective Rewards from Human Preferences, sub. to CVPR 2024

Seattle, WA 07/2023 – 12/2023

SNU Robot Learning Laboratory	Seoul, Korea	
Robotics Researcher (M.S. Student)	09/2021 - 06/2023	
<ul> <li>SeqRank for Feedback-efficient RLHF, accepted to NeurIPS 2023 (01/2023 - 05/2023)</li> </ul>		
<ul> <li>Meta-Explore for Vision-and-Language Navigation, accepted to CVPR 2023 (08/2021 - 11/2022)</li> </ul>		
<ul> <li>Graph Merge for Robust Path Following (08/2021 - 02/2022)</li> </ul>		
Robotics Research Intern	02/2020 - 08/2021	
Geometric Understanding of Reward Function in Multi-Agent Visual Exploration, accepted to ICCAS 2021     (02 (2021) 10 (2021)		
(02/2021 - 10/2021) Video Inference for Human Motion with Toxture Concration Bachelor Thesis (08/2020 - 12	v / 2020)	
<ul> <li>Visual Navigation in Cibcon Env? Environment (02/2020 - 07/2020)</li> </ul>	-/ 2020)	
Com Loss Chata Ling income in Closel Linvia Line and the moment in m		
San Jose State University (SJSU) Silicon Valley Innovation	San Jose, CA	
Startup Team CEO, Startup Training Program	01/2020	
• Led startup team UP-CARE (Use your Phone Camera for Health and Environment).		
<ul> <li>Developed fall detection and alert for elderly users.</li> </ul>		
STEM, SNU Engineering College	Seoul, Korea	
Robotics Engineer	03/2019 - 11/2019	
<ul> <li>Robot Dynamics and Control, Motion Planning, Computer Vision</li> </ul>		
Developed both software and hardware of robot cleaner using 3D printers, Arduino, and computer vision		

open source (Google Mediapipe); led the development of control algorithm considering robot dynamics.

# PROJECTS AND RESEARCH

* RL: Reinforcement Learning / CV: Computer Vision / HRI:	Human-Robot-Interaction
<b>Promptable Behaviors for Efficient Personalization of Robots</b>   <i>RL, HRI, CV</i>	05/2023-12/2023
Learning reward weights for multi-objective rewards from human preference.	AI2
<b>SeqRank for Feedback-efficient RLHF</b>   <i>RL, HRI, Graph Theory</i>	01/2023–05/2023
RLHF framework that uses sequential preference ranking to enhance the feedback efficiency.	RLLAB, SNU
<b>Meta-Explore for Vision-and-Language Navigation</b>   <i>Multimodal, Graph Theory</i>	07/2022–11/2022
Hierarchical decision-making process by recognizing semantically meaningful clues.	RLLAB, SNU
<b>Text-VLAD</b>   <i>CV, Visual Localization</i>	09/2021–12/2021
Visual localization using text and visual features	RLLAB, SNU
<b>Influence based Reward for Communicative Multi-Agent Reinforcement Learning</b>	03/2021–07/2021
<i>Giving rewards based on credit assignment among multi agents</i>	RLLAB, SNU
<b>Video Inference for Human Motion with Texture Generation</b>   <i>CV, Motion Estimation</i>	e 08/2020–12/2020
<i>Reconstruction of 3D multi-view video from 2D human motion video</i>	RLLAB, SNU
<b>Visual Navigation in Gibson Env2 Environment</b>   <i>RL, Visual Navigation</i>	02/2020–07/2020
Implementing robust path following of robots in Gibson simulator	RLLAB, SNU
<b>UP-CARE (Use your Phone Camera for Health and Environment)</b>   <i>HRI, CV</i>	01/2020-01/2020
Fall detection for elderly using phone camera based on human pose estimation	San Jose Univ., CA, US
<b>Scrupulous Robot Cleaner with Mecanum Wheels and Pointed-shaped Inlet</b>   <i>HRI</i>	03/2019–11/2019
<i>Omnidirectional robot cleaner with autonomous &amp; hand-motion controlled modes</i>	STEM, SNU
TEACHING EXPERIENCE	
<b>Teaching Assistant, Introduction to Intelligent Systems (English Lecture)</b> Head TA for 2022 Spring Lecture. Managed RC car racing projects and taught students how to use ROS and Gazebo	09/2021–06/2022 SNU, Korea
<i>Major Tutor,</i> Signals and Systems	03/2021–08/2021
Tutoring for Seoul National University ECE major subject	SNU, Korea
<b>Undergraduate Teaching Assistant, Introduction to Circuit Theory and Laboratory</b>	03/2019–06/2019
Supported and guided students to conduct electric circuit experiments	SNU, Korea
<i>Tutor,</i> <b>Basic Calculus</b>	03/2018–12/2020
<i>Taught Basic Calculus 1, 2, and Basic Calculus for Biological Science.</i>	SNU, Korea

#### AWARDS

Lecture·Research Support Scholarship, Full tuition for 2022 Spring, SNU	03/2022
Grand Prize, Silicon Valley Innovation and Startup Program, San Jose State University	01/2020
1st Prize, International Capstone Design Fair, Korea University Innovation Hub Cent	er 11/2019
2nd Prize, SNU College of Engineering Creative Design Fair, SNU College of Engineer	ring 09/2019
Gold Medal, University Students Contest of Mathematics, Korean Mathematical Socie	ety 11/2018
HONORS AFFILIATION AND TRAINING	
MIT xPRO Robotics Essentials, Massachusetts Institute of Technology	05/2022 - 07/2022
<ul> <li>SNU Tomorrow's Edge Membership (STEM), SNU College of Engineering Honor Society Selects 30 outstanding students from Seoul National University's Engineering College annually si</li> <li>10<sup>th</sup> President (07/2019 - 06/2020)</li> </ul>	y 04/2019 – Present ince 2010.
Machine Learning Theory Korea	03/2022-Present
$\operatorname{TODAM}\operatorname{BOSTON}$ , Global networking club with international graduate students	09/2020 - 12/2021
NorthEast Asia SRT (Student Round Table), International communication partnership	08/2019
INVITED TALK	
<b>UW Computer Science Department</b> Promptable Behaviors: Personalizing Multi-Objective Rewards from Human Preferences	12/2023
<b>CMU Language Technologies Institute</b> Leveraging Human Knowledge to Robots through Interaction: from Vision to Language and Beyond	08/2023
Community Involvement	
<b>SNU Vision Mentoring</b> Mentoring high school and undergraduate students interested in engineering and science	07/2019–02/2022 SNU, Korea
Blended Science Festival: Motion controlled Robot Cleaner Experience         Provided hands-on experience for students to interact with a robot cleaner.	10/2019 eoul Science Park, Korea
<b>PURME Foundation NEXON Children's Rehabilitation Hospital</b> Assisted disabled children with rehabilitation.	03/2017–10/2017 Seoul, Korea
EXTRACURRICULAR ACTIVITIES	
Orchestra Club Activities   Violin	2014 - 2020
Seoul National University Philharmonic Orchestra   Violin	
<i>Music Fountain : Orchestra club in Daejeon Science High School for the Gifted   Concertmaster, 1<sup>st</sup></i>	Violin

### SKILLS

**Programming**: Python, C/C++, MATLAB, Arduino, OpenGL **Patent**: Envelope with built-in sieve (**KR20140003720U**, 06/2014) **Languages**: Korean (native fluency), English (full-professional proficiency)