

## Appendix: Uncertainty-guided Source-free Domain Adaptation

This appendix is organised as follows: Sec. [A](#) lists the notation used throughout the main text. Sec. [B](#) provides further details about Laplace approximations for approximate posterior inference in Bayesian neural networks. Sec. [C](#) provides the algorithm of U-SFAN. Sec. [D](#) includes additional summary statistics on the data sets used for the empirical evaluation and lists additional results on the OFFICE31 and VISDA-C data set for the closed-set DA task.

### A Notation

The following notation is used throughout the paper:

Notation	Description
$\mathcal{D}^{[S]} = \{(\mathbf{x}_i^{[S]}, \mathbf{y}_i^{[S]})\}_{i=1}^{n^{[S]}}$	Source data set
$\mathcal{D}^{[T]} = \{\mathbf{x}_i^{[T]}\}_{i=1}^{n^{[T]}}$	Target data set
$\mathbf{x}^{[S]} \in \mathcal{X}^{[S]}$	Source inputs
$\mathbf{y}^{[S]} \in \mathcal{Y}^{[S]}$	Source class labels
$\mathbf{x}^{[T]} \in \mathcal{X}^{[T]}$	Target inputs
$\mathcal{L}^{[S]}, \mathcal{L}^{[T]}$	Label sets
$f, f'$	Model functions (source and target)
$g$	Feature extractor
$h$	Hypothesis function
$\beta, \theta$	Parameterization of $f$ and $g$
$\mathbf{z} = g(\mathbf{x})$	Latent feature of observation $\mathbf{x}$
$K$	Number of classes
$\phi_k(\cdot)$	Softmax function
$\mathbf{H}$	Hessian matrix

### B Laplace Approximation

In Bayesian neural networks, we aim to incorporate uncertainty about the model and the model predictions. The standard approach places prior distributions ( $p(\theta)$ ) onto the network parameters, which induces a probability distribution over the model predictions. By conditioning the prior (in the weight-space) onto observed source data ( $\mathcal{D}^{[S]}$ ), we obtain the posterior distribution over the network parameters  $p(\theta | \mathcal{D}^{[S]})$ , allowing us to perform predictions by computing the posterior predictive distribution (see Eq. (4) in the main).

Let  $\Psi(\theta)$  denote the unnormalised posterior distribution, *i.e.*,

$$\Psi(\theta) = p(\theta) p(\mathcal{D}^{[S]} | \theta), \quad (\text{A1})$$

then the posterior distribution may be written as

$$p(\theta | \mathcal{D}^{[s]}) = \frac{1}{Z_\Psi} \Psi(\theta), \quad (\text{A2})$$

where  $Z_\Psi$  denotes the normalisation constant. However, computing the posterior distribution and, subsequently, the posterior predictive distribution is intractable in general. We will, therefore, resort to a Laplace approximation to the posterior distribution.

Let  $\theta_{\text{MAP}}$  denote the maximum or a mode of the posterior distribution in [Eq. \(A2\)](#). Then the second-order Taylor expansion of  $\log \Psi(\theta)$  around  $\theta_{\text{MAP}}$  is given as:

$$\log \Psi(\theta) \approx \log \Psi(\theta_{\text{MAP}}) - \frac{1}{2}(\theta - \theta_{\text{MAP}})^\top \mathbf{H}(\theta - \theta_{\text{MAP}}), \quad (\text{A3})$$

where  $\mathbf{H} = -\nabla_\theta^2 \log \Psi(\theta) |_{\theta=\theta_{\text{MAP}}}$  is the negative Hessian of the log joint ( $\log \Psi(\theta)$ ) evaluated at  $\theta_{\text{MAP}}$ . Substituting the value of  $\log \Psi(\theta)$  in [Eq. \(A2\)](#) gives us:

$$\begin{aligned} p(\theta | \mathcal{D}) &= \frac{\Psi(\theta)}{\int \Psi(\theta) d\theta} \\ &\approx \frac{\Psi(\theta_{\text{MAP}}) \exp\left(-\frac{1}{2}(\theta - \theta_{\text{MAP}})^\top \mathbf{H}(\theta - \theta_{\text{MAP}})\right)}{\Psi(\theta_{\text{MAP}}) \int \exp\left(-\frac{1}{2}(\theta - \theta_{\text{MAP}})^\top \mathbf{H}(\theta - \theta_{\text{MAP}})\right) d\theta} \\ &= \frac{\exp\left(-\frac{1}{2}(\theta - \theta_{\text{MAP}})^\top \mathbf{H}(\theta - \theta_{\text{MAP}})\right)}{\int \exp\left(-\frac{1}{2}(\theta - \theta_{\text{MAP}})^\top \mathbf{H}(\theta - \theta_{\text{MAP}})\right) d\theta}. \end{aligned} \quad (\text{A4})$$

The posterior can now be calculated in closed-form, and is given by:

$$\begin{aligned} p(\theta | \mathcal{D}) &\approx \sqrt{\frac{\det \mathbf{H}}{2\pi}} \exp\left(-\frac{1}{2}(\theta - \theta_{\text{MAP}})^\top \mathbf{H}(\theta - \theta_{\text{MAP}})\right) \\ &= \text{N}(\theta | \mu_{\text{MAP}}, \Sigma_{\text{MAP}}), \end{aligned} \quad (\text{A5})$$

where  $\mu_{\text{MAP}} = \theta_{\text{MAP}}$  and  $\Sigma_{\text{MAP}} = \mathbf{H}^{-1}$ .

The posterior predictive distribution of an unseen datum  $\mathbf{x}^{[T]}$  can now be approximated through Monte Carlo integration, *i.e.*,

$$p(\mathbf{x}^{[T]} | \mathcal{D}^{[s]}) \approx \frac{1}{M} \sum_{j=1}^M p(\mathbf{x}^{[T]} | \theta_j), \quad (\text{A6})$$

where  $\theta_j \sim \text{N}(\theta | \mu_{\text{MAP}}, \Sigma_{\text{MAP}})$ .

## C Algorithm

We report the pseudo-code for our U-SFAN in [Algo. 1](#)

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**Algorithm 1:** Uncertainty-guided Source-free DA
 

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**Input** : A probabilistic source model  $f = h \circ g$  with parameters  $\{\beta_{\text{MAP}}^{[S]}, \theta_{\text{MAP}}^{[S]}, \mathbf{H}^{-1}\}$ , target data set  $\mathcal{D}^{[T]}$  containing  $n^{[T]}$  samples, mini-batch size  $b$ , temperature  $\tau$ , and  $M$  MC steps.

**Output:** Target-specific feature extractor parameters  $\beta^{[T]}$ .

```

1 repeat
2    $\mathbf{X} \leftarrow \text{sampleMiniBatch}(\mathcal{D}^{[T]}, b)$ 
3    $\mathbf{Z} \leftarrow g_{\beta^{[T]}}(\mathbf{X})$ 
4    $\hat{\mathbf{Y}} \leftarrow b \times K$  matrix of zeros
      ▷ Estimate predictive mean
5   for  $j = 1, \dots, M$  do
6      $\theta_j \sim \text{N}(\theta_j | \theta_{\text{MAP}}^{[S]}, \mathbf{H}^{-1})$ 
7      $\hat{\mathbf{Y}} \leftarrow \hat{\mathbf{Y}} + \text{softmax}(h_{\theta_j}(\mathbf{Z})/\tau)$ 
8   end
9    $\hat{\mathbf{Y}} \leftarrow \hat{\mathbf{Y}}/M$ 
      ▷ Compute model uncertainties
10  for  $i = 1, \dots, b$  do
11     $w_i \leftarrow \exp(-H(\hat{\mathbf{y}}_i))$ 
12  end
13  Compute uncertainty-guided entropy           ▷ Eq. (7)
14  Compute divergence term                     ▷ Eq. (3)
15  Compute U-SFAN loss
16  Update parameters  $\beta^{[T]}$ 
17 until converged
    
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## D Data Set Details and Experiments

We have summarized the statistics of the SFDA benchmark data sets used for the comparison against the state-of-the-art in [Table A1](#). To demonstrate the challenging aspect of having a strong domain-shift between the source and the target, we used the data set DOMAIN-NET. Moreover, the high number of semantic categories (345 classes) in DOMAIN-NET poses a challenge for the existing IM-based SFDA methods because of the lack of representative samples from every class in a given mini-batch.

**Hyperparameter Selection.** We re-use the hyperparameters from the baseline of [\[6\]](#), *e.g.*, the standard optimization technique for training such as SGD with an initial learning rate of  $10^{-2}$  and  $10^{-3}$  for ResNet-50 and ResNet-101, respectively. The learning rate is decayed by power decay [\[2\]](#). We used the a batch size of 64 and we set  $\alpha = 0.1$  and  $\gamma = 0.5$ . Exclusive to our method, we set the prior precision in LA equal to the weight decay, *i.e.*  $5 \cdot 10^{-4}$ , and set the temperature  $\tau = 0.4$  for all our experiments.

Additionally, we have reported the results of the experiments on OFFICE31 in [Table A2](#). Similar to the results obtained on the other data sets reported in the main paper, U-SFAN outperforms SHOT-IM on OFFICE31. It must be noted that for data sets like OFFICE31, the performance is already saturated, and the performance improvements of U-SFAN over SHOT-IM are minor. More-

**Table A1.** Data set summary for source-free domain adaptation

DATA SET	#DOMAINS	#CLASSES	#IMAGES
OFFICE31	3	31	4,652
OFFICE-HOME	4	65	15,500
VISDA-C	2	12	~ 200K
DOMAIN-NET	6	345	~ 0.6M

over, the data set shift is mild in most adaptation directions, evident from the saturated numbers. Thus, as discussed in the main paper, U-SFAN does not yield remarkable improvement when the domain-shift is milder, and is most effective when much of the target data resides outside the source manifold. Nevertheless, when our method is combined with nearest centroid pseudo-labelling (like in SHOT), U-SFAN+ further improve the performance. Through these extensive experiments on several SFDA benchmarks, we presented the advantages of our proposed method for the task of SFDA.

**Table A2.** Comparison of the classification accuracy on the OFFICE31 for the closed-set SFDA using ResNet-50. Results on the small-scale OFFICE31 are known to be saturated. The visual appearance between the domains do not vary much, thus making the domain shift *milder*. The improvement of U-SFAN upon SHOT is moderate, but competitive w.r.t. A<sup>2</sup>Net [11], which requires complex training objectives

METHOD	A→D	A→W	D→A	D→W	W→A	W→D	AVG.
ResNet-50	68.9	68.4	62.5	96.7	60.7	99.3	76.1
DANN [3]	79.7	82.0	68.2	96.9	67.4	99.1	82.2
DAN [7]	78.6	80.5	63.6	97.1	62.8	99.6	80.4
SAFN [12]	90.7	90.1	73.0	98.6	70.2	99.8	87.1
CDAN [8]	92.9	94.1	71.0	98.6	69.3	100.	87.7
SHOT-IM [6]	90.6	91.2	72.5	98.3	71.4	99.9	87.3
U-SFAN (Ours)	91.8	92.3	75.8	97.7	74.4	99.8	88.6
A <sup>2</sup> Net [11]	94.5	94.0	76.7	99.2	76.1	100.0	90.1
SHOT [6]	94.0	90.1	74.7	98.4	74.3	99.9	88.6
U-SFAN+ (Ours)	94.2	92.8	74.6	98.0	74.4	99.0	88.8

Due to lack of space in the main paper, in Table A3 we report the class-wise accuracy on the VISDA-C data set, whose average accuracy has been reported in the Table 4 (a) of the main paper. While our U-SFAN is competitive with SHOT-IM and SHOT, it underperforms with respect to A<sup>2</sup>Net [11]. Nevertheless, U-SFAN does not optimize a multitude of loss functions, making it more intuitive than the A<sup>2</sup>Net.

**Table A3.** Comparison of the classification accuracy on the Visda-C for the closed-set DA, pertaining to the *Synthetic*  $\rightarrow$  *Real* direction, using ResNet-101. † indicates the numbers of [6] that are obtained using the official code from the authors. Note that several SFDA methods perform equally well for VISDA-C, hinting at saturating performance

METHOD	PLANE	BCYCL	BUS	CAR	HORSE	KNIFE	MCYCL	PERSON	PLANT	SKTBRD	TRAIN	TRUCK	AVG.
ResNet-101	55.1	53.3	61.9	59.1	80.6	17.9	79.7	31.2	81.0	26.5	73.5	8.5	52.4
DANN [3]	81.9	77.7	82.8	44.3	81.2	29.5	65.1	28.6	51.9	54.6	82.8	7.8	57.4
ADR [10]	94.2	48.5	84.0	72.9	90.1	74.2	92.6	72.5	80.8	61.8	82.2	28.8	73.5
CDAN [8]	85.2	66.9	83.0	50.8	84.2	74.9	88.1	74.5	83.4	76.0	81.9	38.0	73.9
CDAN+BSP [1]	92.4	61.0	81.0	57.5	89.0	80.6	90.1	77.0	84.2	77.9	82.1	38.4	75.9
SAFN [12]	93.6	61.3	84.1	70.6	94.1	79.0	91.8	79.6	89.9	55.6	89.0	24.4	76.1
SWD [4]	90.8	82.5	81.7	70.5	91.7	69.5	86.3	77.5	87.4	63.6	85.6	29.2	76.4
DANCE [9]	-	-	-	-	-	-	-	-	-	-	-	-	70.2
SHOT-IM† [6]	94.2	87.6	78.6	48.6	92.1	92.9	76.4	76.2	89.4	86.6	88.8	52.7	80.3
U-SFAN (Ours)	95.1	87.0	76.8	50.1	92.9	94.3	79.0	78.0	88.4	87.5	87.7	57.3	81.2
3C-GAN [5]	94.8	73.4	68.8	74.8	93.1	95.4	88.6	84.7	89.1	84.7	83.5	48.1	81.6
A <sup>2</sup> Net [11]	94.0	87.8	85.6	66.8	93.7	95.1	85.8	81.2	91.6	88.2	86.5	56.0	84.3
SHOT† [6]	94.9	87.1	76.9	55.0	94.2	95.4	80.8	80.0	89.5	88.7	85.6	60.5	82.4
U-SFAN + (Ours)	94.9	87.4	78.0	56.4	93.8	95.1	80.5	79.9	90.1	90.1	85.3	60.4	82.7

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