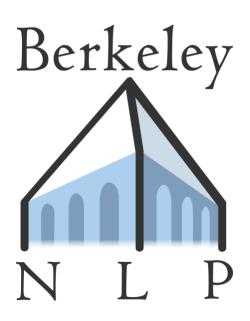
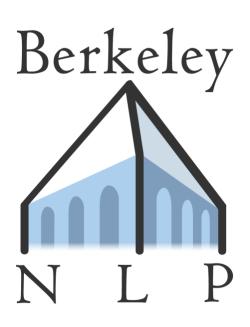
Structure and Interpretation of Neural Codes

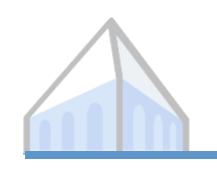


Jacob Andreas

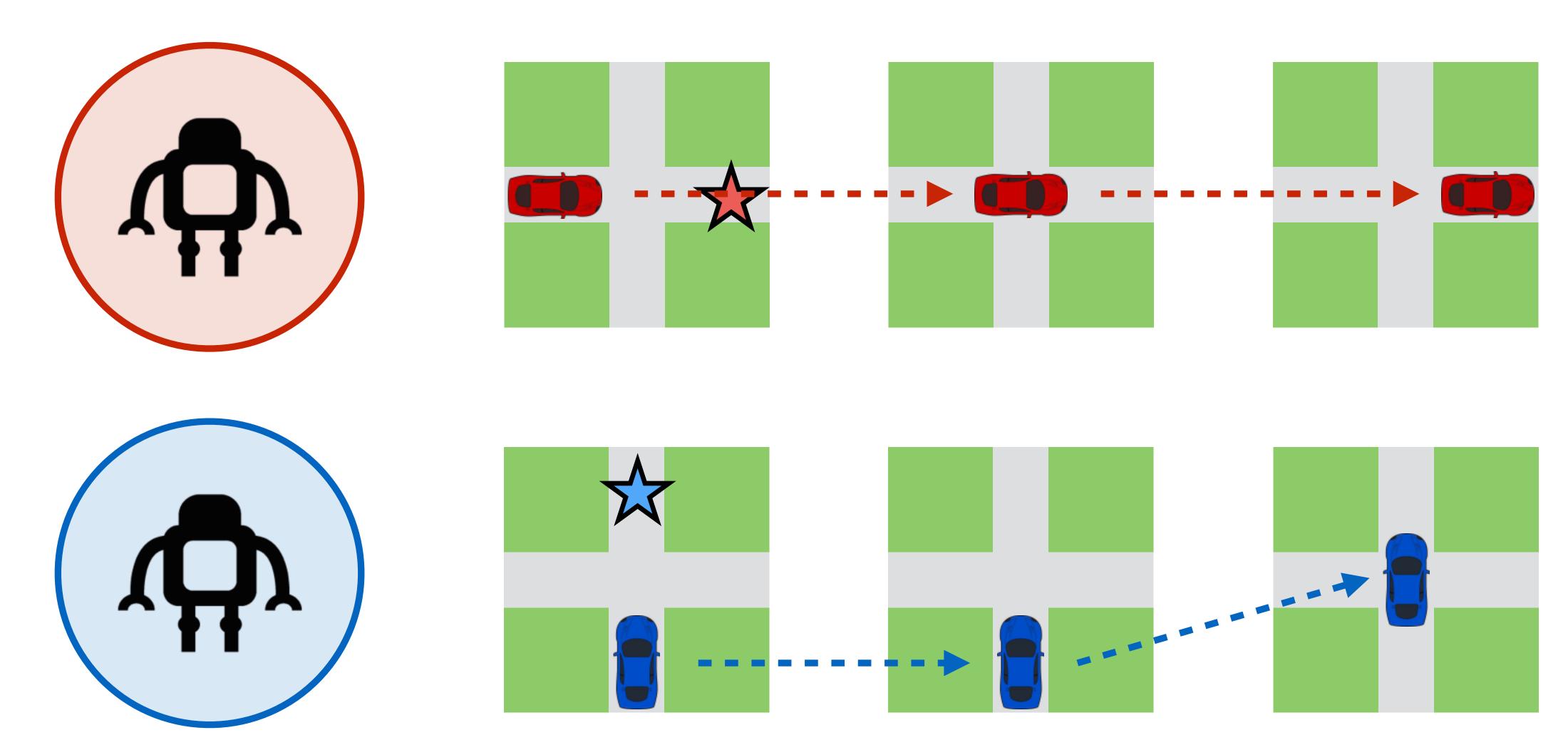
Translating Neuralese

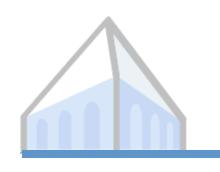


Jacob Andreas, Anca Drăgan and Dan Klein

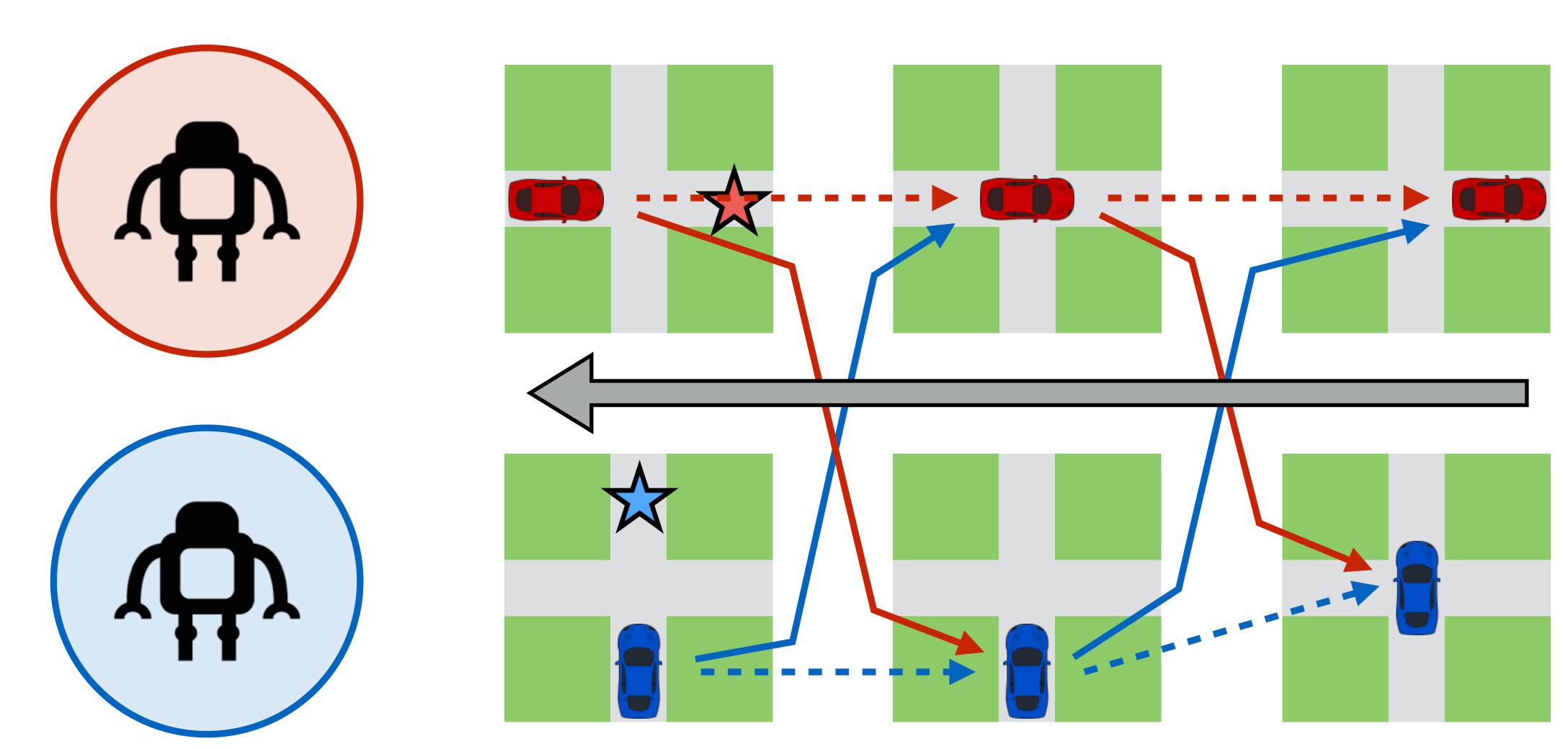


Learning to Communicate



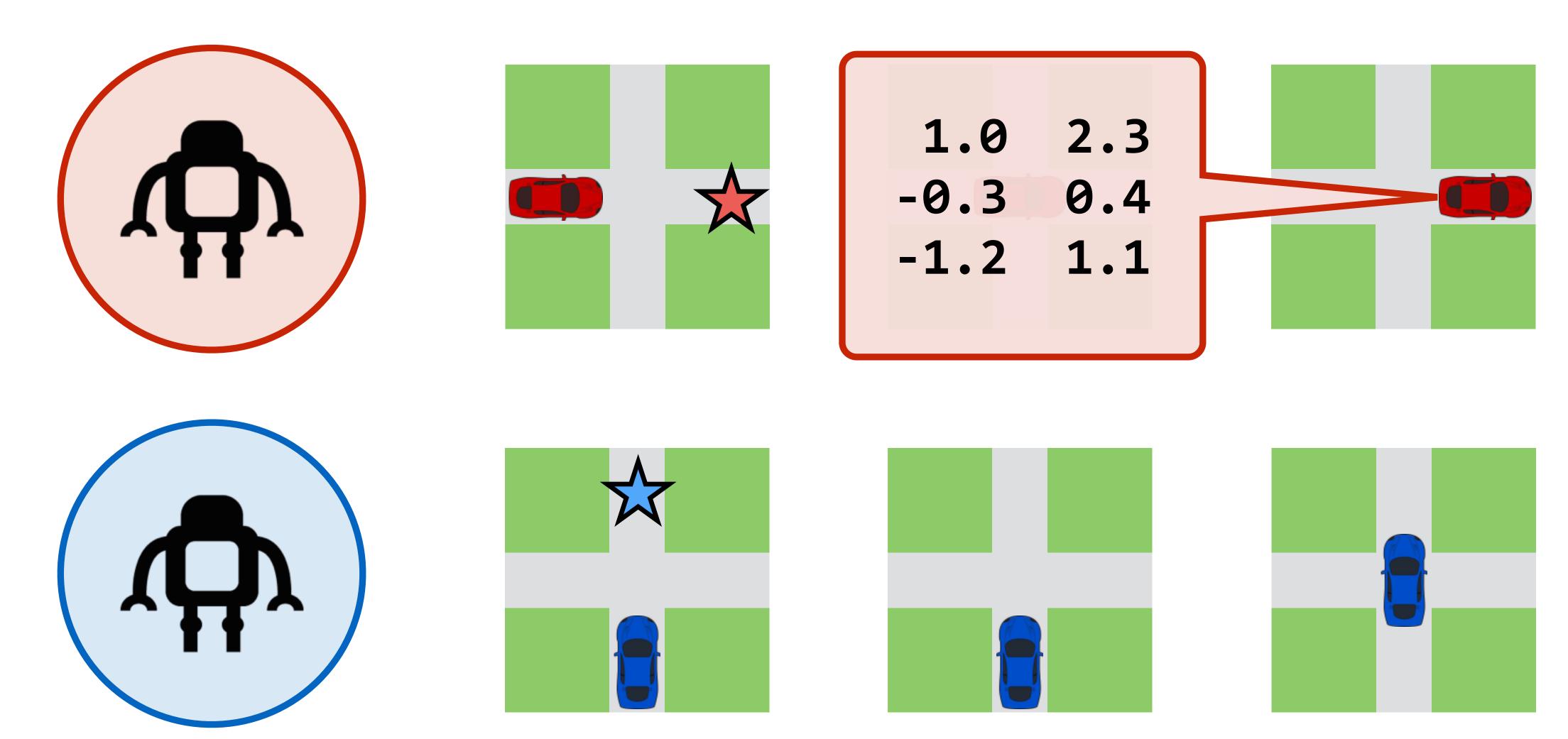


Learning to Communicate



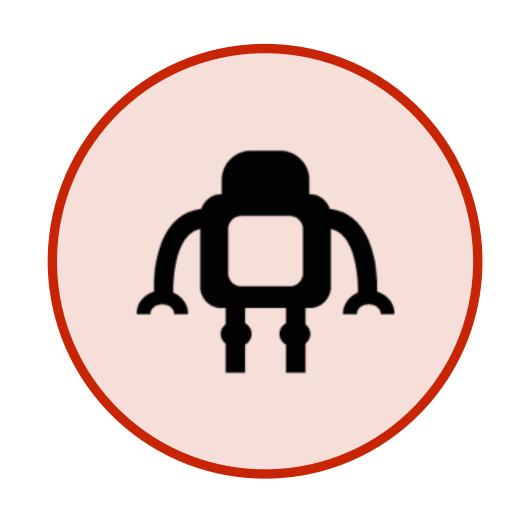


Neuralese

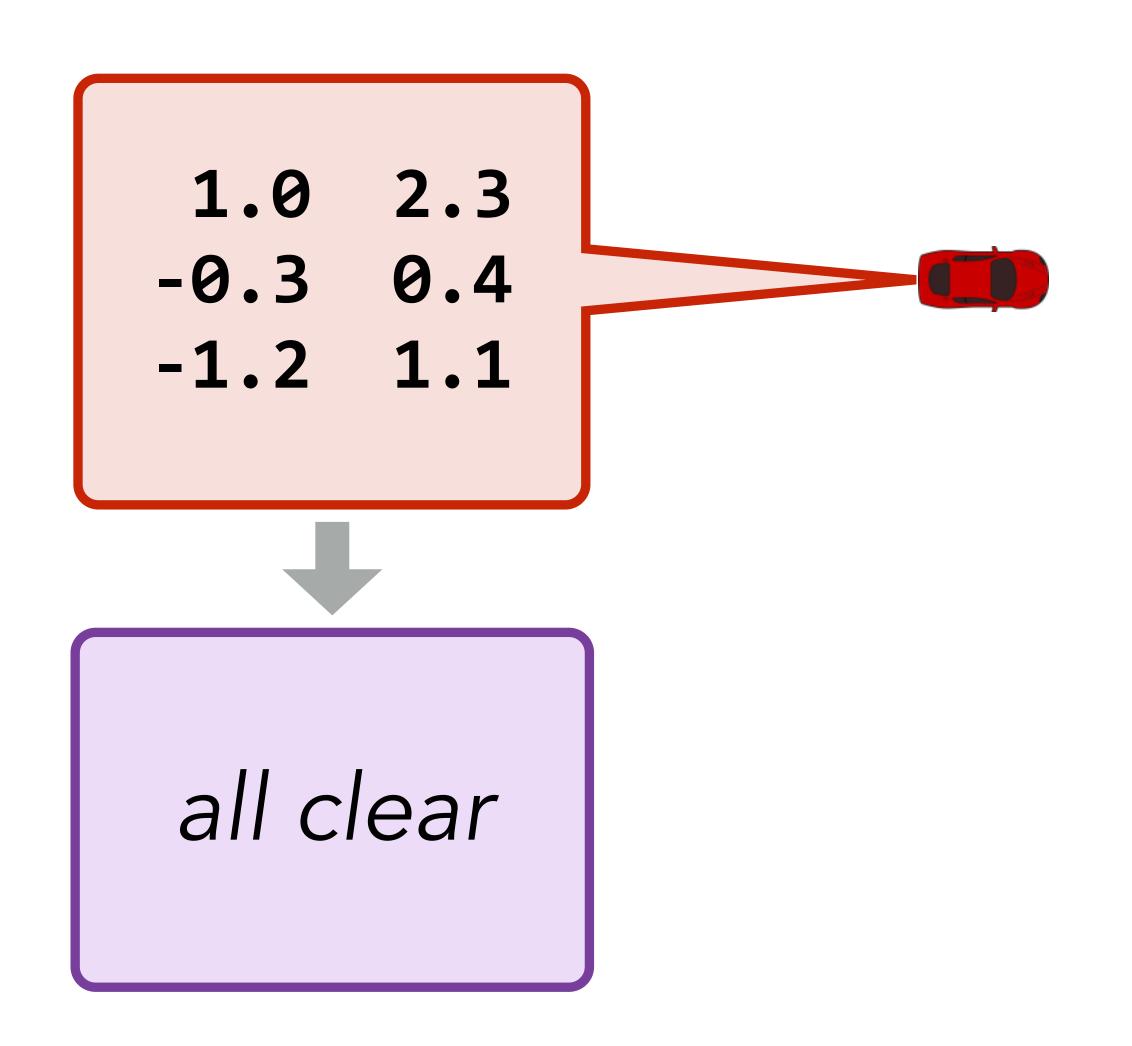


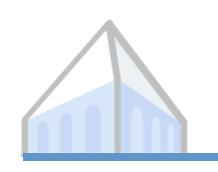


Translating neuralese





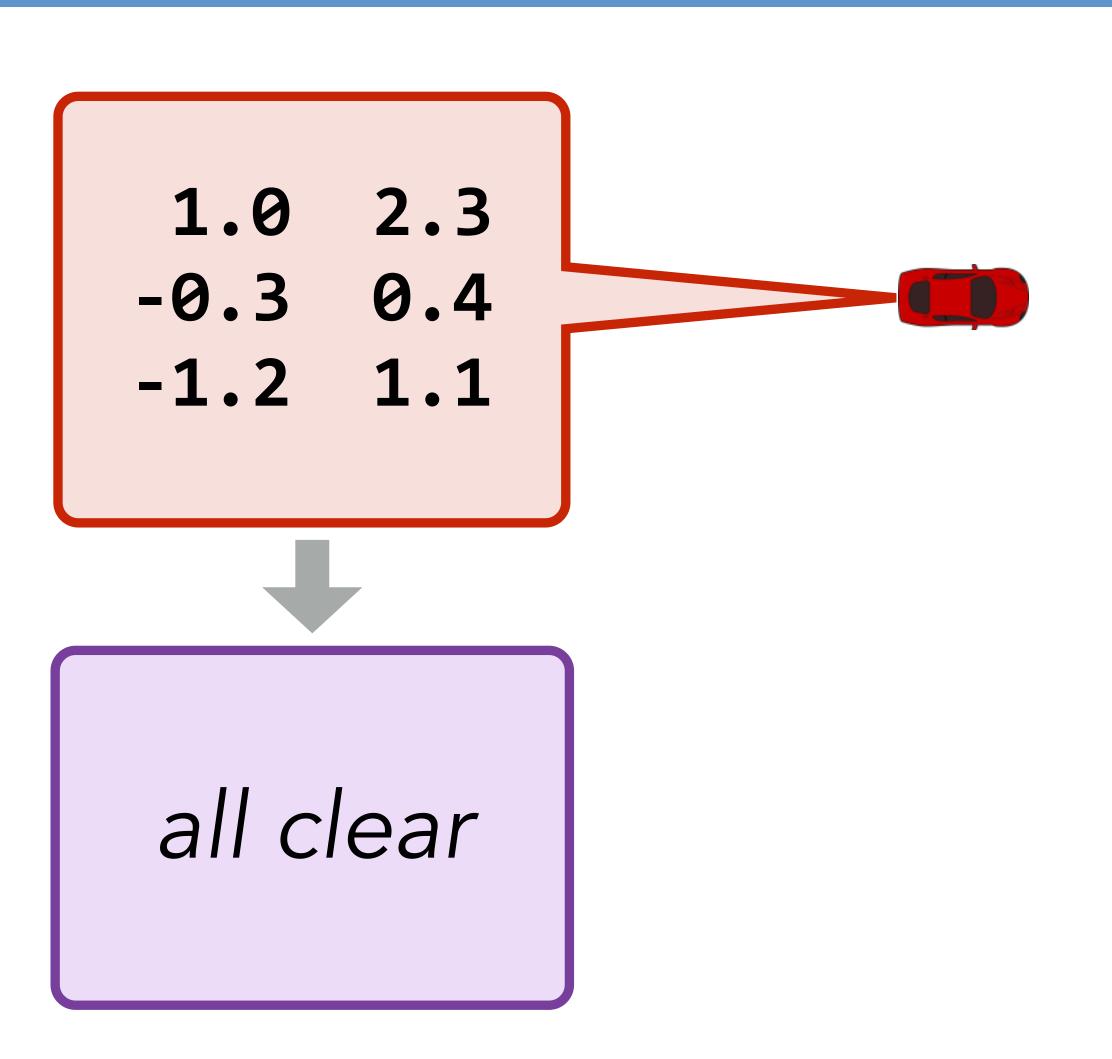


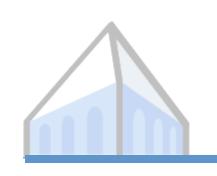


Translating neuralese

 Interoperate with autonomous systems

- Diagnose errors
- Learn from solutions



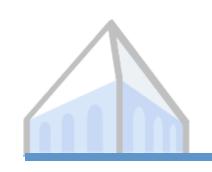


Natural language & neuralese

Statistical machine translation

Semantic machine translation

Implementation details

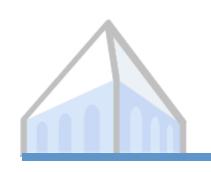


Natural language & neuralese

Statistical machine translation

Semantic machine translation

Implementation details

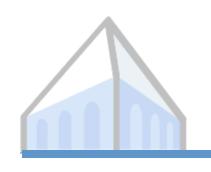


Natural language & neuralese

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Natural language & neuralese

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Implementation details

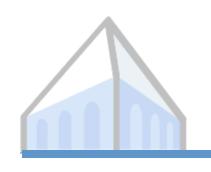


Natural language & neuralese

Statistical machine translation

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Implementation details



Natural language & neuralese

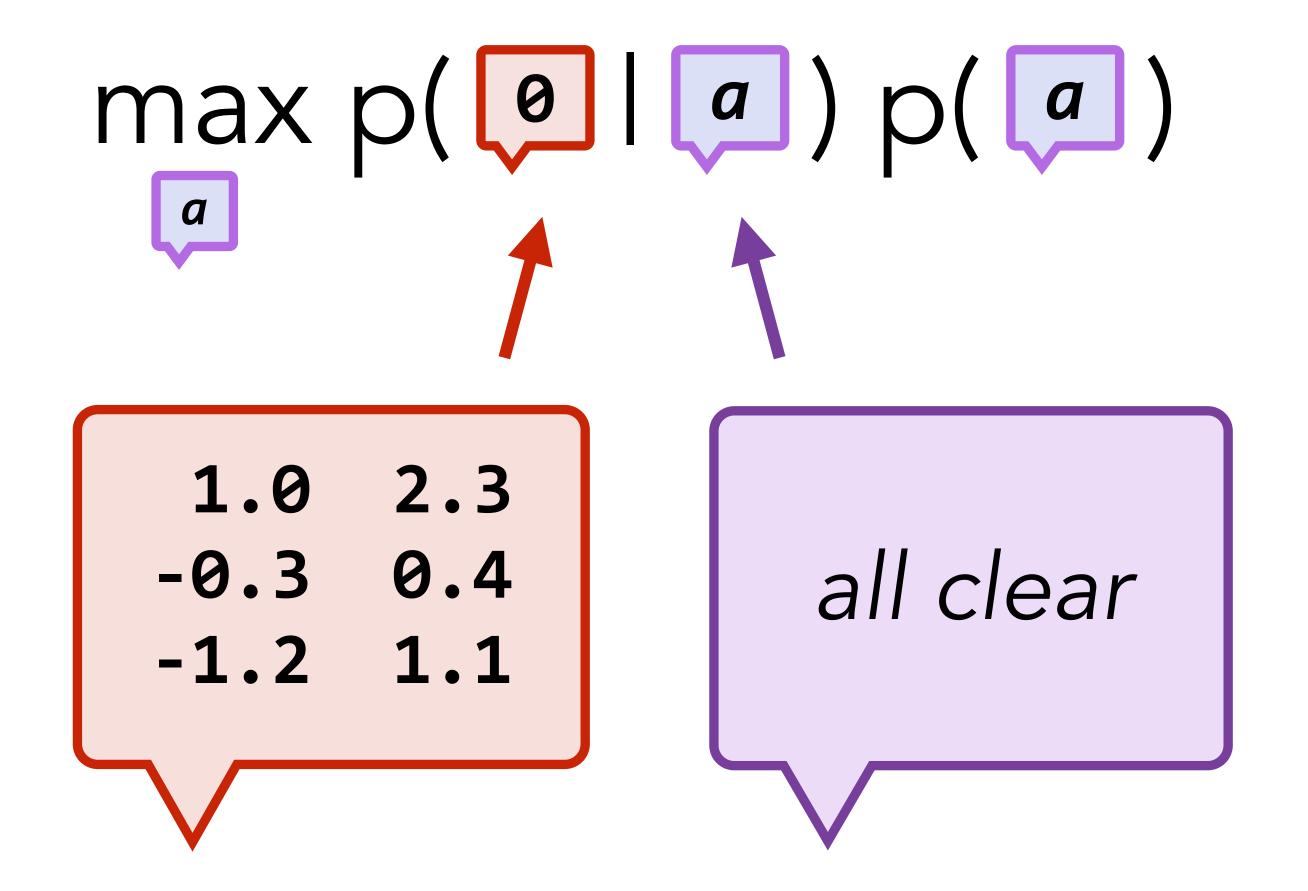
Statistical machine translation

Semantic machine translation

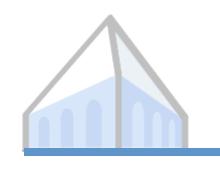
Implementation details



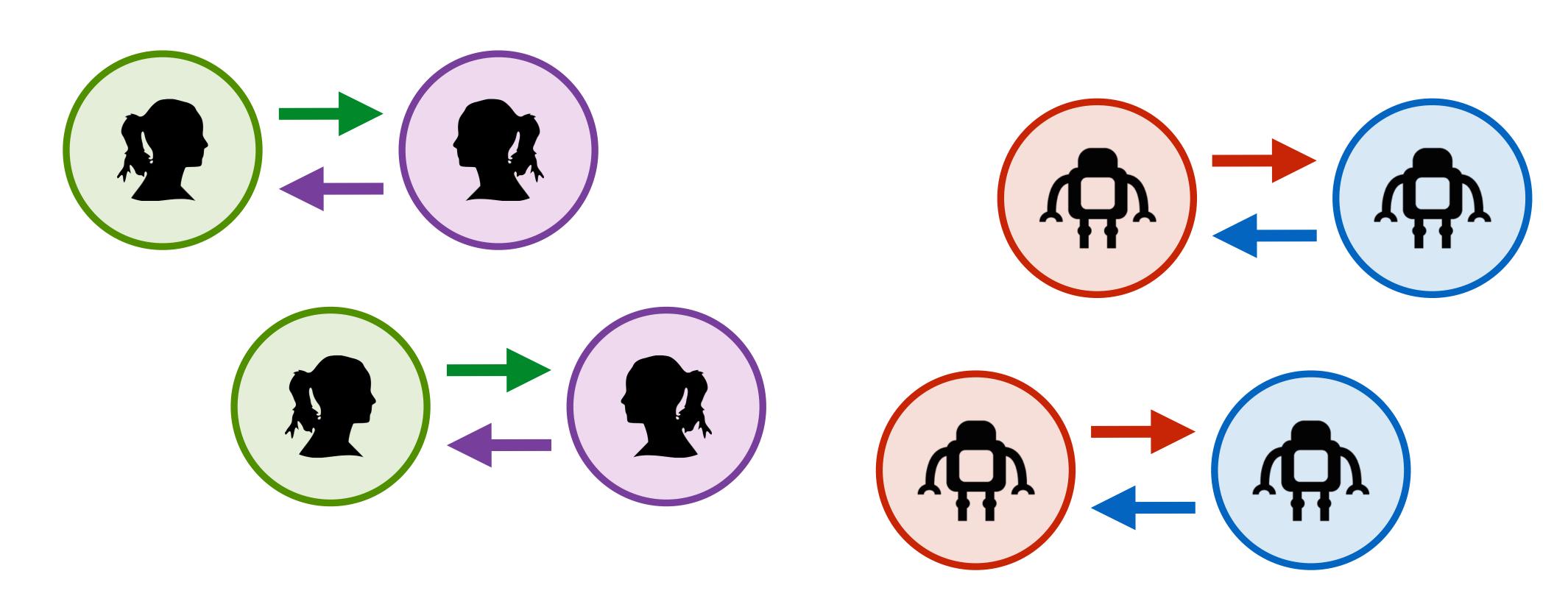
A statistical MT problem



[e.g. Koehn 10]



A statistical MT problem



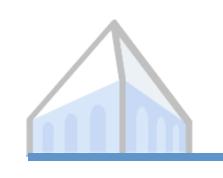
How do we induce a translation model?

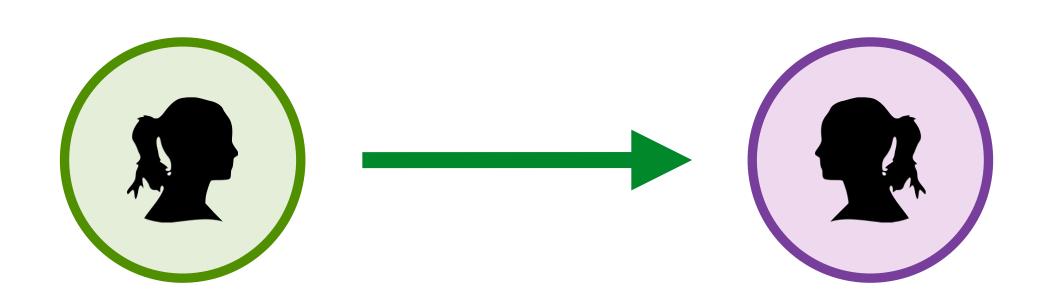


A statistical MT problem

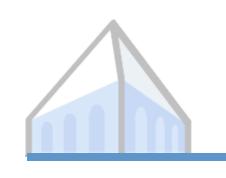
$$\max_{a} p(\mathbf{0} | \mathbf{a}) p(\mathbf{a})$$

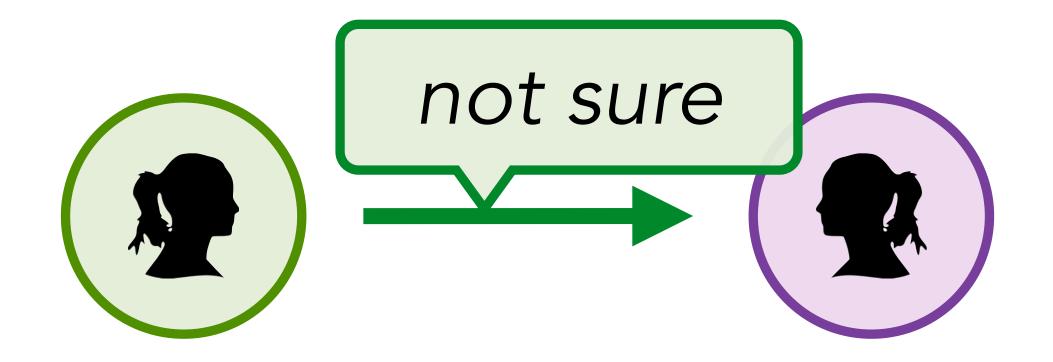
$$\approx \max_{a} \sum_{b} p(\mathbf{0} | \mathbf{a}) p(\mathbf{a} | \mathbf{a}) p(\mathbf{a} | \mathbf{a}) p(\mathbf{a} | \mathbf{a})$$



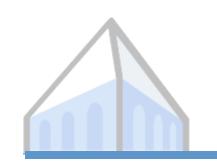


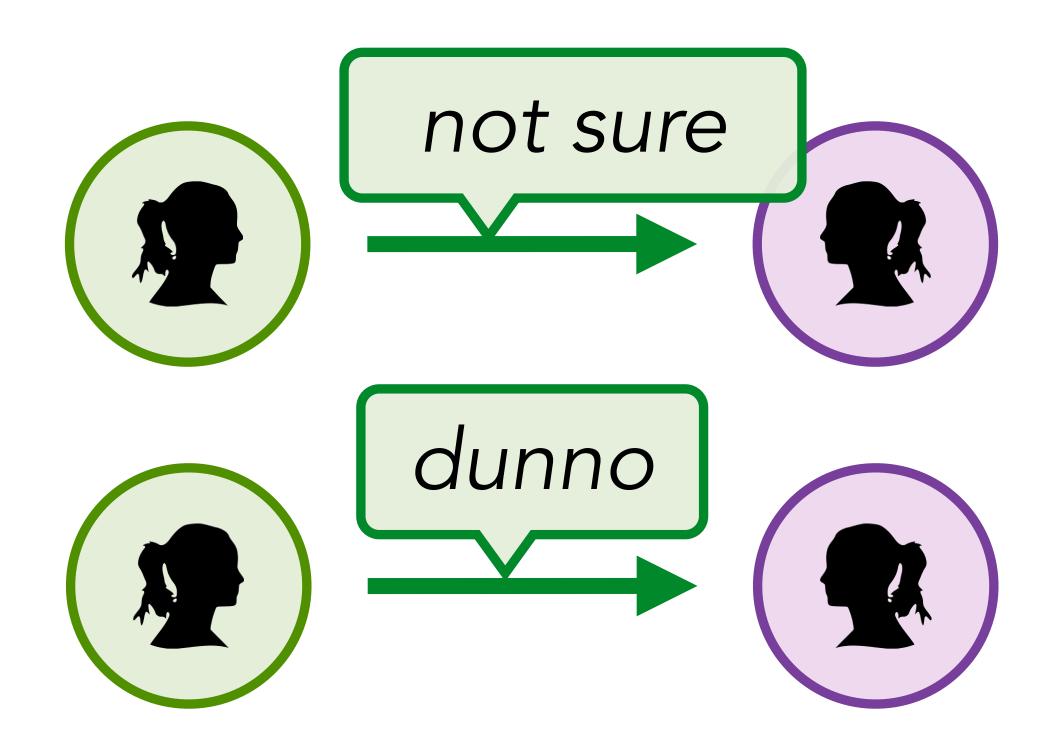
$$\zeta(s) = \frac{1}{\Gamma(s)} \int_0^\infty \frac{1}{e^x - 1} x^s \frac{\mathrm{d}x}{x}$$

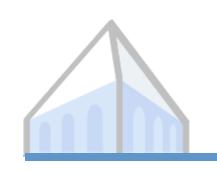


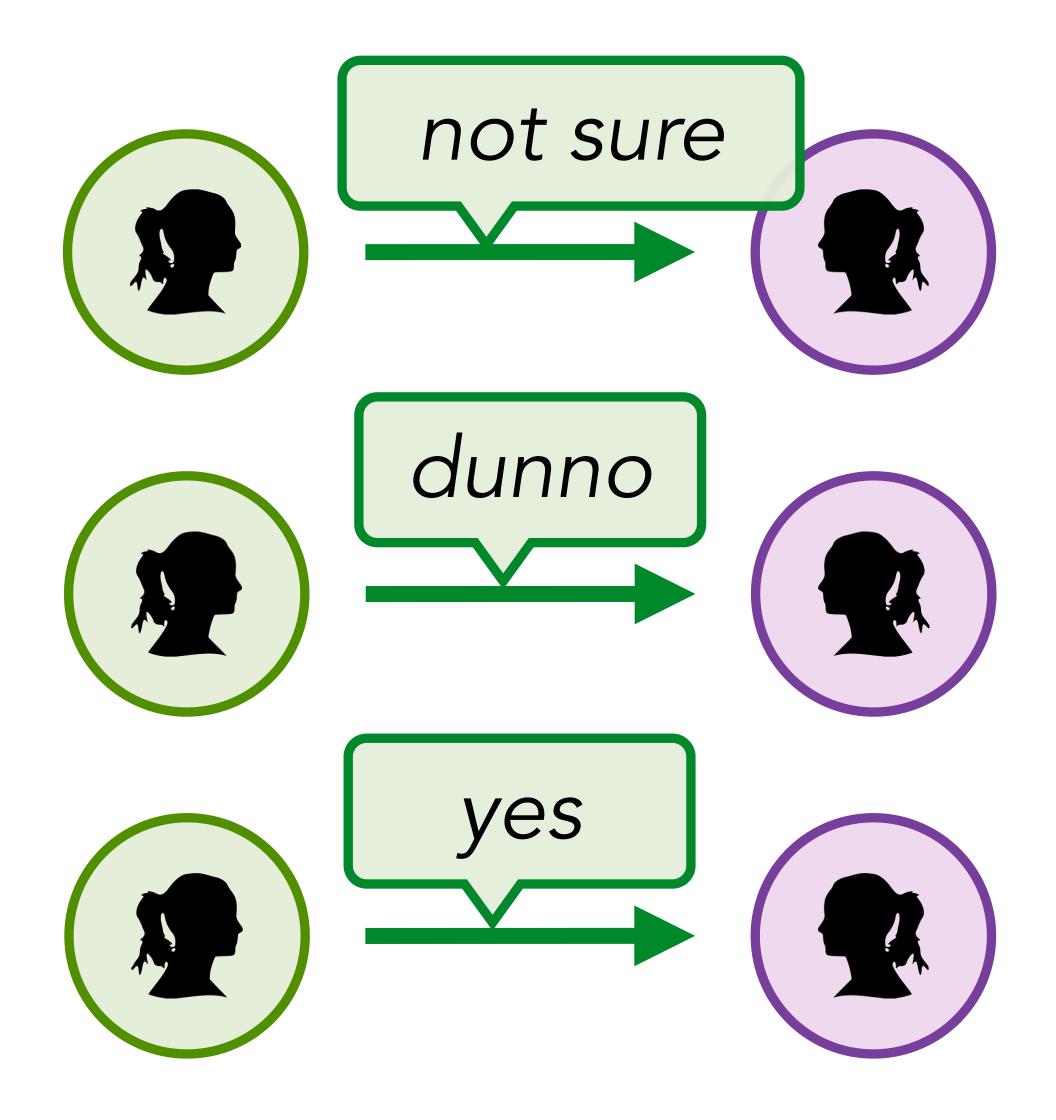


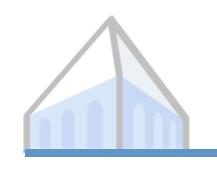
$$\zeta(s) = \frac{1}{\Gamma(s)} \int_0^\infty \frac{1}{e^x - 1} x^s \frac{\mathrm{d}x}{x}$$

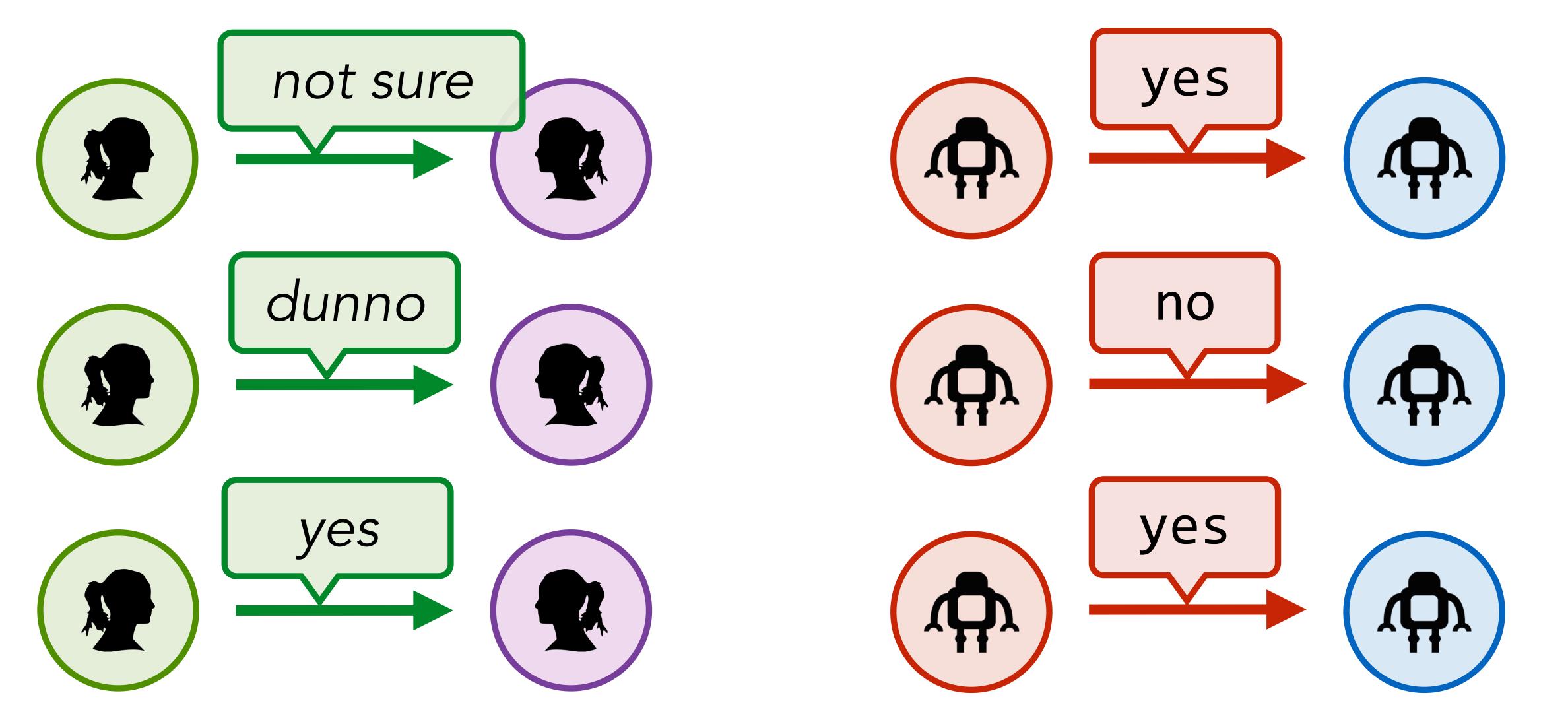


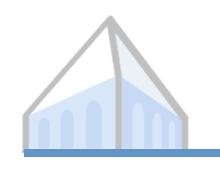






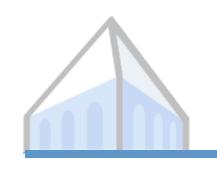




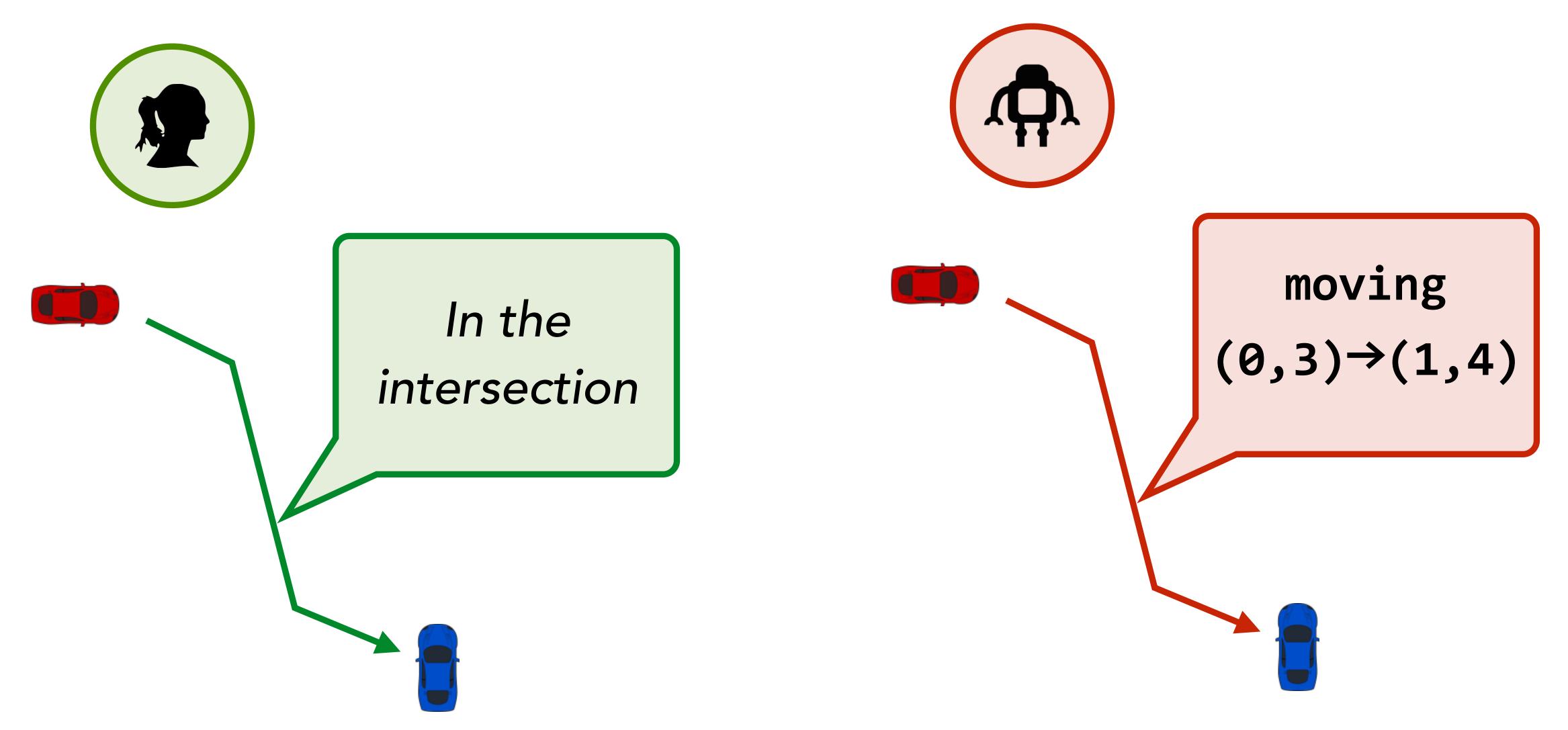




$$\sum p(0)$$
, | Inot sure) $p(not sure)$



Stat MT criterion doesn't capture meaning



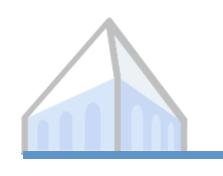


Natural language & neuralese

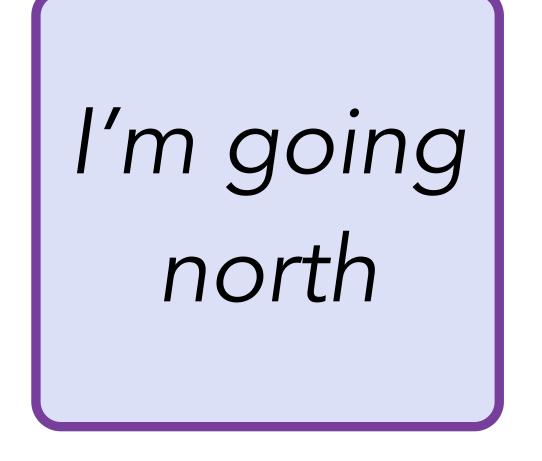
X Statistical machine translation

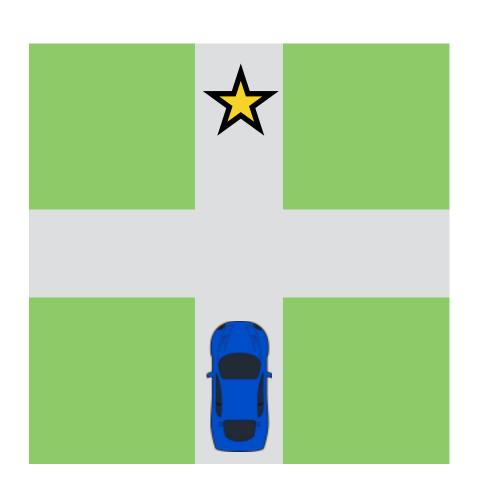
Semantic machine translation

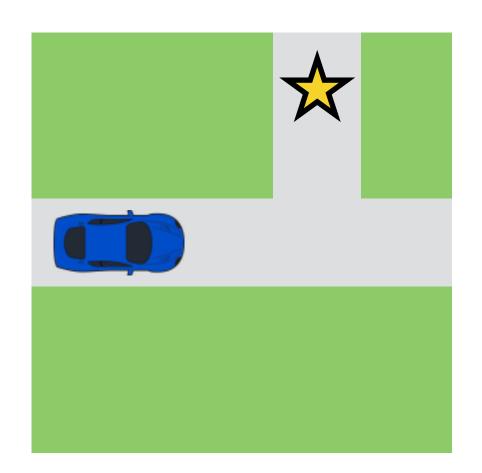
Implementation details

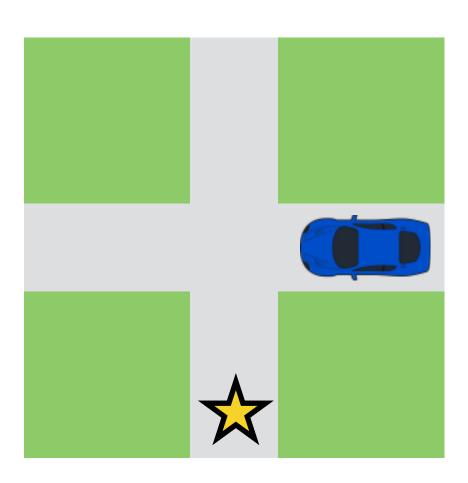


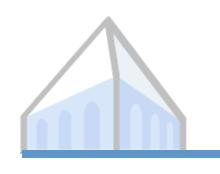
The meaning of an utterance is given by its truth conditions





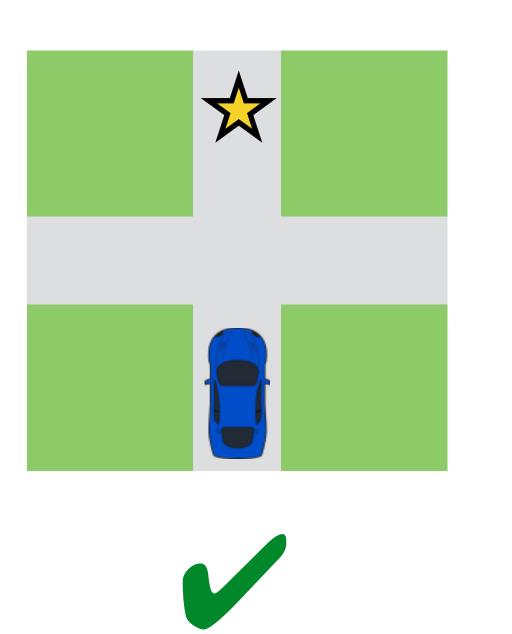


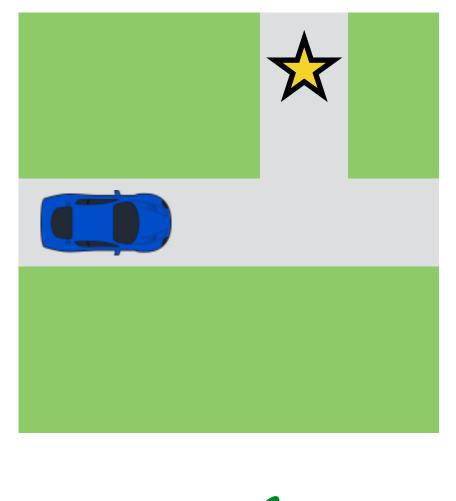


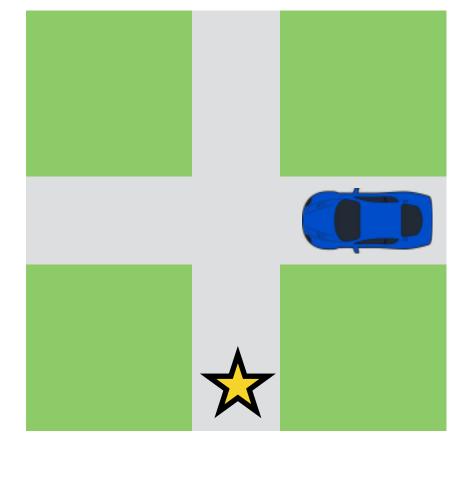


The meaning of an utterance is given by its truth conditions



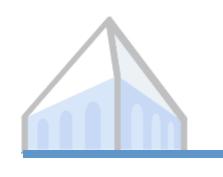






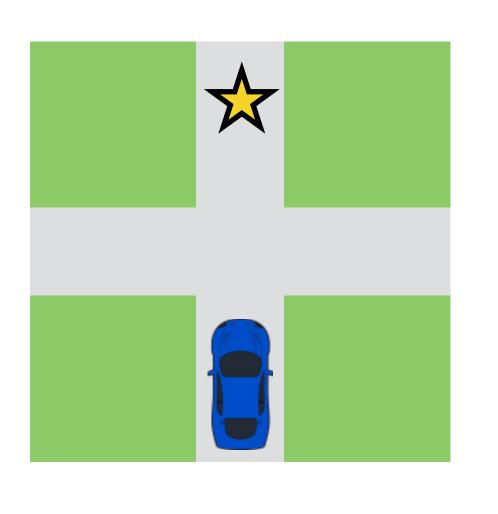


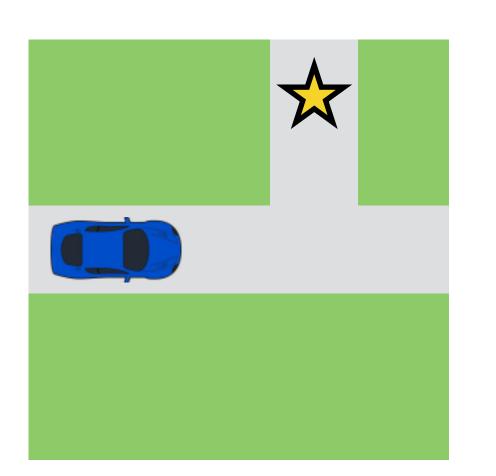


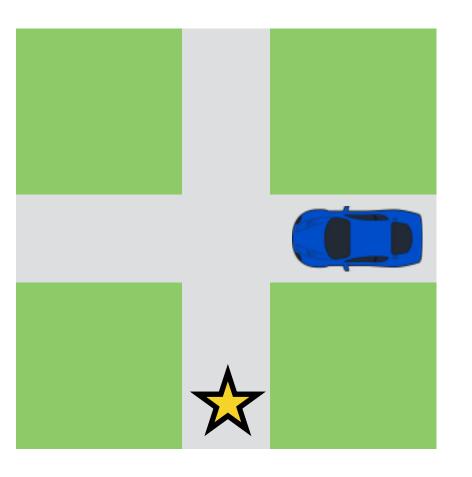


The meaning of an utterance is given by its truth conditions

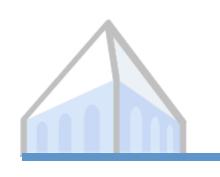








(loc (goal blue) north)

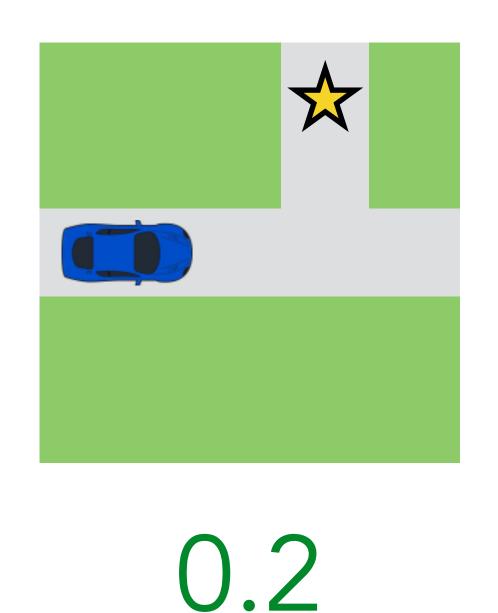


The meaning of an utterance is given by its truth conditions

the distribution over states in which it is uttered

I'm going north

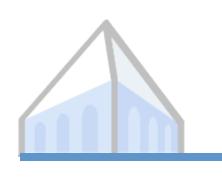






[Beltagy et al. 14]

0.001

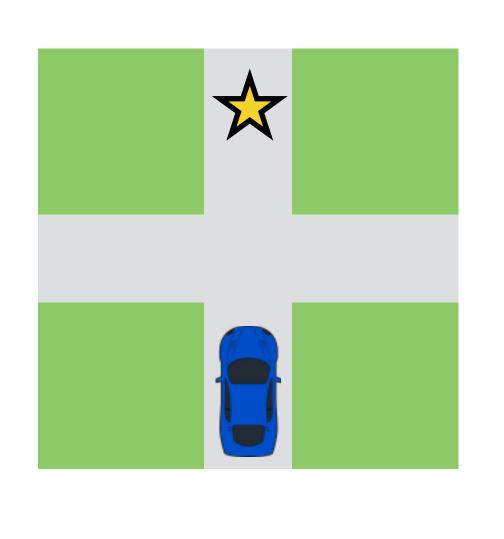


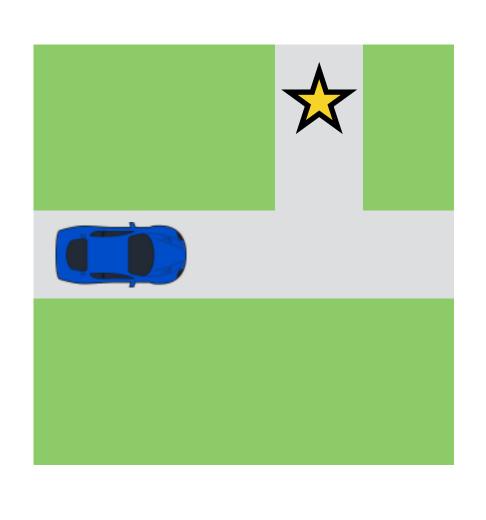
The meaning of an utterance is given by its truth conditions

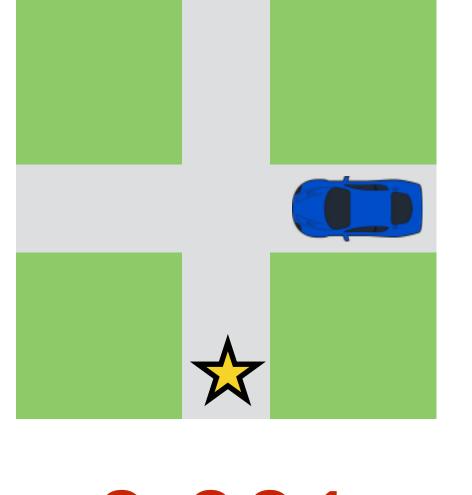
the distribution over states in which it is uttered

the **belief** it induces in listeners





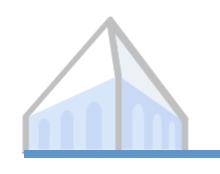




0.4

0.2

0.001

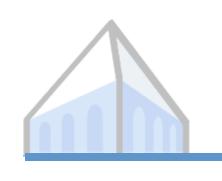


Representing meaning

The meaning of an utterance is given by

the distribution over states in which it is uttered

or equivalently, the **belief** it induces in listeners



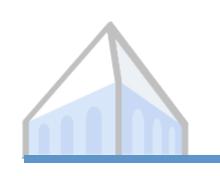
Representing meaning

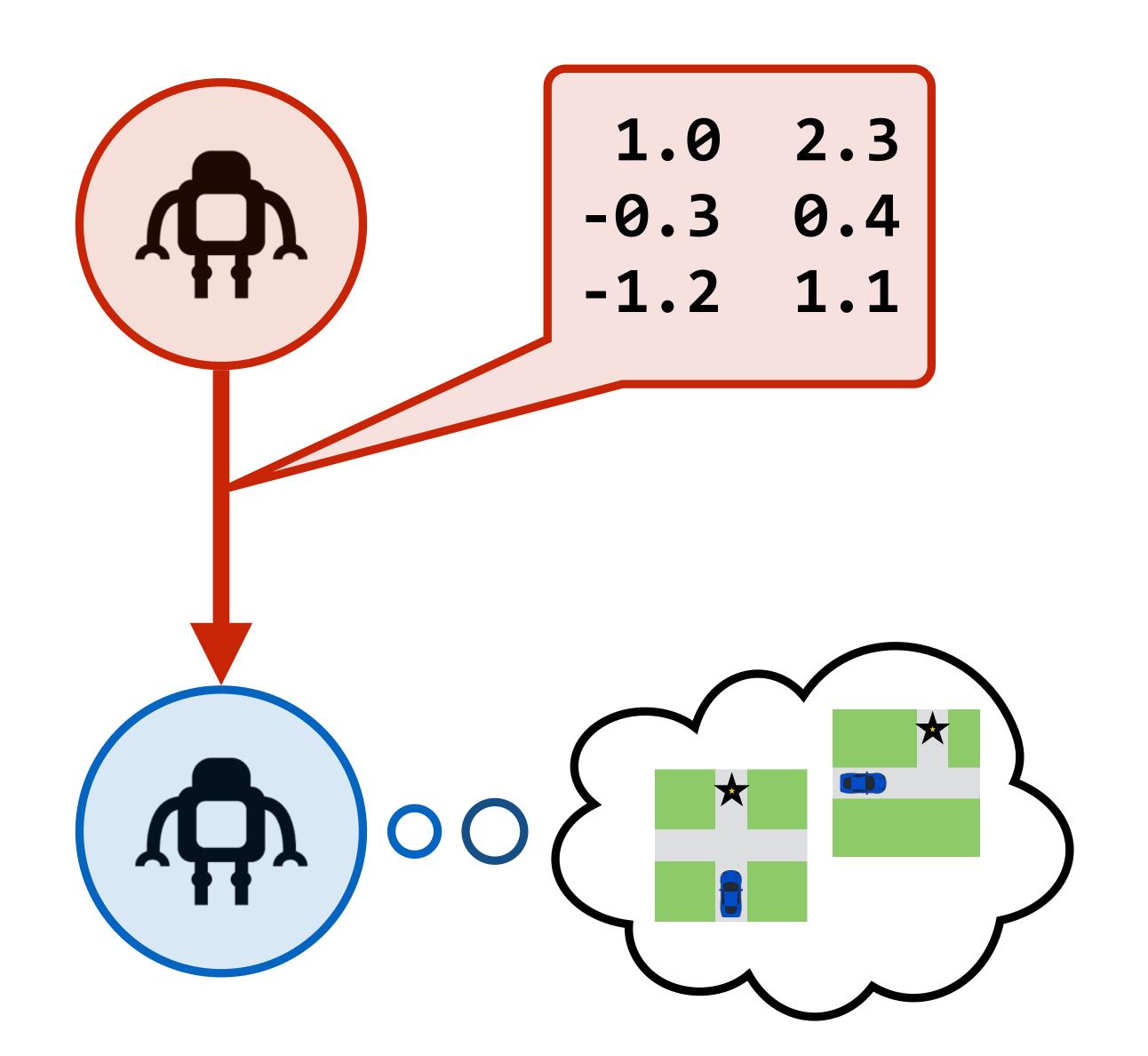
The meaning of an utterance is given by

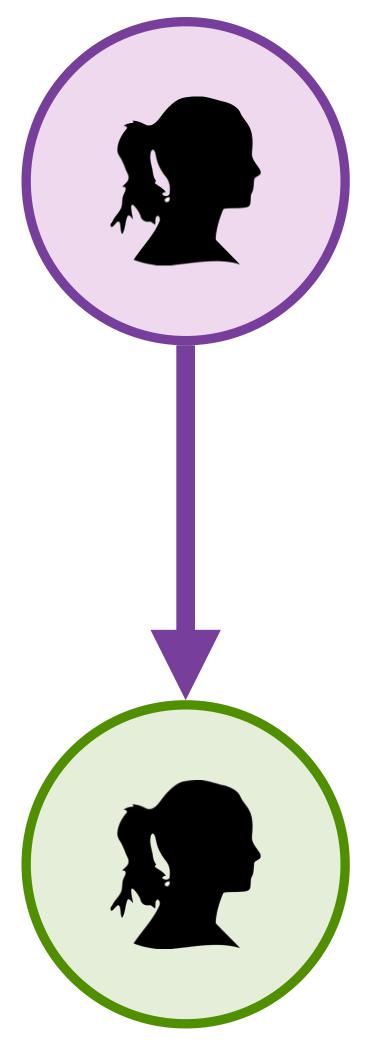
the distribution over states in which it is uttered

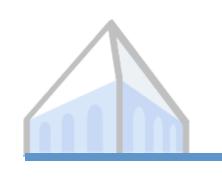
or equivalently, the **belief** it induces in listeners

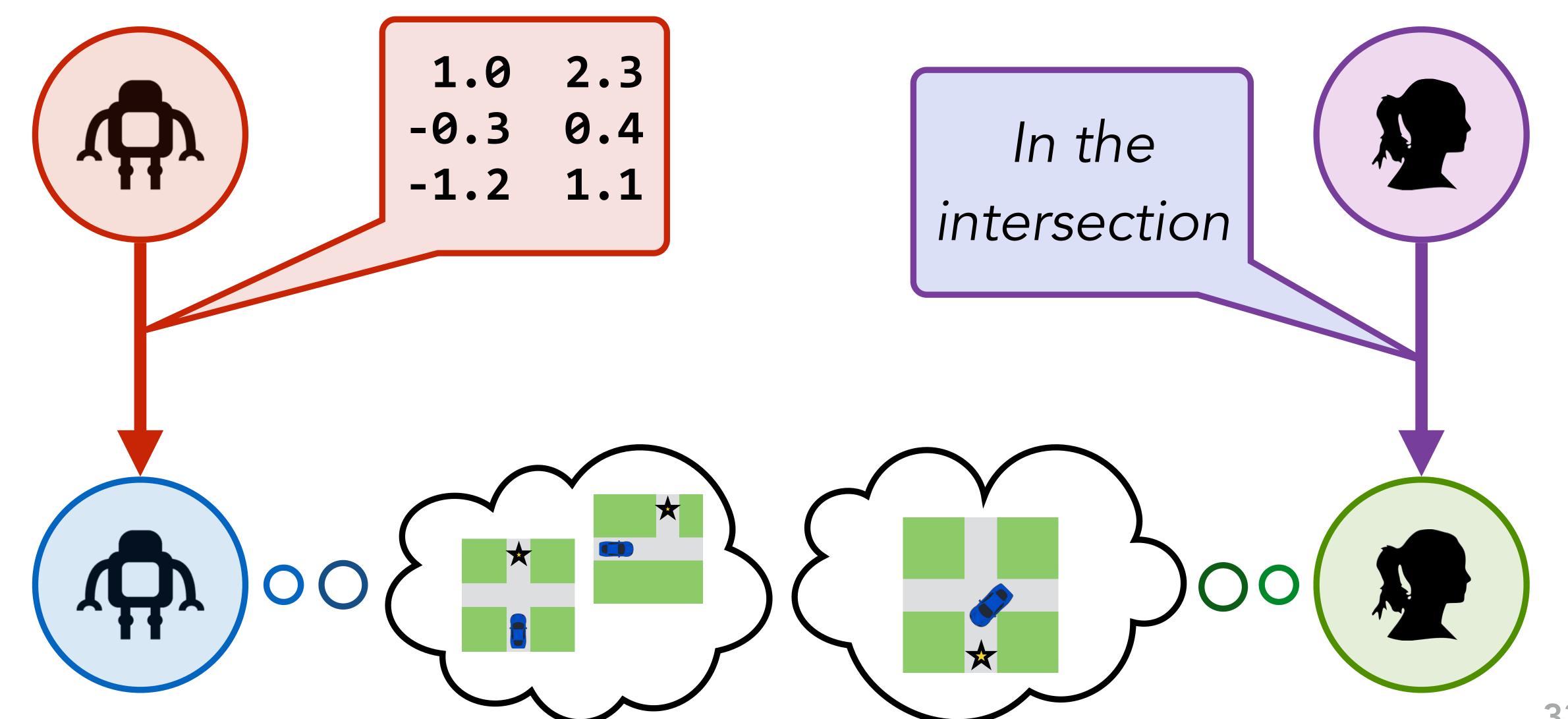
This distribution is well-defined even if the "utterance" is a vector rather than a sequence of tokens.

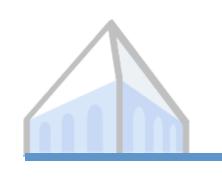


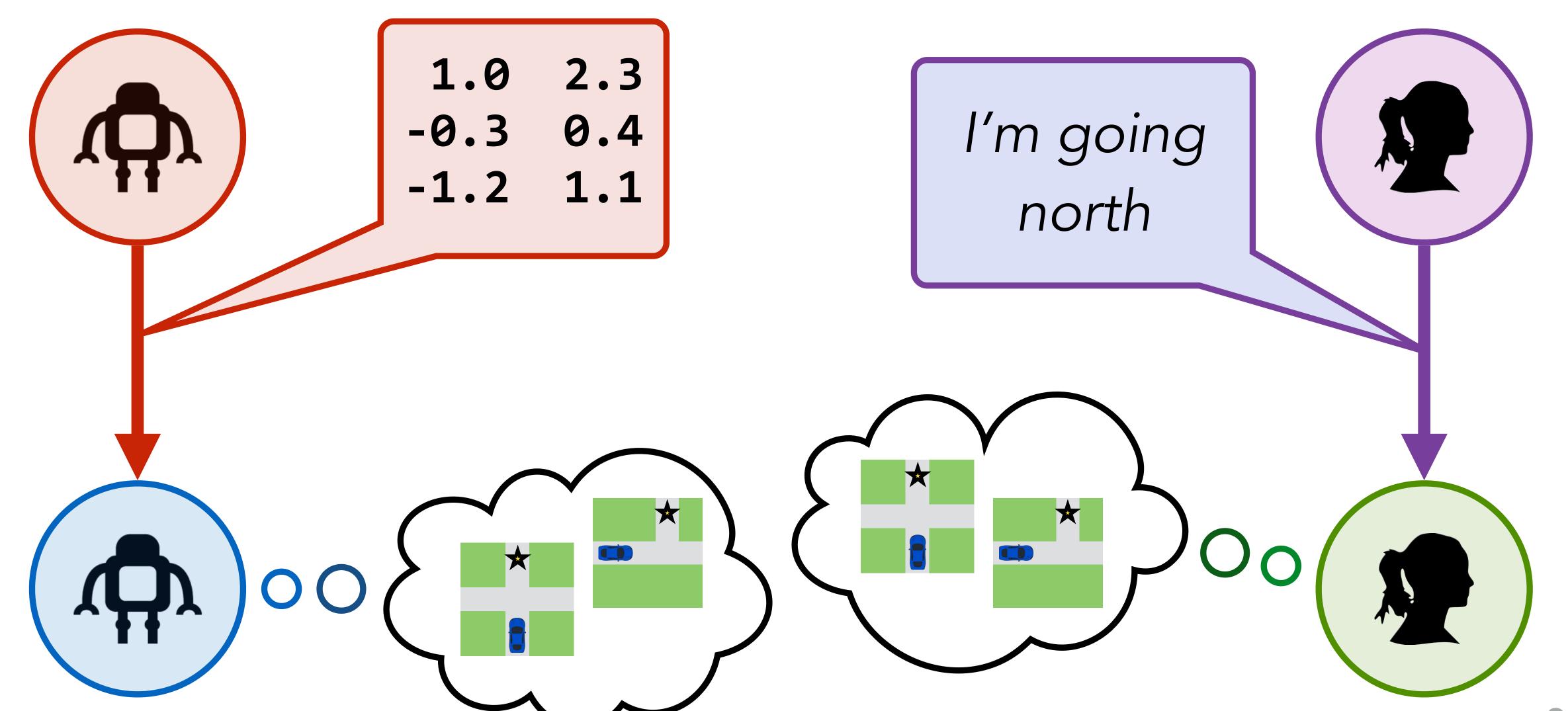


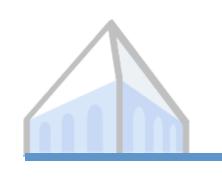


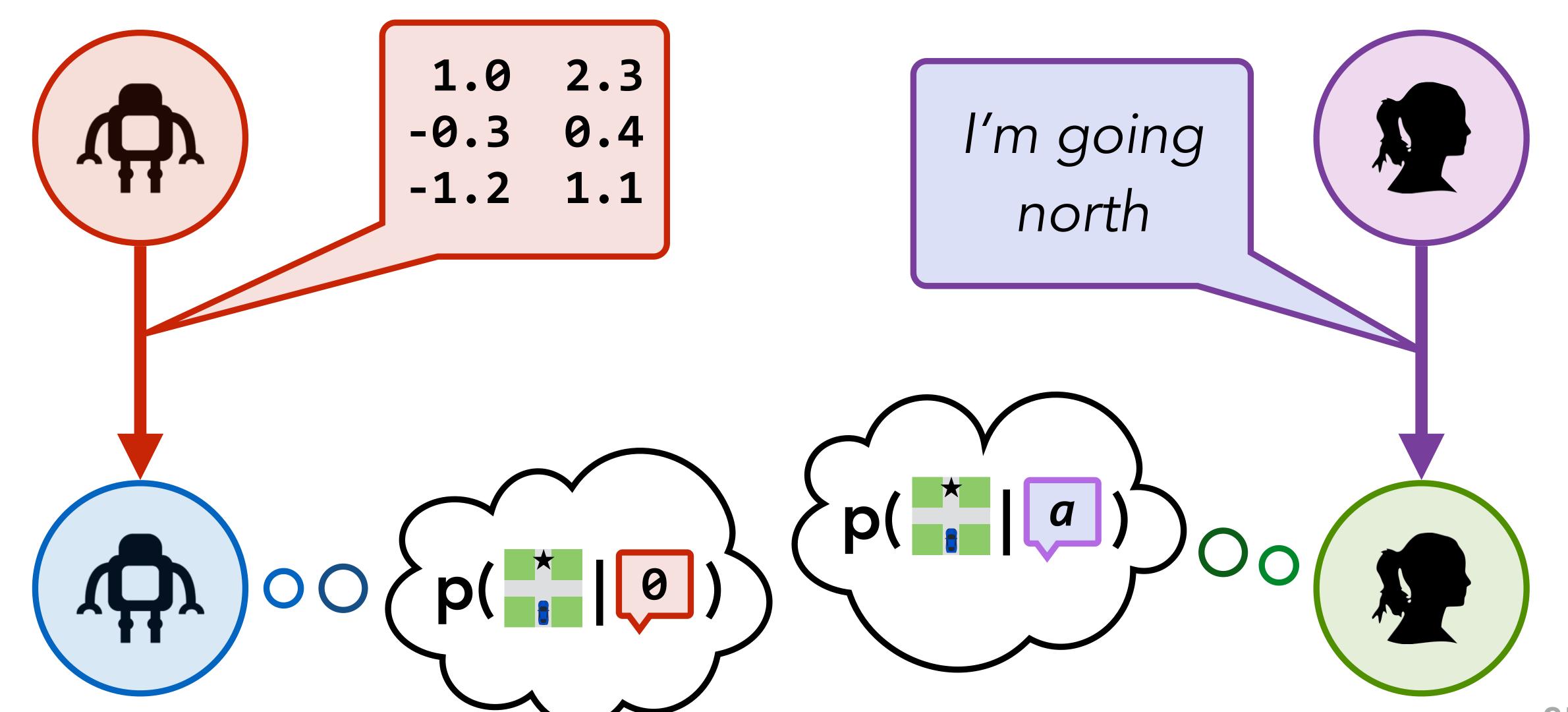


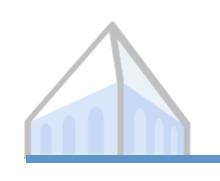


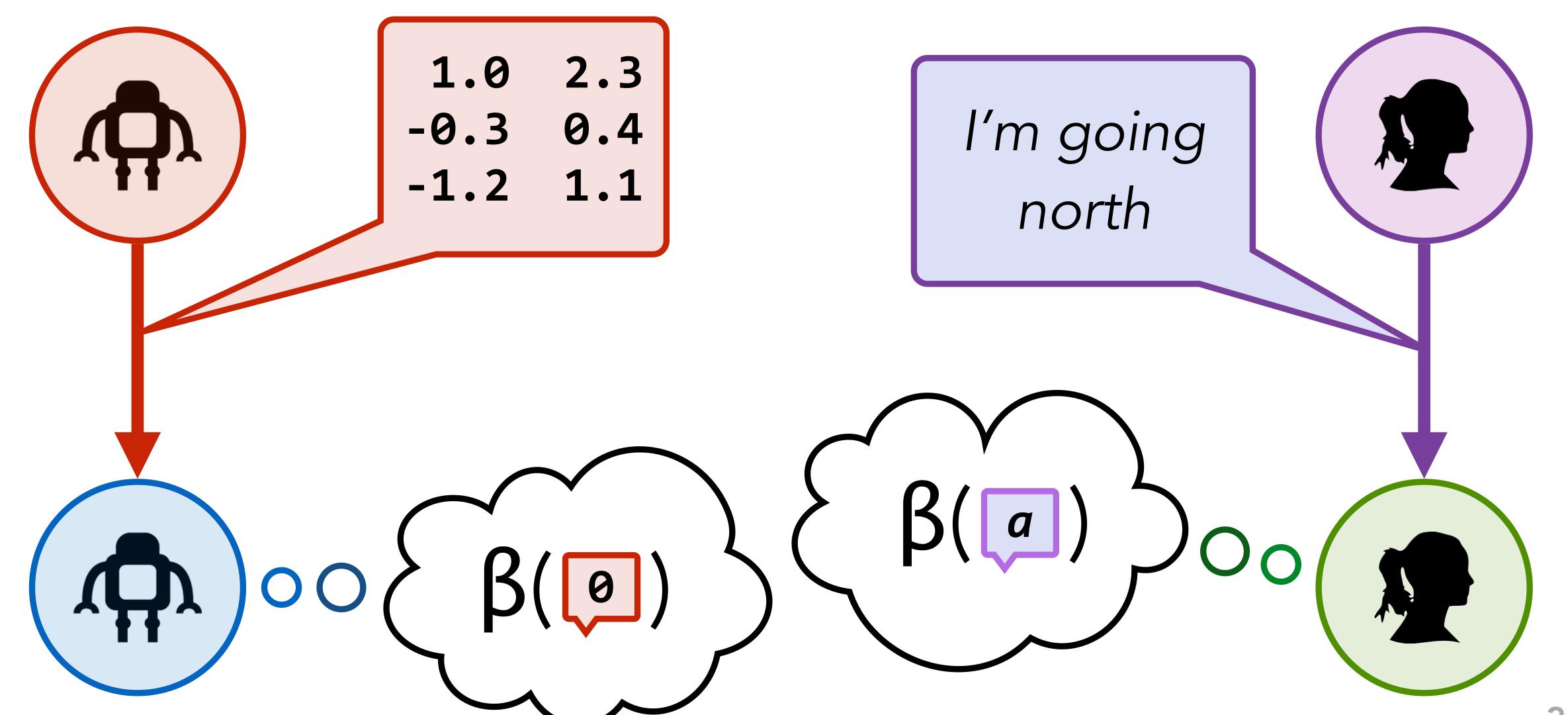






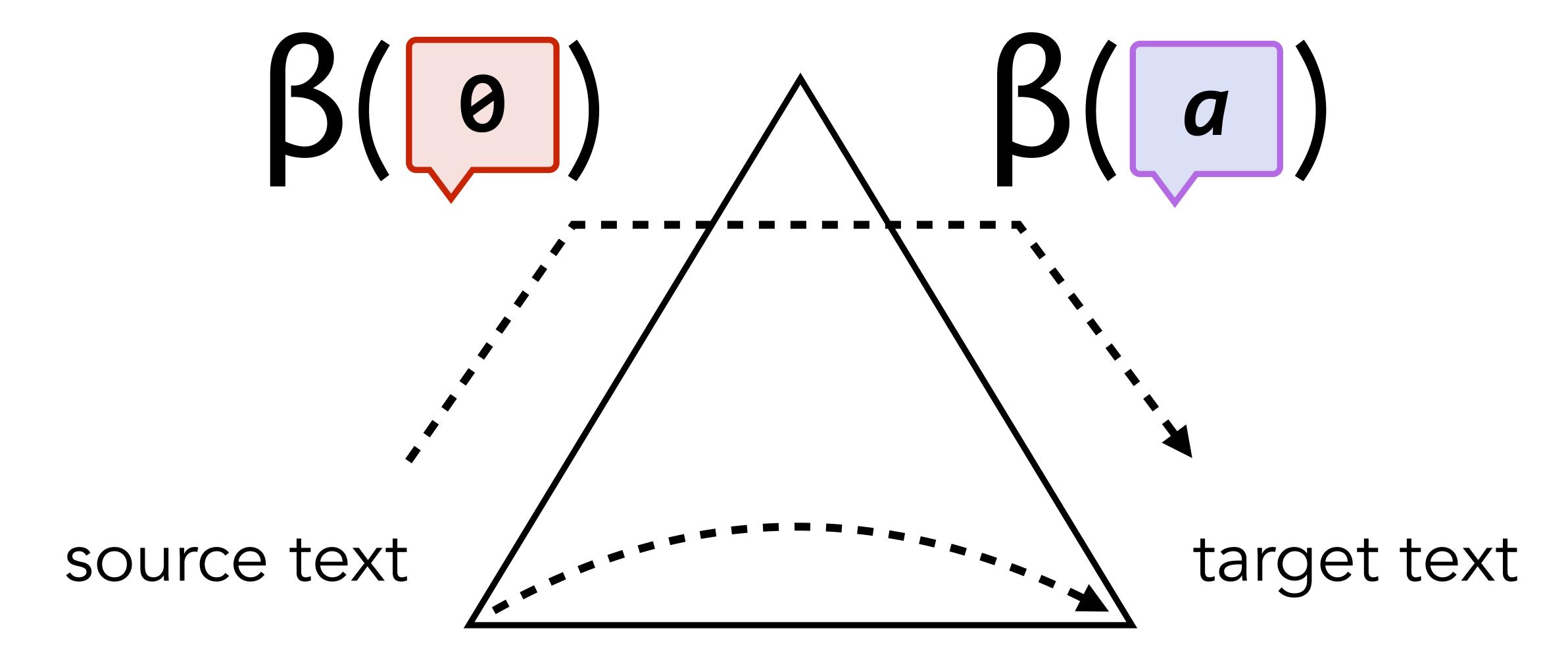








Interlingua!





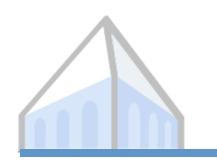
$$KL(\beta(0)|\beta(a))$$



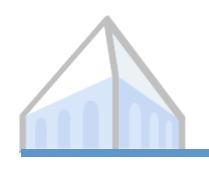
$$KL(\beta(\emptyset))|\beta(a))$$



$$KL(\beta(\Theta))II\beta(\Theta))$$

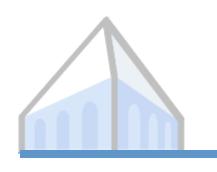


$$KL(\beta(\Theta)||\beta(\Phi))$$



Computing representations

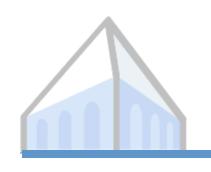
$$\operatorname{argmin}_{a} \operatorname{KL}(\beta(\mathfrak{G}) | \beta(\mathfrak{G}))$$

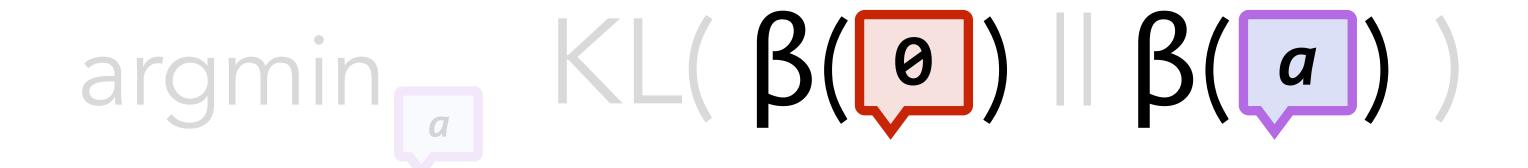


Computing representations: sparsity

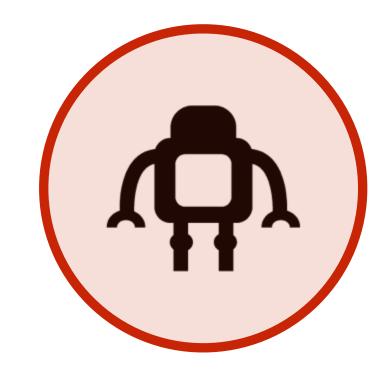
$$\operatorname{argmin}_{a}$$
 KL($\beta(\mathfrak{G})$) | $\beta(\mathfrak{G})$)

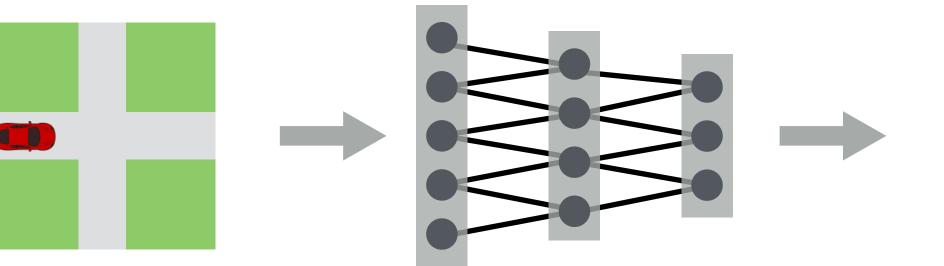




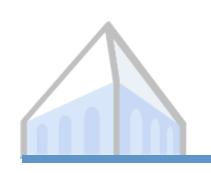


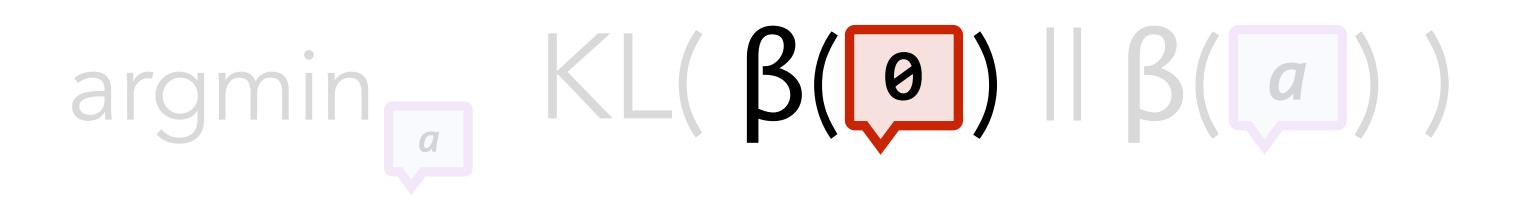
agent policy



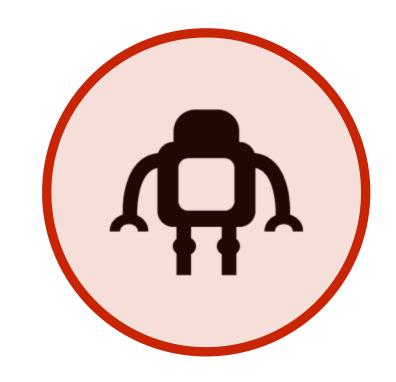


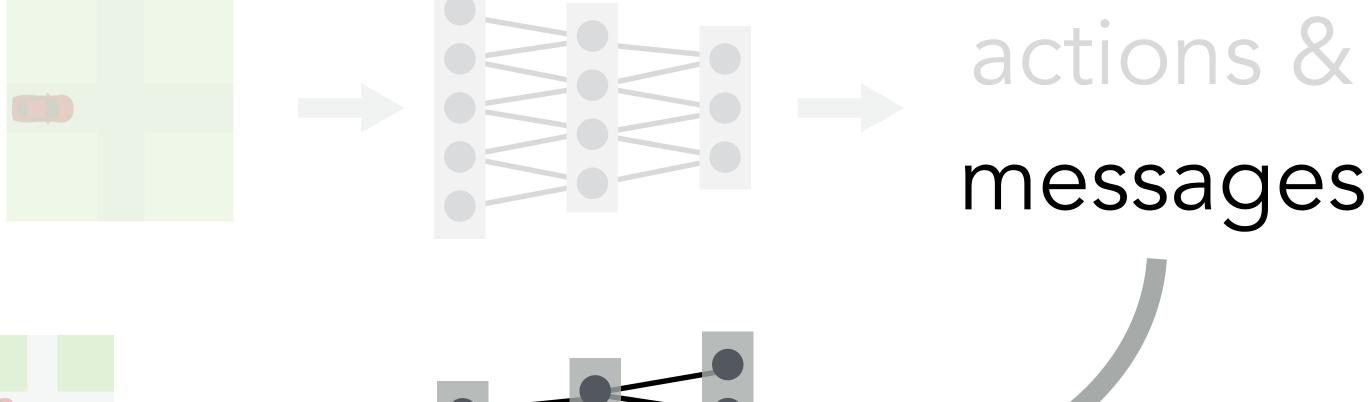
actions & messages



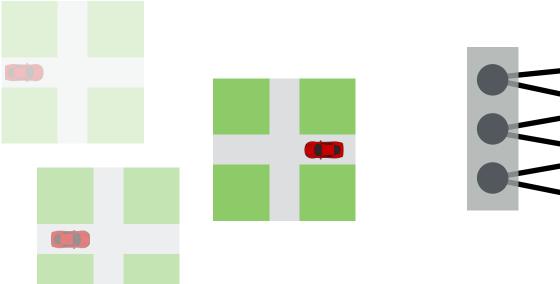


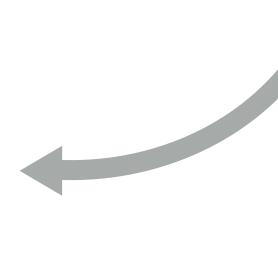
agent policy

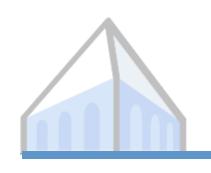


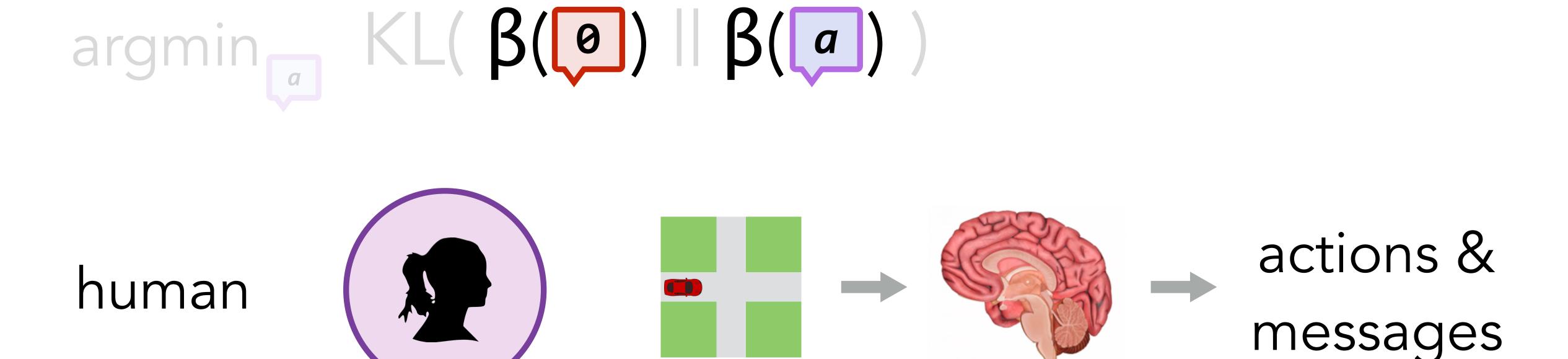


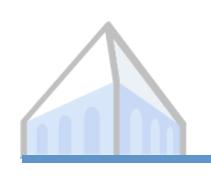
agent model







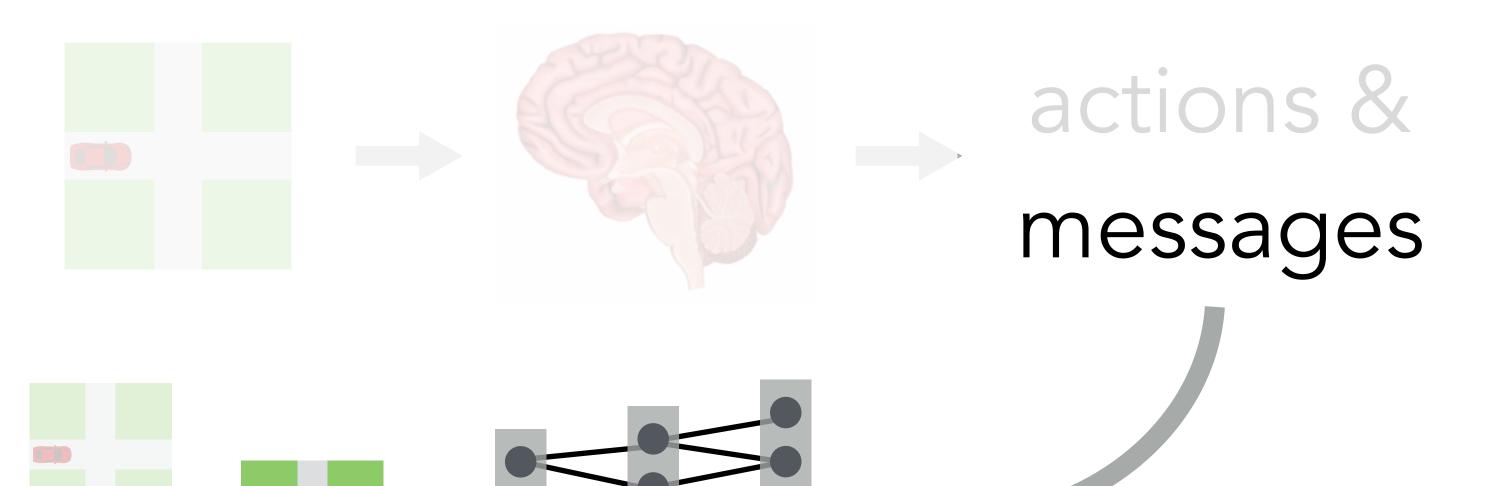




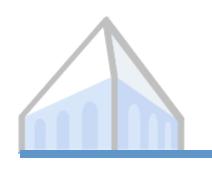
 $\operatorname{argmin}_{a}$ KL($\beta(\mathfrak{G})$) | $\beta(\mathfrak{G})$)

human policy





human model



$$\operatorname{argmin}_{a} \operatorname{KL}(\beta(\mathfrak{G}) | \beta(\mathfrak{G}))$$

0.10	0.08
0.05	0.01
0.13	0.22



Computing KL



Computing KL

$$KL(p | I | q) = \mathbf{E}_p \frac{p(\mathbf{x})}{q(\mathbf{x})}$$



Computing KL: sampling

$$KL(p | | q) = \sum_{i} p(\mathbf{x}_{i}) \log \frac{p(\mathbf{x}_{i})}{q(\mathbf{x}_{i})}$$



Finding translations

$$\operatorname{argmin}_{a}$$
 KL($\beta(a)$) | $\beta(a)$)



Finding translations: brute force

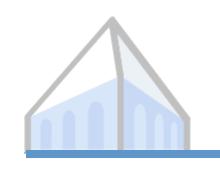
$$\operatorname{argmin}_{a} \operatorname{KL}(\beta(\mathfrak{G}) | \beta(\mathfrak{G}))$$

```
going north \longrightarrow 0.5

crossing the intersection \longrightarrow 2.3

l'm done \longrightarrow 0.2

after you \longrightarrow 9.7
```



Finding translations: brute force

$$\operatorname{argmin}_{a}$$
 KL($\beta(a)$) | $\beta(a)$)

```
going north \longrightarrow 0.5

crossing the intersection \longrightarrow 2.3

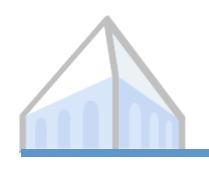
I'm done \longrightarrow 0.2

after you \longrightarrow 9.7
```



Finding translations

$$KL(\beta(0)|\beta(a))$$



Outline

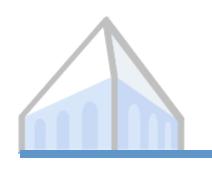
Natural language & neuralese

Statistical machine translation

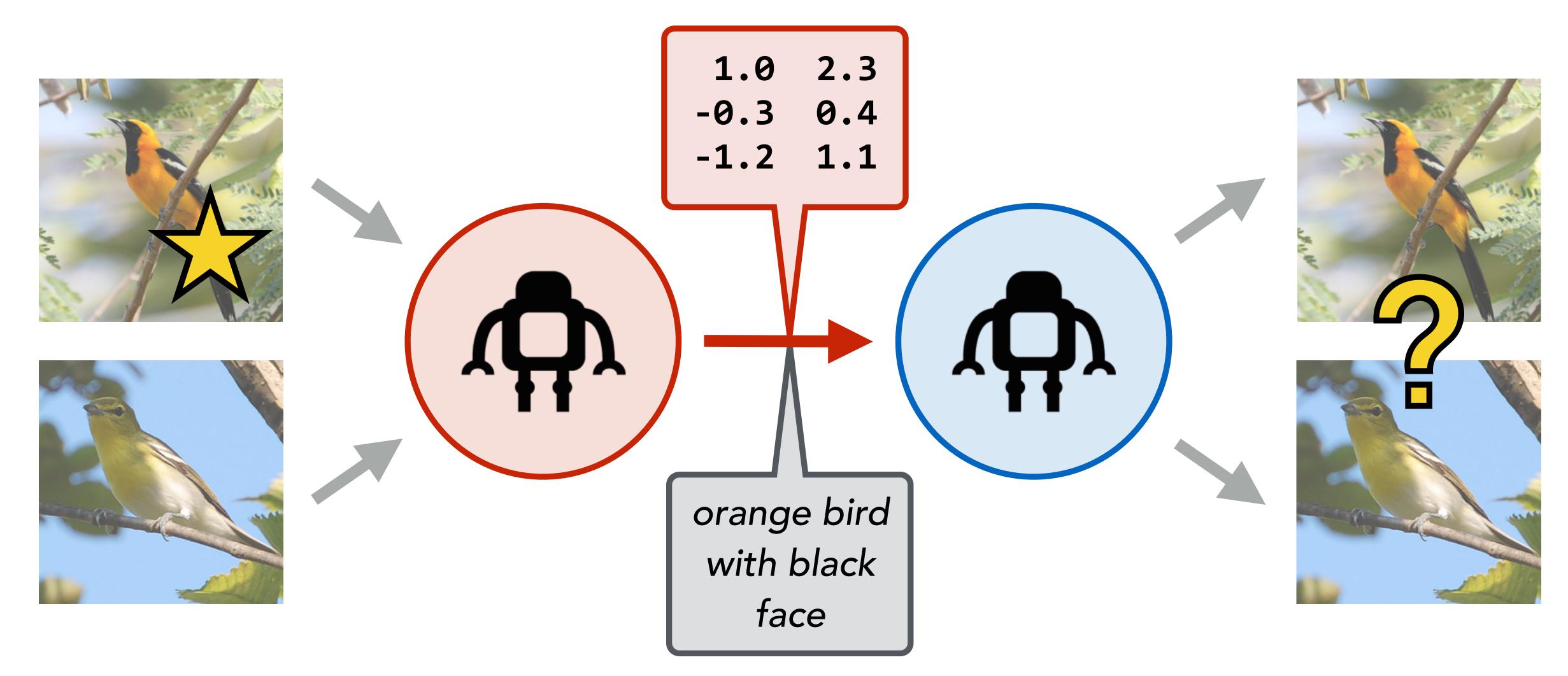
Semantic machine translation

Implementation details

Evaluation

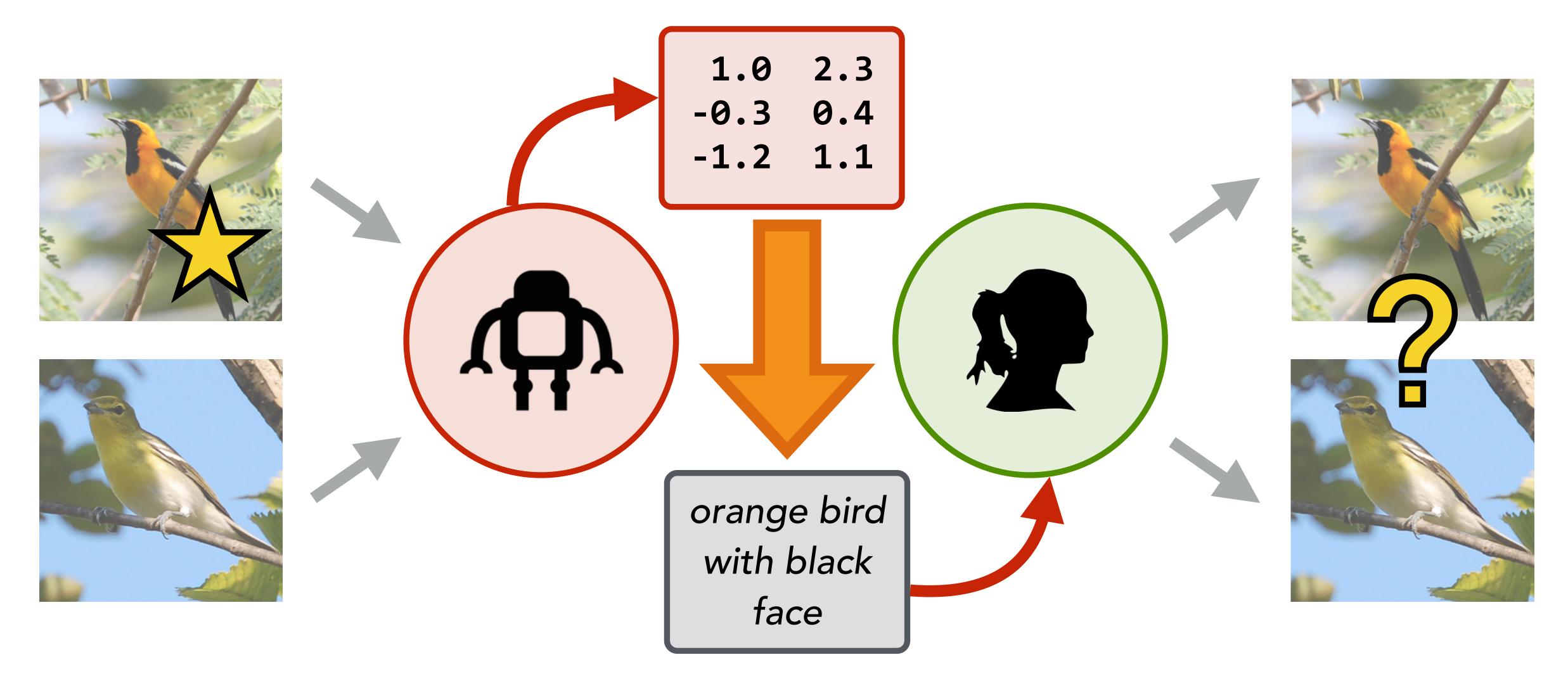


Referring expression games



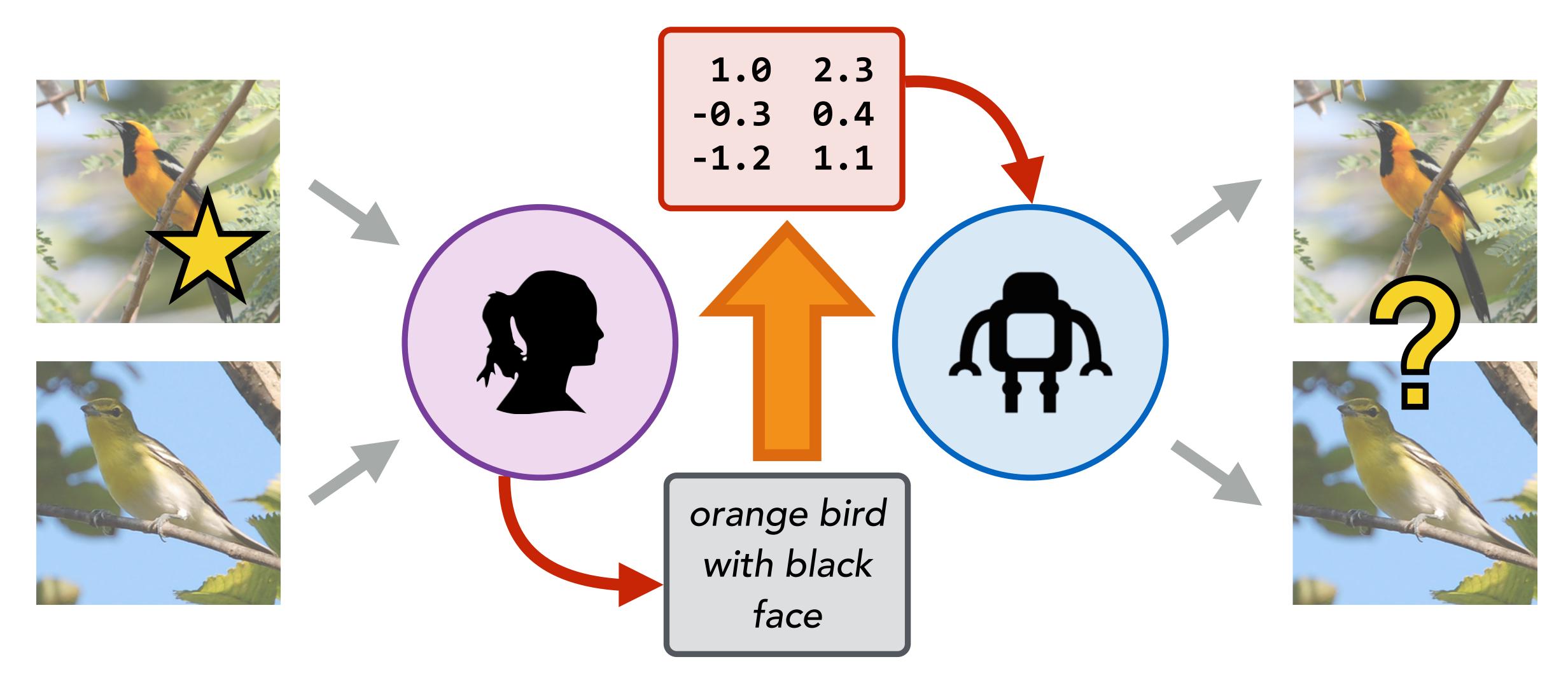


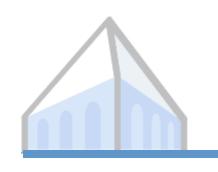
Evaluation: translator-in-the-loop

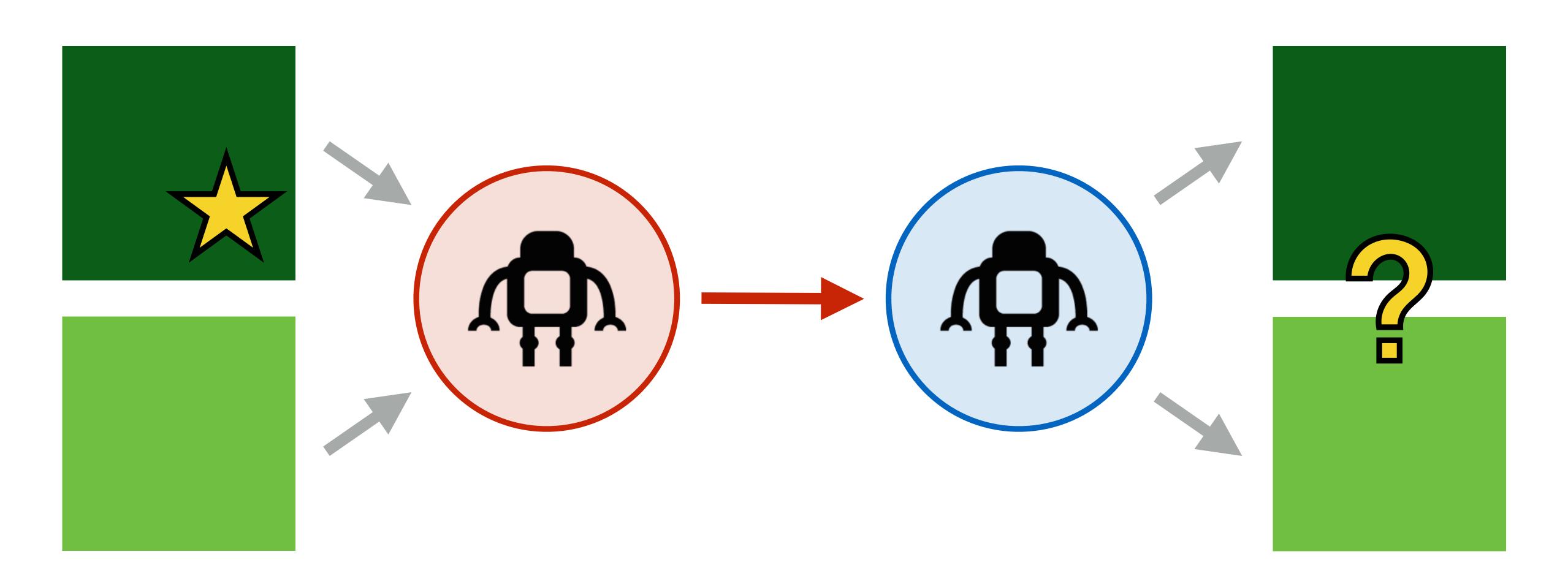




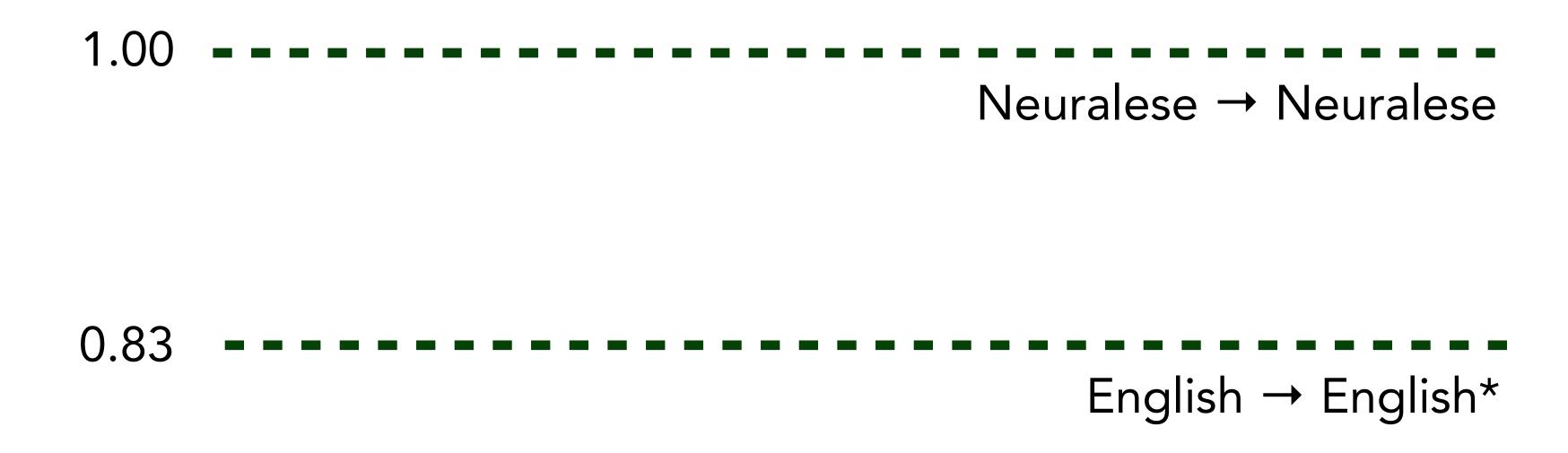
Evaluation: translator-in-the-loop



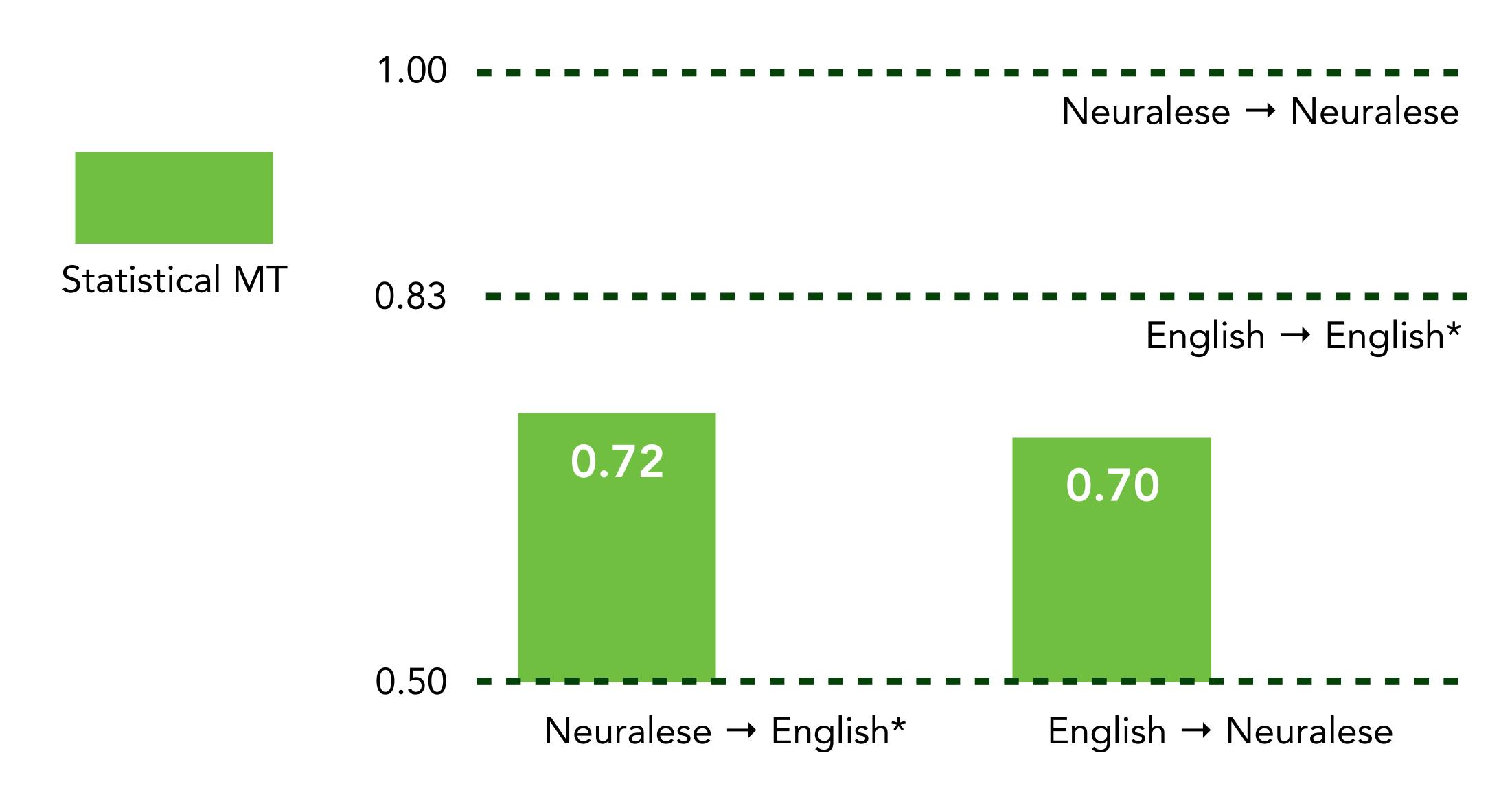


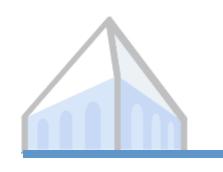


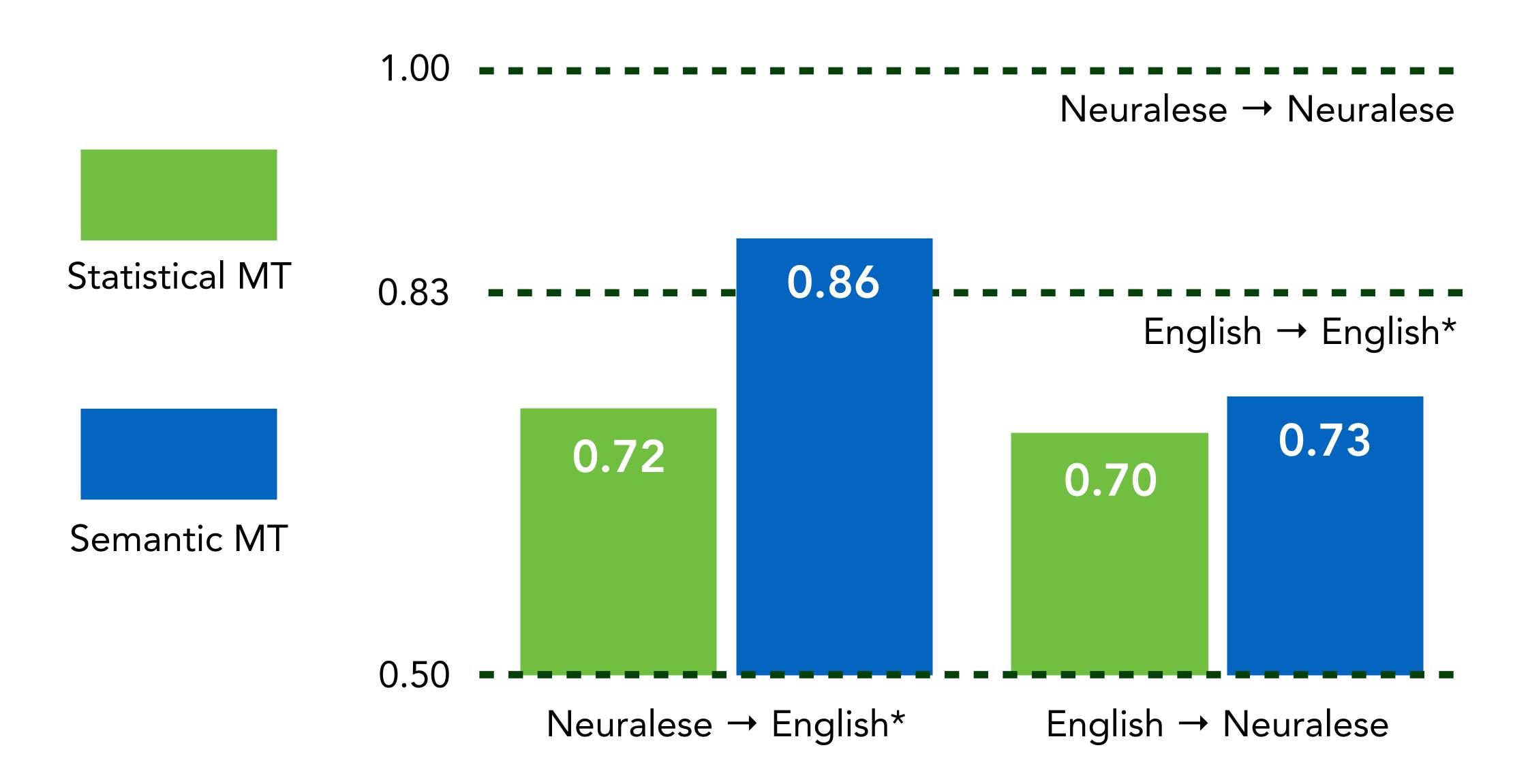




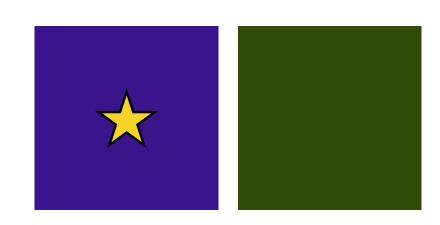




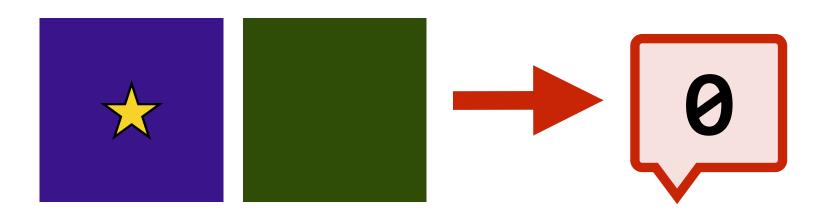




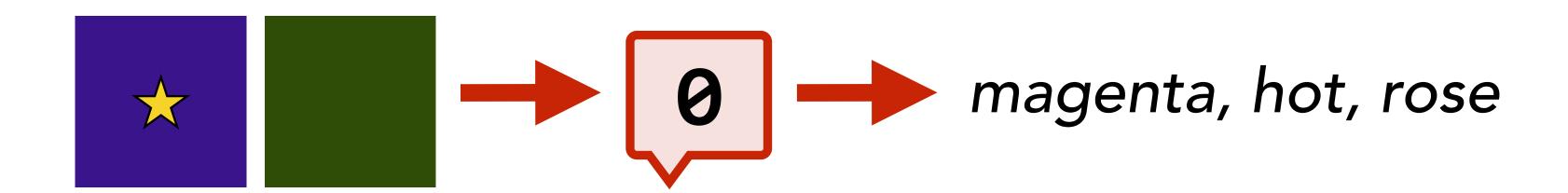




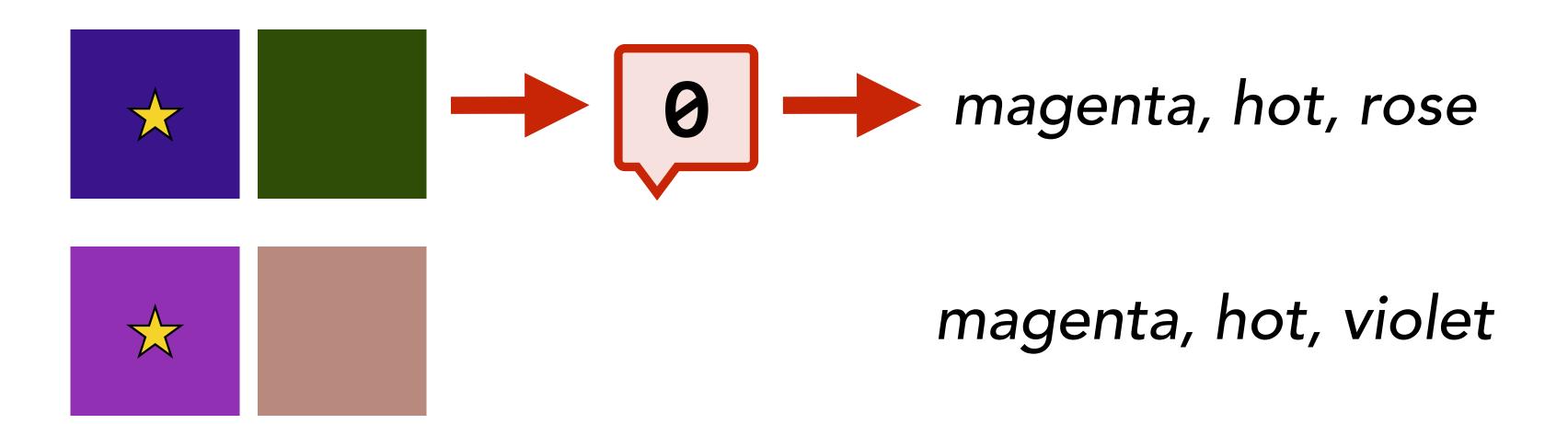




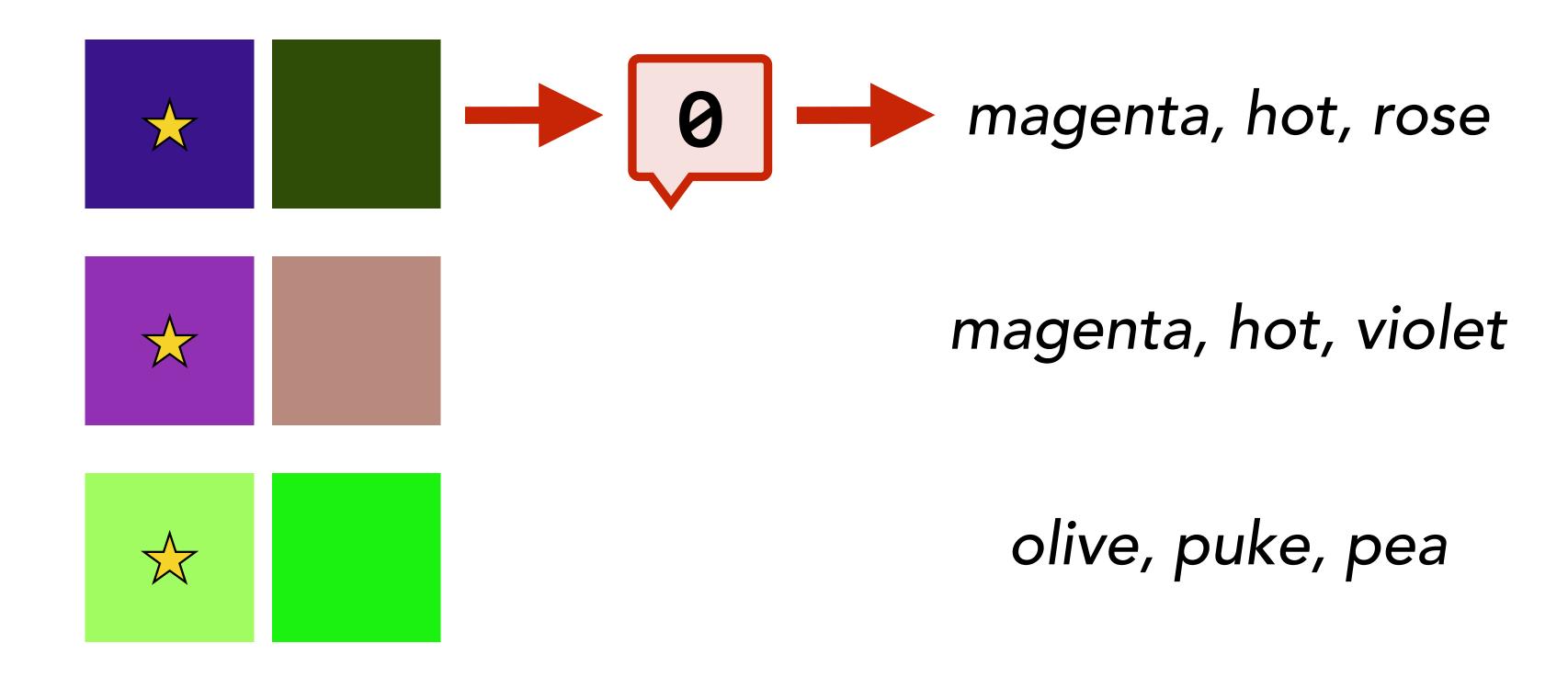




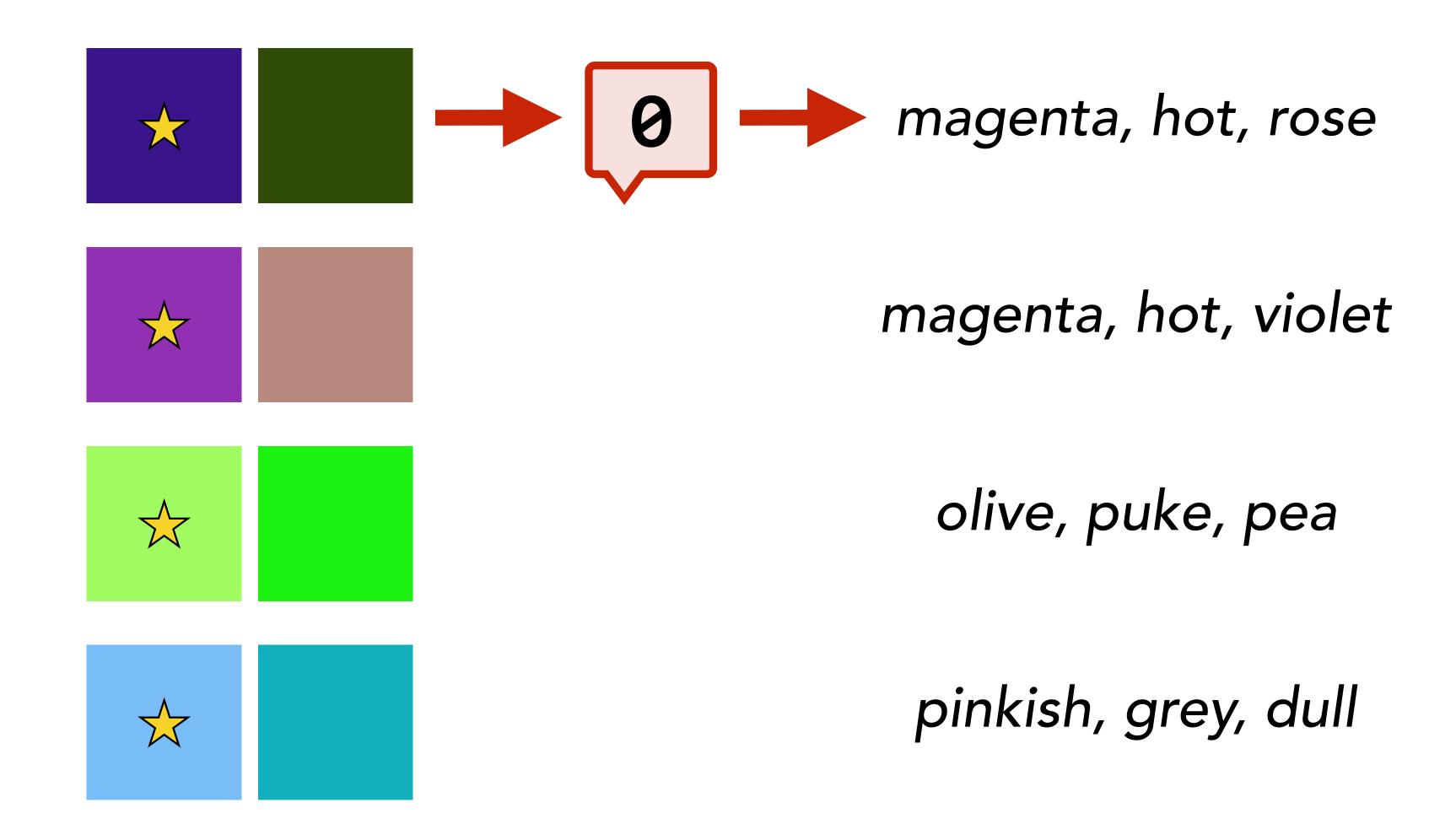


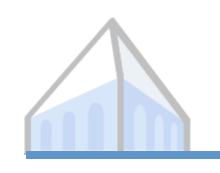




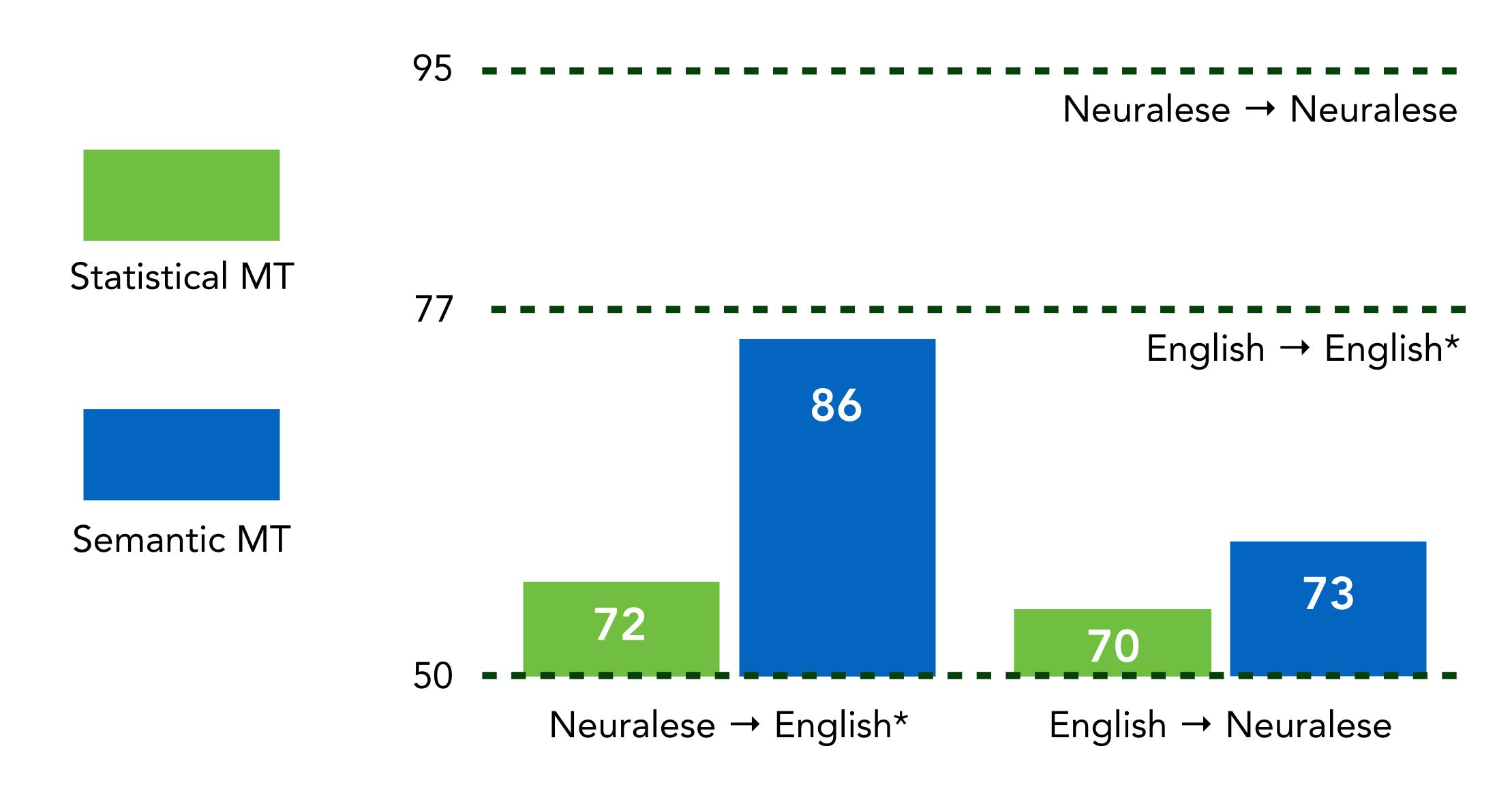








Experiment: image references





Experiment: image references



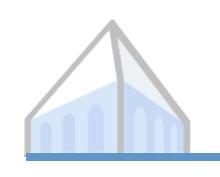


large bird, black wings, black crown

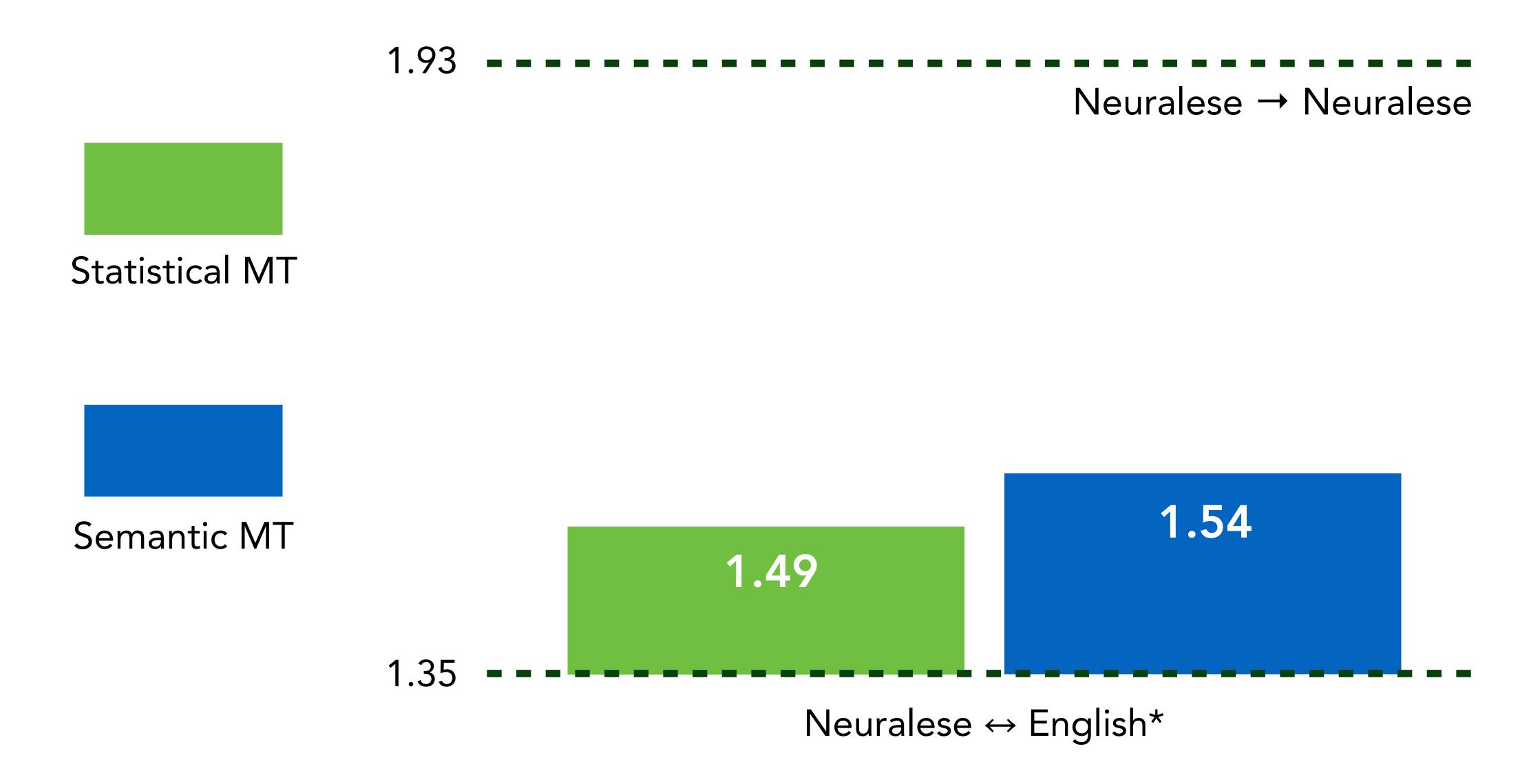


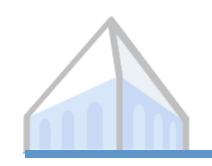


small brown, light brown, dark brown

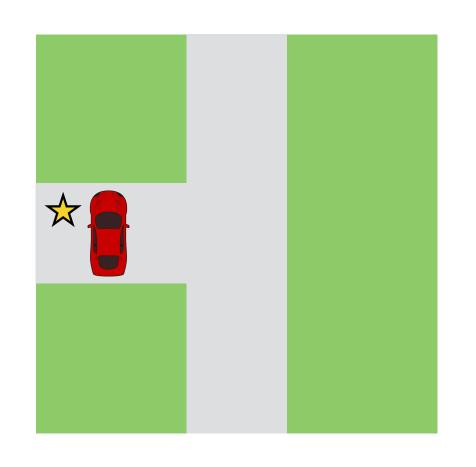


Experiment: driving game

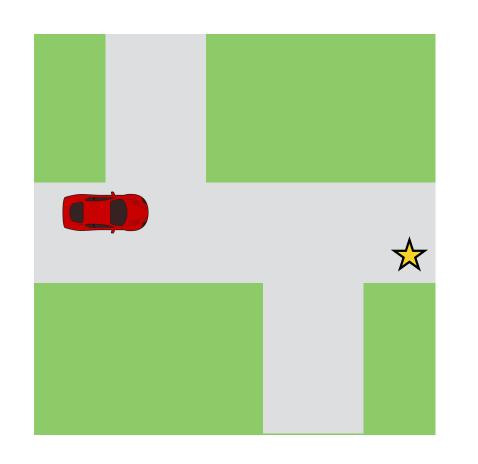




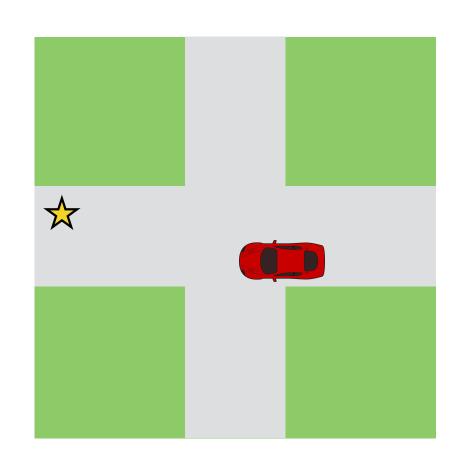
How to translate



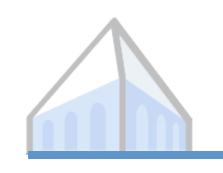
at goal done left to top



you first following going down

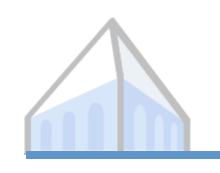


going in intersection proceed going



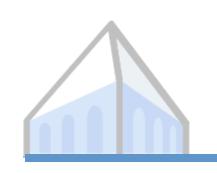
Conclusions so far

- Classical notions of "meaning" apply even to un-language-like things (e.g. RNN states)
- These meanings can be compactly represented without logical forms if we have access to world states
- Communicating policies "say" interpretable things!



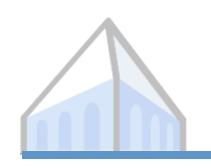
Conclusions so far

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Conclusions so far

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- These meanings can be compactly represented without logical forms if we have access to world states
- Communicating policies "say" interpretable things!

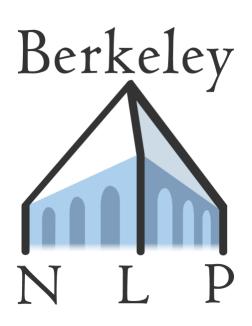


Limitations

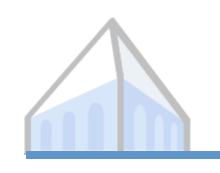
$$KL(p | | q) = \sum_{i} p(\mathbf{x}_{i}) \log \frac{p(\mathbf{x}_{i})}{q(\mathbf{x}_{i})}$$

but what about compositionality?

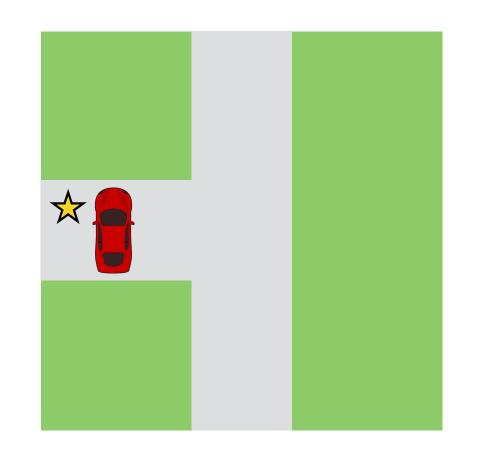
Analogs of linguistic structure in deep representations



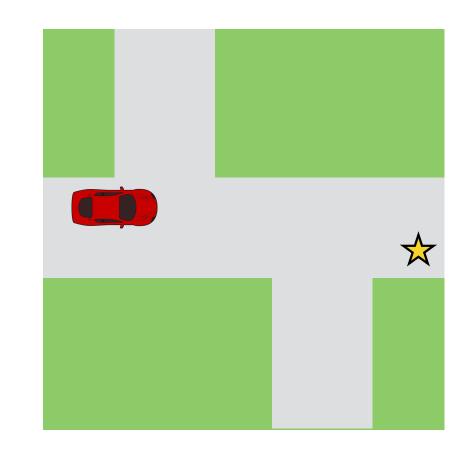
Jacob Andreas and Dan Klein



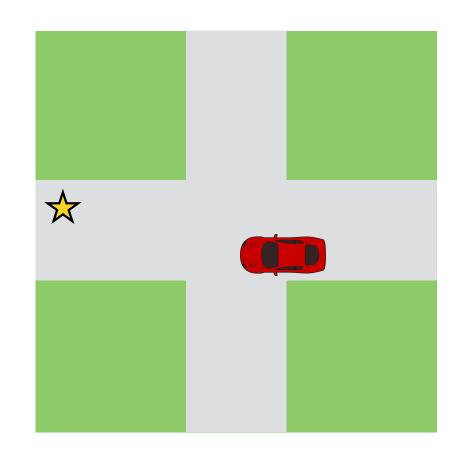
"Flat" semantics



at goal done



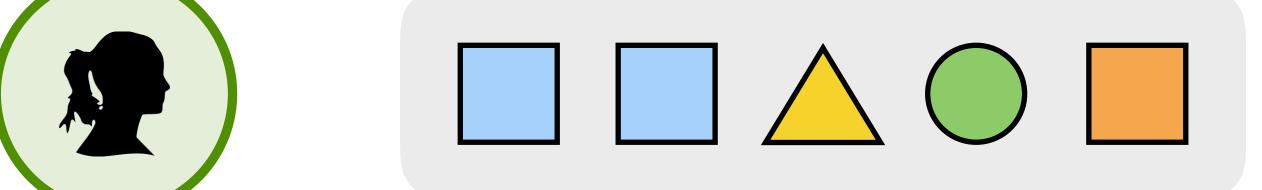
you first following



going in intersection proceed going

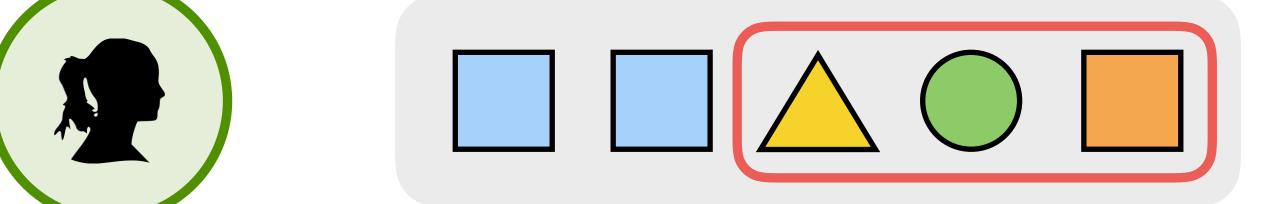




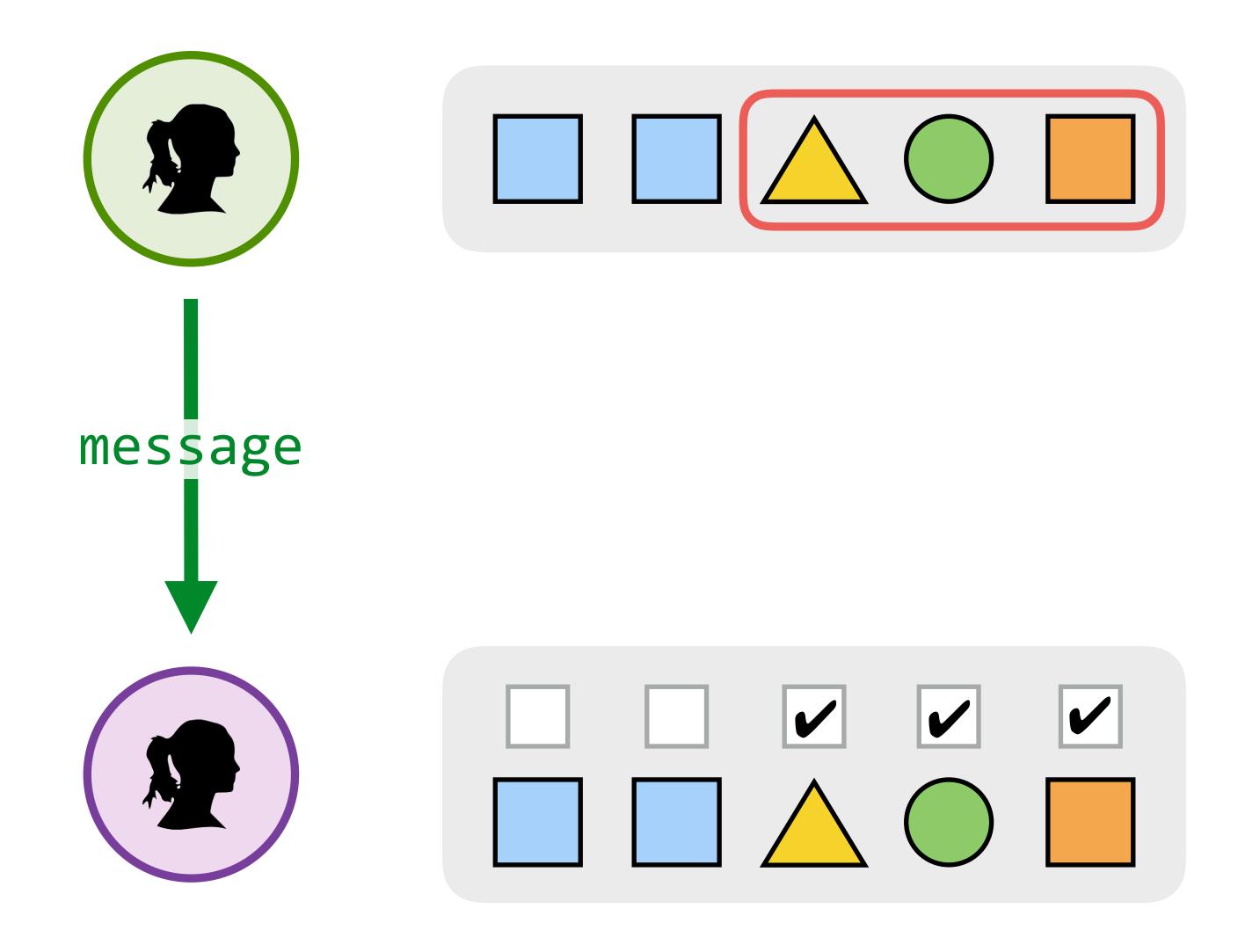




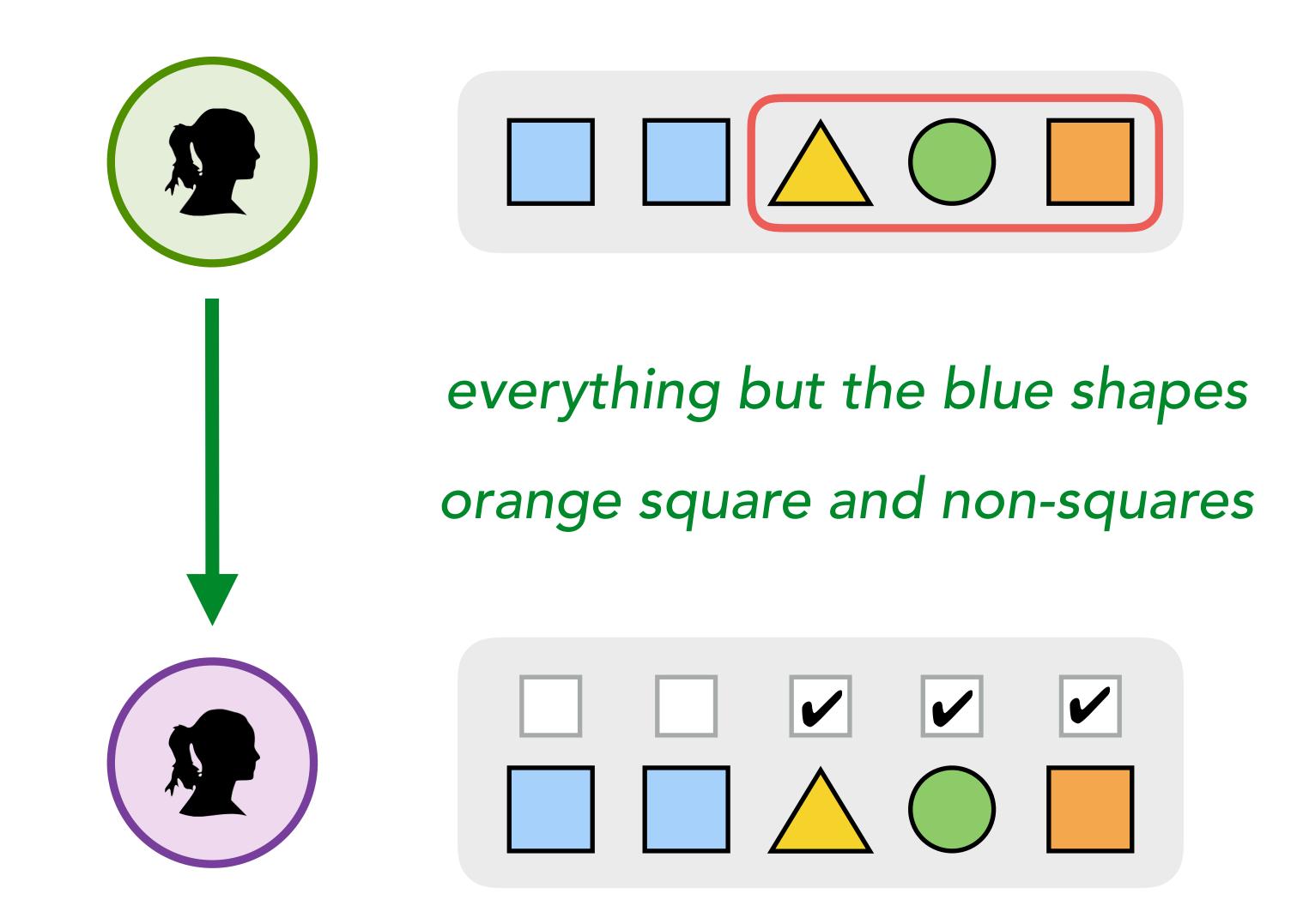




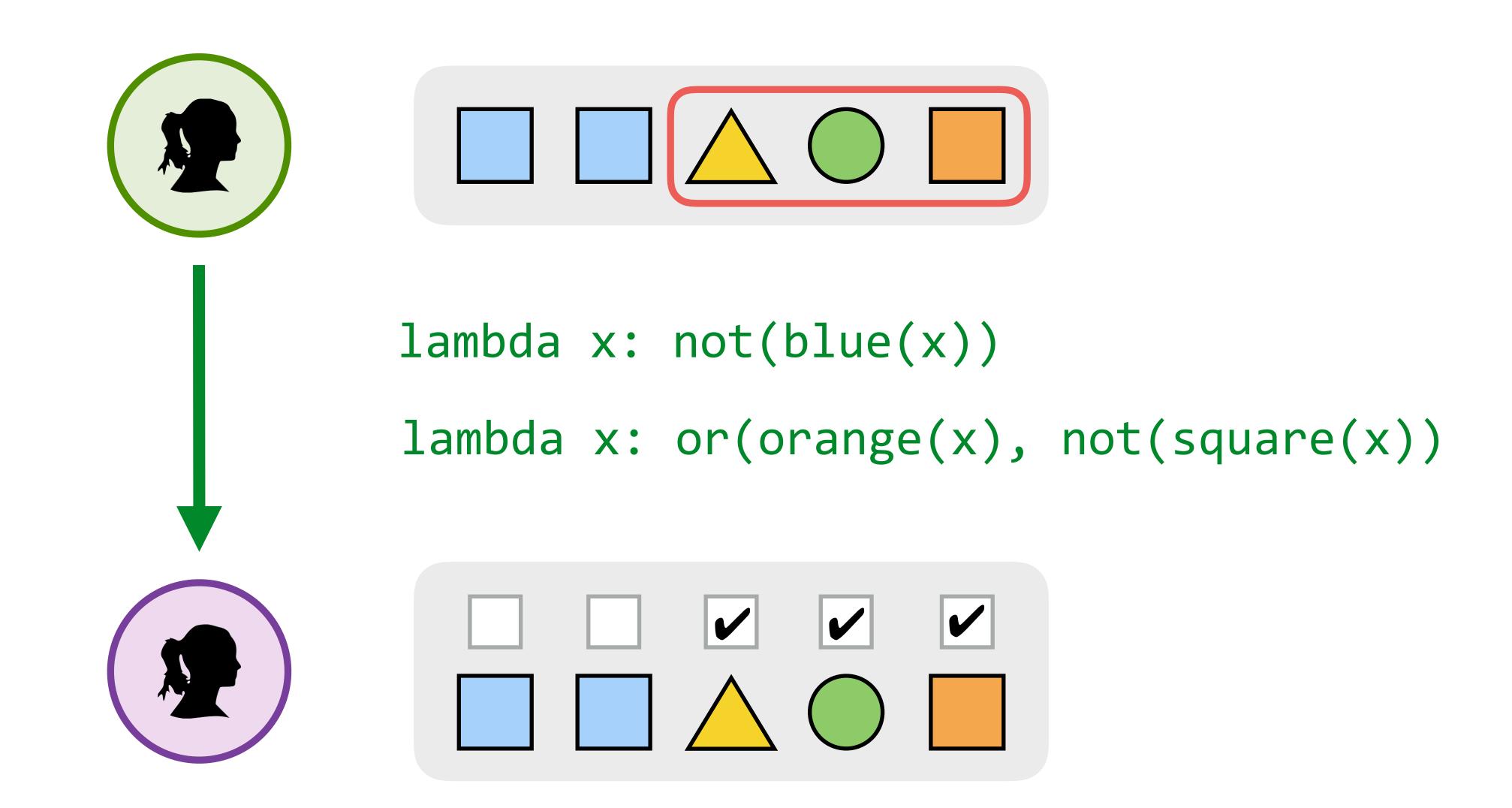






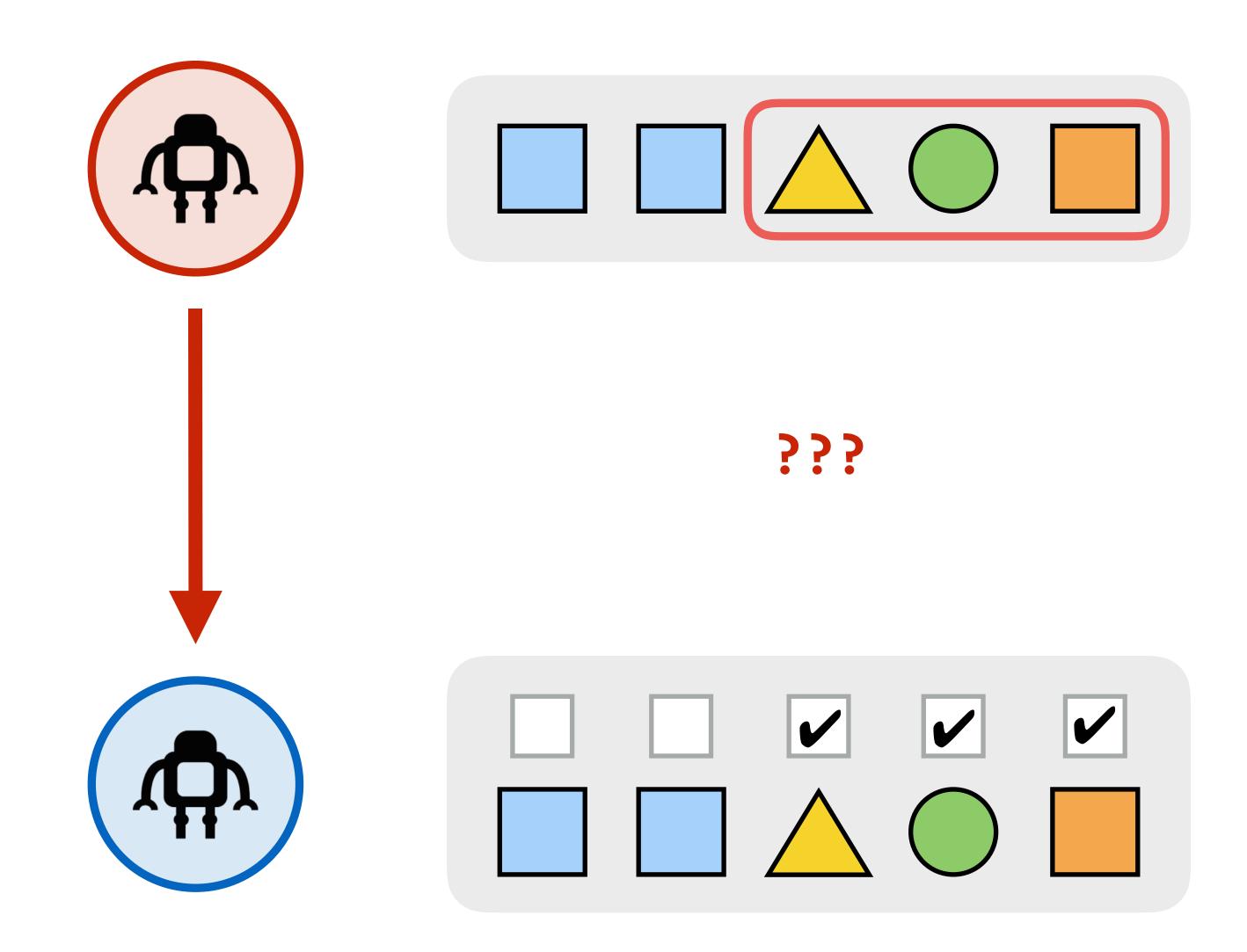




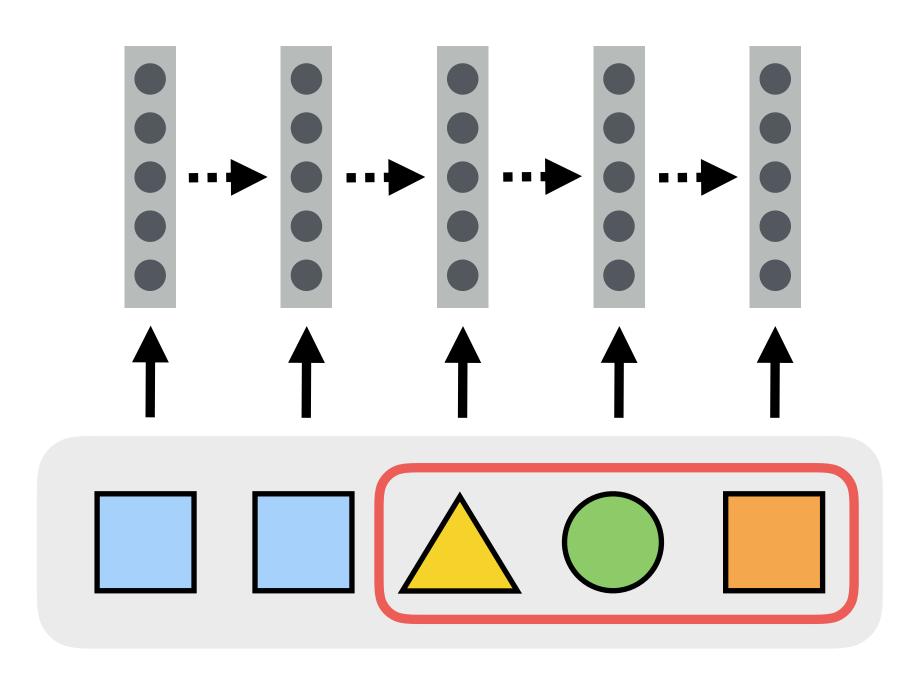


[FitzGerald et al. 2013]

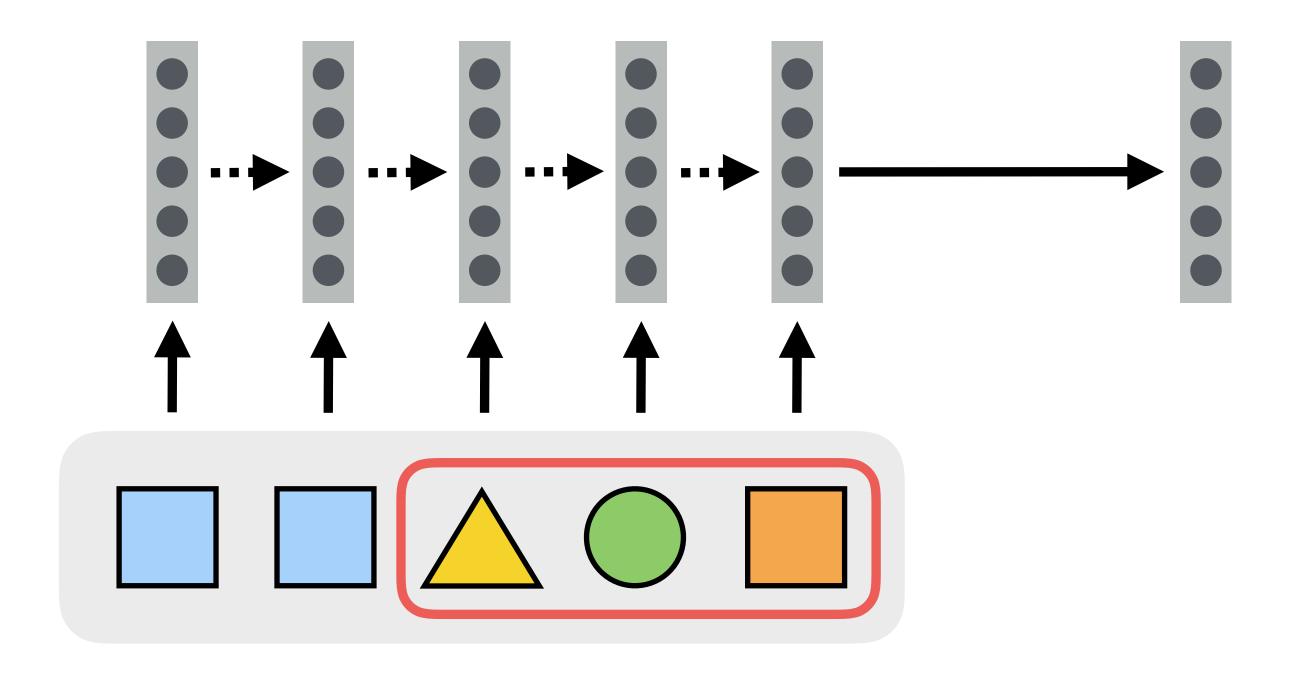


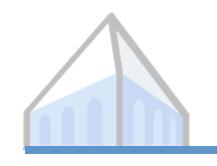


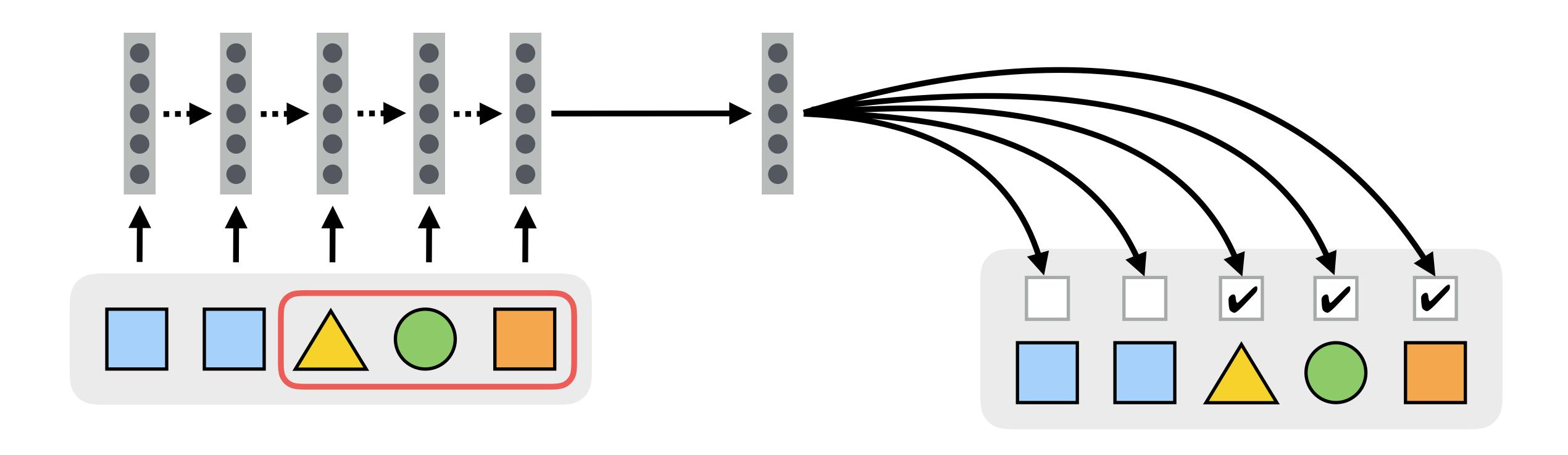




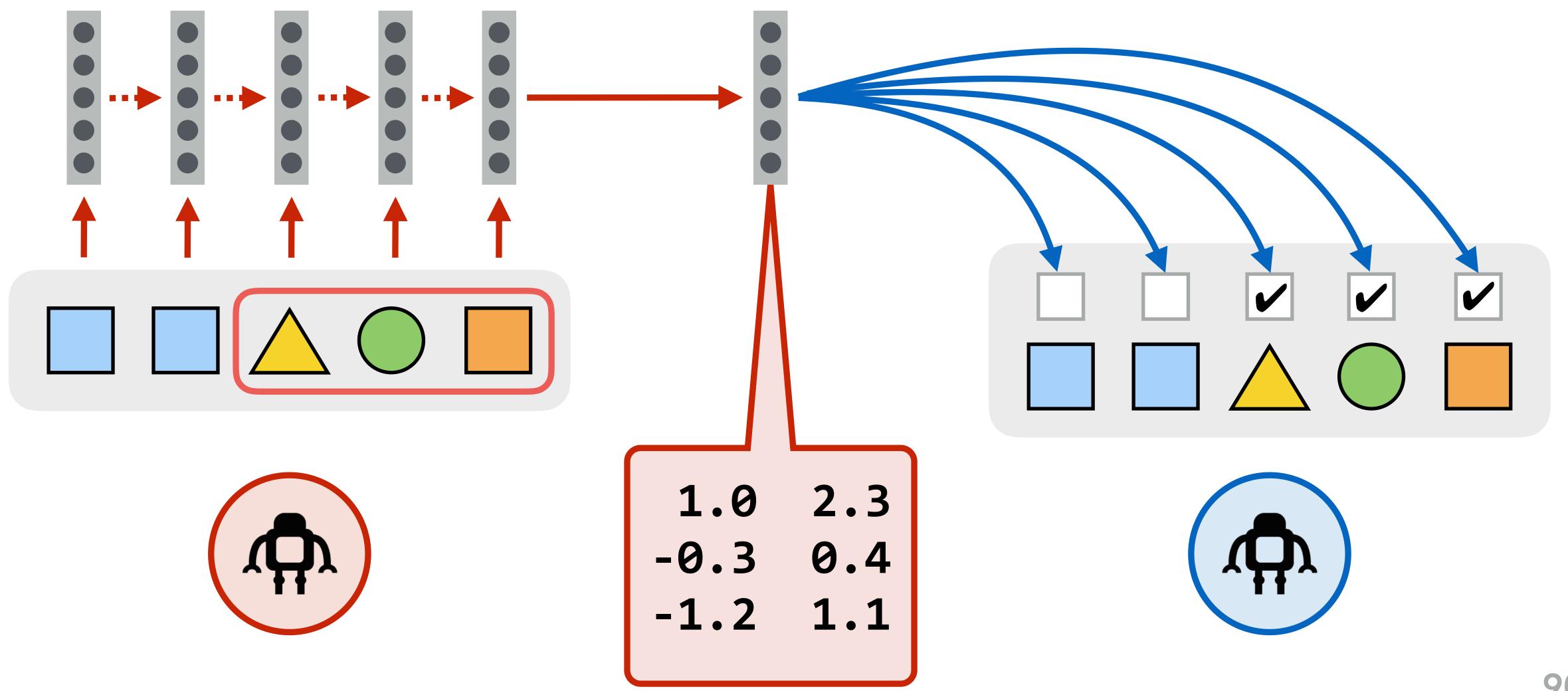


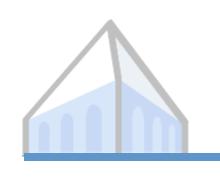


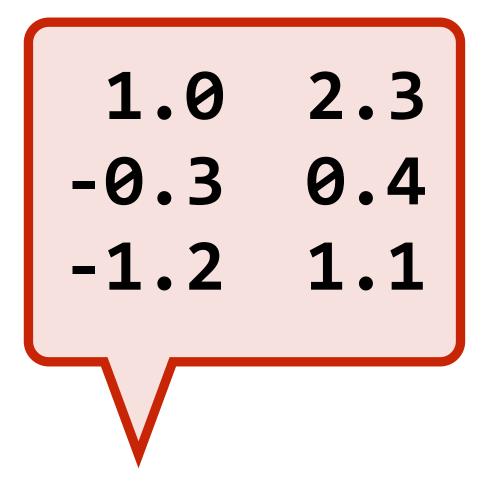




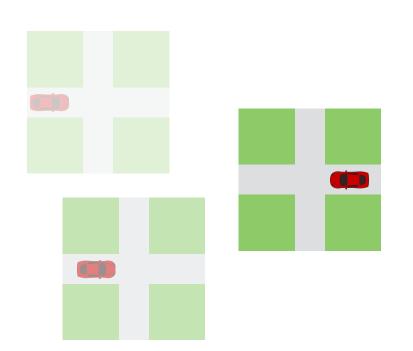


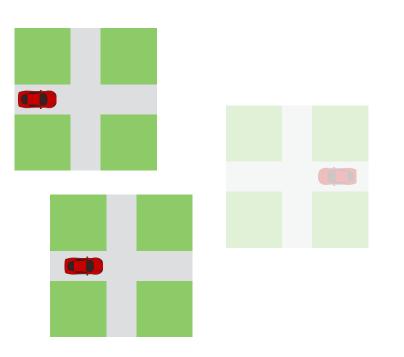


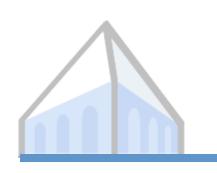


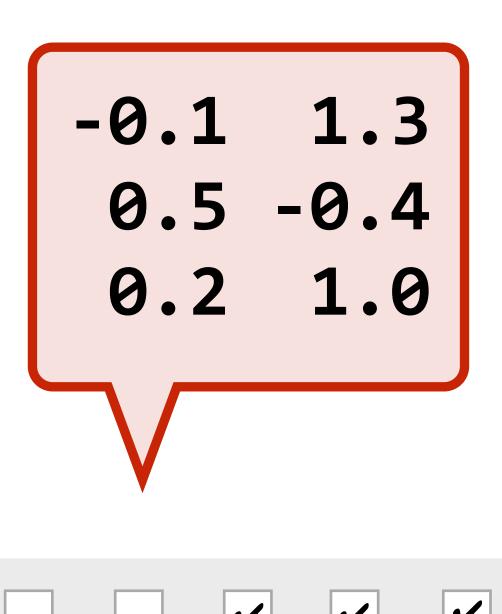


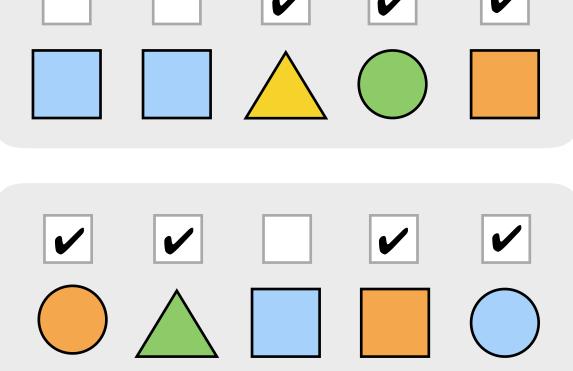




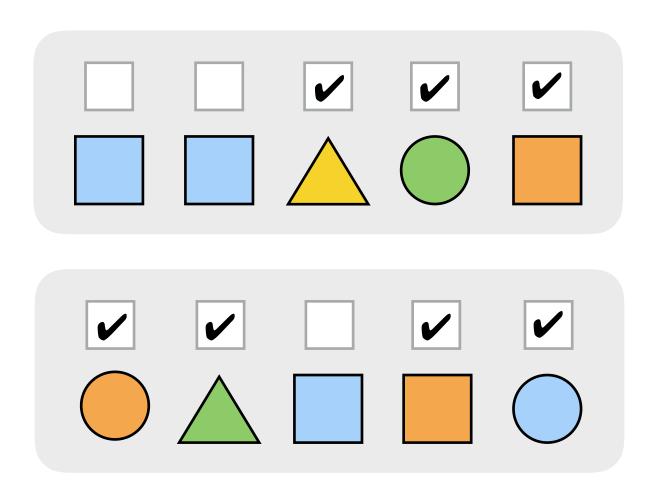


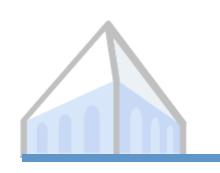


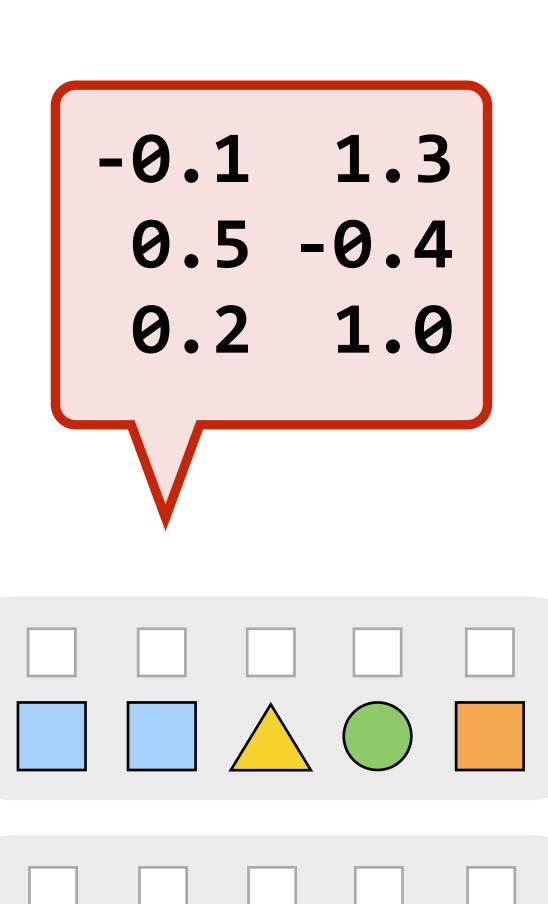




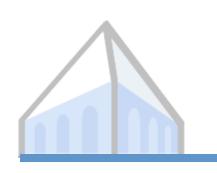
everything but squares

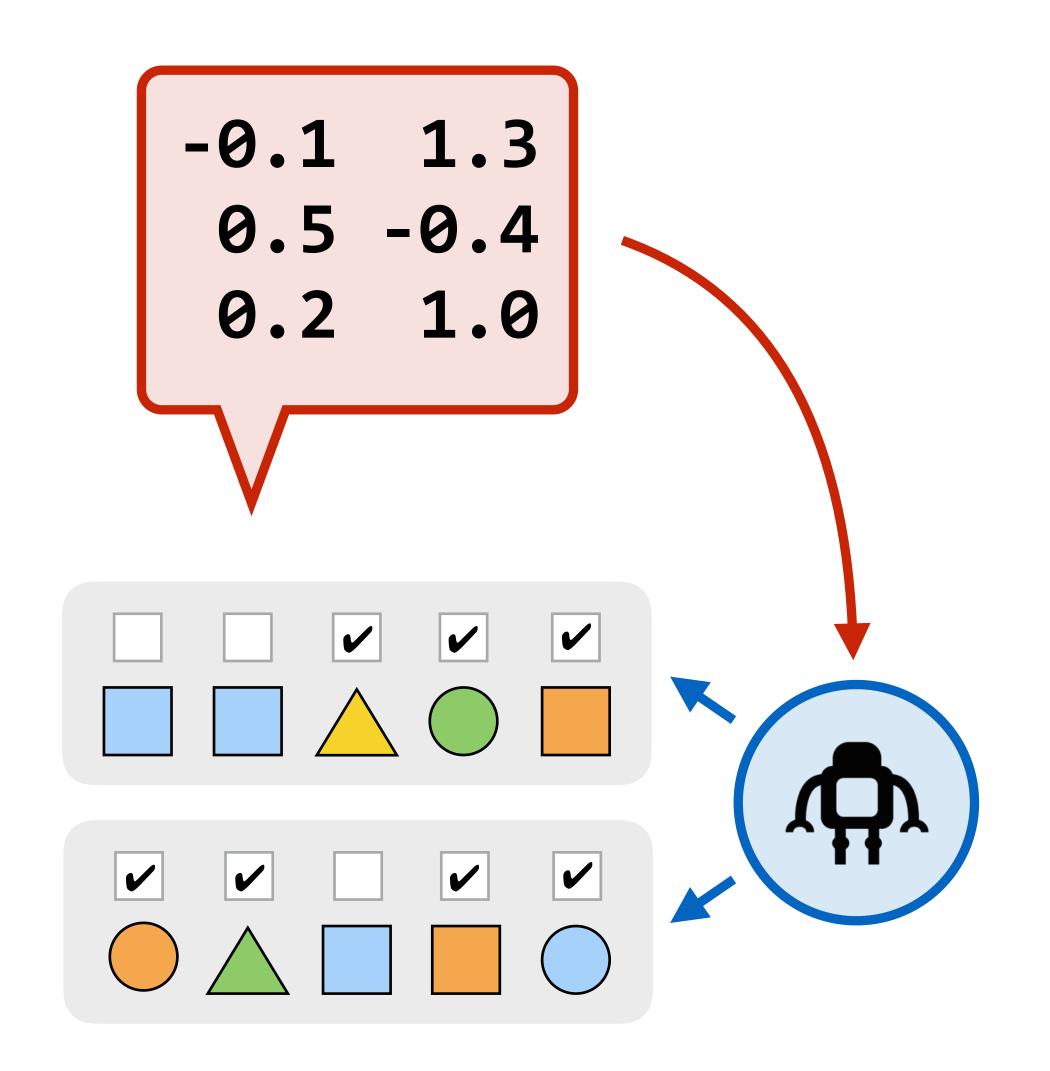


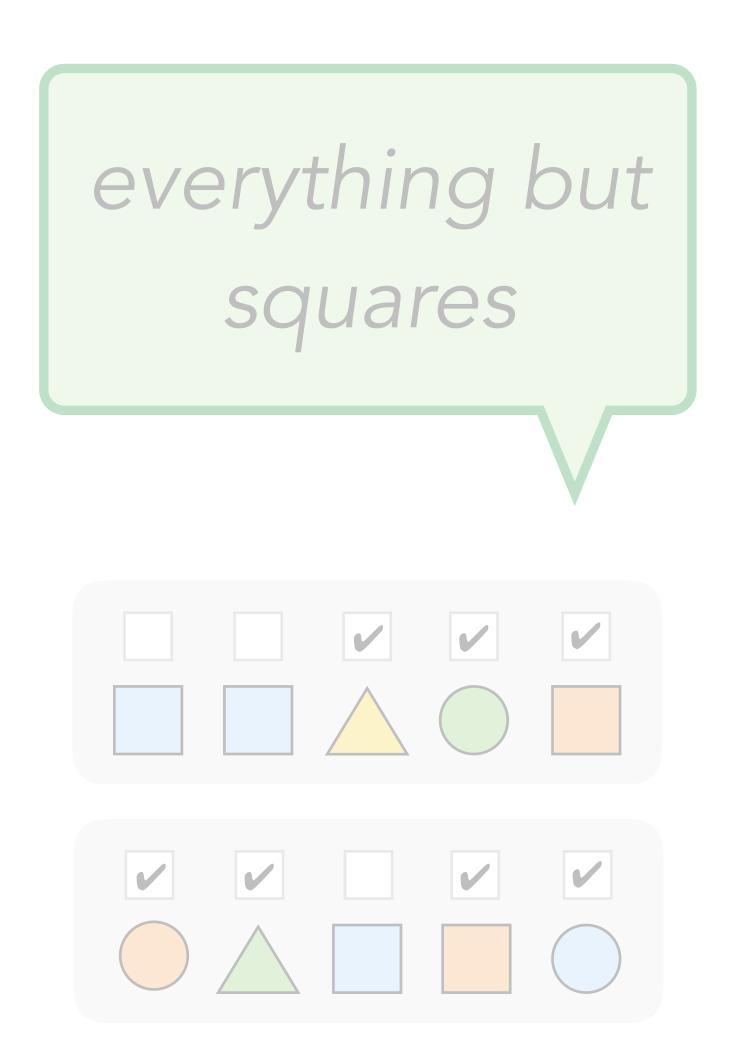


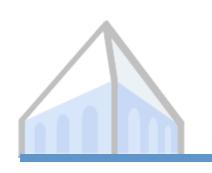


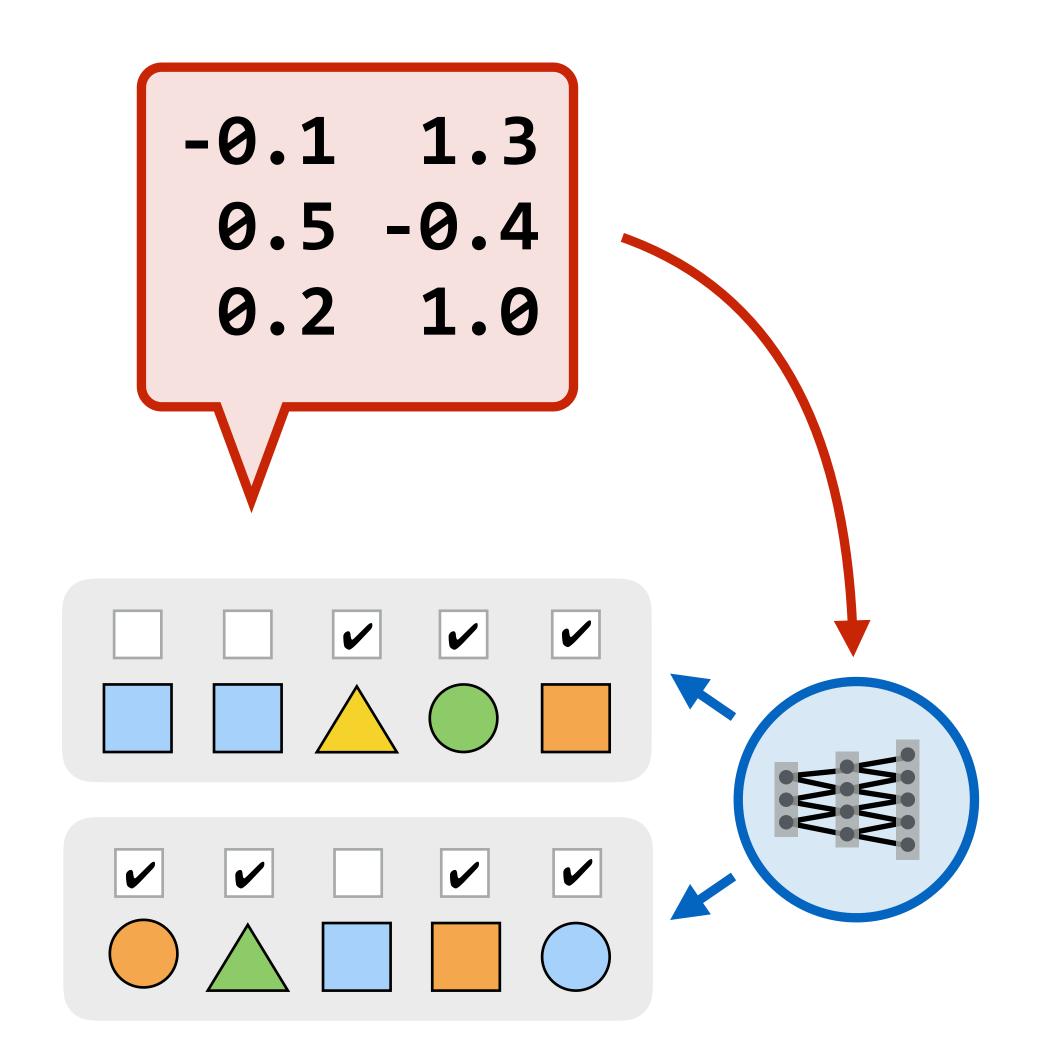




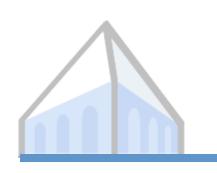


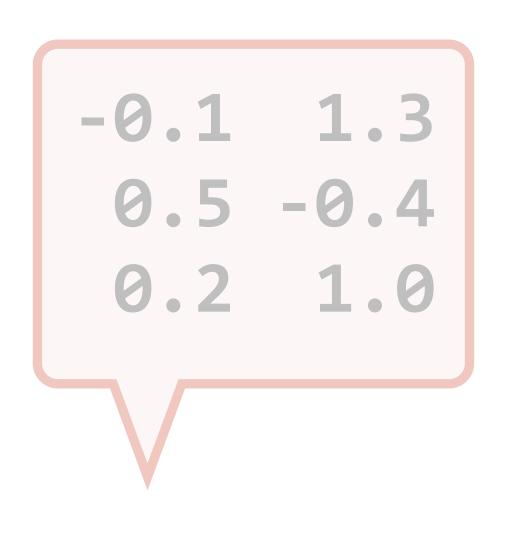




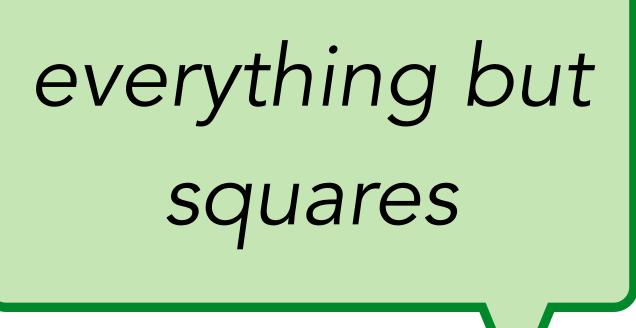


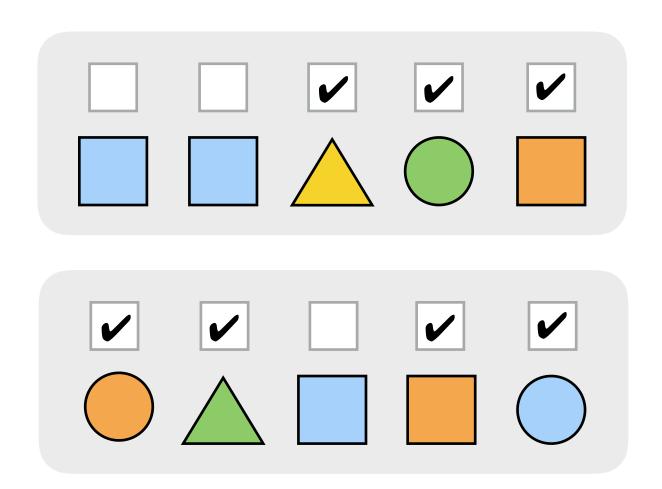




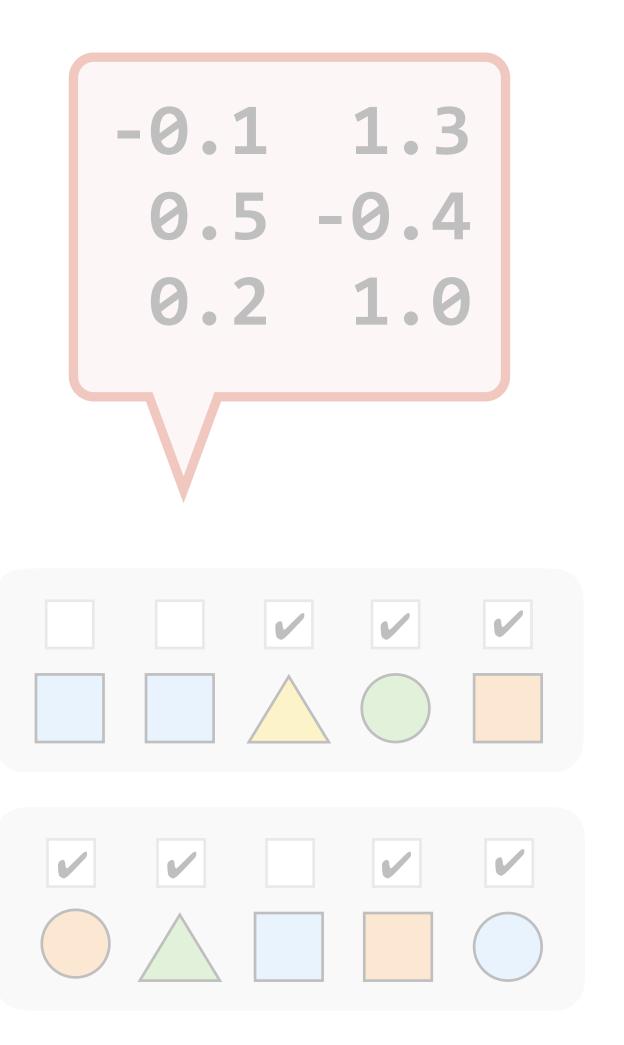


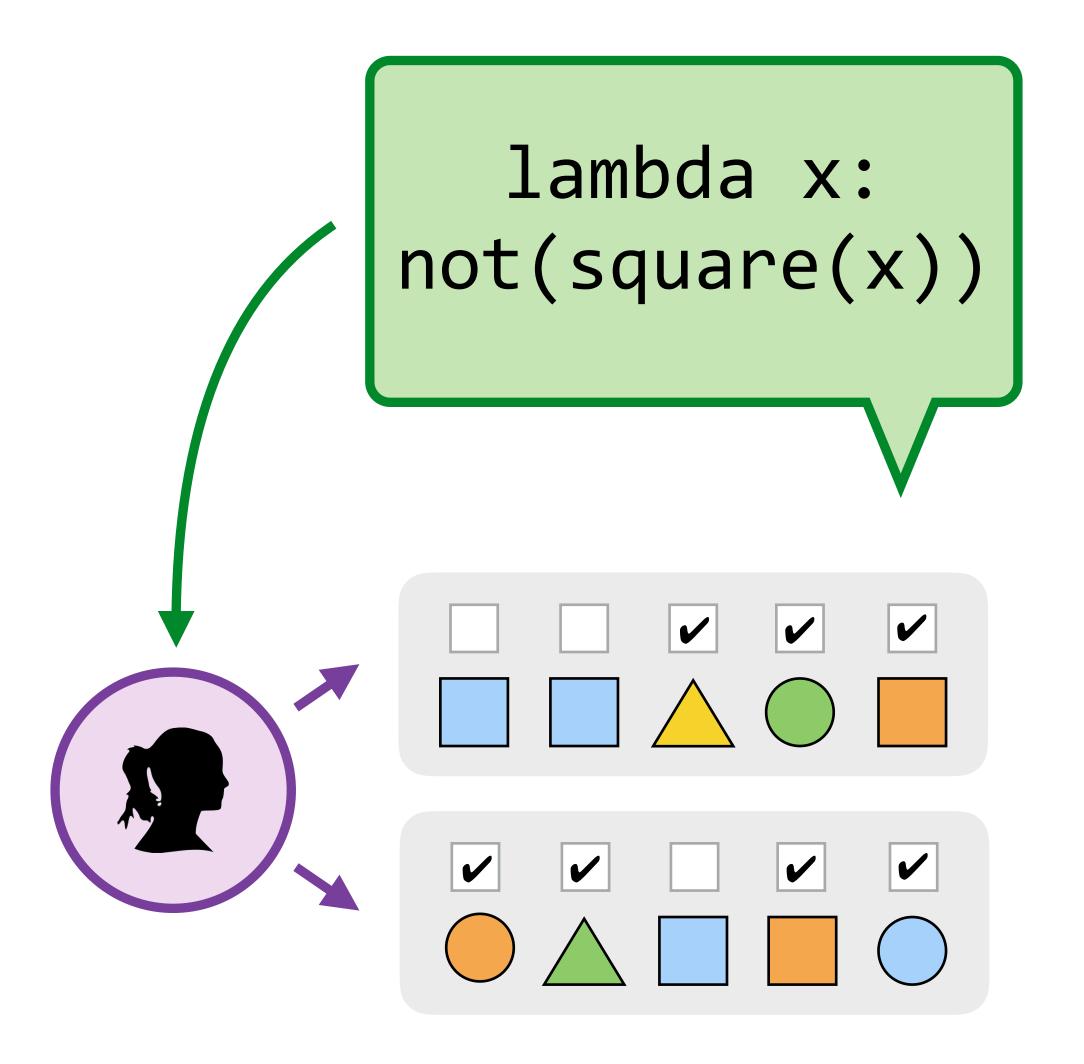




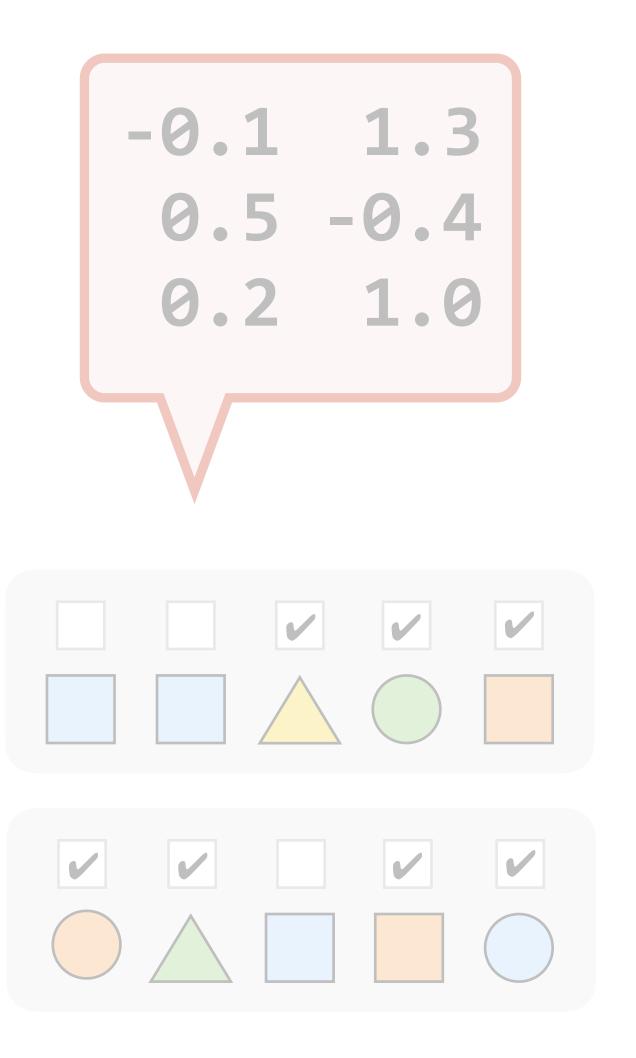


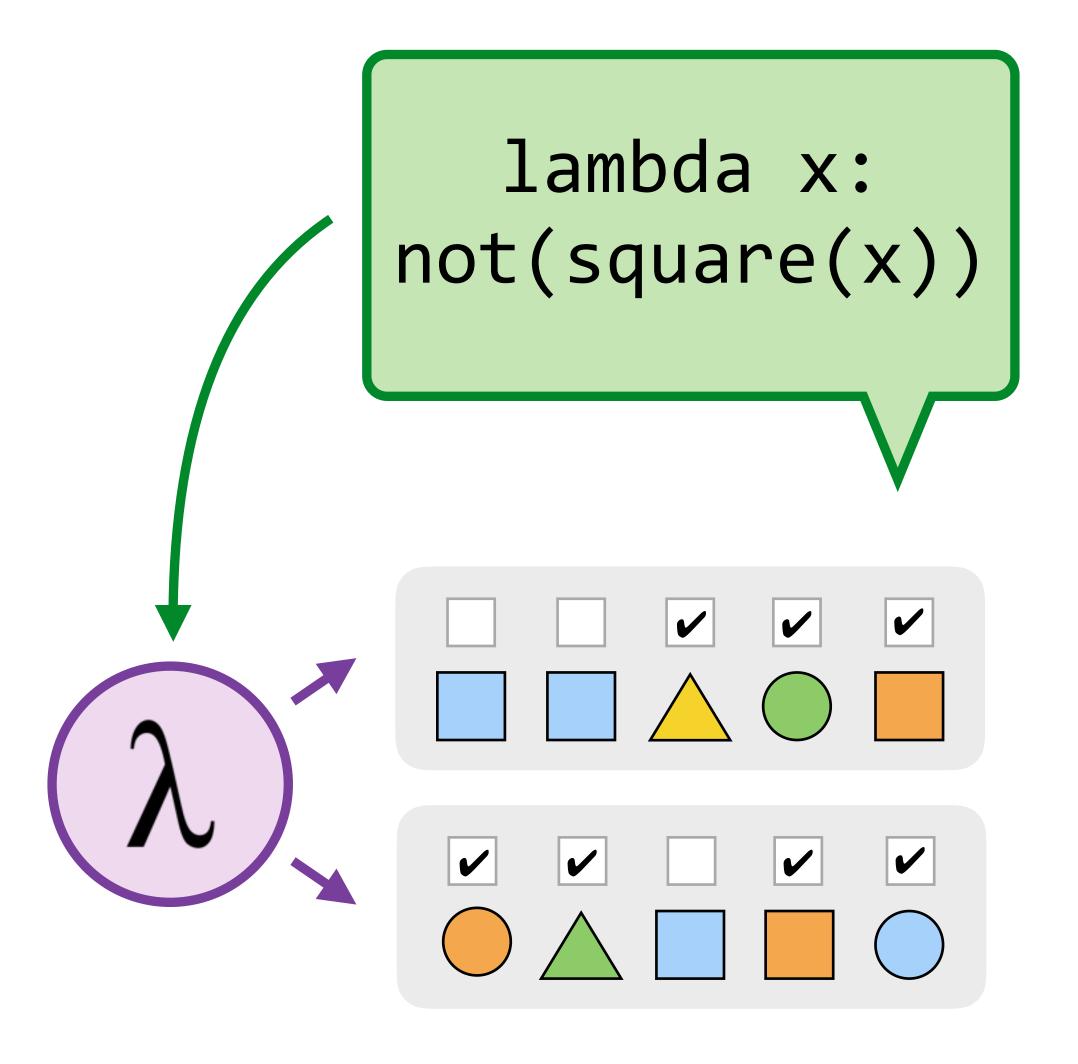














Translation criterion

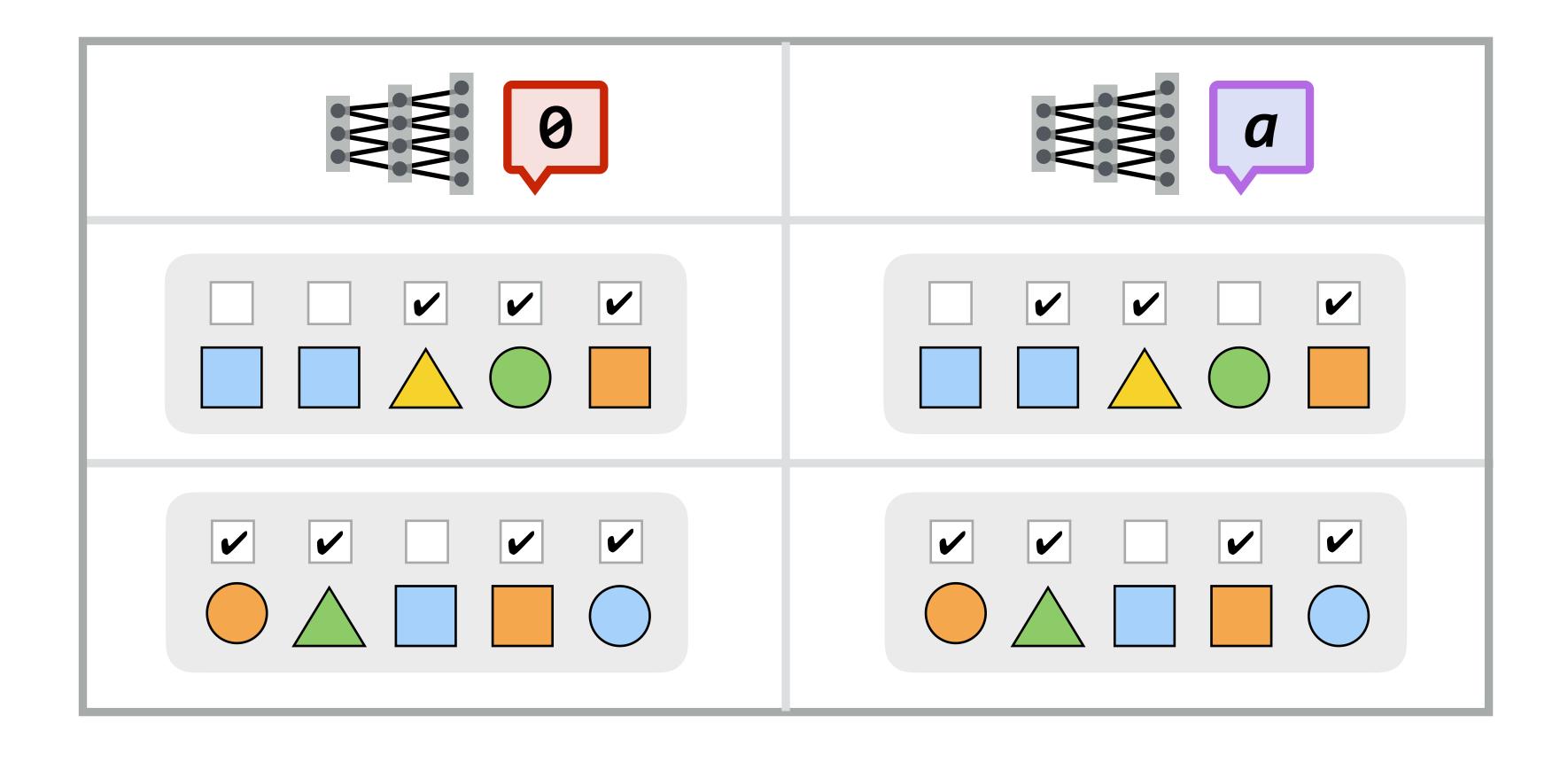
$$q(0, a) = KL(\beta(0) | \beta(a))$$

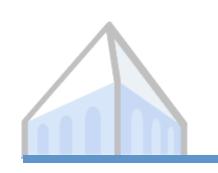
0.10	0.08	
0.05	0.01	
0.13	0.22	



Translation criterion

$$q(\emptyset, \emptyset) = \mathbf{E}[\beta(\emptyset) = \beta(\emptyset)]$$





Experiments

"High-level" communicative behavior

"Low-level" message structure

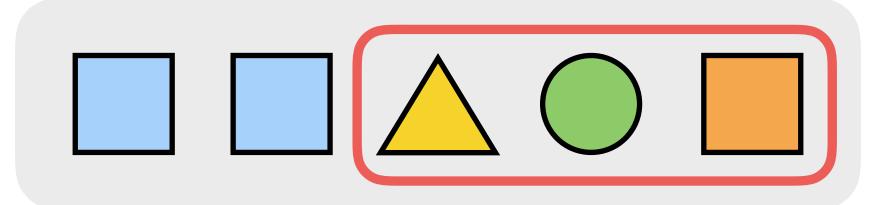


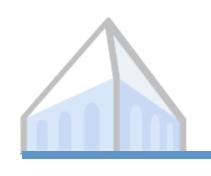
Experiments

"High-level" communicative behavior

"Low-level" message structure



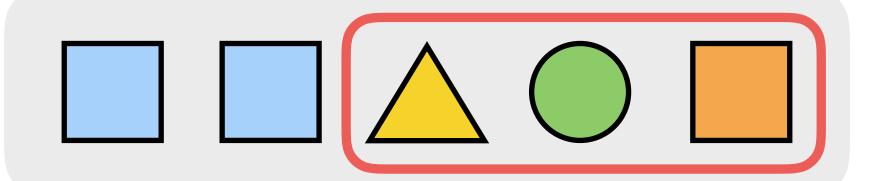




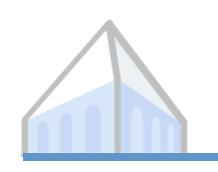
-0.1 1.3

0.5 - 0.4

0.2 1.6



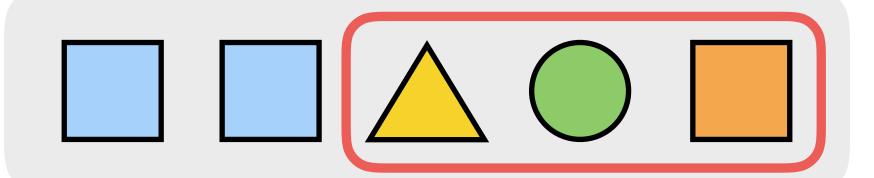
everything but squares



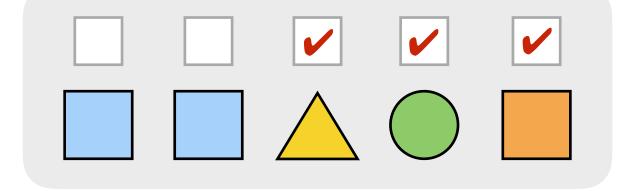
-0.1 1.3

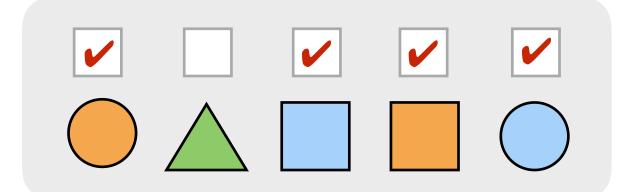
0.5 - 0.4

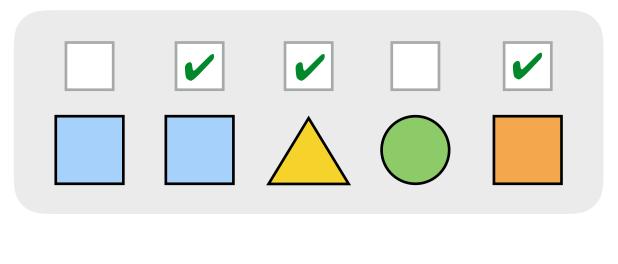
0.2 1.0

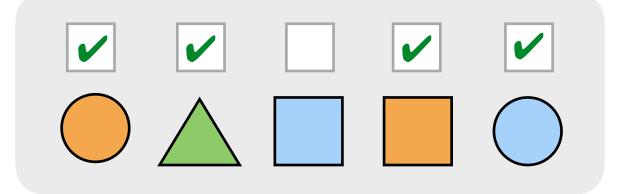


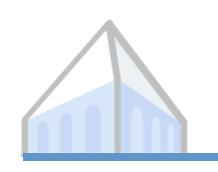
everything but squares



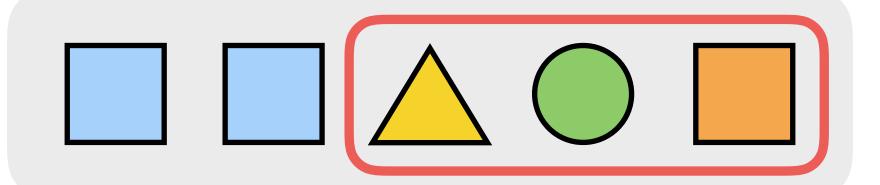




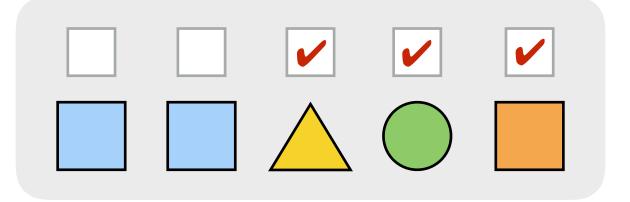




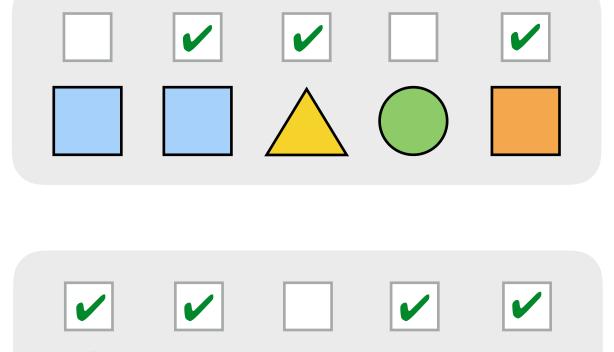
-0.1 1.3 0.5 -0.4

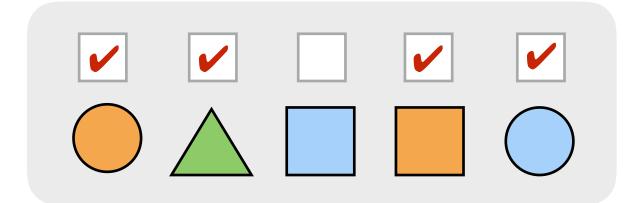


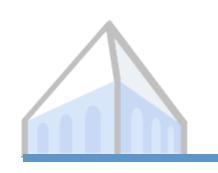
everything but squares





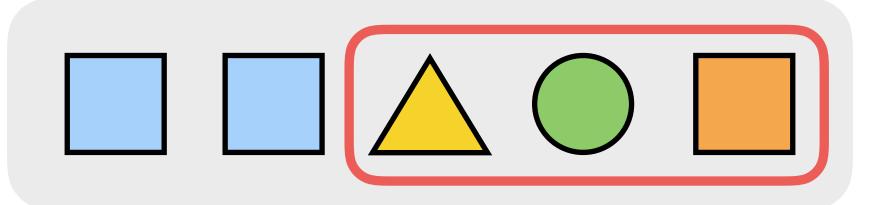


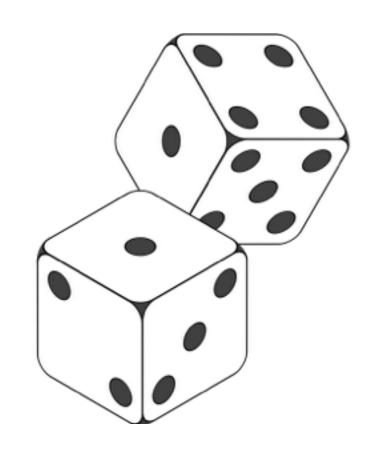


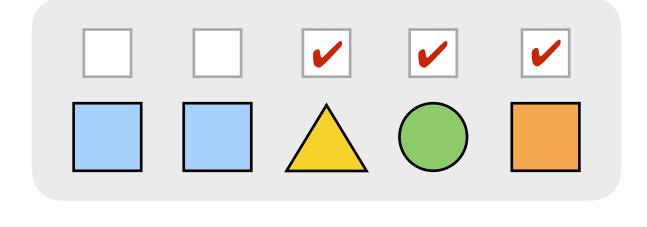


Theories of model behavior: random

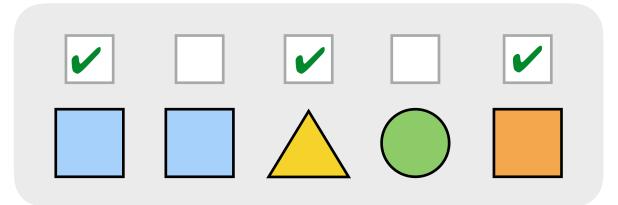


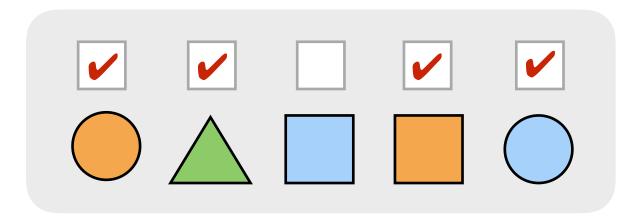


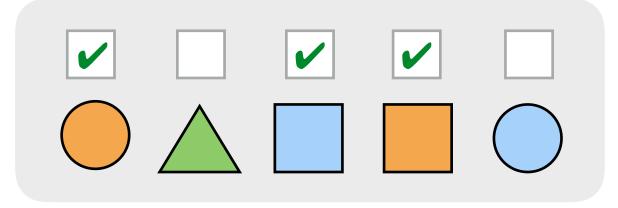








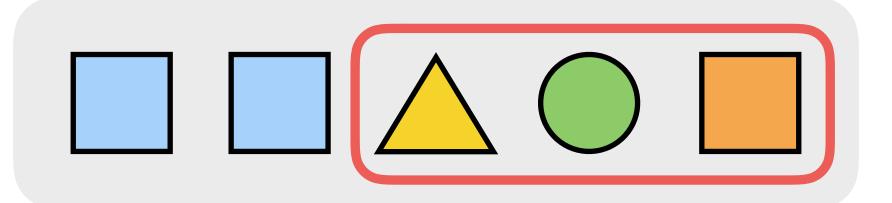


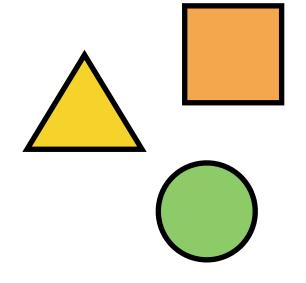


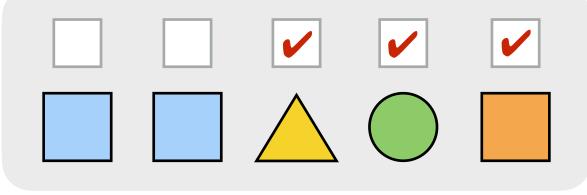


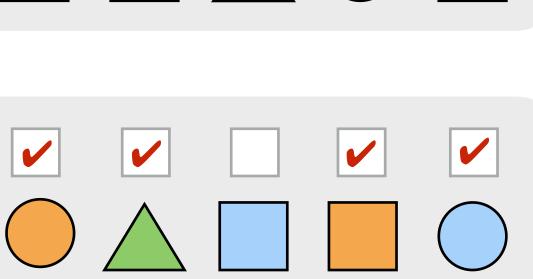
Theories of model behavior: literal

-0.1 1.3 0.5 -0.4 0.2 1.0

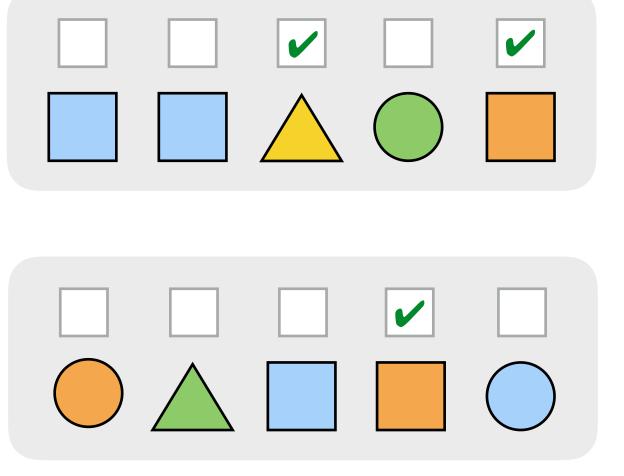


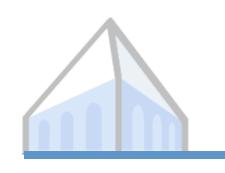




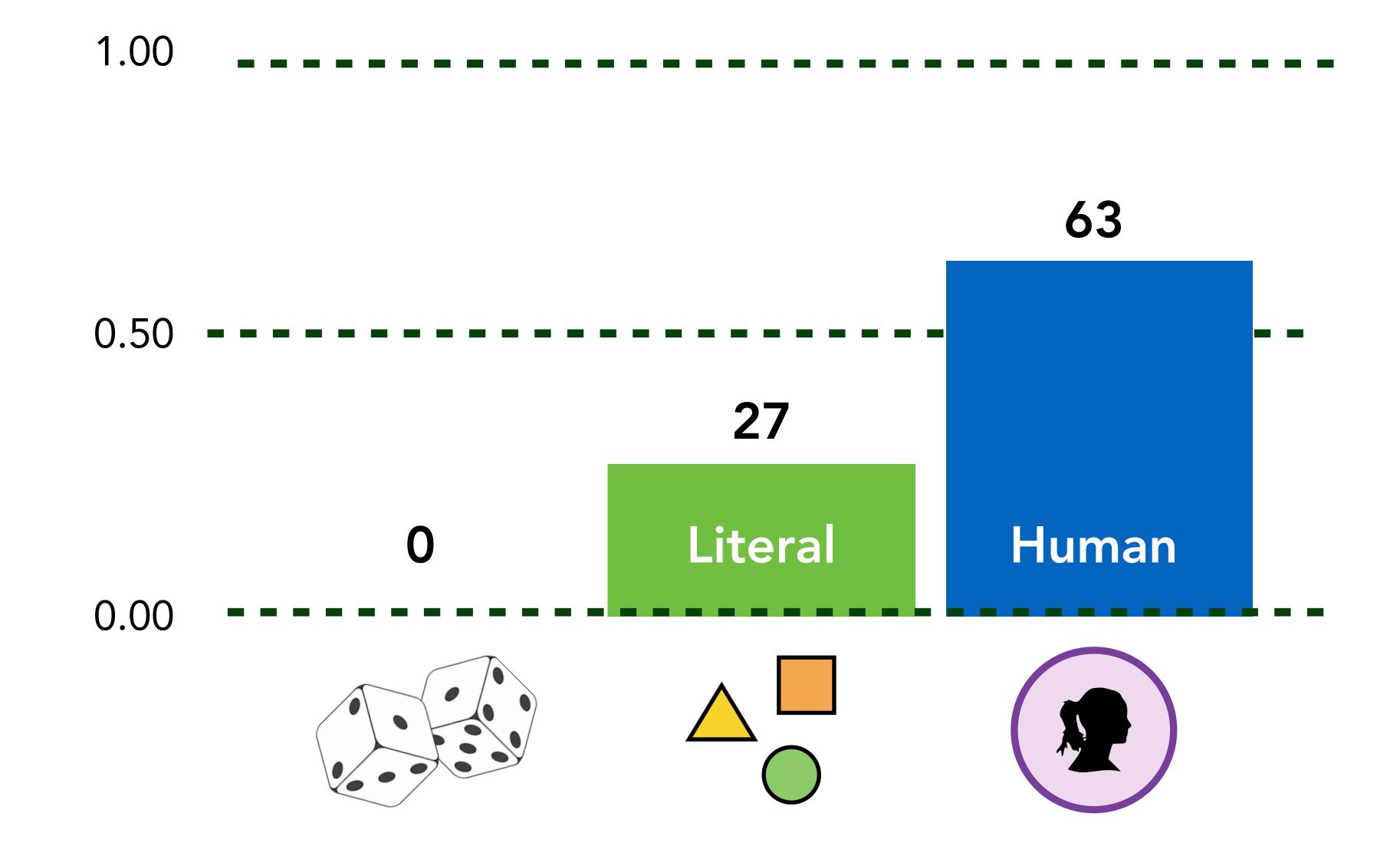






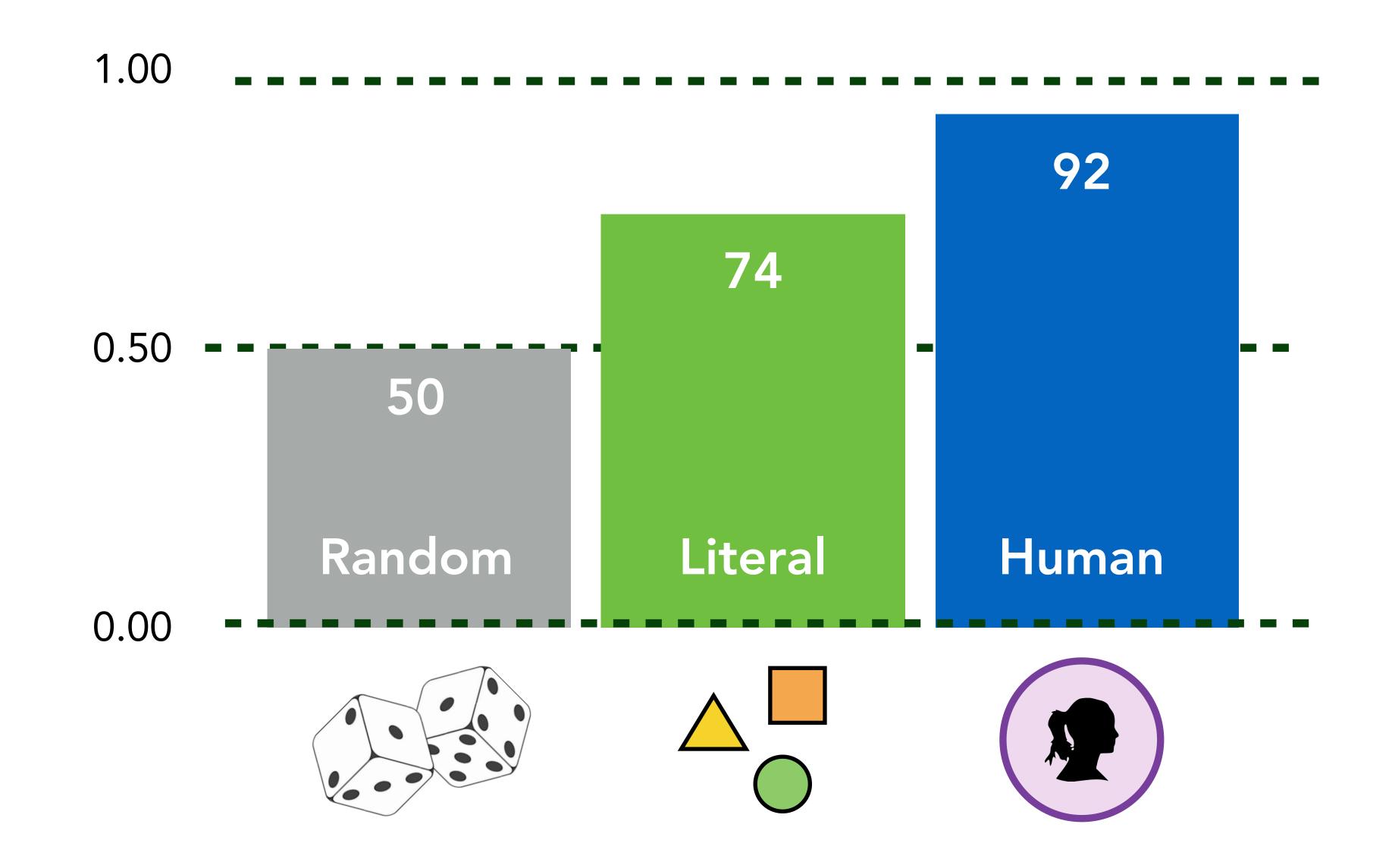


Evaluation: high-level scene agreement





Evaluation: high-level object agreement

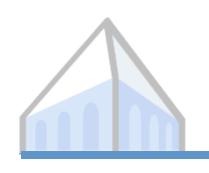




Experiments

"High-level" communicative behavior

"Low-level" message structure



Collecting translation data

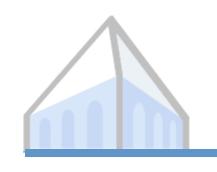
all the red shapes

blue objects

everything but red

green squares

not green squares



Collecting translation data

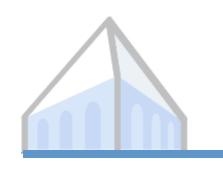
 $\lambda x.red(x)$

 $\lambda x.blu(x)$

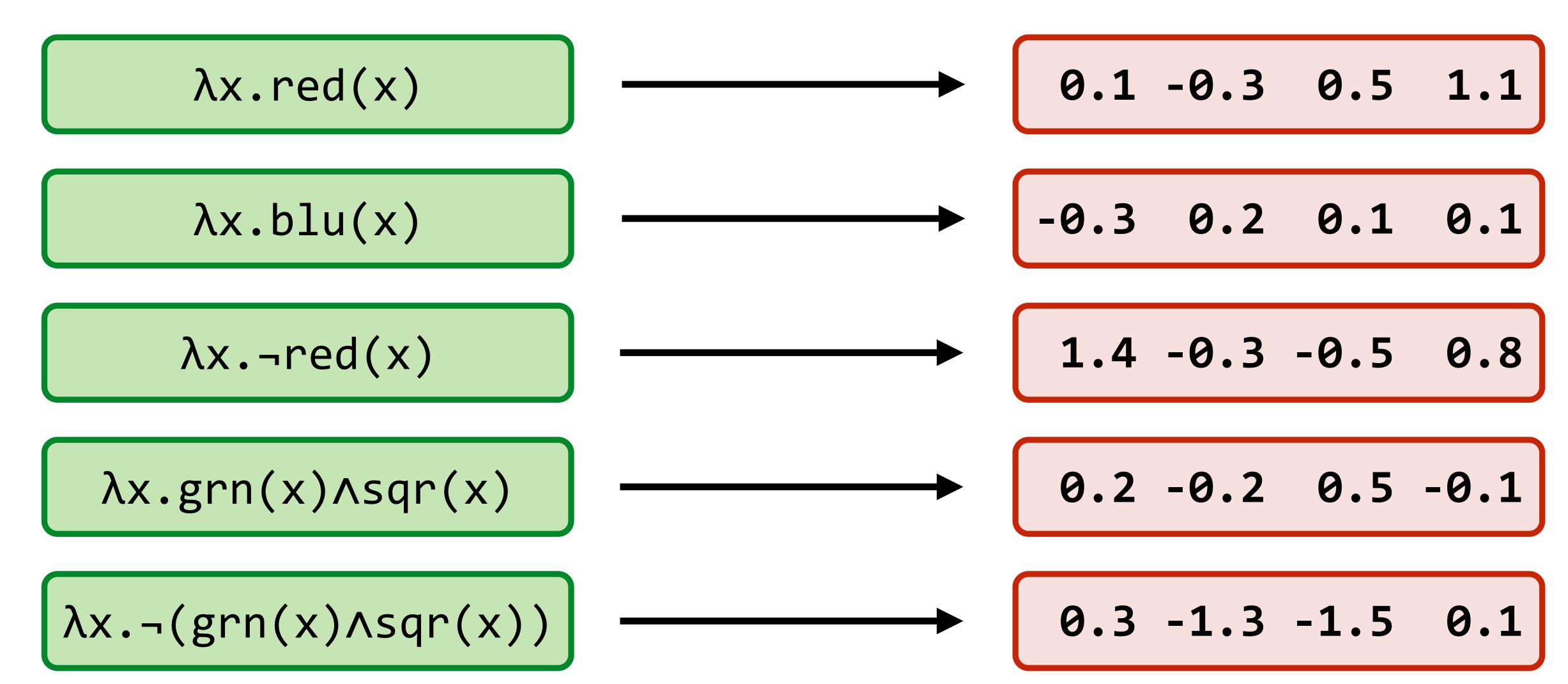
 $\lambda x.\neg red(x)$

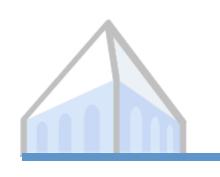
 $\lambda x.grn(x) \wedge sqr(x)$

 $\lambda x.\neg(grn(x)\Lambda sqr(x))$



Collecting translation data





Extracting related pairs

```
\lambda x.red(x)
```

0.1 -0.3 0.5 1.1

 $\lambda x.grn(x) \wedge sqr(x)$

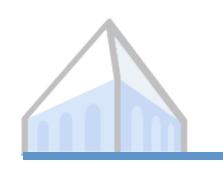
0.2 -0.2 0.5 -0.1

 $\lambda x.\neg red(x)$

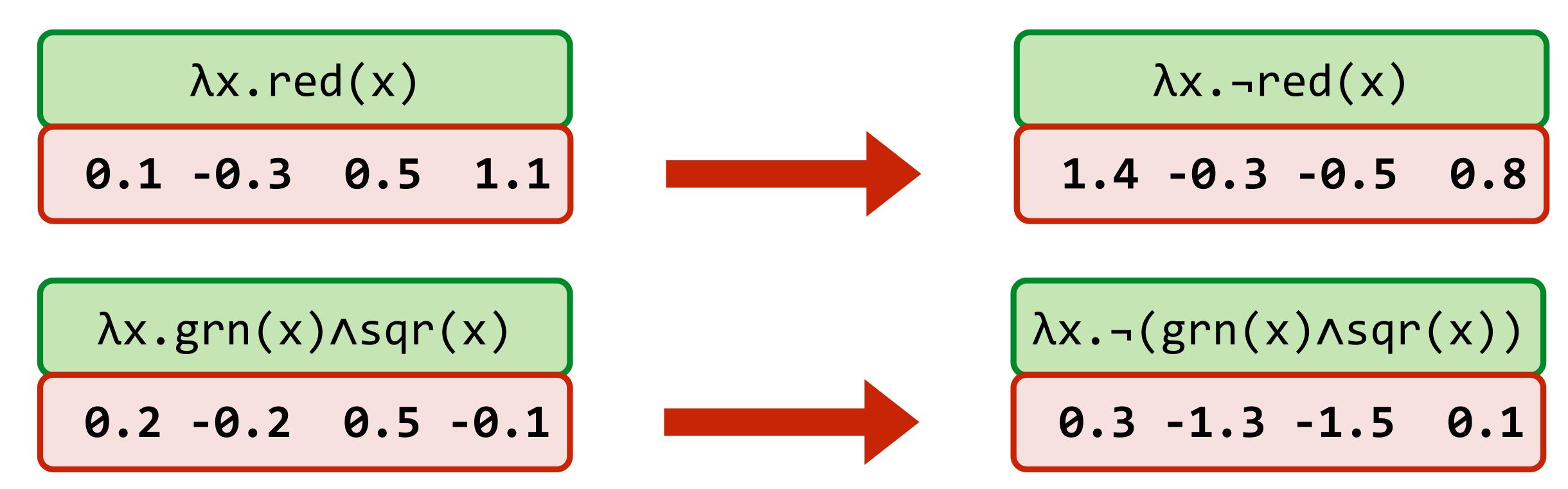
1.4 -0.3 -0.5 0.8

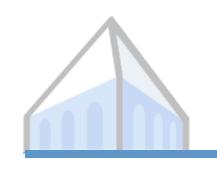
 $\lambda x.\neg(grn(x)\wedge sqr(x))$

0.3 -1.3 -1.5 0.1

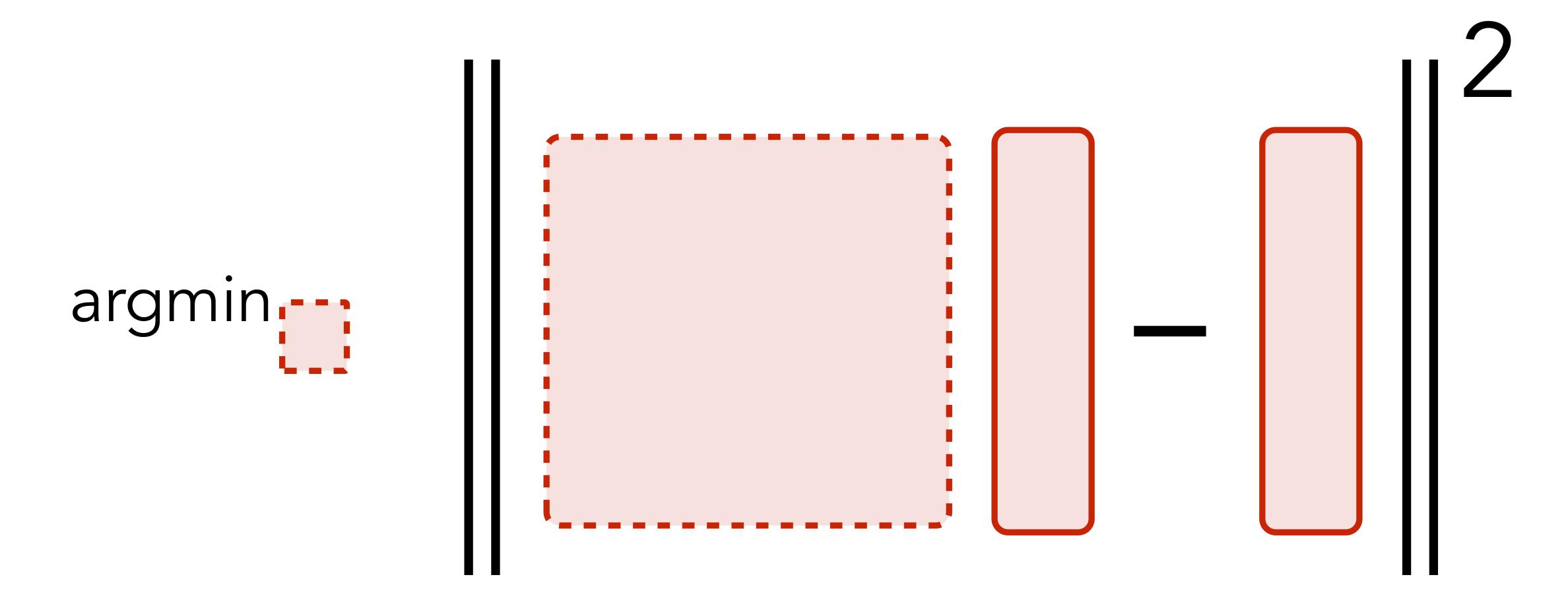


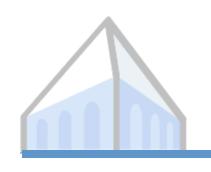
Extracting related pairs





Learning compositional operators





Evaluating learned operators

```
\lambda x.red(x)
```

$$\lambda x.grn(x) \wedge sqr(x)$$

$$\lambda x.f(x)$$

$$\lambda x.\neg red(x)$$

$$\lambda x.\neg(grn(x)\Lambda sqr(x))$$



Evaluating learned operators

 $\lambda x.red(x)$

0.1 -0.3 0.5 1.1

 $\lambda x.\neg red(x)$

1.4 -0.3 -0.5 0.8

 $\lambda x.grn(x) \wedge sqr(x)$

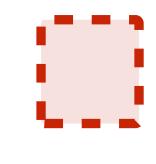
0.2 -0.2 0.5 -0.1

 $\lambda x.\neg(grn(x) \land sqr(x))$

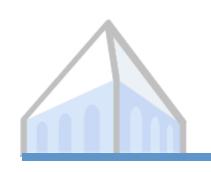
0.3 -1.3 -1.5 0.1

 $\lambda x.f(x)$

0.2 -0.2 0.5 -0.1



-0.2 0.4 -0.3 0.0



Evaluating learned operators

 $\lambda x.red(x)$

0.1 -0.3 0.5 1.1

 $\lambda x.\neg red(x)$

1.4 -0.3 -0.5 0.8

 $\lambda x.grn(x) \wedge sqr(x)$

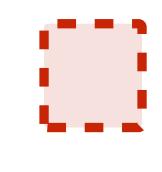
0.2 -0.2 0.5 -0.1

 $\lambda x.\neg(grn(x)\wedge sqr(x))$

0.3 -1.3 -1.5 0.1

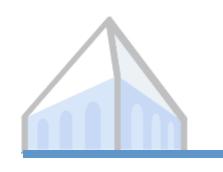
 $\lambda x.f(x)$

0.2 -0.2 0.5 -0.1

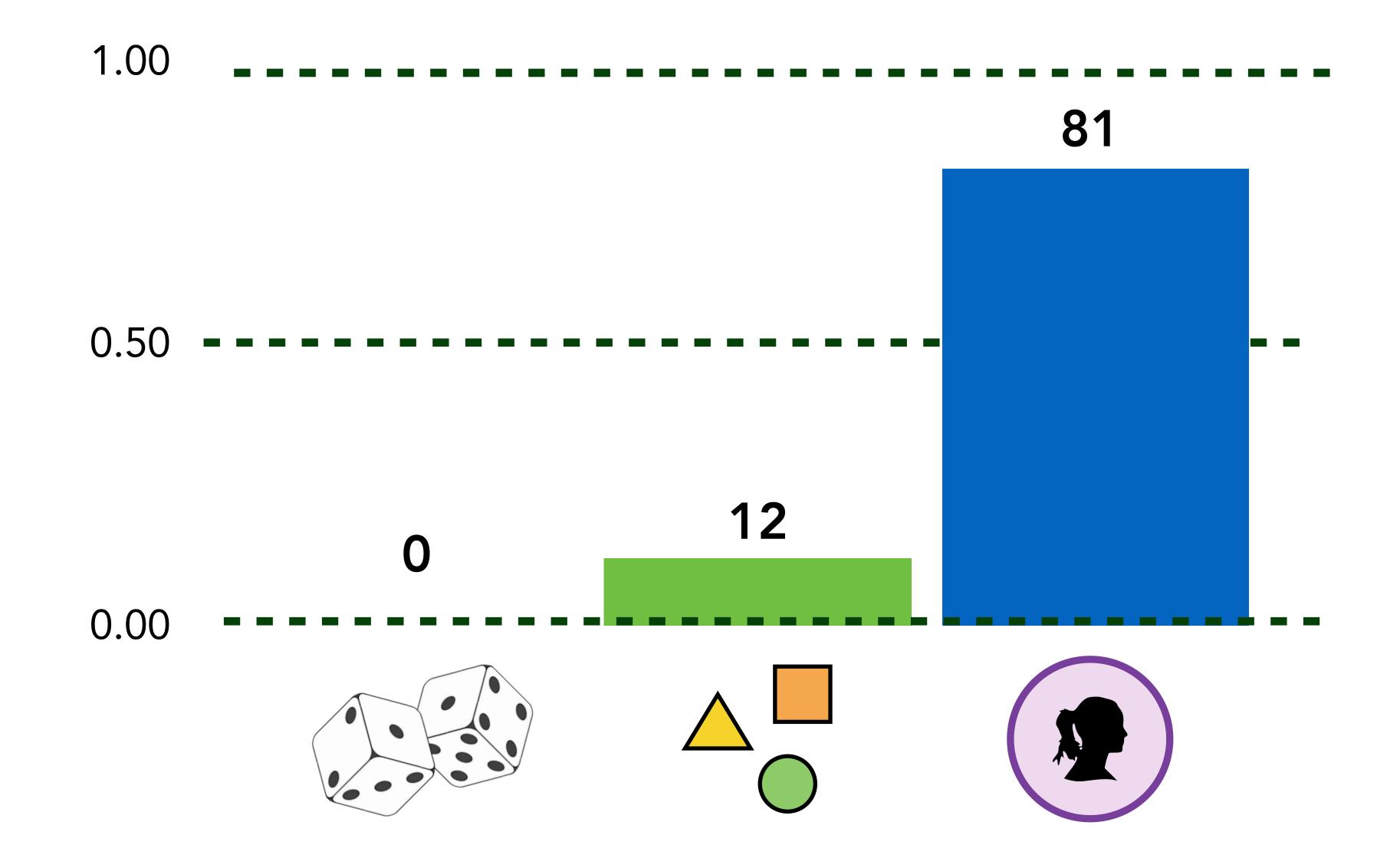


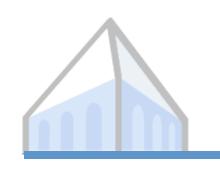
555

-0.2 0.4 -0.3 0.0



Evaluation: scene agreement for negation





Visualizing negation

Input

Predicted

True

all the toys that are not red

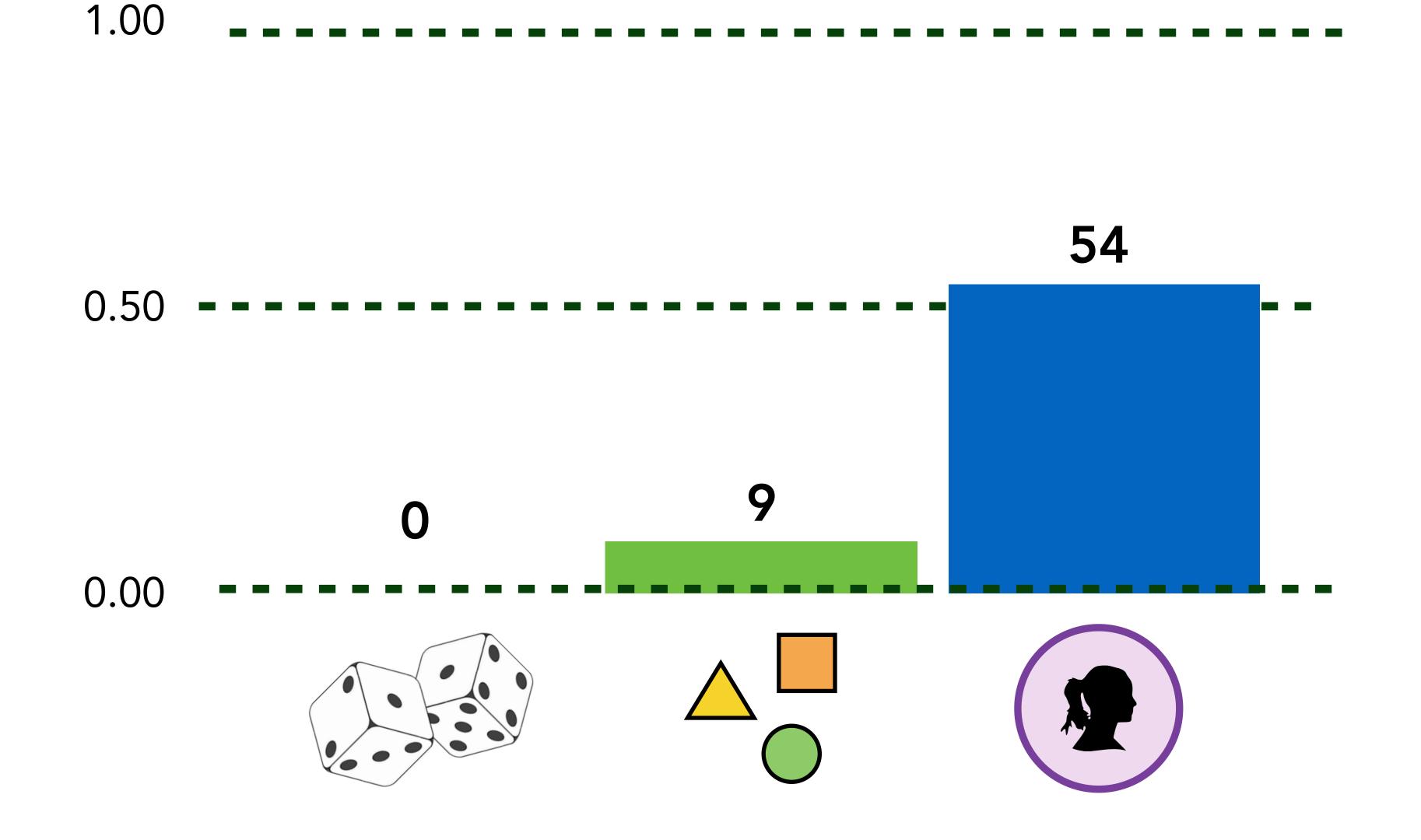
all items that are not blue or green

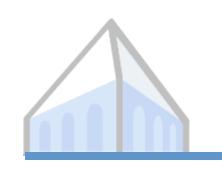
all the toys that of the toys the toy the toy

every thing that is red



Evaluation: scene agreement for disjunction



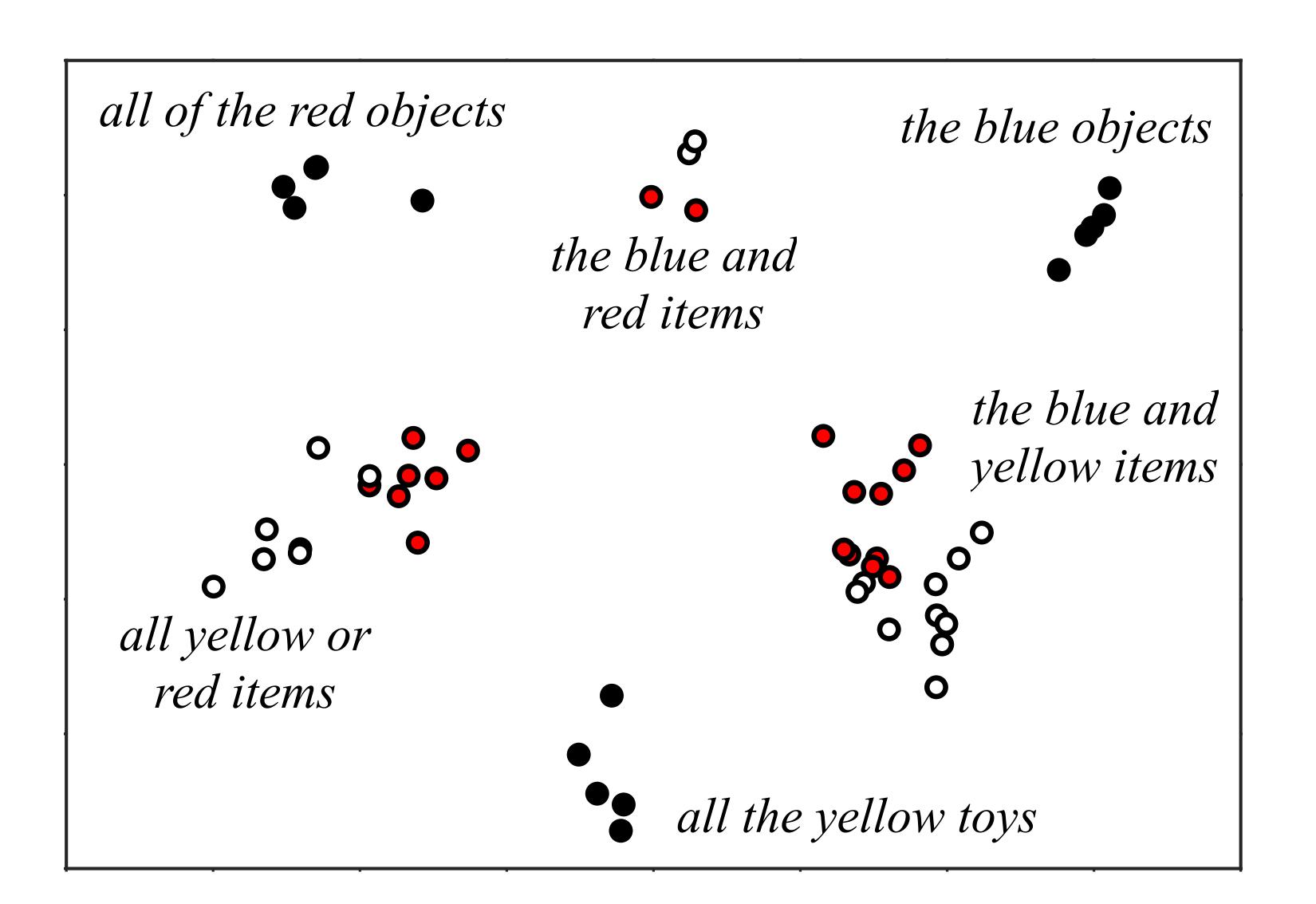


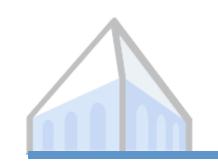
Visualizing disjunction

Input

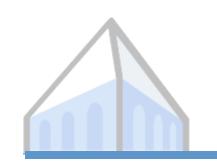
Predicted

True

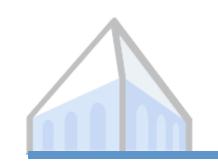




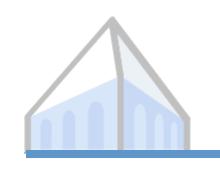
- We can translate between neuralese and natural lang.
 by grounding in distributions over world states
- Under the right conditions, neuralese exhibits interpretable pragmatics & compositional structure
- Not just communication games—language might be a good general-purpose tool for interpreting deep reprs.

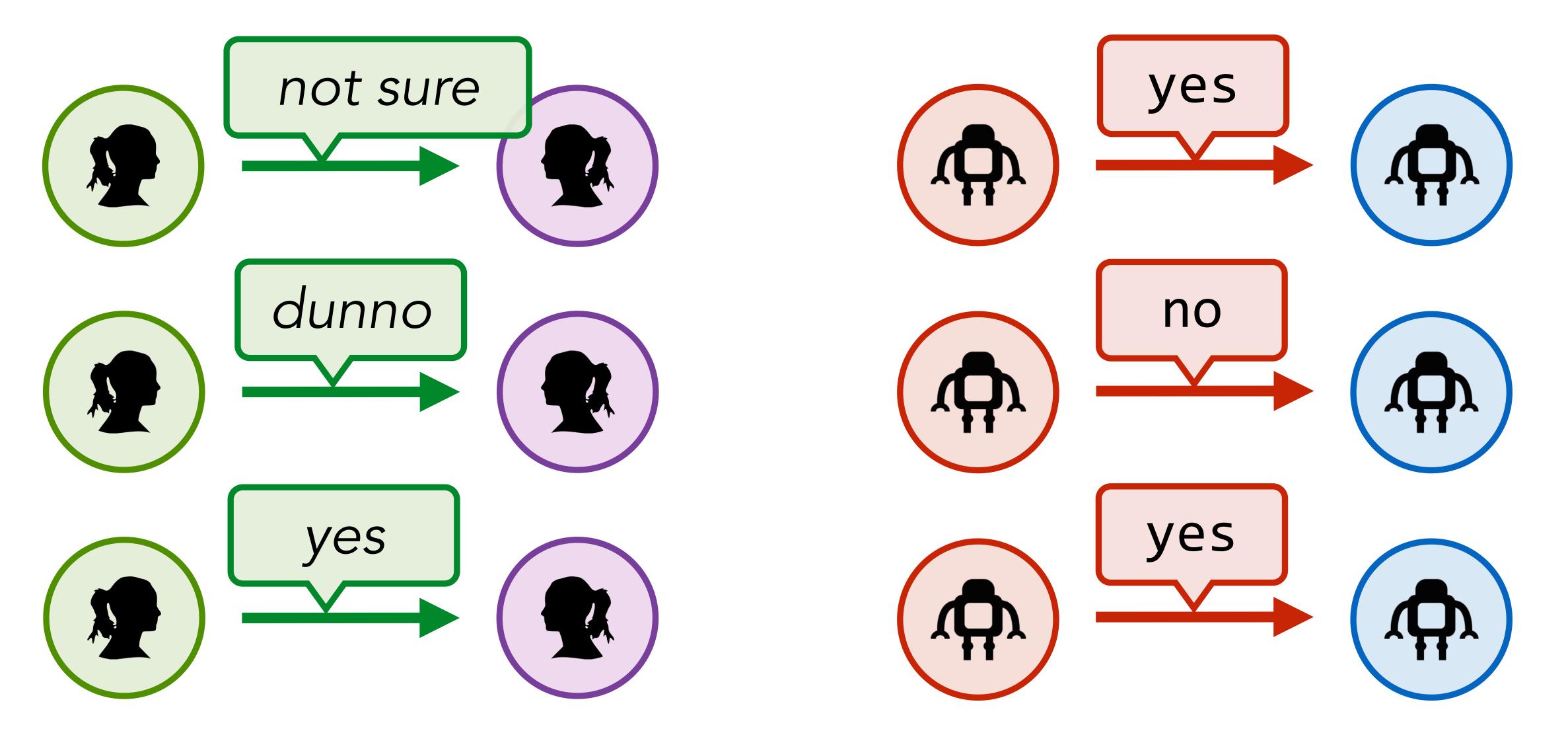


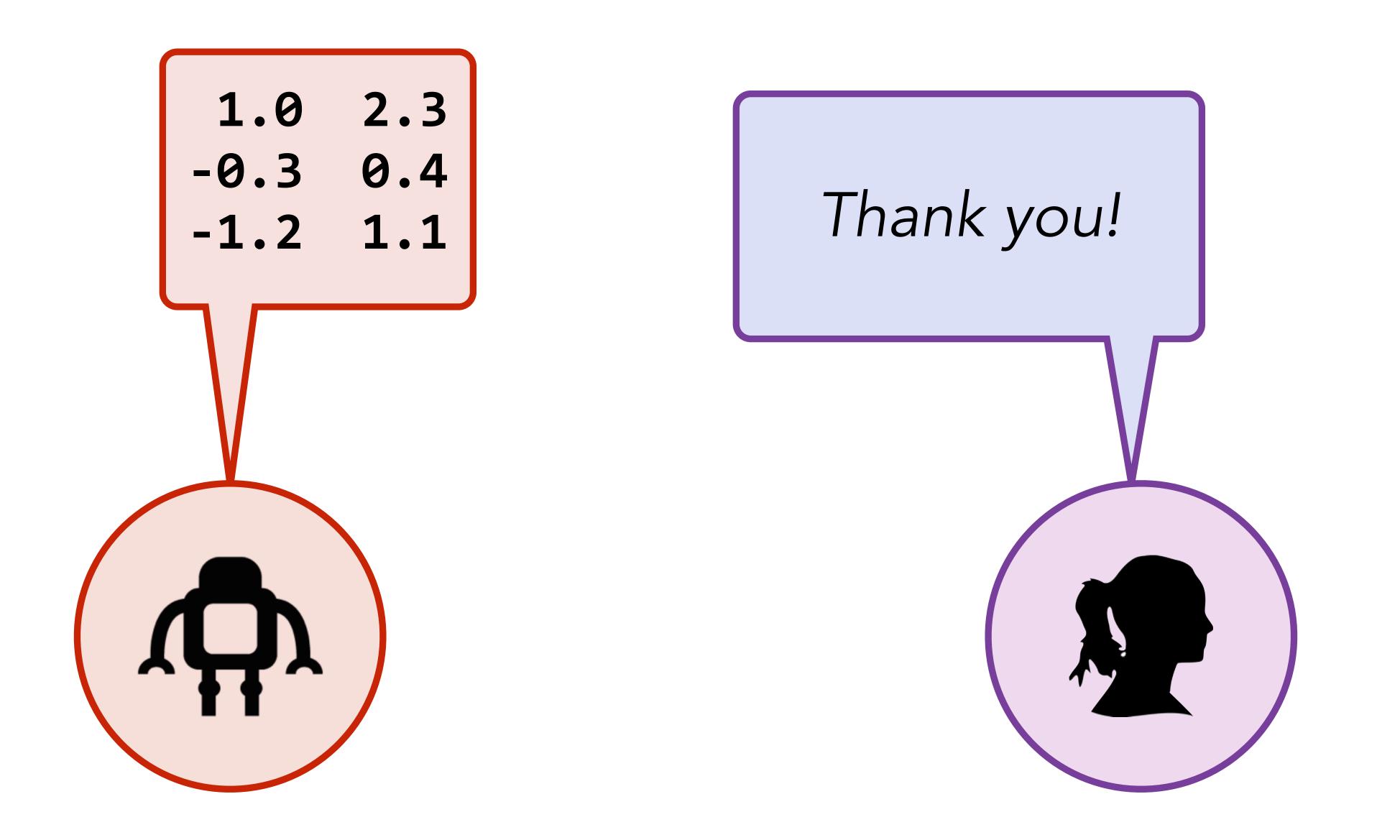
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http://github.com/jacobandreas/{neuralese,rnn-syn}