



Things we underestimated while developing the CPMpy constraint modelling library



Prof. Tias Guns <tias.guns@kuleuven.be>  @TiasGuns

Ignace Bleukx

Wout Vanroose

Emilio Gamba

Jo Devriendt

Dimos Tsouros

Helene Verhaeghe

Ahmed K.A. Abdullah

Maxime Mulamba

Victor Bucarey

Jayanta Mandi

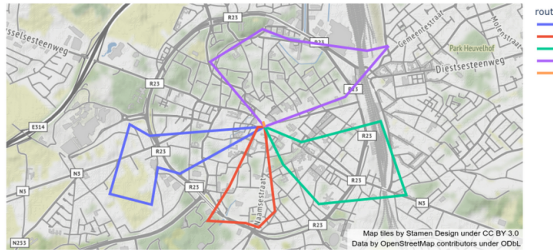
Nicholas Decleyre



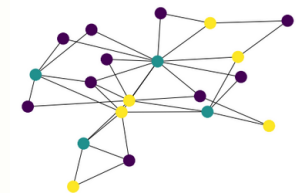
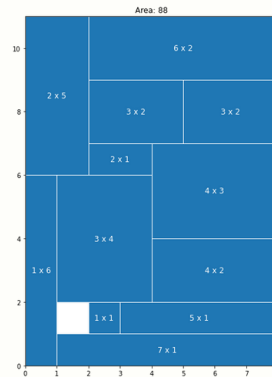
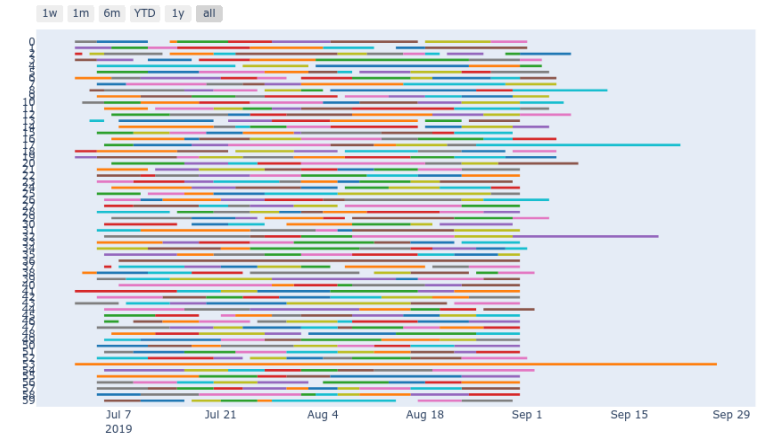
Constraint programming

“Solving combinatorial optimisation problems”

- Vehicle Routing
- Scheduling
- Packing
- Other combinatorial problems



P-Large-02 (59 ROOMS), ExitStatus.OPTIMAL (1558.940814725 seconds)



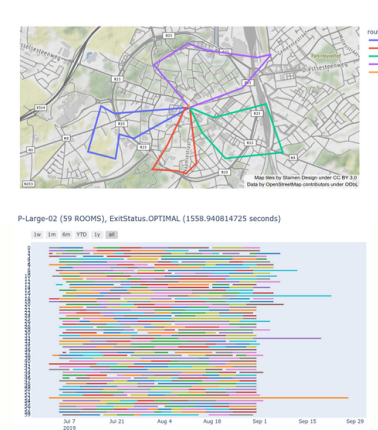
Constraint solving paradigm

Model

+

Solve

Decision variables
Constraints
Objective function



Modeling Tools

	Modeling language	System language	Solver interfacing	Data wrangling
MiniZinc	MiniZinc	C++	Text-based (flatzinc)	minizinc-python
Conjure	Essence	Haskell	Text-based (essence')	Jupyter notebooks
Savile Row	Essence'	Java	Java	Java?
Picat	Picat	C	C	Picat?
CPMpy	Python	Python	Python	Python

CPMpy vision

A top-down effort to make CP technology more accessible to AI researchers and users in general.

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A top-down effort to make CP technology more accessible to AI researchers and users in general.

- Easy integration with Python ML & visualisation libraries
=> decision variables are numpy arrays
- Solver-independent, connect to Python ecosystems
=> to CP, SMT, ILP, SAT and BDD python packages
- Incremental solving and direct access to solvers
- Out-of-the-box UNSAT cores, hyperparam tuning, etc

Solvers

CPMpy only interfaces to Python APIs

Key principle: solver can implement any subset of expressions!

Solvers can also choose to:

- Support assumptions or not
- Be incremental or not
- Expose own solver parameters

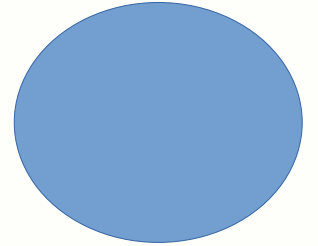
Currently:

- ortools
- pysat
- minizinc
- gurobi
- pySDD
- Z3
- Exact

Wishlist: GCS, CPOptimiser, Choco,
Cplex, Mistral2, Gecode, ...

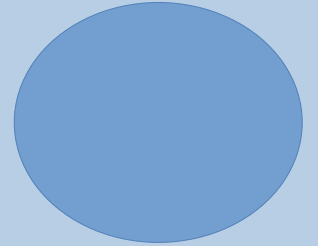
Things we underestimated...

Supporting typical constraint models



Vs

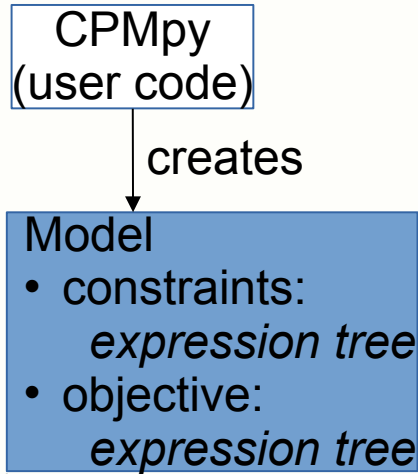
Supporting typical constraint models



V_s

Supporting all valid input

Design



No rewriting!
As specified



Rewriting & Flattening

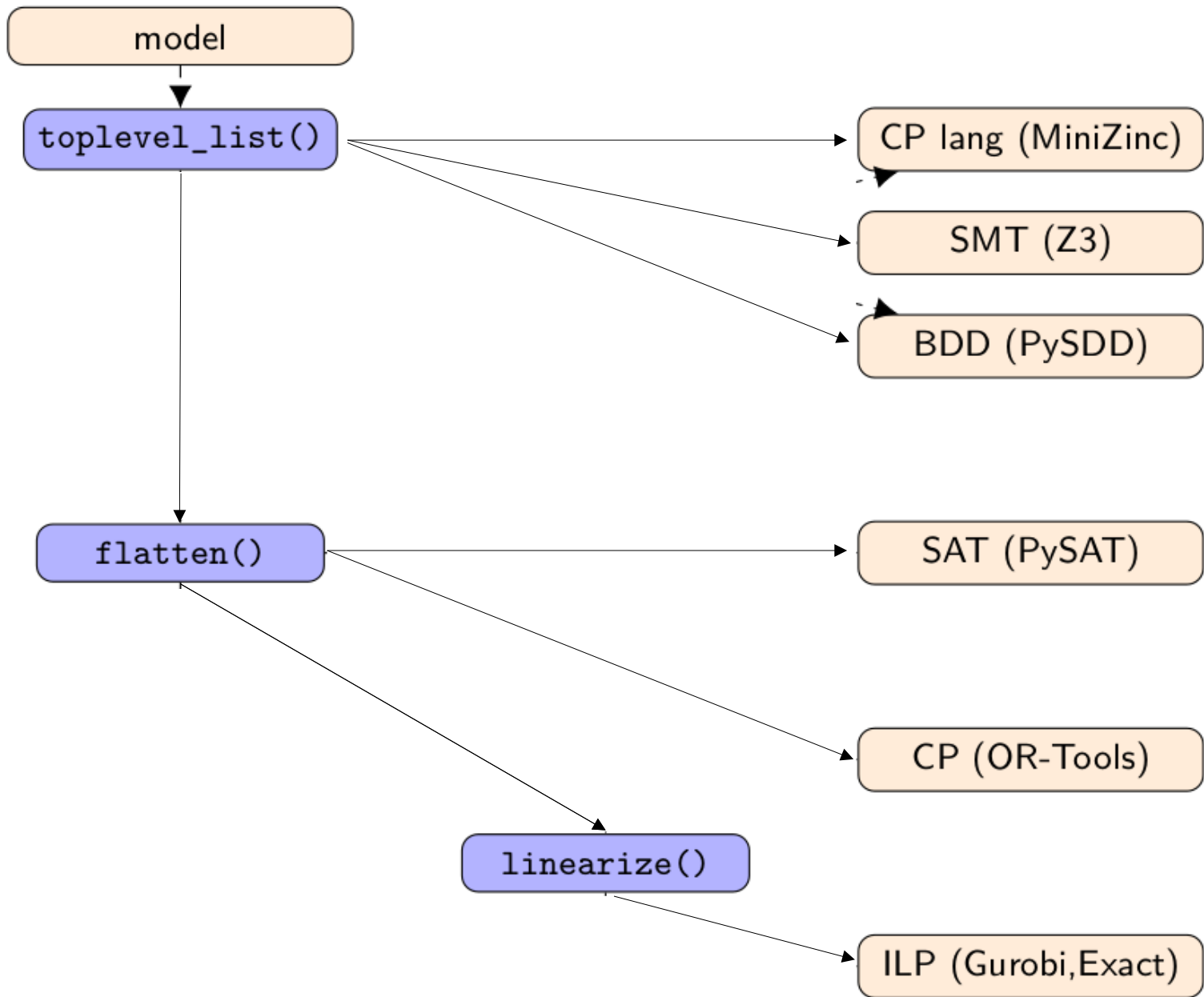
Solver Interface

- CPM_ortools
- CPM_gurobi
- CPM_minizinc
- CPM_z3
- CPM_pysat
- CPM_pySDD

**Only 1-to-1
mapping of
supported
expressions**

Underestimation 1

- *Flattening* is **central** to CP and SAT
- but SMT and BDDs accept nested input
 - $a.\text{implies}(b) \mid (c \ \& \ \sim(a|d))$
 - no need to create auxiliary variables!



- *Flattening* is **central** to CP and SAT
- but SMT & BDDs accept nested input
 - $a.\text{implies}(b) \mid (c \ \& \ \sim(a|d))$
 - no need to create auxiliary variables!
 - they don't support global constraints though...

Underestimation 2

Global constraints are **central** to CP

- Just decompose them, well studied in CP!

But any expression in CPMpy can be *nested* in another expression

- If your language supports a global constraint, it must also support the reified global constraint
- Solvers don't support reified global constraints...
- Reified global == reification of the decomposition?

On the reification of global constraints, 2013.

N. Beldiceanu, M. Carlsson, P. Flener, J. Pearson

“most global constraints can be reformulated as a conjunction of total function constraints together with a constraint that can be easily reified”

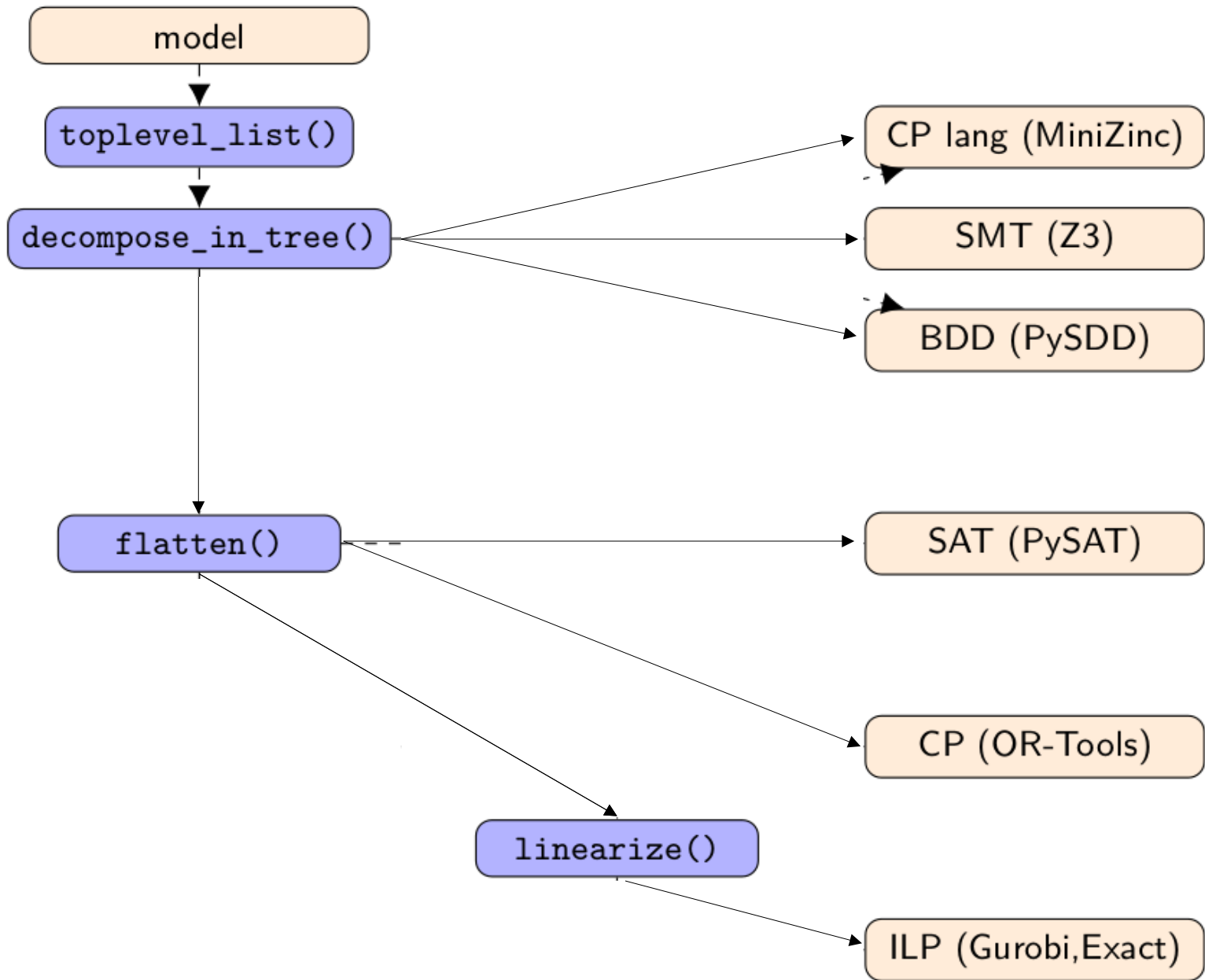
Key issue: decompositions may define auxiliary variables.

Example: `Circuit(nodes)`: creates *successor* variables

Our approach:

`G.decompose()` = (reifiable cons, defining cons)

- Toplevel G: reifiable & defining
- Reified, $bv \leftrightarrow G$: ($bv \leftrightarrow$ reifiable) & defining



Underestimation 3

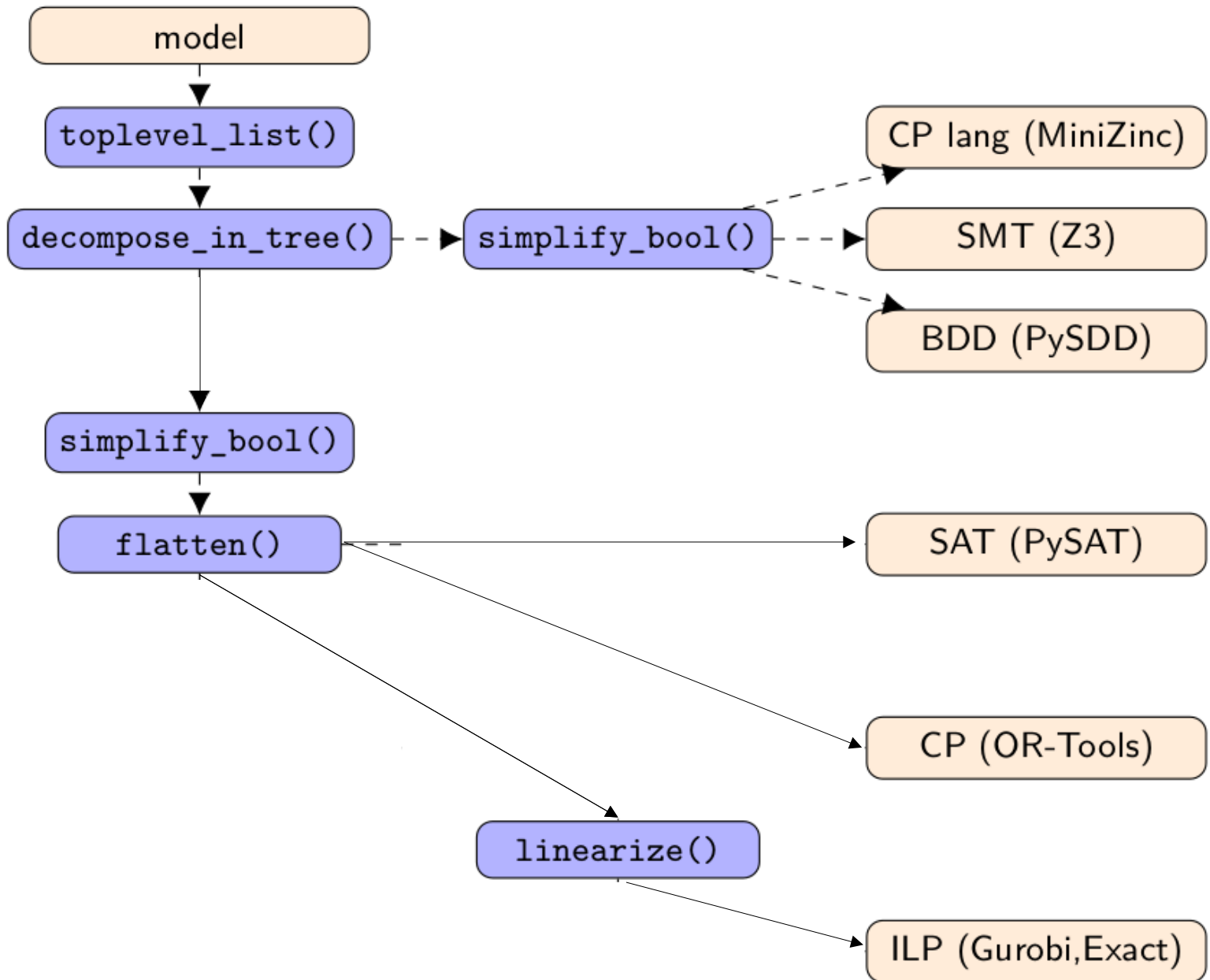
Bool and integer coercions

Flexibility in the language vs strict typing in the solvers.

- No automatic coercion? Or automatically coerce all?
What about $BV == \sim IV$?

=> Bool can be used as int (common use case, e.g. sum(bvs), not the other way around

Solvers require strict typing. When coercing, stay in Bool space if you can
(e.g. $BV1 == 0$, $BV1 + BV2 >= 1$)

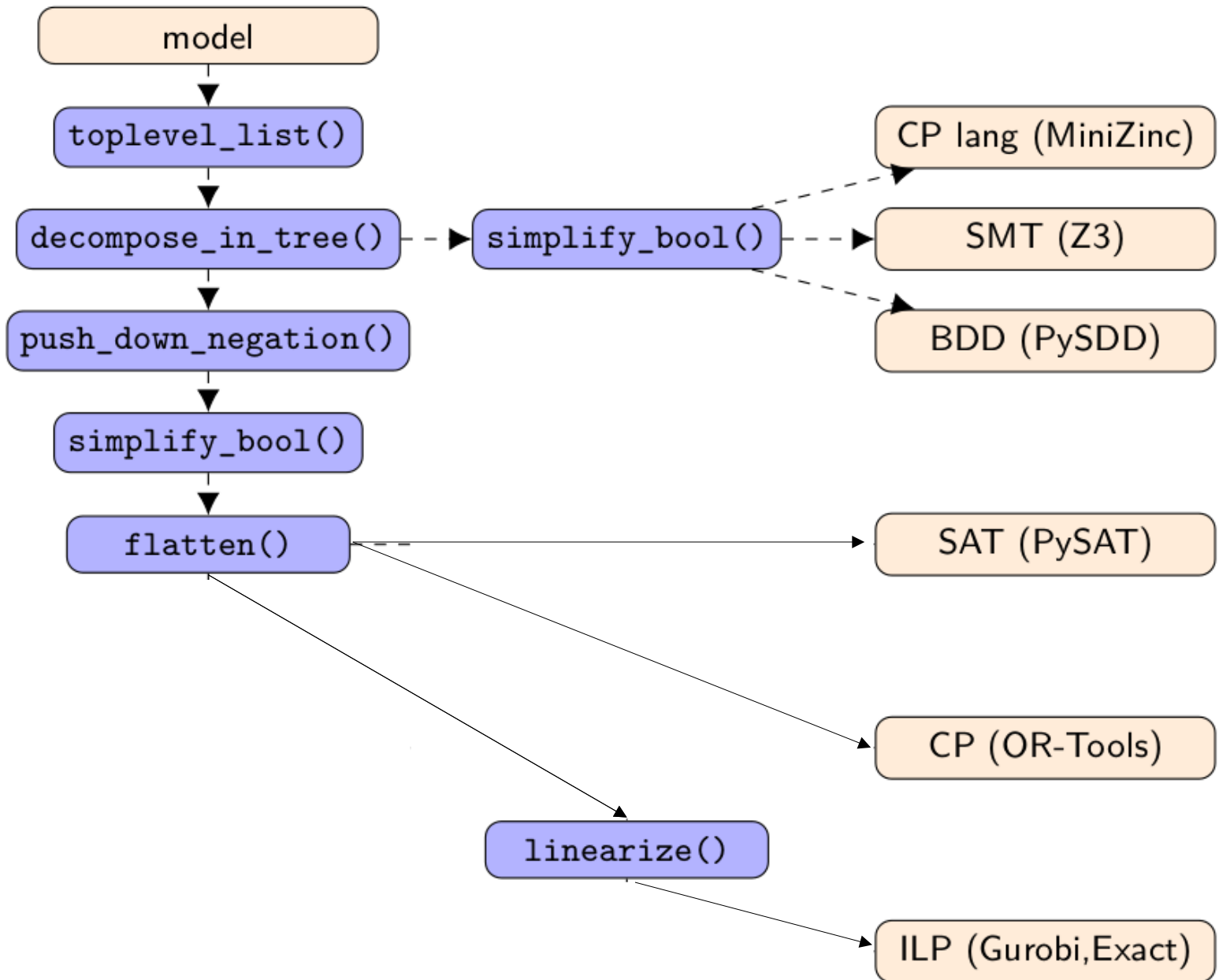


Underestimation 4

Negation

- Just push it down to leafs of expression tree...
- what about global constraints? OK with reifiable, defining
- but don't push all negation down for SMT/BDD...
- avoid introducing unnecessary auxiliary variables in general

So push down early,
do know that later transformations can re-introduce negation...
(creates loop)



Underestimation 4

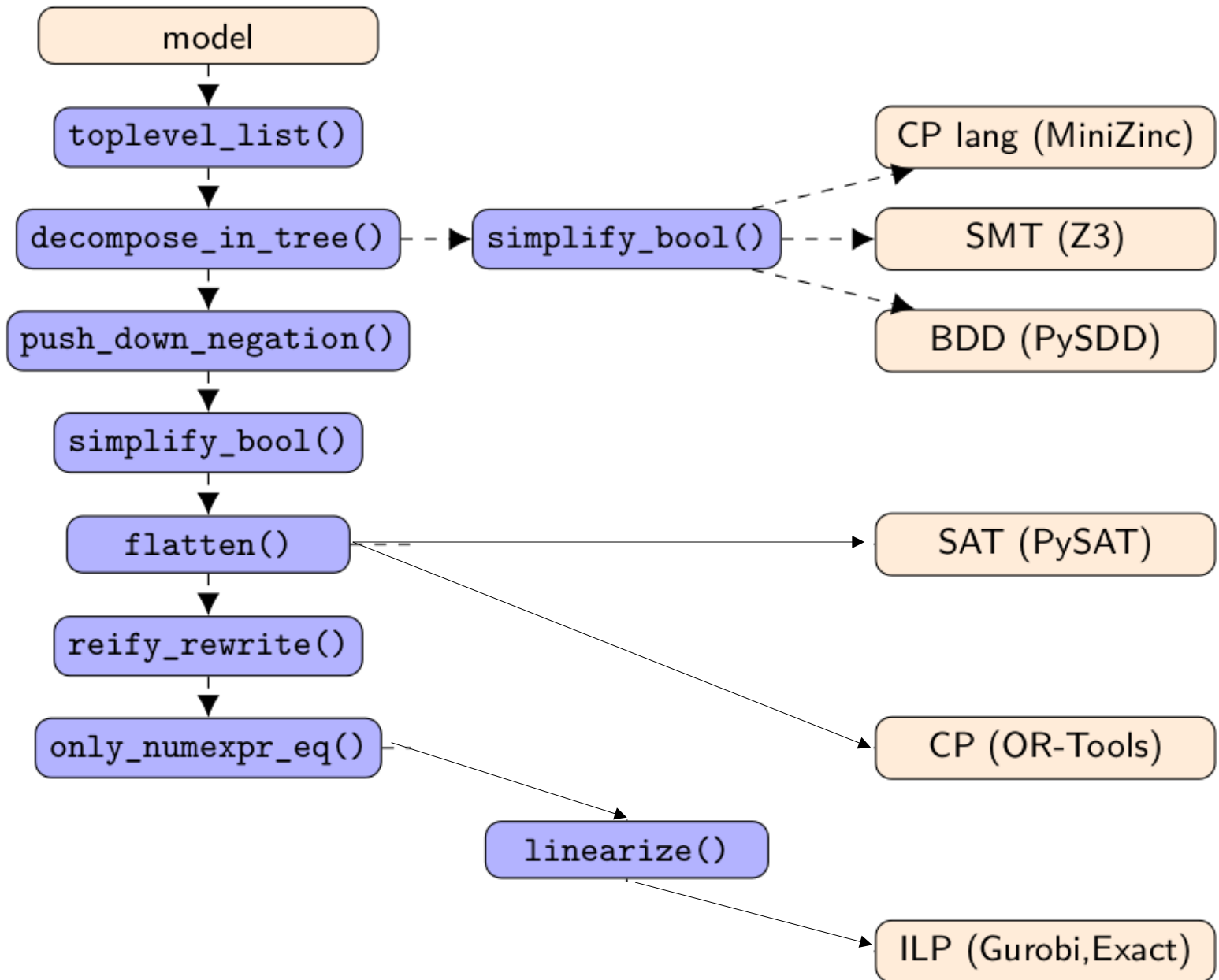
Global constraints again!

- Is $\text{Abs}(x) == y$ a global constraint?
- Is $\text{Abs}(x) \geq y$ a global constraint?
- Is $\text{BV} \leftrightarrow \text{Abs}(x) \geq a$ a global constraint?

Our solution: $\text{Abs}(x)$ is a global function

To solvers that support $\text{Abs}(x) == y$, we rewrite each of the above as:

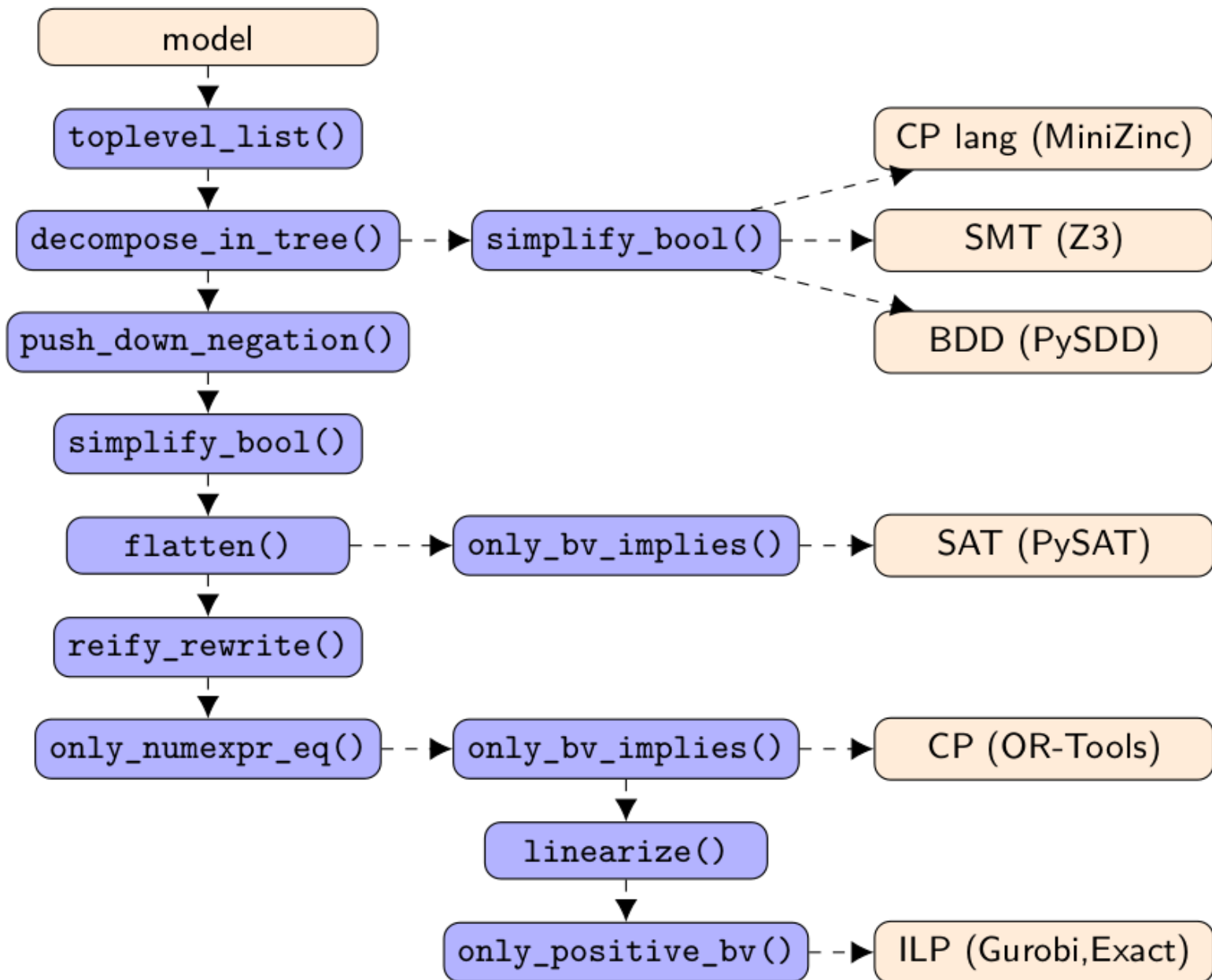
- $\text{Abs}(x) == y$
- $\text{Abs}(x) == \text{tmp} \ \& \ \text{tmp} \geq y$
- $\text{Abs}(x) == \text{tmp} \ \& \ \text{BV} \leftrightarrow \text{tmp} \geq a$



Underestimation 5

Linearisation

- ILP modeling is so similar, and yet so different...
- Custom decompositions (e.g. of AllDifferent, Xor, Circuit)
- Avoid Big-M formulations where possible
- lhs/rhs of expressions versus canonical linear constraint
- negated Boolean variable versus *negative* Boolean var in sum



Underestimation 6

Semantics: which solutions are valid, how many in total

What semantics do the solvers follow? E.g.

- For 'element' global constraint?
=> assumes total (index variable is bounded to array) or not?
- For integer division
=> exact division, floor division, fractional division?

Partial functions... (for now: we assume all are total)

Underestimation 7

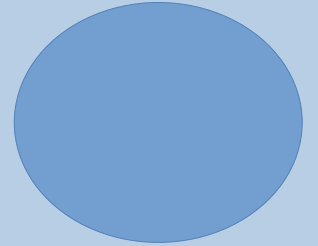
How can you be sure everything is correct?

All cases you can think of?

For all possible expression trees across all solvers
(CP,MIP,SMT,SAT)?

=> Automated fuzztesting!

Supporting typical constraint models



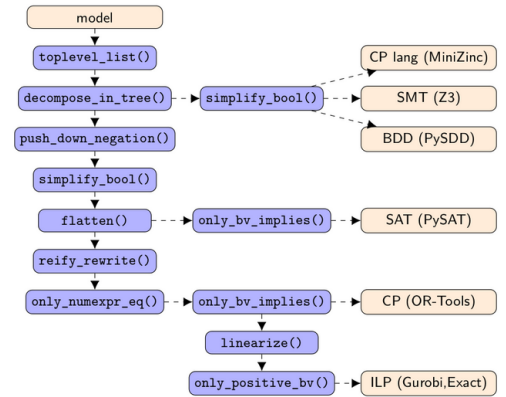
V_s

Supporting all valid input

Conclusion / discussion

- Typical model vs all models
- Keep as much structure as solver supports

- Reify everything?
- FuzzTest everything?
- Efficiency?
- Partial functions?



Extra thanks to Hakan Kjellerstrand for initial testing, Ruben Kindt for initial fuzztesting!