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# Squeeze All: Novel Estimator and Self-Normalized Bound for Linear Contextual Bandits

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## Abstract

We propose a linear contextual bandit algorithm with  $O(\sqrt{dT} \log T)$  regret bound, where  $d$  is the dimension of contexts and  $T$  is the time horizon. Our proposed algorithm is equipped with a novel estimator in which exploration is embedded through explicit randomization. Depending on the randomization, our proposed estimator takes contribution either from contexts of all arms or from selected contexts. We establish a self-normalized bound for our estimator, which allows a novel decomposition of the cumulative regret into *additive* dimension-dependent terms instead of multiplicative terms. We also prove a novel lower bound of  $\Omega(\sqrt{dT})$  under our problem setting. Hence, the regret of our proposed algorithm matches the lower bound up to logarithmic factors. The numerical experiments support the theoretical guarantees and show that our proposed method outperforms the existing linear bandit algorithms.

## 1 INTRODUCTION

The multi-armed bandit (MAB) is a sequential decision making problem where a learner repeatedly chooses an arm and receives a reward as partial feedback associated with the selected arm only. The goal of the learner is to maximize cumulative rewards over a horizon of length  $T$  by suitably balancing exploitation and exploration. The *Linear contextual bandit* is a general version of the MAB problem, where  $d$ -dimensional context vectors are given for each of the arms and the expected rewards for each arm is a linear function of the corresponding context vector.

There are a family of algorithms that utilize the principle of *optimism in the face of uncertainty* (OFU) (Lai and Robbins,

1985). These algorithms for the linear contextual bandit have been widely used in practice (e.g., news recommendation in Li et al. (2010)) and extensively analyzed (Auer, 2002a; Dani et al., 2008; Rusmevichientong and Tsitsiklis, 2010; Chu et al., 2011; Abbasi-Yadkori et al., 2011). Some of the most widely used algorithms in this family are LinUCB (Li et al., 2010) and OFUL (Abbasi-Yadkori et al., 2011) due to their practicality and performance guarantees. The best known regret bound for these algorithms is  $\tilde{O}(d\sqrt{T})$ , where  $\tilde{O}$  stands for big- $O$  notation up to logarithmic factors of  $T$ . Another widely-known family of bandit algorithms are based on randomized exploration, such as Thompson sampling (Thompson, 1933). LinTS (Agrawal and Goyal, 2013; Abeille et al., 2017) is a linear contextual bandit version of Thompson sampling with  $\tilde{O}(d^{3/2}\sqrt{T})$  or  $\tilde{O}(d\sqrt{T} \log N)$  regret bound, where  $N$  is the total number of arms. More recently proposed methods based on random perturbation of rewards (Kveton et al., 2020) also have the same order of regret bound as LinTS. Hence, many practical linear contextual bandit algorithms have linear or super-linear dependence on  $d$ .

A regret bound with sublinear dependence on  $d$  has been shown for SupLinUCB (Chu et al., 2011) with  $\tilde{O}(\sqrt{dT} \log^{3/2} N)$  regret as well as a matching lower bound  $\Omega(\sqrt{dT})$ , hence provably optimal up to logarithmic factors. A more recently proposed variant of SupLinUCB has been shown to achieve an improved regret bound of  $\tilde{O}(\sqrt{dT} \log N)$  (Li et al., 2019). SupLinUCB and its variants (e.g., Li et al. 2017, 2019) improve the regret bound by  $\sqrt{d}$  factor capitalizing on independence of samples via a phased bandit technique proposed by Auer (2002a). Despite their provable near-optimality, all the algorithms based on the framework of Auer (2002a) including SupLinUCB tend to explore excessively with insufficient adaptation and are not practically attractive due to computational inefficiency. Moreover, the question of whether  $\tilde{O}(\sqrt{dT})$  regret is attainable without relying on the framework of Auer (2002a) has remained open.

A tighter regret bound of SupLinUCB and its variants than that of LinUCB (and OFUL) stems from utilizing phases by handling computation separately for each phase. In phased

algorithms such as `SupLinUCB`, the arms in the same phase are chosen without making use of the rewards in the same phase. This independence of samples allows to apply a tight confidence bound, improving the regret bound by  $\sqrt{d}$  factor. On the other hand, this operation should be handled for each arm, which costs polylogarithmic dependence on  $N$  by invoking the union bound over the arms at the expense of improving  $\sqrt{d}$ . In non-phased algorithms such as `LinUCB` and `LinTS`, the estimate is adaptive in a sense that the update is made in every round using all samples collected up to each round; hence the independence argument cannot be utilized. For this, the well-known self-normalized theorem (Abbasi-Yadkori et al., 2011) helps avoid the dependence on  $N$ , however incurring a linear dependence on  $d$  (or super-linear dependence for `LinTS`). Thus, the following fundamental question remains open:

*Can we design a linear contextual bandit algorithm that achieves a sublinear dependence on  $d$  and is adaptive?*

To this end, we propose a novel contextual bandit algorithm that enjoys the best of the both worlds, achieving a faster rate of  $O(\sqrt{dT \log T})$  regret and utilizing adaptive estimation which overcomes the impracticality of the existing phased algorithms. The established regret bound of our algorithm matches the regret bound of `SupLinUCB` in terms of  $d$  without resorting to independence and improves upon it in that its main order does not depend on  $N$ . The proposed algorithm is equipped with a novel estimator in which exploration is embedded through explicit randomization. Depending on the randomization, the novel estimator takes contribution either from full contexts or from selected contexts. Using full contexts is essential in overcoming the dependence due to adaptivity. Explicit randomization has dual roles. First, the randomization allows constructing pseudo-outcomes in (3) and thus including all contexts along with (3). Second, randomization promotes the level of exploration by introducing external uncertainty in the estimator that can be deterministically computed given observed data. These two features allow a novel additive decomposition of the regret which can be bounded using the self-normalized norm of the proposed estimator.

Our main contributions are as follows:

- We propose a novel algorithm, *Hybridization by Randomization* bandit algorithm (`HyRan Bandit`) for a linear contextual bandit. Our proposed algorithm has two notable features: the first is to utilize the contexts of all arms both selected and unselected for parameter estimation, and the second is to randomly perturb the contribution to the estimator.
- We establish that our proposed algorithm, `HyRan Bandit`, achieves  $O(\sqrt{dT \log T})$  regret upper bound without dependence on  $N$  on the leading term. Ours is the first method achieving  $\tilde{O}(\sqrt{dT})$  regret without relying on the widely used technique by Auer (2002a) and its variants (e.g., `SupLinUCB`). To the best of our knowledge, this is the fastest rate regret bound for the linear contextual bandit.
- We propose a novel `HyRan` (Hybridization by randomization) estimator which uses either the contexts of all arms or selected contexts depending on randomization. We establish a self-normalized bound (Theorem 5.4) for our estimator, which allows a novel decomposition of the cumulative regret into *additive* dimension-dependent terms (Lemma 5.2) instead of multiplicative terms. This allows us to establish the faster rate of the cumulative regret.
- We prove a novel lower bound of  $\Omega(\sqrt{dT})$  for the cumulative regrets (Theorem 5.6) under our problem setting. The lower bound matches with the regret upper bound of `HyRan Bandit` up to logarithmic factors, hence showing the provable near-optimality of our method.
- We evaluate `HyRan Bandit` on numerical experiments and show that the practical performance of our proposed algorithm is in line with the theoretical guarantees and is superior to the existing algorithms.

## 2 RELATED WORKS

The linear contextual bandit problem was first introduced by Abe and Long (1999). UCB algorithms for the linear contextual bandit have been proposed and analyzed by Auer (2002a); Dani et al. (2008); Rusmevichientong and Tsitsiklis (2010); Chu et al. (2011); Abbasi-Yadkori et al. (2011) and their follow-up works. Thompson sampling based algorithms have also been widely studied (Agrawal and Goyal, 2013; Abeille et al., 2017). Both classes of the algorithms typically have linear (or superlinear) dependence on context dimension. To our knowledge, all of the regret bounds with sublinear dependence on context dimension are for UCB algorithms based on the IID sample generation technique of Auer (2002a). The examples include `SupLinUCB` Chu et al. (2011) with an  $O(\sqrt{dT} \log^{3/2}(NT))$  regret bound and its variant `VCL-SupLinUCB` (Li et al., 2019) with an  $O(\sqrt{dT}(\log T)(\log N)) \cdot \text{poly}(\log \log(NT))$  regret bound. The phase-based elimination algorithms with  $O(\sqrt{dT \log NT})$  regret bound introduced by Valko et al. (2014) and Lattimore and Szepesvári (2020) is a variant of `SupLinUCB` for the case where the set of contexts does not change over time. Despite their sharp regret bounds, these `SupLinUCB`-type algorithms based on the framework of Auer (2002a) are impractical due to its algorithmic design to discard the observed rewards and to explore excessively with insufficient adaptation.

The rewards for the unselected arms are not observed, hence, missing. Recently some bandit literature has framed the bandit setting as a missing data problem, and employed

missing data methodologies (Dimakopoulou et al., 2019; Kim and Paik, 2019; Kim et al., 2021). Dimakopoulou et al. (2019) employs an *inverse probability weighting* (IPW) estimator using the selected contexts alone and proves an  $\tilde{O}(d\sqrt{\epsilon^{-1}T^{1+\epsilon}N})$  regret bound for LinTS which depends on the number of arms,  $N$ . The *doubly robust* (DR) method (Robins et al., 1994; Bang and Robins, 2005) is adopted in Kim and Paik (2019) with Lasso penalty for high-dimensional settings with sparsity and the regret bound is shown to be improved in terms of the sparse dimension instead of  $d$ . Recently in Kim et al. (2021), a modified LinTS employing the DR method is proposed and provided an  $\tilde{O}(d\sqrt{T})$  regret bound. The authors improve the bound by using contexts of all arms including the unselected ones which paves a way to circumvent the technical definition of unsaturated arms.

A key element in building the DR method is a random variable with a known probability distribution. In Thompson sampling, randomness is inherent in the step sampling from a posterior distribution, and the probability of the selected arm having the largest predicted outcome can be computed. This allows naturally constructing the DR estimator. All previous DR-type estimators capitalize on randomness in Thompson sampling (e.g. Dimakopoulou et al. (2019); Kim et al. (2021)) or in epsilon-greedy (Kim and Paik, 2019). In algorithms without such inherent randomness, the DR estimators cannot be constructed. In this paper, we generate a random variable to determine whether to contribute full contexts or just chosen context.

Another line of the literature that uses stochastic assumptions on contexts include Goldenshluger and Zeevi (2013); Bastani and Bayati (2020) and Bastani et al. (2021). In their work, the problem setting is different from ours in that they consider  $N$  different parameters for each arm with single context vector shared for all arms. They resort to much stronger assumptions for regret analysis such as the margin condition (Goldenshluger and Zeevi, 2013; Bastani and Bayati, 2020; Bastani et al., 2021) as well as the covariate diversity condition (Bastani et al., 2021) that allow for a greedy approach to be efficient. However, in our problem setting, such assumptions are not applied and a simple greedy policy would cause regret linear in  $T$ .

### 3 LINEAR CONTEXTUAL BANDIT PROBLEM

In each round  $t \in [T] := \{1, \dots, T\}$ , the learner observes a set of arms  $[N] := \{1, \dots, N\}$  with their corresponding context vectors  $\{X_{i,t} \in \mathbb{R}^d \mid i \in [N]\}$ . Then, the learner chooses an arm  $a_t \in [N]$  and receives a random reward  $Y_t := Y_{a_t,t}$  for the chosen arm. For all  $t \in [T]$  and  $i \in [N]$ , we assume the linear reward model, i.e.,  $Y_{i,t} = X_{i,t}^T \beta^* + \eta_{i,t}$ , where  $\beta^* \in \mathbb{R}^d$  is an *unknown* parameter and  $\eta_{i,t} \in \mathbb{R}$  is an independent noise. Let  $\mathcal{H}_t$  be the

history at round  $t$  that contains contexts  $\{X_{i,\tau}\}_{i=1,\tau=1}^{N,t}$ , chosen arms  $\{a_\tau\}_{\tau=1}^{t-1}$  and the corresponding rewards  $\{Y_\tau\}_{\tau=1}^{t-1}$ . For each  $t$  and  $i$ , the noise  $\eta_{i,t}$  is zero-mean conditioned on  $\mathcal{H}_t$ , i.e.,  $\mathbb{E}[\eta_{i,t} \mid \mathcal{H}_t] = 0$ . The optimal arm at round  $t$  is defined as  $a_t^* := \arg \max_{i \in [N]} \{X_{i,t}^T \beta\}$ . Let  $\text{regret}(t)$  be the difference between the expected rewards of the chosen arm and the optimal arm at round  $t$ , i.e.,  $\text{regret}(t) := X_{a_t,t}^T \beta^* - X_{a_t^*,t}^T \beta^*$ . The goal is to minimize the sum of regrets over  $T$  rounds,  $R(T) := \sum_{t=1}^T \text{regret}(t)$ . The time horizon  $T$  is finite but possibly unknown.

## 4 PROPOSED METHODS

In this section, we present the methodological contributions, the new estimator (Section 4.1) and the new contextual bandit algorithm that utilizes the proposed estimator (Section 4.2).

### 4.1 Hybridization by Randomization (HyRan) Estimator

We start from two candidate estimators, the ridge estimator and the DR estimator, and their corresponding estimating equations. The first one, the *ridge score* function is a sum of contribution from round  $\tau$ ,

$$X_{a_\tau,\tau} (Y_{a_\tau,\tau} - X_{a_\tau,\tau}^T \beta). \quad (1)$$

The other is the *DR score* function. However, to employ the DR technique in general cases, we need preliminary works. The DR procedure is originally proposed for missing data problems, and requires the observation (or missing) indicator and the observation probability as the main elements. These two elements are naturally provided in Thompson sampling: the indicator  $a_t$  being each arm is a random variable given history since the estimator is sampled from a posterior distribution, and the expectation of this indicator is the probability of choosing each arm. All previous DR-typed bandits apply the DR technique to algorithms equipped with inherent randomness such as Thompson sampling or epsilon-greedy. The DR procedure cannot be naturally applied to the algorithms without inherent randomness, e.g. LinUCB, since the indicator that  $a_t$  equals each arm is not random but deterministic given history. For the DR technique to be applied regardless whether  $a_t$  is random or not, we introduce an external random device by sampling  $h_t$  from  $[N]$  with a known non-zero probability. We can convert  $h_t$  into  $N$ -variate one hot vector following a multinomial distribution. Thanks to this seemingly superfluous external random variable through  $h_t$ , we can construct a DR score, whose contribution at round  $\tau$  is:

$$\sum_{i=1}^N X_{i,\tau} \left( \tilde{Y}_{i,\tau} - X_{i,\tau}^T \beta \right), \quad (2)$$

where the pseudo reward  $\tilde{Y}_{i,\tau}$  is defined as

$$\tilde{Y}_{i,\tau} = \left\{ 1 - \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}} \right\} X_{i,\tau}^T \check{\beta}_\tau + \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}} Y_{h_\tau,\tau}, \quad (3)$$

for some random variable  $h_\tau$  sampled from  $[N]$ , with probability  $\pi_{i,\tau} := \mathbb{P}(h_\tau = i)$ , and  $\check{\beta}_\tau$  is an imputation estimator defined in Section A.5.1. The DR score (2) uses  $\tilde{Y}_{i,\tau}$  instead of  $Y_{i,\tau}$  in the original score function to estimate  $\beta$  as if all rewards were observed. Using the pseudo reward (3), we can use all contexts rather than just selected contexts.

Although the external random variable paves a way to utilize DR techniques, it also causes trouble in computing (3) since  $Y_{i,t}$  is observed for  $i = a_t$  not for  $i = h_t$ . Therefore the second term of (3) cannot be computed if  $h_t \neq a_t$ . The solution to this problem shapes the main theme of our proposed method, namely *hybridization*. Our strategy is to construct a score function from (2) when  $h_t = a_t$ , but from (1) when  $h_t \neq a_t$ .

We denote the indices of  $t$  by  $\Psi_t$  if  $h_t = a_t$ . With the subsampled set of rounds  $\Psi_t$  we can define our hybrid score equation

$$\begin{aligned} & \sum_{\tau \in \Psi_t} \sum_{i=1}^N X_{i,\tau} \left( \tilde{Y}_{i,\tau} - X_{i,\tau}^T \beta \right) \\ & + \sum_{\tau \notin \Psi_t} X_{a_\tau,\tau} \left( Y_{a_\tau,\tau} - X_{a_\tau,\tau}^T \beta \right) + \lambda_t \beta = 0. \end{aligned} \quad (4)$$

The first term is from the DR score (2) and the second term is from the ridge score (1). The contribution of the two score functions is determined by the subset  $\Psi_t$  which is randomized with the random variable  $h_t$ . Therefore, we call the random variable  $h_t$  as a *hybridization variable*. Specifically, for each round  $t \in [T]$  and given  $p \in (0, 1)$ , we sample  $h_t$  from  $[N]$  with probability,

$$\begin{aligned} \pi_{a_t,t} &:= \mathbb{P}(h_t = a_t | \mathcal{F}_t) = p, \\ \pi_{j,t} &:= \mathbb{P}(h_t = j | \mathcal{F}_t) = \frac{1-p}{N-1}, \quad \forall j \neq a_t, \end{aligned} \quad (5)$$

where  $\mathcal{F}_t := \mathcal{H}_t \cup \{a_t\} \cup \{h_1, \dots, h_{t-1}\}$ . We emphasize that  $h_t$  is sampled after an arm  $a_t$  is pulled and does not affect the choice of  $a_t$ .

Our proposed estimator is the solution of (4) which can be written as

$$\begin{aligned} \hat{\beta}_t &:= \left( \sum_{\tau \in \Psi_t} \sum_{i=1}^N X_{i,\tau} X_{i,\tau}^T + \sum_{\tau \notin \Psi_t} X_{a_\tau,\tau} X_{a_\tau,\tau}^T + \lambda_t I \right)^{-1} \\ & \left( \sum_{\tau \in \Psi_t} \sum_{i=1}^N X_{i,\tau} \tilde{Y}_{i,\tau} + \sum_{\tau \notin \Psi_t} X_{a_\tau,\tau} Y_\tau \right). \end{aligned} \quad (6)$$

This is a hybrid form of using the contexts of all arms and using the contexts of the selected arms, and the contribution

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### Algorithm 1 Hybridization by Randomization Bandit Algorithm for Linear Contextual Bandits

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**INPUT:** Regularization parameter  $\lambda_t > 0$ , subsampling parameter  $p \in (0, 1)$ .

Initialize  $V_0 = I_d$ ,  $Z_0 = 0_d$

**for**  $t = 1$  to  $T$  **do**

Observe contexts  $\{X_{i,t}\}_{i=1}^N$  and estimate  $\hat{\beta}_{t-1} = (V_{t-1} + \lambda_t I_d)^{-1} Z_{t-1}$

Play  $a_t = \arg \max_i X_{i,t}^T \hat{\beta}_{t-1}$  and observe  $Y_t$

Set  $\pi_{a_t,t} := p$  and  $\pi_{j,t} := \frac{1-p}{N-1}$  for  $j \neq a_t$

Sample a hybridization variable  $h_t$  from the multinomial distribution with probability  $(\pi_{1,t}, \dots, \pi_{N,t})$

**if**  $h_t = a_t$  **then**

Update  $V_t = V_{t-1} + \sum_{i=1}^N X_{i,t} X_{i,t}^T$  and  $Z_t = Z_{t-1} + \sum_{i=1}^N X_{i,t} \tilde{Y}_{i,t}$

**else**

Update  $V_t = V_{t-1} + X_{a_t,t} X_{a_t,t}^T$  and  $Z_t = Z_{t-1} + X_{a_t,t} Y_t$

**end if**

Update  $\check{\beta}_t = (V_t + \sqrt{t} I_d)^{-1} Z_t$

**end for**

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is set by the random variable the subsampled rounds  $\Psi_t$ . We later provide the estimation error bound for this newly proposed estimator in Theorem 5.4 which allows us to shave off the dimensionality dependence in regret analysis.

## 4.2 HyRan Bandit Algorithm

Our proposed algorithm, HyRan Bandit, is presented in Algorithm 1. At each round  $t$ , the algorithm computes  $X_{i,t}^T \hat{\beta}_{t-1}$  for each arm  $i \in [N]$  based on our estimator (6) and finds the arm  $a_t$  with the maximum estimated reward. After pulling  $a_t$  and observing the reward for the selected arm, the next step is to determine whether the contribution to the estimator is the ridge score (1) or the DR score (2). HyRan Bandit then samples the hybridization variable  $h_t \in [N]$  from the multinomial distribution with probability  $(\pi_{1,t}, \dots, \pi_{N,t})$ . This procedure determines whether the contexts and reward at round  $t$  is added by (1) or (2). When  $h_t$  is equal to  $a_t$ , we can observe the reward  $\tilde{Y}_{h_t,t}$  and compute the pseudo reward in (3). Therefore we include the round  $t$  in  $\Psi_t$ , and use (2), otherwise we use (1). When the contribution to the score function is determined, HyRan Bandit updates  $\hat{\beta}_t$  as in (6).

In order to compute  $\hat{\beta}_t$ , the algorithm requires another imputation estimator  $\check{\beta}_t$  to determine the pseudo reward in (3). In order to obtain the near-optimal regret bound, one must use an imputation estimator such that  $\|\check{\beta}_t - \beta^*\|_2 \leq N^{-1}$  holds after some explorations. For the definition of the imputation estimator  $\check{\beta}_t$  used in our analysis, see Section A.5.1. Since  $\check{\beta}_t$  is multiplied with mean zero random variable in (3) the unbiasedness of the estimator does not depend on

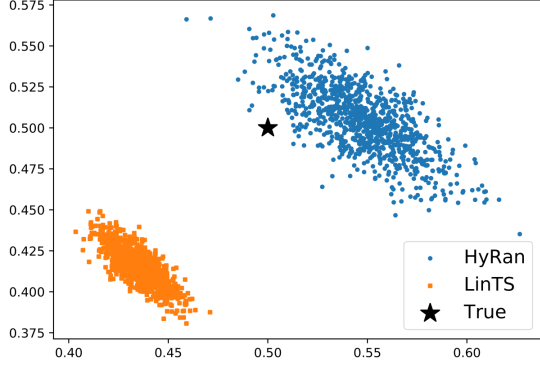


Figure 1: An illustration of the 1000 generated estimators of  $\beta^*$  used in HyRan `Bandit` and LinTS at round  $t = 1000$ , when  $d = 2$  and  $N = 5$ . The points in blue and orange represent the generated HyRan and LinTS estimators, respectively. The black star in the plot represents the true parameter  $\beta^*$ .

the choice of  $\check{\beta}_t$ .

*Discussion of the algorithm.* The action selection in HyRan `Bandit` is greedy given the HyRan estimator. However the algorithm is not exploration-free since the HyRan estimator is generated randomly. Note that action selection in LinTS is also greedy given the sampled estimator. The estimator from LinTS represents a realization from a posterior distribution. Hence, exploration is embedded in the estimator through variability in the distribution. Similarly, in our method, exploration is embedded in the HyRan estimator. Our estimator represents a realization of random variables corresponding to a particular subset  $\Psi_t$  out of all possible subsets. Therefore, exploration is inherent from the variability of randomization scheme. For the sake of illustrating inherent exploration, we purposely generate multiple estimators both for HyRan and LinTS in a given round. Note that both algorithms compute only a single estimator per round. In Figure 1, the points in blue represent the HyRan estimators of  $\beta^*$  from many possible realizations of  $\Psi_t$  due to the randomness of  $h_t$ . For LinTS, the points in orange represent the sampled estimators of  $\beta^*$  from its posterior distribution. We observe that there is enough variability for our estimator as in LinTS.

## 5 MAIN RESULTS

In this section, we present our main theoretical results: the regret bound for HyRan `Bandit` (Theorem 5.1) and the estimation error bound of the proposed HyRan estimator (Theorem 5.4). We first provide the assumptions used throughout the analysis.

**Assumption 1** (Boundedness). For all  $i \in [N]$  and  $t \in [T]$ ,  $\|X_{i,t}\|_2 \leq 1$  and  $\|\beta^*\|_2 \leq 1$ .

**Assumption 2** (Sub-Gaussian noise). For each  $t$  and  $i$ , the

noise  $\eta_{i,t}$  is conditionally  $\sigma$ -sub-Gaussian for a fixed constant  $\sigma \geq 0$ , i.e.,  $\mathbb{E}[\exp(\lambda\eta_{i,t}) | \mathcal{H}_t] \leq \exp(\lambda^2\sigma^2/2)$ , for all  $\lambda \in \mathbb{R}$ .

**Assumption 3** (Context stochasticity). The set of context vectors  $\mathcal{X}_t := \{X_{i,t} \in \mathbb{R}^d : i \in [N]\}$  is independently drawn from unknown distribution  $P_{\mathcal{X}}$  with  $\lambda_{\min}(\mathbb{E}[\frac{1}{N} \sum_{i=1}^N X_{i,t} X_{i,t}^T]) \geq \phi^2 > 0$ , for all  $t$ .

*Discussion of the assumptions.* Assumptions 1 and 2 are standard in the stochastic contextual bandit literature (see e.g. Agrawal and Goyal (2013)). The same or similar assumption to Assumption 3 has been frequently used in the contextual bandit literature (Goldenshluger and Zeevi, 2013; Li et al., 2017; Bastani and Bayati, 2020; Oh et al., 2021; Kim et al., 2021). We emphasize that stochasticity is assumed for the entire context set and that we allow context vectors to be correlated in each round. We also emphasize that even under the stochasticity of contexts, achieving a regret bound sublinear in  $d$  was only possible by resorting to the technique as used in SupLinUCB (Auer, 2002a) and its follow-up works.

The positive-definiteness on the average of the covariance matrix in Assumption 3 can be satisfied regardless of the number of arms - even when  $N = 1$ , e.g., when the context vector (s) is (are) drawn from the Uniform distribution or the truncated Gaussian distribution. Recently, Bastani et al. (2021); Kim et al. (2022) identified the practical cases where Assumption 3 holds. Technically, Assumption 3 is required to obtain the fast convergence rate in estimating linearly parametrized responses in Statistics (see e.g., Bühlmann and Van De Geer (2011)). In our work the assumption is used to obtain the fast convergence rate for the imputation estimator (Lemma B.3).

### 5.1 Regret Bound of HyRan `Bandit`

Under the assumptions above, we present the following regret bound for the HyRan `Bandit` algorithm.

**Theorem 5.1.** Suppose Assumptions 1-3 hold and the total number of rounds  $T$  satisfies

$$T \geq \mathcal{E} = \max \left\{ \frac{8}{p} \log \frac{T}{\delta}, C_{p,\sigma} N^2 \phi^{-4} \log \frac{2T}{\delta} \right\}, \quad (7)$$

where  $C_{p,\sigma} := \frac{8(2-p)}{(1-p)\sqrt{p}} + \frac{\sqrt{2}C\sigma}{p^2} + \frac{8}{\sqrt{p}}$  is a constant depending only on  $p$  and  $\sigma$ . Set  $\lambda_t := d \log \frac{4t^2}{\delta}$ . Then the total regret by time  $T$  for HyRan `Bandit` is bounded by

$$R(T) \leq 2\mathcal{E} + 4D_{p,\sigma} \sqrt{2T \log \frac{1}{\delta}} + 3\delta D_{p,\sigma} + \frac{(16\sqrt{2} + 8) D_{p,\sigma}}{\sqrt{p}} \sqrt{dT \log \frac{2T}{\delta}}, \quad (8)$$

with probability at least  $1 - 8\delta$ , where  $D_{p,\sigma} := 1 + \frac{4\sqrt{2}}{1-p} + \frac{\sigma}{p}$  is a constant depending only on  $p$  and  $\sigma$ .

*Discussion on the regret bound.* The subsampling parameter  $p \in (0, 1)$  in `HyRan Bandit` is chosen independently with respect to  $N$ ,  $d$  or  $T$  and does not affect the rate of our regret bound. The number of rounds  $\mathcal{E}$  defined in (7) is required for the imputation estimator  $\hat{\beta}_t$  to obtain a suitable estimation error bound which is crucial to derive our self-normalized bound for `HyRan` estimator. The number of exploration rounds is  $O(N^2\phi^{-4}\log T)$  which is only logarithmic in  $T$  and is bounded by  $O(\sqrt{dT}\log T)$  when  $\frac{T}{\log T} \geq N^4d^{-1}\phi^{-8}$ . The value of  $\phi^{-2}$  is  $O(d)$  for many standard context distributions (see e.g., Lemma 5.2 in Kim et al. (2022)). As a result, the regret bound of `HyRan Bandit` is  $O(\sqrt{dT}\log T)$ . Our bound is sharper than the existing regret bounds of  $O(\sqrt{dT}\log T\log N) \cdot \text{poly}(\log \log(NT))$  for `VCL-SupLinUCB` (Li et al., 2019) and  $O(\sqrt{dT}\log^{3/2}(NT))$  for `SupLinUCB` (Chu et al., 2011), although direct comparison is not immediate due to difference in the assumptions used. It is important to note that the leading term in our regret bound does not depend on  $N$  while the existing  $\tilde{O}(\sqrt{dT})$  regret bounds all contain  $N$  dependence in their leading terms. To our knowledge, the regret bound in Theorem 5.1 is the fastest rate among linear contextual bandit algorithms. Furthermore, we believe that `HyRan Bandit` is the first method achieving a regret that is sublinear in context dimension *without* using the widely used technique by Auer (2002a) and its variants (e.g., `SupLinUCB`).

Our regret bound in Theorem 5.1 is smaller than the existing lower bounds for the linear contextual bandits in Rusmevichientong and Tsitsiklis (2010); Lattimore and Szepesvári (2020) and Li et al. (2019). This is not a contradiction since the slightly different set of assumptions are used. i.e., Assumptions 3. We discuss this issue in Section 5.3 by proving a lower bound under Assumption 3, which matches with (8) up to a logarithmic factor.

## 5.2 Regret Decomposition

In the analysis of `LinUCB` and `OFUL`, an instantaneous regret is controlled by using the joint maximizer of the reward

$$(a_t, \hat{\beta}_{\text{ucb}}) = \arg \max_{i \in [N], \beta \in \mathcal{C}_t} X_{i,t}^T \beta$$

where  $\mathcal{C}_t$  is a high-probability confidence ellipsoid. Then,  $\text{regret}(t)$  is typically decomposed as

$$\text{regret}(t) \leq \left\| \hat{\beta}_{\text{ucb}} - \beta^* \right\|_{A_t} \|X_{a_t,t}\|_{A_t^{-1}}, \quad (9)$$

where  $A_t := \sum_{\tau=1}^t X_{a_\tau,\tau} X_{a_\tau,\tau}^T + \lambda I$ . Each of the two terms on the right hand side in (9) has a  $\sqrt{d}$  factor. In particular,  $\sqrt{d}$  factor in the first term comes from the radius of  $\mathcal{C}_t$ . Hence, this results in  $O(d)$  regret when combined.

In our work, we introduce new decomposition of regret that allows to avoid multiplicative terms. This decomposition

allows for non-OFU based analysis for sharper dependence on dimensionality.

**Lemma 5.2** (Regret decomposition). *Define the max-residual function for  $x = (x_1, \dots, x_N) \in \mathbb{R}^{d \times N}$  as  $\Delta_{\hat{\beta}}(x) := \max_{i \in [N]} |x_i^T(\hat{\beta} - \beta^*)|$ . For each  $t \in [T]$ , let  $\mathcal{X}_t := (X_{1,t}, \dots, X_{N,t})$  and denote  $\mathcal{G}_t := \cup_{\tau=1}^t \{\mathcal{X}_\tau, \hat{\beta}_\tau\}$ . Then for  $t \geq 1$ ,*

$$\begin{aligned} & \text{regret}(t+1) \\ & \leq 2 \left\{ \Delta_{\hat{\beta}_t}(\mathcal{X}_{t+1}) - \mathbb{E} \left[ \Delta_{\hat{\beta}_t}(\mathcal{X}_{t+1}) \middle| \mathcal{G}_t \right] \right\} \\ & + 2 \left\{ \mathbb{E} \left[ \Delta_{\hat{\beta}_t}(\mathcal{X}_{t+1}) \middle| \mathcal{G}_t \right] - \frac{1}{|\Psi_t|} \sum_{\tau \in \Psi_t} \Delta_{\hat{\beta}_t}(\mathcal{X}_\tau) \right\} \quad (10) \\ & + \frac{2}{\sqrt{|\Psi_t|}} \left\| \hat{\beta}_t - \beta^* \right\|_{V_t}, \end{aligned}$$

where

$$V_t := \sum_{\tau \in \Psi_t} \sum_{i=1}^N X_{i,\tau} X_{i,\tau}^T + \sum_{\tau \notin \Psi_t} X_{a_\tau,\tau} X_{a_\tau,\tau}^T + \lambda_t I.$$

The decomposition of the expected regret given in (10) directly bounds the regret by approximating the max-residual with  $t+1$ -th contexts  $\mathcal{X}_{t+1}$  to that with the average over the contexts in round  $\tau \in \Psi_t$ , which is bounded by the self-normalized bound for `HyRan` estimator. This approximation yields two additive terms: the difference between the max-residual function and its expectation ( $\Delta_{\hat{\beta}_t}(\mathcal{X}_{t+1}) - \mathbb{E} \left[ \Delta_{\hat{\beta}_t}(\mathcal{X}_{t+1}) \middle| \mathcal{G}_t \right]$ ), and the difference between the expectation over the context distribution and its empirical distribution ( $\mathbb{E} \left[ \Delta_{\hat{\beta}_t}(\mathcal{X}_{t+1}) \middle| \mathcal{G}_t \right] - \frac{1}{|\Psi_t|} \sum_{\tau \in \Psi_t} \Delta_{\hat{\beta}_t}(\mathcal{X}_\tau)$ ). The bound becomes tighter as the size of  $\Psi_t$  increases, because we can use more contexts for the approximation.

The decomposition is insightful in that the regret from sub-optimal arm selections is incurred due to poor estimate, thus can be bounded by the quantities involving the maximum residual. To bound the maximum residual, `SupLinUCB` and their variants that achieve  $\tilde{O}(\sqrt{dT})$  regret bound handle the maximum residual with the union of  $N \times T$  probability inequalities, and this gives  $\log N$  term in the regret bound. But in Lemma 5.2, we use the fact that the maximum residual is bounded by a sum of residuals. The sum of residuals can be shown to be bounded by the self-normalized bound for our estimator in (6). This replacement is possible since our novel estimator uses all contexts for some subsampled rounds. In this way, we can use only  $T$  probability inequalities and eliminate the  $N$  independence on the leading term of the regret bound. We emphasize that the decomposition yields the self-normalized bound of our new estimator, not any estimator using the contexts of selected arms only (e.g. ridge estimator for `OFUL`). Our bound is normalized with the hybrid Gram matrix  $V_t$ , not that of selected contexts.

To bound the terms in the decomposed instantaneous regret (10), we see that the first term is bounded by using Azuma’s inequality. We bound the second and third term using Lemma 5.3 and Theorem 5.4, respectively. Lemma 5.3 adopts the empirical theories on the distribution of the contexts.

**Lemma 5.3.** *Suppose Assumptions 1-3 hold. For each  $t \in [T]$ , and  $L > 0$ , conditioned on  $\Psi_t$ , with probability at least  $1 - \delta/T$ ,*

$$\begin{aligned} & \sup_{\|\beta_1 - \beta^*\|_2 \leq L} \left| \mathbb{E}[\Delta_{\beta_1}(\mathcal{X}_{t+1}) | \mathcal{G}_t] - \frac{1}{|\Psi_t|} \sum_{\tau \in \Psi_t} \Delta_{\beta_1}(\mathcal{X}_\tau) \right| \\ & \leq \frac{3L\delta}{2T} + 4L \sqrt{\frac{1}{|\Psi_t|}} \sqrt{d \log \frac{2T}{\delta}}. \end{aligned}$$

In the following theorem, we present the self-normalized bound for the compound estimator which allows us to bound the last term in (10).

**Theorem 5.4** (A self-normalized bound for HyRan estimator). *Suppose Assumptions 1-3 hold. Let  $\hat{\beta}_t$  be the estimator defined in (6) and  $p \in (0, 1)$  be a constant used in (5). Then with probability at least  $1 - 6\delta$ ,*

$$\left\| \hat{\beta}_t - \beta^* \right\|_{V_t} \leq \sqrt{\lambda_t} + \left( \frac{4\sqrt{2}}{1-p} + \frac{\sigma}{p} \right) \sqrt{d \log \frac{4t^2}{\delta}}, \quad (11)$$

for all  $t \geq \max \left\{ \frac{8}{p} \log \frac{T}{\delta}, C_{p,\sigma} N^2 \phi^{-4} \log \frac{2T}{\delta} \right\}$ , where  $C_{p,\sigma} > 0$  is a constant depending only on  $p$  and  $\sigma$ .

Theorem 5.4 is a self-normalized bound for the HyRan estimator, which is a crucial element in our regret analysis. Compared to the widely-used self-normalization bound (Theorem 2 in Abbasi-Yadkori et al. (2011)) in the contextual bandit literature, the estimation error bound (11) is self-normalized by the covariance matrix constructed by the contexts of all arms, not just selected contexts. The self-normalized bound is derived by using the pairs of pseudo reward  $\tilde{Y}_{i,\tau}$  defined in (3) and contexts  $X_{i,\tau}$  for all arms  $i \in [N]$  and  $\tau \in \Psi_t$ , instead of using just the pairs of selected arms. The full usage of pseudo rewards and contexts enables us to take advantage of the new decomposition of the regret in (10), which derives a  $O(\sqrt{dT \log T})$  regret bound.

The last concern regarding our regret bound is the size of  $\Psi_t$ . To obtain a regret bound sublinear to  $T$ , we need to make sure that the sum of the subsampled rounds satisfies  $\sum_{t=1}^T |\Psi_t|^{-1/2} = O(\sqrt{T})$ . In the following Lemma, we show this by proving that the size of the selected subset  $\Psi_t$  is  $\Omega(t)$  with high probability.

**Lemma 5.5.** *Let  $\Psi_t$  be a subset of  $[t]$  determined by the Algorithm 1 at round  $t$ . For any  $\epsilon \in (0, 1)$ , with probability at least  $1 - \delta$ ,*

$$|\Psi_t| \geq \epsilon pt, \quad (12)$$

for all  $t \geq \frac{2}{p(1-\epsilon)^2} \log \frac{T}{\delta}$ .

With (12), we guarantee the rate of the regret bound is sublinear with respect to the total round  $T$ .

### 5.3 Matching Lower Bound

Regarding the lower bounds of the linear contextual bandit, a  $\Omega(d\sqrt{T})$  bound has been proven for linear bandits with infinitely many arms (Dani et al., 2008; Rusmevichientong and Tsitsiklis, 2010; Lattimore and Szepesvári, 2020). When the number of arms is finite, the derived lower bound of the cumulative regret is  $\Omega(\sqrt{dT})$  (Chu et al., 2011). Recently in Li et al. (2019), a lower bound  $\Omega(\sqrt{dT \log T \log N})$  was shown when  $N \leq 2^{d/2}$ . These lower bounds are derived by finding the settings of contexts and parameters that make the algorithm difficult to reduce the regret. However, the problem settings of the existing lower bounds do not satisfy Assumptions 3 in our problem setting. In the following theorem, we prove a lower bound which is valid under Assumptions 1-3.

**Theorem 5.6.** *Assume  $2 \leq d \leq N < \infty$  and  $T \geq d/4$ . Then there exists a distribution of contexts,  $\mathcal{P}_{\mathcal{X}}$ , a distribution of noise,  $\eta_{i,t}$  and  $\beta^*$ , which satisfies Assumptions 1-3 and for any bandit algorithms that selects  $a_t$ ,*

$$\mathbb{E}_{\beta^*} R(T) \geq \frac{1}{8} \sqrt{dT}. \quad (13)$$

We prove that the rate of  $\Omega(\sqrt{dT})$  cannot be improved even under the stochastic assumptions on contexts (e.g., Assumption 3). The lower bound in Theorem 5.6 matches with our regret upper bound for HyRan Bandit established in Theorem 5.1 up to the logarithmic factor. Therefore, our proposed algorithm HyRan Bandit is provably near-optimal, i.e., optimal up to the logarithmic factor. To our knowledge, all of the existing near-optimal linear contextual bandit algorithms are based on the framework of Auer (2002a) (e.g., SupLinUCB and VCL-SupLinUCB). Our proposed algorithm is the first algorithm that achieves near-optimality without relying on this existing framework.

Despite the lower bound is derived under Assumption 3 related to the factor  $\phi > 0$ , our lower bound (13) does not have  $\phi$ . This is because the lower bound depends only on the number of orthogonal vectors in the contexts space  $\mathbb{R}^d$ , not the value of  $\phi > 0$ .

## 6 NUMERICAL EXPERIMENTS

In this section, we compare the performances of the five linear contextual bandit algorithms: SupLinUCB (Chu et al., 2011), LinUCB (Li et al., 2010), LinTS (Agrawal and Goyal, 2013), DRTS (Kim et al., 2021) and our proposed method, HyRan Bandit. For simulation, the number of arms  $N$  is set to 10 or 20, and the dimension of contexts  $d$  is set to 5,

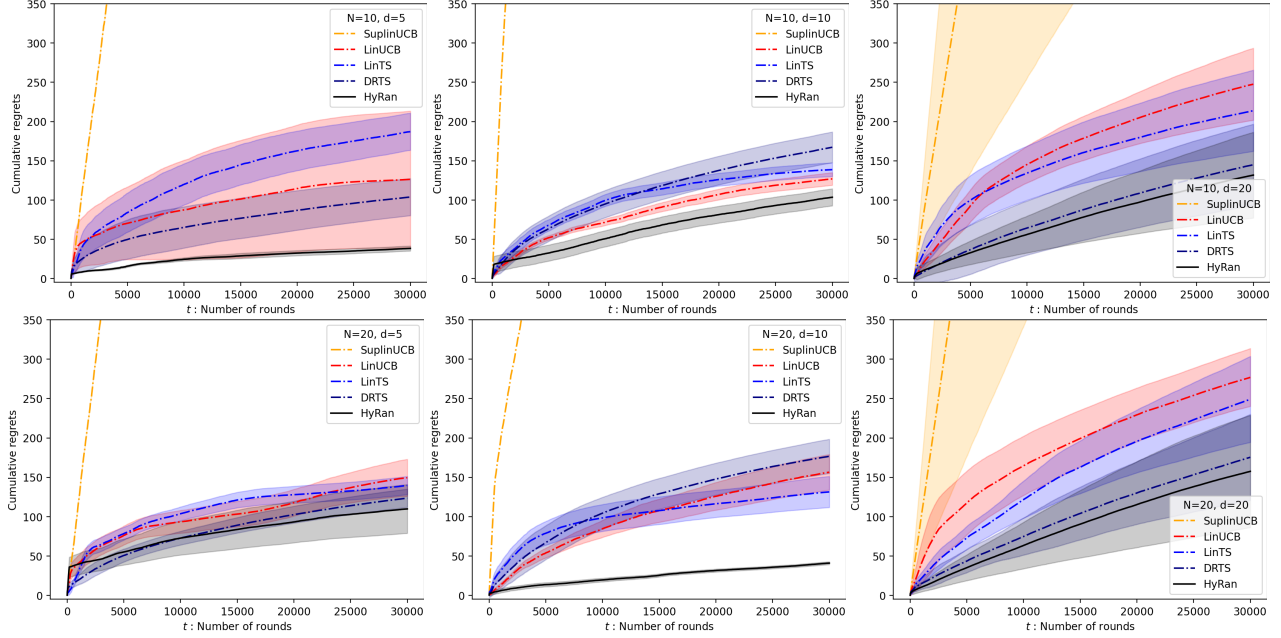


Figure 2: A comparison of cumulative regrets of SupLinUCB, LinTS, LinUCB, DRTS and HyRan Bandit. Each curve shows the cumulative regret as a function of rounds, averaged over 20 repeated experiments. The scale of  $y$ -axis is set to be equivalent in each row for the comparison of the regret as  $d$  increases. The standard deviations of SupLinUCB in  $d = 5$  and  $d = 10$  are too large to present and omitted.

10 and 20. Let  $X_{i,t}^{(1)}, \dots, X_{i,t}^{(d)}$  be the  $d$  elements of a context  $X_{i,t}$ . For  $j = 1, \dots, d-1$ , we independently generate  $(X_{1,t}^{(j)}, \dots, X_{N,t}^{(j)})$  from a normal distribution  $\mathcal{N}(\mu_N, V_N)$  with mean  $\mu_{10} = (-10, -8, \dots, -2, 2, \dots, 8, -10)^T$ , or  $\mu_{20} = (-20, -18, \dots, -2, 2, \dots, 18, 20)^T$ . To impose correlation among each arms the covariance matrix  $V_N \in \mathbb{R}^{N \times N}$  is set as  $V(i, i) = 1$  for every  $i$  and  $V(i, k) = 0.5$  for every  $i \neq k$ . Then, for each arm  $i \in [N]$ , we randomly select a generated element  $X_{i,t}^{(j)}$  and append it to the last element, i.e.  $X_{i,t}^{(d)}$  is the same as one of  $X_{i,t}^{(1)}, \dots, X_{i,t}^{(d-1)}$ . This setting is to impose a severe multicollinearity on each contexts. Finally, we truncated the sampled contexts to satisfy  $\|X_{i,t}\|_2 \leq 1$ . To generate the stochastic rewards, we sample  $\eta_{i,t}$  independently from  $\mathcal{N}(0, 1)$ . Each element of  $\beta^*$  is sampled from a uniform distribution,  $\mathcal{U}(-1/\sqrt{d}, 1/\sqrt{d})$  at the beginning of each instance and stays fixed during experiments. About the set of hyperparameters, LinTS, LinUCB, SupLinUCB and DRTS searches  $\alpha$  (or  $v$ ) in  $\{0.001, 0.01, 0.1, 1\}$ . In HyRan Bandit we set  $\lambda_t := d \log(t+1)^2$  to be consistent with the theoretical results and  $p$  to be in  $\{0.5, 0.65, 0.8, 0.95\}$ . We optimize the hyperparameters over the grid set and report the best performance for each algorithm. Figure 2 shows the average of the cumulative regrets over the horizon length  $T = 30000$  with 20 repeated experiments. The experimental results demonstrate that HyRan Bandit performs better than the benchmarks in all of the cases and shows superior performances as the context dimension increases. The worst performance of

SupLinUCB is mainly because its estimator does not include rewards in exploitation rounds.

## 7 CONCLUSION

We address a long-standing research question of whether a practical algorithm can achieve near-optimality for linear contextual bandits. We show that our proposed algorithm achieves  $\tilde{O}(\sqrt{dT})$  regret upper bound which matches the lower bound under our problem setting. We empirically evaluate our algorithm to support our theoretical claims and show that the practical performance of our algorithm outperforms the existing methods, hence achieving both provable near-optimality and practicality.

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## A MISSING PROOFS

### A.1 Technical lemmas

**Lemma A.1.** *Lee et al. (2016, Lemma 2.3)* Let  $\{N_t\}$  be a martingale on a Hilbert space  $(\mathcal{H}, \|\cdot\|_{\mathcal{H}})$ . Then there exists a  $\mathbb{R}^2$ -valued martingale  $\{M_t\}$  such that for any time  $t \geq 0$ ,  $\|M_t\|_2 = \|N_t\|_{\mathcal{H}}$  and  $\|M_{t+1} - M_t\|_2 = \|N_{t+1} - N_t\|_{\mathcal{H}}$ .

**Lemma A.2.** (Azuma-Hoeffding) If a super-martingale  $(Y_t; t \geq 0)$  corresponding to filtration  $\mathcal{F}_t$ , satisfies  $|Y_t - Y_{t-1}| \leq c_t$  for some constant  $c_t$ , for all  $t = 1, \dots, T$ , then for any  $a \geq 0$ ,

$$\mathbb{P}(Y_T - Y_0 \geq a) \leq e^{-\frac{a^2}{2 \sum_{t=1}^T c_t^2}}.$$

### A.2 Proof of Theorem 5.1

*Proof.* [Step 1. Regret decomposition] For each  $t \in [T]$ , define the event

$$\begin{aligned} A_t &:= \left\{ |\Psi_t| > \frac{1}{2}pt \right\}, \\ B_t &:= \left\{ \left\| \widehat{\beta}_t - \beta^* \right\|_{V_t} \leq \sqrt{\lambda_t} + \left( \frac{4\sqrt{2}}{1-p} + \frac{\sigma}{p} \right) \sqrt{d \log \frac{4t^2}{\delta}} \right\}, \\ C_t &:= \left\{ \left\| \widehat{\beta}_t - \beta^* \right\|_2 \leq 1 + \frac{4\sqrt{2}}{1-p} + \frac{\sigma}{p} := D_{p,\sigma} \right\}. \end{aligned}$$

The three events have an explicit relationship as follows: In the proof of Theorem 5.4, Lemma 5.5 and Lemma A.3, the event  $B_t$  requires  $A_t$ , i.e.  $A_t \subseteq B_t$ . Under the event  $B_t$ , setting  $\lambda_t = d \log \frac{4t^2}{\delta}$  gives

$$\begin{aligned} \left\| \widehat{\beta}_t - \beta^* \right\|_2 &\leq \sqrt{\left( \widehat{\beta}_t - \beta^* \right)^T V_t^{-\frac{1}{2}} V_t^{-1} V_t^{\frac{1}{2}} \left( \widehat{\beta}_t - \beta^* \right)} \\ &\leq \sqrt{\lambda_{\max}(V_t^{-1})} \left\| \widehat{\beta}_t - \beta^* \right\|_{V_t} \\ &\leq \lambda_t^{-\frac{1}{2}} \left( \sqrt{\lambda_t} + \left( \frac{4\sqrt{2}}{1-p} + \frac{\sigma}{p} \right) \sqrt{d \log \frac{4t^2}{\delta}} \right) \\ &\leq D_{p,\sigma}, \end{aligned}$$

which implies  $C_t$ . Set  $\mathcal{E} := \max \left\{ \frac{8}{p} \log \frac{T}{\delta}, C_{p,\sigma} N^2 \phi^{-4} \log \frac{2T}{\delta} \right\}$ , where  $C_{p,\sigma}$  is defined in (25). By Theorem 5.4 we have

$$\mathbb{P} \left( \bigcap_{t \geq \mathcal{E}} \{A_t \cap B_t \cap C_t\} \right) \geq 1 - 6\delta. \quad (14)$$

By Lemma 5.2, for each  $t \geq \mathcal{E}$ ,

$$\begin{aligned} \text{regret}(t) &\leq 2 \left\{ \Delta_{\widehat{\beta}_{t-1}}(\mathcal{X}_t) - \mathbb{E} \left[ \Delta_{\widehat{\beta}_{t-1}}(\mathcal{X}_t) \middle| \mathcal{G}_{t-1} \right] \right\} \\ &\quad + 2 \left\{ \mathbb{E} \left[ \Delta_{\widehat{\beta}_{t-1}}(\mathcal{X}_t) \middle| \mathcal{G}_{t-1} \right] - \frac{1}{|\Psi_{t-1}|} \sum_{\tau \in \Psi_{t-1}} \Delta_{\widehat{\beta}_{t-1}}(\mathcal{X}_\tau) \right\} \\ &\quad + \frac{2}{\sqrt{|\Psi_{t-1}|}} \left\| \beta^* - \widehat{\beta}_{t-1} \right\|_{V_{t-1}}. \end{aligned}$$

Let

$$\begin{aligned}
 R_1(t) &:= 2 \left\{ \Delta_{\hat{\beta}_{t-1}}(\mathcal{X}_t) - \mathbb{E} \left[ \Delta_{\hat{\beta}_{t-1}}(\mathcal{X}_t) \middle| \mathcal{G}_{t-1} \right] \right\}, \\
 R_2(t) &:= 2 \left\{ \mathbb{E} \left[ \Delta_{\hat{\beta}_{t-1}}(\mathcal{X}_t) \middle| \mathcal{G}_{t-1} \right] - \frac{1}{|\Psi_{t-1}|} \sum_{\tau \in \Psi_{t-1}} \Delta_{\hat{\beta}_{t-1}}(\mathcal{X}_\tau) \right\}, \\
 R_3(t) &:= \frac{2}{\sqrt{|\Psi_{t-1}|}} \left\| \beta^* - \hat{\beta}_{t-1} \right\|_{V_{t-1}}.
 \end{aligned} \tag{15}$$

[Step 2. Bounding  $R_1(t)$ ] Let us bound  $R_1(t)$ . Since the event  $C_t$  is  $\mathcal{G}_t$ -measurable for each  $t \in [T]$ , we have

$$R_1(t)\mathbb{I}(C_{t-1}) = 2 \left\{ \Delta_{\hat{\beta}_{t-1}}(\mathcal{X}_t)\mathbb{I}(C_{t-1}) - \mathbb{E} \left[ \Delta_{\hat{\beta}_{t-1}}(\mathcal{X}_t)\mathbb{I}(C_{t-1}) \middle| \mathcal{G}_{t-1} \right] \right\}.$$

By Assumption 1,

$$\begin{aligned}
 \Delta_{\hat{\beta}_{t-1}}(\mathcal{X}_t)\mathbb{I}(C_{t-1}) &:= \max_{i \in [N]} \left| X_{i,t}^T (\hat{\beta}_{t-1} - \beta^*) \right| \mathbb{I}(C_{t-1}) \\
 &\leq \max_{i \in [N]} \|X_{i,t}\|_2 \left\| \hat{\beta}_{t-1} - \beta^* \right\|_2 \mathbb{I}(C_{t-1}) \\
 &\leq \left\| \hat{\beta}_{t-1} - \beta^* \right\|_2 \mathbb{I}(C_{t-1}) \\
 &\leq D_{p,\sigma}.
 \end{aligned}$$

Thus,  $|R_1(t)\mathbb{I}(C_{t-1})| \leq 4D_{p,\sigma}$ . Since  $R_1(t)\mathbb{I}(C_{t-1})$  is  $\mathcal{G}_t$ -measurable and

$$\mathbb{E} [R_1(t)\mathbb{I}(C_{t-1}) | \mathcal{G}_{t-1}] = 0,$$

we can use Lemma A.2 to have

$$\sum_{t > \mathcal{E}} R_1(t)\mathbb{I}(C_{t-1}) \leq 4D_{p,\sigma} \sqrt{2T \log \frac{1}{\delta}}, \tag{16}$$

with probability at least  $1 - \delta$ .

[Step 3. Bounding  $R_2(t)$ ] Now we bound  $R_2(t)$ . By Lemma 5.3 with probability at least  $1 - \delta/T$ ,

$$\begin{aligned}
 R_2(t)\mathbb{I}(A_{t-1} \cap C_{t-1}) &\leq 2\mathbb{I}(A_{t-1}) \sup_{\|\beta_1 - \beta^*\|_2 \leq D_{p,\sigma}} \left| \mathbb{E} [\Delta_{\beta_1}(\mathcal{X}_t) | \mathcal{G}_{t-1}] - \frac{1}{|\Psi_{t-1}|} \sum_{\tau \in \Psi_{t-1}} \Delta_{\beta_1}(\mathcal{X}_\tau) \right| \\
 &\leq \left( \frac{3\delta D_{p,\sigma}}{T} + 8D_{p,\sigma} \sqrt{\frac{1}{|\Psi_{t-1}|}} \sqrt{d \log \frac{2T}{\delta}} \right) \mathbb{I}(A_{t-1}) \\
 &\leq \frac{3\delta D_{p,\sigma}}{T} + 8D_{p,\sigma} \sqrt{\frac{2}{pt}} \sqrt{d \log \frac{2T}{\delta}}.
 \end{aligned}$$

Thus, with probability at least  $1 - \delta$ ,

$$\sum_{t > \mathcal{E}} R_2(t)\mathbb{I}(A_{t-1} \cap C_{t-1}) \leq 3\delta D_{p,\sigma} + \frac{16\sqrt{2}D_{p,\sigma}}{\sqrt{p}} \sqrt{dT \log \frac{2T}{\delta}}. \tag{17}$$

[Step 4. Bounding  $R_3(t)$ ] To bound  $R_3(t)$ ,

$$\begin{aligned}
 R_3(t)\mathbb{I}(A_{t-1} \cap B_{t-1}) &\leq \frac{2\sqrt{2}}{\sqrt{pt}} \left( 1 + \frac{4C}{1-p} + \frac{\sigma}{p} \right) \sqrt{d \log \frac{4t^2}{\delta}} \\
 &= \frac{2\sqrt{2}}{\sqrt{pt}} D_{p,\sigma} \sqrt{d \log \frac{4t^2}{\delta}}.
 \end{aligned}$$

and

$$\sum_{t>\mathcal{E}} R_3(t) \mathbb{I}(A_{t-1} \cap B_{t-1}) \leq \frac{8D_{p,\sigma}}{\sqrt{p}} \sqrt{dT \log \frac{2T}{\delta}}, \quad (18)$$

holds almost surely.

[Step 5. Collecting the bounds] For any  $x > 2\mathcal{E}$ ,

$$\begin{aligned} \mathbb{P}(R(T) > x) &\leq \mathbb{P}\left(2\mathcal{E} + \sum_{t>\mathcal{E}} \text{regret}(t) > x\right) \\ &= \mathbb{P}\left(2\mathcal{E} + \sum_{t>\mathcal{E}} R_1(t) + R_2(t) + R_3(t) > x\right) \\ &\leq \mathbb{P}\left(2\mathcal{E} + \sum_{t>\mathcal{E}} R_1(t) \mathbb{I}(C_{t-1}) + R_2(t) \mathbb{I}(A_{t-1} \cap C_{t-1}) + R_3(t) \mathbb{I}(A_{t-1} \cap B_{t-1}) > x\right) \\ &\quad + \mathbb{P}\left(\bigcup_{t \geq \mathcal{E}} \{A_t^c \cup B_t^c \cup C_t^c\}\right) \\ &\leq \mathbb{P}\left(2\mathcal{E} + \sum_{t>\mathcal{E}} R_1(t) \mathbb{I}(C_{t-1}) + R_2(t) \mathbb{I}(A_{t-1} \cap C_{t-1}) + R_3(t) \mathbb{I}(A_{t-1} \cap B_{t-1}) > x\right) \\ &\quad + 6\delta, \end{aligned}$$

where the last inequality holds due to (14). Setting

$$x = 2\mathcal{E} + 4D_{p,\sigma} \sqrt{2T \log \frac{1}{\delta}} + 3\delta D_{p,\sigma} + \frac{16\sqrt{2}D_{p,\sigma}}{\sqrt{p}} \sqrt{dT \log \frac{2T}{\delta}} + \frac{8D_{p,\sigma}}{\sqrt{p}} \sqrt{dT \log \frac{2T}{\delta}},$$

gives

$$\begin{aligned} \mathbb{P}(R(T) > x) &\leq 6\delta + \mathbb{P}\left(\sum_{t>\mathcal{E}} R_1(t) \mathbb{I}(C_{t-1}) > 4D_{p,\sigma} \sqrt{2T \log \frac{1}{\delta}}\right) \\ &\quad + \mathbb{P}\left(\sum_{t>\mathcal{E}} R_2(t) \mathbb{I}(A_{t-1} \cap C_{t-1}) > 3\delta D_{p,\sigma} + \frac{16\sqrt{2}D_{p,\sigma}}{\sqrt{p}} \sqrt{dT \log \frac{2T}{\delta}}\right) \\ &\quad + \mathbb{P}\left(\sum_{t>\mathcal{E}} R_3(t) \mathbb{I}(A_{t-1} \cap C_{t-1}) > \frac{8D_{p,\sigma}}{\sqrt{p}} \sqrt{dT \log \frac{2T}{\delta}}\right) \\ &\leq 8\delta, \end{aligned}$$

where the inequality holds due to (15)-(18).  $\square$

### A.3 Proof of Lemma 5.2

*Proof.* By the definition of  $a_t$ , we have

$$\begin{aligned} \text{regret}(t+1) &= \left(X_{a_{t+1}^*, t+1} - X_{a_{t+1}, t+1}\right)^T (\beta^* - \hat{\beta}_t) + \left(X_{a_{t+1}^*, t+1} - X_{a_{t+1}, t+1}\right)^T \hat{\beta}_t \\ &\leq \left(X_{a_{t+1}^*, t+1} - X_{a_{t+1}, t+1}\right)^T (\beta^* - \hat{\beta}_t) \\ &\leq 2 \max_{i \in [N]} \left|X_{i, t+1}^T (\hat{\beta}_t - \beta^*)\right|, \end{aligned}$$

which gives  $\text{regret}(t+1) \leq 2\Delta_{\hat{\beta}_t}(\mathcal{X}_{t+1})$ . Adding and subtracting  $\mathbb{E}\left[\Delta_{\hat{\beta}_t}(\mathcal{X}_{t+1}) \mid \mathcal{G}_t\right]$  and  $\frac{1}{|\Psi_t|} \sum_{\tau \in \Psi_t} \Delta_{\hat{\beta}_t}(\mathcal{X}_\tau)$ , we only need to show,

$$\frac{1}{|\Psi_t|} \sum_{\tau \in \Psi_t} \Delta_{\hat{\beta}_t}(\mathcal{X}_\tau) \leq \frac{1}{\sqrt{|\Psi_t|}} \left\| \hat{\beta}_t - \beta^* \right\|_{V_t},$$

for (10). By the Cauchy-Schwartz inequality,

$$\begin{aligned}
 \sum_{\tau \in \Psi_t} \Delta_{\hat{\beta}_t}(\mathcal{X}_\tau) &\leq \sqrt{|\Psi_t|} \sqrt{\sum_{\tau \in \Psi_t} \left\{ \Delta_{\hat{\beta}_t}(\mathcal{X}_\tau) \right\}^2} \\
 &= \sqrt{|\Psi_t|} \sqrt{\sum_{\tau \in \Psi_t} \max_{i \in [N]} \left\{ X_{i,\tau}^T (\hat{\beta}_t - \beta^*) \right\}^2} \\
 &\leq \sqrt{|\Psi_t|} \sqrt{\sum_{\tau \in \Psi_t} \sum_{i=1}^N \left\{ X_{i,\tau}^T (\hat{\beta}_t - \beta^*) \right\}^2} \\
 &\leq \sqrt{|\Psi_t|} \sqrt{(\hat{\beta}_t - \beta^*)^T V_t (\hat{\beta}_t - \beta^*)},
 \end{aligned}$$

where the last inequality holds with the fact that  $V_t \succeq \sum_{\tau \in \Psi_t} \sum_{i=1}^N X_{i,\tau} X_{i,\tau}^T$ .  $\square$

#### A.4 Proof of Lemma 5.3

*Proof.* Let us fix  $t \in [T]$  and  $\Psi_t \subseteq [t]$ . By Assumption 3,  $\mathcal{X}_t$  is independent with  $\mathcal{G}_{t-1}$ . Thus,

$$\mathbb{E}[\Delta_{\beta_1}(\mathcal{X}_t) | \mathcal{G}_{t-1}] = \mathbb{E}_X[\Delta_{\beta_1}(X)],$$

where  $X \in \mathbb{R}^{d \times N}$  arises from  $P_X$  defined in Assumption 3. For any  $x > 0$  and  $\theta > 0$ ,

$$\begin{aligned}
 &\mathbb{P} \left( \sup_{\|\beta_1 - \beta^*\|_2 \leq L} \left| \mathbb{E}[\Delta_{\beta_1}(\mathcal{X}_t) | \mathcal{G}_{t-1}] - \frac{1}{|\Psi_t|} \sum_{\tau \in \Psi_t} \Delta_{\beta_1}(\mathcal{X}_\tau) \right| > x \mid \Psi_t \right) \\
 &\leq \exp(-\theta x) \mathbb{E} \left[ \exp \left( \theta \sup_{\|\beta_1 - \beta^*\|_2 \leq L} \left| \mathbb{E}_X[\Delta_{\beta_1}(\mathcal{X}_t)] - \frac{1}{|\Psi_t|} \sum_{\tau \in \Psi_t} \Delta_{\beta_1}(\mathcal{X}_\tau) \right| \right) \mid \Psi_t \right].
 \end{aligned}$$

Let  $\tau_1 \leq \tau_2, \dots \leq \tau_{|\Psi_t|}$  be an ordered round in  $\Psi_t$ . Then by Assumption 3,  $\mathcal{X}_{\tau_1}, \dots, \mathcal{X}_{\tau_{|\Psi_t|}}$  are IID random variables and we can use the symmetrization lemma (van der Vaart and Wellner, 1996, Lemma 2.3.1) to have

$$\begin{aligned}
 &\mathbb{E} \left[ \exp \left( \theta \sup_{\|\beta_1 - \beta^*\|_2 \leq L} \left| \mathbb{E}_X[\Delta_{\beta_1}(\mathcal{X}_t)] - \frac{1}{|\Psi_t|} \sum_{\tau \in \Psi_t} \Delta_{\beta_1}(\mathcal{X}_\tau) \right| \right) \right] \\
 &\leq \mathbb{E} \left[ \exp \left( 2\theta \sup_{\|\beta_1 - \beta^*\|_2 \leq L} \left| \frac{1}{|\Psi_t|} \sum_{n=1}^{|\Psi_t|} \xi_n \Delta_{\beta_1}(\mathcal{X}_{\tau_n}) \right| \right) \right], \tag{19}
 \end{aligned}$$

where  $\xi_1, \dots, \xi_{|\Psi_t|}$  are independent Rademacher random variables. For any  $\epsilon > 0$  let  $\tilde{\beta}_1, \dots, \tilde{\beta}_{\Theta(\epsilon)}$  be the  $\epsilon$ -cover of  $\mathcal{B} := \{\beta_1 \in \mathbb{R}^d : \|\beta_1 - \beta^*\|_2 \leq L\}$ . By the definition of  $\epsilon$ -cover, for each  $\beta_1 \in \mathcal{B}$ , there exists  $\tilde{\beta}_j$  such that  $\|\tilde{\beta}_j - \beta_1\|_2 \leq \epsilon$ . Thus,

$$\begin{aligned}
 \left| \sum_{n=1}^{|\Psi_t|} \xi_n \Delta_{\beta_1}(\mathcal{X}_{\tau_n}) \right| &\leq \left| \sum_{n=1}^{|\Psi_t|} \xi_n \left\{ \Delta_{\beta_1}(\mathcal{X}_{\tau_n}) - \Delta_{\tilde{\beta}_j}(\mathcal{X}_{\tau_n}) \right\} \right| + \left| \sum_{n=1}^{|\Psi_t|} \xi_n \Delta_{\tilde{\beta}_j}(\mathcal{X}_{\tau_n}) \right| \\
 &\leq \sum_{n=1}^{|\Psi_t|} \left| \Delta_{\beta_1}(\mathcal{X}_{\tau_n}) - \Delta_{\tilde{\beta}_j}(\mathcal{X}_{\tau_n}) \right| + \left| \sum_{n=1}^{|\Psi_t|} \xi_n \Delta_{\tilde{\beta}_j}(\mathcal{X}_{\tau_n}) \right|.
 \end{aligned}$$

By the definition of  $\Delta_{\beta_1}(\mathcal{X}_{\tau_n})$  and Assumption 1,

$$\begin{aligned}
 \left| \Delta_{\beta_1}(\mathcal{X}_{\tau_n}) - \Delta_{\tilde{\beta}_j}(\mathcal{X}_{\tau_n}) \right| &= \left| \max_i |X_{i,\tau_n}^T (\beta^* - \beta_1)| - \max_i |X_{i,\tau_n}^T (\beta^* - \tilde{\beta}_j)| \right| \\
 &\leq \max_i \left| |X_{i,\tau_n}^T (\beta^* - \beta_1)| - |X_{i,\tau_n}^T (\beta^* - \tilde{\beta}_j)| \right| \\
 &\leq \max_i |X_{i,\tau_n}^T (\beta_1 - \tilde{\beta}_j)| \\
 &\leq \max_i \|X_{i,\tau_n}\|_2 \|\beta_1 - \tilde{\beta}_j\|_2 \\
 &\leq \epsilon.
 \end{aligned}$$

Thus,

$$\sup_{\|\beta_1 - \beta^*\|_2 \leq L} \left| \sum_{n=1}^{|\Psi_t|} \xi_n \Delta_{\beta_1}(\mathcal{X}_{\tau_n}) \right| \leq |\Psi_t| \epsilon + \sup_{j=1, \dots, \Theta(\epsilon)} \left| \sum_{n=1}^{|\Psi_t|} \xi_n \Delta_{\tilde{\beta}_j}(\mathcal{X}_{\tau_n}) \right|.$$

Plugging in (19) gives

$$\begin{aligned}
 &\mathbb{P} \left( \sup_{\|\beta_1 - \beta^*\|_2 \leq L} \left| \mathbb{E}[\Delta_{\beta_1}(\mathcal{X}_t) | \mathcal{G}_{t-1}] - \frac{1}{|\Psi_t|} \sum_{\tau \in \Psi_t} \Delta_{\beta_1}(\mathcal{X}_\tau) \right| > x \mid \Psi_t \right) \\
 &\leq \exp(-\theta x + \theta \epsilon) \mathbb{E} \left[ \exp \left( \frac{2\theta}{|\Psi_t|} \sup_{j=1, \dots, \Theta(\epsilon)} \left| \sum_{n=1}^{|\Psi_t|} \xi_n \Delta_{\tilde{\beta}_j}(\mathcal{X}_{\tau_n}) \right| \right) \mid \Psi_t \right] \\
 &\leq \exp(-\theta x + \theta \epsilon) \sum_{j=1}^{\Theta(\epsilon)} \mathbb{E} \left[ \exp \left( \frac{2\theta}{|\Psi_t|} \left| \sum_{n=1}^{|\Psi_t|} \xi_n \Delta_{\tilde{\beta}_j}(\mathcal{X}_{\tau_n}) \right| \right) \mid \Psi_t \right].
 \end{aligned}$$

Observe that for each  $j = 1, \dots, \Theta(\epsilon)$ ,

$$\left| \Delta_{\tilde{\beta}_j}(\mathcal{X}_{\tau_n}) \right| \leq \max_i \|X_{i,\tau_n}\|_2 \|\beta^* - \tilde{\beta}_j\|_2 \leq L.$$

Then by Hoeffding's Lemma,

$$\begin{aligned}
 &\mathbb{E} \left[ \exp \left( \frac{2\theta}{|\Psi_t|} \left| \sum_{n=1}^{|\Psi_t|} \xi_n \Delta_{\tilde{\beta}_j}(\mathcal{X}_{\tau_n}) \right| \right) \mid \Psi_t \right] \\
 &= \mathbb{E} \left[ \exp \left( \frac{2\theta}{|\Psi_t|} \left| \sum_{n=1}^{|\Psi_t|} \xi_n \Delta_{\tilde{\beta}_j}(\mathcal{X}_{\tau_n}) \right| \right) \mid \{X(\tau_n)\}_{n=1}^{|\Psi_t|}, \Psi_t \right] \\
 &= \mathbb{E} \prod_{n=1}^{|\Psi_t|} \mathbb{E} \left[ \exp \left( \frac{2\theta}{|\Psi_t|} \xi_n \Delta_{\tilde{\beta}_j}(\mathcal{X}_{\tau_n}) \right) \mid \{X(\tau_n)\}_{n=1}^{|\Psi_t|}, \Psi_t \right] \\
 &\leq \exp \left( \frac{2\theta^2 L^2}{|\Psi_t|} \right).
 \end{aligned}$$

Thus,

$$\begin{aligned}
 &\mathbb{P} \left( \sup_{\|\beta_1 - \beta^*\|_2 \leq L} \left| \mathbb{E}[\Delta_{\beta_1}(\mathcal{X}_t) | \mathcal{G}_{t-1}] - \frac{1}{|\Psi_t|} \sum_{\tau \in \Psi_t} \Delta_{\beta_1}(\mathcal{X}_\tau) \right| > x \mid \Psi_t \right) \\
 &\leq \exp(-\theta x + \theta \epsilon) 2\Theta(\epsilon) \exp \left( \frac{2\theta^2 L^2}{|\Psi_t|} \right) \\
 &= 2\Theta(\epsilon) \exp \left\{ -\theta(x - \epsilon) + \frac{2\theta^2 L^2}{|\Psi_t|} \right\}.
 \end{aligned}$$

Minimizing with respect to  $\theta > 0$  gives,

$$\begin{aligned} & \mathbb{P} \left( \sup_{\|\beta_1 - \beta^*\|_2 \leq L} \left| \mathbb{E}[\Delta_{\beta_1}(\mathcal{X}_t) | \mathcal{G}_{t-1}] - \frac{1}{|\Psi_t|} \sum_{\tau \in \Psi_t} \Delta_{\beta_1}(\mathcal{X}_\tau) \right| > x \mid \Psi_t \right) \\ & \leq 2\Theta(\epsilon) \exp \left\{ -\frac{|\Psi_t| (x - \epsilon)^2}{8L^2} \right\}. \end{aligned}$$

The covering number of  $\mathcal{B}$  is bounded by  $\Theta(\epsilon) \leq (\frac{3L}{\epsilon})^d$ . Thus, with probability at least  $1 - \delta/T$ ,

$$\begin{aligned} \sup_{\|\beta_1 - \beta^*\|_2 \leq L} \left| \mathbb{E}[\Delta_{\beta_1}(\mathcal{X}_t) | \mathcal{G}_{t-1}] - \frac{1}{|\Psi_t|} \sum_{\tau \in \Psi_t} \Delta_{\beta_1}(\mathcal{X}_\tau) \right| & \leq \epsilon + L \sqrt{\frac{8}{|\Psi_t|}} \sqrt{\log \frac{2\Theta(\epsilon)T}{\delta}} \\ & \leq \epsilon + L \sqrt{\frac{8}{|\Psi_t|}} \sqrt{d \log \frac{3L}{\epsilon} + \log \frac{2T}{\delta}}. \end{aligned}$$

Setting  $\epsilon = 3L\delta/(2T)$  gives,

$$\begin{aligned} \sup_{\|\beta_1 - \beta^*\|_2 \leq L} \left| \mathbb{E}[\Delta_{\beta_1}(\mathcal{X}_t) | \mathcal{G}_{t-1}] - \frac{1}{|\Psi_t|} \sum_{\tau \in \Psi_t} \Delta_{\beta_1}(\mathcal{X}_\tau) \right| & \leq \frac{3L\delta}{2T} + L \sqrt{\frac{8}{|\Psi_t|}} \sqrt{d \log \frac{2T}{\delta} + \log \frac{2T}{\delta}} \\ & \leq \frac{3L\delta}{2T} + 4L \sqrt{\frac{1}{|\Psi_t|}} \sqrt{d \log \frac{2T}{\delta}}. \end{aligned}$$

□

## A.5 Proof of Theorem 5.4

### A.5.1 A bound for the imputation estimator

To prove Theorem 5.4, we need to prove the following bound for the imputation estimator  $\check{\beta}_t$  which is used in  $\tilde{Y}_{i,t}$  and  $\hat{\beta}_t$ . The proposed imputation estimator is used to obtain the bound (21) exploiting Assumptions 1-3.

**Lemma A.3.** *Suppose Assumptions 1-3 hold. Let*

$$\begin{aligned} \check{\beta}_t := & \left( \sum_{\tau \in \Psi_t} \sum_{i=1}^N X_{i,\tau} X_{i,\tau}^T + \sum_{\tau \notin \Psi_t} X_{a_\tau,\tau} X_{a_\tau,\tau}^T + \gamma_t I \right)^{-1} \\ & \left\{ \sum_{\tau \in \Psi_t} \sum_{i=1}^N X_{i,\tau} \left( \left\{ 1 - \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}} \right\} X_{i,\tau}^T \hat{\beta}_{t-1}^{ridge} + \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}} Y_{h_\tau,t} \right) + \sum_{\tau \notin \Psi_t} X_{a_\tau,\tau} Y_\tau \right\}, \end{aligned} \quad (20)$$

for  $\gamma_t := 4\sqrt{2}N\sqrt{|\Psi_t| \log \frac{4t^2}{\delta}}$  and  $\hat{\beta}_t^{ridge}$  is a normalized ridge estimator using pairs of selected contexts and corresponding rewards until round  $t$ , i.e.

$$\hat{\beta}_t^{ridge} := \frac{\left( \sum_{\tau=1}^t X_{a_\tau,\tau} X_{a_\tau,\tau}^T + I_d \right)^{-1} \left( \sum_{\tau=1}^t X_{a_\tau,\tau} Y_\tau \right)}{\max \left\{ \left\| \left( \sum_{\tau=1}^t X_{a_\tau,\tau} X_{a_\tau,\tau}^T + I_d \right)^{-1} \left( \sum_{\tau=1}^t X_{a_\tau,\tau} Y_\tau \right) \right\|, 1 \right\}}.$$

Then with probability at least  $1 - \delta$ ,

$$\|\check{\beta}_t - \beta^*\|_2 \leq \frac{1}{N}, \quad (21)$$

holds for  $t \geq \max \left\{ \frac{8}{p} \log \frac{4T}{\delta}, C_{p,\sigma} N^2 \phi^{-4} \log \frac{8T}{\delta} \right\}$ .



*Remark A.4.* In deriving the bound (21), the minimum eigenvalue of the Gram matrix is required to be  $\Omega(t)$ , which is challenging even under Assumption 3 when the ridge estimator consist of only selected contexts and rewards is used (See Section 5 in (Li et al., 2017)). Therefore we propose the imputation estimator as in 20 which uses the contexts from all arms to exploit Assumption 3 elevating the minimum eigenvalue of the Gram matrix.

*Proof.* [Step 1. Bounding the minimum eigenvalue of the Gram matrix] Fix  $t$  and set

$$\begin{aligned}\gamma_t &:= 4\sqrt{2}N\sqrt{|\Psi_t|\log\frac{4t^2}{\delta}}, \\ W_t &:= \sum_{\tau \in \Psi_t} \sum_{i=1}^N X_{i,\tau} X_{i,\tau}^T + \sum_{\tau \notin \Psi_t} X_{a_\tau,\tau} X_{a_\tau,\tau} + \gamma_t I.\end{aligned}$$

Then by definition of  $\check{\beta}_t$ , we have

$$\begin{aligned}\|\check{\beta}_t - \beta^*\|_2 &= \left\| W_t^{-1} \left( \sum_{\tau \in \Psi_t} \sum_{i=1}^N X_{i,\tau} \tilde{Y}_{i,\tau} + \sum_{\tau \notin \Psi_t} X_{a_\tau,\tau} Y_\tau - W_t \beta^* \right) \right\|_2 \\ &\leq \|W_t^{-1}\|_2 \left\{ \left\| \sum_{\tau \in \Psi_t} \sum_{i=1}^N X_{i,\tau} (\tilde{Y}_{i,\tau} - X_{i,\tau}^T \beta^*) + \sum_{\tau \notin \Psi_t} X_{a_\tau,\tau} \eta_{a_\tau,\tau} \right\|_2 + \gamma_t \|\beta^*\|_2 \right\} \\ &\leq \lambda_{\min}(W_t)^{-1} \left\{ \left\| \sum_{\tau \in \Psi_t} \sum_{i=1}^N X_{i,\tau} (\tilde{Y}_{i,\tau} - X_{i,\tau}^T \beta^*) + \sum_{\tau \notin \Psi_t} X_{a_\tau,\tau} \eta_{a_\tau,\tau} \right\|_2 + \gamma_t \right\},\end{aligned}\tag{22}$$

where  $\eta_{i,t} = Y_{i,t} - X_{i,t}^T \beta^*$ . For the minimum eigenvalue term, we have

$$\lambda_{\min}(W_t) \geq \lambda_{\min} \left( \sum_{\tau \in \Psi_t} \sum_{i=1}^N X_{i,\tau} X_{i,\tau}^T + \gamma_t I_d \right).$$

Let  $\tau_1 < \tau_2 < \dots < \tau_{|\Psi_t|}$  be the ordered rounds in  $\Psi_t$ . Since  $\left\| \sum_{i=1}^N X_{i,\tau} X_{i,\tau}^T \right\|_F \leq N$  and

$$\lambda_{\min} \left( \mathbb{E} \left[ \sum_{i=1}^N X_{i,\tau_k} X_{i,\tau_k}^T \middle| \mathcal{X}_{\tau_1}, \dots, \mathcal{X}_{\tau_{k-1}} \right] \right) = \lambda_{\min} \left( \mathbb{E} \left[ \sum_{i=1}^N X_{i,\tau_k} X_{i,\tau_k}^T \right] \right) \geq N\phi^2,$$

we can use Lemma 6 in Kim et al. (2021) to have

$$\lambda_{\min}(W_t) \geq \lambda_{\min} \left( \sum_{\tau \in \Psi_t} \sum_{i=1}^N X_{i,\tau} X_{i,\tau}^T + \gamma_t I_d \right) \geq |\Psi_t| N\phi^2.\tag{23}$$

[Step 2. Estimation error decomposition] By definition of  $\tilde{Y}_{i,\tau}$ , we have

$$\begin{aligned}\sum_{\tau \in \Psi_t} \sum_{i=1}^N X_{i,\tau} (\tilde{Y}_{i,\tau} - X_{i,\tau}^T \beta^*) &= \sum_{\tau \in \Psi_t} \sum_{i=1}^N \left( 1 - \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}} \right) X_{i,\tau} X_{i,\tau}^T (\hat{\beta}_{t-1}^{ridge} - \beta^*) \\ &\quad + \sum_{\tau \in \Psi_t} \sum_{i=1}^N \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}} \eta_{i,\tau} \\ &= \sum_{\tau \in \Psi_t} \sum_{i=1}^N \left( 1 - \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}} \right) \mathbf{X}_{i,\tau} (\hat{\beta}_{t-1}^{ridge} - \beta^*) \\ &\quad + \sum_{\tau \in \Psi_t} \frac{\eta_{h_\tau,\tau}}{\pi_{h_\tau,\tau}} X_{h_\tau,\tau},\end{aligned}$$

where  $\mathbf{X}_{i,\tau} = X_{i,\tau} X_{i,\tau}^T$ . Plugging this and (23) in (22) gives,

$$\begin{aligned} \|\check{\beta}_t - \beta^*\|_2 &\leq \frac{1}{|\Psi_t| N \phi^2} \left\| \sum_{\tau \in \Psi_t} \sum_{i=1}^N \left(1 - \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}}\right) \mathbf{X}_{i,\tau} \left(\widehat{\beta}_{t-1}^{ridge} - \beta^*\right) \right\|_2 \\ &\quad + \frac{1}{|\Psi_t| N \phi^2} \left\| \sum_{\tau \in \Psi_t} \frac{\eta_{h_\tau,\tau}}{\pi_{h_\tau,\tau}} X_{h_\tau,\tau} + \sum_{\tau \notin \Psi_t} \eta_{a_\tau,\tau} X_{a_\tau,\tau} \right\|_2 + \frac{4\sqrt{2 \log \frac{4t^2}{\delta}}}{\phi^2 \sqrt{|\Psi_t|}}. \end{aligned} \quad (24)$$

[Step 3. Bounding the first term in (24)] For the first term,

$$\begin{aligned} &\left\| \sum_{\tau \in \Psi_t} \sum_{i=1}^N \left(1 - \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}}\right) \mathbf{X}_{i,\tau} \left(\widehat{\beta}_{t-1}^{ridge} - \beta^*\right) \right\|_2 \\ &\leq \left\| \sum_{\tau \in \Psi_t} \sum_{i=1}^N \left(1 - \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}}\right) \mathbf{X}_{i,\tau} \right\|_2 \left\| \widehat{\beta}_{t-1}^{ridge} - \beta^* \right\|_2 \\ &\leq 2 \left\| \sum_{\tau \in \Psi_t} \sum_{i=1}^N \left(1 - \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}}\right) \mathbf{X}_{i,\tau} \right\|_F \end{aligned}$$

Define the filtration as  $\mathcal{G}_0 = \Psi_t$  and  $\mathcal{G}_\tau = \mathcal{G}_{\tau-1} \cup \{\mathcal{X}_\tau, h_\tau, a_\tau\}$  for  $\tau \in [t]$ . This filtration refers to the case where the subset of rounds  $\Psi_t$  for using contexts from all arms is observed first and  $h_1, a_1, h_2, a_2, \dots, h_t$  are observed later. In HyRan Bandit, the hybridization variables  $h_1, \dots, h_t$  and actions  $a_1, \dots, a_t$  are observed first to determine  $\Psi_t$ . But in theoretical analysis, we change the order of observation by defining a new filtration  $\mathcal{G}_0, \dots, \mathcal{G}_t$  and obtain a suitable bound with the martingale method (Kontorovich and Ramanan, 2008). Set

$$M := \sum_{\tau \in \Psi_t} \sum_{i=1}^N \left(1 - \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}}\right) \mathbf{X}_{i,\tau},$$

and define  $M_\tau = \mathbb{E}[M | \mathcal{G}_\tau]$ . Then  $\{M_\tau\}_{\tau=0}^t$  is a  $\mathbb{R}^{d \times d}$ -valued martingale sequence since

$$\mathbb{E}[M_\tau | \mathcal{G}_{\tau-1}] = \mathbb{E}[\mathbb{E}[M | \mathcal{G}_\tau] | \mathcal{G}_{\tau-1}] = \mathbb{E}[M | \mathcal{G}_{\tau-1}] = M_{\tau-1}.$$

By Lemma A.1, we can find a  $\mathbb{R}^2$ -valued martingale sequence  $\{N_\tau\}_{\tau=0}^t$  such that  $N_0 = (0, 0)^T$  and

$$\|M_\tau\|_F = \|N_\tau\|_2, \quad \|M_\tau - M_{\tau-1}\|_F = \|N_\tau - N_{\tau-1}\|_2,$$

for all  $\tau \in [t]$ . Set  $N_\tau = (N_\tau^{(1)}, N_\tau^{(2)})^T$ . Then for each  $r = 1, 2$  and  $\tau \in [t]$ ,

$$\begin{aligned} \left| N_\tau^{(r)} - N_{\tau-1}^{(r)} \right| &\leq \|N_\tau - N_{\tau-1}\|_2 \\ &= \|M_\tau - M_{\tau-1}\|_F \\ &= \|\mathbb{E}[M | \mathcal{G}_\tau] - \mathbb{E}[M | \mathcal{G}_{\tau-1}]\|_F \\ &= \begin{cases} \left\| \sum_{i=1}^N \left(1 - \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}}\right) \mathbf{X}_{i,\tau} \right\|_F & \tau \in \Psi_t \\ 0 & \tau \notin \Psi_t \end{cases} \\ &\leq \begin{cases} \left\| \sum_{i=1}^N \mathbf{X}_{i,\tau} \right\|_F + \left\| \frac{1}{\pi_{h_\tau,\tau}} \mathbf{X}_{i,\tau} \right\|_F & \tau \in \Psi_t \\ 0 & \tau \notin \Psi_t \end{cases} \\ &\leq \begin{cases} N \left( \frac{2-p}{1-p} \right) & \tau \in \Psi_t \\ 0 & \tau \notin \Psi_t \end{cases}, \end{aligned}$$

holds almost surely. The third equality holds since for any  $\tau \in [t]$ ,

$$\mathbb{E} \left[ \sum_{i=1}^N \left(1 - \frac{\mathbb{I}(h_u = i)}{\pi_{i,u}}\right) \middle| \mathcal{G}_\tau \right] = 0, \quad \forall u > \tau,$$

$$\mathbb{E}[M | \mathcal{G}_\tau] = \sum_{u \in \Psi_t, u \leq \tau} \sum_{i=1}^N \left(1 - \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}}\right) \mathbf{X}_{i,\tau}.$$

Using Lemma A.2, for  $x > 0$  and  $r = 1, 2$ ,

$$\mathbb{P} \left( \left| N_\tau^{(r)} \right| > x \mid \mathcal{G}_0 \right) \leq 2 \exp \left( - \frac{x^2}{2N^2 |\Psi_t| \left( \frac{2-p}{1-p} \right)^2} \right),$$

which implies that

$$\mathbb{P} \left( \left| N_\tau^{(r)} \right| > N \left( \frac{2-p}{1-p} \right) \sqrt{2 |\Psi_t| \log \frac{4t^2}{\delta}} \mid \mathcal{G}_0 \right) \leq \frac{\delta}{2t^2}.$$

Since

$$\|M\|_F = \|M_t\|_F = \|N_t\|_2 \leq |N_t^{(1)}| + |N_t^{(2)}|,$$

we have

$$\mathbb{P} \left( \|M\|_F > 2N \left( \frac{2-p}{1-p} \right) \sqrt{2 |\Psi_t| \log \frac{4t^2}{\delta}} \mid \mathcal{G}_0 \right) \leq \frac{\delta}{t^2},$$

for any subset  $\Psi_t \subseteq [t]$ . Thus, we conclude that

$$\begin{aligned} & \mathbb{P} \left( \left\| \sum_{\tau \in \Psi_t} \sum_{i=1}^N \left( 1 - \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}} \right) \mathbf{X}_{i,\tau} (\check{\beta}_{t-1} - \beta^*) \right\|_2 > 4N \left( \frac{2-p}{1-p} \right) \sqrt{2 |\Psi_t| \log \frac{4t^2}{\delta}} \right) \\ & \leq \mathbb{P} \left( 2 \|M\|_F > 4N \left( \frac{2-p}{1-p} \right) \sqrt{2 |\Psi_t| \log \frac{4t^2}{\delta}} \right) \\ & \leq \mathbb{E} \mathbb{P} \left( 2 \|M\|_F > 4N \left( \frac{2-p}{1-p} \right) \sqrt{2 |\Psi_t| \log \frac{4t^2}{\delta}} \mid \Psi_t \right) \\ & \leq \frac{\delta}{t^2}. \end{aligned}$$

[Step 4. Bounding the second term in (24)] Now for the second term in (24), we have for any  $x > 0$ ,

$$\begin{aligned} & \mathbb{P} \left( \left\| \sum_{\tau \in \Psi_t} \frac{\eta_{h_\tau, \tau}}{\pi_{h_\tau, \tau}} X_{h_\tau, \tau} + \sum_{\tau \notin \Psi_t} \eta_{a_\tau, \tau} X_{a_\tau, \tau} \right\|_2 > x \right) \\ & \leq \mathbb{P} \left( \left\{ \left\| \sum_{\tau \in \Psi_t} \frac{\eta_{h_\tau, \tau}}{\pi_{h_\tau, \tau}} X_{h_\tau, \tau} + \sum_{\tau \notin \Psi_t} \eta_{a_\tau, \tau} X_{a_\tau, \tau} \right\|_2 > x \right\} \cap \left\{ \bigcap_{\tau \in \Psi_t} \{h_\tau = a_\tau\} \right\} \right) \\ & \quad + \mathbb{P} \left( \bigcup_{\tau \in \Psi_t} \{h_\tau \neq a_\tau\} \right) \\ & \leq \mathbb{P} \left( \left\| \sum_{\tau \in \Psi_t} \frac{\eta_{a_\tau, \tau}}{\pi_{a_\tau, \tau}} X_{a_\tau, \tau} + \sum_{\tau \notin \Psi_t} \eta_{a_\tau, \tau} X_{a_\tau, \tau} \right\|_2 > x \right). \end{aligned}$$

The last inequality holds since HyRan Bandit selects allocates the round  $\tau$  in  $\Psi_t$  only when  $h_\tau = a_\tau$ , almost surely. Since  $\pi_{a_\tau, \tau} = p$ , we observe that  $\frac{\eta_{a_\tau, \tau}}{\pi_{a_\tau, \tau}}$  and  $\eta_{a_\tau, \tau}$  are  $\frac{\sigma}{p}$ -sub-Gaussian. Using Lemma 4 in Kim et al. (2021) we have,

$$\mathbb{P} \left( \left\| \sum_{\tau \in \Psi_t} \frac{\eta_{a_\tau, \tau}}{\pi_{a_\tau, \tau}} X_{a_\tau, \tau} + \sum_{\tau \notin \Psi_t} \eta_{a_\tau, \tau} X_{a_\tau, \tau} \right\|_2 > \frac{C\sigma}{p} \sqrt{t} \sqrt{\log \frac{4t^2}{\delta}} \right) \leq \frac{\delta}{t^2},$$

for some absolute constant  $C > 0$ . Now from (24), with probability  $1 - \frac{3\delta}{t^2}$ , we have

$$\|\check{\beta}_t - \beta^*\|_2 \leq \frac{1}{|\Psi_t| N \phi^2} \left\{ 4N \left( \frac{2-p}{1-p} \right) \sqrt{2 |\Psi_t| \log \frac{4t^2}{\delta}} + \frac{C\sigma}{p} \sqrt{t} \sqrt{\log \frac{4t^2}{\delta}} \right\} + \frac{4\sqrt{2 \log \frac{4t^2}{\delta}}}{\phi^2 \sqrt{|\Psi_t|}}.$$

By Lemma 5.5,  $|\Psi_t| \geq \frac{p}{2}t$  for all  $t \geq \frac{1}{p} \log \frac{T}{\delta}$ , with probability at least  $1 - \delta$ . Then we have

$$\begin{aligned} \|\check{\beta}_t - \beta^*\|_2 &\leq \frac{1}{\phi^2 \sqrt{t}} \left\{ \frac{8(2-p)}{(1-p)\sqrt{p}} + \frac{\sqrt{2}C\sigma}{p^2 N} + \frac{8}{\sqrt{p}} \right\} \sqrt{2 \log \frac{4t^2}{\delta}} \\ &\leq \frac{2}{\phi^2 \sqrt{t}} \left\{ \frac{8(2-p)}{(1-p)\sqrt{p}} + \frac{\sqrt{2}C\sigma}{p^2} + \frac{8}{\sqrt{p}} \right\} \sqrt{\log \frac{2T}{\delta}}. \end{aligned}$$

Set

$$C_{p,\sigma} := \frac{8(2-p)}{(1-p)\sqrt{p}} + \frac{\sqrt{2}C\sigma}{p^2} + \frac{8}{\sqrt{p}}. \quad (25)$$

Then for all  $t \geq \max \left\{ \frac{1}{p} \log \frac{T}{\delta}, C_{p,\sigma} N^2 \phi^{-4} \log \frac{2T}{\delta} \right\}$ , we have  $\|\check{\beta}_t - \beta^*\|_2 \leq \frac{1}{N}$ , with probability at least  $1 - 4\delta$ .  $\square$

### A.5.2 Proof of Theorem 5.4

Now we are ready to prove Theorem 5.4.

*Proof.* [Step 1. Decomposition] By the definition of  $\hat{\beta}_t$  in 6,

$$\begin{aligned} \|\hat{\beta}_t - \beta^*\|_{V_t} &= \left\| V_t^{-1} \left( \sum_{\tau \in \Psi_t} \sum_{i=1}^N X_{i,\tau} \tilde{Y}_{i,\tau} + \sum_{\tau \notin \Psi_t} X_{a_\tau,\tau} Y_{a_\tau,\tau} V_t \beta^* \right) \right\|_{V_t} \\ &= \left\| \sum_{\tau \in \Psi_t} \sum_{i=1}^N X_{i,\tau} \tilde{Y}_{i,\tau} + \sum_{\tau \notin \Psi_t} X_{a_\tau,\tau} Y_{a_\tau,\tau} V_t \beta^* \right\|_{V_t^{-1}} \\ &= \left\| \sum_{\tau \in \Psi_t} \sum_{i=1}^N X_{i,\tau} (\tilde{Y}_{i,\tau} - X_{i,\tau}^T \beta^*) + \sum_{\tau \notin \Psi_t} X_{a_\tau,\tau} (Y_{a_\tau,\tau} - X_{a_\tau,\tau}^T \beta^*) - \lambda_t \beta^* \right\|_{V_t^{-1}}. \end{aligned}$$

Set  $\tilde{\eta}_{i,\tau} := \tilde{Y}_{i,\tau} - X_{i,\tau}^T \beta^*$ . Since  $Y_{a_\tau,\tau} = X_{a_\tau,\tau}^T \beta^* + \eta_{a_\tau,\tau}$ , we have

$$\begin{aligned} \|\hat{\beta}_t - \beta^*\|_{V_t} &= \left\| \sum_{\tau \in \Psi_t} \sum_{i=1}^N \tilde{\eta}_{i,\tau} X_{i,\tau} + \sum_{\tau \notin \Psi_t} \eta_{a_\tau,\tau} X_{a_\tau,\tau} - \lambda_t \beta^* \right\|_{V_t^{-1}} \\ &\leq \|\lambda_t \beta^*\|_{V_t^{-1}} + \left\| \sum_{\tau \in \Psi_t} \sum_{i=1}^N \tilde{\eta}_{i,\tau} X_{i,\tau} + \sum_{\tau \notin \Psi_t} \eta_{a_\tau,\tau} X_{a_\tau,\tau} \right\|_{V_t^{-1}}. \end{aligned} \quad (26)$$

For the first term, we have

$$\|\lambda_t \beta^*\|_{V_t^{-1}} \leq \sqrt{\lambda_{\max}(V_t^{-1})} \|\lambda_t \beta^*\|_2 \leq \sqrt{\lambda_t} \|\beta^*\|_2 \leq \sqrt{\lambda_t}, \quad (27)$$

where the last inequality holds due to Assumption 1. For the second term, we use the decomposition,

$$\begin{aligned} \sum_{\tau \in \Psi_t} \sum_{i=1}^N \tilde{\eta}_{i,\tau} X_{i,\tau} &= \sum_{\tau \in \Psi_t} \sum_{i=1}^N \left( 1 - \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}} \right) X_{i,\tau} X_{i,\tau}^T (\check{\beta}_t - \beta^*) \\ &\quad + \sum_{\tau \in \Psi_t} \sum_{i=1}^N \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}} \eta_{i,\tau} X_{i,\tau}, \end{aligned}$$

to have

$$\begin{aligned}
 & \left\| \sum_{\tau \in \Psi_t} \sum_{i=1}^N \tilde{\eta}_{i,\tau} X_{i,\tau} + \sum_{\tau \notin \Psi_t} \eta_{a,\tau} X_{a,\tau} \right\|_{V_t^{-1}} \\
 & \leq \left\| \sum_{\tau \in \Psi_t} \sum_{i=1}^N \left(1 - \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}}\right) X_{i,\tau} X_{i,\tau}^T (\check{\beta}_t - \beta^*) \right\|_{V_t^{-1}} \\
 & \quad + \left\| \sum_{\tau \in \Psi_t} \sum_{i=1}^N \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}} \eta_{i,\tau} X_{i,\tau} + \sum_{\tau \notin \Psi_t} \eta_{a,\tau} X_{a,\tau} \right\|_{V_t^{-1}}.
 \end{aligned} \tag{28}$$

[Step 2. Bounding the first term in (28)] Let  $\mathbf{X}_{i,\tau} := X_{i,\tau} X_{i,\tau}^T$ . For the first term, we can use Lemma A.3 to have

$$\begin{aligned}
 & \left\| \sum_{\tau \in \Psi_t} \sum_{i=1}^N \left(1 - \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}}\right) \mathbf{X}_{i,\tau} (\check{\beta}_t - \beta^*) \right\|_{V_t^{-1}} \\
 & = \left\| \sum_{\tau \in \Psi_t} \sum_{i=1}^N \left(1 - \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}}\right) V_t^{-\frac{1}{2}} \mathbf{X}_{i,\tau} (\check{\beta}_t - \beta^*) \right\|_2 \\
 & \leq \left\| \sum_{\tau \in \Psi_t} \sum_{i=1}^N \left(1 - \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}}\right) V_t^{-\frac{1}{2}} \mathbf{X}_{i,\tau} \right\|_2 \|\check{\beta}_t - \beta^*\|_2 \\
 & \leq \frac{1}{N} \left\| \sum_{\tau \in \Psi_t} \sum_{i=1}^N \left(1 - \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}}\right) V_t^{-\frac{1}{2}} \mathbf{X}_{i,\tau} \right\|_F.
 \end{aligned}$$

With similar technique in the proof of Lemma A.3, define the filtration as  $\mathcal{G}_0 = \Psi_t \cup \{\mathcal{X}_1, \dots, \mathcal{X}_t\}$  and  $\mathcal{G}_\tau = \mathcal{G}_{\tau-1} \cup \{h_\tau, a_\tau\}$  for  $\tau \in [t]$ . Set

$$M := \sum_{\tau \in \Psi_t} \sum_{i=1}^N \left(1 - \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}}\right) V_t^{-\frac{1}{2}} \mathbf{X}_{i,\tau},$$

and define  $M_\tau = \mathbb{E}[M | \mathcal{G}_\tau]$ . Then  $\{M_\tau\}_{\tau=0}^t$  is a  $\mathbb{R}^{d \times d}$ -valued martingale sequence. Since for any  $\tau \in [t]$ , the contexts  $\mathcal{X}_{\tau+1}, \dots, \mathcal{X}_t$  are independent of  $h_\tau$  and

$$\mathbb{E} \left[ \sum_{i=1}^N \left(1 - \frac{\mathbb{I}(h_u = i)}{\pi_{i,u}}\right) V_t^{-\frac{1}{2}} \mathbf{X}_{i,u} \middle| \mathcal{G}_\tau \right] = V_t^{-\frac{1}{2}} \sum_{i=1}^N \mathbb{E} \left[ 1 - \frac{\mathbb{I}(h_u = i)}{\pi_{i,u}} \middle| \mathcal{G}_\tau \right] \mathbf{X}_{i,u} = 0,$$

for all  $u > \tau$ . This leads to

$$\mathbb{E}[M | \mathcal{G}_\tau] = \sum_{u \in \Psi_t, u \leq \tau} \sum_{i=1}^N \left(1 - \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}}\right) V_t^{-\frac{1}{2}} \mathbf{X}_{i,\tau}.$$

By Lemma A.1, we can find a  $\mathbb{R}^2$ -valued martingale sequence  $\{N_\tau\}_{\tau=0}^t$  such that  $N_0 = (0, 0)^T$  and

$$\|M_\tau\|_F = \|N_\tau\|_2, \quad \|M_\tau - M_{\tau-1}\|_F = \|N_\tau - N_{\tau-1}\|_2,$$

for all  $\tau \in [t]$ . Set  $N_\tau = (N_\tau^{(1)}, N_\tau^{(2)})^T$ . Then for each  $r = 1, 2$  and  $\tau \in [t]$ ,

$$\begin{aligned}
 \left| N_\tau^{(r)} - N_{\tau-1}^{(r)} \right| &\leq \|N_\tau - N_{\tau-1}\|_2 \\
 &= \|M_\tau - M_{\tau-1}\|_F \\
 &= \|\mathbb{E}[M | \mathcal{G}_\tau] - \mathbb{E}[M | \mathcal{G}_{\tau-1}]\|_F \\
 &= \begin{cases} \left\| \sum_{i=1}^N \left(1 - \frac{\mathbb{I}(h_\tau=i)}{\pi_{i,\tau}}\right) V_t^{-\frac{1}{2}} \mathbf{X}_{i,\tau} \right\|_F & \tau \in \Psi_t \\ 0 & \tau \notin \Psi_t \end{cases} \\
 &\leq \begin{cases} \sqrt{\sum_{i=1}^N \left(1 - \frac{\mathbb{I}(h_\tau=i)}{\pi_{i,\tau}}\right)^2} \sqrt{\sum_{i=1}^N \|V_t^{-\frac{1}{2}} \mathbf{X}_{i,\tau}\|_F^2} & \tau \in \Psi_t \\ 0 & \tau \notin \Psi_t \end{cases} \\
 &\leq \begin{cases} 2 \frac{N}{1-p} \sqrt{\sum_{i=1}^N \|X_{i,\tau}\|_{V_t^{-1}}^2} & \tau \in \Psi_t \\ 0 & \tau \notin \Psi_t \end{cases},
 \end{aligned}$$

holds almost surely. The last inequality holds due to

$$\begin{aligned}
 \|V_t^{-1/2} \mathbf{X}_{i,\tau}\|_F^2 &= \text{Tr}(\mathbf{X}_{i,\tau}^T V_t^{-1} \mathbf{X}_{i,\tau}) \\
 &= X_{i,\tau}^T V_t^{-1} X_{i,\tau} \text{Tr}(X_{i,\tau} X_{i,\tau}^T) \\
 &= \|X_{i,\tau}\|_{V_t^{-1}}^2 \|X_{i,\tau}\|_2^2 \\
 &\leq \|X_{i,\tau}\|_{V_t^{-1}}^2.
 \end{aligned}$$

Using Lemma A.2, for  $x > 0$  and  $r = 1, 2$ ,

$$\mathbb{P}\left(\left|N_\tau^{(r)}\right| > x \mid \mathcal{G}_0\right) \leq 2 \exp\left\{-\frac{x^2}{2 \left(\frac{2N}{1-p}\right)^2 \sum_{\tau \in \Psi_t} \sum_{i=1}^N \|X_{i,\tau}\|_{V_t^{-1}}^2}\right\},$$

which implies that

$$\mathbb{P}\left(\left|N_\tau^{(r)}\right| > \frac{2N}{1-p} \sqrt{2 \left(\sum_{\tau \in \Psi_t} \sum_{i=1}^N \|X_{i,\tau}\|_{V_t^{-1}}^2\right) \log \frac{4t^2}{\delta}} \mid \mathcal{G}_0\right) \leq \frac{\delta}{2t^2}.$$

Since

$$\|M\|_F = \|M_t\|_F = \|N_t\|_2 \leq \left|N_t^{(1)}\right| + \left|N_t^{(2)}\right|,$$

we have

$$\mathbb{P}\left(\|M\|_F > \frac{4N}{1-p} \sqrt{2 \left(\sum_{\tau \in \Psi_t} \sum_{i=1}^N \|X_{i,\tau}\|_{V_t^{-1}}^2\right) \log \frac{4t^2}{\delta}} \mid \Psi_t\right) \leq \frac{\delta}{2t^2},$$

for any subset  $\Psi_t \subseteq [t]$ . Let  $U_t := \sum_{\tau \in \Psi_t} \sum_{i=1}^N X_{i,\tau} X_{i,\tau}^T + \lambda_t I$ . Since  $V_t \succeq U_t$ , we have  $\|X_{i,\tau(u)}\|_{V_t^{-1}}^2 \leq \|X_{i,\tau(u)}\|_{U_t^{-1}}^2$ . By the definition of the Frobenous norm and  $\mathbf{X}_{i,\tau}$ , we have

$$\begin{aligned}
 \sum_{\tau \in \Psi_t} \sum_{i=1}^N \|X_{i,\tau(u)}\|_{U_t^{-1}}^2 &= \sum_{\tau \in \Psi_t} \sum_{i=1}^N X_{i,\tau}^T U_t^{-1} X_{i,\tau} \\
 &= \sum_{\tau \in \Psi_t} \sum_{i=1}^N \text{Tr} (X_{i,\tau}^T U_t^{-1} X_{i,\tau}) \\
 &= \sum_{\tau \in \Psi_t} \sum_{i=1}^N \text{Tr} (X_{i,\tau} X_{i,\tau}^T U_t^{-1}) \\
 &= \text{Tr} \left( \left( \sum_{\tau \in \Psi_t} \sum_{i=1}^N X_{i,\tau} X_{i,\tau}^T \right) U_t^{-1} \right) \\
 &\leq \text{Tr} \left( \left( \sum_{\tau \in \Psi_t} \sum_{i=1}^N X_{i,\tau} X_{i,\tau}^T + \lambda_t I \right) U_t^{-1} \right) \\
 &= \text{Tr} (I_d) = d.
 \end{aligned}$$

Thus, we have

$$\mathbb{P} \left( \|M\|_F > \frac{4N}{1-p} \sqrt{2d \log \frac{4t^2}{\delta}} \mid \Psi_t \right) \leq \frac{\delta}{t^2},$$

and

$$\begin{aligned}
 &\mathbb{P} \left( \left\| \sum_{\tau \in \Psi_t} \sum_{i=1}^N \left( 1 - \frac{\mathbb{I}(h_\tau = i)}{\pi_{i,\tau}} \right) V_t^{-\frac{1}{2}} \mathbf{X}_{i,\tau} (\hat{\beta}_t - \beta^*) \right\|_2 > \frac{4}{1-p} \sqrt{2d \log \frac{4t^2}{\delta}} \right) \\
 &\leq \mathbb{P} \left( \frac{1}{N} \|M\|_F > \frac{4}{1-p} \sqrt{2d \log \frac{4t^2}{\delta}} \right) \\
 &\leq \mathbb{E} \mathbb{P} \left( \|M\|_F > \frac{4N}{1-p} \sqrt{2d \log \frac{4t^2}{\delta}} \mid \Psi_t \right) \\
 &\leq \frac{\delta}{t^2}.
 \end{aligned} \tag{29}$$

[Step 3. Bounding the second term in (28)] For the second term in 28, we have for any  $x > 0$ ,

$$\begin{aligned}
 &\mathbb{P} \left( \left\| \sum_{\tau \in \Psi_t} \frac{\eta_{h_\tau, \tau}}{\pi_{h_\tau, \tau}} X_{h_\tau, \tau} + \sum_{\tau \notin \Psi_t} \eta_{a_\tau, \tau} X_{a_\tau, \tau} \right\|_{V_t^{-1}} > x \right) \\
 &\leq \mathbb{P} \left( \left\{ \left\| \sum_{\tau \in \Psi_t} \frac{\eta_{h_\tau, \tau}}{\pi_{h_\tau, \tau}} X_{h_\tau, \tau} + \sum_{\tau \notin \Psi_t} \eta_{a_\tau, \tau} X_{a_\tau, \tau} \right\|_{V_t^{-1}} > x \right\} \cap \left\{ \bigcap_{\tau \in \Psi_t} \{h_\tau = a_\tau\} \right\} \right) \\
 &\quad + \mathbb{P} \left( \bigcup_{\tau \in \Psi_t} \{h_\tau \neq a_\tau\} \right) \\
 &\leq \mathbb{P} \left( \left\| \sum_{\tau \in \Psi_t} \frac{\eta_{a_\tau, \tau}}{\pi_{a_\tau, \tau}} X_{a_\tau, \tau} + \sum_{\tau \notin \Psi_t} \eta_{a_\tau, \tau} X_{a_\tau, \tau} \right\|_{V_t^{-1}} > x \right).
 \end{aligned}$$

Since  $\pi_{a_\tau, \tau} = p$ , we observe that  $\frac{\eta_{a_\tau, \tau}}{\pi_{a_\tau, \tau}}$  and  $\eta_{a_\tau, \tau}$  are  $\frac{\sigma}{p}$ -sub-Gaussian. Define  $W_t := \sum_{\tau=1}^t X_{a_\tau, \tau} X_{a_\tau, \tau}^T + \lambda_t I$ . Since  $V_t \succeq W_t$ , we have

$$\left\| \sum_{\tau \in \Psi_t} \frac{\eta_{a_\tau, \tau}}{\pi_{a_\tau, \tau}} X_{a_\tau, \tau} + \sum_{\tau \notin \Psi_t} \eta_{a_\tau, \tau} X_{a_\tau, \tau} \right\|_{V_t^{-1}} \leq \left\| \sum_{\tau \in \Psi_t} \frac{\eta_{a_\tau, \tau}}{\pi_{a_\tau, \tau}} X_{a_\tau, \tau} + \sum_{\tau \notin \Psi_t} \eta_{a_\tau, \tau} X_{a_\tau, \tau} \right\|_{W_t^{-1}}.$$

By assumption 2,  $\eta_{a_\tau, \tau}$  is a  $\mathcal{H}_{\tau+1}$ -measurable and  $\sigma$ -sub-Gaussian random variable given  $\mathcal{H}_\tau$ . Since  $X_{a_\tau, \tau}$  is  $\mathcal{H}_\tau$ -measurable, we can use Theorem 1 in Abbasi-Yadkori et al. (2011) to have

$$\left\| \sum_{\tau \in \Psi_t} \frac{\eta_{a_\tau, \tau}}{p} X_{a_\tau, \tau} + \sum_{\tau \notin \Psi_t} \eta_{a_\tau, \tau} X_{a_\tau, \tau} \right\|_{W_t^{-1}}^2 \leq \frac{\sigma^2}{p^2} d \log \left( \frac{t}{\delta} \right), \quad (30)$$

for all  $t \geq 0$  with probability at least  $1 - \delta$ . Now with (26)-(30), we can conclude that

$$\begin{aligned} \left\| \hat{\beta}_t - \beta^* \right\|_{V_t} &\leq \frac{4}{1-p} \sqrt{2d \log \frac{4t^2}{\delta}} + \frac{\sigma}{p} \sqrt{d \log \left( \frac{t}{\delta} \right)} + \sqrt{\lambda_t} \\ &\leq \left( \frac{4\sqrt{2}}{1-p} + \frac{\sigma}{p} \right) \sqrt{d \log \frac{4t^2}{\delta}} + \sqrt{\lambda_t}, \end{aligned}$$

with probability at least  $1 - 6\delta$ . □

## A.6 Proof of Lemma 5.5

*Proof.* The proof follows from Chernoff's lower bound. In Algorithm 1,  $\Psi_t$  is constructed as  $\Psi_t = \{\tau \in [t] : h_\tau = a_\tau\}$ . Thus we have

$$|\Psi_t| = \sum_{\tau=1}^t \mathbb{I}(h_\tau = a_\tau).$$

Then for any  $\epsilon \in (0, 1)$  and  $s < 0$ ,

$$\mathbb{P}(|\Psi_t| \leq \epsilon pt) = \mathbb{P}\left(s \sum_{\tau=1}^t \mathbb{I}(h_\tau = a_\tau) \geq s\epsilon pt\right) \leq \exp(-s\epsilon pt) \mathbb{E}\left[\exp\left(s \sum_{\tau=1}^t \mathbb{I}(h_\tau = a_\tau)\right)\right].$$

Let  $\mathcal{G}_\tau = \mathcal{F}_\tau \cup \{h_1, \dots, h_{\tau-1}\}$ . Then  $\mathbb{E}[\mathbb{I}(h_\tau = a_\tau) | \mathcal{G}_\tau] = p$ , for all  $\tau \in [t]$  and

$$\begin{aligned} \mathbb{E}\left[\exp\left(s \sum_{\tau=1}^t \mathbb{I}(h_\tau = a_\tau)\right)\right] &= \mathbb{E}\mathbb{E}\left[\exp\left(s \sum_{\tau=1}^t \mathbb{I}(h_\tau = a_\tau)\right) \middle| \mathcal{G}_t\right] \\ &= \mathbb{E}\left[\exp\left(s \sum_{\tau=1}^{t-1} \mathbb{I}(h_\tau = a_\tau)\right) \mathbb{E}[\exp\{s\mathbb{I}(h_t = a_t)\} | \mathcal{G}_t]\right] \\ &= \{(1-p) + pe^s\} \mathbb{E}\left[\exp\left(s \sum_{\tau=1}^{t-1} \mathbb{I}(h_\tau = a_\tau)\right)\right] \\ &= \vdots \\ &= \{(1-p) + pe^s\}^t \\ &\leq \{\exp(-p + pe^s)\}^t. \end{aligned}$$

The last inequality holds due to  $1 + x \leq e^x$  for all  $x \in \mathbb{R}$ . Thus, we have

$$\mathbb{P}(|\Psi_t| \leq \epsilon pt) \leq \exp\{(e^s - se - 1)pt\}.$$



The right hand side is minimized when  $s = \log \epsilon$ . Setting  $s = \log \epsilon$  gives

$$\begin{aligned} \mathbb{P}(|\Psi_t| \leq \epsilon pt) &\leq \exp\{(\epsilon - \epsilon \log \epsilon - 1)pt\} \leq \exp\left\{\left(-\epsilon^2 + 2\epsilon - 1 + \frac{(1-\epsilon)^2}{2}\right)pt\right\}, \\ &= \exp\left[\left\{-\frac{1}{2}(1-\epsilon)^2\right\}pt\right] \end{aligned}$$

where the last inequality holds due to  $\log x \geq x - 1 - \frac{(1-x)^2}{2x}$  for all  $x \in (0, 1)$ . Setting the right hand side smaller than  $\delta/T$  gives

$$t \geq \frac{2}{p(1-\epsilon)^2} \log \frac{T}{\delta}. \quad (31)$$

For  $t$  that satisfies (31),  $\mathbb{P}(|\Psi_t| \leq \epsilon pt) \leq \frac{\delta}{T}$  holds. □

### A.7 Proof of Theorem 5.6

*Proof.* The proof is inspired by that of Theorem 5.1 in Auer et al. (2002b), and that of Theorem 24.2 in Lattimore and Szepesvári (2020). Define the context distribution  $\mathcal{P}_X$  sampled from

$$\left( \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \dots, \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \right) \in (\mathbb{R}^d)^N.$$

Here, the covariance matrix  $\mathbb{E}\left[N^{-1} \sum_{i=1}^N X_{i,t} X_{i,t}^T\right]$  is positive definite. Let  $\eta_{i,t}$  be a random variable sampled from the normal distribution  $\mathcal{N}(0, 1^2)$ , independently. Then the reward distribution is Gaussian with mean  $X_{i,t}^T \beta$ , and variance  $1^2$ . For each  $i \in [d]$  let  $\beta_i = (0, \dots, 0, \Delta, 0, \dots, 0)$  where  $\Delta > 0$  is in  $i$ -th component only. Then we have

$$\mathbb{E}_{\beta_i} \left[ \sum_{t=1}^T X_{a_t, t}^T \beta \right] = \Delta T. \quad (32)$$

For each  $i \in [d]$ , we have

$$\mathbb{E}_{\beta_i} \left[ \sum_{t=1}^T X_{a_t, t}^T \beta_i \right] = \Delta \mathbb{E}_{\beta_i} \left[ \sum_{t=1}^T \mathbb{I}(a_t = i) \right].$$

Now set  $\beta_0 = \mathbf{0}$ . Let  $\mathbb{P}_{\beta_i}$  and  $\mathbb{P}_{\beta_0}$  be the laws of  $\sum_{t=1}^T \mathbb{I}(a_t = i)$  with respect to the bandit/learner interaction measure induced by  $\beta_i$  and  $\beta_0$  respectively. Then by the result in Exercise 14.4 in Lattimore and Szepesvári (2020),

$$\mathbb{E}_{\beta_i} \left[ \sum_{t=1}^T \mathbb{I}(a_t = i) \right] \leq \mathbb{E}_{\beta_0} \left[ \sum_{t=1}^T \mathbb{I}(a_t = i) \right] + T \sqrt{\frac{1}{2} D(\mathbb{P}_{\beta_0}, \mathbb{P}_{\beta_i})},$$

where  $D(\cdot, \cdot)$  is the relative entropy between two probability measures. Set  $\mathcal{X}_t := (X_{1,t}, \dots, X_{N,t})$ . By the chain rule for the relative entropy,

$$\begin{aligned}
 & D(\mathbb{P}_{\beta_0}, \mathbb{P}_{\beta_i}) \\
 &= \sum_{t=1}^T D(\mathbb{P}_{\beta_0}(Y_{a_t}|Y_{a_1}, \dots, Y_{a_{t-1}}, \mathcal{X}_1, \dots, \mathcal{X}_t), \mathbb{P}_{\beta_i}(Y_{a_t}|Y_{a_1}, \dots, Y_{a_{t-1}}, \mathcal{X}_1, \dots, \mathcal{X}_t)) \\
 &\quad + \sum_{t=1}^T D(\mathbb{P}_{\beta_0}(\mathcal{X}_t|Y_{a_1}, \dots, Y_{a_{t-1}}, \mathcal{X}_1, \dots, \mathcal{X}_{t-1}), \mathbb{P}_{\beta_i}(\mathcal{X}_t|Y_{a_1}, \dots, Y_{a_{t-1}}, \mathcal{X}_1, \dots, \mathcal{X}_{t-1})) \\
 &= \sum_{t=1}^T \mathbb{E}_{\beta_0} \frac{\{X_{a_t,t}^T(\beta_i - \beta_0)\}^2}{2} \\
 &= \frac{\Delta^2}{2} \mathbb{E}_{\beta_0} \left[ \sum_{t=1}^T \mathbb{I}(a_t = i) \right],
 \end{aligned}$$

where the second equality holds since the distribution of  $\mathcal{X}_t$  does not change over  $\beta$ , and

$$\begin{aligned}
 & D(\mathbb{P}_{\beta_0}(Y_{a_t}|Y_{a_1}, \dots, Y_{a_{t-1}}, \mathcal{X}_1, \dots, \mathcal{X}_t), \mathbb{P}_{\beta_i}(Y_{a_t}|Y_{a_1}, \dots, Y_{a_{t-1}}, \mathcal{X}_1, \dots, \mathcal{X}_t)) \\
 &= \int \int \log \frac{d\mathbb{P}_{\beta_i}(y|a_t)}{d\mathbb{P}_{\beta_0}(y|a_t)} d\mathbb{P}_{\beta_0}(y|a_t) d\mathbb{P}_{\beta_0}(a_t) \\
 &= \int \frac{\{X_{a_t,t}^T(\beta_i - \beta_0)\}^2}{2} d\mathbb{P}_{\beta_0}(a_t) \\
 &= \mathbb{E}_{\beta_0} \frac{\{X_{a_t,t}^T(\beta_i - \beta_0)\}^2}{2}.
 \end{aligned}$$

Thus we have

$$\mathbb{E}_{\beta_i} \left[ \sum_{t=1}^T X_{a_t,t}^T \beta_i \right] \leq \Delta \mathbb{E}_{\beta_0} \left[ \sum_{t=1}^T \mathbb{I}(a_t = i) \right] + \frac{\Delta^2 T}{2} \sqrt{\mathbb{E}_{\beta_0} \left[ \sum_{t=1}^T \mathbb{I}(a_t = i) \right]}.$$

With (32),

$$\mathbb{E}_{\beta_i} [R(T)] \geq \Delta T - \Delta \mathbb{E}_{\beta_0} \left[ \sum_{t=1}^T \mathbb{I}(a_t = i) \right] - \frac{\Delta^2 T}{2} \sqrt{\mathbb{E}_{\beta_0} \left[ \sum_{t=1}^T \mathbb{I}(a_t = i) \right]}.$$

Taking average over  $i \in [d]$  gives

$$\begin{aligned}
 \frac{1}{d} \sum_{i=1}^d \mathbb{E}_{\beta_i} [R(T)] &\geq \Delta T - \frac{\Delta}{d} \sum_{i=1}^d \mathbb{E}_{\beta_0} \left[ \sum_{t=1}^T \mathbb{I}(a_t = i) \right] - \frac{\Delta^2 T}{2d} \sum_{i=1}^d \sqrt{\mathbb{E}_{\beta_0} \left[ \sum_{t=1}^T \mathbb{I}(a_t = i) \right]} \\
 &\geq \Delta T - \frac{\Delta T}{d} - \frac{\Delta^2 T \sqrt{d}}{2d} \sqrt{\sum_{i=1}^d \mathbb{E}_{\beta_0} \left[ \sum_{t=1}^T \mathbb{I}(a_t = i) \right]} \\
 &\geq \frac{\Delta T}{2} - \frac{\Delta^2 T \sqrt{T}}{2\sqrt{d}}.
 \end{aligned}$$

Setting  $\Delta = \frac{1}{2} \sqrt{\frac{d}{T}}$  gives

$$\frac{1}{d} \sum_{i=1}^d \mathbb{E}_{\beta_i} [R(T)] \geq \frac{1}{8} \sqrt{dT}.$$

Thus, there exists  $\beta_i$  such that  $\mathbb{E}_{\beta_i} [R(T)] \geq \frac{1}{8} \sqrt{dT}$ . □

## B LIMITATIONS

1. The regret bound is derived under stochastic conditions for contexts in Assumption 3. Although the same or similar assumptions have been used in the previous literature (Li et al., 2017; Amani et al., 2019; Oh et al., 2021; Kim et al., 2021), we hope that this can be relaxed in the future work. Nevertheless, achieving a regret bound sublinear in both time horizon and the dimensionality, even under such a stochastic assumption, has not been shown for any practical algorithm other than the variants of “Sup”-type algorithms (Auer, 2002a). We strongly believe that our work fills the long-standing gap between sublinear dependence on  $d$  and a practical algorithm other than SupLinUCB variants.
2. The proposed Hyran estimator requires more computations compared to ridge estimator in that it uses contexts of all arms and the imputation estimator. However, we believe that these additional computations are reasonable costs to obtain more precise estimator and to achieve a near-optimal regret bound.