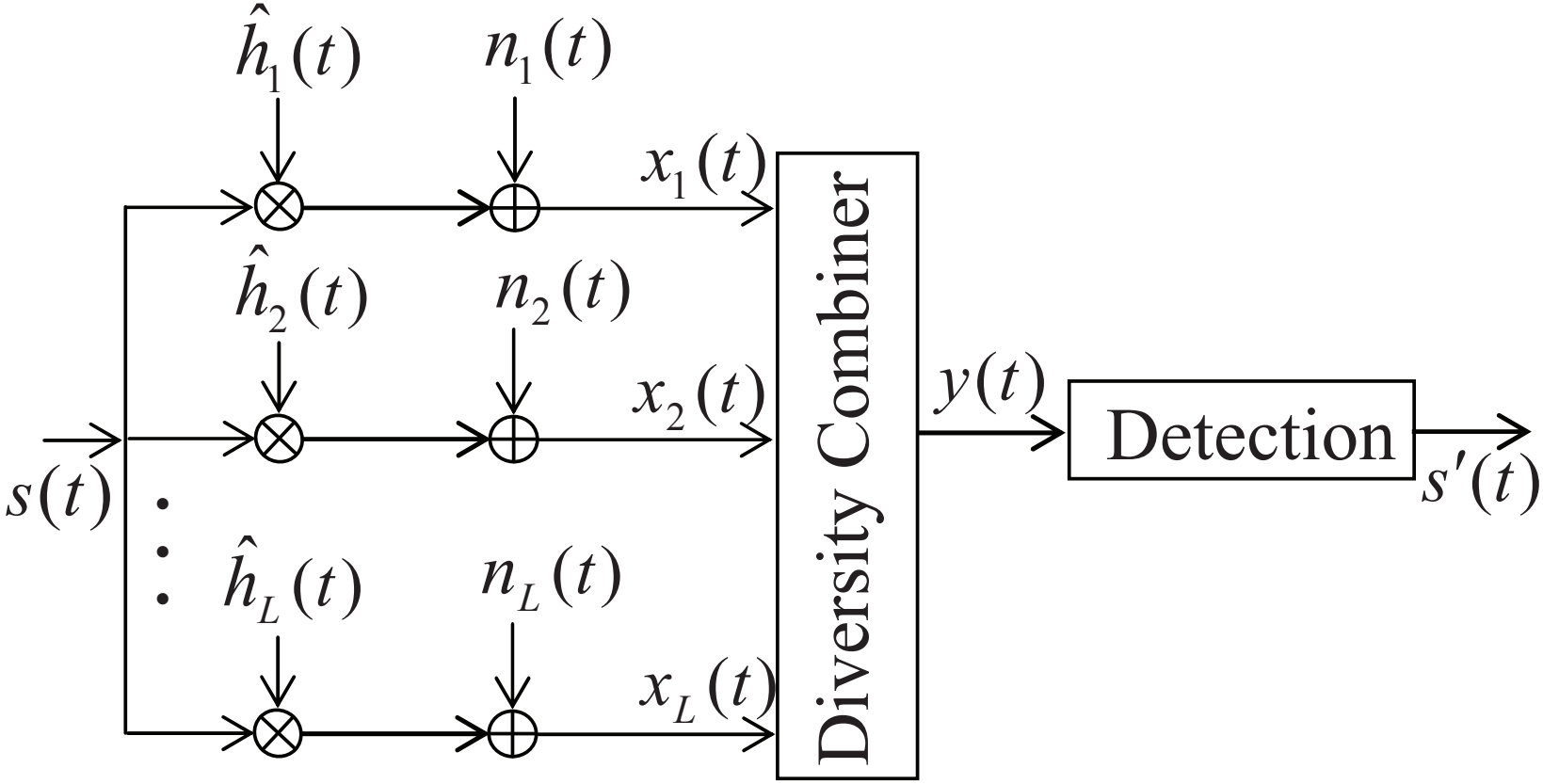
$\hat{h}_1(t)$
$n_1(t)$
$x_1(t)$
$\hat{h}_2(t)$
$n_2(t)$
$x_2(t)$
$s(t)$
$\hat{h}_L(t)$
$n_L(t)$
$x_L(t)$
Diversity Combiner
$y(t)$
Detection
$s'(t)$