

Supplementary Information

Paper-Based Piezoresistive MEMS Sensors

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Fig. S1 A photograph of the setup for sensor calibration. A paper-based sensor was mounted onto a three-degree-of-freedom (3-DOF) positioner that was used to move the sensor to contact a precision balance. The precision balance was for measuring forces applied to the free end of sensor beam. Resistance changes of the carbon resistor were measured by a LCR (L: inductance, C: capacitance, and R: resistance) meter.

Fig. S1

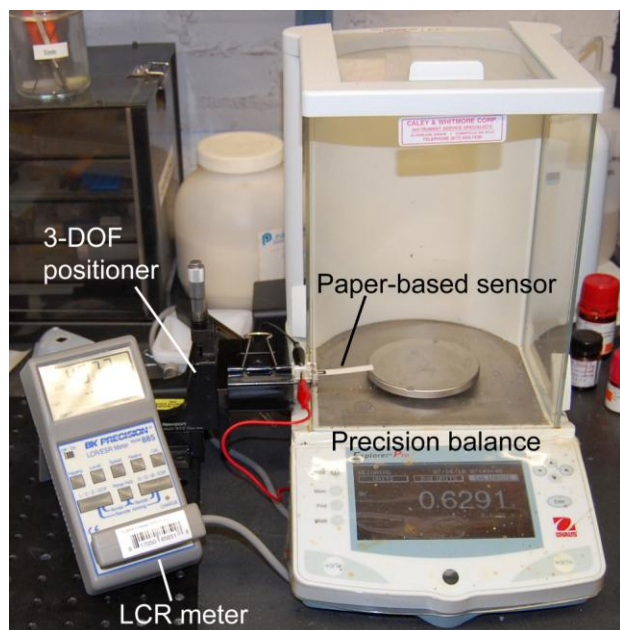


Fig. S2 Sensor calibration data for carbon resistors under stretching strain shows a nonlinear behavior. Error bars in all figures represent one standard deviation. (A) Calibration plot of the output (resistance change) of the sensor as a function of the input (applied force), based on measurement of seven devices. The solid line represents a second-order polynomial fit to the experimental data with a regression equation: $y=0.028x^2+0.14x$ ($R^2=0.999$, $N=7$). (B) Calibration plot of the relative change in resistance as a function of the applied strain. The solid line represents a second-order polynomial fit to the experimental data with a regression equation: $y=3300x^2+2.3x$ ($R^2=0.999$, $N=7$).

Fig. S2

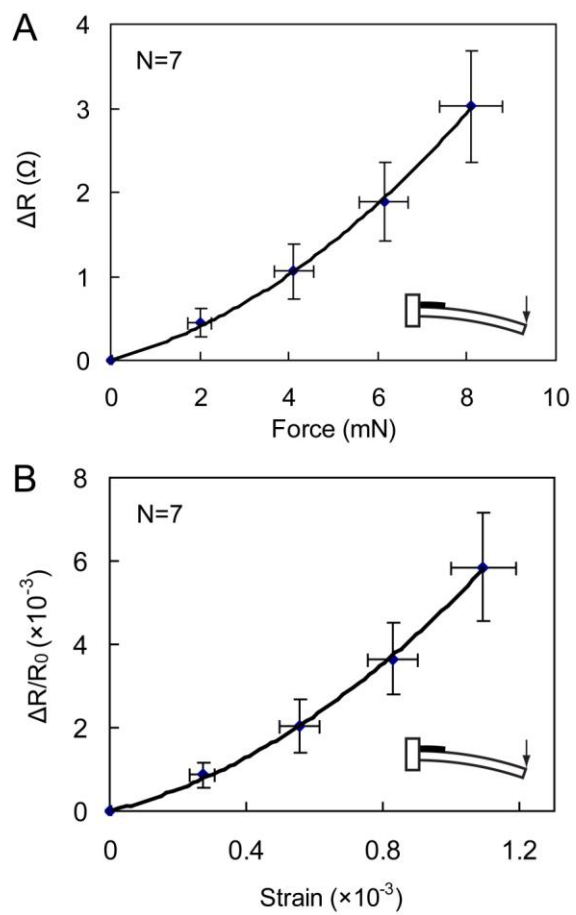
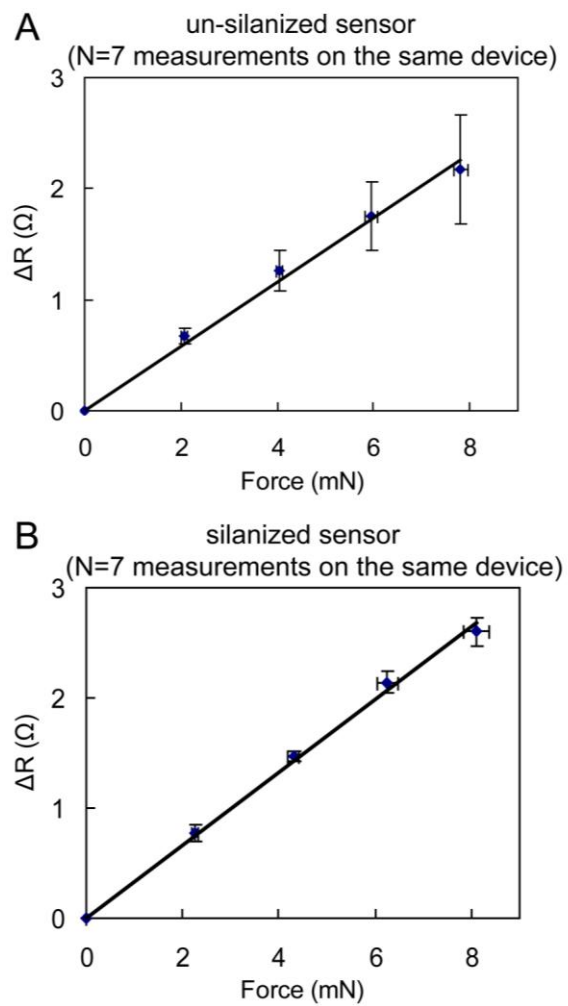


Fig. S3 Calibration plots of resistance change as a function of applied force based on seven measurements on a sensor: (A) data collected from an un-silanized device, and (B) data collected from a silanized device. These data demonstrate the repeatability of the performance of the sensor. Silanization of the paper surface minimizes the effect of environmental humidity on the performance of the sensor, and the silanized devices produced less variation in output of the sensor than the un-silanized devices. The solid lines represent a linear fit to the experimental data with regression equations: (A) $y=0.29x$ ($R^2=0.993$, $N=$ seven measurements), and (B) $y=0.33x$ ($R^2=0.997$, $N=$ seven measurements).

Fig. S3



EXPERIMENTAL SECTION

Device fabrication

We patterned the paper cantilever beams by cutting Whatman[®] 3MM CHR chromatography paper (catalog number: 3030-6185) using a laser cutter (VersaLASER VLS3.50, Universal Laser Systems Inc.). We laid out the carbon resistor and silver contact pad by manually screen-printing graphite ink (or silver ink, for wires) on the paper cantilever.¹ We generated a mask for screen-printing by cutting designed patterns into vinyl stencil film (Grafix[®] Frisket film) using laser-cutting. We visually aligned the stencil mask with the paper cantilever, placed the mask on top of the cantilever, and filled the openings of the mask with graphite ink (E3456, Ercon) to produce the carbon resistor. We then removed the mask, and dried the paper device on a hotplate at 60 °C for 20 minutes. After drying the carbon ink, we screen-printed silver ink to form the contact pads following the same procedures.

Dimensions of the PDMS cantilever beams

The dimensions of the PDMS cantilever beams, for characterizing mechanical properties of the cured polymer, are summarized in Table S2. L is the length of the beam, and W and H are the width and height of the cross-section of the beam respectively.

REFERENCE

1. Z. Nie, F. Deiss, X.Y. Liu, O. Akbulut and G. M. Whitesides, *Lab Chip*, 2010, **10**, 3163-3169.

Table S1 Different types of paper for fabrication of the sensor cantilevers. The values of beam stiffness were measured from the cantilevers with the same dimensions (44.5 mm long, and 7.7 mm wide), but made from different types of paper.

Paper type	Thickness (mm)	Grammage (g/m ²)	Beam stiffness (mN/mm)
Staples [®] copy paper	0.1	75	0.065
OfficeMax [®] copy paper	0.11	75	0.067
Vellum paper	0.09	112	0.1
1mm chromatography paper	0.18	84	0.14
Ivory paper	0.17	120	0.27
Card stock paper	0.24	199	0.8
HP [®] photo paper	0.25	240	1.3
3mm chromatography paper	0.34	186	2.0

Table S2 Dimensions of the PDMS cantilever beams for mechanical characterization (in mm).

Mixing ratio (w/w)	Beam	Length (<i>L</i>)	Width (<i>W</i>)	Height (<i>H</i>)
5:1	Beam #1	36.1	9.8	2.3
	Beam #2	40.2	10.4	2.2
	Beam #3	39.2	10.8	2.2
	Beam #4	38.4	10.2	2.3
	Beam #5	39.9	10.1	2.4
	Beam #6	38.6	10.0	2.3
	Beam #7	39.8	11.0	2.2
10:1	Beam #1	41.0	10.3	2.2
	Beam #2	39.7	10.2	2.1
	Beam #3	41.1	9.8	2.2
	Beam #4	40.0	10.1	2.3
	Beam #5	39.8	10.0	2.2
	Beam #6	40.9	10.8	2.3
	Beam #7	40.2	9.9	2.3
20:1	Beam #1	31.3	10.2	2.2
	Beam #2	32.4	9.8	2.1
	Beam #3	32.1	10.1	2.2
	Beam #4	30.4	9.8	2.1
	Beam #5	31.0	10.2	2.2
	Beam #6	32.1	10.1	2.1
	Beam #7	29.7	9.8	2.2