

# Bounded Partial-Order Reduction

## Proof Companion Source Material

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This companion source material contains the proofs for all the theorems in the main paper. For completeness, it repeats the definitions, theorems, and lemmas.

### 1. Definitions

#### Definition 1.1. Traces [1].

Equivalence classes of  $\equiv_{\Lambda}$  are *traces* over  $\Lambda$ . The term  $[\omega]$  denotes the trace that contains the sequence of transitions  $\omega$ .

#### Definition 1.2. Prefix( $[\omega]$ ) [1].

$Prefix([\omega])$  returns the set containing all prefixes of all sequences in the Mazurkiewicz trace defined by  $\omega$ .

#### Definition 1.3. Local sufficient.

A nonempty set  $T \subseteq \mathcal{T}$  of transitions enabled in a state  $s$  in  $A_{G(Bv,c)}$  is *local sufficient* in  $s$  if and only if for all sequences  $\omega$  of transitions from  $s$  in  $A_{G(Bv,c)}$ , there exists a sequence  $\omega'$  from  $s$  in  $A_{G(Bv,c)}$  such that  $\omega \in Prefix([\omega'])$  and  $\omega'_1 \in T$ .

#### Definition 1.4. $ext(s, t)$ .

Given a state  $s = final(S)$  and a transition  $t \in enabled(s)$ ,  $ext(s, t)$  returns the unique sequence of transitions  $\beta$  from  $s$  such that

1.  $\forall i \in dom(\beta) : \beta_i.tid = t.tid$
2.  $t.tid \notin enabled(final(S, \beta))$

#### 1.1 Preemption-bounded search

##### Definition 1.5. Preemption bound [2].

$$Pb(t) = 0$$

$$Pb(S.t) = \begin{cases} Pb(S) + 1 & \text{if } t.tid \neq last(S).tid \text{ and} \\ & last(S).tid \in enabled(final(S)) \\ Pb(S) & \text{otherwise} \end{cases}$$

#### Definition 1.6. Preemption-bound persistent sets.

A set  $T \subseteq \mathcal{T}$  of transitions enabled in a state  $s = final(S)$  is *preemption-bound persistent* in  $s$  iff for all nonempty sequences  $\alpha$  of transitions from  $s$  in  $A_{G(Pb,c)}$  such that  $\forall i \in dom(\alpha), \alpha_i \notin T$  and for all  $t \in T$ ,

1.  $Pb(S.t) \leq Pb(S.\alpha_1)$

2. if  $Pb(S.t) < Pb(S.\alpha_1)$ , then  $t \leftrightarrow last(\alpha)$  and  $t \leftrightarrow next(final(S.\alpha), last(\alpha).tid)$
3. if  $Pb(S.t) = Pb(S.\alpha_1)$ , then  $ext(s, t) \leftrightarrow last(\alpha)$  and  $ext(s, t) \leftrightarrow next(final(S.\alpha), last(\alpha).tid)$

#### Definition 1.7. PC for Explore( $S$ ) – Preemption bound.

$\forall u \forall \omega : \text{if } Pb(S.\omega) \leq c \text{ then } Post(S.\omega, len(S), u)$

#### Definition 1.8. Post( $S, k, u$ ) – Preemption bound.

$\forall v : \text{if } i = max(\{i \in dom(S) \mid S_i \leftrightarrow next(final(S), u) \text{ and } S_i.tid = v\}) \text{ then}$

1. **if**  $i \leq k$  **then**  
     **if**  $u \in enabled(pre(S, i))$  **then**  $u \in backtrack(pre(S, i))$   
     **else**  $backtrack(pre(S, i)) = enabled(pre(S, i))$
2. **if**  $j = max(\{j \in dom(S) \mid j = 0 \text{ or } S_{j-1}.tid \neq S_j.tid \text{ and } j < i\})$  **and**  $j < k$  **then**  
     **if**  $u \in enabled(pre(S, j))$  **then**  $u \in backtrack(pre(S, j))$   
     **else**  $backtrack(pre(S, j)) = enabled(pre(S, j))$

#### 1.2 Fair-bounded search

##### Definition 1.9. Fair bound ( $Fb$ ).

Let  $Y(S, u)$  return Thread  $u$ 's yield count in  $final(S)$ .

$$Fb(t) = 0$$

$$Fb(S.t) = max(Fb(S),$$

$$max_{u \in enabled(final(S))} (Y(S, t.tid) - Y(S, u)))$$

#### Definition 1.10. Fair-bound persistent sets.

A set  $T \subseteq \mathcal{T}$  of transitions enabled in a state  $s = final(S)$  is *fair-bound persistent* in  $s$  if and only if for all nonempty sequences  $\alpha$  of transitions from  $s$  in  $A_{G(Fb,c)}$  such that  $\forall i \in dom(\alpha) : \alpha_i \notin T$  and for all  $t \in T$ ,

1.  $Fb(S.t) \leq c$
2. if  $t$  is a release operation, then  $\forall u \in enabled(s) : next(s, u) \in T$
3.  $t \leftrightarrow last(\alpha)$

#### Definition 1.11. PC for Explore( $S$ ) - Fair bound.

$\forall u \forall \omega : \text{if } Fb(S.\omega) \leq c \text{ and } len(S.\omega) \leq MAX \text{ then } Post(S.\omega, len(S), u)$

**Definition 1.12.  $Post(S, k, u)$  - Fair bound.**

$\forall v : \mathbf{if } i = \max(\{i \in \text{dom}(S) \mid S_i \leftrightarrow \text{next}(\text{final}(S), u)\}) \mathbf{and } S_i.tid = v \mathbf{) and } i \leq k \mathbf{ then}$

$\mathbf{if } u \in \text{enabled}(\text{pre}(S, i)) \mathbf{ and } S_i \mathbf{ is not a release then}$   
 $u \in \text{backtrack}(\text{pre}(S, i))$   
 $\mathbf{else } \text{backtrack}(\text{pre}(S, i)) = \text{enabled}(\text{pre}(S, i))$

**2. Proofs**

Let  $A_{R(Bv,c)}$  be the reduced state space explored by a selective search that explores a nonempty local sufficient set in each state.

**Theorem 1.** *Let  $s$  be a state in  $A_{R(Bv,c)}$ , and let  $l$  be a local state reachable from  $s$  in  $A_{G(Bv,c)}$  by a sequence  $\omega$  of transitions. Then,  $l$  is also reachable from  $s$  in  $A_{R(Bv,c)}$ .*

*Proof.* The proof is by induction on the length of the longest sequence of transitions that leads to  $l$  from  $s$  in  $A_{G(Bv,c)}$ .

**Case 1.1. Base Case.**

For  $\text{len}(\omega) = 0$  the result is immediate.

**Case 1.2. Inductive case.**

Let  $l$  be a local state such that the longest sequence of transitions  $\omega$  from  $s$  to  $l$  has length  $n + 1$ . Let  $u$  be a thread such that  $l = \text{local}(\text{final}(S.\omega), u)$ . Let  $T$  be the nonempty local sufficient set explored from  $s$  in  $A_{R(Bv,c)}$ .

By Definition 1.3 of local sufficient sets, there exists a sequence  $\omega'$  of transitions from  $s$  in  $A_{G(Bv,c)}$  such that  $\omega'_1 \in T$  and  $\omega \in \text{Prefix}([\omega'])$ . Thus, by Definition 1.2 of the prefix function, there exists a sequence  $\beta$  of transitions from  $\text{final}(S.\omega)$  such that  $\omega.\beta \in [\omega']$ . Assume that none of the transitions in  $\omega$  are by  $u$ . Then, by definition of local states,

$$\text{local}(\text{final}(S.\omega), u) = \text{local}(\text{final}(S), u)$$

and the result is immediate.

Assume that a transition in  $\omega$  is by  $u$ . Let  $i \in \text{dom}(\omega)$  be the maximum value of  $i$  such that  $\omega_i.tid = u$ . Because  $\omega.\beta \in [\omega']$ , there must exist  $j \in \text{dom}(\omega')$  such that  $\omega'_j = \omega_i$ . Let  $\omega' = \alpha.t.\gamma$  such that  $t = \omega'_j$ . Because  $\omega.\beta \in [\omega']$ ,

$$\text{local}(\text{final}(S.\omega), u) = \text{local}(\text{final}(S.\alpha.t), u)$$

Thus,  $\omega'$  leads to  $l$ . Because  $\omega'_1$  is in  $T$ , it is explored from  $s$  and the state  $\text{final}(S.\omega'_1)$  is reachable in  $A_{R(Bv,c)}$ . Because  $\omega$  is the longest sequence of transitions that leads to  $l$  in  $A_{G(Bv,c)}$ ,  $\text{len}(S.\alpha.t) \leq \text{len}(\omega)$ . Thus, from  $\text{final}(S.\omega'_1)$ ,  $l$  is reachable via a sequence of transitions of length  $n$ . By the inductive hypothesis,  $l$  is also reachable from  $s$  in  $A_{R(Bv,c)}$ .  $\square$

**2.1 Preemption-bounded search**

Let  $A_{R(Pb,c)}$  be the reduced state space for a selective search that explores a preemption-bound persistent set in each state.

We provide two lemmas to manage the bound, and a theorem stating that a nonempty preemption-bound persistent set is local sufficient.

**Lemma 2.** *Let  $\alpha$  and  $\beta$  be nonempty sequences of transitions from  $s = \text{final}(S)$  in  $A_{G(Pb,c)}$  such that*

1.  $\beta \leftrightarrow \alpha$
2.  $\text{Pb}(S.\beta_1) \leq \text{Pb}(S.\alpha_1)$
3.  $\forall i \in \text{dom}(\beta) : \beta_i.tid = \beta_1.tid$
4.  $\beta \leftrightarrow \text{next}(\text{final}(S.\alpha_1 \dots \alpha_i), \alpha_i.tid), 1 \leq i < \text{len}(\alpha)$
5. *if*  $\text{Pb}(S.\beta_1) = \text{Pb}(S.\alpha_1)$ , *then*  
 $\beta_1.tid \notin \text{enabled}(\text{final}(S.\beta))$

*Then,  $\beta.\alpha$  is a sequence of transitions from  $s$  in  $A_{G(Pb,c)}$ .*

*Proof.* By Assumption 1,  $\beta.\alpha$  is a sequence of transitions from  $s$  in  $A_G$ . For each preemption in  $S.\beta.\alpha$ , from left to right, show that there exists a unique preemption in  $S.\alpha$ . Assume that  $\beta_1$  requires a preemption from  $\text{final}(S)$ . By Assumption 2,  $\alpha_1$  also requires a preemption from  $\text{final}(S)$ . By Assumption 3, no transition in  $\beta$  after  $\beta_1$  requires a preemption.

Assume that  $\alpha_1$  requires a preemption from  $\text{final}(S.\beta)$ . Then,

$$\beta_1.tid \in \text{enabled}(\text{final}(S.\beta))$$

and thus by Assumptions 2 and 5,  $\text{Pb}(S.\beta_1) < \text{Pb}(S.\alpha_1)$ . Thus,  $\alpha_1$  requires a preemption from  $\text{final}(S)$  and  $\beta_1$  does not, so this preemption is unique. Assume that a transition  $\alpha_i$ ,  $2 \leq i \leq \text{len}(\alpha)$ , requires a preemption in  $S.\beta.\alpha$ . By Assumption 4,  $\alpha_i$  also requires a preemption in  $S.\alpha$ . Thus, for each preemption in  $S.\beta.\alpha$  there exists a unique preemption in  $S.\alpha$  and

$$\text{Pb}(S.\beta.\alpha) \leq \text{Pb}(S.\alpha) \leq c$$

Thus,  $\beta.\alpha$  is a sequence of transitions from  $s$  in  $A_{G(Pb,c)}$ .  $\square$

**Lemma 3.** *Let  $T$  be a nonempty preemption-bound persistent set in a state  $s = \text{final}(S)$  in  $A_{R(Pb,c)}$  and let  $\alpha.\beta.\gamma$  be a sequence of transitions from  $s$  in  $A_{G(Pb,c)}$  such that  $\alpha$  and  $\beta$  are nonempty and*

1.  $\forall i \in \text{dom}(\alpha) : \alpha_i \notin T$
2.  $\beta_1 \in T$
3.  $\forall i \in \text{dom}(\beta) : \beta_i.tid = \beta_1.tid$
4. *if*  $\text{Pb}(S.\beta_1) < \text{Pb}(S.\alpha_1)$  *then*  $\text{len}(\beta) = 1$
5. *if*  $\text{Pb}(S.\beta_1) = \text{Pb}(S.\alpha_1)$  *and*  $\gamma$  *is empty, then*  $\beta_1.tid \notin \text{enabled}(\text{final}(S.\beta))$
6. *if*  $\text{Pb}(S.\beta_1) = \text{Pb}(S.\alpha_1)$  *and*  $\gamma$  *is nonempty, then*  $\gamma_1.tid \neq \beta_1.tid$

*Then,  $\beta.\alpha.\gamma$  is a sequence of transitions from  $s$  in  $A_{G(Pb,c)}$ .*

*Proof.* By Assumptions 1-4 and by Requirements 2 and 3 of Definition 1.6 of preemption-bound persistent sets,  $\beta \leftrightarrow \alpha$

and

$$\forall i \in \text{dom}(\alpha) : \beta \leftrightarrow \text{next}(\text{final}(S.\alpha_1 \dots \alpha_i), \alpha_i.\text{tid}) \quad (1)$$

Thus,  $\beta.\alpha.\gamma$  is a sequence of transitions from  $s$  in  $A_G$ . For each preemption in  $S.\beta.\alpha.\gamma$ , from left to right, show that there exists a unique preemption in  $S.\alpha.\beta.\gamma$ . Assume that  $\beta_1$  requires a preemption from  $\text{final}(S)$ . Then, by Requirement 1 of Definition 1.6 of preemption-bound persistent sets,  $\alpha_1$  also requires a preemption from  $\text{final}(S)$ . By Assumption 3, no transition in  $\beta$  after  $\beta_1$  requires a preemption.

Assume that  $\alpha_1$  requires a preemption from  $\text{final}(S.\beta)$ . If  $Pb(S.\beta_1) < Pb(S.\alpha_1)$ , then  $\alpha_1$  requires a preemption from  $\text{final}(S)$  and  $\beta_1$  does not, so this preemption is unique. Otherwise, by Requirement 1 of Definition 1.6 of preemption-bound persistent sets,  $Pb(S.\beta_1) = Pb(S.\alpha_1)$ . Because  $\alpha_1$  requires a preemption from  $\text{final}(S.\beta)$ ,

$$\beta_1.\text{tid} \in \text{enabled}(\text{final}(S.\beta)) \quad (2)$$

By Assumption 5,  $\gamma$  is nonempty, and by Assumption 6  $\gamma_1.\text{tid} \neq \beta_1.\text{tid}$ . By Equation 2 and Requirement 3 of Definition 1.6 of preemption-bound persistent sets,

$$\beta_1.\text{tid} \in \text{enabled}(\text{final}(S.\alpha.\beta))$$

Thus,  $\gamma_1$  requires a preemption from  $\text{final}(S.\alpha.\beta)$ . Assume that a transition  $\alpha_i$ ,  $2 \leq i \leq \text{len}(\alpha)$ , requires a preemption in  $S.\beta.\alpha.\gamma$ . By Equation 1,  $\alpha_i$  also requires a preemption in  $S.\alpha.\beta.\gamma$ .

Assume that  $\gamma_1$  requires a preemption from  $\text{final}(S.\beta.\alpha)$ . Then,

$$\text{last}(\alpha).\text{tid} \in \text{enabled}(\text{final}(S.\beta.\alpha))$$

By Equation 1,

$$\text{last}(\alpha).\text{tid} \in \text{enabled}(\text{final}(S.\alpha))$$

Because  $\beta \leftrightarrow \alpha$ ,  $\beta_1.\text{tid} \neq \text{last}(\alpha).\text{tid}$ . Thus,  $\beta_1$  requires a preemption from  $\text{final}(S.\alpha)$ . Assume that a transition  $\gamma_i$ ,  $2 \leq i \leq \text{len}(\gamma)$ , requires a preemption in  $S.\beta.\alpha.\gamma$ . Because  $\beta \leftrightarrow \alpha$ ,  $\text{final}(S.\alpha.\beta.\gamma_1) = \text{final}(S.\beta.\alpha.\gamma_1)$ . Thus, by Definition 1.5 of the preemption bound,  $\gamma_i$  also requires a preemption in  $S.\alpha.\beta.\gamma$ . Thus, for each preemption in  $S.\beta.\alpha.\gamma$  there exists a unique preemption in  $S.\alpha.\beta.\gamma$  and

$$Pb(S.\beta.\alpha.\gamma) \leq Pb(S.\alpha.\beta.\gamma) \leq c$$

Thus,  $\beta.\alpha.\gamma$  is a sequence of transitions from  $s$  in  $A_{G(Pb,c)}$ .  $\square$

**Theorem 4.** *If  $T$  is a nonempty preemption-bound persistent set in a state  $s$  in  $A_{R(Pb,c)}$ , then  $T$  is local sufficient in  $s$ .*

*Proof.* Let  $s$  be a state in  $A_{R(Pb,c)}$  and let  $l$  be a local state reachable from  $s$  in  $A_{G(Pb,c)}$  via a nonempty sequence  $\omega$  of transitions.

**Case 4.1.**  $\forall i \in \text{dom}(\omega) : \omega_i \notin T$ .

Let  $t$  be any transition in  $T$ . By Requirement 1 of Definition 1.6 of preemption-bound persistent sets,  $Pb(S.t) \leq Pb(S.\omega_1)$ . Let  $\beta = t$  if  $Pb(S.t) < Pb(S.\omega_1)$ , and let  $\beta = \text{ext}(s, t)$  otherwise. Consider the sequence  $\omega' = \beta.\omega$ . By Requirements 2 and 3 of Definition 1.6 of preemption-bound persistent sets,  $\beta \leftrightarrow \omega$  and  $\forall i \in \text{dom}(\omega) : \beta \leftrightarrow \text{next}(\text{final}(S.\omega_1 \dots \omega_i), \omega_i.\text{tid})$ . Thus, by Lemma 2  $\beta.\omega$  is a sequence of transitions from  $s$  in  $A_{G(Pb,c)}$  and by Definition 1.1 of a trace,  $\omega.\beta \in [\omega']$ . By Definition 1.2 of the prefix function,  $\omega \in \text{Prefix}([\omega'])$ . Thus,  $T$  is local sufficient in  $s$ .

**Case 4.2.**  $\exists i \in \text{dom}(\omega) : \omega_i \in T$ .

Let  $\omega = \alpha.\beta.\gamma$  such that

1.  $\forall i \in \text{dom}(\alpha) : \alpha_i \notin T$
2.  $\beta_1 \in T$
3.  $\forall i \in \text{dom}(\beta) : \beta_i.\text{tid} = \beta_1.\text{tid}$
4. if  $Pb(S.\beta_1) < Pb(S.\alpha_1)$  then  $\text{len}(\beta) = 1$
5. if  $Pb(S.\beta_1) = Pb(S.\alpha_1)$  and  $\gamma$  is nonempty, then  $\gamma_1.\text{tid} \neq \beta_1.\text{tid}$

Assume that  $\alpha$  is empty. Then,  $T$  is local sufficient in  $s$  because  $\omega_1 \in T$  and  $l$  is reachable via  $\omega$ . Assume that  $\alpha$  is nonempty. By Requirement 1 of Definition 1.6 of preemption-bound persistent sets,  $Pb(S.\beta_1) \leq Pb(S.\alpha_1)$ .

**Case 4.2a.**  $\gamma$  is nonempty, or  $\gamma$  is empty and

$\beta_1.\text{tid} \notin \text{enabled}(\text{final}(S.\beta))$ , or  $Pb(S.\beta_1) < Pb(S.\alpha_1)$ .

Consider the sequence  $\omega' = \beta.\alpha.\gamma$ , i.e.,  $\omega$  with  $\beta$  moved to the beginning. By Requirements 2 and 3 of Definition 1.6 of preemption-bound persistent sets,  $\beta \leftrightarrow \alpha$  and  $\forall i \in \text{dom}(\alpha) : \beta \leftrightarrow \text{next}(\text{final}(S.\alpha_1 \dots \alpha_i), \alpha_i.\text{tid})$ . Thus, by Lemma 3  $\omega'$  is a sequence of transitions from  $s$  in  $A_{G(Pb,c)}$  and by Definition 1.1 of a trace  $\omega' \in [\omega]$ . By Definition 1.2 of the prefix function  $\omega \in \text{Prefix}([\omega'])$ , so  $T$  is local sufficient in  $s$ .

**Case 4.2b.**  $\gamma$  is empty,  $\beta_1.\text{tid} \in \text{enabled}(\text{final}(S.\beta))$ , and  $Pb(S.\beta_1) = Pb(S.\alpha_1)$ .

Let  $\beta' = \text{ext}(s, \beta_1)$ . Consider the sequence  $\omega' = \beta'.\alpha$ . By Requirement 3 of Definition 1.6 of preemption-bound persistent sets,  $\beta' \leftrightarrow \alpha$  and  $\forall i \in \text{dom}(\alpha) : \beta' \leftrightarrow \text{next}(\text{final}(S.\alpha_1 \dots \alpha_i), \alpha_i.\text{tid})$ . Thus, by Lemma 2  $\beta'.\alpha$  is a sequence of transitions from  $s$  in  $A_{G(Pb,c)}$  and by Definition 1.1 of a trace  $\omega.\beta' \in [\omega']$ . By Definition 1.2 of the prefix function  $\omega \in \text{Prefix}([\omega'])$ , so  $T$  is local sufficient in  $s$ .  $\square$

**Lemma 5.** *Whenever a state  $s = \text{final}(S)$  is backtracked by Algorithm 1, the set  $T$  of transitions explored from  $s$  is preemption-bound persistent in  $s$ , provided that postcondition PC holds for every recursive call **Explore**( $S.t$ ) for all  $t \in T$ .*

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**Algorithm 1** BPOR with bound function  $Bv$  and bound  $c$ 

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1: Initially, Explore( $\epsilon$ ) from  $s_0$ 
2: procedure Explore( $S$ ) begin
3:   Let  $s = \text{final}(S)$ 
   # Add backtrack points
4:   for all ( $u \in \text{Tid}$ ) do
5:     for all ( $v \in \text{Tid} \mid v \neq u$ ) do
       # Find most recent dependent transition
6:       if ( $\exists i = \max(\{i \in \text{dom}(S) \mid S_i \leftrightarrow$ 
          $\text{next}(s, u) \text{ and } S_i.\text{tid} = v\})$ ) then
7:         Backtrack( $S, i, u$ )
   # Continue the search by exploring successor states
8:   Initialize( $S$ )
9:   Let  $\text{visited} = \emptyset$ 
10:  while ( $\exists u \in (\text{enabled}(s) \cap \text{backtrack}(s) \setminus \text{visited})$ )
    do
11:    add  $u$  to  $\text{visited}$ 
12:    if ( $Bv(S.\text{next}(s, u)) \leq c$ ) then
13:      Explore( $S.\text{next}(s, u)$ )
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**Algorithm 2** BPOR for preemption-bounded search

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1: procedure Initialize( $S$ ) begin
2:   if ( $\text{last}(S).\text{tid} \in \text{enabled}(\text{final}(S))$ ) then
3:     add  $\text{last}(S).\text{tid}$  to  $\text{backtrack}(\text{final}(S))$ 
4:   else
5:     add any  $u \in \text{enabled}(\text{final}(S))$  to
        $\text{backtrack}(\text{final}(S))$ 
6:   procedure Backtrack( $S, i, u$ ) begin
7:     AddBacktrackPoint( $S, i, u$ )
8:     if ( $j = \max(\{j \in \text{dom}(S) \mid j = 0 \text{ or } S_{j-1}.\text{tid} \neq$ 
        $S_j.\text{tid} \text{ and } j < i\})$ ) then
9:       AddBacktrackPoint( $S, j, u$ )
10:    procedure AddBacktrackPoint( $S, i, u$ ) begin
11:      if ( $u \in \text{enabled}(\text{pre}(S, i))$ ) then
12:        Add  $u$  to  $\text{backtrack}(\text{pre}(S, i))$ 
13:      else
14:         $\text{backtrack}(\text{pre}(S, i)) = \text{enabled}(\text{pre}(S, i))$ 
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*Proof.* Let  $T = \text{next}(s, u) \mid u \in \text{backtrack}(s)$ . Show that if  $T$  violates any requirement in Definition 1.6 of preemption-bound persistent sets, then we have a contradiction.

**Case 5.1.**  $T$  violates Requirement 1.

Proceed by contradiction. Assume that there exist transitions  $t \in T$  and  $t' \notin T$  such that  $t$  and  $t'$  are both enabled in  $s$  and  $Pb(S.t') < Pb(S.t)$ . By Definition 1.5 of the preemption bound

$$t'.\text{tid} = \text{last}(S).\text{tid}$$

Thus, by Line 3 of Algorithm 2,  $t'.\text{tid} \in \text{backtrack}(s)$  and thus  $t' \in T$ , and we have a contradiction.

**Case 5.2.**  $T$  violates Requirement 2.

Proceed by contradiction. Assume that there exists a nonempty sequence  $\alpha$  of transitions from  $s$  in  $A_{G(Pb, c)}$  and a transition  $t \in T$  such that, if we let  $u = \text{last}(\alpha).\text{tid}$ :

1.  $\forall i \in \text{dom}(\alpha) : \alpha_i \notin T$
2.  $Pb(S.t) < Pb(S.\alpha_1)$
3.  $t$  is dependent with  $\text{last}(\alpha)$  or with  $\text{next}(\text{final}(S.\alpha), u)$

Let  $n = \text{len}(\alpha)$  and let  $\omega = \alpha_1 \dots \alpha_{n-1}$ , i.e.,  $\alpha$  with its last transition removed. Let there be no prefixes of  $\alpha$  that also meet the criteria above, and thus

4.  $t \leftrightarrow \omega$  and  $\forall i \in \text{dom}(\omega) :$   
 $t \leftrightarrow \text{next}(\text{final}(S.\omega_1 \dots \omega_i), \omega_i.\text{tid})$

Assume that  $t.\text{tid} = u$ . Because  $t \leftrightarrow \omega$ ,

$$t = \text{next}(\text{final}(S), u) = \text{next}(\text{final}(S.\omega), u) = \text{last}(\alpha)$$

Thus,  $\text{last}(\alpha) \in T$  and we have a contradiction.

Assume that  $t.\text{tid} \neq u$ . Let  $\omega' = \omega$  if  $t$  is dependent with  $\text{last}(\alpha)$ , and let  $\omega' = \alpha$  if  $t \leftrightarrow \alpha$  and  $t$  is dependent with  $\text{next}(\text{final}(S.\alpha), u)$ . Consider the postcondition

$$\text{Post}(S.t.\omega', \text{len}(S) + 1, u)$$

for the recursive call **Explore**( $S.t$ ). By Lemma 2,  $t.\omega'$  is a sequence of transitions from  $s$  in  $A_{G(Pb, c)}$ . Because  $t \leftrightarrow \omega'$ ,  $t$  is the most recent transition by  $t.\text{tid}$  that is dependent with  $\text{next}(\text{final}(S.t.\omega'), u)$ . Thus, by Definition 1.8 of *Post*, either  $u \in \text{backtrack}(s)$ , or  $\text{backtrack}(s) = \text{enabled}(s)$  and thus  $\alpha_1 \in T$ . In either case, we have a contradiction.

**Case 5.3.**  $T$  violates Requirement 3.

Proceed by contradiction. Assume that there exists a nonempty sequence  $\alpha$  of transitions from  $s$  in  $A_{G(Pb, c)}$  and a transition  $t \in T$  such that, if we let  $u = \text{last}(\alpha).\text{tid}$  and let  $\beta = \text{ext}(s, t)$ :

1.  $Pb(S.t) = Pb(S.\alpha_1)$
2.  $\forall i \in \text{dom}(\alpha) : \alpha_i \notin T$
3. a transition in  $\beta$  is dependent with  $\text{last}(\alpha)$  or with  $\text{next}(\text{final}(S.\alpha), u)$

Let  $n = \text{len}(\alpha)$ , and let  $\omega = \alpha_1 \dots \alpha_{n-1}$ , i.e.,  $\alpha$  with its last transition removed. Let there be no prefixes of  $\alpha$  that also meet the criteria above, and thus

4.  $\beta \leftrightarrow \omega$  and  $\forall i \in \text{dom}(\omega) : \beta \leftrightarrow \text{next}(\text{final}(S.\omega_1 \dots \omega_i), \omega_i.\text{tid})$

Assume that  $\beta_1.\text{tid} = u$ . Because  $\beta \leftrightarrow \omega$ ,

$$\beta_1 = \text{next}(\text{final}(S), u) = \text{next}(\text{final}(S.\omega), u) = \text{last}(\alpha)$$

Thus,  $\text{last}(\alpha) \in T$  and we have a contradiction.

Assume that  $\beta_1.\text{tid} \neq u$ . Let  $\beta_k$  be the last transition in  $\beta$  that is dependent with  $\text{last}(\alpha)$  or with  $\text{next}(\text{final}(S.\alpha), u)$ . Let  $\omega' = \omega$  if  $\beta_k$  is dependent with  $\text{last}(\alpha)$ , and let  $\omega' = \alpha$  if  $\beta \leftrightarrow \alpha$  and  $\beta_k$  is dependent with  $\text{next}(\text{final}(S.\alpha), u)$ .

By Lemma 2,  $\beta.\omega'$  is a sequence of transitions from  $s$  in  $A_{G(Pb,c)}$ . Consider the postcondition

$$Post(S.\beta.\omega', len(S) + 1, u)$$

for the recursive call **Explore**( $S.\beta_1$ ). Because  $\beta \leftrightarrow \omega'$ ,  $\beta_k$  is the most recent transition by  $\beta_1.tid$  that is dependent with  $next(final(S.\beta.\omega'), u)$ . Because  $Pb(S.\beta_1) = Pb(S.\alpha_1)$ , by Definition 1.5 of the preemption bound either  $\beta_1.tid \neq last(S).tid$ , or  $S$  is empty. Because all transitions in  $\beta$  are by the same thread,  $\beta_1$  is the most recent such location to  $\beta_k$ . Thus, by Requirement 2 of Definition 1.8 of postcondition *Post*, either  $u \in backtrack(s)$ , or  $backtrack(s) = enabled(s)$  and thus  $\alpha_1 \in T$ . In either case, we have a contradiction.  $\square$

Thus, if postcondition *PC* holds in each state  $s$  that Algorithm 1 explores with the **Backtrack** procedure from Algorithm 2, then the set of transitions Algorithm 1 explores from  $s$  is preemption-bound persistent in  $s$ .

Next, we prove that postcondition *PC* holds in each state  $s$  that Algorithm 1 explores. First, we prove a lemma that simplifies the inductive step. Lemma 6 differs from the similar lemma used in depth-bounded and context-bounded search because it must account for the more complex postcondition that preemption-bounded search requires.

**Lemma 6.** *Let  $s = final(S)$  be a state in  $A_{R(Pb,c)}$ , let  $\omega$  and  $\omega'$  be nonempty sequences of transitions from  $s$  in  $A_{G(Pb,c)}$  such that  $Pb(S.\omega'_1) \leq Pb(S.\omega_1)$ , and let  $u$  be a thread such that*

1.  $\exists \beta : \omega.\beta \in [\omega']$  and  $\beta \leftrightarrow next(final(S.\omega), u)$ , or
2.  $\exists \beta : \omega'.\beta \in [\omega]$  and  $\beta \leftrightarrow next(final(S.\omega), u)$

*Then,  $Post(S.\omega', len(S) + 1, u) \implies Post(S.\omega, len(S), u)$ .*

*Proof.* Because  $\beta \leftrightarrow next(final(S.\omega), u)$ ,

$$next(final(S.\omega), u) = next(final(S.\omega'), u)$$

Assume that in Definition 1.8 of postcondition *Post*,  $i \leq k$  for  $Post(S.\omega, len(S), u)$ . Then,  $i$  and  $j$  have the same values in  $Post(S.\omega', len(S), u)$  that they have in  $Post(S.\omega, len(S), u)$  because  $\beta \leftrightarrow next(final(S.\omega), u)$ .

Assume that  $i > k$  for  $Post(S.\omega, len(S), u)$ . Because  $Pb(S.\omega'_1) \leq Pb(S.\omega_1)$ , by Definition 1.5 of the preemption bound either  $S$  is empty or  $\omega_1.tid \neq last(S).tid$ . Thus,  $j \geq k$  for  $Post(S.\omega, len(S), u)$ , so Definition 1.8 of *Post* does not require any backtrack points. In either case,

$$Post(S.\omega', len(S), u) \implies Post(S.\omega, len(S), u) \quad (3)$$

Because Requirement 1 of Definition 1.8 of *Post* requires that  $i \leq k$  and Requirement 2 of Definition 1.8 of *Post* requires that  $j < k$

$$Post(S.\omega', len(S) + 1, u) \implies Post(S.\omega', len(S), u)$$

Thus, by Equation 3,

$$Post(S.\omega', len(S) + 1, u) \implies Post(S.\omega, len(S), u)$$

$\square$

**Theorem 7.** *Whenever a state  $s = final(S)$  is backtracked during the search performed by Algorithm 1 in an acyclic state space, the postcondition *Post* for **Explore**( $S$ ) is satisfied, and the set  $T$  of transitions explored from  $s$  is preemption-bound persistent in  $s$ .*

*Proof.* The proof is by induction on the order in which states are backtracked.

**Base case.**

Because the search is acyclic, is performed in depth-first order, and the preemption bound provides a zero-cost transition in each state, the first backtracked state must be a deadlock state in which no transition is enabled. Thus, the postcondition for the first backtracked state is

$$\forall u : Post(S, len(S), u)$$

and is directly established by Lines 4-7 in Algorithm 1.

**Inductive case.**

Assume that each recursive call to **Explore**( $S.t$ ) satisfies its postcondition. By Lemma 5,  $T$  is preemption-bound persistent in  $s$ . Show that **Explore**( $S$ ) satisfies its postcondition for any sequence  $\omega$  of transitions from  $s$  in  $A_{G(Pb,c)}$  and for any thread  $u$ .

**Case 7.1.**  $\forall i \in dom(\omega) : \omega_i \notin T$  and  $u \in backtrack(s)$ .

Because  $u \in backtrack(s)$ ,  $next(s, u) \in T$ . By Definition 1.5 of preemption-bound persistent sets,  $next(s, u) \leftrightarrow \omega$ , and thus

$$next(final(S.\omega), u) = next(s, u)$$

Thus,  $next(final(S.\omega), u) \leftrightarrow \omega$ , and  $Post(S.\omega, len(S), u)$  iff  $Post(S, len(S), u)$ . The latter is directly established by Lines 4-7 in Algorithm 1.

**Case 7.2.**  $\forall i \in dom(\omega) : \omega_i \notin T$  and  $u \notin backtrack(s)$ .

Because  $u \notin backtrack(s)$ ,  $next(s, u) \notin T$ . Let  $t$  be any transition in  $T$ , and thus  $t.tid \neq u$ . Let  $\beta = t$  if  $Pb(S.t) < Pb(S.\omega_1)$ , and let  $\beta = ext(s, t)$  otherwise. Consider the sequence  $\omega' = \beta.\omega$ . By Definition 1.6 of preemption-bound persistent sets,

1.  $Pb(S.t) \leq Pb(S.\omega_1)$
2.  $\beta \leftrightarrow \omega$
3.  $\forall i \in dom(\omega) : \beta \leftrightarrow next(final(S.\omega_1 \dots \omega_i), \omega_i.tid)$

By Lemma 2,  $\omega'$  is a sequence of transitions from  $s$  in  $A_{G(Pb,c)}$ . Because  $\beta \leftrightarrow \omega$ ,  $\omega.\beta \in [\omega']$ . By the inductive hypothesis for the recursive call **Explore**( $S.t$ ),

$$Post(S.\omega', len(S) + 1, u)$$

Assume that  $next(final(S.\omega'), u)$  is dependent with a transition in  $\beta$ . Because  $\beta \leftrightarrow \omega$ , the most recent dependent transition to  $next(final(S.\omega'), u)$  by  $\beta_1.tid$  must be in  $\beta$ . If  $\beta_1$  is the most recent dependent transition, then by Requirement 1 of Definition 1.8 of *Post* either  $u \in backtrack(s)$ , or  $backtrack(s) = enabled(s)$  and thus  $\omega_1 \in T$ . If the most recent dependent transition is another transition in  $\beta$ , then  $Pb(S.t) = Pb(S.\omega_1)$  because otherwise  $\beta$  would contain only a single transition, and thus either  $S$  is empty or  $last(S).tid \neq \beta_1.tid$ . Thus,  $j$  must be  $len(S)$  in Definition 1.8, and thus either  $u \in backtrack(s)$ , or  $backtrack(s) = enabled(s)$  and thus  $\omega_1 \in T$ . In either case, we have a contradiction.

Assume that  $\beta \leftrightarrow next(final(S.\omega'), u)$ . Because  $\beta_1.tid \neq u$ ,  $next(final(S.\omega), u) = next(final(S.\omega'), u)$  and

$$\beta \leftrightarrow next(final(S.\omega), u)$$

Thus, by Lemma 6 where  $\omega.\beta \in [\omega']$ ,

$$Post(S.\omega, len(S), u)$$

**Case 7.3.**  $\exists i \in dom(\omega) : \omega_i \in T$ .

Let  $\omega = \alpha.\beta.\gamma$  such that

1.  $\forall i \in dom(\alpha) : \alpha_i \notin T$
2.  $\beta_1 \in T$
3.  $\forall i \in dom(\beta) : \beta_i.tid = \beta_1.tid$
4. if  $Pb(S.\beta_1) < Pb(S.\alpha_1)$  then  $len(\beta) = 1$
5. if  $Pb(S.\beta_1) = Pb(S.\alpha_1)$  and  $\gamma$  is nonempty, then  $\gamma_1.tid \neq \beta_1.tid$

Assume that  $\alpha$  is empty. Then,  $\omega_1 \in T$  and by the inductive hypothesis,

$$Post(S.\omega, len(S) + 1, u)$$

Because Requirement 1 of Definition 1.8 of *Post* requires that  $i \leq k$  and Requirement 2 of Definition 1.8 of *Post* requires that  $j < k$ ,

$$Post(S.\omega, len(S), u)$$

as required.

Assume that  $\alpha$  is nonempty. By Requirement 1 of Definition 1.6 of preemption-bound persistent sets,  $Pb(S.\beta_1) \leq Pb(S.\alpha_1)$ .

**Case 7.3a.**  $\gamma$  is nonempty, or  $\gamma$  is empty and

$\beta_1.tid \notin enabled(final(S.\beta))$ , or  $Pb(S.\beta_1) < Pb(S.\alpha_1)$ .

Consider the sequence  $\omega' = \beta.\alpha.\gamma$ , i.e.,  $\omega$  with  $\beta$  moved to the beginning. By Requirements 2 and 3 of Definition 1.6 of preemption-bound persistent sets,  $\beta \leftrightarrow \alpha$  and  $\forall i \in dom(\alpha) : \beta \leftrightarrow next(final(S.\alpha_1 \dots \alpha_i), \alpha_i.tid)$ . Thus, by Definition 1.1 of a trace,  $\omega' \in [\omega]$ . By Lemma 3,  $\omega'$  is a sequence of transitions from  $s$  in  $A_{G(Pb, c)}$ . By the inductive hypothesis for the recursive call **Explore**( $S.\beta_1$ ),

$$Post(S.\omega', len(S) + 1, u)$$

and thus by Lemma 6 where  $\beta$  is empty and  $\omega' \in [\omega]$ ,

$$Post(S.\omega, len(S), u)$$

**Case 7.3b.**  $\gamma$  is empty,  $\beta_1.tid \in enabled(final(S.\beta))$ ,  $Pb(S.\beta_1) = Pb(S.\alpha_1)$ , and  $u \in backtrack(s)$ .

Because  $\gamma$  is empty,  $\omega = \alpha.\beta$ . Consider the sequence  $\omega' = \beta$ . By Requirement 3 of Definition 1.6 of preemption-bound persistent sets,  $\beta \leftrightarrow \alpha$  and thus

$$\omega'.\alpha \in [\omega]$$

Because  $u \in backtrack(s)$ ,  $next(s, u) \in T$  and  $next(s, u) \leftrightarrow \alpha$ . If  $\beta_1.tid = u$ , then  $next(final(S.\omega), u)$  is a transition in  $ext(s, \beta_1)$  and by Requirement 3 of Definition 1.6 of preemption-bound persistent sets  $next(final(S.\omega), u) \leftrightarrow \alpha$ . If  $\beta_1.tid \neq u$ , then  $next(s, u) = next(final(S.\omega), u)$ . In either case,

$$next(final(S.\omega), u) \leftrightarrow \alpha$$

Because  $Pb(S.\beta_1) = Pb(S.\alpha_1)$  and all transitions in  $\beta$  are by the same thread and thus do not require a preemption,  $\omega'$  is a sequence of transitions from  $s$  in  $A_{G(Pb, c)}$ . By the inductive hypothesis for the recursive call **Explore**( $S.\beta_1$ ),

$$Post(S.\omega', len(S) + 1, u)$$

and thus by Lemma 6 where  $\beta = \alpha$  and  $\omega'.\alpha \in \omega$ ,

$$Post(S.\omega, len(S), u)$$

**Case 7.3c.**  $\gamma$  is empty,  $\beta_1.tid \in enabled(final(S.\beta))$ ,  $Pb(S.\beta_1) = Pb(S.\alpha_1)$ , and  $u \notin backtrack(s)$ .

Because  $\gamma$  is empty,  $\omega = \alpha.\beta$ . Let  $\beta'$  be the unique, nonempty sequence of transitions from  $final(S.\beta)$  such that  $\beta.\beta' = ext(s, \beta_1)$ . Consider the sequence  $\omega' = \beta.\beta'.\alpha$ . By Requirement 3 of Definition 1.6 of preemption-bound persistent sets,  $\beta.\beta' \leftrightarrow \alpha$  and  $\forall i \in dom(\alpha) : \beta.\beta' \leftrightarrow next(final(S.\alpha_1 \dots \alpha_i), \alpha_i.tid)$ . Thus, by Lemma 2,  $\omega'$  is a sequence of transitions from  $s$  in  $A_{G(Pb, c)}$ . Because  $\beta.\beta' \leftrightarrow \alpha$ ,

$$\omega.\beta' \in [\omega']$$

By the inductive hypothesis for **Explore**( $S.\beta_1$ ),

$$Post(S.\omega', len(S) + 1, u)$$

Assume that  $next(final(S.\omega'), u)$  is dependent with a transition in  $\beta'$ . Then, because  $\beta.\beta' \leftrightarrow \alpha$ , the most recent dependent transition to  $next(final(S.\omega'), u)$  by  $\beta_1.tid$  is in  $\beta'$ . Thus, by Definition 1.8 of *Post*, either  $u \in backtrack(s)$  or  $backtrack(s) = enabled(s)$  and thus  $\omega_1 \in T$ . In either case, we have a contradiction.

Assume that  $\beta' \leftrightarrow next(final(S.\omega'), u)$ . Because  $\beta_1 \in T$  and  $u \notin backtrack(s)$ ,  $\beta_1.tid \neq u$ . Thus, it must be the case that  $next(final(S.\omega), u) = next(final(S.\omega'), u)$ , and

$$\beta' \leftrightarrow next(final(S.\omega), u)$$

Thus, by Lemma 6 where  $\beta = \beta'$  and  $\omega.\beta' \in [\omega']$ ,

$$Post(S.\omega, len(S), u)$$

□

## 2.2 Fair-bounded search

Let  $A_{R(Fb,c)}$  be the reduced state space explored by a selective search that explores a fair-bound persistent set in each state. We provide two lemmas to manage the bound, and a theorem stating that a nonempty fair-bound persistent set is local sufficient.

**Lemma 8.** *Let  $\alpha$  be a nonempty sequence of transitions from  $s = \text{final}(S)$  in  $A_{G(Fb,c)}$  and let  $t$  be a transition enabled in  $s$  such that*

1.  $Fb(S.t) \leq c$
2.  $t$  is not a release operation
3.  $t \leftrightarrow \alpha$

*Then,  $t.\alpha$  is a sequence of transitions from  $s$  in  $A_{G(Fb,c)}$ .*

*Proof.* Because  $t \leftrightarrow \alpha$ ,  $t.\alpha$  is a sequence of transitions from  $s$  in  $A_G$ . Because  $t$  is not a release operation,

$$\forall i \in \text{dom}(\alpha) : \text{enabled}(\text{final}(S.t.\alpha_1 \dots \alpha_i)) \subseteq \text{enabled}(\text{final}(S.\alpha_1 \dots \alpha_i))$$

Thus, by Definition 1.9 of the fair bound, the transitions in  $\alpha$  cost no more in  $S.t.\alpha$  than they do in  $S.\alpha$ . By Assumption 1,  $t$  is within the bound from  $s$ . Thus, by Definition 1.9 of the fair bound,

$$Fb(S.t.\alpha) \leq c$$

and  $t.\alpha$  is a sequence of transitions from  $s$  in  $A_{G(Fb,c)}$ .  $\square$

**Lemma 9.** *Let  $T$  be a nonempty fair-bound persistent set in a state  $s = \text{final}(S)$  in  $A_{R(Fb,c)}$  and let  $\alpha.t.\gamma$  be a sequence of transitions from  $s$  in  $A_{G(Fb,c)}$  such that  $\alpha$  is nonempty,  $\forall i \in \text{dom}(\alpha) : \alpha_i \notin T$ , and  $t \in T$ . Then,  $t.\alpha.\gamma$  is a sequence of transitions from  $s$  in  $A_{G(Fb,c)}$ .*

*Proof.* By Requirement 3 of Definition 1.10 of fair-bound persistent sets,  $t \leftrightarrow \alpha$ . Thus,  $t.\alpha.\gamma$  is a sequence of transitions from  $s$  in  $A_G$ . By Requirements 1 and 2 of Definition 1.10 of fair-bound persistent sets,  $Fb(S.t) \leq c$  and  $t$  is not a release operation. Thus, by Lemma 8,

$$Fb(S.t.\alpha) \leq Fb(S.\alpha)$$

Assume that  $\gamma_1$  exceeds the bound from  $\text{final}(S.t.\alpha)$ , yet  $t$  does not exceed the bound from  $\text{final}(S.\alpha)$  and  $\gamma_1$  does not exceed the bound from  $\text{final}(S.\alpha.t)$ . Then,  $t$  must be a release operation that enables a transition  $t'$  such that  $t'.tid$  has a lower yield count than  $\gamma_1.tid$  has in  $\text{final}(S.t.\alpha)$ , because otherwise  $\gamma_1$  would also exceed the bound from  $\text{final}(S.\alpha)$ . Because  $t$  is not a release operation, we have a contradiction. Thus,

$$Fb(S.t.\alpha.\gamma_1) \leq c$$

Because  $t \leftrightarrow \alpha$ ,  $\text{final}(S.t.\alpha.\gamma_1) = \text{final}(S.\alpha.t.\gamma_1)$  and thus each transition in  $\gamma$  executes from exactly the same state in

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### Algorithm 3 BPOR procedures for fair-bounded search

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1: procedure Initialize( $S$ ) begin
2:   if ( $\text{len}(S) > \text{MAX}$ ) then
3:     report livelock and exit
4:   Backtrack( $S, \text{len}(S), u$ ) where  $u$  is a lowest cost enabled thread in  $\text{final}(S)$ 
5: procedure Backtrack( $S, i, u$ ) begin
6:   if ( $u \in \text{enabled}(\text{pre}(S, i))$  and  $\text{next}(\text{pre}(S, i), u)$  is not a release operation) then
7:     add  $u$  to  $\text{backtrack}(\text{pre}(S, i))$ 
8:   else
9:      $\text{backtrack}(\text{pre}(S, i)) = \text{enabled}(\text{pre}(S, i))$ 

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$S.t.\alpha.\gamma$  as it does in  $S.\alpha.t.\gamma$ . Thus, by Definition 1.9 of the fair bound,

$$Fb(S.t.\alpha.\gamma) \leq c$$

Thus,  $t.\alpha.\gamma$  is a sequence of transitions from  $s$  in  $A_{G(Fb,c)}$ .  $\square$

**Theorem 10.** *If  $T$  is a nonempty fair-bound persistent set in a state  $s$  in  $A_{R(Fb,c)}$ , then  $T$  is local sufficient in  $s$ .*

*Proof.* Let  $s$  be a state in  $A_{R(Fb,c)}$  and let  $l$  be a local state reachable from  $s$  in  $A_{G(Fb,c)}$  via a nonempty sequence  $\omega$  of transitions.

**Case 10.1.**  $\forall i \in \text{dom}(\omega) : \omega_i \notin T$ .

Let  $t$  be any transition in  $T$ . Consider the sequence  $\omega' = t.\omega$ . By Requirement 3 of Definition 1.10 of fair-bound persistent sets,  $t \leftrightarrow \omega$ . Thus,  $\omega.t \in [\omega']$ , and  $\omega \in \text{Prefix}([\omega'])$ . By Requirements 1 and 2 of Definition 1.10 of fair-bound persistent sets,  $Fb(S.t) \leq c$  and  $t$  is not a release operation. Thus, by Lemma 8,  $t.\omega$  is a sequence of transitions from  $s$  in  $A_{G(Fb,c)}$  and  $T$  is local sufficient in  $s$ .

**Case 10.2.**  $\exists i \in \text{dom}(\omega) : \omega_i \in T$ .

Let  $\omega = \alpha.t.\gamma$  such that  $\forall i \in \text{dom}(\alpha) : \alpha_i \notin T$  and  $t \in T$ . Assume that  $\alpha$  is empty. Then,  $T$  is local sufficient in  $s$  because  $\omega_1 \in T$  and  $l$  is reachable via  $\omega$ .

Assume that  $\alpha$  is nonempty. Consider the sequence  $\omega' = t.\alpha.\gamma$ , i.e.,  $\omega$  with  $t$  moved to the first position. By Requirement 3 of Definition 1.10 of fair-bound persistent sets,  $t \leftrightarrow \alpha$ . Thus,  $\omega' \in [\omega]$  and  $\omega \in \text{Prefix}([\omega'])$ . By Lemma 9,  $t.\alpha.\gamma$  is a sequence of transitions from  $s$  in  $A_{G(Fb,c)}$ , and  $T$  is local sufficient in  $s$ .  $\square$

**Lemma 11.** *Whenever Algorithm 1 backtracks a state  $s = \text{final}(S)$ , the set  $T$  of transitions explored from  $s$  is fair-bound persistent in  $s$ , provided that postcondition PC holds for every recursive call **Explore**( $S.t$ ) for all  $t \in T$ .*

*Proof.* Let  $T = \text{next}(s, u) \mid u \in \text{backtrack}(s)$ . Show that if  $T$  violates any requirement in Definition 1.10 of fair-bound persistent sets, then we have a contradiction.

**Case 11.1.  $T$  violates Requirement 1.**

Proceed by contradiction. Assume that for some  $t \in T$ ,  $Fb(S.t) > c$ . By Line 12 in Algorithm 1, the search explores only transitions that do not exceed the bound from  $s$ . Thus, we have a contradiction.

**Case 11.2.  $T$  violates Requirement 2.**

Proceed by contradiction. Assume that there exists a transition  $t \in T$  such that  $t$  is a release operation and a thread  $u \in \text{enabled}(s)$  such that  $\text{next}(s, u) \notin T$ . Because  $t$  is a release operation Line 9 in Algorithm 3 must add it to  $\text{backtrack}(s)$ . Because  $u \in \text{enabled}(s)$ , Line 9 also adds  $u$  to  $\text{backtrack}(s)$  and thus  $\text{next}(s, u) \in T$  and we have a contradiction.

**Case 11.3.  $T$  violates Requirement 3.**

Proceed by contradiction. Assume that there exists a nonempty sequence  $\alpha$  of transitions from  $s$  in  $A_{G(Fb,c)}$  such that  $\forall i \in \text{dom}(\alpha) : \alpha_i \notin T$ , and a transition  $t \in T$  such that

1.  $Fb(S.t) \leq c$
2.  $t$  is not a release operation
3.  $t$  is dependent with  $\text{last}(\alpha)$

Let  $n = \text{len}(\alpha)$  and let  $\omega = \alpha_1 \dots \alpha_{n-1}$ , i.e.,  $\alpha$  with its last transition removed. Let there be no prefixes of  $\alpha$  that also meet the criteria above, and thus

3.  $t \leftrightarrow \omega$

Let  $u = \text{last}(\alpha).tid$ . Assume that  $t.tid = u$ . Because  $t \leftrightarrow \omega$ ,

$$t = \text{next}(\text{final}(S), u) = \text{next}(\text{final}(S.\omega), u) = \text{last}(\alpha)$$

Thus,  $\text{last}(\alpha) \in T$  and we have a contradiction.

Assume that  $t.tid \neq u$ . Consider the postcondition

$$\text{Post}(S.t.\omega, \text{len}(S) + 1, u)$$

for the recursive call **Explore**( $S.t$ ). By Lemma 8,  $t.\omega$  is a sequence of transitions from  $s$  in  $A_{G(Fb,c)}$ . Because  $t \leftrightarrow \omega$ ,  $t$  is the most recent transition by  $t.tid$  that is dependent with  $\text{next}(\text{final}(S.t.\omega), u)$ . Thus, by Definition 1.12 of *Post*,  $u \in \text{backtrack}(s)$  and thus a transition in  $\alpha$  must be in  $T$  so we have a contradiction.  $\square$

Thus, if postcondition *PC* holds in each state  $s$  explored by Algorithm 1 with the **Backtrack** procedure from Algorithm 3, then the set of transitions explored from  $s$  is fair-bound persistent in  $s$ . Next, we prove that postcondition *PC* holds in each state  $s$  explored by Algorithm 1. First, we prove a lemma to simplify the inductive step.

**Lemma 12.** Let  $s = \text{final}(S)$  be a state in  $A_{R(Fb,c)}$ , let  $\omega$  and  $\omega'$  be nonempty sequences of transitions from  $s$  in  $A_{G(Fb,c)}$ , and let  $u$  be a thread such that

1.  $\exists \beta : \omega.\beta \in [\omega']$  **and**  $\beta \leftrightarrow \text{next}(\text{final}(S.\omega), u)$ , or
2.  $\exists \beta : \omega'.\beta \in [\omega]$  **and**  $\beta \leftrightarrow \text{next}(\text{final}(S.\omega), u)$

Then,  $\text{Post}(S.\omega', \text{len}(S) + 1, u) \implies \text{Post}(S.\omega, \text{len}(S), u)$ .

*Proof.* Because  $\beta \leftrightarrow \text{next}(\text{final}(S.\omega), u)$ ,

$$\text{next}(\text{final}(S.\omega), u) = \text{next}(\text{final}(S.\omega'), u)$$

Assume that in Definition 1.12 of *Post*( $S.\omega, \text{len}(S), u$ ) for some thread  $v$ ,  $i > k$ . Then, *Post* does not require any backtrack points for  $v$ .

Assume that for some thread  $v$  in Definition 1.12 of *Post*( $S.\omega, \text{len}(S), u$ ),  $i \leq k$ . Then,  $i$  is the same for thread  $v$  in *Post*( $S.\omega', \text{len}(S), u$ ) because  $\beta \leftrightarrow \text{next}(\text{final}(S.\omega), u)$ . Because  $i \leq \text{len}(S)$ , the yield counts for all threads are the same in *pre*( $S, i$ ), as well. Thus, by Definition 1.12 of *Post*,

$$\text{Post}(S.\omega, \text{len}(S), u) \text{ iff } \text{Post}(S.\omega', \text{len}(S), u) \quad (4)$$

Because Definition 1.12 of *Post* requires that  $i$  be less than or equal to  $k$ ,

$$\text{Post}(S.\omega', \text{len}(S) + 1, u) \implies \text{Post}(S.\omega', \text{len}(S), u)$$

Thus, by Equation 4,

$$\text{Post}(S.\omega', \text{len}(S) + 1, u) \implies \text{Post}(S.\omega, \text{len}(S), u)$$

$\square$

**Theorem 13.** Whenever a state  $s = \text{final}(S)$  is backtracked during the search performed by Algorithm 1, the postcondition *Post* for **Explore**( $S$ ) is satisfied, and the set  $T$  of transitions explored from  $s$  is fair-bound persistent in  $s$ .

*Proof.* The proof is by induction on the order in which states are backtracked.

**Base case.**

If the stack depth exceeds *MAX*, then the search terminates and reports a livelock. Thus, the state space that the search may explore without reporting a livelock is a subset of the cyclic state space. Assume that the test does not contain a livelock. Because the search is performed in depth-first order, and the fair bound always provides a zero-cost transition, the first backtracked state must be a deadlock state in which no transition is enabled. Thus, the postcondition for the first backtracked state is

$$\forall u : \text{Post}(S, \text{len}(S), u)$$

and is directly established by Lines 4-7 in Algorithm 1.

**Inductive case.**



Assume that each call to **Explore**( $S.t$ ) satisfies its postcondition. By Lemma 11,  $T$  is fair-bound persistent in  $s$ . Show that **Explore**( $S$ ) satisfies its postcondition for any sequence  $\omega$  of transitions from  $s$  in  $A_{G(Fb,c)}$  and for any thread  $u$ . If  $\omega$  is empty then the postcondition is directly established by Lines 4-7 in Algorithm 1, so assume that  $\omega$  is nonempty.

**Case 13.1.**  $\forall i \in \text{dom}(\omega) : \omega_i \notin T$  and  $u \in \text{backtrack}(s)$ . Because  $u \in \text{backtrack}(s)$ ,  $\text{next}(s, u) \in T$ . Thus, by Requirement 3 of Definition 1.10 of fair-bound persistent sets,  $\text{next}(s, u) \leftrightarrow \omega$ , and thus

$$\text{next}(\text{final}(S.\omega), u) = \text{next}(s, u)$$

Thus,  $\text{next}(\text{final}(S.\omega), u) \leftrightarrow \omega$ , and thus  $\text{Post}(S.\omega, \text{len}(S), u)$  iff  $\text{Post}(S, \text{len}(S), u)$ . The latter is directly established by Lines 4-7 in Algorithm 1.

**Case 13.2.**  $\forall i \in \text{dom}(\omega) : \omega_i \notin T$  and  $u \notin \text{backtrack}(s)$ . Let  $t$  be any transition in  $T$ . Consider the sequence  $\omega' = t.\omega$ . By Definition 1.10 of fair-bound persistent sets,  $Fb(S.t) \leq c$  and  $t \leftrightarrow \omega$ . Because  $\omega$  is nonempty and  $\omega_1 \notin T$ , by Requirement 2 of Definition 1.10 of fair-bound persistent sets,  $t$  is not a release operation. Thus, by Lemma 8,  $\omega'$  is a sequence of transitions from  $s$  in  $A_{G(Fb,c)}$ . Because  $t \leftrightarrow \omega$ ,

$$\omega.t \in [\omega']$$

By the inductive hypothesis for **Explore**( $S.t$ ),

$$\text{Post}(S.\omega', \text{len}(S) + 1, u)$$

If  $t$  is dependent with  $\text{next}(\text{final}(S.\omega'), u)$ , then because  $t \leftrightarrow \omega$ ,  $\omega'_1$  must be the most recent dependent transition to  $\text{next}(\text{final}(S.\omega'), u)$  by  $t.tid$ . Thus, by Definition 1.12 of *Post*, either  $u \in \text{backtrack}(s)$  or  $\text{backtrack}(s) = \text{enabled}(s)$ , in which case  $\omega_1 \in T$ . In either case, we have a contradiction. Thus,  $t \leftrightarrow \text{next}(\text{final}(S.\omega'), u)$  and additionally,  $t \leftrightarrow \text{next}(\text{final}(S.\omega), u)$ . Thus, by Lemma 12 where  $\beta = t$  and  $\omega.t \in [\omega']$ ,

$$\text{Post}(S.\omega, \text{len}(S), u)$$

**Case 13.3.**  $\exists i \in \text{dom}(\omega) : \omega_i \in T$ .

Let  $\omega = \alpha.t.\gamma$  such that

1.  $\forall i \in \text{dom}(\alpha) : \alpha_i \notin T$
2.  $t \in T$

Assume that  $\alpha$  is empty. Then,  $\omega_1 \in T$ , and by the inductive hypothesis

$$\text{Post}(S.\omega, \text{len}(S) + 1, u)$$

Thus, because Definition 1.12 of *Post* requires that  $i \leq k$ ,

$$\text{Post}(S.\omega, \text{len}(S), u)$$

as required.

Assume that  $\alpha$  is nonempty. Consider the sequence  $\omega' = t.\alpha.\gamma$ , i.e.,  $\omega$  with  $t$  moved to the beginning. By Definition 1.10 of fair-bound persistent sets,  $Fb(S.t) \leq c$  and  $t \leftrightarrow \alpha$ . Thus, by Definition 1.1 of a trace,

$$\omega' \in [\omega]$$

By Lemma 9,  $\omega'$  is a sequence of transitions from  $s$  in  $A_{G(Fb,c)}$ . By the inductive hypothesis for the recursive call **Explore**( $S.t$ ),

$$\text{Post}(S.\omega', \text{len}(S) + 1, u)$$

and thus by Lemma 12 where  $\beta$  is empty and  $\omega' \in [\omega]$ ,

$$\text{Post}(S.\omega, \text{len}(S), u)$$

□

## References

- [1] GODEFROID, P. *Partial-Order Methods for the Verification of Concurrent Systems: An Approach to the State-Explosion Problem*. Springer-Verlag, 1996.
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