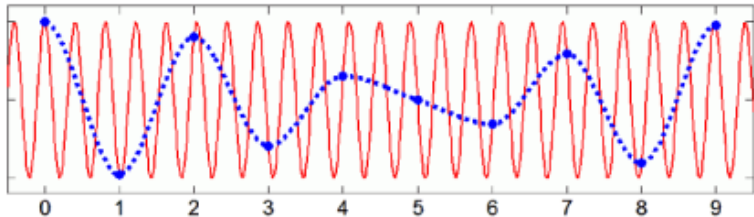


Reasoning About Sound Programs

Emilio Jesús Gallego Arias

Joint work with O. Hermant & P. Jouvelot
MINES ParisTech, PSL Research University, France

Rennes, 15 Avril 2015



Some Music DSLs



- 4CED
- Adagio
- AML
- AMPLE
- Arctic
- Autaklang
- Bang
- Canon
- CHANT
- Chuck
- CLCE
- CMIX
- Cosmic
- CMUSIC
- Common Lisp Music
- Common Music
- Common Music Notation
- Coound
- Cuckoo
- DARMS
- DCMP
- DMIX
- Ebdy
- ExAC
- Euterpea
- Exttempore
- Faust
- Flavors Band
- Flavour
- FOIL
- FORMES
- FORMULA
- Fugue
- Gibber
- GROOVE
- GUIDO
- HARP
- Haskell
- HMSL
- INV
- Invokator
- KERN
- LPC
- Mars
- MASC
- Mas
- MidLisp
- MidLogo
- MODE
- MOM
- Mox
- MSX
- MUS10
- MUS8
- MUSCMP
- MusData
- MusES
- MUSIC 10
- MUSIC 11
- MUSIC 360
- MUSIC 48
- MUSIC 48F
- MUSIC 4F
- MCL
- MUSIC III/IV/V
- MusicLogo
- Music1000
- MUSIC7
- Musitex
- MUSIGOL
- MusicXML
- Musitex
- NIFF
- NOTELIST
- Nyquist
- OPAL
- OpenMusic
- Organum1
- Outperform
- Overtone
- PE
- Patchwork
- PILE
- PL
- PLACOMP
- PLAY1
- PLAY2
- PMX
- POCO
- POD6
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Software verification?

Some Music DSLs



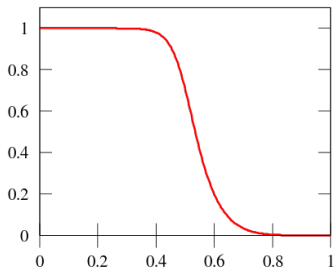
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Software verification?

What is our gain?

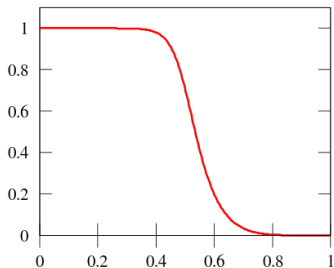
Let's assume a simple IIR filter:

$$\text{smooth}_n = (1 - c) \cdot x_n + c \cdot \text{smooth}_{n-1}$$



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What would we like to know about it?

$$\text{smooth}_n = (1 - c) \cdot x_n + c \cdot \text{smooth}_{n-1}$$

Natural questions are:

- ▶ Frequency response;
- ▶ Stability;
- ▶ Linearity/Time Invariance.

Standard DSP theory gives answers.

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Paradigm shift!

Faust

- ▶ Functional PL for digital signal processing.
- ▶ Synchronous paradigm, geared towards audio.
- ▶ Programs: circuits/block diagrams with feedback.
- ▶ Semantics: streams of samples.
- ▶ *Efficiency is crucial.*
- ▶ Created in 2000 by Yann Orlarey et al. at GRAME.
- ▶ Mature, compiles to more than 14 platforms.

Faust's Ecosystem

Users:

- ▶ Grame: Multiple projects, main developer.
- ▶ Stanford: Class/books on signal processing, STK instrument toolkit, Faust2android, Mephisto...
- ▶ Ircam: Acoustic libraries, effects libraries,...
- ▶ Other: Guitarix, moForte guitar, etc...

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Recent Events:

- ▶ Faust day at Stanford, LAC 2015.
- ▶ Faust program competition (€2,000).
- ▶ FEEVER project :)

Syntax and Well-Formedness

$$\text{TERM} \frac{}{\vdash ! : 1 \rightarrow 0}$$

$$\text{ID} \frac{}{\vdash _ : 1 \rightarrow 1}$$

$$\text{PAR} \frac{\vdash f_1 : i_1 \rightarrow o_1 \quad \cdots \quad \vdash f_n : i_n \rightarrow o_n}{\vdash (f_1, \dots, f_n) : \sum_j^n i_j \rightarrow \sum_j^n o_j}$$

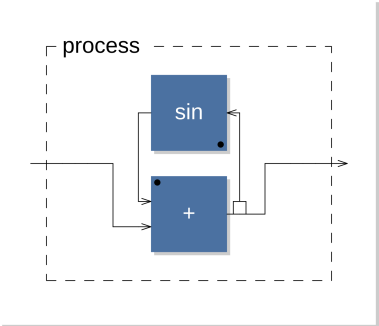
$$\text{COMP} \frac{\vdash f : i \rightarrow k \quad \vdash g : k \rightarrow o}{\vdash (f : g) : i \rightarrow o}$$

$$\text{PAN} \frac{\vdash f : i \rightarrow k \quad \vdash g : k * n \rightarrow o \quad 0 < k \wedge 0 < n}{\vdash f < : g : i \rightarrow o}$$

Feedback

$$\text{FEED} \frac{\vdash f : o_g + i_f \rightarrow i_g + o_f \quad \vdash g : i_g \rightarrow o_g}{\vdash f \sim g : i_f \rightarrow i_g + o_f}$$

Diagram for $+ \sim \text{sin}$:

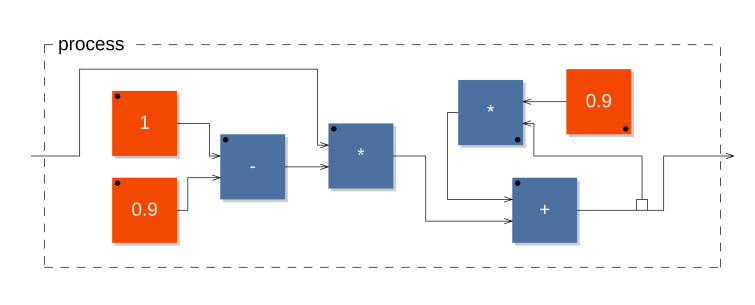


Back to the Filter

$$\text{smooth}_n = (1 - c)x_n + c \cdot \text{smooth}_{n-1}$$

Using Faust:

$$\text{smooth}(c) = *(1-c) : + \sim *(c)$$



[For $c = 0.9$]

Feedback Delay Network

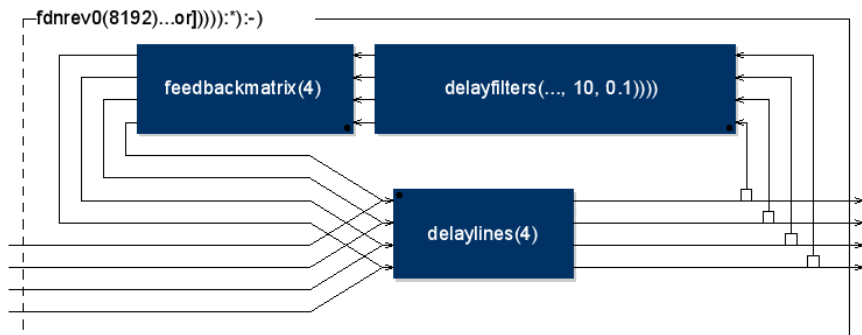
```
fdnrev(N, dp, freqs, durs, loopgainmax)
  = delaylines ~ (delayfilters : feedbackmatrix)
where
  delaylines      = rep(N,i,delay(dp[i]));
  delayfilters    = rep(N,filter(freqs,durs));
  feedbackmatrix = bhadamard(N);
```

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PL & Faust

- ▶ Causal/Synchronous Programming.
See next week's talk!
- ▶ Functional Reactive Programming/Arrows.
- ▶ String Diagrams, Monoidal Closed Categories.
- ▶ Stream/Data Flow Programming.

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Some related DSL: VOBLA, Ziria, Halide, Darkroom, Julia.

DSP & Faust

- ▶ Real-time Linear Processing.
- ▶ Real-time Non-linear Processing.
- ▶ Frequency Domain Processing.
- ▶ Non-necessarily causal.
- ▶ Filters, Feedback Networks, Interpolation.
- ▶ Windowing!
- ▶ Numerical issues.
- ▶ Nyquist/precision/aliasing.

Verification in DSP/Faust

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Problems with Audio:

bad sound, stability/glitches, under/overflows, time, safety/security, remote distribution.

We need more!

A Case Study: Stability

Test-bed: use Coq

Coq is a theorem prover that provides very strong evidence
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Smooth is stable when $c \in]0, 1[$. Formally:

$$\forall i \in [a, b], c \in]0, 1[\rightarrow \text{smooth}(c) i \in [a, b]$$

Let's build a mechanized constructive proof.

What's the plan?

1. Define the syntax of Faust inside Coq.

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4. Define a logic to simplify reasoning.
5. Verify!

Mechanized Semantics for Streams

- ▶ Coinductive semantics [Boulmé, et al]: problematic.
- ▶ Didn't consider PACO, etc. . . .
- ▶ Our wish: Sequences \mathbb{S} of a base type \mathbf{R} [Auger2013]

Mechanized Semantics for Streams

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Soundness needs stronger semantics (also [Guatto2014]):

$$\llbracket \vdash f : i \rightarrow o \rrbracket^n : \underbrace{\llbracket \mathbf{R} \times \dots \times \mathbf{R} \rrbracket^n}_i \rightarrow \underbrace{\llbracket \mathbf{R} \times \dots \times \mathbf{R} \rrbracket^n}_o$$

Index by number of steps; equality of streams more intensional wrt to $(\mathbb{N} \rightarrow \mathbf{R})$.

The Second Piece: Real Analysis

What about the base type **R**?

- ▶ Reals not in Mathcomp – algebraic structures good enough for most of our experiments so far.
- ▶ There are lots of work to do here. We lack convenient complex numbers, exponentials, etc...

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Not practical.

To remedy this, we define a *program logic* for sample-level properties.

Sampled-Level Predicates

Definition (Sample-Level Property)

A property $P : \mathbb{S} \rightarrow \mathbb{B}$ is sample-level if there exists a characteristic predicate $\varphi : \mathbf{R} \rightarrow \mathbb{B}$ such that for all streams s :

$$P(s) \iff \forall n. \varphi(s[n])$$

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Boundedness $x \in [a, b]$ is a sample-level property!
Properties can be made sample-level by self-composition,
e.g: ratio:

$$f \Rightarrow \langle f, f' \rangle : /$$

We can also prove this way equivalence of filter implementation.

A Sampled Logic

Definition (Sampled Judgment)

Given two characteristic predicates φ, ψ , we write

$$\{\varphi\} f \{\psi\}$$

“for all input i meeting φ , the fi satisfies ψ .”

Example

The stability judgment for smooth is written as:

$$\{x \in [a, b]\} \text{ smooth } \{x \in [a, b]\}$$

Rules for The Sampled Logic

$$\frac{\forall i_1, i_2, (\varphi_1(i_1) \wedge \varphi_1(i_2)) \implies \psi(i_1 + i_2)}{\{\varphi_1, \varphi_2\} + \{\psi\}} \textit{Prim}$$

$$\frac{\{\varphi\} f \{\theta\} \quad \{\theta\} g \{\psi\}}{\{\varphi\} f : g \{\psi\}} \textit{Comp}$$

$$\frac{\models \psi(x_0) \quad \{\theta, \varphi\} f \{\psi\} \quad \{\psi\} g \{\theta\}}{\{\varphi\} f \sim g \{\psi\}} \textit{Feed}$$

Soundness of the Logic

Definition (Validity)

$$\llbracket \{\varphi\} f \{\psi\} \rrbracket \equiv \forall i. (\forall t. \varphi(i(t))) \implies (\forall t. \psi(\llbracket f \rrbracket)(i)(t))$$

Theorem (Soundness)

For any program f of type $i \rightsquigarrow o$, if

$$\{\varphi_1, \dots, \varphi_i\} f \{\psi_1, \dots, \psi_o\}$$

is derivable then,

$$\llbracket \{\varphi_1, \dots, \varphi_i\} f \{\psi_1, \dots, \psi_o\} \rrbracket$$

is valid.

Stability Proof for Smooth

$$\frac{\frac{\square}{\{I_{ab}\} * (1 - c) \{I_{ab\bar{c}}\}} \quad \frac{\frac{\square}{\{I_{abc}, I_{ab\bar{c}}\} + \{I_{ab}\}} \quad \frac{\square}{\{I_{ab}\} * (c) \{I_{abc}\}}}{\{I_{ab\bar{c}}\} + \sim * (c) \{I_{ab}\}}}{\{i \in [a, b]\} * (1 - c) : + \sim * (c) \{o \in [a, b]\}}$$

with:

$$I_{ab}(x) \equiv x \in [a, b]$$

$$I_{abc}(x) \equiv x \in [a * c, b * c]$$

$$I_{ab\bar{c}}(x) \equiv x \in [a * (1 - c), b * (1 - c)]$$

Stability of Smooth

Three main VC in the proof:

```
(* (1 - c) * i \in [(1 - c) * a, (1 - c) * b] *)  
by rewrite ?ler_wpmul2r ?ler_subr_addr ?add0r.
```

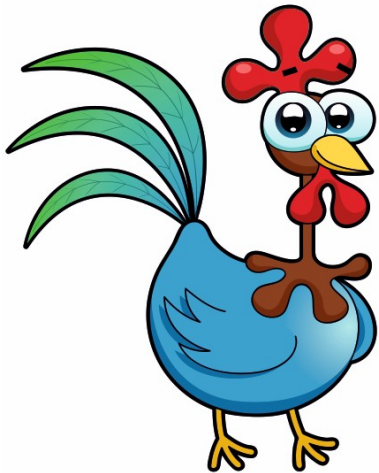
```
have Ha: a = a * c + a * (1 - c)  
  by rewrite -mulrDr addrC addrNK mulr1.
```

```
have Hb: b = b * c + b * (1 - c)  
  by rewrite -mulrDr addrC addrNK mulr1.  
by rewrite Ha Hb !ler_add.
```

```
(* c * i \in [c * a, c * b] *)  
by rewrite ?ler_wpmul2r.
```

We pushed the VCs to Why3 with success.
Interval technique ready to go into the main compiler.

Stability Proof



One Step Beyond

Extending the logic

Allow predicates to refer to windows.

$$\varphi(i) \equiv \{i/i_{\square} = 0.8\}$$

where i_{\square} is the sample produced in the execution step.

Linear System Theory

Consider the following subset of Faust:

- $\ast(c)$ scaling by c
- $+$ addition
- $:$ composition
- \sim addition

Then every Faust program is LTI. Very related to [Bonchi et al. 2015]

A consequence of that is that every program can be viewed as a polynomial.

Two Poles IIR Filter

twopole = fir : + ~ feedback

where

$$\text{fir}(x) = (x - x'') * g * (1-RR) / 2;$$

$$\text{feedback}(v) = 2*R*\cos(T) * v - RR * v';$$

.....

Two Poles IIR Filter

twopole = fir : + ~ feedback

where

$$\text{fir}(x) = (x - x'') * g * (1-RR) / 2;$$

$$\text{feedback}(v) = 2*R*\cos(T) * v - RR * v';$$

.....

Get and verify its transfer function:

$$H(z) = \frac{1 - z^{-2}}{1 - 2R\cos(\Theta_c)z^{-1} + R^2z^{-2}}$$

Ongoing: Frequency Domain Analysis

Recall the Fourier Matrix:

$$W = 1/\sqrt{N} \begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & \omega & \omega^2 & \dots & \omega^{N-1} \\ 1 & \omega^2 & \omega^4 & \dots & \omega^{2(N-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega^{N-1} & \omega^{2(N-1)} & \dots & \omega^{(N-1)(N-1)} \end{bmatrix}$$

or:

$$W = \left(\frac{\omega^{jk}}{\sqrt{N}} \right)_{j,k=0,\dots,(N-1)}$$

where ω the n th-root of the unity. Then the DFT can be expressed as:

$$X = WX$$

Fourier Properties Formally

Linearity, shifting and scaling follow from lemmas already in the MathComp linear algebra library!

Parseval's theorem is work in progress:

$$\sum_{n=0}^{N-1} |x_n|^2 = \sum_{n=0}^{N-1} |X_n|^2$$

Transfer Functions

- ▶ We can use a similar approach for the certification of transfer functions.
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- ▶ We can use a similar approach for the certification of transfer functions.
- ▶ We use the finite Z -transform, plus some caveats, mainly about the bounds.
- ▶ C.f: Algebraic Signal Processing [Puesel, Moura]

Paper with our adventures coming end of month.

Conclusions

- ▶ It was an interesting exercise; we learned a lot!
- ▶ The full Faust language is basically done.
- ▶ So far verification has been about math verification.
- ▶ Floating point issues ignored. . .
- ▶ Help from audio people. What are important things to certify?
- ▶ Non-Linear systems.
- ▶ We are investigating a different approaches to certification beyond program logics.
- ▶ Verified FFT/DSP computation. Trying CoqEAL.
- ▶ Improving the language for spectral processing.
- ▶ Non-linear Wave Filter, Scattered Delays Networks.