1	
2	
3	
4	Supplementary Materials for
5 6	Plastic waste discharge to the global ocean constrained by seawater observations
7	Yanxu Zhang ^{1,2*†} , Peipei Wu ^{1†} , Ruochong Xu ¹ , Xuantong Wang ¹ , Lili Lei ^{1*} , Amina T.
8	Schartup ³ , Yiming Peng ¹ , Qiaotong Pang ¹ , Xinle Wang ¹ , Lei Mai ⁴ , Ruwei Wang ⁴ , Huan Liu ⁵ ,
9 10	Xiaotong Wang ⁵ , Arjen Luijendijk ^{6,7} , Eric Chassignet ⁸ , Xiaobiao Xu ⁸ , Huizhong Shen ⁹ , Shuxiu Zheng ¹⁰ , Eddy Y. Zeng ^{4*}
11	
11	School of Atmospheric Sciences, Nanjing University; Nanjing 210023, China.
12 13	² Frontiers Science Center for Critical Earth Material Cycling, Nanjing University; Nanjing 210023, China
14	³ Scripps Institution of Oceanography, University of California, San Diego; La Jolla, CA, USA.
15 16	⁴ Center for Environmental Microplastics Studies, Guangdong Key Laboratory of Environmental Pollution and Health, School of Environment, Jinan University; Guangzhou 511443, China.
17 18 19	⁵ State Key Joint Laboratory of ESPC, State Environmental Protection Key Laboratory of Sources and Control of Air Pollution Complex, School of Environment, Tsinghua University; Beijing, China.
20 21	⁶ Faculty of Civil Engineering and Geosciences, Delft University of Technology; Delft, Netherlands.
22	⁷ Hydraulic Engineering; Deltares, Delft, Netherlands.
23 24	⁸ Center for Ocean-Atmospheric Prediction Studies (COAPS), Florida State University; Tallahassee, FL, United States.
25 26	⁹ School of Environmental Science and Technology, Southern University of Science and Technology; Shenzhen, Guangdong, China.
27	¹⁰ College of Urban and Environmental Sciences, Peking University; Beijing, China
28 29	*Corresponding author. Email: YZ zhangyx@nju.edu.cn; LL lililei@nju.edu.cn; and EYZ eddyzeng@jnu.edu.cn
30 31	[†] These authors contributed equally.

33 Supplementary Discussion

34 Inclusion of seawater observations

Supplementary Table 8 lists the observed surface ocean plastic abundance data used in this 35 36 study. Isobe et al. compiled a multilevel dataset that includes almost all available ocean plastic 37 abundance data so far¹. The Isobe database includes a total of 9959 data points obtained by 38 Neuston net, WP2 net, Manta net, Bango net, and Plankton net. The identification method 39 includes visual identification, FTIR (Fourier transform infrared spectrophotometer), and Raman 40 spectroscopy. There is a large discrepancy among data obtained with a different method^{2,3}. The 41 risk of clogging and uncertainty in sample volumes also depends on the mesh size of the net and 42 the flow conditions³. Visual inspection is known to lead to an overestimation of the particle 43 count because 20-70% of the particles identified visually as plastics might be of other chemical compositions, e.g., coal ash, especially for the particle smaller than 500 µm^{4,5}. However, visual 44 45 identification misses the transparent and small microplastics thus underestimating the plastic 46 concentrations². The data obtained by different methodologies are thus generally not comparable 47 with each other. More importantly, different methodologies are used in different studies covering 48 different ocean basins. A mixture of data obtained by different methodologies may distort the 49 real spatial pattern of surface ocean plastic abundance and reduce the reliability of the 50 comparison between simulations and observations. There is a trade-off between "more data" and 51 "ghost spatial pattern" arising from different measurement methodologies. Therefore, we use 52 only the dataset obtained by Neuston net and the visual identification method due to its large

- sampling number and spatial coverage. The number of such data is 7431 (Supplementary Table
 8), accounting for 75% of the Isobe database. The data in different ocean basins are also
- 55 comparable due to similar methodology.
- 56 All the data used in this study are reported as numerical concentrations (*N*), which are transferred 57 to mass concentrations (*M*) following Cozar et al.⁶:

$$\log M(g \cdot km^{-2}) = 1.21 \times \log N(items \cdot km^{-2}) - 3.99$$
(1)

and are compared with modeled mass concentrations of plastics in the surface ocean. Such a

- transfer does not change the number of independent measurements used in this study. The
- 61 conversion bears uncertainty but the uncertainty is reduced due to the large sampling number⁷.
- 62 The item-mass conversion factors of all observed concentrations range from 1.3×10^{-5} to 2.4×10^{3}
- 63 g per item, with a mean value of 31 g per item. However, mass concentrations (or total mass) are
- 64 more comparable with plastic emission inventories that are also in a mass unit. Moreover, the 65 modeled number concentrations are prone to larger uncertainties due to the fragmentation
- 66 process, which is mass-conservative but could greatly change the number concentrations⁶.

67 Supplementary Methods

- 68 Other sources of plastics to the ocean than MPW
- 69 There are other potential sources contributing to the ocean plastics beyond riverine discharge,
- 70 coastal erosions, and marine sources that are considered in this study. One potential source is
- 71 atmospheric transport and deposition. The total deposition of plastics to ocean surfaces from land
- sources is 13 kilo Mt yr⁻¹, much smaller than the three sources mentioned in the main text.
- 73 Moreover, there is a suggested net transport of 9 kilo Mt yr⁻¹ plastics from ocean to land, i.e. the
- 74 loss of sea surface ocean plastics to the atmosphere (via mechanical processes similar to sea salt

- emissions) surpasses that is deposited to the ocean⁸. Another source is direct wastewater to ocean
- 76 by coastal population (other wastewater enters the ocean via rivers, hence being considered in
- this study), which is estimated about 0.44 kilo Mt yr⁻¹, even smaller than what we already
- considered⁹. Other plastic sources than mismanaged plastic waste include unintentional plastic
- remissions, such as fibers from textiles, tire wear particles, and lost resin pellets. We assume that
- 80 they have been included in the riverine inventories of plastic waste discharge, as these
- inventories were built upon riverine measurements that cover all plastic types. Natural disasters
 are also potential significant sources. For example, the Fukishima earthquake and tsunami in
- March, 2011 released \sim 20 million Mt of debris to the ocean¹⁰. However, the emission of plastic
- 84 waste in such events is poorly quantified at global scale, and its contribution to the ocean plastics
- 85 is rather small given its unusual and episodic nature.

86 Stokes drift

- 87 We take the estimated Stokes drift velocity from the GlobCurrent and apply it to all the plastic
- tracers in our model¹¹. The data are available between 1990 and 2015, with a time resolution of 3
- 89 hours. We calculate a 26-year average of the Stokes drift velocity for each month. In this way, 12
- 90 months of Stokes drift velocity is achieved and cycled in the model for the whole simulation
- 91 period. The strongest Stokes drift is simulated in the Southern Ocean and the high-latitude ocean
- 92 in the northern hemisphere where plastic concentrations are relatively low (Supplementary Fig.
 93 6), consistent with previous results¹². The modeled plastic accumulation in the subtropical gyres
- 95 b), consistent with previous results²². The modeled plastic accumulation in the subtropical gyre 94 is moved westward slightly by Stokes drift, while plastics in the Southern Ocean are moved
- 95 eastward.

96 Sinking and rising

97 The sinking/rising rate of plastics depends on its density. Plastic particles in our model are

- 98 treated as spheres. At steady state, the forces acting on plastic particles are balanced:
- 99

102

$$\mathbf{F}_{\mathbf{D}} + \mathbf{F}_{\mathbf{g}} + \mathbf{F}_{\mathbf{b}} = 0 \tag{2}$$

100 where F_D is vertical dragging force, F_g is gravity, and F_b is buoyancy. These forces are calculated 101 as:

$$\mathbf{F}_{\mathbf{g}} = V_{p} \rho_{p} \mathbf{g} \tag{3}$$

$$\mathbf{F}_{\mathbf{h}} = -V_{s} \boldsymbol{\rho}_{s} \mathbf{g}$$

104
$$\mathbf{F}_{\mathbf{D}} = -\frac{1}{2} C_D (\operatorname{Re}_s) A_p \rho_s \frac{(\mathbf{w} - \mathbf{w}_s)^3}{|\mathbf{w} - \mathbf{w}_s|}$$
(5)

105 where
$$V_p$$
 is the volume of the particle, while V_s is the volume of the particle that is submerged in
106 seawater ($V_p = V_s$ in this case, but $V_p > V_s$ for floating particles with zero sinking/rising velocity
107 relative to the seawater, e.g., unbiofouled PP and PE). C_D is the coefficient of dragging, which is
108 a function of the Reynolds number (Re) of a certain motion of a fluid. A_p is the horizontal
109 sectional area of a particle, ρ_s is the density of seawater, ρ_p is the mean density of a particle, **w** is
110 the vertical velocity of the particle, **w**_s is the vertical velocity of seawater, and **g** is the gravity
111 acceleration.

112 Based on Supplementary Equation (2)–(5), we get $(\mathbf{w}-\mathbf{w}_s)^2$:

113
$$\left(\mathbf{w} - \mathbf{w}_{s}\right)^{2} = \frac{4|\mathbf{g}|d(\rho_{p} - \rho_{s})}{3C_{D}(\operatorname{Re}_{s})\rho_{s}}$$
(6)

114 where *d* is Stokes diameter of a particle, and C_D is calculated as¹³:

(4)

115
$$C_D(\text{Re}) = \begin{cases} 24 \,\text{Re}^{-1} & \text{Re} \le 0.3 \\ 18.5 \,\text{Re}^{-0.6} & 0.3 < \text{Re} \le 1000 \\ 0.44 & 1000 < \text{Re} \le 20000 \end{cases}$$
(7)

116 Re_s is the Re of seawater and is calculated as:

117
$$\operatorname{Re}_{s} = \frac{d\rho_{s} |\mathbf{w} - \mathbf{u}_{s}|}{\mu_{s}}$$
(8)

118 Based on Supplementary Equation (6) (7), we get w-w_s:

$$\frac{d^2g(\rho_p - \rho_s)}{18\mu} \qquad \qquad \text{Re} \le 0.3$$

119
$$\mathbf{w} - \mathbf{w}_{s} = \begin{cases} \frac{0.153d^{1.143} [g(\rho_{p} - \rho_{s})]^{0.714}}{\rho_{s}^{0.286} \mu^{0.429}} & 0.3 < \text{Re} \le 1000 \end{cases}$$
(9)
$$\frac{1.74(\frac{dg(\rho_{p} - \rho_{s})}{\rho_{s}})^{\frac{1}{2}}}{1000 < \text{Re} < 200000} \end{cases}$$

- 120 Supplementary Equation (6) is a piecewise function. The three conditions of different Re are all
- 121 possible in reality because of the variety of particles, but it is hard to know which range of
- 122 Supplementary Equation (6) should be used in a certain situation, since Re should be calculated
- 123 directly by sinking velocity **w**, which is unknown here.
- 124 Notice that Supplementary Equation (7) can be represented by:

125
$$C_{D} = \frac{a}{\operatorname{Re}^{b}} \begin{cases} a = 24, b = 1 & \operatorname{Re} \le 0.3 \\ a = 18.5, b = 0.6 & 0.3 < \operatorname{Re} \le 1000 \\ a = 0.4, b = 0 & 1000 < \operatorname{Re} < 200000 \end{cases}$$
(10)

126 Combine Supplementary Equation (6) (8) (10) and eliminate $|\mathbf{w}-\mathbf{u}_s|$ and C_D :

127
$$\operatorname{Re} = \left(\frac{4}{3a}\right)^{\frac{1}{2-b}} \left(d^3 \frac{\rho_s g(\rho_p - \rho_s)}{\mu^2}\right)^{\frac{1}{2-b}}$$
(11)

128 Define *K*:

$$K = d^3 \frac{\rho_s g(\rho_p - \rho_s)}{\mu^2} \tag{12}$$

130 Then:

131

$$Re = \begin{cases} 0.0556K & Re \le 0.3 \\ 0.072K^{\frac{5}{7}} & 0.3 < Re \le 1000 \\ 1.74K^{\frac{1}{2}} & 1000 < Re < 200000 \end{cases}$$
(13)

132

$$\mathbf{w} - \mathbf{w}_{s} = \begin{cases} \frac{d^{2}g(\rho_{p} - \rho_{s})}{18\mu} & K \leq 5.4 \\ \frac{0.153d^{1.143}[g(\rho_{p} - \rho_{s})]^{0.714}}{\rho_{s}^{0.286}\mu^{0.429}} & 5.4 < K \leq 24 \\ 1.74(\frac{dg(\rho_{p} - \rho_{s})}{\rho_{s}})^{\frac{1}{2}} & K > 24 \end{cases}$$
133



142 Supplementary Fig. 1: The historical trends of global total plastic emissions during 1950-

2018 for the High (Lebreton), Middle (Mai), and Low (Weiss) scenarios. The abrupt decrease in the 1980s is associated with the MARPOL Convention that bans the damping of waste from ships.



151Calculated surface ocean mass [tonnes]152Supplementary Fig. 2: Probability distribution function of the calculated surface ocean

- **plastic mass**. The results are from the ensemble members (N = 52) driven by the Middle 154 emission scenario.





159 Supplementary Fig. 3: Parameters of the model ensemble (N = 50). a parameter values. b frequency distributions of the values. Parameters are represented as the ratio to the corresponding values in the test case simulation (Table 1), including focean: fraction of marine discharge to the total discharge; fbeach: beaching rate; fsediment: sedimentation rate; fbiofoul: biofouling rate; ffrag: fragmentation rate.



16710⁻¹10⁰10¹10²10³10⁴10⁵168Supplementary Fig. 4: Comparison between observed and modeled surface ocean plastic

169 mass concentrations driven by the best-estimate emissions. The background colors in panel a

are the modeled results, while the circles are observations. The dashed lines in panel **b** are 100:1, 10:1, 1:1, 1:10, and 1:100. All the concentrations, and the calculation of R^2 and RMSE are in a

171 10:1, 1:1, 1:10, and 1:100. All the concentrations, and the calculation of R^2 and RMSE are in a 172 base 10 logarithmic scale with a unit of g km⁻². The best-estimate emission is close to the middle

emission scenario and the simulated concentrations in panel **b** are just slightly higher than those

- 174 in Fig. 2e.
- 175



176Observed plastic concentration [g m³]Observed plastic concentration [g m³]177Supplementary Fig. 5: Comparison between observed and modeled vertical profile of

plastic mass. a Pacific. b Atlantic Ocean. The dash lines indicate individual observed profiles
 with the filled-colored circles representing sampling depths. The light blue solid lines are the

180 mean plastic mass concentrations over the sampling sites by the 52 member models under the

181 middle emission scenario (other emission scenarios simulate higher or lower concentrations but

182 with similar vertical trends), while the dark blue solid lines are the ensemble means. The

182 with similar vertical tickels), while the dark ofde sofie lines are the ensemble means. The 183 observations are from Egger et al. (2020) and Pabortsave and Lampitt (2020) for the Pacific and

- 184 Atlantic Ocean, respectively^{14,15}.
- 185
- 186



188 Supplementary Fig. 6: The modeled spatial pattern of surface plastic abundance. a Without

Stokes drift. **b** With Stokes drift. Compared with panel **a**, Stokes drift slightly changes the spatial pattern in panel **b**.



19415101520253035404550195Supplementary Fig. 7: Modeled amount of plastics in the water column, sediments, and

196 beaches. The 52 ensemble members are driven by the middle emission scenario. The parameters 197 of the model members are listed in Supplementary Table 7.

Supplementary Table	1. Mapping of emission inventory to the size ons of
Emission inventory	Model tracers
Microplastics	All assumed as the <0.0781-5 mm bin
Macroplastics	Equally distributed between 5-50 mm and > 50
	mm bins

Supplementary Table 1. Mapping of emission inventory to the size bins of our model

	Lebreton	Mai	Weiss
Asia	86.00%	69.00%	45.34%
Africa	7.80%	1.55%	11.31%
North America	0.95%	6.23%	14.78%
South America	4.80%	21.39%	17.31%
Europe	0.28%	1.71%	10.61%
Oceania	0.02%	0.16%	0.65%

Supplementary Table 2. Fraction of emissions from different continents

J	unit of 10 thousand metric tons ¹⁰ .							
	Туре	Type Global		North	Western	Middle		
				America	Europe	East		
	PE	8157.8	3648.1	1557.9	1101.2	534.5		
	PP	5606.8	3070.9	720.1	737.4	375.2		
	PVC	3854.9	2192.4	514.4	402	215.9		
	Others	2387.3	1345.9	323.8	326.1	126		

Supplementary Table 3. Consumption of different plastic types around the world in 2013, in the unit of 10 thousand metric $tons^{16}$. 220

FDkg m s ⁻² Dragging force of seawater (vertical) $\mathbf{F}_{\mathbf{b}} = -\frac{1}{2}C_{D}(\mathrm{Re}_{s})A_{p}\rho_{s}\frac{(\mathbf{w}- \mathbf{w}- \mathbf{w}-$	Parameter	Unit	Description	Value or formula
$ \begin{array}{c cccc} \mathbf{F_g} & \mathrm{kg} \mbox{ m s}^2 & \mathrm{Gravity} & \mathbf{F_g} = V_p \rho_p \mathbf{g} \\ \hline \mathbf{F_b} & \mathrm{kg} \mbox{ m s}^2 & \mathrm{Buoyancy} & \mathbf{F_b} = -V_s \rho_s \mathbf{g} \\ \hline C_D & \mathrm{unitless} & \mathrm{Coefficient} \mbox{ of dragging (function of } & C_D = C_D(\mathrm{Re}) \\ \hline \mathrm{Res} & \mathrm{unitless} & \mathrm{Reynolds} \mbox{ number of seawater} & \mathrm{Res}_s = \frac{d\rho_s \mathbf{W} - \mathbf{w}_s }{\mu_s} \\ \hline \\ \hline A_p & \mathrm{m}^2 & \mathrm{Sectional area} & A_p = \frac{1}{4} \pi d^2 \\ \hline d & \mathrm{m} & \mathrm{Stokes \ diameter \ (For \ strict \ sphere \\ particle, \ stokes \ diameter \ is \ normal \\ diameter. \ For \ other \ shapes \ of \\ particles, \ stokes \ diameter \ is \ normal \\ diameter \ of \ the \ sphere \ particle \ which \\ has \ the \ same \ sinking \ speed. \end{array} } & V_p = \frac{1}{6} \pi d^3 \\ \hline V_s & \mathrm{m}^3 & \mathrm{Volume \ of \ microplastics \ particle \\ p_s & \mathrm{kg \ m}^{-3} & \mathrm{Mean \ density \ of \ particle } \\ \hline M_s & \mathrm{kg \ m}^{-3} & \mathrm{Density \ of \ sea \ water} & \mathrm{Model \ input} \\ \hline p_s & \mathrm{kg \ m}^{-3} & \mathrm{Density \ of \ sea \ water} \\ \hline \mathbf{w} & \mathrm{m \ s}^{-1} & \mathrm{Sinking \ or \ rising \ speed \ (Need \ also \ a \ technique \ to \ eliminate \ Res \ risk \ seawater \\ \hline \mathbf{w} & \mathrm{m \ s}^{-1} & \mathrm{Sinking \ or \ rising \ speed \ (Need \ also \ a \ technique \ to \ eliminate \ Res \ risk \ risk \ seawater \ Model \ input \\ \hline \mathbf{w} & \mathrm{m \ s}^{-1} & Sinking \ or \ rising \ speed \ (Need \ also \ a \ technique \ to \ eliminate \ Res \ risk \ risk \ risk \ risk \ risk \ Res \ risk \ Res \ $	FD	kg m s ⁻²	Dragging force of seawater (vertical)	$\mathbf{F}_{\mathbf{D}} = -\frac{1}{2}C_D(\operatorname{Re}_s)A_p\rho_s \frac{(\mathbf{w} - \mathbf{w}_s)}{ \mathbf{w} - \mathbf{w}_s }$
Fbkg m s²Buoyancy $\mathbf{F}_{\mathbf{b}} = -V_s \rho_s \mathbf{g}$ C_D unitlessCoefficient of dragging (function of Re) $C_D = C_D(\mathbf{Re})$ \mathbf{Re}_s unitlessReynolds number of seawater $\mathbf{Re}_s = \frac{d\rho_s \mathbf{w} - \mathbf{w}_s }{\mu_s}$ A_p m²Sectional area $A_p = \frac{1}{4}\pi d^2$ d mStokes diameter (For strict sphere particle, stokes diameter is normal diameter. For other shapes of particles, stokes diameter is the diameter of the sphere particle which has the same sinking speed.)Model input V_p m³Volume of microplastics particle submerged in sweater (when sinking or rising) $V_p = \frac{1}{6}\pi d^3$ ρ_p kg m³Density of sea waterModel input μ_s kg m³Density of sea waterModel input μ_s kg m¹Dynamic-viscosity coefficient of seawater $(\mathbf{w} - \mathbf{w}_s)^2 = \frac{4 \mathbf{g} d(\rho_p - \rho_s)}{3C_D(\mathbf{Re}_s)\rho_s}$ \mathbf{w} m s¹Sinking or rising speed (Need also a technique to eliminate Re. Flux of particle also have parameterization) $(\mathbf{w} - \mathbf{w}_s)^2 = \frac{4 \mathbf{g} d(\rho_p - \rho_s)}{3C_D(\mathbf{Re}_s)\rho_s}$	Fg	kg m s ⁻²	Gravity	$\mathbf{F}_{\mathbf{g}} = V_p \rho_p \mathbf{g}$
$\begin{array}{c cccc} C_{\mathcal{D}} & \mbox{unitless} & \mbox{Coefficient of dragging (function of Re)} & C_{\mathcal{D}} = C_{\mathcal{D}}(\text{Re}) \\ \hline \text{Re} & \mbox{unitless} & \mbox{Reynolds number of seawater} & \mbox{Re}_{s} = \frac{d\rho_{s} \mathbf{w} - \mathbf{w}_{s} }{\mu_{s}} \\ \hline M_{p} & \mbox{m}^{2} & \mbox{Sectional area} & \mbox{A}_{p} = \frac{1}{4}\pi d^{2} \\ \hline M_{p} & \mbox{m}^{2} & \mbox{Stokes diameter (For strict sphere particle, stokes diameter is normal diameter. For other shapes of particles, stokes diameter is the diameter of the sphere particle which has the same sinking speed.) \\ \hline V_{p} & \mbox{m}^{3} & \mbox{Volume of microplastics particle} & \mbox{V}_{p} = \frac{1}{6}\pi d^{3} \\ \hline Vs & \mbox{m}^{3} & \mbox{Volume of microplastics particle} & \mbox{V}_{s} = V_{p} \\ \hline g & \mbox{m} s^{-2} & \mbox{Gravitational acceleration} & \mbox{9.8} \\ \mu_{s} & \mbox{kg m}^{-3} & \mbox{Density of sea water} & \mbox{Model input} \\ \hline g & \mbox{m} s^{-1} & \mbox{Sinking or rising speed (Need also a technique to eliminate Re. Flux of particle also have parameterization) \\ \hline w_{c} & \mbox{m} s^{-1} & \mbox{Velocity of seawater} & \mbox{Model input} \\ \hline w & \mbox{m} s^{-1} & \mbox{Velocity of seawater} & \mbox{Model input} \\ \hline w & \mbox{m} s^{-1} & \mbox{Velocity of seawater} & \mbox{Model input} \\ \hline w & \mbox{m} s^{-1} & \mbox{Velocity of seawater} & \mbox{Model input} \\ \hline w & \mbox{m} s^{-1} & \mbox{Velocity of seawater} & \mbox{Model input} \\ \hline w & \mbox{m} s^{-1} & \mbox{Velocity of seawater} & \mbox{Model input} \\ \hline w & \mbox{m} s^{-1} & \mbox{Velocity of seawater} & \mbox{Model input} \\ \hline w & \mbox{m} s^{-1} & \mbox{Velocity of seawater} & \mbox{Model input} \\ \hline w & \mbox{m} s^{-1} & \mbox{Velocity of seawater} & \mbox{Model input} \\ \hline w & \mbox{m} s^{-1} & \mbox{Velocity of seawater} & \mbox{Model input} \\ \hline w & \mbox{m} s^{-1} & \mbox{Velocity of seawater} & \mbox{Model input} \\ \hline w & \mbox{m} s^{-1} & \mbox{Velocity of seawater} & \mbox{Model input} \\ \hline w & \mbox{m} s^{-1} & \mbox{Velocity of seawater} & \mbox{Model input} \\ \hline w & \mbox{m} s^{-1} & Veloc$	Fb	kg m s ⁻²	Buoyancy	$\mathbf{F}_{\mathbf{b}} = -V_{s}\boldsymbol{\rho}_{s}\mathbf{g}$
ResunitlessReynolds number of seawater $\operatorname{Re}_{s} = \frac{d\rho_{s} \mathbf{w} - \mathbf{w}_{s} }{\mu_{s}}$ A_{p} m²Sectional area $A_{p} = \frac{1}{4}\pi d^{2}$ d mStokes diameter (For strict sphere particle, stokes diameter is normal diameter. For other shapes of particles, stokes diameter is the diameter of the sphere particle which has the same sinking speed.)Model input V_{p} m³Volume of microplastics particle submerged in sweater (when sinking or rising) $V_{p} = \frac{1}{6}\pi d^{3}$ ρ_{p} kg m³Mean density of particle $V_{s}=V_{p}$ p_{s} kg m³Density of sea waterModel input \mathbf{g} m s²²Gravitational acceleration 9.8 μ_{s} kg m¹Dynamic-viscosity coefficient of seawaterModel input \mathbf{w} m s²¹Sinking or rising speed (Need also a technique to eliminate Re. Flux of particle and settling of particle also have parameterization)($\mathbf{w} - \mathbf{w}_{s}$)² = $\frac{4 \mathbf{g} d(\rho_{p} - \rho_{s})}{3C_{D}(\text{Re}_{s})\rho_{s}}$	C_D	unitless	Coefficient of dragging (function of Re)	$C_D = C_D(\text{Re})$
A_p m^2 Sectional area $A_p = \frac{1}{4}\pi d^2$ d mStokes diameter (For strict sphere particle, stokes diameter is normal diameter. For other shapes of particles, stokes diameter is the diameter of the sphere particle which has the same sinking speed.)Model input V_p m^3 Volume of microplastics particle submerged in sweater (when sinking or rising) $V_p = \frac{1}{6}\pi d^3$ V_s m^3 Volume of microplastics particle submerged in sweater (when sinking or rising) $V_s = V_p$ ρ_p kg m ⁻³ Density of sea waterModel input g $m s^{-2}$ Gravitational acceleration seawater9.8 μ_s kg m ⁻¹ Dynamic-viscosity coefficient of seawaterModel inputw $m s^{-1}$ Sinking or rising speed (Need also a technique to eliminate Re. Flux of particle and settling of particle also have parameterization) $(\mathbf{w} - \mathbf{w}_s)^2 = \frac{4 \mathbf{g} d(\rho_p - \rho_s)}{3C_D(Re_s)\rho_s}$	Res	unitless	Reynolds number of seawater	$\operatorname{Re}_{s} = \frac{d\rho_{s} \mathbf{w} - \mathbf{w}_{s} }{\mu_{s}}$
dmStokes diameter (For strict sphere particle, stokes diameter is normal diameter. For other shapes of particles, stokes diameter is the diameter of the sphere particle which has the same sinking speed.)Model input V_p m³Volume of microplastics particle submerged in sweater (when sinking or rising) $V_p = \frac{1}{6}\pi d^3$ ρ_p kg m³Volume of microplastics particle submerged in sweater (when sinking or rising) $V_s = V_p$ ρ_s kg m³Mean density of particleModel input g m s²²Gravitational acceleration seawater9.8 μ_s kg m¹Dynamic-viscosity coefficient of particle and settling of particle also have parameterization)Model inputwm s¹Vincity of seawater velocity of seawaterModel inputwm s¹Vincity of seawater velocity of seawaterModel inputwm s¹Vincity of seawater velocity of seawaterModel input	A_p	m ²	Sectional area	$A_p = \frac{1}{4}\pi d^2$
V_p m^3 Volume of microplastics particle $V_p = \frac{1}{6}\pi d^3$ Vs m^3 Volume of microplastics particle submerged in sweater (when sinking or rising) $Vs = V_p$ ρ_p kg m ⁻³ Mean density of particleModel input ρ_s kg m ⁻³ Density of sea waterModel input \mathbf{g} $m s^{-2}$ Gravitational acceleration9.8 μ_s kg m ⁻¹ Dynamic-viscosity coefficient of seawaterModel input \mathbf{w} $m s^{-1}$ Sinking or rising speed (Need also a technique to eliminate Re. Flux of particle and settling of particle also have parameterization) $(\mathbf{w} - \mathbf{w}_s)^2 = \frac{4 \mathbf{g} d(\rho_p - \rho_s)}{3C_D(Re_s)\rho_s}$	d	m	Stokes diameter (For strict sphere particle, stokes diameter is normal diameter. For other shapes of particles, stokes diameter is the diameter of the sphere particle which has the same sinking speed.)	Model input
Vsm³Volume of microplastics particle submerged in sweater (when sinking or rising) $Vs=V_p$ ρ_p kg m⁻³Mean density of particleModel input ρ_s kg m⁻³Density of sea waterModel input g m s⁻²Gravitational acceleration9.8 μ_s kg m⁻¹Dynamic-viscosity coefficient of seawaterModel inputwm s⁻¹Sinking or rising speed (Need also a technique to eliminate Re. Flux of particle and settling of particle also have parameterization) $(\mathbf{w} - \mathbf{w}_s)^2 = \frac{4 \mathbf{g} d(\rho_p - \rho_s)}{3C_D(\text{Re}_s)\rho_s}$	V_p	m ³	Volume of microplastics particle	$V_p = \frac{1}{6}\pi d^3$
ρ_p kg m ⁻³ Mean density of particleModel input ρ_s kg m ⁻³ Density of sea waterModel input g m s ⁻² Gravitational acceleration9.8 μ_s kg m ⁻¹ Dynamic-viscosity coefficient of seawaterModel inputwm s ⁻¹ Sinking or rising speed (Need also a technique to eliminate Re. Flux of particle and settling of particle also have parameterization)(w - w_s)^2 = $\frac{4 \mathbf{g} d(\rho_p - \rho_s)}{3C_D(\text{Re}_s)\rho_s}$	Vs	m ³	Volume of microplastics particle submerged in sweater (when sinking or rising)	$V_{S}=V_{p}$
ρ_s kg m ⁻³ Density of sea waterModel input g m s ⁻² Gravitational acceleration9.8 μ_s kg m ⁻¹ Dynamic-viscosity coefficient of seawaterModel input w m s ⁻¹ Sinking or rising speed (Need also a technique to eliminate Re. Flux of particle and settling of particle also have parameterization) $(w - w_s)^2 = \frac{4 \mathbf{g} d(\rho_p - \rho_s)}{3C_D(\text{Re}_s)\rho_s}$ w_s m s ⁻¹ Velocity of seawaterModel input	$ ho_p$	kg m ⁻³	Mean density of particle	Model input
gm s ⁻² Gravitational acceleration9.8 μ_s kg m ⁻¹ s ⁻¹ Dynamic-viscosity coefficient of seawaterModel inputwm s ⁻¹ Sinking or rising speed (Need also a technique to eliminate Re. Flux of particle and settling of particle also have parameterization)(w - w_s)^2 = $\frac{4 \mathbf{g} d(\rho_p - \rho_s)}{3C_D(\mathrm{Re}_s)\rho_s}$ w_sm s ⁻¹ Velocity of seawaterModel input	ρ_s	kg m ⁻³	Density of sea water	Model input
$\mu_{s} \qquad \begin{array}{c} \text{kg m}^{-1} & \text{Dynamic-viscosity coefficient of} \\ \text{w} & \text{m s}^{-1} & \text{Sinking or rising speed (Need also a} \\ & \text{technique to eliminate Re. Flux of} \\ & \text{particle and settling of particle also} \\ & \text{have parameterization)} \end{array} \qquad (\mathbf{w} - \mathbf{w}_{s})^{2} = \frac{4 \mathbf{g} d(\rho_{p} - \rho_{s})}{3C_{D}(\text{Re}_{s})\rho_{s}}$	g	m s ⁻²	Gravitational acceleration	9.8
w m s ⁻¹ Sinking or rising speed (Need also a technique to eliminate Re. Flux of particle and settling of particle also have parameterization) $(\mathbf{w} - \mathbf{w}_s)^2 = \frac{4 \mathbf{g} d(\rho_p - \rho_s)}{3C_D(\text{Re}_s)\rho_s}$	μ_s	kg m ⁻¹ s ⁻¹	Dynamic-viscosity coefficient of seawater	Model input
\mathbf{w}_{c} m s ⁻¹ Velocity of seawater Model input	w	m s ⁻¹	Sinking or rising speed (Need also a technique to eliminate Re. Flux of particle and settling of particle also have parameterization)	$(\mathbf{w} - \mathbf{w}_s)^2 = \frac{4 \mathbf{g} d(\rho_p - \rho_s)}{3C_D(\operatorname{Re}_s)\rho_s}$
my mis velocity of seawater withder input	Ws	m s ⁻¹	Velocity of seawater	Model input

Supplementary Table 4. Model parameterization of plastic particle settling.

Parameter	Unit	Description	Value or formula
Fs	kg m s ⁻²	Dragging force by sea water (horizontal)	$\mathbf{F}_{\mathbf{s}} = -\frac{1}{2}C_D(\operatorname{Re}_s)A_s\rho_s \frac{(\mathbf{u} - \mathbf{u}_s)^3}{ \mathbf{u} - \mathbf{u}_s }$
Fa	kg m s ⁻²	Dragging force by air (horizontal)	$\mathbf{F}_{\mathbf{a}} = -\frac{1}{2}C_D(\operatorname{Re}_a)A_a\rho_a \frac{(\mathbf{u} - \mathbf{u}_a)}{ \mathbf{u} - \mathbf{u}_a }$
Fc	kg m s ⁻²	Coriolis force	$\mathbf{F}_{\mathbf{c}} = V_p \rho_p f_C \mathbf{u}$
Re _a	unitless	Reynolds number of seawater	$Re_{a} = \frac{d\rho_{a} \mathbf{u} - \mathbf{u}_{a} }{\mu_{a}}$
Vs	m ³	Volume of microplastics particle submerged in sweater	$V_{s} = \frac{1}{6}\pi d^{3} - \pi h^{2} (\frac{d}{2} - \frac{h_{a}}{3})$
h _a	m	height of the upper part (exposed to air)	By solving $\mathbf{F}_{g} + \mathbf{F}_{b} = 0$
A_a	m ²	Sectional area of particle exposed to air	$A_a = \frac{1}{4}r^2(\alpha - \sin\alpha)$
			$\alpha = 2\arccos(1 - \frac{2h_a}{d})$
A_s	m ²	Sectional area of particle exposed to seawater	$A_s = \frac{1}{4}\pi d^2 - A_a$
$ ho_a$	kg m ⁻³	Density of air	Model input
fc	rad s ⁻¹	Coriolis parameter	$f_c = 2\Omega \sin \varphi$
Ω	rad s ⁻¹	Angular speed of the earth	7.3×10 ⁻⁵
φ	degree	Latitude	Model grid
u	m s ⁻¹	Drifting speed (using gradient descent and fourth-order Adams method to calculate)	$m\frac{d\mathbf{u}}{dt} = \mathbf{F}_{\mathbf{s}} + \mathbf{F}_{\mathbf{a}} + \mathbf{F}_{\mathbf{c}}$

Supplementary Table 5. Model parameterization of plastic particle drifting.

Parameter	Unit	Description	Value or formula		
V_{bf}	m ³	Volume of biofilm	$\frac{dV_{bf}}{dt} = V_a \theta_p \frac{dA}{dt} + V_a A \frac{d\theta_p}{dt}$		
Va	m ³	Individual algae volume	2.0×10 ⁻¹⁶		
A	# m ⁻²	the biomass of attached algae	$\frac{dA}{dt} = \frac{\beta_a A_a}{\theta_p} - m_a A$		
θ_p	m ²	surface area of plastic particle	Model input		
β_a	$m^3 s^{-1}$	Encounter kernel rate	$\beta_a = \beta_{brownian} + \beta_{shear}$		
A_a	# m ⁻³	Ambient algae concentration	Model input		
m_a	s ⁻¹	Mortality rate	4.5×10 ⁻⁶		
$eta_{_{brownian}}$	$m^3 s^{-1}$	Brownian motion frequencies	$\beta_{brownian} = 4\pi (D_p + D_a)(r_p + r_a)$		
$eta_{\scriptscriptstyle shear}$	m ³ s ⁻¹	Advective shear collision frequencies	$\beta_{shear} = 1.3\gamma (r_p + r_a)^3$		
D_p	$m^2 s^{-1}$	Diffusivity of plastics	$D_{p} = \frac{k(T + 273.16)}{6\pi\mu_{sw}r_{p}}$		
D _a	$m^2 s^{-1}$	Diffusivity of individual algae cells	$D_a = \frac{k(T + 273.16)}{6\pi\mu_{sw}r_a}$		
r_p	m	radius of plastics	Model input		
<i>r</i> _a	m	radius of algae cells	Model input		
k	kg m ⁻¹ s ⁻¹	Boltzmann constant	1.3806×10 ⁻²³		
Т	°C	Seawater temperature	Model input		
$ ho_{\scriptscriptstyle b\!f}$	kg m ⁻³	Algae density	1388		
γ	s ⁻¹	Shear rate	1.9676		
μ_{sw}	kg m ⁻¹ s ⁻¹	Dynamic water viscosity	1.174×10 ⁻³		
$ au_{trans}$	s ⁻¹	Fraction of transformation between biofouled and unbiofouled plastics	$-\frac{dV_{bf}}{dt}$		
			$\tau_{trans} = O \frac{\Delta V}{\Delta V}$		
ΔV	m ³	Deviation of volume between the two plastics	Calculate in the model		
$V_{PE_{neutral}}$	m ³	Volume of a neutral PE particle	$\frac{4}{3}\pi r_{PE_{neutral}}^3$		
$V_{PE_{floating}}$	m ³	Volume of a floating PE particle	$\frac{4}{3}\pi r_{PE_{floating}}^{3}$		
			5		

Supplementary Table 6. Model parameterization of plastic particle biofouling and defouling¹⁷.

231	Supplementary Table 7. Parameters of ensemble model members used in this study (ratios to
232	those of the test scenario).

No.		focean ^a	fbe ach ^b	fsediment ^c	fbiofoul ^d	ffrag ^e
1	l	1.65	2.06	0.15	9.37	0.29
2	2	1.11	1.82	1.18	14.06	23.78
3	3	1.07	0.73	0.38	0.41	0.27
4	ł	1.04	2.58	0.44	0.72	3.83
5	5	1.61	1.36	3.26	2.72	0.64
6	5	1.21	0.78	0.35	2.08	1.08
7	7	0.91	1.22	3.12	1.57	1.25
8	3	1.14	1.04	0.41	2.47	5.06
9)	0.73	2.45	0.82	0.76	0.36
1	10	0.60	0.29	1.50	6.29	1.84
1	1	1.43	2.01	0.06	0.82	1.50
1	2	1.36	0.02	0.31	2.49	0.87
1	3	1.28	0.28	0.15	2.40	3.95
1	 4	1.82	0.97	0.49	4.54	0.19
1	15	0.13	1.15	3.95	0.40	0.23
1	16	0.93	1.01	2.60	1.28	0.11
1	17	0.73	0.77	8.07	2.87	0.94
1	18	1.65	0.22	0.67	5.08	5.64
1	19	1.37	1.37	0.51	2.36	0.39
2	20	1.29	1.21	3.71	0.61	2.08
2	21	1.40	0.33	1.20	6.29	1.14
2	22	0.85	1.34	0.73	1.67	0.86
2	23	0.99	1.35	4.80	1.68	6.67
2	24	0.78	1.18	0.38	0.23	2.03
2	25	1.31	1.22	1.58	0.37	0.56
2	26	0.95	0.48	1.47	15.23	0.57
2	27	1.32	0.22	4.67	0.33	1.27
2	28	0.69	1.38	1.01	0.95	29.82
2	29	0.68	0.96	21.95	0.27	1.89
3	30	0.46	1.77	1.46	2.12	0.73
3	81	1.12	2.10	0.07	0.15	1.61
3	32	0.67	0.78	0.18	0.35	0.63
3	33	0.64	0.35	0.62	0.34	4.69
3	34	0.51	2.36	0.65	0.19	0.49
3	85	1.47	1.79	1.20	1.39	2.07
3	86	0.27	0.56	0.12	0.60	2.98
3	87	1.36	2.72	1.21	0.08	6.99
3	38	1.64	0.56	1.29	2.45	1.56
3	<u>89</u>	1.35	0.92	0.96	1.11	0.40
4	10	1.71	1.00	2.20	0.37	0.29
4	11	0.95	0.81	3.96	2.01	1.86
4	12	0.28	0.27	1.26	0.67	4.42
4	13	1.67	0.56	2.74	4.99	1.45

44	1.81	1.80	1.28	2.74	1.25
45	0.79	1.27	1.04	0.66	7.68
46	1.11	3.05	0.71	1.91	6.18
47	2.36	1.23	0.40	2.52	0.22
48	0.86	1.20	5.56	5.23	0.97
49	1.46	0.76	2.14	9.07	1.20
50	0.85	0.62	2.28	4.66	11.56
51	0.13	3.05	21.95	15.23	29.82
52	2.36	0.02	0.06	0.08	0.11
mean ^f	1.11	1.18	2.37	2.87	3.62
stdev ^g	0.50	0.77	4.28	3.70	6.53

^afractions of the ocean emission to the total discharge. ^bbeaching rate. ^csedimentation rate. ^dbiofouling rate. ^efragmentation rate. ^fthe mean of all the members. ^gthe standard deviation of the members.

Area	Sampli ng method	Mesh size [mm]	Numb er of data	Witho ut fiber (%)	Flowm eter	Identifi cation method	Unit	Reference
Eastern N. Pacific	N ^a	0.335	2529	NR⁵	W/O ^c	V ^e	pieces/ km ²	Law et al. 2014 ¹⁸
World's ocean	Ν	0.2	1943	100 ^f	W ^d	V	pieces/ km ²	Cozar et al. 2014^6
World's ocean	Ν	0.33	679	100 ^g	W/O	V	pieces/ km ²	Eriksen et al. 2014 ¹⁹
Western N. Atlantic & Caribbean Sea ^h	Ν	0.335	2280	NR	W/O	V	pieces/ km ²	Law et al. 2010 ²⁰

Supplementary Table 8. summarizes the data sources and measurement procedures.

^aNeuston net, ^bNot recorded, ^{c,d}Without or with a flowmeter, ^eVisual identification, ^fFibrous microplastics were discarded by this project, ^gThe "vast majority" of collected microplastics

were fragments, ^hAlso includes macroplastics.

247 Supplementary References:

- Isobe, A. *et al.* A multilevel dataset of microplastic abundance in the world's upper ocean and the Laurentian Great Lakes. *Microplastics and Nanoplastics* 1 (2021).
- Song, Y. K. *et al.* A comparison of microscopic and spectroscopic identification methods
 for analysis of microplastics in environmental samples. *Marine Pollution Bulletin* 93,
 202-209 (2015).
- 3. Bai, M., Lin, Y., Hurley, R. R., Zhu, L. & Li, D. Controlling factors of microplastic
 riverine flux and implications for reliable monitoring strategy. *Environmental Science & Technology* 56, 48–61 (2021).
- Eriksen, M. *et al.* Microplastic pollution in the surface waters of the Laurentian Great
 Lakes. *Marine Pollution Bulletin* 77, 177-182 (2013).
- 5. Hidalgo-Ruz, V., Gutow, L., Thompson, R. C. & Thiel, M. Microplastics in the marine
 environment: A review of the methods used for identification and quantification. *Environmental Science & Technology* 46, 3060–3075 (2012).
- 261 6. Cozar, A. *et al.* Plastic debris in the open ocean. *Proceedings of the National Academy of Sciences* 111, 10239-10244, doi:10.1073/pnas.1314705111 (2014).
- 7. Roebroek, C. T. J., Laufkötter, C., González-Fernández, D. & van Emmerik, T. The quest
 for the missing plastics: Large uncertainties in river plastic export into the sea. *Environmental Pollution* **312** (2022).
- 8. Brahney, J. *et al.* Constraining the atmospheric limb of the plastic cycle. *Proceedings of the National Academy of Sciences* 118 (2021).
- 9. Weiss, L. *et al.* The missing ocean plastic sink: Gone with the rivers. *Science* 373, 107-111 (2021).
- 27010.BBC NEWS. Japan's tsunami debris: Five remarkable stories,271<<u>https://www.bbc.com/news/world-asia-35638091</u>> (2016).
- 272 11. GlobCurrent. *Data catalogue*, <<u>http://globcurrent.ifremer.fr/products-data/data-</u>
 273 <u>catalogue</u>> (2013).
- 274 12. Carrasco, A., Semedo, A., Isachsen, P. E., Christensen, K. H. & Saetra, Ø. Global surface
 275 wave drift climate from ERA-40: the contributions from wind-sea and swell. *Ocean*276 *Dynamics* 64 (2014).
- 277 13. Khalaf, H. K. *The theoretical investigation of drag coefficient and settling velocity correlations* Master thesis, Nahrain University, (2009).
- Egger, M., Sulu-Gambari, F. & Lebreton, L. First evidence of plastic fallout from the
 North Pacific Garbage Patch. *Scientific Reports* 10 (2020).
- 15. Pabortsava, K. & Lampitt, R. S. High concentrations of plastic hidden beneath the surface
 of the Atlantic Ocean. *Nature Communications* 11 (2020).
- 283 16. China Plastic. China plastics industry yearbook. (China Petrocheical Press, 2014).
- 17. Kooi, M., Van Nes, E. H., Scheffer, M. & Koelmans, A. A. Ups and downs in the ocean:
 Effects of biofouling on the vertical transport of microplastics. *Environmental Science & Technology* 51, 7963–7971 (2017).
- 18. Law, K. L. *et al.* Distribution of surface plastic debris in the eastern Pacific Ocean from
 an 11-Year data set. *Environmental Science & Technology* 48, 4732-4738 (2014).
- 289 19. Eriksen, M. *et al.* Plastic pollution in the world's oceans: More than 5 trillion plastic
 290 pieces weighing over 250,000 tons afloat at sea. *PloS one* 9, e111913 (2014).
- 20. Law, K. L. *et al.* Plastic Accumulation in the North Atlantic Subtropical Gyre. *Science*329, 1185-1188 (2010).