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## 1 Calculating the variance of $\varepsilon$

The set $\mathbb{O}$ is a mixture of three types of TISs $\mathbb{T}, \mathbb{F}_{u}$ and $\mathbb{F}_{d}$, we have

$$
\begin{equation*}
\hat{W}_{\mathbb{O}}^{(\mathbb{O})}=\alpha_{\mathbb{T}} \hat{W}_{\mathbb{T}}^{(\mathbb{O})}+\alpha_{\mathbb{F}_{u}} \hat{W}_{\mathbb{F}_{u}}^{(\mathbb{O})}+\alpha_{\mathbb{F}_{d}} \hat{W}_{\mathbb{F}_{d}}^{(\mathbb{O})}, \tag{1}
\end{equation*}
$$

where the superscript $(\mathbb{O})$ refers to PWMs obtained from the set $\mathbb{O}$ and three PWMs $\hat{W}_{\mathbb{T}}^{(\mathbb{O})}$, $\hat{W}_{\mathbb{F}_{u}}^{(\mathbb{O})}$ and $\hat{W}_{\mathbb{F}_{d}}^{(\mathbb{O})}$ are virtually calculated from the three types of TISs in the set $\mathbb{O}$. Since we don't know these three PWMs, we use three other PWMs obtained from the set $\mathbb{I}$ to replace them, and an error $\varepsilon$ is generated

$$
\begin{equation*}
\hat{W}_{\mathscr{O}}^{(\mathbb{O})}=\alpha_{\mathbb{T}} \hat{W}_{\mathbb{T}}^{(\mathbb{I})}+\alpha_{\mathbb{F}_{u}} \hat{W}_{\mathbb{F}_{u}}^{(\mathbb{I})}+\alpha_{\mathbb{F}_{d}} \hat{W}_{\mathbb{F}_{d}}^{(\mathbb{I})}+\varepsilon, \tag{2}
\end{equation*}
$$

Here we arrange the $4 \times(l+r)$ matrices in row order to $4(l+r)$-dimension vectors. Consequently, $W_{j}(\mu)$ (in main text) becomes $W(4(j-1)+\mu), j=1,2, \ldots, l+r$ and $\mu=1,2,3,4$.

Thus the error term $\varepsilon$ can be explicitly written as

$$
\begin{equation*}
\varepsilon=\sum_{i=1}^{3} \alpha_{i}\left(\hat{W}_{i}^{(\mathbb{C})}-\hat{W}_{i}^{(\mathbb{I})}\right), \tag{3}
\end{equation*}
$$

where the index $\mathrm{i}=1,2,3$ refer to the three sets $\mathbb{T}, \mathbb{F}_{u}$ and $\mathbb{F}_{d}$, respectively. The "homogeneity assumption" (see the paper) says that $\hat{W}_{i}^{(\mathbb{(})}$ and $\hat{W}_{i}^{(\mathbb{I})}$ are independent finite-sample estimations of the same PWM $W_{i}$. Therefore,

$$
\begin{equation*}
E(\varepsilon)=\sum_{i} \alpha_{i}\left(E\left(\hat{W}_{i}^{(\mathbb{O})}\right)-E\left(\hat{W}_{i}^{(\mathbb{I})}\right)\right)=\sum_{i} \alpha_{i}\left(W_{i}-W_{i}\right)=0, \tag{4}
\end{equation*}
$$

and the variance of $\varepsilon$ can be written as

$$
\begin{equation*}
\operatorname{Var}(\varepsilon)=\sum_{i} \alpha_{i}^{2}\left(\operatorname{Var}\left(\hat{W}_{i}^{(\mathbb{O})}\right)+\operatorname{Var}\left(\hat{W}_{i}^{(\mathbb{I})}\right)\right) . \tag{5}
\end{equation*}
$$

We further assume that the nucleotide frequencies at different positions in the PWM are independent (Staden, R. (1984) Computer methods to locate signals in nucleic acid sequences. Nucleic Acids Res, 12 :505-519). Thus, for position $j$ and position $k$ (where $j, k=1,2, \ldots$, $l+r)$, we have

$$
\begin{align*}
\operatorname{Cov} & \left(\hat{W}_{i}^{(\mathbb{Q})}(4(j-1)+\mu), \hat{W}_{i}^{(\mathbb{O})}(4(k-1)+\nu)\right) \\
& =\frac{W_{i}(4(j-1)+\mu) \delta_{\mu, \nu}-W_{i}(4(j-1)+\mu) W_{i}(4(k-1)+\nu)}{\alpha_{i} \Omega_{\mathbb{O}}} \delta_{j, k} \tag{6}
\end{align*}
$$

and

$$
\begin{align*}
& \operatorname{Cov}\left(\hat{W}_{i}^{(\mathbb{I})}(4(j-1)+\mu), \hat{W}_{i}^{(\mathbb{I})}(4(k-1)+\nu)\right) \\
& \quad=\frac{W_{i}(4(j-1)+\mu) \delta_{\mu, \nu}-W_{i}(4(j-1)+\mu) W_{i}(4(k-1)+\nu)}{\Omega_{i}} \delta_{j, k}, \tag{7}
\end{align*}
$$

where $\mu, \nu=1,2,3,4$, denoting nucleotide A, C, G, T, respectively. This yields

$$
\begin{equation*}
\operatorname{Var}\left(\hat{W}_{i}^{(\mathbb{Q})}\right)=\frac{1}{\alpha_{i} \Omega_{\mathbb{O}}} \Sigma_{i} \tag{8}
\end{equation*}
$$

and

$$
\begin{equation*}
\operatorname{Var}\left(\hat{W}_{i}^{(\mathbb{I})}\right)=\frac{1}{\Omega_{i}} \Sigma_{i}, \tag{9}
\end{equation*}
$$

where $\Sigma_{i}$ is a block diagonal symmetric matrix and the number of blocks is determined by the number of positions of the PWM alignment. An block according to position $j$ is shown as below:
$\left(\begin{array}{cccc}W_{i}(4 j-3)-W_{i}^{2}(4 j-3) & -W_{i}(4 j-3) W_{i}(4 j-2) & -W_{i}(4 j-3) W_{i}(4 j-1) & -W_{i}(4 j-3) W_{i}(4 j) \\ \cdot & W_{i}(4 j-2)-W_{i}^{2}(4 j-2) & -W_{i}(4 j-2) W_{i}(4 j-1) & -W_{i}(4 j-2) W_{i}(4 j) \\ \cdot & \cdot & W_{i}(4 j-1)-W_{i}^{2}(4 j-1) & -W_{i}(4 j-1) W_{i}(4 j) \\ \cdot & \cdot & \cdot & W_{i}(4 j)-W_{i}^{2}(4 j)\end{array}\right)$

With Eq. 5, Eq. 8 and Eq. 9, we finally obtain the variance of $\varepsilon$

$$
\begin{equation*}
\operatorname{Var}(\varepsilon)=\sum_{i}\left(\frac{\alpha_{i}^{2}}{\Omega_{i}}+\frac{\alpha_{i}}{\Omega_{\mathscr{O}}}\right) \Sigma_{i} \tag{10}
\end{equation*}
$$

Then we reduce data redundancy in the PWM to make $\operatorname{Var}(\varepsilon)$ full rank with a Z-transformation as below (Zhang, C.T. and Zhang, R. (1991) Analysis of distribution of bases in the coding sequences by a diagrammatic technique. Nucleic Acids Res, 19 :6313-6317)

$$
\left\{\begin{array}{l}
V(3 j-2)=W(4 j-3)+W(4 j-2)-W(4 j-1)-W(4 j) \\
V(3 j-1)=W(4 j-3)-W(4 j-2)+W(4 j-1)-W(4 j) \\
V(3 j)=W(4 j-3)-W(4 j-2)-W(4 j-1)+W(4 j)
\end{array}\right.
$$

Consequently,

$$
\begin{equation*}
\hat{V}_{\mathbb{O}}=\sum_{i} \alpha_{i} \hat{V}_{i}+\varepsilon^{\prime} . \tag{11}
\end{equation*}
$$

The variance of $\varepsilon^{\prime}$ has a similar form with $\varepsilon$

$$
\begin{equation*}
\operatorname{Var}\left(\varepsilon^{\prime}\right)=\sum_{i}\left(\frac{\alpha_{i}^{2}}{\Omega_{i}}+\frac{\alpha_{i}}{\Omega_{\mathbb{O}}}\right) \Sigma_{i}^{\prime} \tag{12}
\end{equation*}
$$

where $\Sigma_{i}^{\prime}=H \Sigma_{i} H^{T}$ and H is a block diagonal matrix with each block being

$$
\left(\begin{array}{cccc}
1 & 1 & -1 & -1 \\
1 & -1 & 1 & -1 \\
1 & -1 & -1 & 1
\end{array}\right)
$$

$\hat{W}_{i}$ is used as an estimate of $W_{i}$ to calculate $\Sigma_{i}^{\prime}$. The effect of this approximation is of high order in our model if the samples are sufficient, for example over 50 . In the following part, $\operatorname{Var}\left(\varepsilon^{\prime}\right)$ will be denoted by $\Sigma^{\prime}$ for convenience.

## 2 Minimizing the weighted sum of squared errors $\varepsilon^{\prime T} \Sigma^{\prime-} \varepsilon^{\prime}$

In the main text we mentioned that $\alpha$ is estimated by minimizing the weighted sum of square errors

$$
\begin{equation*}
f\left(\alpha_{1}, \alpha_{2}, \alpha_{3}\right)=\left(\hat{V}_{\mathbb{Q}}-\sum_{i=1}^{3} \alpha_{i} \hat{V}_{i}\right)^{T} \Sigma^{\prime-}\left(\hat{V}_{\mathbb{O}}-\sum_{i=1}^{3} \alpha_{i} \hat{V}_{i}\right) \tag{13}
\end{equation*}
$$

, where the index $\mathrm{i}=1,2,3$ refer to the three sets $\mathbb{T}, \mathbb{F}_{u}$ and $\mathbb{F}_{d}$ respectively.
Substitute $\alpha_{3}$ with

$$
\begin{equation*}
\alpha_{3}=1-\sum_{i=1}^{2} \alpha_{i} \tag{14}
\end{equation*}
$$

and Eq. 13 can be written as

$$
\begin{equation*}
f\left(\alpha_{1}, \alpha_{2}\right)=\left(S-\sum_{i=1}^{2} \alpha_{i} T_{i}\right)^{T} \Sigma^{\prime-}\left(S-\sum_{i=1}^{2} \alpha_{i} T_{i}\right) \tag{15}
\end{equation*}
$$

where

$$
\begin{equation*}
S=\hat{V}_{\mathbb{O}}-\hat{V}_{3} \tag{16}
\end{equation*}
$$

and

$$
\begin{equation*}
T_{i}=\hat{V}_{i}-\hat{V}_{3}, \quad i=1,2 \tag{17}
\end{equation*}
$$

To minimize $f\left(\alpha_{1}, \alpha_{2}\right)$, we let the partial derivatives be zero

$$
\begin{equation*}
\frac{\partial f}{\partial \alpha_{j}}=-2 T_{j}^{T} \Sigma^{\prime-}\left(S-\sum_{i=1}^{2} \alpha_{i} T_{i}\right)-\left(S-\sum_{i=1}^{2} \alpha_{i} T_{i}\right)^{T} \Sigma^{\prime-} \frac{\partial \Sigma}{\partial \alpha_{j}} \Sigma^{\prime-}\left(S-\sum_{i=1}^{2} \alpha_{i} T_{i}\right)=0 \tag{18}
\end{equation*}
$$

Eq. 18 can be simplified to

$$
\begin{equation*}
\sum_{i=1}^{2} K_{i j} \alpha_{i}=L_{j}, j=1,2 \tag{19}
\end{equation*}
$$

where

$$
\begin{equation*}
K_{i j}=T_{j}^{T} \Sigma^{\prime-} T_{i}, i, j=1,2 \tag{20}
\end{equation*}
$$

and

$$
\begin{equation*}
L_{j}=T_{j}^{T} \Sigma^{\prime-} S+\frac{1}{2}\left(S-\sum_{i=1}^{2} \alpha_{i} T_{i}\right)^{T} \Sigma^{\prime-} \frac{\partial \Sigma^{\prime}}{\partial \alpha_{j}} \Sigma^{\prime-}\left(S-\sum_{i=1}^{2} \alpha_{i} T_{i}\right) \cdot j=1,2 \tag{21}
\end{equation*}
$$

There are 2 equations and 2 variables. The equations can be solved iteratively. First we set

$$
\begin{equation*}
\alpha_{i}^{(0)}=1 / 3, i=1,2 \tag{22}
\end{equation*}
$$

Then we calculate $\Sigma^{\prime(0)}$ and $\partial \Sigma^{\prime(0)} / \partial \alpha_{j}$ by Eq. $12, K_{i j}^{(0)}$ and $L_{j}^{(0)}$ by Eq. 20 and Eq. 21, and then obtain $\alpha^{(1)}$ by solving

$$
\begin{equation*}
\sum_{i=1}^{2} K_{i j}^{(0)} \alpha_{i}^{(1)}=L_{j}^{(0)}, j=1,2 \tag{23}
\end{equation*}
$$

Then $\alpha_{i}^{(1)}$ is used to calculate $\alpha_{i}^{(2)}$ and the process is repeated until $\sum_{i=1}^{2}\left|\alpha_{i}^{(n)}-\alpha_{i}^{(n-1)}\right|<$ $10^{-6}$.

It's difficult to prove that this iteration process will always converge, but in practice it converges quite fast. For instance, when to estimate the accuracy of RefSeq annotation for $E$. coli K12, the algorithm converge in less than 10 steps (Fig. (1); we also show the iteration process of another 12 randomly selected genomes in Fig. 2.
[Fig. 1 about here.]
[Fig. 2 about here.]


Fig. 1. The convergency of the optimization algorithm (shown on E. coli K12).


Fig. 2. The convergency of the optimization algorithm (shown on 12 randomly selected genomes).

