



Article

Entanglement Property of Tripartite GHZ State in Different Accelerating Observer Frames [†]

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Abstract: According to the single-mode approximation applied to two different modes, each associated with different uniformly accelerating reference frames, we present analytical expression of the Minkowski states for both the ground and first excited states. Applying such an approximation, we study the entanglement property of Bell and Greenberger–Horne–Zeilinger (GHZ) states formed by such states. The corresponding entanglement properties are described by studying negativity and von Neumann entropy. The degree of entanglement will be degraded when the acceleration parameters increase. We find that the greater the number of particles in the entangled system, the more stable the system that is studied by the von Neumann entropy. The present results will be reduced to those in the case of the uniformly accelerating reference frame.

Keywords: single mode approximation; entanglement measures; Dirac field; noninertial frames

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1. Introduction

Up to now, quantum entanglement has become the central resource for quantum information as a new and fast-growing field. Its development has been concerned with many useful branches, e.g., quantum computation, quantum cryptography and quantum teleportation. Quantum entanglement plays a fundamental part in the creation of a large amount of information protocols, such as the Quantum Key Distribution [1–3]. In recent years, a new, emerging field named relativistic quantum information, which combines quantum information theory, quantum field theory and general relativity, has been developed in quantum information. Its central question is the study of the entanglement measures in a noninertial frame. Previous studies show that the entanglement between modes of bosonic or fermionic fields is degraded from the perspective of observers moving in a uniform acceleration; therefore, we need to have a quantitative understanding of such degradation. Based on this idea, a single-mode approximation has been proposed and developed widely in relativistic quantum information [4–24]. For example, Asling and his coauthors have used a single-mode approximation to study the behavior of the entanglement between the modes of a free Dirac field in a noninertial frame in flat space-time from the point of view of two observers, Alice and Rob, in a relative uniform acceleration [9]. After that, the entanglement properties of bipartite and multipartite, including the tripartite, tetrapartite and pentapartite entangled systems, have been studied. These systems are concerned with the GHZ, generalized GHZ, W-class pure states and Werner mixed state, etc.

However, in the commonly used single-mode approximation, only one uniformly accelerated observer is concerned, and thus, there are some limitations in applications, so it still remains to consider the case in which two different uniformly accelerated observers exist. Similar to the single-mode approximation, we still want to obtain a quantitative expression and show how two different acceleration parameters r_j and r_k affect the entanglement property.

In this paper, based on the single-mode approximation, we derive analytical expressions of two different accelerating observer frames. In Section 2, we first review the transformation between Minkowski, Unruh and Rindler modes, and then we present an approximate transformation by considering different accelerations of the observer frames. We shall use this transformation to study the entanglement of the Bell and GHZ states in Section 3 through the calculation of their negativities and the von Neumann entropy. Finally, we present the conclusions in Section 4.

2. Generalization of Single Mode Approximation

Let us consider a free Minkowski Dirac field in the single mode approximation before we generalize it to the case for two different accelerating observer frames. The field ψ can be expanded in terms of the positive (fermions) and negative (antifermions) energy solutions of the Dirac equation ψ_k^+ and ψ_k^- since they form a completely orthogonal set of modes [25–28]

$$\psi = \int \left(a_k \psi_k^+ + b_k^\dagger \psi_k^- \right) dk, \tag{1}$$

where k is the notation for the wave vector k , and the positive and negative energy Minkowski modes have the form

$$\left(\psi_k^\pm \right)_s = \frac{1}{\sqrt{2\pi\omega_k}} \phi_s^\pm e^{\pm i(kx - t\omega_k)}, \tag{2}$$

where $\omega_k = (m^2 + k^2)^{1/2}$ and ϕ_s is a constant spinor with $s = \{\uparrow, \downarrow\}$, and all the wave functions satisfy the normalization relation. The operators a_k^\dagger, b_k^\dagger and a_k, b_k are the creation and annihilation operators for the positive and negative energy solutions of momentum k , which satisfy the anticommutation relations

$$\left\{ a_i, a_j^\dagger \right\} = \left\{ b_i, b_j^\dagger \right\} = \delta_{ij}. \tag{3}$$

The definition of the Minkowski vacuum state in an inertial frame is

$$|0\rangle = \prod_{kk'} |0_k\rangle^+ |0_{k'}\rangle^-, \tag{4}$$

where the signs $\{+, -\}$ are used to denote the particle and antiparticle vacua, so we have $a_k |0_k\rangle^+ = b_k |0_k\rangle^- = 0, (a_k^\dagger)^2 = (b_k^\dagger)^2 = 0$ and $|1_k\rangle^+ = a_k^\dagger |0_k\rangle^+,$ To study the Bell and GHZ states in the potentially different accelerating observer frame, it is helpful for us to use Rindler coordinates and divide Minkowski space-time into two inaccessible regions I and II. For convenience, in this work, we denote the inertial observers Alice, Bob and Charlie as A, B and C , respectively. Following the pioneering work [9] and our recent study [28], we use the $\left\{ c_k^{I,II}, c_k^{I\dagger,II\dagger} \right\}$ to denote the annihilation and creation operators for fermions (particles) and $\left\{ d_k^{I,II}, d_k^{I\dagger,II\dagger} \right\}$ to denote the annihilation and creation operators for antifermions (antiparticles) in regions I and II, respectively, so that Equation (1) can be rewritten as

$$\psi = \int \left(c_k^I \psi_k^{I+} + d_k^{I\dagger} \psi_k^{I-} + c_k^{II} \psi_k^{II+} + d_k^{II\dagger} \psi_k^{II-} \right) dk. \tag{5}$$

To avoid the repeated calculation, we suggest the reader refer to recent pioneering contributions to this topic [29–35]. Using the relation between the Minkowski and Rindler creation and annihilation operators satisfying the Bogoliubov transformation, we are able to obtain [9]

$$|0_k\rangle^+ = \cos(r)|0_k\rangle_I^+ |0_{-k}\rangle_{II}^+ + e^{-i\phi} \sin(r)|1_k\rangle_I^+ |1_{-k}\rangle_{II}^+ = |0\rangle_R \tag{6}$$

and

$$a_k^\dagger |0\rangle_R = c_k^{I\dagger} |0_k\rangle_I^+ |0_{-k}\rangle_{II}^- = |1_k\rangle_I^+ |0_{-k}\rangle_{II}^- = |1\rangle_R. \tag{7}$$

Now, let us consider the case in which we consider a superposition of two annihilation operators on modes j and k , acting in region I, that is, $c_{jk}^I = (\omega_j c_j^I + \omega_k c_k^I)$, where two complex coefficients of this superposition given as ω_j and ω_k , respectively, satisfy the normalization condition $|\omega_k|^2 + |\omega_j|^2 = 1$. For a single mode k , based on the definition of the operator S [9],

$$S = \exp[re^{-i\phi} c_k^{I\dagger} d_{-k}^{II\dagger} + re^{i\phi} c_k^I d_{-k}^{II}], \tag{8}$$

when applied to two different modes, each associated with different uniformly accelerating reference frames, we are able to express the operator S_{jk} as follows:

$$\begin{aligned} S_{jk} &= S_j \otimes S_k \\ &= \exp\left\{r_j e^{-i\phi} c_j^{I\dagger} d_{-j}^{II\dagger} + r_j e^{i\phi} c_j^I d_{-j}^{II} \right. \\ &\quad \left. + r_k e^{-i\phi} c_k^{I\dagger} d_{-k}^{II\dagger} + r_k e^{i\phi} c_k^I d_{-k}^{II}\right\}. \end{aligned} \tag{9}$$

By using this relation, we can obtain

$$\begin{aligned} a_{jk} &= S_{jk} c_{jk}^I S_{jk}^\dagger \\ &= \omega_j \left[\cos(r_j) c_j^I - e^{-i\phi_j} \sin(r_j) d_j^{II\dagger} \right] \\ &\quad + \omega_k \left[\cos(r_k) c_k^I - e^{-i\phi_k} \sin(r_k) d_k^{II\dagger} \right] \end{aligned} \tag{10}$$

and

$$\begin{aligned} b_{-jk}^\dagger &= S_{jk} d_{-jk}^{II\dagger} S_{jk}^\dagger \\ &= \bar{\omega}_j \left[\cos(r_j) d_j^{II\dagger} + e^{i\phi_j} \sin(r_j) c_j^I \right] \\ &\quad + \bar{\omega}_k \left[\cos(r_k) d_k^{II\dagger} + e^{i\phi_k} \sin(r_k) c_k^I \right]. \end{aligned} \tag{11}$$

In a Minkowski vacuum space, a_{jk} and b_{-jk} annihilate the two-mode particle and antiparticle ($a_{jk}|0_{jk}\rangle^+ = 0$ and $b_{-jk}|0_{jk}\rangle^+ = 0$). For two different modes, each associated with different uniformly accelerating reference frames, we have

$$\begin{aligned} |0_{jk}\rangle^+ &= |0_j\rangle^+ \otimes |0_k\rangle^+ \\ &= \left(\sum_{n=0}^{\infty} j_n |n_j\rangle_I^+ |n_{-j}\rangle_{II}^- \right) \otimes \left(\sum_{n=0}^{\infty} k_n |n_k\rangle_I^+ |n_{-k}\rangle_{II}^- \right) \\ &= j_0 k_0 |0_{\hat{j}I} 0_{\hat{j}II} 0_{\hat{k}I} 0_{\hat{k}II}\rangle + j_0 k_1 |0_{\hat{j}I} 0_{\hat{j}II} 1_{\hat{k}I} 1_{\hat{k}II}\rangle \\ &\quad + j_1 k_0 |1_{\hat{j}I} 1_{\hat{j}II} 0_{\hat{k}I} 0_{\hat{k}II}\rangle + j_1 k_1 |1_{\hat{j}I} 1_{\hat{j}II} 1_{\hat{k}I} 1_{\hat{k}II}\rangle. \end{aligned} \tag{12}$$

Based on Equations (10) and (12) we obtain $a_{jk}|0_{jk}\rangle^+ = 0$, i.e.,

$$\begin{aligned} 0 &= \left[\omega_j \left(\cos(r_j) c_j^I - e^{-i\phi_j} \sin(r_j) d_j^{II\dagger} \right) \right. \\ &\quad \left. + \omega_k \left(\cos(r_k) c_k^I - e^{-i\phi_k} \sin(r_k) d_k^{II\dagger} \right) \right] \\ &\quad \left[j_0 k_0 |0_{\hat{j}I} 0_{\hat{j}II} 0_{\hat{k}I} 0_{\hat{k}II}\rangle + j_0 k_1 |0_{\hat{j}I} 0_{\hat{j}II} 1_{\hat{k}I} 1_{\hat{k}II}\rangle \right. \\ &\quad \left. + j_1 k_0 |1_{\hat{j}I} 1_{\hat{j}II} 0_{\hat{k}I} 0_{\hat{k}II}\rangle + j_1 k_1 |1_{\hat{j}I} 1_{\hat{j}II} 1_{\hat{k}I} 1_{\hat{k}II}\rangle \right]. \end{aligned} \tag{13}$$

After simplifying the equation

$$\begin{aligned} j_1 \cos(r_j) - j_0 e^{-i\phi_j} \sin(r_j) &= 0, \\ k_1 \cos(r_k) - k_0 e^{-i\phi_k} \sin(r_k) &= 0, \end{aligned} \tag{14}$$

we have the result

$$\begin{aligned} j_1 &= j_0 e^{-i\phi_j} \frac{\sin(r_j)}{\cos(r_j)} = j_0 e^{-i\phi_j} \tan(r_j), \\ k_1 &= k_0 e^{-i\phi_k} \frac{\sin(r_k)}{\cos(r_k)} = k_0 e^{-i\phi_k} \tan(r_k). \end{aligned} \tag{15}$$

By substituting them into Equation (12)

$$\begin{aligned} |0_{jk}\rangle^+ &= j_0 k_0 |0_{\hat{j}} 0_{\hat{j}\hat{\Pi}} 0_{\hat{k}} 0_{\hat{k}\hat{\Pi}}\rangle \\ &+ j_0 k_0 e^{-i\phi_j} \tan(r_j) |1_{\hat{j}} 1_{\hat{j}\hat{\Pi}} 0_{\hat{k}} 0_{\hat{k}\hat{\Pi}}\rangle \\ &+ j_0 k_0 e^{-i\phi_k} \tan(r_k) |0_{\hat{j}} 0_{\hat{j}\hat{\Pi}} 1_{\hat{k}} 1_{\hat{k}\hat{\Pi}}\rangle \\ &+ j_0 k_0 e^{-i\phi_j - i\phi_k} \tan(r_j) \tan(r_k) |1_{\hat{j}} 1_{\hat{j}\hat{\Pi}} 1_{\hat{k}} 1_{\hat{k}\hat{\Pi}}\rangle, \end{aligned} \tag{16}$$

and then normalizing the state

$$\left(|0_{jk}\rangle^+\right)^\dagger |0_{jk}\rangle^+ = 1, \quad (j_0 k_0)^2 \sec^2(r_j) \sec^2(r_k) = 1, \tag{17}$$

we have $j_0 k_0 = \pm \sqrt{\cos(r_j) \cos(r_k)}$. Substituting this into (16) allows us to find

$$\begin{aligned} |0\rangle_R &= |0_{jk}\rangle^+ = \cos(r_j) \cos(r_k) |0_{\hat{j}} 0_{\hat{j}\hat{\Pi}} 0_{\hat{k}} 0_{\hat{k}\hat{\Pi}}\rangle \\ &+ e^{-i\phi_k} \cos(r_j) \sin(r_k) |0_{\hat{j}} 0_{\hat{j}\hat{\Pi}} 1_{\hat{k}} 1_{\hat{k}\hat{\Pi}}\rangle \\ &+ e^{-i\phi_j} \cos(r_k) \sin(r_j) |1_{\hat{j}} 1_{\hat{j}\hat{\Pi}} 0_{\hat{k}} 0_{\hat{k}\hat{\Pi}}\rangle \\ &+ e^{-i\phi_j - i\phi_k} \sin(r_j) \sin(r_k) |1_{\hat{j}} 1_{\hat{j}\hat{\Pi}} 1_{\hat{k}} 1_{\hat{k}\hat{\Pi}}\rangle. \end{aligned} \tag{18}$$

For the excited state, however, one has

$$|1\rangle_R = |1_{jk}\rangle^+ = a_{jk}^\dagger |0_{jk}\rangle^+ \tag{19}$$

where

$$\begin{aligned} a_{jk}^\dagger &= \omega_j^* (\cos(r_j) c_j^\dagger - e^{i\phi_j} \sin(r_j) d_j) \\ &+ \omega_k^* (\cos(r_k) c_k^\dagger - e^{i\phi_k} \sin(r_k) d_k). \end{aligned} \tag{20}$$

Using the following properties,

$$\begin{aligned} a_{jk} |0_{jk}\rangle^+ &= a_{jk} |0\rangle_R = 0, \quad a_{jk}^\dagger |0_{jk}\rangle^+ = a_{jk}^\dagger |0\rangle_R = |1\rangle_R, \\ (a_{jk}^\dagger)^2 |0_{jk}\rangle^+ &= (a_{jk}^\dagger)^2 |0\rangle_R = a_{jk}^\dagger |1\rangle_R = 0, \end{aligned} \tag{21}$$

we can finally obtain

$$\begin{aligned} |1\rangle_R &= |1_{jk}\rangle^+ = \omega_k^* \cos(2r_k) \cos(r_j) |0_{\hat{j}} 0_{\hat{j}\hat{\Pi}} 1_{\hat{k}} 0_{\hat{k}\hat{\Pi}}\rangle \\ &+ \omega_j^* \cos(2r_j) \cos(r_k) |1_{\hat{j}} 0_{\hat{j}\hat{\Pi}} 0_{\hat{k}} 0_{\hat{k}\hat{\Pi}}\rangle \\ &+ e^{-i\phi_k} \omega_j^* \cos(2r_j) \sin(r_k) |1_{\hat{j}} 0_{\hat{j}\hat{\Pi}} 1_{\hat{k}} 1_{\hat{k}\hat{\Pi}}\rangle \\ &+ e^{-i\phi_j} \omega_k^* \cos(2r_k) \sin(r_j) |1_{\hat{j}} 1_{\hat{j}\hat{\Pi}} 1_{\hat{k}} 0_{\hat{k}\hat{\Pi}}\rangle. \end{aligned} \tag{22}$$

3. Fermionic Entanglement in Two Different Accelerating Observer Frames

When single mode approximation is applied to two different modes, each associated with different uniformly accelerating reference frames, we use j and k to represent the modes on states, but satisfy relation $|\omega_k|^2 + |\omega_j|^2 = 1$. $|n\rangle_A$ means Alice for the Minkowski particle mode $|n\rangle^+$, $|n\rangle_I$ for the Rindler region I particle mode $|n\rangle_I^+$, and $|n\rangle_{II}$ for the Rindler region II antiparticle mode $|n\rangle_{II}^-$. Similarly, we simplify the description “Minkowski mode for Alice” to “mode A” and the Rindler particle and antiparticle modes in regions I and II to “mode I” and “mode II”, respectively. Before studying GHZ states, we first consider the Bell state in an inertial frame, $|\phi\rangle = \frac{1}{\sqrt{2}}(|0_{\hat{A}}0_{\hat{R}}\rangle + |1_{\hat{A}}1_{\hat{R}}\rangle)$. After expanding the Minkowski particle state into the Rindler region I and II (particle and antiparticle) and the mode j and k using Equations (18) and (22), we can obtain the following matrix form

$$\rho_{A_{j|k}I} = \frac{1}{2} \begin{pmatrix} \beta^2\delta^2 & 0 & 0 & 0 & 0 & \beta^2\delta\eta_2\omega_k & \beta\delta^2\eta_1\omega_j & 0 \\ 0 & \beta^2\gamma^2 & 0 & 0 & 0 & 0 & 0 & \beta\gamma^2\eta_1\omega_j \\ 0 & 0 & \alpha^2\delta^2 & 0 & 0 & 0 & 0 & \alpha^2\delta\eta_2\omega_k \\ 0 & 0 & 0 & \alpha^2\gamma^2 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \beta^2\delta\eta_2\omega_k^* & 0 & 0 & 0 & 0 & \beta^2\eta_2^2|\omega_k|^2 & \beta\delta\eta_1\eta_2\omega_j\omega_k^* & 0 \\ \beta\delta^2\eta_1\omega_j^* & 0 & 0 & 0 & 0 & \beta\delta\eta_1\eta_2\omega_j^*\omega_k & \delta^2\eta_1^2|\omega_j|^2 & 0 \\ 0 & \beta\gamma^2\eta_1\omega_j^* & \alpha^2\delta\eta_2\omega_k^* & 0 & 0 & 0 & 0 & \gamma^2\eta_1^2|\omega_j|^2 + \alpha^2\eta_2^2|\omega_k|^2 \end{pmatrix}, \tag{23}$$

where $\alpha = \sin(r_j), \beta = \cos(r_j), \gamma = \sin(r_k), \delta = \cos(r_k), \eta_1 = \cos(2r_j), \eta_2 = \cos(2r_k)$. For the bipartite subsystem $\rho_{A_{j|k}I}$, its matrix form is given by

$$\rho_{A_{j|k}I} = \frac{1}{2} \begin{pmatrix} \beta^2 & 0 & 0 & (2\beta^3 - \beta)\omega_j \\ 0 & \alpha^2 & 0 & 0 \\ 0 & 0 & \beta^2\eta_2^2|\omega_k|^2 & 0 \\ (2\beta^3 - \beta)\omega_j^* & 0 & 0 & \eta_1^2|\omega_j|^2 + \alpha^2\eta_2^2|\omega_k|^2 \end{pmatrix}. \tag{24}$$

The matrix $\rho_{A_{k|j}I}$ can easily be obtained from $\rho_{A_{j|k}I}$ by replacing r_j with r_k and ω_j with ω_k , respectively. In this case, we will use the negativities and von Neumann entropy to show its entanglement properties.

To calculate the negativity, we need to obtain the partial transpose of the density matrix [35]. After this process, if the density matrix has at least one negative eigenvalue, we can say the density matrix is entangled. The negativity is defined as [36,37]

$$N_{\alpha(\beta\gamma)} = \|\rho_{\alpha(\beta\gamma)}^{T_\alpha}\| - 1 = 2 \sum_{i=1}^N |\lambda_M^{(-)}|^i, \quad N_{\alpha\beta} = \|\rho_{\alpha\beta}^{T_\alpha}\| - 1, \tag{25}$$

where $\lambda_M^{(-)}$ are the negative eigenvalues of the matrix M .

When we study an entangled quantum system, it is also necessary to study the von Neumann entropy defined as [38],

$$S = -\text{Tr}(\rho \log_2 \rho) = - \sum_{i=1}^n \lambda^{(i)} \log_2 \lambda^{(i)}, \tag{26}$$

where $\lambda^{(i)}$ denotes the i -th nonzero eigenvalue of the density matrix ρ . It should be pointed out that the density matrix is not taken as its partial transpose. Thus, we are able to use it to measure the stability of the studied quantum system.

We illustrate the negativity in Figure 1 and notice that the degree of the entanglement always decreases with the acceleration parameters r_j and r_k , but the degree of entanglement for all of them still exists even in the acceleration limit $r \rightarrow \pi/4$.

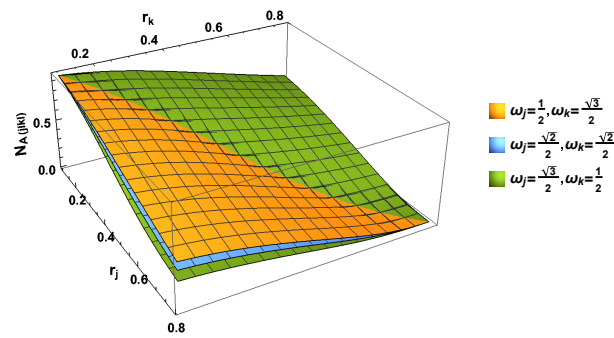


Figure 1. (Color online) Negativity $N_{A(j|k)}$ plotted as the function of acceleration parameters r_j and r_k .

$$\begin{aligned}
 N_{A(j|l)} = N_{j|l(A)} = & \\
 & \frac{1}{4} \left[-2|\omega_k|^2 \cos^2(r_j) \cos^2(2r_k) + \cos(2r_j) - 1 \right. \\
 & + 2\{(\sin^2(r_j) - |\omega_k|^2 \cos^2(r_j) \cos^2(2r_k))^2 \\
 & \left. + 4|\omega_j|^2 \cos^2(r_j) \cos^2(2r_j)\}^{1/2} \right].
 \end{aligned} \tag{27}$$

Due to the symmetry, one has $N_{A(kl)} = N_{kl(A)}$, which can be easily obtained by exchanging ω_j and ω_k of $N_{A(jl)} = N_{j|l(A)}$. As illustrated in Figure 2, we notice that the degree of the entanglement for the negativity ($N_{A(jl)} = N_{A(kl)}$ by exchanging $\omega_j \leftrightarrow \omega_k$ due to symmetry) always decreases with the acceleration parameters r_j (r_k) but increases with the increasing of the acceleration parameter r_k (r_j). As ω_j/ω_k increases, the negativities increase, too. For convenience, we take $\{\omega_j, \omega_k\}$ as follows:

$$\{\omega_j, \omega_k\} = \left\{ \frac{1}{2}, \frac{\sqrt{3}}{2} \right\}, \left\{ \frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2} \right\}, \left\{ \frac{\sqrt{3}}{2}, \frac{1}{2} \right\}. \tag{28}$$

In particular, it is found that the negativity $N_{A(jl)}$ will disappear when r_j exceeds some values, which are proportional to the ratio of the ω_j/ω_k .

To calculate the von Neumann entropy, we are going to present eigenvalues of all subsystems and whole systems for the case of the Bell state as follows:

$$\begin{aligned}
 \lambda_{A|j|k|l}^{(1)} = & \frac{1}{4} \left[2 \cos^2(r_k) (|\omega_j|^2 \cos^2(2r_j) + \cos^2(r_j)) \right. \\
 & \left. + |\omega_k|^2 \cos^2(r_j) (\cos(4r_k) + 1) \right], \\
 \lambda_{A|j|k|l}^{(2,3)} = & \frac{1}{8} \left\{ \mp \left[4|\omega_j|^4 \cos^4(2r_j) \sin^4(r_k) + 4 \cos^2(2r_j) \sin^2(r_k) \right. \right. \\
 & \left. \left. |\omega_j|^2 \left(\cos(2r_j) - \cos(2r_k) + 2|\omega_k|^2 \sin^2(r_j) \cos^2(2r_k) \right) \right. \right. \\
 & \left. \left. + \left(-\cos(2r_j) 2|\omega_k|^2 \sin^2(r_j) \cos^2(2r_k) + \cos(2r_k) \right)^2 \right]^{1/2} \right. \\
 & \left. + 2|\omega_j|^2 \cos^2(2r_j) \sin^2(r_k) + 2|\omega_k|^2 \sin^2(r_j) \cos^2(2r_k) \right. \\
 & \left. - \cos(2r_j) \cos(2r_k) + 1 \right\}, \\
 \lambda_{A|j|k|l}^{(4)} = & \frac{1}{2} \sin^2(r_j) \sin^2(r_k),
 \end{aligned} \tag{29}$$

$$\begin{aligned} \lambda_{A\bar{J}I}^{(1)} &= \frac{1}{2} |\omega_k|^2 \cos^2(r_j) \cos^2(2r_k), \\ \lambda_{A\bar{J}I}^{(2,3)} &= \frac{1}{8} \left\{ \mp 2 \left[|\omega_k|^2 \sin^2(2r_j) (-\cos^2(2r_k)) \right. \right. \\ &\quad \left. \left. + (|\omega_k|^2 \sin^2(r_j) \cos^2(2r_k) + |\omega_j|^2 \cos^2(2r_j) + \cos^2(r_j))^2 \right]^{1/2} \right. \\ &\quad \left. + 2(|\omega_k|^2 \sin^2(r_j) \cos^2(2r_k) + \cos^2(r_j)) + |\omega_j|^2 \cos(4r_j) + |\omega_j|^2 \right\}, \\ \lambda_{A\bar{J}I}^{(4)} &= \frac{1}{2} \sin^2(r_j), \end{aligned} \tag{30}$$

$$\begin{aligned} \lambda_{\bar{J}IKI}^{(1)} &= \frac{1}{2} \cos^2(r_j) \cos^2(r_k), \\ \lambda_{\bar{J}IKI}^{(2,3)} &= \frac{1}{8} \left\{ \mp \left[4|\omega_j|^4 \cos^4(2r_j) \cos^4(r_k) \right. \right. \\ &\quad \left. \left. + \left(\cos(2r_j) 2|\omega_k|^2 \cos^2(r_j) \cos^2(2r_k) - \cos(2r_k) \right)^2 \right. \right. \\ &\quad \left. \left. + 4|\omega_j|^2 \cos^2(2r_j) \cos^2(r_k) \right. \right. \\ &\quad \left. \left. \left(-\cos(2r_j) 2|\omega_k|^2 \cos^2(r_j) \cos^2(2r_k) + \cos(2r_k) \right) \right]^{1/2} \right. \\ &\quad \left. + 2|\omega_j|^2 \cos^2(2r_j) \cos^2(r_k) + 2|\omega_k|^2 \cos^2(r_j) \cos^2(2r_k) \right. \\ &\quad \left. - \cos(2r_j) \cos(2r_k) + 1 \right\}, \\ \lambda_{\bar{J}IKI}^{(4)} &= \frac{1}{2} \left[|\omega_j|^2 \cos^2(2r_j) \sin^2(r_k) + |\omega_k|^2 \sin^2(r_j) \cos^2(2r_k) \right. \\ &\quad \left. + \sin^2(r_j) \sin^2(r_k) \right], \end{aligned} \tag{31}$$

where superscripts 2 and 3 in $\lambda_{A\bar{J}IKI}^{(2,3)}$ and $\lambda_{\bar{J}IKI}^{(2,3)}$ correspond to the signs “−” and “+” of the expressions, respectively.

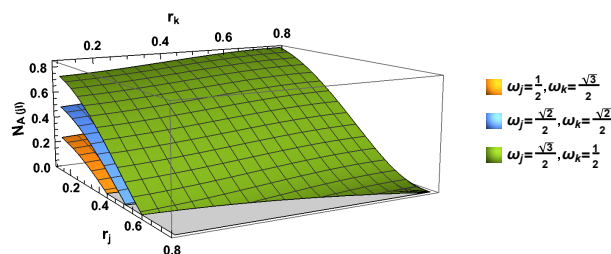


Figure 2. (Color online) The negativity $N_{A(\bar{J}I)}$ (equally $N_{A(\bar{K}I)}$) as the functions of acceleration parameters r_j or r_k .

Likewise, the $\lambda_{A\bar{K}I}^{(1,2,3,4)}$ can be obtained directly from $\lambda_{A\bar{J}I}^{(1,2,3,4)}$ by exchanging $\omega_k \leftrightarrow \omega_j$. As shown in Figure 3, the entropy $S_{A\bar{J}IKI}$ and $S_{\bar{J}IKI}$ increase with the increasing acceleration parameters r_j and r_k . However, $S_{A\bar{J}I}$ ($S_{A\bar{K}I}$) increases with the acceleration parameters r_j but decreases with the acceleration parameters r_k . This is because $S_{A\bar{J}I}$, which is only concerned with the observer Bob confined in region I is mainly from the contribution of the ω_j . To satisfy the constraint $|\omega_j|^2 + |\omega_k|^2 = 1$, the entropy $S_{A\bar{J}I}$ increases with the acceleration parameter r_j but has to be decreased with parameter r_k .

We are now in the position to study the GHZ state, which has the following form in an inertial frame

$$|\phi\rangle = \frac{1}{\sqrt{2}} (|0_{\hat{A}}0_{\hat{B}}0_{\hat{C}}\rangle + |1_{\hat{A}}1_{\hat{B}}1_{\hat{C}}\rangle). \tag{32}$$

Following a similar process to the Bell state studied above, we obtain the matrix form by tracing over the inaccessible Rindler modes in region II

eration parameters r_j and r_k , while the degree of entanglement for all them still exists even in the acceleration limit $r \rightarrow \pi/4$. The negative eigenvalues of the negativities $N_{A(BC_{j\bar{l}}C_{k\bar{l}})}$, $N_{B(AC_{j\bar{l}}C_{k\bar{l}})}$, $N_{C_{j\bar{l}}C_{k\bar{l}}(AB)}$ and $N_{AB(C_{j\bar{l}}C_{k\bar{l}})}$ are written out explicitly in Appendices A and B. If we only consider the subsystem, we can partially track Alice, Bob, Charlie $j\bar{l}$ or Charlie $k\bar{l}$ independently. Based on Equation (25), we are able to calculate the corresponding negativites. For this GHZ state, all 1-1 tangle negativities are equal to 0.

This means that in the subsystems, the entanglement does not exist any more.

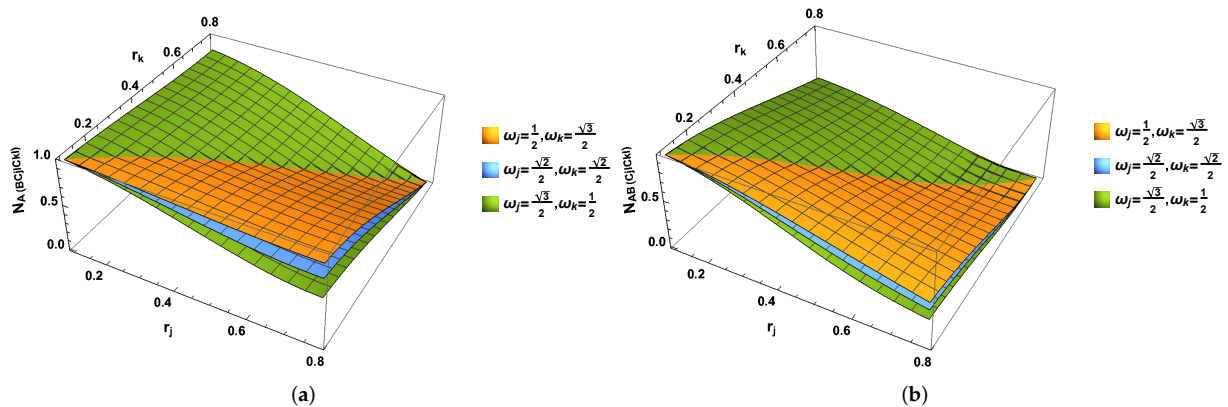


Figure 4. (Color online) The negativity $N_{A(BC_{j\bar{l}}C_{k\bar{l}})}$ (or $N_{B(AC_{j\bar{l}}C_{k\bar{l}})}$) and $N_{AB(C_{j\bar{l}}C_{k\bar{l}})}$ (or $N_{C_{j\bar{l}}C_{k\bar{l}}(AB)}$) as the functions of both acceleration parameters r_j and r_k .

In this part, we use the von Neumann Entropy to measure the degree of the stability of the studied quantum state. In Figures 5 and 6, we can observe the behavior of the von Neumann entropy, and here, we present all the eigenvalues of the whole system and all subsystems.

$$\lambda_{AB}^{(1)} = \frac{1}{2}, \tag{34}$$

$$\lambda_{AB}^{(2)} = \frac{1}{4} (|\omega_j|^2 \cos(4r_j) + |\omega_j|^2 + |\omega_k|^2 \cos(4r_k) + |\omega_k|^2)$$

$$\lambda_{AC_{j\bar{l}}}^{(1)} = \frac{1}{2} \cos^2(r_j),$$

$$\lambda_{AC_{j\bar{l}}}^{(2)} = \frac{1}{2} \sin^2(r_j),$$

$$\lambda_{AC_{j\bar{l}}}^{(3)} = \frac{1}{2} |\omega_k|^2 \cos^2(r_j) \cos^2(2r_k), \tag{35}$$

$$\lambda_{AC_{j\bar{l}}}^{(4)} = \frac{1}{2} (|\omega_k|^2 \sin^2(r_j) \cos^2(2r_k) + |\omega_j|^2 \cos^2(2r_j)),$$

$$\lambda_{ABC_{j\bar{l}}}^{(1)} = \frac{1}{2} \sin^2(r_j),$$

$$\lambda_{ABC_{j\bar{l}}}^{(2)} = \frac{1}{2} |\omega_k|^2 \cos^2(r_j) \cos^2(2r_k),$$

$$\lambda_{ABC_{j\bar{l}}}^{(3,4)} = \frac{1}{8} \left\{ \mp 2 \left[\left(|\omega_k|^2 \sin^2(r_j) \cos^2(2r_k) + |\omega_j|^2 \cos^2(2r_j) + \cos^2(r_j) \right)^2 - |\omega_k|^2 \sin^2(2r_j) \cos^2(2r_k) \right]^{1/2} + 2 (|\omega_k|^2 \sin^2(r_j) \cos^2(2r_k) + \cos^2(r_j)) + |\omega_j|^2 (\cos(4r_j) + 1) \right\}, \tag{36}$$

$$\begin{aligned}
 \lambda_{C_{j\bar{l}}C_{kl}}^{(1)} &= \frac{1}{2} \cos^2(r_j) \cos^2(r_k), \\
 \lambda_{C_{j\bar{l}}C_{kl}}^{(2)} &= \frac{1}{2} \left[|\omega_j|^2 \cos^2(2r_j) \sin^2(r_k) \right. \\
 &\quad \left. + |\omega_k|^2 \sin^2(r_j) \cos^2(2r_k) + \sin^2(r_j) \sin^2(r_k) \right], \\
 \lambda_{C_{j\bar{l}}C_{kl}}^{(3,4)} &= \frac{1}{8} \left\{ \mp \left[4|\omega_j|^4 \cos^4(2r_j) \cos^4(r_k) \right. \right. \\
 &\quad \left. \left. + \left(\cos(2r_j) 2|\omega_k|^2 \cos^2(r_j) \cos^2(2r_k) - \cos(2r_k) \right)^2 \right. \right. \\
 &\quad \left. \left. + 4 \cos^2(2r_j) \cos^2(r_k) |\omega_j|^2 \right. \right. \\
 &\quad \left. \left. \left(-\cos(2r_j) + 2|\omega_k|^2 \cos^2(r_j) \cos^2(2r_k) + \cos(2r_k) \right) \right]^{1/2} \right. \\
 &\quad \left. + 2|\omega_j|^2 \cos^2(2r_j) \cos^2(r_k) + 2|\omega_k|^2 \cos^2(r_j) \cos^2(2r_k) \right. \\
 &\quad \left. - \cos(2r_j) \cos(2r_k) + 1 \right\}, \tag{37}
 \end{aligned}$$

$$\begin{aligned}
 \lambda_{AC_{j\bar{l}}C_{kl}}^{(1)} &= \frac{1}{2} \cos^2(r_j) \cos^2(r_k), \\
 \lambda_{AC_{j\bar{l}}C_{kl}}^{(2)} &= \frac{1}{2} \sin^2(r_j) \cos^2(r_k), \\
 \lambda_{AC_{j\bar{l}}C_{kl}}^{(3)} &= \frac{1}{2} \cos^2(r_j) \sin^2(r_k), \\
 \lambda_{AC_{j\bar{l}}C_{kl}}^{(4)} &= \frac{1}{2} \sin^2(r_j) \sin^2(r_k), \\
 \lambda_{AC_{j\bar{l}}C_{kl}}^{(5)} &= \frac{1}{2} \left[|\omega_j|^2 \cos^2(2r_j) \cos^2(r_k) \right. \\
 &\quad \left. + |\omega_k|^2 \cos^2(r_j) \cos^2(2r_k) \right], \\
 \lambda_{AC_{j\bar{l}}C_{kl}}^{(6)} &= \frac{1}{2} \left[|\omega_j|^2 \cos^2(2r_j) \sin^2(r_k) \right. \\
 &\quad \left. + |\omega_k|^2 \sin^2(r_j) \cos^2(2r_k) \right], \tag{38}
 \end{aligned}$$

$$\begin{aligned}
 \lambda_{ABC_{j\bar{l}}C_{kl}}^{(1)} &= \frac{1}{2} \sin^2(r_k) \sin^2(r_j), \\
 \lambda_{ABC_{j\bar{l}}C_{kl}}^{(2)} &= \frac{1}{4} \left\{ 2 \cos^2(r_k) (|\omega_j|^2 \cos^2(2r_j) + \cos^2(r_j)) \right. \\
 &\quad \left. + |\omega_k|^2 \cos^2(r_j) (\cos(4r_k) + 1) \right\}, \\
 \lambda_{ABC_{j\bar{l}}C_{kl}}^{(3,4)} &= \frac{1}{8} \left\{ \mp \left[\left(2|\omega_k|^2 \sin^2(r_j) \cos^2(2r_k) \right. \right. \right. \\
 &\quad \left. \left. - \cos(2r_j) + \cos(2r_k) \right)^2 + 4|\omega_j|^4 \cos^4(2r_j) \sin^4(r_k) \right. \right. \\
 &\quad \left. \left. + 4 \cos^2(2r_j) \sin^2(r_k) |\omega_j|^2 \left(\cos(2r_j) - \cos(2r_k) \right. \right. \right. \\
 &\quad \left. \left. \left. + 2|\omega_k|^2 \sin^2(r_j) \cos^2(2r_k) \right) \right]^{1/2} \right. \\
 &\quad \left. + 2|\omega_j|^2 \cos^2(2r_j) \sin^2(r_k) \right. \\
 &\quad \left. + 2|\omega_k|^2 \sin^2(r_j) \cos^2(2r_k) \right. \\
 &\quad \left. - \cos(2r_j) \cos(2r_k) + 1 \right\}. \tag{39}
 \end{aligned}$$

It should be noted that $\lambda_{AC_{kl}}$ and $\lambda_{ABC_{kl}}$ can easily be obtained from $\lambda_{AC_{j\bar{l}}}$ and $\lambda_{ABC_{j\bar{l}}}$ by exchanging $r_j \leftrightarrow r_k$ and $\omega_j \leftrightarrow \omega_k$.

In Figure 5, we can see that the entropy $S_{ABC_{j\bar{l}}C_{kl}}$, $S_{AC_{j\bar{l}}C_{kl}}$ and $S_{C_{j\bar{l}}C_{kl}}$ increase with the increasing acceleration parameter r_j and r_k . If we only consider the j mode (k mode), we can partially trace the k mode (j mode). It is seen that von Neumann entropies and $S_{ABC_{j\bar{l}}}$ increase with the increasing r_j . However, von Neumann entropies $S_{A_{j\bar{l}}}$ in the Bell case and $S_{AC_{j\bar{l}}}$ in GHZ state first increase and then decrease with the increasing r_j . All of them $S_{AC_{j\bar{l}}}$, $S_{ABC_{j\bar{l}}}$ and $S_{AC_{j\bar{l}}}$, always decrease with the acceleration parameter r_k .

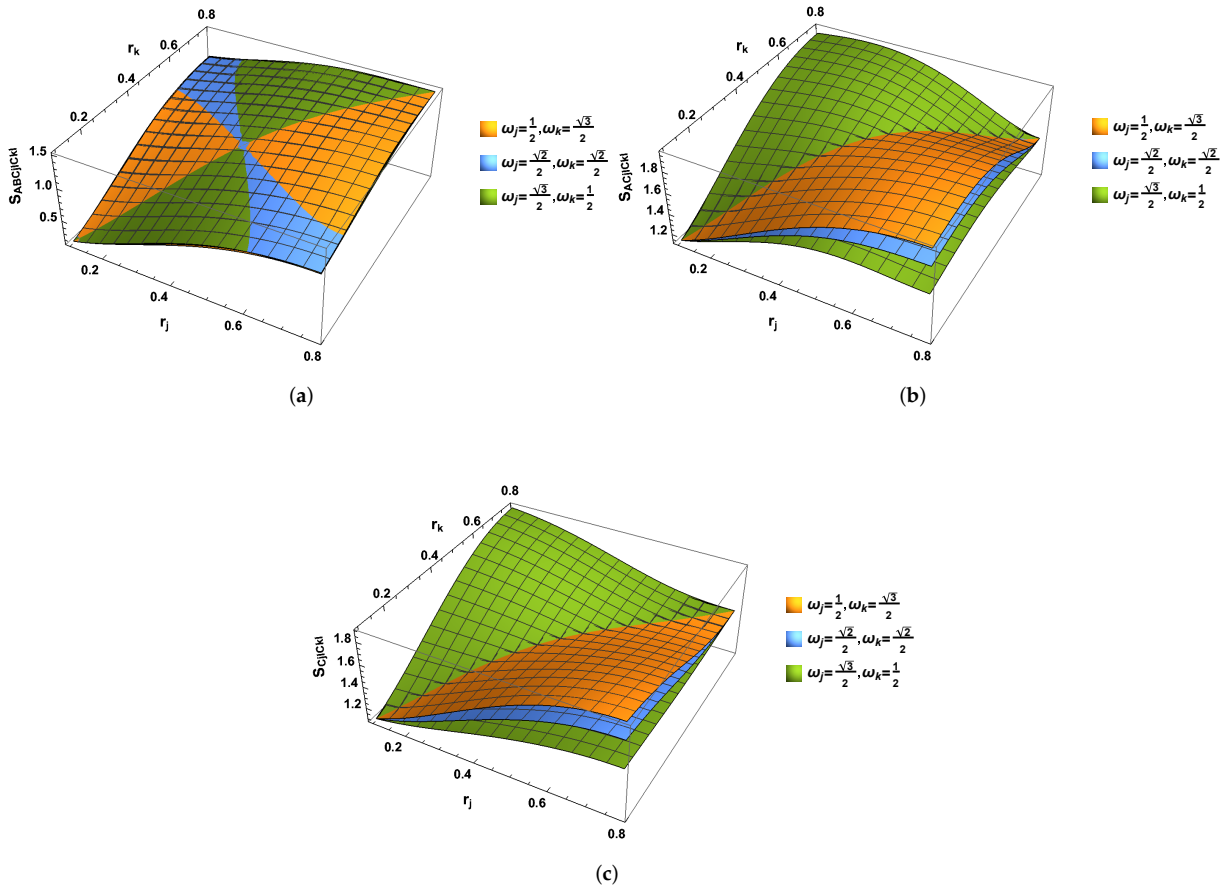


Figure 5. (Color online) The von Neumann entropies $S_{ABC_{\bar{j}}C_{kl}}$, $S_{AC_{\bar{j}}C_{kl}}$ and $S_{C_{\bar{j}}C_{kl}}$ as the functions of both acceleration parameters r_j and r_k .

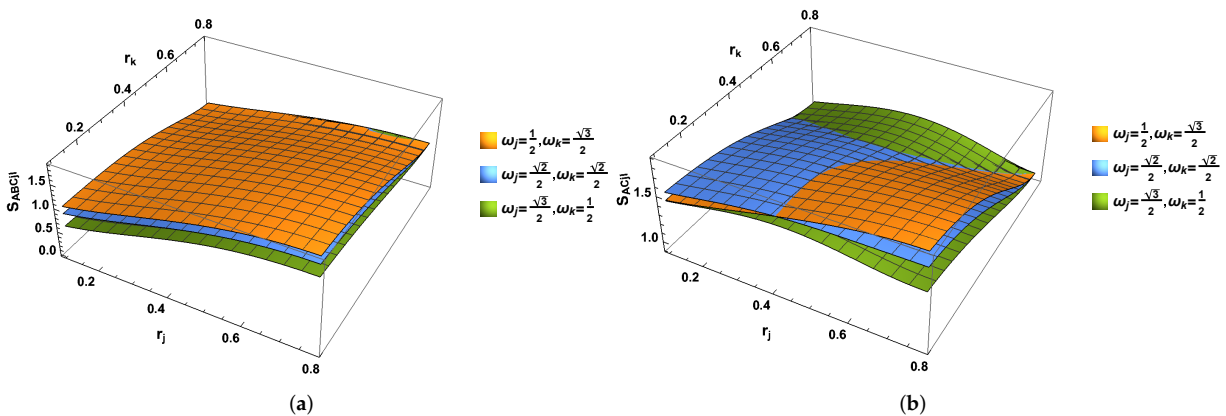


Figure 6. (Color online) The von Neumann Entropies $S_{ABC_{\bar{j}}}$ (or $S_{ABCk_{\bar{j}}}$) and $S_{AC_{\bar{j}}}$ (or $S_{ACk_{\bar{j}}}$) as the functions of both acceleration parameters r_j or r_k .

4. Concluding Remarks

In this work, we have first presented analytical expressions of the Minkowski states $|0\rangle$ and $|1\rangle$ by taking different accelerating observer frames into account. We used the transformation to test the degree of the Bell state’s entanglement by computing the negativity and the von Neumann entropy. For negativity, we can see that for the whole system, the negativity is always positive. However, for the subsystems, if we only consider one

mode, the entanglement of the state depends on the ratio ω_j/ω_k . For the von Neumann entropy of the whole system, we have observed that the entropy increases as the increasing r_j and r_k in the entangled system. However, it is shown from the von Neumann entropy of the subsystem, e.g., S_{ABCjI} and S_{ACjI} , that the former increases with the increasing r_j , but the latter first increases and then decreases with the increasing r_j . Both S_{ABCjI} and S_{ACjI} always decrease with the acceleration parameter r_k .

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Conflicts of Interest: The authors declare no conflict of interest.

Appendix A. Negative Eigenvalues for $N_{A(BCjI)Ckl}$ and $N_{B(ACjI)Ckl}$

$$\begin{aligned} \lambda_{A(BCjI)Ckl}^{(1,2)} = & -\frac{1}{16\sqrt{2}} \left\{ \mp \left[64 \cos(2r_j) \cos(2r_k) \right. \right. \\ & \left. \left. \left(|\omega_j|^2 \cos^2(r_j) \cos(2r_j) + |\omega_k|^2 \cos^2(r_k) \cos(2r_k) \right) \right] \right. \\ & + 4|\omega_j|^2 (\cos(r_j) + \cos(3r_j))^2 (\cos(4r_k) + 3) \\ & \left. + 4|\omega_k|^2 (\cos(4r_j) + 3) (\cos(r_k) + \cos(3r_k))^2 \right\}^{\frac{1}{2}} \end{aligned} \quad (A1)$$

where superscripts 1 and 2 in $\lambda_{A(BCjI)Ckl}^{(1,2)}$ correspond to the signs “−” and “+” of the expressions, respectively.

Appendix B. Negative Eigenvalue for $N_{AB}(C_{j\bar{l}}C_{kl})$ and $N_{C_{j\bar{l}}C_{kl}}(AB)$

$$\begin{aligned}
 \lambda_{AB(C_{j\bar{l}}C_{kl})}^{(1)} &= \lambda_{C_{j\bar{l}}C_{kl}(AB)}^{(1)} = \\
 &\frac{1}{2} \left\{ \text{Root} \left[\#1^2 (512 \cos(2r_j + 2r_k) + 512 \cos(2r_j - 2r_k)) \right. \right. \\
 &+ 2048\#1^3 + 48|\omega_j|^2 \cos(2r_j) + 32|\omega_j|^2 \cos(4r_j) + 28|\omega_j|^2 - 1024 \\
 &- 12|\omega_j|^2 \cos(2r_j - 6r_k) + 16|\omega_j|^2 \cos(6r_j) + 4|\omega_j|^2 \cos(8r_j) \\
 &- 8|\omega_j|^2 \cos(4r_j - 6r_k) - 4|\omega_j|^2 \cos(6r_j - 6r_k) - |\omega_j|^2 \cos(8r_j - 6r_k) \\
 &- 24|\omega_j|^2 \cos(2r_j - 4r_k) - 16|\omega_j|^2 \cos(4r_j - 4r_k) - 8|\omega_j|^2 \cos(6r_j - 4r_k) \\
 &+ 12|\omega_j|^2 \cos(2r_j - 2r_k) + 8|\omega_j|^2 \cos(4r_j - 2r_k) - 2|\omega_j|^2 \cos(8r_j - 4r_k) \\
 &+ 14|\omega_j|^2 \cos(2r_k) + 4|\omega_j|^2 \cos(6r_j - 2r_k) + |\omega_j|^2 \cos(8r_j - 2r_k) \\
 &- 28|\omega_j|^2 \cos(4r_k) - 14|\omega_j|^2 \cos(6r_k) + 12|\omega_j|^2 \cos(2r_j + 2r_k) \\
 &+ 8|\omega_j|^2 \cos(4r_j + 2r_k) + 4|\omega_j|^2 \cos(6r_j + 2r_k) + |\omega_j|^2 \cos(8r_j + 2r_k) \\
 &- 24|\omega_j|^2 \cos(2r_j + 4r_k) - 16|\omega_j|^2 \cos(4r_j + 4r_k) - 8|\omega_j|^2 \cos(6r_j + 4r_k) \\
 &- 2|\omega_j|^2 \cos(8r_j + 4r_k) - 12|\omega_j|^2 \cos(2r_j + 6r_k) - 8|\omega_j|^2 \cos(4r_j + 6r_k) \\
 &- 4|\omega_j|^2 \cos(6r_j + 6r_k) - |\omega_j|^2 \cos(8r_j + 6r_k) + 14|\omega_k|^2 \cos(2r_j) + 28|\omega_k|^2 \\
 &- 28|\omega_k|^2 \cos(4r_j) - 14|\omega_k|^2 \cos(6r_j) + |\omega_k|^2 \cos(2r_j - 8r_k) \\
 &+ 4|\omega_k|^2 \cos(2r_j - 6r_k) - 2|\omega_k|^2 \cos(4r_j - 8r_k) - |\omega_k|^2 \cos(6r_j - 8r_k) \\
 &+ 8|\omega_k|^2 \cos(2r_j - 4r_k) - 8|\omega_k|^2 \cos(4r_j - 6r_k) - 4|\omega_k|^2 \cos(6r_j - 6r_k) \\
 &+ 12|\omega_k|^2 \cos(2r_j - 2r_k) - 16|\omega_k|^2 \cos(4r_j - 4r_k) - 8|\omega_k|^2 \cos(6r_j - 4r_k) \\
 &- 24|\omega_k|^2 \cos(4r_j - 2r_k) - 12|\omega_k|^2 \cos(6r_j - 2r_k) + 48|\omega_k|^2 \cos(2r_k) \\
 &+ 12|\omega_k|^2 \cos(2r_j + 2r_k) + 32|\omega_k|^2 \cos(4r_k) + 16|\omega_k|^2 \cos(6r_k) + 4|\omega_k|^2 \cos(8r_k) \\
 &- 24|\omega_k|^2 \cos(4r_j + 2r_k) - 12|\omega_k|^2 \cos(6r_j + 2r_k) + 8|\omega_k|^2 \cos(2r_j + 4r_k) \\
 &- 16|\omega_k|^2 \cos(4r_j + 4r_k) - 8|\omega_k|^2 \cos(6r_j + 4r_k) + 4|\omega_k|^2 \cos(2r_j + 6r_k) \\
 &- 8|\omega_k|^2 \cos(4r_j + 6r_k) - 4|\omega_k|^2 \cos(6r_j + 6r_k) + |\omega_k|^2 \cos(2r_j + 8r_k) \\
 &- 2|\omega_k|^2 \cos(4r_j + 8r_k) - |\omega_k|^2 \cos(6r_j + 8r_k) + \#1 (32 - 32 \cos(4r_j) \\
 &+ 16 \cos(4r_j + 4r_k) + 16 \cos(4r_j - 4r_k) - 32 \cos(4r_k) \\
 &- 288|\omega_j|^2 \cos(2r_j) - 192|\omega_j|^2 \cos(4r_j) - 96|\omega_j|^2 \cos(6r_j) - 192|\omega_j|^2 \\
 &- 48|\omega_j|^2 \cos(2r_j - 4r_k) - 32|\omega_j|^2 \cos(4r_j - 4r_k) - 16|\omega_j|^2 \cos(6r_j - 4r_k) \\
 &- 192|\omega_j|^2 \cos(2r_j - 2r_k) - 128|\omega_j|^2 \cos(4r_j - 2r_k) - 64|\omega_j|^2 \cos(6r_j - 2r_k) \\
 &- 256|\omega_j|^2 \cos(2r_k) - 64|\omega_j|^2 \cos(4r_k) - 192|\omega_j|^2 \cos(2r_j + 2r_k) \\
 &- 128|\omega_j|^2 \cos(4r_j + 2r_k) - 64|\omega_j|^2 \cos(6r_j + 2r_k) - 48|\omega_j|^2 \cos(2r_j + 4r_k) \\
 &- 32|\omega_j|^2 \cos(4r_j + 4r_k) - 16|\omega_j|^2 \cos(6r_j + 4r_k) - 256|\omega_k|^2 \cos(2r_j) - 192|\omega_k|^2 \\
 &- 64|\omega_k|^2 \cos(4r_j) - 64|\omega_k|^2 \cos(2r_j - 6r_k) - 16|\omega_k|^2 \cos(4r_j - 6r_k) \\
 &- 192|\omega_k|^2 \cos(2r_j - 2r_k) - 128|\omega_k|^2 \cos(2r_j - 4r_k) - 32|\omega_k|^2 \cos(4r_j - 4r_k) \\
 &- 48|\omega_k|^2 \cos(4r_j - 2r_k) - 288|\omega_k|^2 \cos(2r_k) - 192|\omega_k|^2 \cos(4r_k) \\
 &- 192|\omega_k|^2 \cos(2r_j + 2r_k) - 48|\omega_k|^2 \cos(4r_j + 2r_k) - 96|\omega_k|^2 \cos(6r_k) \\
 &- 128|\omega_k|^2 \cos(2r_j + 4r_k) - 32|\omega_k|^2 \cos(4r_j + 4r_k) - 64|\omega_k|^2 \cos(2r_j + 6r_k) \\
 &\left. \left. - 16|\omega_k|^2 \cos(4r_j + 6r_k) \right) \& , 1 \right\} ,
 \end{aligned}
 \tag{A2}$$

where special symbols Root, # and & are generated automatically by Mathematica.

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