## 1 Comparison $LC^2$ vs DISA- $LC^2$



Fig. 1: Heat-scatterplot of the model prediction on the validation set

## 2 Probe deformation model

## (MR: Here $\alpha$ is used again, should use a different letter)

We model the displacement due to the probe pressure as a spherical compression originating from a point **c** and acting from distance r up to distance R. Our model has two parameters:  $\alpha \in [0, 1]$  controls the intensity of the deformation, while  $\beta \in [0, 10]$  controls the rate at which the deformation dissipates. Concretely we formulate the displacement of a point **p** as follows:

$$\mathbf{d}(\mathbf{p},\alpha,\beta) = \alpha R \frac{\mathbf{p} - \mathbf{c}}{\|\mathbf{p} - \mathbf{c}\|} f(\|\mathbf{p} - \mathbf{c}\|)^{1+\beta} \text{ where } f(x) = \begin{cases} \frac{10x}{8r} & \text{if } x < \frac{8}{10}r\\ 1 & \text{if } kr \le x \le r\\ 1 - \frac{x-r}{R-r} & \text{if } r < x \le R\\ 0 & \text{if } x > R \end{cases}$$