Jie Xu

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Education: • Massachusetts Institute of Te PhD in CSAIL, Electrical Engine Thesis Title: Towards Computati	ll GPA: 5.0/5.0)	019.7 - 2022.8	
 Massachusetts Institute of Technology Master of Science in CSAIL, Electrical Engineering and Computer Science (Overall GPA: 5.0/5.0) Thesis Title: Learning to Fly: Computational Controller Design for Hybrid UAVs with Reinforcement Learning 			
• Tsinghua University Bachelor of Engineering in Comp Graduated with Outstanding Hon		2(all GPA: 93.2/100, Major GPA: 94.9/100, Rank:	012.9 - 2016.7 1/116)
 Research Interests: Robotics: Control, Co-Design, S Computer Graphics: (Different Machine Learning: Reinforcem 	iable) Physics-based Simulation, O	Computational Design and Fabrication	
Professional Experience:			
• Research Scientist at NVIDL Job Responsibilities: Robotics F		202	2.10 - present
• Advisor: Prof. Wojciech Matusik Research Topics: Computationa		20 CSAIL, Massachusetts Institute o	016.8 - 2022.8 of Technology
• Advisor: Miles Macklin, Viktor M Research Topic: Differentiable	lakoviychuk, Tae-Yong Kim Physics-based Simulation for l	Simulation Technology Te	021.6 - 2021.8 eam, NVIDIA
• Advisor: Prof. Shree K. Nayar Research Topic: Data-driven Cl	haracter Motion Generation	20 Computational Imaging Laboratory, S	020.5 - 2020.8 nap Research
• Research Assistant at CMU • Advisor: Prof. Stelian Coros Research Topics: Simulation, A	nimation & Robot Design	20 Robotics Institute, Carnegie Mell	015.7 - 2015.9 on University
• Research Assistant at Tsingh • Advisor: Prof. Shi-Min Hu Research Topic: Point Cloud-ba	-	20 Graphics & Geometric Computing Gro	014.3 - 2016.7 oup, Tsinghua
Awards and Honors: CoRL 2021 Best Paper Awar Paper title: A System for Genera			2021
• Outstanding Graduate in Tsi • Awarded the most excellent gradu	nghua University ates all over the university. (63 or	ut of 3000+ graduates)	2016
• ACM International Collegiate - Gold Medal in the ACM-ICPC	World Finals	,	2012 - 2015 2015
- Champion in the ACM-ICPC	C Asia Shanghai Regional Contest	in 101 countries)	$2014 \\ 2014 \\ 2012$
• Gold Medal in National Olymp	iad in Informatics		2011
Conference on Robot Learning (C • Efficient Tactile Simulation w	Valts Blukis, Yu-Wei Chao, Diete boRL), 2023 (Oral) tith Differentiability for Robot en, Alberto Rodriguez, Pulkit Agra	r Fox	

- Conference on Robot Learning (CoRL), 2022
 Accelerated Policy Learning with Parallel Differentiable Simulation

Jie Xu, Viktor Makoviychuk, Yashraj Narang, Fabio Ramos, Wojciech Matusik, Animesh Garg, Miles Macklin International Conference on Learning Representations (ICLR), 2022

- Assemble Them All: Physics-Based Planning for Generalizable Assembly by Disassembly Yunsheng Tian, Jie Xu, Yichen Li, Jieliang Luo, Shinjiro Sueda, Hui Li, Karl D.D. Wills, Wojciech Matusik ACM Transaction on Graphics, 41(6) (In proceeding of SIGGRAPH Asia 2022), 2022
- Automatic Co-Design of Aerial Robots Using a Graph Grammar Allan Zhao, Tao Du, Jie Xu, Josie Hughes, Juan Salazar, Pingchuan Ma, Wei Wang, Daniela Rus, Wojciech Matusik IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2022
- Closed-Loop Control of Direct Ink Writing via Reinforcement Learning Michal Piovarči*, Michael Foshey*, Jie Xu, Timothy Erps, Vahid Babaei, Piotr Didyk, Szymon Rusinkiewicz, Wojciech Matusik, Bernd Bickel ACM Transactions on Graphics, 41(4) (In proceeding of SIGGRAPH 2022), 2022
- DiffCloth: Differentiable Cloth Simulation with Dry Frictional Contact Yifei Li, Tao Du, Kui Wu, Jie Xu, Wojciech Matusik
- ACM Transactions on Graphics, 2022
- Graph Grammar-based Automatic Design for Heterogeneous Fleets of Underwater Robots Allan Zhao, Jie Xu, Juan Salazar, Wei Wang, Pingchuan Ma, Daniela Rus, and Wojciech Matusik IEEE International Conference on Robotics and Automation (ICRA), 2022
- An Integrated Design Pipeline for Tactile Sensing Robotic Manipulators Lara Zlokapa, Yiyue Luo, Jie Xu, Michael Foshey, Kui Wu, Pulkit Agrawal, Wojciech Matusik IEEE International Conference on Robotics and Automation (ICRA), 2022
- An End-to-End Differentiable Framework for Contact-Aware Robot Design Jie Xu, Tao Chen, Lara Zlokapa, Michael Foshey, Wojciech Matusik, Shinjiro Sueda, Pulkit Agrawal Robotics: Science and Systems (RSS), 2021
- A System for General In-Hand Object Re-Orientation Tao Chen, Jie Xu, Pulkit Agrawal Conference on Robot Learning (CoRL), 2021 (Oral, Best Paper Award)
- Evolution Gym: A Large-Scale Benchmark for Evolving Soft Robots Jagdeep Singh Bhatia, Holly Jackson, Yunsheng Tian, Jie Xu, Wojciech Matusik Thirty-fifth Conference on Neural Information Processing Systems (NeurIPS), 2021
- Multi-Objective Graph Heuristic Search for Terrestrial Robot Design Jie Xu, Andrew Spielberg, Allan Zhao, Daniela Rus, Wojciech Matusik IEEE International Conference on Robotics and Automation (ICRA), 2021
- Prediction-Guided Multi-Objective Reinforcement Learning for Continuous Robot Control Jie Xu, Yunsheng Tian, Pingchuan Ma, Daniela Rus, Shinjiro Seuda, Wojciech Matusik International Conference on Machine Learning (ICML), 2020
- RoboGrammar: Graph Grammar for Terrain-Optimized Robot Design Allan Zhao, Jie Xu, Mina Konaković Luković, Josephine Hughes, Andrew Spielberg, Daniela Rus, Wojciech Matusik ACM Transactions on Graphics, 39(6), (In proceeding of SIGGRAPH Asia), 2020
- Learning to Fly: Computational Controller Design for Hybrid UAVs with Reinforcement Learning *Jie Xu*, *Tao Du*, *Michael Foshey*, *Beichen Li*, *Bo Zhu*, *Adriana Schulz*, *Wojciech Matusik* ACM Transactions on Graphics, 38(4), (In proceeding of SIGGRAPH 2019), 2019
- Interactive Design Space Exploration and Optimization for CAD Models Adriana Schulz, Jie Xu, Bo Zhu, Changxi Zheng, Eitan Grispun, Wojciech Matusik ACM Transactions on Graphics, 36(4), (In proceeding of SIGGRAPH 2017), 2017
- View Suggestion for Interactive Segmentation of Indoor Scenes Sheng Yang, Jie Xu, Kang Chen, Hong-Bo Fu Computational Visual Media, June 2017, Volume 3, Issue 2
- Extracting Sharp Features from RGB-D images Yan-Pei Cao, Tao Ju, Jie Xu, Shi-Min Hu Computer Graphics Forum, Vol. 35, No. 8, pp. 138-174, 2017.

Teaching:

• Teaching Assistant (MIT 6.839/6.807)	
MIT 6.839 Advanced Computer Graphics/6.807 Computational Design and Fabrication	
Scholarships:	
Google Excellence Scholarship	2015
• Awards the students who demonstrate superior academic achievement, 58 students are selected nationwide	

2015

2013

- China Computer Federation Outstanding Undergraduate Award Awards the students who have excellent academic and researching performance, 4 students in Tsinghua
- Comprehensive Excellence Scholarship in Tsinghua University • The scholarship for comprehensive performance

Professional Services:

- Conference Review: RSS, CoRL, ICRA, IROS, SIGGRAPH Asia
- Journal Review: TOG, RAL, AAMAS