

# Verification of Recursive Methods on Tree-like Data Structures

Jyotirmoy V. Deshmukh   E. Allen Emerson  
{deshmukh,emerson}@cs.utexas.edu

University of Texas at Austin

Formal Methods in Computer-Aided Design 2009

# Recursive Methods are Everywhere!

- Data Structure Libraries.
- File Systems.
- BDD packages.
- Netlist Manipulation Routines.

## Recursive Method: `changeData`

```
void changeData (iter) {
    if ((iter->next1==∅) && (iter->next2==∅)) {
        incMod3(iter->data);
        return;
    }
    incMod3 (iter->data);
    if (iter->next1!=∅) { changeData (iter->next1); }
    incMod3 (iter->data);
    if (iter->next2!=∅) { changeData (iter->next2); }
    incMod3 (iter->data);
    return;
}
```

```
void incMod3 (x) {
    return (x + 1) mod 3;
}
```

# Properties of Interest

## Sample Pre-Condition

Input is a binary tree, data values in  $\{0, 1, 2\}$ .

## Sample Post-Condition(s)

- (A) Output is an acyclic data structure.
- (B) Output is a binary tree (subsumes (A)).
- (C) Leaf nodes in Output incremented by one (mod 3).
- (D) Non-leaf nodes in Output remain unchanged.

Verification instance of the Parameterized Reasoning problem.

# General Methods and Properties

In general, methods could . . .

- Change links.
- Add nodes.
- Delete nodes.

For example, specifications could be . . .

- Sorted-ness in a list.
- Left key is less than Right key.
- Both children of every red node are black.
- All leaves are black.

# Outline

- 1 Scope
- 2 Method Automata
- 3 Verification Framework
- 4 Complexity and Results

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# Most General Recursive Method over a Tree...

## Signature:

- Arbitrary pointer arguments, data arguments.
- Pointer/Data value as return value.

## Body: (in no particular order)

- Assignments to pointer expressions.
- Recursive calls.
- Access to global pointer/data values.



# Decidable Fragment

An arbitrary recursive method can simulate a Turing Machine.

## Syntactic restrictions for decidability?

Disallow:

- Global pointer variables.  
(... else method models  $k$ -pebble automaton)
- Pointers arbitrarily far apart.  
(... else method models  $k$ -headed automaton)
- Unbounded destructive changes.  
(... else method models linear bounded automaton)

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# Syntactic Fragment: Updates within a bounded region

Designated pointer argument 'iterator' (**iter**).

## Destructive Update relative to **iter**

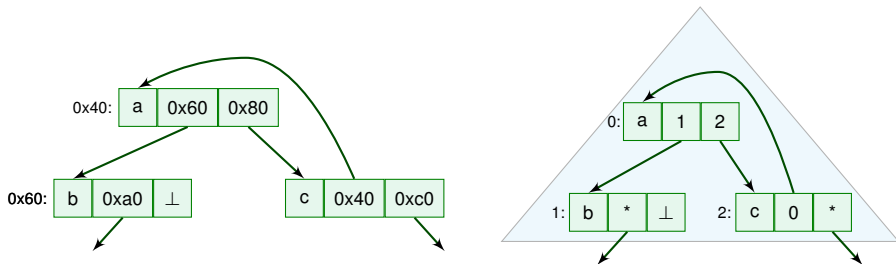
```
ptr = iter, iter->nextj, iter->nextj->...->nextk.
```

- **ptr->data = d;**
- **ptr->next<sub>j</sub> = ptr' ;**
- **ptr->next<sub>j</sub> = new node(d, ptr<sup>1</sup>, ...ptr<sup>k</sup>);**
- **delete(ptr);**

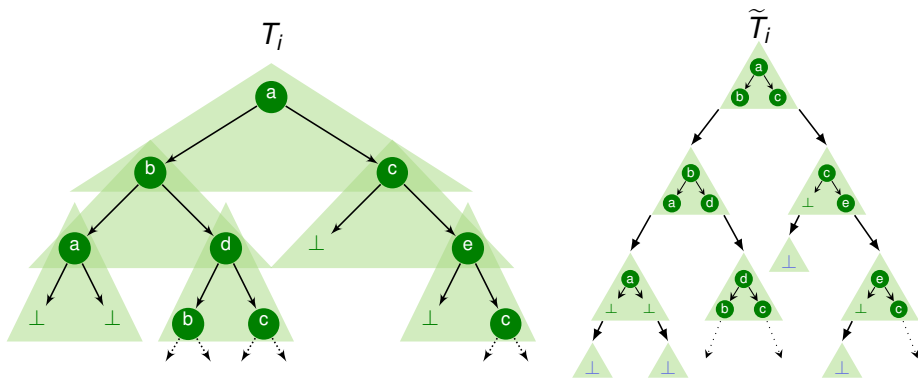
# Windows: Model updates within a bounded distance

## Definition (Window)

- Finite Encoding for *neighborhood* of **node**.
- Concrete address replaced by “Local” address.



# Abstract Tree



Obtain  $T_i$  from  $\tilde{T}_i$  by eliding everything but the root of each window.

# Decidable Fragment

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(... else method models Linear Bounded Automata)

# Syntactic Fragment: Bounded Destructive Updates

## Lemma

*For trees,  $\leq 1$  recursive invocation/child  $\Rightarrow$  #destructive updates by  $\mathcal{M}$  bounded.*

## Proof.

$\mathcal{M}$  can destructively update  $n$ :

- (0) when  $\mathcal{M}$  first visits  $n$  (after invoked from parent of  $n$ ),
- (1) when  $\mathcal{M}$  returns from 1<sup>st</sup> recursive call,
- $\vdots$
- ( $K$ ) when  $\mathcal{M}$  returns from  $K^{\text{th}}$  recursive call.

$\Rightarrow$   $\mathcal{M}$  destructively updates  $n$  at most  $K + 1$  times.

$K$  is fixed for given  $K$ -ary tree. □

# Decidable Fragment

## Syntactic restrictions for decidability?

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# Outline

1 Scope

**2 Method Automata**

- Tail Recursive Methods
- Non Tail-Recursive Methods

3 Verification Framework

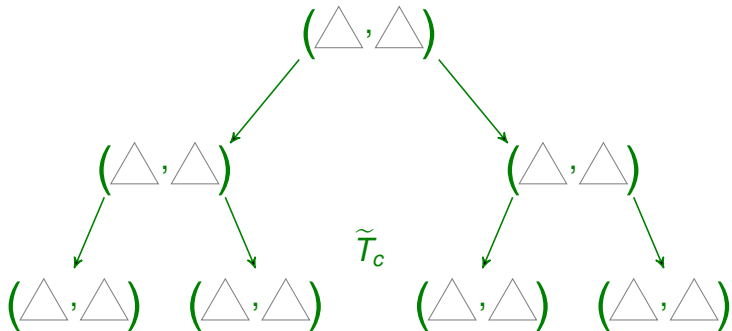
4 Complexity and Results

# Template Tail-Recursive Method

```
void foo(iter) {  
    if (cond) {  
        base-du;  
    }  
    recur-du;  
    foo (iter->next2);  
    foo (iter->next1);  
    foo (iter->next3);  
}
```

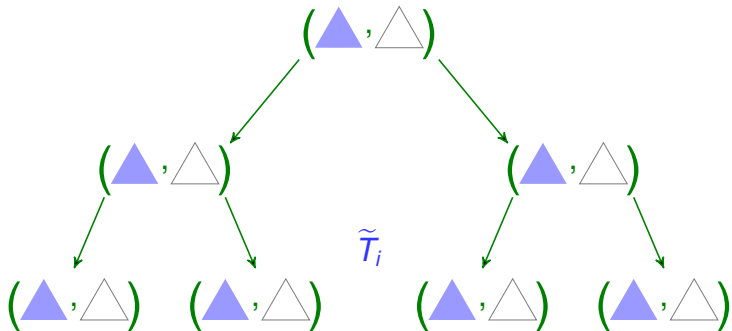
# Method Automaton $\mathcal{A}_M$

- $\mathcal{A}_M$  accepts  $\tilde{T}_i \circ \tilde{T}_o$  iff  $T_o = \mathcal{M}(T_i)$ .
- $\tilde{T}_c$  encodes valid actions of  $\mathcal{M}$ .



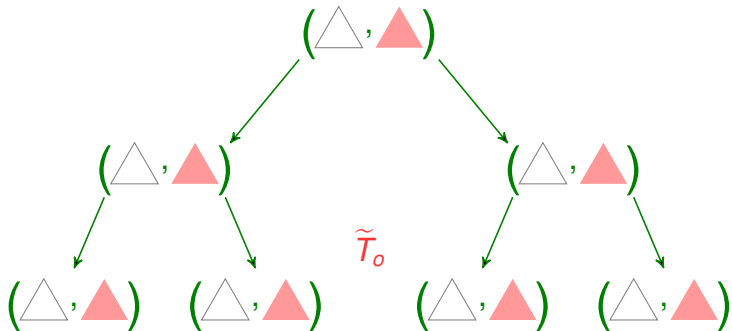
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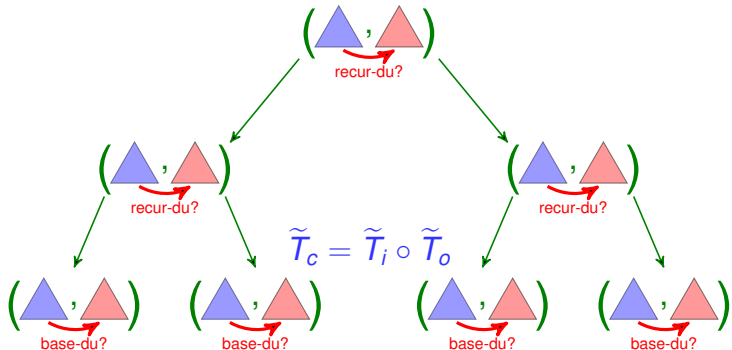
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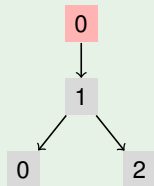


# Template Non Tail-Recursive Method

```
void foo(iter) {
  if (cond) {
    base-du;
  }
  recur-du[0];
  foo (iter->next2);
  recur-du[1];
  foo (iter->next1);
  recur-du[2];
  foo (iter->next3);
  recur-du[3];
}
```

# Action of $\mathcal{M}$

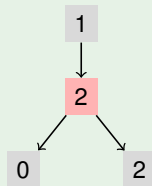
```
void changeData (iter) {  
    if ((iter->next1==∅) &&  
        (iter->next2==∅) {  
        incMod3(iter->data);  
        return;  
    }  
    incMod3 (iter->data);  
    if (iter->next1!=∅) {  
        changeData (iter->next1);  
    }  
    incMod3 (iter->data);  
    if (iter->next2!=∅) {  
        changeData (iter->next2);  
    }  
    incMod3 (iter->data);  
    return;  
}
```





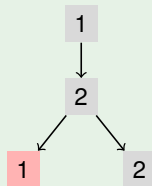
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  }  
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  return;  
}
```



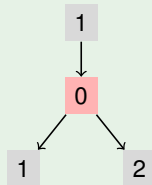
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  }  
  incMod3 (iter->data);  
  if (iter->next2!=∅) {  
    changeData (iter->next2);  
  }  
  incMod3 (iter->data);  
  return;  
}
```



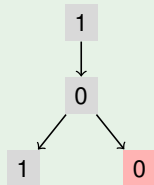
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    incMod3(iter->data);  
    return;  
  }  
  incMod3 (iter->data);  
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    changeData (iter->next1);  
  }  
  incMod3 (iter->data);  
  if (iter->next2!=∅) {  
    changeData (iter->next2);  
  }  
  incMod3 (iter->data);  
  return;  
}
```



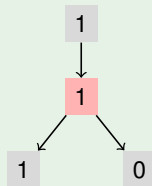
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    }  
    incMod3 (iter->data);  
    return;  
}
```



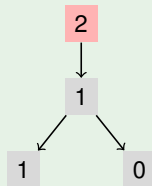
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      (iter->next2==∅)) {  
    incMod3(iter->data);  
    return;  
  }  
  incMod3 (iter->data);  
  if (iter->next1!=∅) {  
    changeData (iter->next1);  
  }  
  incMod3 (iter->data);  
  if (iter->next2!=∅) {  
    changeData (iter->next2);  
  }  
  incMod3 (iter->data);  
  return;  
}
```



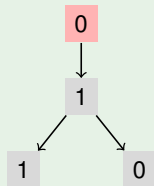
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        return;  
    }  
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    if (iter->next1!=∅) {  
        changeData (iter->next1);  
    }  
    incMod3 (iter->data);  
    if (iter->next2!=∅) {  
        changeData (iter->next2);  
    }  
    incMod3 (iter->data);  
    return;  
}
```

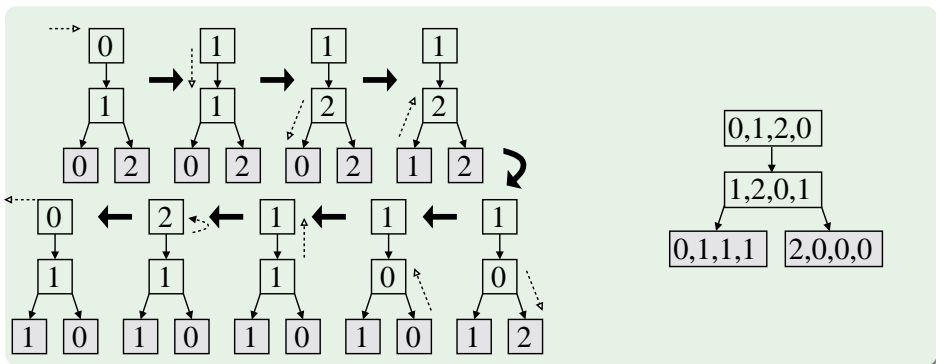


# Action of $\mathcal{M}$

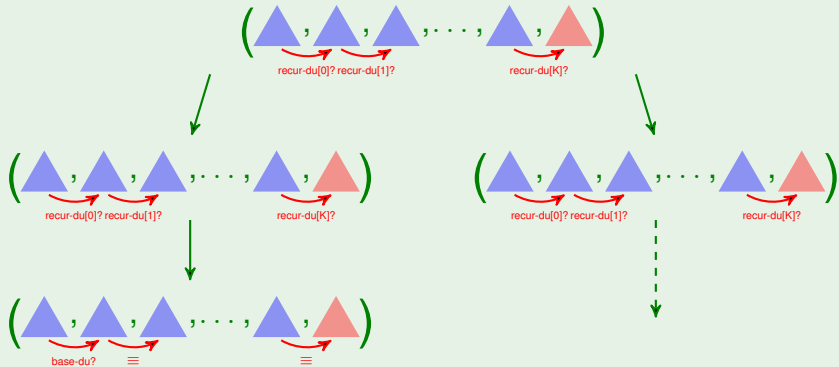
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    return;  
  }  
  incMod3 (iter->data);  
  if (iter->next1!=∅) {  
    changeData (iter->next1);  
  }  
  incMod3 (iter->data);  
  if (iter->next2!=∅) {  
    changeData (iter->next2);  
  }  
  incMod3 (iter->data);  
  return;  
}
```



# Depth-first action represented by Finite Annotation





Structure of  $\mathcal{A}_M$ 

# Outline

- 1 Scope
- 2 Method Automata
- 3 Verification Framework**
- 4 Complexity and Results

# Properties as Automata

## Pre-condition

- Pre-condition  $\varphi$  provided as  $\mathcal{A}_\varphi$ .
- $\mathcal{A}_\varphi$  operates on  $\tilde{T}_c = \tilde{T}_i \circ \tilde{T}_o$ .
- Accepts  $\tilde{T}_i$  if  $T_i \models \varphi$ .
- Ignores  $\tilde{T}_o$  component of  $\tilde{T}_c$ .

## Post-condition

- Negated Post-condition  $\psi$  provided as  $\mathcal{A}_{\neg\psi}$ .
- $\mathcal{A}_{\neg\psi}$  operates on  $\tilde{T}_c$ .
- Accepts  $\tilde{T}_o$  if  $T_o \not\models \psi$ .
- Ignores  $\tilde{T}_i$  component of  $\tilde{T}_c$ .

# Product Automaton

- $\mathcal{A}_p = \mathcal{A}_M \otimes \mathcal{A}_\varphi \otimes \mathcal{A}_{\neg\psi}$ .
- $\mathcal{A}_p$  is *non-empty*  $\Leftrightarrow$ :
  - $\mathcal{A}_M$  accepts  $\tilde{T}_i \circ \tilde{T}_o$ , i.e.  $T_o = \mathcal{M}(T_i)$ ,
  - $\mathcal{A}_\varphi$  accepts  $\tilde{T}_i$ , i.e.  $T_i \models \varphi$ ,
  - $\mathcal{A}_{\neg\psi}$  accepts  $\tilde{T}_o$ , i.e.  $T_o \not\models \psi$ .
- $\mathcal{A}_p$  is empty  $\Leftrightarrow \mathcal{M}$  satisfies pre/post-conditions for **all** input trees.

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# Complexity

- $|\mathcal{A}_p|$  proportional to  $|\mathcal{A}_M|$ , properties.
- $|\mathcal{A}_M|$  linear in  $|\mathcal{M}|$ , exp. in size of window.
- Overall complexity: polynomial in  $|\mathcal{A}_p|$ .

# Experimental Results

Method	Spec.	Time <sup>a</sup>		Mem. (MB)
		$\mathcal{A}_M$	Total	
On Linked Lists:				
<b>DeleteNode</b>	Acyclic	0.3	1.3	20
<b>InsertAtTail</b>	Acyclic	0.01	0.8	<1
<b>InsertNode</b>	Acyclic	0.4	1.6	48
On Binary Trees:				
<b>InsertNode</b>	Acyclic	15	329	2512
<b>ReplaceAll(a, b)</b>	Acyclic	5	26	324
	$\#iter : iter \rightarrow d = a$	5	27	432
<b>DeleteLeaf</b>	Acyclic	12	48	630

<sup>a</sup>Experiments were performed on an Athlon 64X2 4200+ system with 6GB RAM.

Thank You!



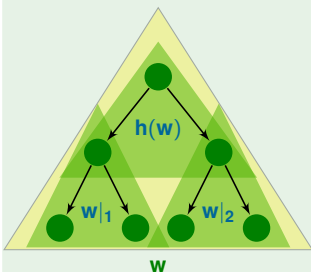
# Template for Method in Decidable Fragment

```
void foo (iter, d1, ..., dn) {  
    /* base case: */  
    if (condition) {  
        d.u. to w(iter);  
        return;  
    }  
    /* recursive case: */  
    d.u. to w(iter);  
    foo (iter->3); // call to 3rd successor  
    d.u. to w(iter);  
    foo (iter->1); // call to 1st successor  
    d.u. to w(iter);  
    foo (iter->2); // call to 2nd successor  
    d.u. to w(iter);  
    return;  
}
```

## Structure of $\mathcal{A}_{\mathcal{M}}$ : Tail Recursive Methods

- Input symbol  $\sigma = (w_i, w_o)$ .
- State encodes part of  $\sigma$  overlapping with successor.
- Reads new  $\sigma'$ ; rejects if overlapping parts differ.
- If  $\sigma \models$  base-case condition,  $\mathcal{A}_{\mathcal{M}}$  accepts if  $w_o = \mathcal{M}(w_i)$ .
- If  $\sigma \not\models$  base-case condition:
  - Checks  $w_o \stackrel{?}{=} \mathcal{M}(w_i)$  (rejects otherwise).
  - Transitions to  $(w_i|_j, w_o|_j)$  along  $j^{\text{th}}$  successor.

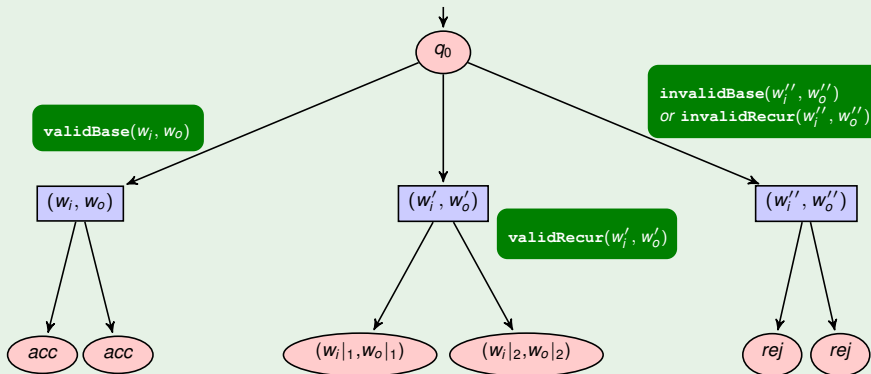
# Macros



$$\text{consistent}(\underbrace{(x_i, x_o)}_q, \underbrace{(w_i, w_o)}_\sigma) \stackrel{\text{def}}{=} \underbrace{(h(w_i) = x_i)}_{\text{cons. input}} \wedge \underbrace{(h(w_o) = x_o)}_{\text{cons. output}}$$

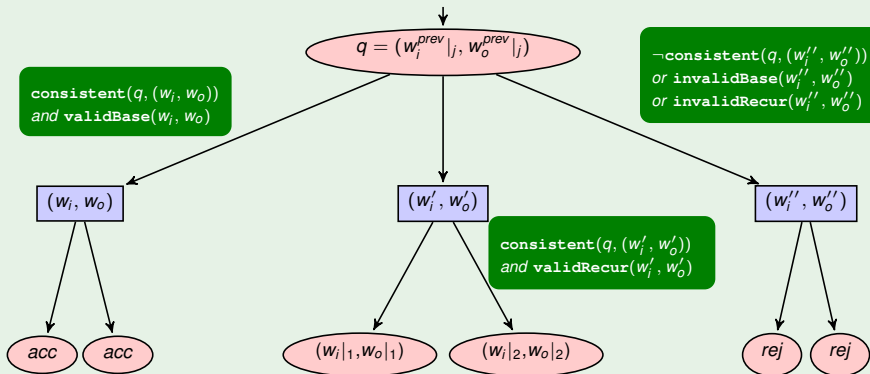
# $\mathcal{A}_M$ for Tail-Recursive Methods

## Transitions from the Initial State



# $\mathcal{A}_M$ for Tail-Recursive Methods

## Transitions from non-initial/final states



# More Macros

$$\text{validBase}(w_i, w_o) \stackrel{\text{def}}{=} \underbrace{(w_i \models \mathbf{bcond})}_{\text{is base case.}} \wedge \underbrace{(w_o = \mathbf{base\_du}(w_i))}_{\text{matches base\_du}}$$

$$\text{invalidBase}(w_i, w_o) \stackrel{\text{def}}{=} \underbrace{(w_i \models \mathbf{bcond})}_{\text{is base case.}} \wedge \underbrace{(w_o \neq \mathbf{base\_du}(w_i))}_{\text{doesn't match base\_du}}$$

$$\text{validRecur}(w_i, w_o) \stackrel{\text{def}}{=} \underbrace{(w_i \not\models \mathbf{bcond})}_{\text{not base case}} \wedge \underbrace{(w_o = \mathbf{recur\_du}(w_i))}_{\text{matches recur\_du}}$$

$$\text{invalidRecur}(w_i, w_o) \stackrel{\text{def}}{=} \underbrace{(w_i \not\models \mathbf{bcond})}_{\text{not base case}} \wedge \underbrace{(w_o \neq \mathbf{recur\_du}(w_i))}_{\text{doesn't match recur\_du}}$$

# Non Tail-Recursive Methods

## Modified Macros:

$$\text{consistent}(\underbrace{(x_i, x_o)}_q, \underbrace{(w_0, \dots, w_{K+1})}_\sigma) \stackrel{\text{def}}{=} \underbrace{(h(w_0) = x_i)}_{\text{cons. input}} \wedge \underbrace{(h(w_{K+1}) = x_o)}_{\text{cons. output}}$$

$$\text{validBase}(w_0, w_1, \dots, w_{K+1}) \stackrel{\text{def}}{=} \underbrace{(w_0 \models \text{bcond})}_{\text{is base case.}} \wedge \underbrace{(w_{K+1} = w_K = \dots = w_1 = \text{base\_du}(w_0))}_{\text{matches base\_du}}$$

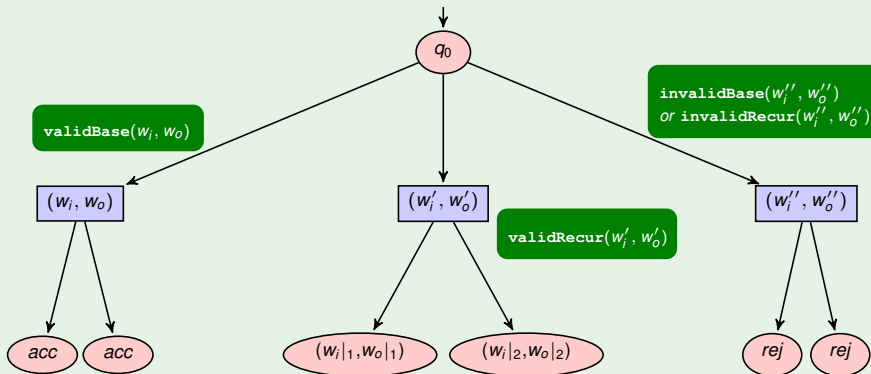
$$\text{invalidBase}(w_i, w_o) \stackrel{\text{def}}{=} \underbrace{(w_0 \models \text{bcond})}_{\text{is base case.}} \wedge \underbrace{\neg(w_{K+1} = w_K = \dots = w_1 = \text{base\_du}(w_0))}_{\text{doesn't match base\_du}}$$

$$\text{validRecur}(w_i, w_o) \stackrel{\text{def}}{=} \underbrace{(w_0 \not\models \text{bcond})}_{\text{not base case}} \wedge \underbrace{(w_1 = \text{recur\_du}[0](w_0)) \wedge \dots \wedge (w_{K+1} = \text{recur\_du}[K](w_K))}_{\text{matches all recur\_du's}}$$

$$\text{invalidRecur}(w_i, w_o) \stackrel{\text{def}}{=} \underbrace{(w_i \not\models \text{bcond})}_{\text{not base case}} \wedge \underbrace{\neg((w_1 = \text{recur\_du}[0](w_0)) \wedge \dots \wedge (w_{K+1} = \text{recur\_du}[K](w_K)))}_{\text{doesn't match all recur\_du's}}$$

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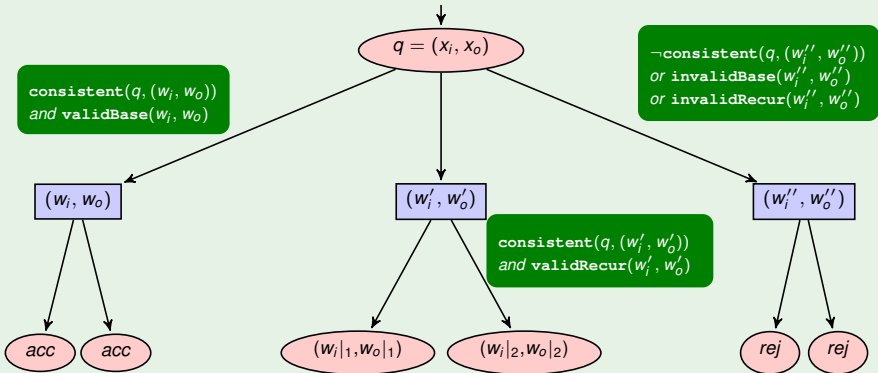
## Transitions from the Initial State





# $A_M$ for Non Tail-Recursive Methods

## Transitions from non-initial/final states



# Future Work

- Reduce  $|\Sigma_p|$  by clustering-based abstraction.
- Verify methods on *dags*: use single visit property.
- Use of Pushdown/Stack Tree Automata as Method Automata.