

Supplementary Information for Fast and Simple Super-resolution with Single Images

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Here we present details of the conjugate gradients (CG) algorithm and its Matlab implementation, based on the Wikipedia lemma (https://en.wikipedia.org/wiki/Conjugate_gradient_method). We start with the one-dimensional case. The PSF is represented by the m -by- n matrix S and the observed "image" is the m -vector y . We have to solve the system of penalized least squares equations $(S'S + \kappa I + \lambda D'D)x = S'y$ for the n -vector x . For efficiency, it is re-written as $Gx = u$.

Listing 1: Code for standard conjugate gradients algorithm.

```
1  % Set up ridge regression
2  n = size(S, 2);
3  kappa = 0.001;
4  D = diff(eye, n);
5  lambda = 1;
6  G = S' * S + kappa * eye(n) + lambda * D' * D;
7  u = S' * y;
8
9  % Initialize for conjugate gradients
10 x = zeros(n, 1);
11 r = u - G * x;
12 p = r;
13
14 % Iterate CG
15 for it = 1:50
16
17 % Update p and r
```

```

18  q = G * p;
19  alpha = (r' * r) / (p' * q);
20  x = x + alpha * p;
21  rnew = r - alpha * q;
22  beta = (rnew' * rnew) / (r' * r);
23  r = rnew;
24  p = r + beta * p;
25
26  % Monitor convergence
27  err = sqrt(mean((u - G * x) .^ 2));
28  disp([it log10(err)])
29  if err < 1e-3
30  break
31  end
32  end

```

The core of the algorithm takes only seven lines. One operation is a matrix-vector product ($q = G * p$), all others work on only vectors.

Listing 2: Code for two-dimensional conjugate gradients algorithm.

```

1  % Prepare components of linear system
2  U = S1' * Y * S2;
3  G1 = S1' * S1;
4  G2 = S2' * S2;
5  kappa = 1;
6  lambda = 1;
7  D1 = diff(eye(n1));
8  D2 = diff(eye(n2));
9  V1 = lambda * D1' * D1;
10 V2 = lambda * D2' * D2;
11
12 % Initialize for conjugate gradients
13 R = U;
14 P = R;
15 n1 = size(G1, 2);
16 n2 = size(G2, 2);
17 X = zeros(n1, n2);
18
19 for it = 1:100
20

```

```

21 % Update P and R
22 Q = G1 * P * G2 + kappa * P + V1 * P + P * V2';
23 alpha = sum(R(:) .^ 2) / sum(P(:) .* Q(:));
24 X = X + alpha * P;
25 Rnew = R - alpha * Q;
26 rs1 = sum(R(:) .^ 2);
27 rs2 = sum(Rnew(:) .^ 2);
28 beta = rs2 / rs1;
29 P = Rnew + beta * P;
30 R = Rnew;
31
32 % Monitor convergence
33 rms = sqrt(rs1 / (n1 * n2));
34 disp([it log10(rms)])
35 if rms < 1e-3
36 break
37 end
38 end

```