Bayesian networks, Kullback-leibler and topology

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Abstract

In this paper, I will propose a topology allowing to measure a neighborhood for the Bayesian networks. This topology will correspond to a Kullback-Leibler distance ratio and will allow to know the distance between a current Bayesian network and a Bayesian network having a transitive closure. This topology applied to Bayesian networks will be normalized and will therefore vary from 0 to 1. The value 0 will correspond to a Bayesian network with transitive closure and the value 1 to a Bayesian network without edges.

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1 Introduction

In this paper we will use the results obtained in the report [6] page 21 in order to propose a topology corresponding to a Kullback-liebler distance ratio.

This topology will vary from 0 to 1 and will give 0 for a Bayesian network having a transitive closure and 1 for a Bayesian network without edges.

From a fixed neighborhood ϵ around the transitive closure, we will propose an algorithm allowing to select an optimal Bayesian network.

2 Bayesian networks, Kullback-leibler and topology

In what follows we will use a Kullback-leibler distance ratio as a topology measuring the neighborhood of a current Bayesian network \mathcal{B} to the transitive closure of the directed acyclic graph:

$$0 \le \frac{D_{KL}[P_X(\vec{x}|\mathcal{B}^C)||P_X(\vec{x}|\mathcal{B})]}{D_{KL}[P_X(\vec{x}|\mathcal{B}^C||P_X(\vec{x}|\mathcal{B}^R)]} \le 1$$

Where \mathcal{B}^C will correspond to the transitive closure of the Bayesian network and \mathcal{B}^R to the Bayesian network without edges.

The inequality is based on the paper [6] page 21.

The lower bound 0 corresponds to the Bayesian network which is a transitive closure (chain rule) and the upper bound 1 corresponds to the Bayesian network whithout edges: $\frac{D_{KL}[P_X(\vec{x}|\mathcal{B}^C)||P_X(\vec{x}|\mathcal{B}^C)]}{D_{KL}[P_X(\vec{x}|\mathcal{B}^C)||P_X(\vec{x}|\mathcal{B}^R)]} = 0 \text{ and } \frac{D_{KL}[P_X(\vec{x}|\mathcal{B}^C)||P_X(\vec{x}|\mathcal{B}^R)]}{D_{KL}[P_X(\vec{x}|\mathcal{B}^C)||P_X(\vec{x}|\mathcal{B}^R)]} = 1$

- 1. The goal of the algorithm is to start from a Bayesian network without edges \mathcal{B}^R .
- Then we add the edges producing the strongest variations of conditional entropy in order to produce the strongest oriented dependencies without producing cycles in the graph.
- 3. The current Bayesian network \mathcal{B} then has a ratio $\frac{D_{KL}[P_X(\vec{x}|\mathcal{B}^c)||P_X(\vec{x}|\mathcal{B})]}{D_{KL}[P_X(\vec{x}|\mathcal{B}^c||P_X(\vec{x}|\mathcal{B}^R)]}$ which will decrease by adding the edges.
- 4. When the current ratio $\frac{D_{KL}[P_X(\vec{x}|\mathcal{B}^C)||P_X(\vec{x}|\mathcal{B})]}{D_{KL}[P_X(\vec{x}|\mathcal{B}^C||P_X(\vec{x}|\mathcal{B}^R)]}$ is in a good neighborhood of the transitive closure \mathcal{B}^C :

$$0 \le \frac{D_{KL}[P_X(\vec{x}|\mathcal{B}^C)||P_X(\vec{x}|\mathcal{B})]}{D_{KL}[P_X(\vec{x}|\mathcal{B}^C||P_X(\vec{x}|\mathcal{B}^R)]} \le \epsilon$$

we select the most likely Bayesian network \mathcal{B} .

A good neighborhood is fixed for ϵ equal to 1%: ϵ = 0.01

3 Conclusion

In this paper, we proposed a topology based on the Kullbak-leibler distance and allowing the selection of an optimal Bayesian network. The topology allows to put two bounds in which a current Bayesian network moves.

Starting from a Bayesian network without edges, the goal of the algorithm was then, by adding the edges, to find the Bayesian network closest to the lower bound corresponding to a transitive closure with a neighborhood value ϵ set to 0.01.

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