

Part 1



Similarity search, pattern discovery and summarization

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Outline

- Motivation
- Similarity Search and Indexing
- Feature extraction
- Linear forecasting
- Streaming pattern discovery
- Automatic mining

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Stream mining



- Applications
 - Sensor monitoring
 - Network analysis
 - Financial and/or business transaction data
 - Web access and media service logs
 - Moving object tracking
 - Industrial manufacturing

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Stream mining



- Requirements
 - Fast**
high performance and quick response
 - Nimble**
low memory consumption, single scan
 - Accurate**
good approximation for pattern discovery and feature extraction

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Monitoring data streams



- Correlation coefficient

$$\rho = \frac{\sum_{t=1}^n (x_t - \bar{x}) \cdot (y_t - \bar{y})}{\sigma(x) \cdot \sigma(y)}$$

$$\sigma(x) = \sqrt{\sum_{t=1}^n (x_t - \bar{x})^2}$$

- Correlation coefficient and the (Euclidean) distance

$$\rho = 1 - \frac{1}{2} \sum_{t=1}^n (\hat{x}_t - \hat{y}_t)^2 \quad \hat{x}_t = (x_t - \bar{x}) / \sigma(x)$$

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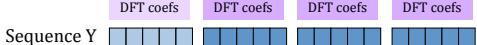


Monitoring data streams



Dennis Shasha

- Correlation monitoring [Zhu+, vldb02]
 - DFT coefficients for each basic window
 - Correlation coefficient of each sliding window computed from the 'sketch' (DFT coeffs)

Sequence X: 
 Sequence Y: 

Sliding window: 

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Kumamoto U **Monitoring data streams** **CMU CS**

- Grid structure (to avoid checking all pairs)
 - DFT coefficients yields a vector
 - High correlation -> closeness in the vector space

Vector V_X of sequence X
Vector V_Y of sequence Y
Correlation coefficients and the Euclidean distance
 $\rho = 1 - \frac{1}{2} \sum_{i=1}^n (\hat{x}_i - \hat{y}_i)^2$

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Kumamoto U **Monitoring data streams** **CMU CS**

- Lag correlation [Sakurai+, sigmod05]

CCF (Cross-Correlation Function)

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Kumamoto U **Monitoring data streams** **CMU CS**

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Kumamoto U **Lag correlation** **CMU CS**

- Definition of ‘score’, absolute value of $R(l)$

$$score(l) = |R(l)| \quad R(l) = \frac{\sum_{t=l+1}^n (x_t - \bar{x})(y_{t-l} - \bar{y})}{\sqrt{\sum_{t=l+1}^n (x_t - \bar{x})^2} \sqrt{\sum_{t=1}^{n-l} (y_t - \bar{y})^2}}$$

- Lag correlation
 - Given a threshold γ , $score(l) > \gamma$
 - A local maximum
 - The earliest such maximum, if more maxima exist

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Kumamoto U **Lag correlation** **CMU CS**

- Why not naïve?
 - Compute correlation coefficient for each lag
 $l = \{0, 1, 2, 3, \dots, n/2\}$
- But
 - $O(n)$ space
 - $O(n^2)$ time
 - or $O(n \log n)$ time w/ FFT

Correlation

Time

$t=n$

Level

$2^3 \ 2^2 \ 2^1 \ 2^0$

$h=0$

$t=n$

$0 \quad Lag \quad n/2$

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Kumamoto U **Lag correlation** **CMU CS**

- BRAID
 - Geometric lag probing + smoothing
 - Use colored windows
 - Keep track of only a geometric progression of the lag values: $l = \{0, 1, 2, 4, 8, \dots, 2^h, \dots\}$

Correlation

Time

$2^3 \ 2^2 \ 2^1 \ 2^0$

Level

$h=0$

$t=n$

$0 \quad Lag \quad 2^3$

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Lag correlation

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Lag correlation

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Lag correlation

- BRAID
 - Geometric lag probing + smoothing
 - Keep track of only a geometric progression of the lag values: $l = \{0, 1, 2, 4, 8, \dots, 2^h, \dots\}$
 - Use a cubic spline to interpolate

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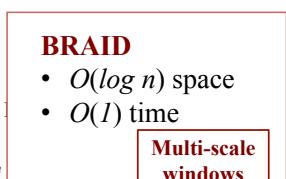
Lag correlation

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 - Compute correlation coefficient for each lag
 $l = \{0, 1, 2, 3, \dots, n/2\}$
- But
 - $O(n)$ space
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 - or $O(n \log n)$ time w/ \dots

BRAID

- $O(\log n)$ space
- $O(1)$ time

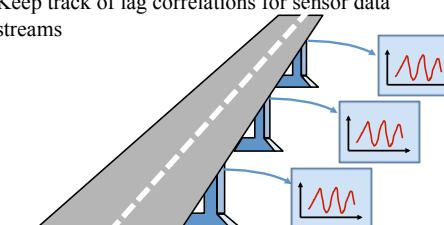
Multi-scale windows



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BRAID in the real world

- Bridge structural health monitoring
 - Structural monitoring using vibration/shock sensors
 - Keep track of lag correlations for sensor data streams



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BRAID in the real world

- Bridge structural health monitoring
 - Goal: real-time anomaly detection for disaster prevention
 - Several thousands readings (per sec) from several hundreds sensor nodes



- Uses BRAID
- Metropolitan Expressway (Tokyo, Japan)

Structural health monitoring

Vibration/shock sensor

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BRAID in the real world

- Bridge structural health monitoring with BRAID



Metropolitan Expressway
(Tokyo, Japan)



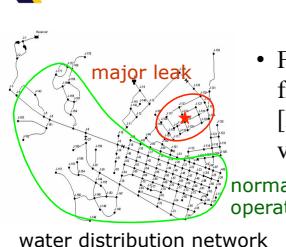
Tokyo Gate Bridge
(Tokyo, Japan)



Can Tho Bridge (Vietnam)

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Feature extraction from streams



- Find hidden variables from streams [Papadimitriou+, vldb2005]

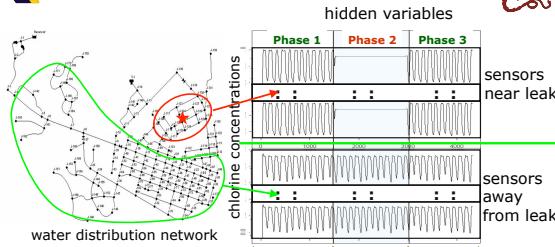


water distribution network

May have hundreds of measurements, but it is **unlikely they are completely unrelated!**

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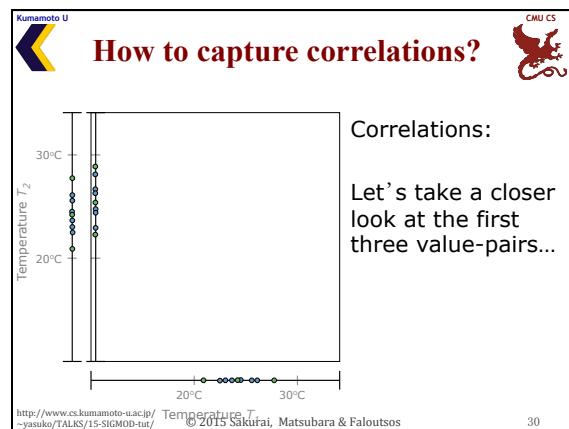
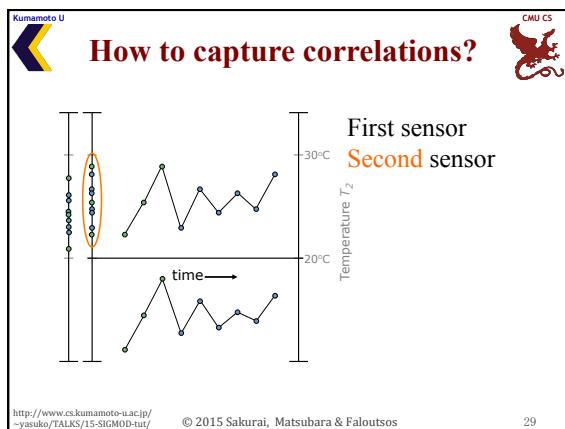
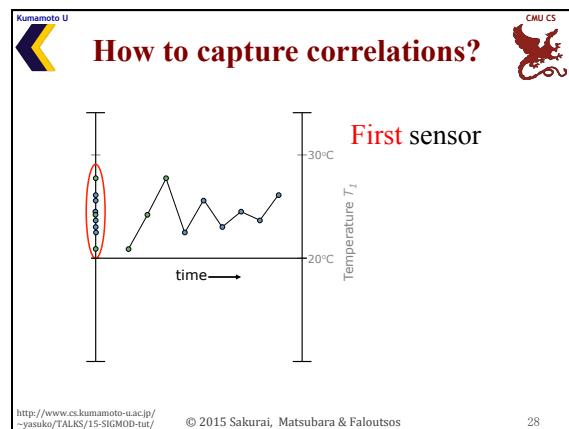
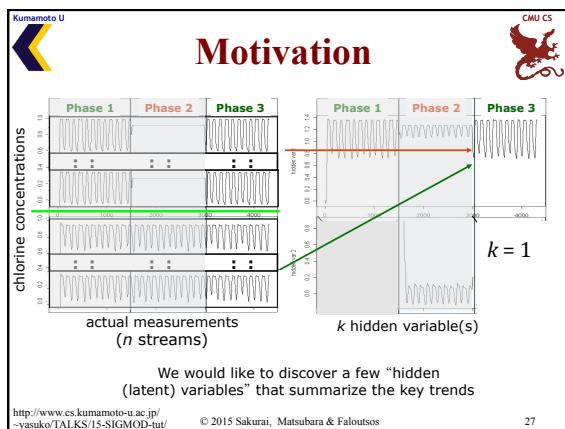
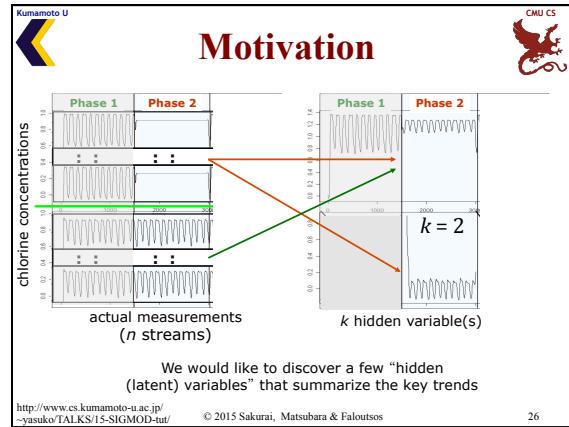
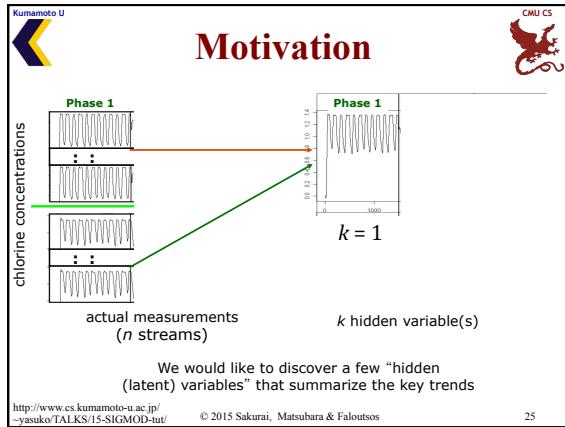
Feature extraction from streams

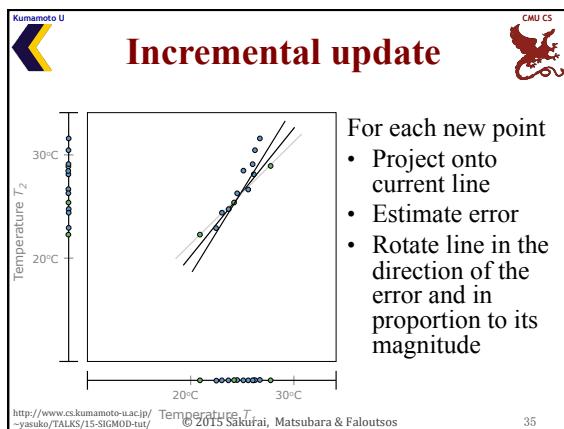
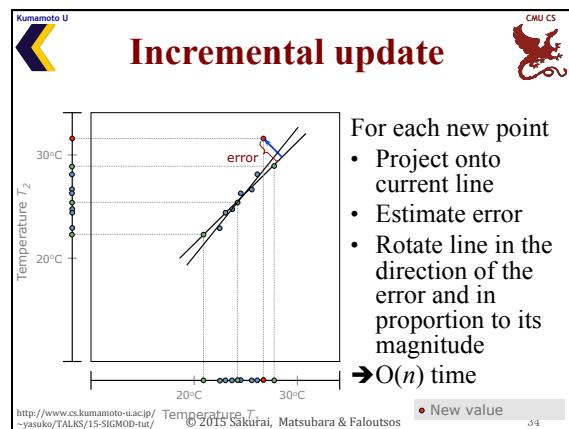
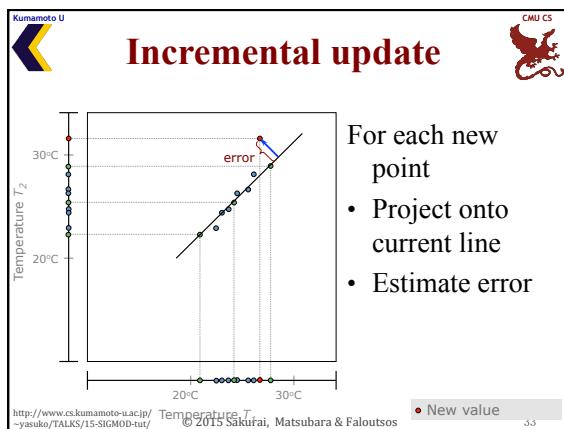
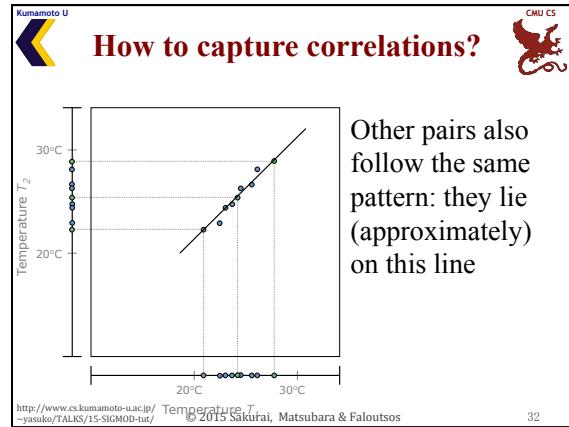
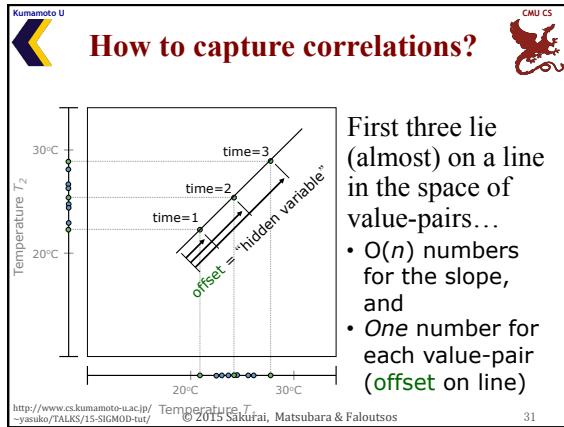


hidden variables		
Phase 1	Phase 2	Phase 3
⋮	⋮	⋮
sensors near leak		
chlorine concentrations	⋮	⋮
⋮	⋮	⋮
sensors away from leak		
⋮	⋮	⋮
normal operation	⋮	⋮

May have hundreds of measurements, but it is **unlikely they are completely unrelated!**

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- Related work**
- Wavelet over streams [Gilbert+, vldb01] [Guha+, vldb04]
 - Fourier representations [Gilbert+, stoc02]
 - KNN [Koudas+, 04] [Korn+, vldb02]
 - Histograms [Guha+, stoc01]
 - Clustering [Guha+, focs00] [Aggarwal+, vldb03]
 - Sketches [Indyk+, vldb00] [Cormode+, J. Algorithms 05]
 - ...
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Related work

- Heavy hitters [Cormode+, vldb03]
- Data embedding [Indyk+, focs00]
- Burst detection [Zhu+, kdd03]
- Segmentation [Keogh+, icdm01]
- Multiple scale analysis [Papadimitriou+, sigmod06]
- Fractal [Korn+, sigmod06]
- Time warping [Sakurai+, icde07]...
- ...

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Motivation

Given: co-evolving time-series
– e.g., MoCap (leg/arm sensors)

“Chicken dance”

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Motivation

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Motivation

Challenges: co-evolving sequences

- Unknown # of patterns (e.g., beaks)
- Different durations

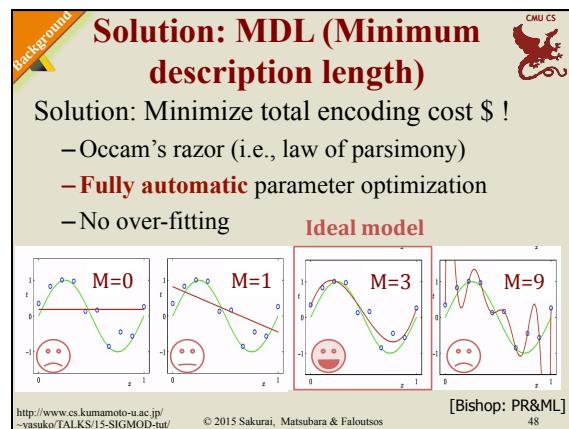
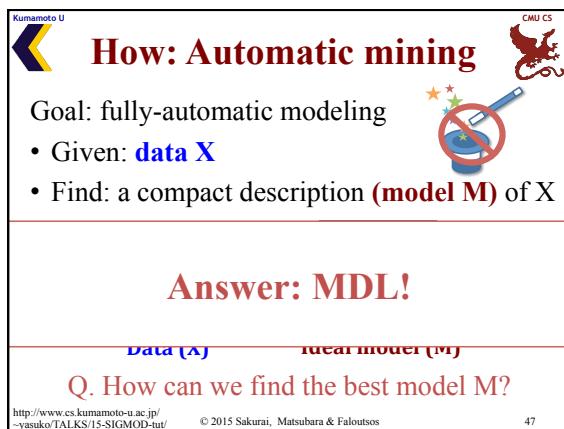
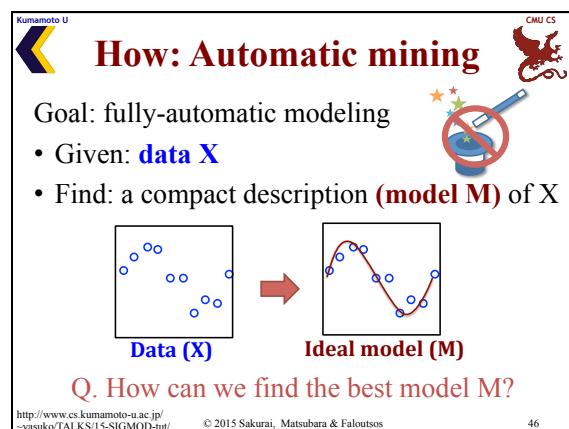
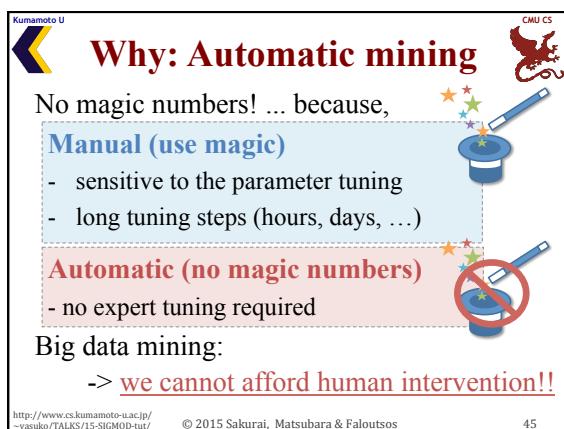
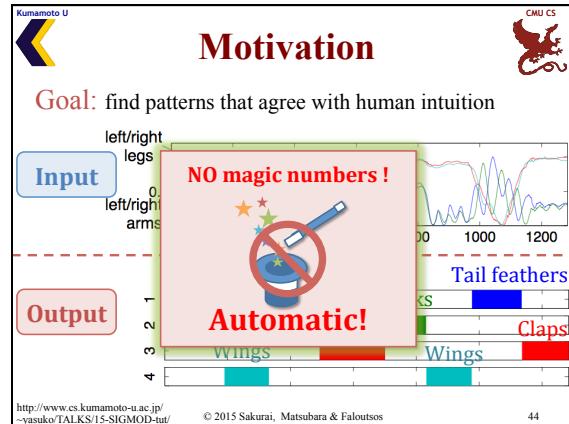
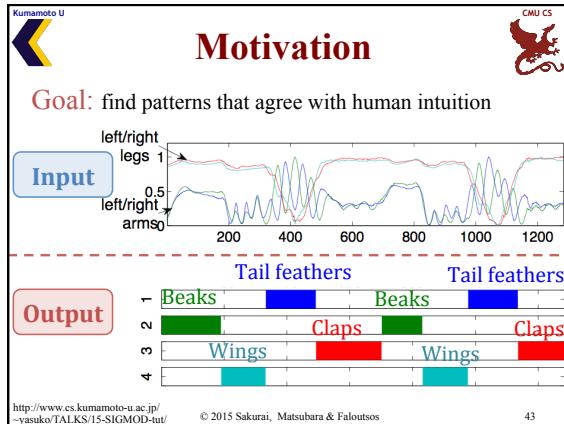
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Motivation

Goal: find patterns that agree with human intuition

Input

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Solution: MDL (Minimum description length)

Solution: Minimize total encoding cost \$!

$$\text{Cost}_T(X;M) = \min (\text{Cost}_M(M) + \text{Cost}_c(X|M))$$

Total cost Model cost Coding cost(error)

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[Matsubara+ SIGMOD'14]

AutoPlait: Automatic Mining of Co-evolving Time Sequences

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Yasushi Sakurai (Kumamoto University),
Christos Faloutsos (CMU)

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Kumamoto U

Problem definition

Goal: find patterns that agree with human intuition

Input: left/right legs, left/right arms

Output: Tail feathers, Beaks, Claps, Wings

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Kumamoto U

Problem definition

- **Bundle**: set of d co-evolving sequences

given $X = \{x_1, \dots, x_n\}_{d \times n}$

Bundle X (d=4)

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Kumamoto U

Problem definition

- **Segment**: convert $X \rightarrow m$ segments, S

hidden $S = \{s_1, \dots, s_m\}$

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Kumamoto U

Problem definition

- **Regime**: segment groups: $\Theta = \{\theta_1, \theta_2, \dots, \theta_r, \Delta_{r,r}\}$

hidden
Regimes ($r=4$)

θ_r : model of regime r

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Kumamoto U **CMU CS**

Problem definition

- Segment-membership: assignment

hidden

$$F = \{f_1, \dots, f_m\}$$

$F = \{ \dots \}$

Segment-membership ($m=8$)

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Kumamoto U **CMU CS**

Problem definition

- Given: **bundle X**

$$X = \{x_1, \dots, x_n\}$$

left/right legs

left/right arms

- Find: **compact description C of X**

$$C = \{m, r, S, \Theta, F\}$$

$C = \{m, r, S, \Theta, F\}$

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Kumamoto U **CMU CS**

Problem definition

- Given: **bundle X**

$$X = \{x_1, \dots, x_n\}$$

left/right legs

left/right arms

- Find: **compact description C of X**

$$C = \{m, r, S, \Theta, F\}$$

m segments

r regimes

Segment-membership

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Kumamoto U **CMU CS**

Main ideas

Goal: compact description of X

$$C = \{m, r, S, \Theta, F\}$$

without user intervention!!

Challenges:

Q1. How to generate ‘informative’ regimes ?

Q2. How to decide # of regimes/segments ?

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Kumamoto U **CMU CS**

Main ideas

Goal: compact description of X

$$C = \{m, r, S, \Theta, F\}$$

without user intervention!!

Challenges:

Q1. How to generate ‘informative’ regimes ?
Idea (1): Multi-level chain model

Q2. How to decide # of regimes/segments ?
Idea (2): Model description cost

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Idea (1): MLCM: multi-level chain model

Q1. How to generate ‘informative’ regimes ?

Sequences

Model

beaks

claps

wings

Regimes

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Idea (1): MLCM: multi-level chain model

Q1. How to generate ‘informative’ regimes?

Sequences → Model → Regimes (beaks, wings, claps)

Idea (1): Multi-level chain model
–HMM-based probabilistic model
–with “across-regime” transitions

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Idea (1): MLCM: multi-level chain model

$\Theta = \{\theta_1, \theta_2, \dots, \theta_r, \Delta_{r,r}\}$ (Regimes $r=2$)
 $(\theta_i = \{\pi, A, B\})$ across-regime transition prob.
Single HMM parameters

Regime switch: δ_{12} , δ_{21}

Regime 1 “beaks” Regime 2 “wings”

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Idea (2): model description cost

Q2. How to decide # of regimes/segments?

Idea (2): Model description cost

- Minimize encoding cost
- find “optimal” # of segments/regimes

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Idea (2): model description cost

Idea: Minimize encoding cost!

$\min (\text{Cost}_M(\mathbf{M}) + \text{Cost}_C(\mathbf{X}|\mathbf{M}))$

Model cost Coding cost

Good compression Good description

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Idea (2): model description cost

Total cost of bundle \mathbf{X} , given \mathcal{C}

$$C = \{m, r, S, \Theta, F\}$$

$$\begin{aligned} \text{Cost}_T(\mathbf{X}; \mathcal{C}) &= \text{Cost}_T(\mathbf{X}; m, r, S, \Theta, \mathcal{F}) \\ &= \log^*(n) + \log^*(d) + \log^*(m) + \log^*(r) + m \log(r) \\ &\quad + \sum_{i=1}^{m-1} \log^* |s_i| + \text{Cost}_M(\Theta) + \text{Cost}_C(\mathbf{X}|\Theta) \end{aligned} \quad (6)$$

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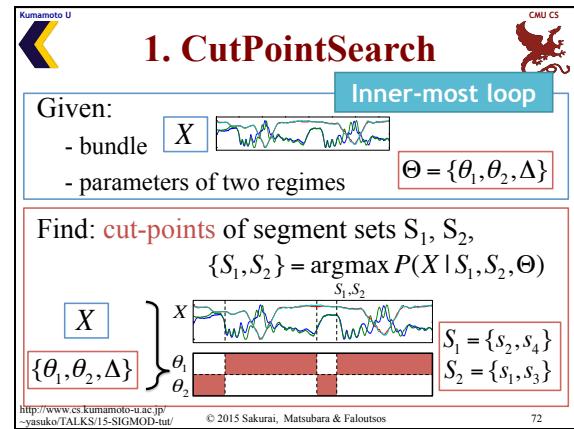
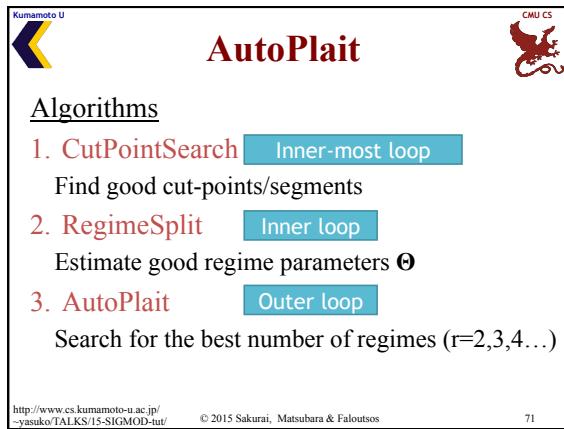
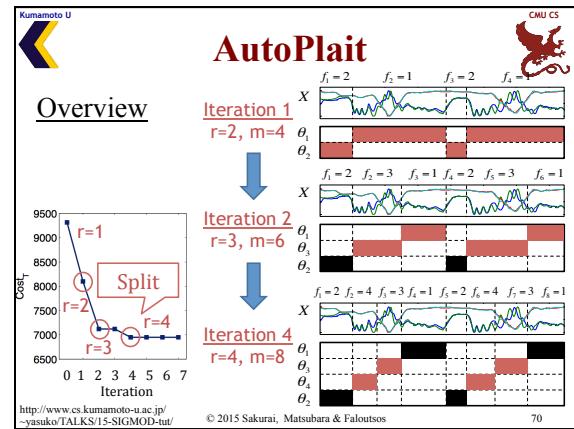
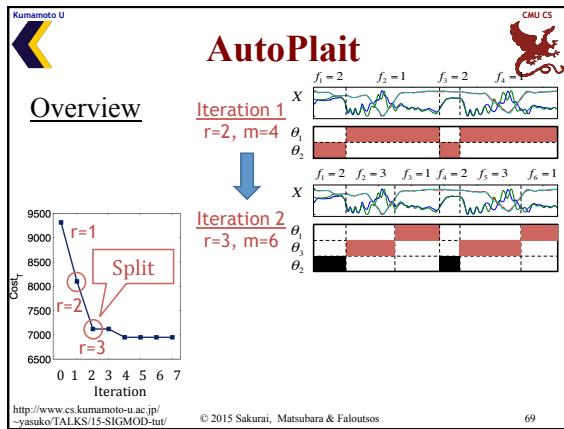
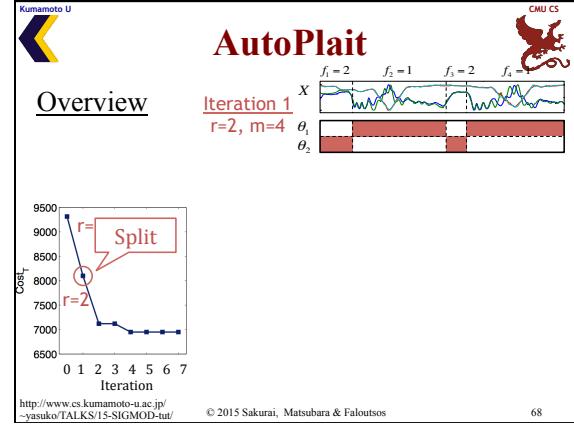
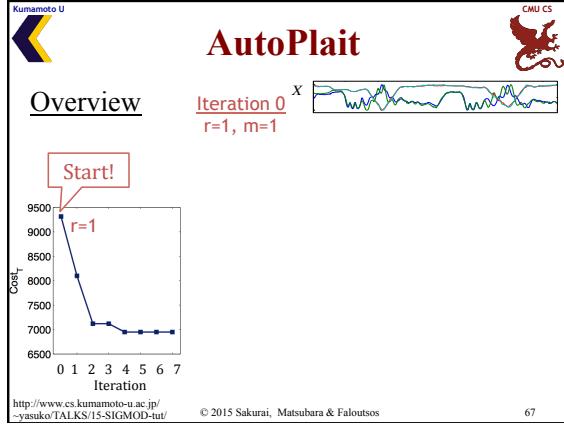
Idea (2): model description cost

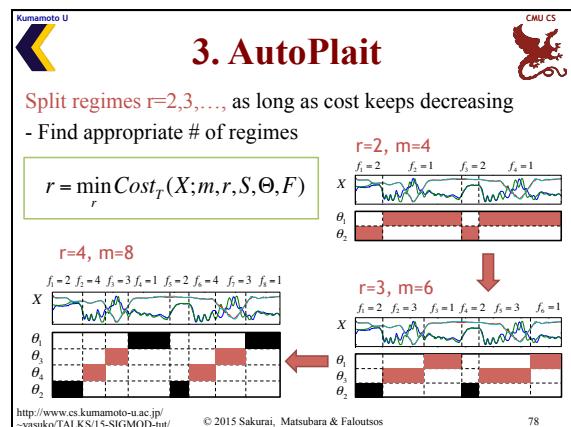
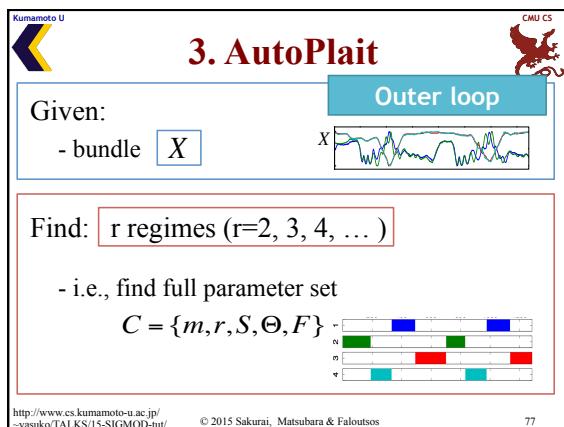
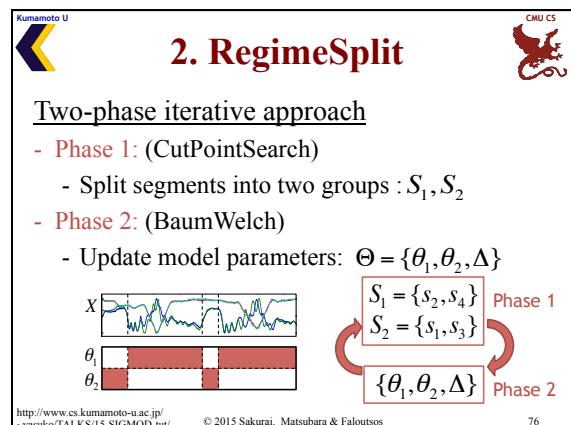
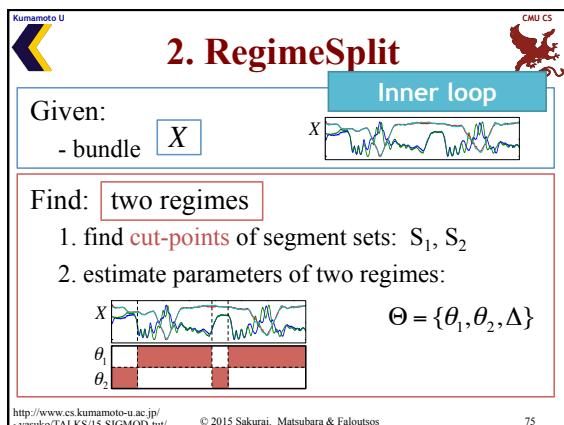
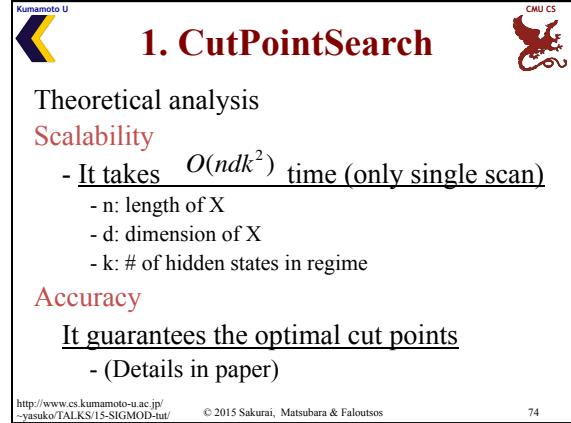
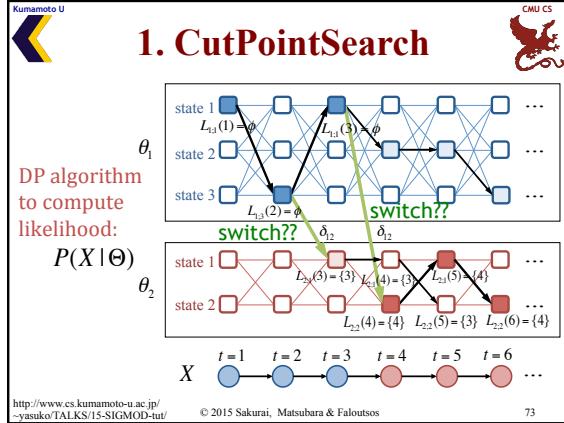
Total cost of bundle \mathbf{X} , given \mathcal{C}

$$C = \{m, r, S, \Theta, F\}$$

duration/dimensions	# of segments/regimes	segment-membership F
$\text{Cost}_T(\mathbf{X}; \mathcal{C}) = \text{Cost}_T(\mathbf{X}; m, r, S, \Theta, \mathcal{F})$	$= \log^*(n) + \log^*(d) + \log^*(m) + \log^*(r) + m \log(r)$	
	$+ \sum_{i=1}^{m-1} \log^* s_i + \text{Cost}_M(\Theta) + \text{Cost}_C(\mathbf{X} \Theta)$	
segment lengths	Model description cost of Θ	Coding cost of \mathbf{X} given Θ

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Results

- Mocap data
- WebClick data
- Google Trends

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Q1. Sense-making

MoCap data

AutoPlait (NO magic numbers)

(a) AUTOPLAIT (no user defined parameters)

DynaMMo (Li et al., KDD'09) pHMM (Wang et al., SIGMOD'11)

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Q1. Sense-making

MoCap data

AutoPlait (NO magic numbers)

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Q2. Accuracy

(a) Segmentation

(a) Precision and recall (higher is better)

(b) Clustering

(b) CE score (lower is better)

AutoPlait needs “no magic numbers” *

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Q3. Scalability

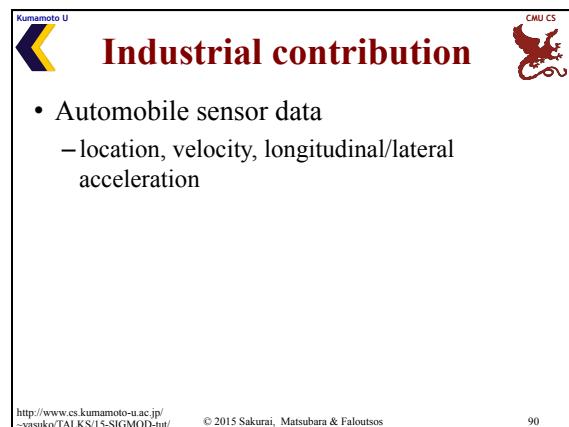
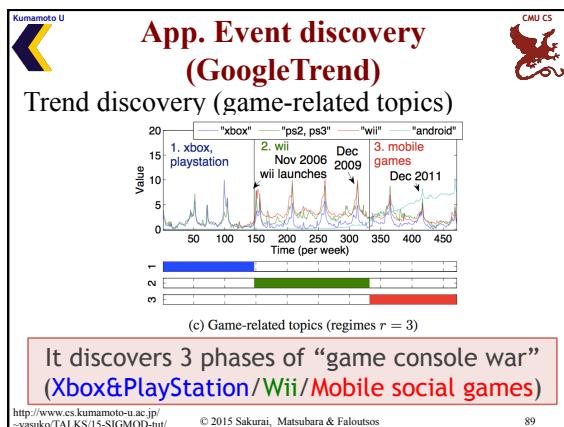
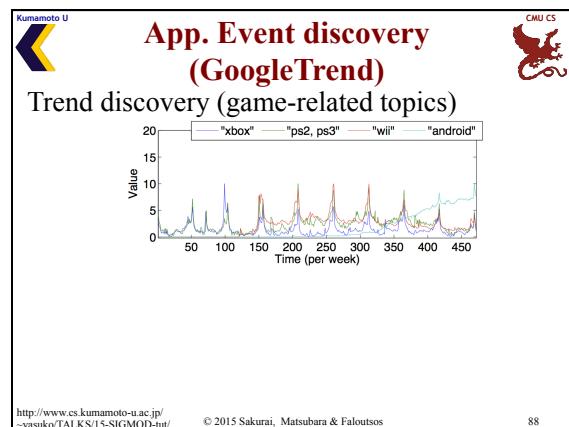
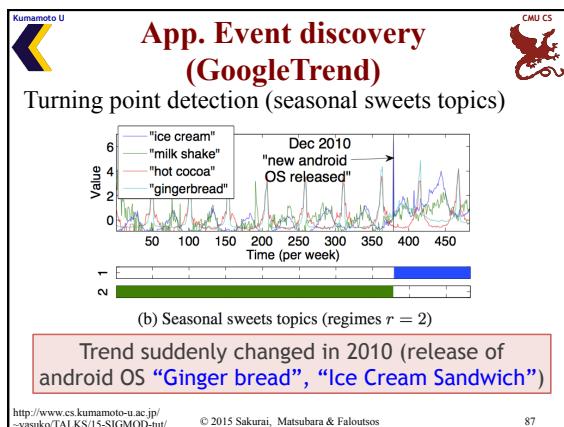
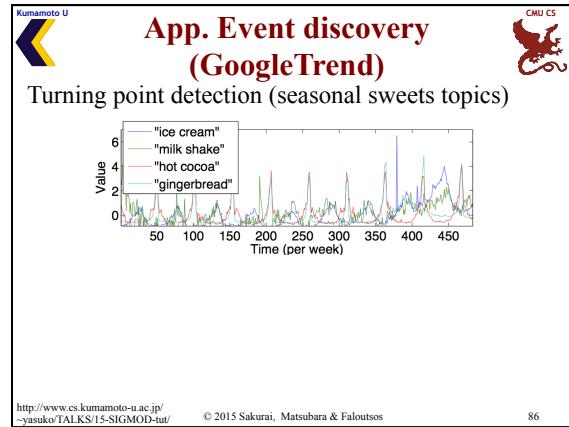
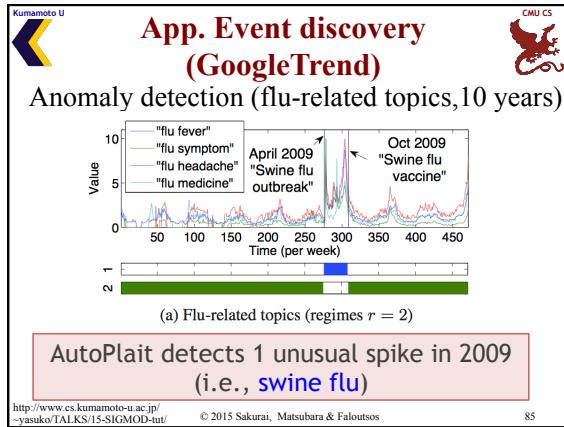
Wall clock time vs. data size (length) : n
AutoPlait scales linearly, i.e., O(n)

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App. Event discovery (GoogleTrend)

Anomaly detection (flu-related topics, 10 years)

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Code at

- <http://www.cs.kumamoto-u.ac.jp/~yasuko/software.html>

<http://www.cs.kumamoto-u.ac.jp/~yasuko/TALKS/15-SIGMOD-tut/> © 2015 Sakurai, Matsubara & Faloutsos 91

Part 1 – Conclusions

- Motivation
- Similarity Search and Indexing
- Feature extraction
- Linear forecasting
- Streaming pattern discovery
- Automatic mining

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Part 1 – Conclusions

- Motivation
- Similarity Search and Indexing
 - Euclidean/time-warping
 - extract features
 - index (SAM, R-tree)
- Feature extraction
 - SVD, ICA, DFT, DWT (multi-scale windows)

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Part 1 – Conclusions

- Linear forecasting
 - AR, RLS
- Streaming pattern discovery
 - RLS, “incremental” wavelet transform
 - Multi-scale windows
- Automatic mining
 - MDL

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Part 1

**Similarity search,
pattern discovery and
summarization**

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