

# Directed Information Optimization and Capacity of the POST Channel with and without Feedback

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## Directed Information

$$I(X^n \rightarrow Y^n) \triangleq \sum_{i=1}^n I(X^i; Y_i | Y^{i-1})$$

POST Channel  
Previous Output is the State

Convex Optimization

$$I(X^n; Y^n) \triangleq H(Y^n) - H(Y^n|X^n)$$

$$H(Y^n|X^n) \triangleq E[-\log P(Y^n|X^n)]$$

$$P(y^n|x^n) = \prod_{i=1}^n P(y_i|x^n, y^{i-1})$$

*Directed Information*

[Massey90] inspired by [Marko 73]

$$I(X^n \rightarrow Y^n) \triangleq H(Y^n) - H(Y^n || X^n)$$

$$I(X^n; Y^n) \triangleq H(Y^n) - H(Y^n | X^n)$$

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## *Causal Conditioning*

[Kramer98]

$$H(Y^n || X^n) \triangleq E[-\log P(Y^n || X^n)]$$

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$$P(y^n || x^{n-1}) \triangleq \prod_{i=1}^n P(y_i | x^{i-1}, y^{i-1})$$

# Directed information and causal conditioning characterizes

- 1 rate reduction in **lossless compression** due to causal side information at the decoder,
- 2 the gain in growth rate in **horse-race gambling** due to causal side information
- 3 **channel capacity** with feedback,
- 4 **multi user capacity with feedback**: broadcast, MAC, compound, memory-in-block networks
- 5 **rate distortion** with feedforward,
- 6 **causal MMSE** for additive Gaussian noise,
- 7 **stock investment** with causal side information,
- 8 measure of **causal relevance** between processes,
- 9 **actions with causal constraint** such as “to feed or not to feed back”,



# Directed information optimization

How to find

$$\max_{p(x^n||y^{n-1})} I(X^n \rightarrow Y^n).$$

Recall

$$\begin{aligned} I(X^n \rightarrow Y^n) &= \sum_{i=1}^n I(X^i; Y_i | Y^{i-1}) \\ &= H(Y^n) - H(Y^n || X^n) \\ &= \sum_{y^n, x^n} p(x^n, y^n) \log \frac{p(y^n || x^n)}{p(y^n)} \end{aligned}$$

$P(x^n, y^n)$  can be expressed by the chain-rule

$$p(x^n, y^n) = p(x^n || y^{n-1}) p(y^n || x^n)$$

## Lemma: causal conditioning is a polyhedron

The set of all causal conditioning distributions of the form  $P(x^n || y^{n-1})$  is a polyhedron in  $\mathbb{R}^{|\mathcal{X}|^n |\mathcal{Y}|^{n-1}}$  and is given by the following linear equalities and inequalities:

$$\begin{aligned} p(x^n || y^{n-1}) &\geq 0, & \forall x^n, y^{n-1}, \\ \sum_{x_{i+1}^n} p(x^n || y^{n-1}) &= \gamma_{x^i, y^{i-1}}, & \forall x^i, y^{i-1}, i \geq 1, \\ \sum_{x_1^n} p(x^n || y^{n-1}) &= 1, & \forall y^{n-1}. \end{aligned}$$

# Convexity of directed information causal conditioning

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## Lemma: concavity of directed information

For a fixed channel  $p(y^n || x^n)$ , the directed information  $I(X^n \rightarrow Y^n)$  is concave in  $p(x^n || y^{n-1})$ .

$$I(X^n; Y^n) \triangleq H(Y^n) - H(Y^n|X^n)$$

# Directed information as a functional

$$\begin{aligned} I(X^n; Y^n) &\triangleq H(Y^n) - H(Y^n|X^n) \\ &= \sum_{y^n, x^n} Q(x^n)P(y^n|x^n) \ln \frac{P(y^n|x^n)}{\sum_{x^n} Q(x^n)P(y^n|x^n)} \end{aligned}$$

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# Property of the optimization problem

$$\max_{p(x^n||y^{n-1})} I(X^n \rightarrow Y^n)$$

## Good news

- $I(X^n \rightarrow Y^n)$  is convex in  $p(x^n||y^{n-1})$  for a fixed  $p(y^n||x^n)$ .
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## Benefits:

- Efficient algorithm for finding the maximum.
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## To be careful

- $I(X^n \rightarrow Y^n)$  non-convex in  $p(x_1), \dots, p(x_n|x^{n-1}, y^{n-1})$
- Cannot optimize each term in  $\sum_i I(X^i; Y_i|Y^{i-1})$  separately.

# The Alternating maximization procedure

## Lemma (Double maximization)

$$\max_{p(x^n \| y^{n-1})} I(X^n \rightarrow Y^n) = \max_{p(x^n \| y^{n-1}), q(x^n | y^n)} I(X^n \rightarrow Y^n).$$

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Let  $f(u_1, u_2)$ , be a convex fun and we want to find

$$\max_{u_1 \in \mathcal{A}_1, u_2 \in \mathcal{A}_2} f(u_1, u_2).$$

The procedure is

$$u_1^{(k+1)} = \arg \max_{u_1 \in \mathcal{A}_1} f(u_1^{(k)}, u_2^{(k)}), \quad u_2^{(k+1)} = \arg \max_{u_2 \in \mathcal{A}_2} f(u_1^{(k+1)}, u_2^{(k)}).$$

$$f^{(k)} = f(u_1^{(k)}, u_2^{(k)}).$$

## Theorem (The Alternating maximization procedure)

$$\lim_{k \rightarrow \infty} f^{(k)} = \max_{u_1 \in \mathcal{A}_1, u_2 \in \mathcal{A}_2} f(u_1, u_2).$$

Compute by the alternating maximization procedure

$$\max_{p(x^n|y^{n-1})} \max_{q(x^n|y^n)} I(X^n \rightarrow Y^n).$$

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$$\max_{p(x^n \| y^{n-1})} \max_{q(x^n | y^n)} I(X^n \rightarrow Y^n).$$

## 1st step

**Lemma** ( $\max_{q(x^n | y^n)} I(X^n \rightarrow Y^n)$ )

*For fixed  $p(x^n \| y^{n-1})$ ,  $q^*(x^n | y^n)$  that achieves  $\max_{q(x^n | y^n)} I(X^n \rightarrow Y^n)$ , is*

$$q^*(x^n | y^n) = \frac{p(x^n \| y^{n-1})p(y^n \| x^n)}{\sum_{x^n} p(x^n \| y^{n-1})p(y^n \| x^n)}.$$

## 2nd Step

**Lemma** ( $\max_{p(x^n||y^{n-1})} I(X^n \rightarrow Y^n)$ )

For fixed  $q(x^n|y^n)$ ,  $p^*(x^n||y^{n-1})$  that achieves  $\max_{p(x^n||y^{n-1})} I(X^n \rightarrow Y^n)$ , is:  
starting from  $i = n$ , compute  $p(x_i|x^{i-1}, y^{i-1})$

$$p_i = p^*(x_i|x^{i-1}, y^{i-1}) = \frac{p'(x^i, y^{i-1})}{\sum_{x_i} p'(x^i, y^{i-1})},$$

where

$$p'(x^i, y^{i-1}) = \prod_{x_{i+1}^n, y_i^n} \left[ \frac{q(x^n|y^n)}{\prod_{j=i+1}^n p_j} \right]^{\prod_{j=i}^n p(y_j|x^j, y^{j-1}) \prod_{j=i+1}^n p_j},$$

and do so **backwards** until  $i = 1$ .

## Main ideas of 2nd Step

- Exchange  $p(x^n \| y^{n-1})$  by the set  $\{p_i\}_{i=1}^n$  where  
 $p_i = p(x_i | x^{i-1}, y^{i-1})$

$$\max_{p(x^n \| y^{n-1})} I(X^n \rightarrow Y^n) = \max_{p_1} \max_{p_2} \dots \max_{p_n} I(X^n \rightarrow Y^n)$$

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$$q(x^n | y^n), p_{i+1}, p_{i+2}, \dots, p_n$$

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- Hence we can find

$$\max_{p_1} \dots \left( \max_{p_{n-1}} \left( \max_{p_n} I(X^n \rightarrow Y^n) \right) \right)$$

despite being nonconvex.

# How to terminate the algorithm?

- Using steps 1 and 2 we can compute

$$I_L = \sum_{y^n, x^n} p(y^n \| x^n) r(x^n \| y^{n-1}) \log \frac{q(x^n | y^n)}{p(x^n \| y^{n-1})}.$$

which converges from below to  $\max_{p(x^n \| y^{n-1})} I(X^n \rightarrow Y^n)$

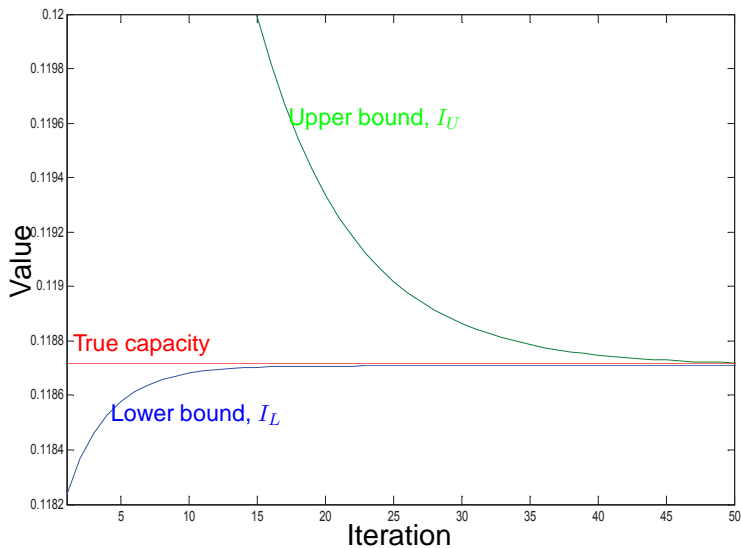
- We also have an upper bound

$$I_U = \max_{x_1} \sum_{y_1} \max_{x_2} \cdots \sum_{y_{n-1}} \max_{x_n} \sum_{y_n} p(y^n \| x^n) \log \frac{p(y^n \| x^n)}{\sum_{x'^n} p(y^n \| x'^n) p(x'^n \| y^{n-1})}$$

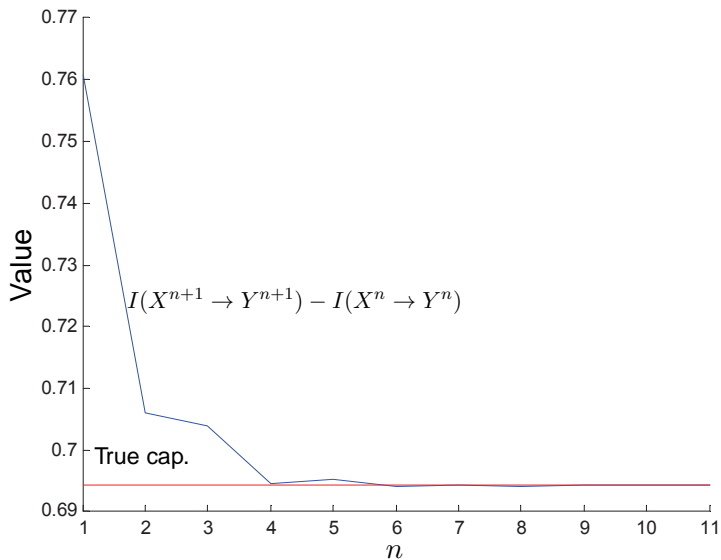
- The algorithm terminates when

$$|I_U - I_L| \leq \epsilon$$

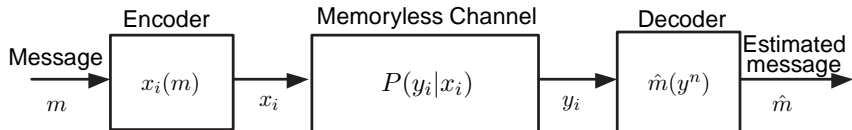
# maximizing the directed information for BSC(0.3)



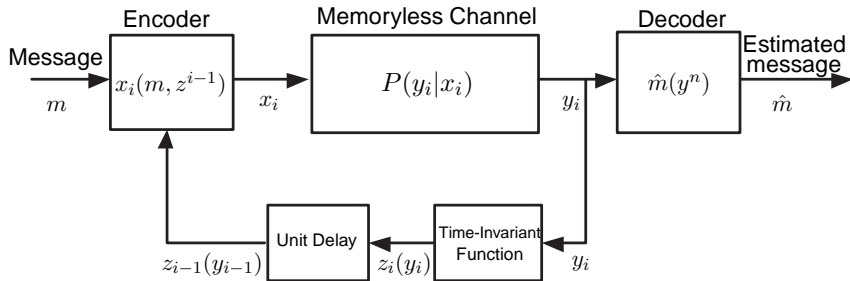
# Directed information rate



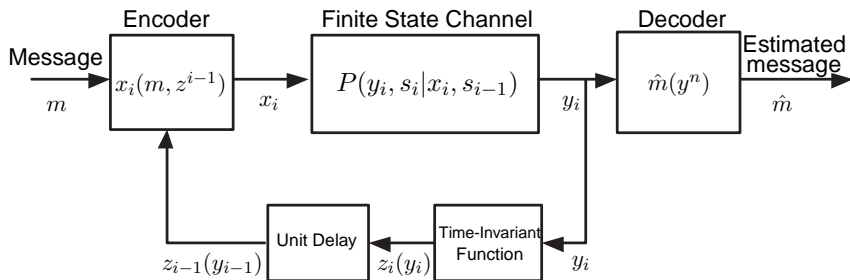
# Channels without feedback



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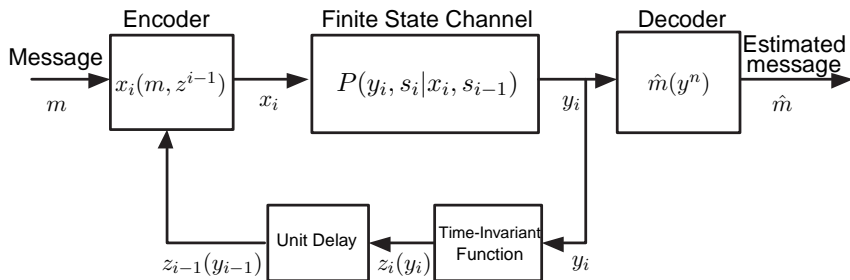


# Channels with feedback





# Channels with feedback



Finite State Channel(FSC) property:

$$P(y_i, s_i | x^i, s^{i-1}, y^{i-1}) = P(y_i, s_i | x_i, s_{i-1})$$

# Exact capacity computations

- For memoryless channels we know the exact capacity:
  - Binary Symmetric channel (BSC)
  - Erasure channel
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  - Numerical solutions [Blahut72, Arimoto72]
  - Feedback does not increase capacity [Shannon56]
- What about channels with memory?
  - Mod-2 addition channel  $Y_i = X_i \oplus Z_i$ , where  $Z_i$  stationary.

$$C = 1 - \lim_{n \rightarrow \infty} H(Z_i | Z^{i-1}) \quad \text{[with feedback, by Alajaji95]}$$

# Exact capacity computations

- For memoryless channels we know the exact capacity:
  - Binary Symmetric channel (BSC)
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  - Z- channel
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- What about channels with memory?
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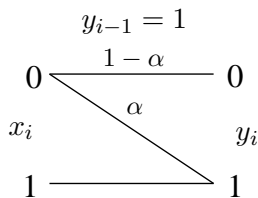
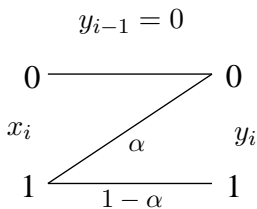
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POST  
Previous Output is the State

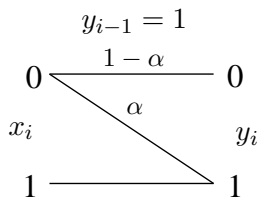
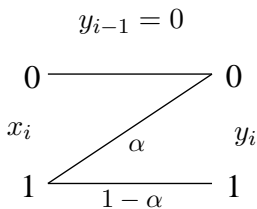
# POST( $\alpha$ ) channel

- If  $y_{i-1} = 0$  then the channel behaves as an  $Z$  channel with parameter  $\alpha$
- If  $y_{i-1} = 1$  then it behaves as an  $S$  channel with parameter  $\alpha$ .



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Alternatively,

if  $X_i = Y_{i-1}$ ,  $Y_i = X_i$

otherwise,  $Y_i = X_i \oplus Z_i$ , where  $Z_i \sim \text{Bernoulli}(\alpha)$

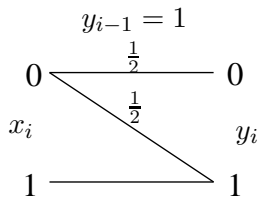
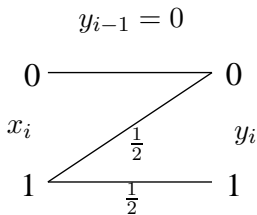
# Simple POST channel or $\text{POST}(\alpha = \frac{1}{2})$

if  $X_i = Y_{i-1}$ ,

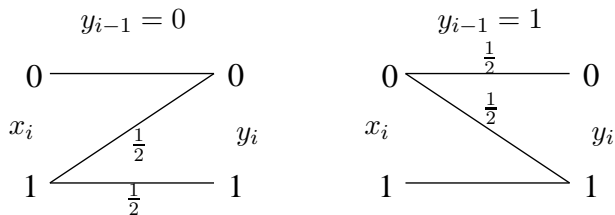
$$Y_i = X_i$$

otherwise,

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# Goals and motivation

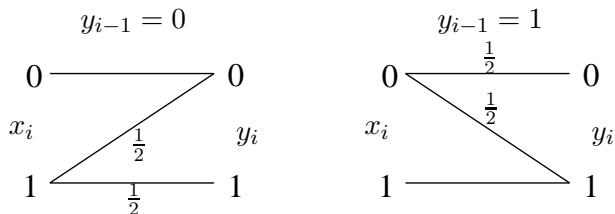


## Questions

- What is the capacity with feedback?



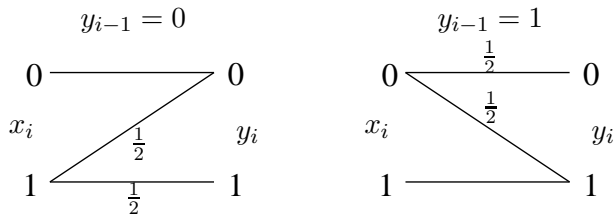
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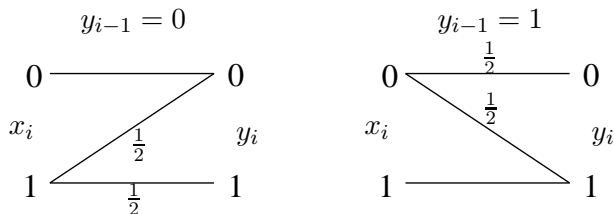
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- What is the capacity with feedback?
- What is the capacity without feedback?
- Does feedback increase capacity?

# Goals and motivation



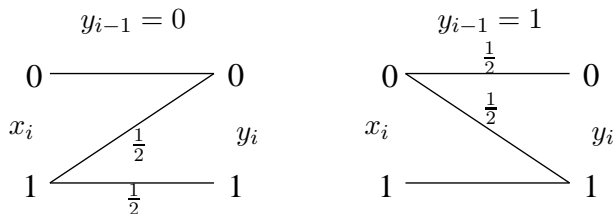
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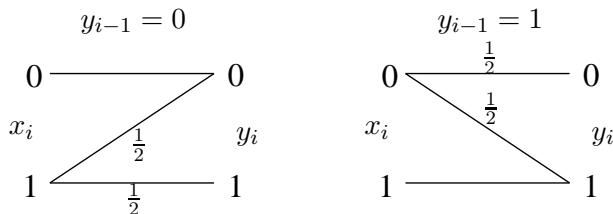
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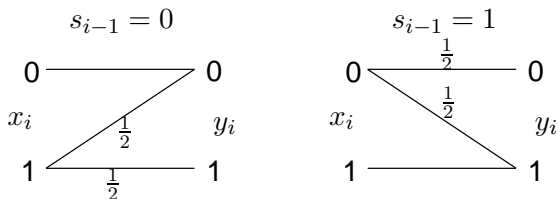
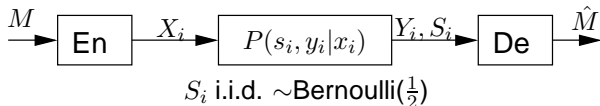
## Questions

- What is the capacity with feedback?
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## Motivation

- Simple channel with memory
- Models writing on memory with cell interference
- “To feed or not to feed back”

# Gaining intuition via a similar example



- Regular capacity

$$C = \max_{P(x)} I(X; Y, S) = H_b\left(\frac{1}{4}\right) - \frac{1}{2} = 0.3111$$

- Feedback capacity is the capacity of the  $Z$  channel

$$C_{fb} = -\log_2 0.8 = 0.3219$$

## Theorem

For any FSC with feedback

[P.& Weissman & Goldsmith 09]

$$C_{FB} \geq \frac{1}{n} \max_{P(x^n || z^{n-1})} \min_{s_0} I(X^n \rightarrow Y^n | s_0) - \frac{\log |\mathcal{S}|}{n}$$

$$C_{FB} \leq \frac{1}{n} \max_{P(x^n || z^{n-1})} \max_{s_0} I(X^n \rightarrow Y^n | s_0) + \frac{\log |\mathcal{S}|}{n}$$

- $I(X^n \rightarrow Y^n)$  is the *directed information*.
- $P(x^n || z^{n-1})$  is a *causally conditioned distribution*.
- $|\mathcal{S}|$  is the number of states.

## Theorem

Feedback does not increase the capacity of the  $\text{POST}(\alpha)$  channel.



## Theorem

Feedback does not increase the capacity of the  $\text{POST}(\alpha)$  channel.

**Main Idea:** show that for any  $n$  the two optimization problems have the same value.

$$\max_{P(x^n || y^{n-1})} I(X^n \rightarrow Y^n)$$

$$\max_{P(x^n)} I(X^n \rightarrow Y^n)$$

# A convex optimization problem

## Definition

A *convex optimization problem* is of the form

$$\begin{aligned} & \text{minimize} && f_0(x) \\ & \text{subject to} && f_i(x) \leq b_i \quad i = 1, \dots, k \\ & && g_j(x) = 0 \quad j = 1, \dots, l \end{aligned}$$

where  $f_0(x)$  and  $\{f_i(x)\}_{i=1}^k$  are convex functions, and  $\{g_j(x)\}_{j=1}^l$  are affine.

- The problem  $\max_{P(x^n || y^{n-1})} I(X^n \rightarrow Y^n)$  is a convex optimization problem.

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- The problem  $\max_{P(x^n||y^{n-1})} I(X^n \rightarrow Y^n)$  is a convex optimization problem.
- **Tool:** KKT conditions are sufficient and necessary conditions for a solutions to be optimal.

# Necessary and sufficient for $\max I(X^n \rightarrow Y^n)$

## Theorem

A set of necessary and sufficient conditions for an input probability  $P(x^n||y^{n-1})$  to maximize  $I(X^n \rightarrow Y^n)$  is that for some numbers  $\beta_{y^{n-1}}$

$$\sum_{y^n} p(y^n||x^n) \log \frac{p(y^n||x^n)}{ep(y^n)} = \beta_{y^{n-1}}, \quad \forall x^n, y^{n-1}, \text{ if } p(x^n||y^{n-1}) > 0$$

$$\sum_{y^n} p(y^n||x^n) \log \frac{p(y^n||x^n)}{ep(y^n)} \leq \beta_{y^{n-1}}, \quad \forall x^n, y^{n-1}, \text{ if } p(x^n||y^{n-1}) = 0$$

where  $p(y^n) = \sum_{x^n} p(y^n||x^n)p(x^n||y^{n-1})$ . The solution of the optimization is

$$\max_{P(x^n||y^{n-1})} I(X^n \rightarrow Y^n) = \sum_{y^{n-1}} \beta_{y^{n-1}} + 1.$$

# Main corollary we use to prove equality of the optimization problems

## Corollary

Let  $P^*(x^n || y^{n-1})$  achieve the maximum of  $\max_{P(x^n || y^{n-1})} I(X^n \rightarrow Y^n)$  and let  $P^*(y^n)$  be the induced output pmf. If there exists an input probability distribution  $P(x^n)$  such that

$$p^*(y^n) = \sum_{x^n} p(y^n || x^n) p(x^n),$$

for any  $n$  then the feedback capacity and the nonfeedback capacity are the same.

# Simple POST channel

Binary symmetric Markov  $\{Y\}_{i \geq 1}$  with transition probability 0.2 can be described recursively

$$P_0(y^n) = \begin{bmatrix} 0.8P_0(y^{n-1}) \\ 0.2P_1(y^{n-1}) \end{bmatrix} \quad P_1(y^n) = \begin{bmatrix} 0.2P_0(y^{n-1}) \\ 0.8P_1(y^{n-1}) \end{bmatrix},$$

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Conditional probabilities:

$$P(Y_1|X_1, s_0 = 0)$$

$Y_1 \backslash X_1$	0	1
0	1	$\frac{1}{2}$
1	0	$\frac{1}{2}$

$$P(Y_1|X_1, s_0 = 1)$$

$Y_1 \backslash X_1$	0	1
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$$P_{n,0} = \begin{bmatrix} 1 \cdot P_{n-1,0} & \frac{1}{2} \cdot P_{n-1,0} \\ 0 \cdot P_{n-1,1} & \frac{1}{2} \cdot P_{n-1,1} \end{bmatrix} \quad P_{n,1} = \begin{bmatrix} \frac{1}{2} \cdot P_{n-1,0} & 0 \cdot P_{n-1,0} \\ \frac{1}{2} \cdot P_{n-1,1} & 1 \cdot P_{n-1,1} \end{bmatrix}$$

Using

$$P_0(x^n) = P_{n,0}^{-1}P_0(y^n), \quad P_1(x^n) = P_{n,1}^{-1}P_1(y^n)$$

we obtained

$$P_0(x^n) = \begin{bmatrix} 0.8P_0(x^{n-1}) - 0.2P_1(x^{n-1}) \\ 0.4P_1(x^{n-1}) \end{bmatrix},$$
$$P_1(x^n) = \begin{bmatrix} 0.4P_0(x^{n-1}) \\ 0.8P_1(x^{n-1}) - 0.2P_0(x^{n-1}) \end{bmatrix}.$$

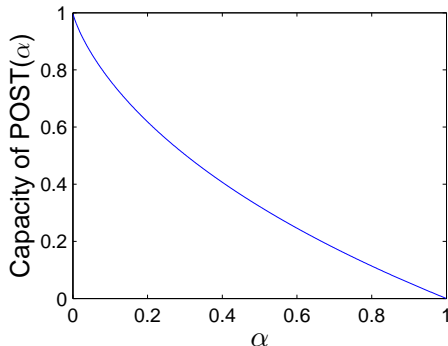


# Main result

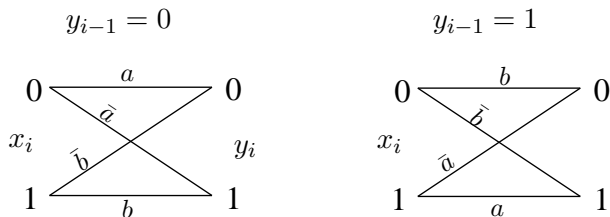
## Feedback does not increase capacity of POST( $\alpha$ )

The feedback and the non-feedback capacity of POST( $\alpha$ ) channel is the same as of the memoryless  $Z$  channel with parameter  $\alpha$ , which is  $C = -\log_2 c$  where

$$c = (1 + \bar{\alpha}\alpha^{\frac{\alpha}{\bar{\alpha}}})^{-1}$$



# POST( $a, b$ ) channel



If  $y_{i-1} = 0$  then the channel behaves as DMC with parameters  $(a, b)$  and if  $y_{i-1} = 1$  then the channel behaves as DMC with parameters  $(b, a)$ .

We are able to show numerically on a grid of resolution  $10^{-5} \times 10^{-5}$  on  $(a, b) \in [0, 1] \times [0, 1]$  that feedback does not increase the capacity.

We were able to obtain an input distribution that attains  $P^*(y^n)$ ,

$$P_0(x^n) = \frac{1}{(a+b-1)(\gamma+1)} \begin{bmatrix} b\gamma P_0(x^{n-1}) - \bar{b}P_1(x^{n-1}) \\ -\bar{a}\gamma P_0(x^{n-1}) + aP_1(x^{n-1}) \end{bmatrix},$$

$$P_1(x^n) = \frac{1}{(a+b-1)(\gamma+1)} \begin{bmatrix} aP_0(x^{n-1}) - \bar{a}\gamma P_1(x^{n-1}) \\ -\bar{b}P_0(x^{n-1}) + b\gamma P_1(x^{n-1}) \end{bmatrix},$$

$$\gamma = 2^{\frac{H(b)-H(a)}{a+b-1}}.$$

but how to show analytically that  $P_0(x^n)$  and  $P_1(x^n)$  are valid.

# Inequalities that we needed.

In order to prove that  $P(x^n)$  is valid we needed:

- $\gamma \geq \frac{\bar{b}}{b}$
- $\gamma \leq \frac{a}{\bar{a}}$
- $\gamma \geq \frac{a}{b}$  for  $a \geq \bar{b}$
- $\gamma^2 \leq \frac{a^2}{b\bar{a}}$  for  $a \geq \bar{b}$
- $\frac{\gamma(\bar{a}+b)}{2b} \geq 1$  for  $a \geq \bar{b}$  and  $a\bar{a} \leq b\bar{b}$
- $\gamma^2(\bar{a}+b)^2 - 4a\bar{b} \geq 0$
- $\gamma(\bar{a}+b) - \sqrt{\gamma^2(\bar{a}+b)^2 - 4a\bar{b}} \leq 2\bar{b}$ , for  $a \geq \bar{b}$  and  $a\bar{a} \leq b\bar{b}$

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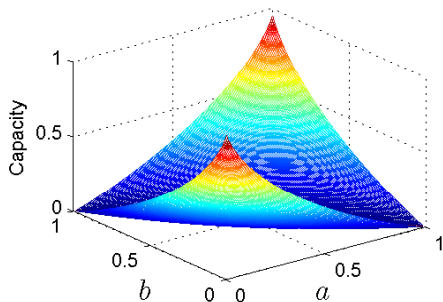
$$\gamma = 2^{\frac{H(b)-H(a)}{a+b-1}}.$$

# Main result

Feedback does not increase capacity of a  $\text{POST}(a, b)$  channel

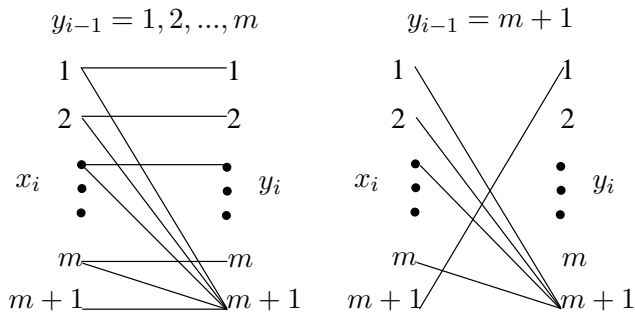
The feedback and the non-feedback capacity of  $\text{POST}(a, b)$  channel is the same as of a binary DMC channel with parameters  $(a, b)$ , which is given by

$$C = \log \left[ 2^{\frac{\bar{a}H_b(b) - bH_b(a)}{a+b-1}} + 2^{\frac{\bar{b}H_b(a) - aH_b(b)}{a+b-1}} \right].$$



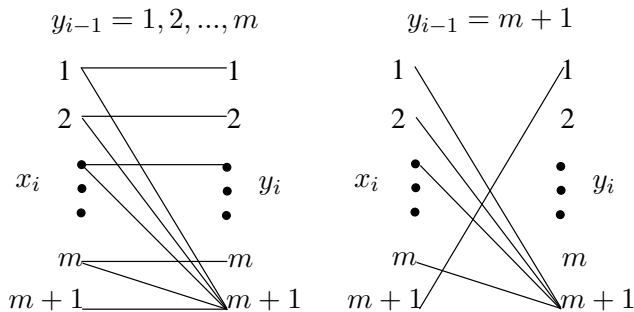
Is there a POST channel where feedback increases capacity?

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# Is there a POST channel where feedback increases capacity?



	upper bound on capacity	lower bound on $C_{fb}$
$m$	$\frac{1}{6} \max_{s_0} \max_{P(x^6)} I(X^6; Y^6   s_0)$	$R = \frac{\log_2 m}{3}$
$2^9$	2.5376	3.0000

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## Channels with memory

- If we can generate  $P_{fb}^*(y^n)$  using non feedback input then feedback does not increase capacity.
- Feedback does not increase capacity of  $\text{POST}(a, b)$

*Thank you very much!*

# Convex Optimization vs Dynamic Programming

Comparing two approaches to compute

$$\max_{p(x^n||y^{n-1})} I(X^n \rightarrow Y^n).$$

	Convex Optimization	Dynamic Programming
Channel	any FSC	unifilar FSC
Length	$n \leq 15$	unlimited
Solution	exact for $n < \infty$	approximate
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